

Simultaneous measurement of NO and NO₂ by a dual-channel cavity ring-down spectroscopy technique

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Abstract. Nitric oxide (NO) and nitrogen dioxide (NO₂) are relevant to air quality due to their roles in tropospheric ozone (O₃) production. In China, NO_x emissions are very high and NO_x emissions exhausted from on-road vehicles make up 20% of total NO_x emissions. In order to detect the NO and NO₂ emissions on road, a dual-channel cavity ring-down spectroscopy (CRDS) system for NO2 and NO detection has been developed. In the system, NO is converted to NO₂ by its reaction with excess O_3 in the NO_x channel, such that NO can be determined through the difference between two channels. The detection limits of NO2 and NO_x for the system are estimated to be about 0.030 (1 σ , 1 s) and 0.040 ppb (1 σ , 1 s), respectively. Considering the error sources of NO₂ absorption cross section and $R_{\rm L}$ determination, the total uncertainty of NO2 measurements is about 5%. The performance of the system was validated against a chemiluminescence (CL) analyser (42i, Thermo Scientific, Inc.) by measuring the NO₂ standard mixtures. The measurement results of NO2 showed a linear correction factor (R^2) of 0.99 in a slope of 1.031 ± 0.006 , with an offset of (-0.940 ± 0.323) ppb. An intercomparison between the system and a cavity-enhanced absorption spectroscopy (CEAS) instrument was also conducted separately for NO2 measurement in an ambient environment. Least-squares analysis showed that the slope and intercept of the regression line are 1.042 ± 0.002 and (-0.393 ± 0.040) ppb, respectively, with a linear correlation factor of $R^2 = 0.99$. Another intercomparison conducted between the system and the CL analyser for NO detection also showed a good agreement within their uncertainties, with an absolute shift of (0.352 ± 0.013) ppb, a slope of 0.957 ± 0.007 and a correlation coefficient of $R^2 = 0.99$. The system was deployed on the measurements of on-road vehicle emission plumes in Hefei, and the different areas of the city. The successful deployment of the system has demonstrated that the instrument can provide a new method for retrieving fast variations in NO and NO₂ plumes.

1 Introduction

In recent years, with the improvement of people's living standards, more and more attention is given to the improvement of the living environment. Thus the management of environmental pollution has gradually become one of the focus issues, and it is believed that the detection of pollutants is prerequisite for environmental governance. As one of the main air pollutants, NO_x ($NO_x=NO + NO_2$) is well known as one by-product of organic decay, the emission from natural forest fires, and the main anthropogenic emission from both stationary sources (electric power generation using fossil fuels) (Jaramillo and Muller, 2016) and mobile sources (motor vehicles and catalytic converters of most cars) (Carslaw, 2005). NO_x can determine the tropospheric O_3 levels and lead to the formation of photochemical "smog". Furthermore, NO_x is also known as the precursor of nitric acid (Brown et al., 2004). In addition, NO_x can do harm to the human body and animals by damaging the respiratory system and leading to pulmonary edema (Yang and Omaye, 2009). Moreover, it is believed that accurate NO_2 measurement plays a key role in accurate measurement of other species, such as organic nitrate (Thieser et al., 2016; Paul et al., 2009; Day et al., 2002) and RO_2 radicals (Chen et al., 2016).

During the last few years, many direct and indirect techniques for monitoring NO₂ have been established, such as chemiluminescence (CL) detection (Yuba et al., 2010; Sadanaga et al., 2008; Fahey et al., 1985), differential optical absorption spectroscopy (DOAS) (Platt et al., 1984; McLaren et al., 2010), tunable diode laser absorption spectroscopy (TDLAS) (Li et al., 2004), cavity ring-down spectroscopy (CRDS) (Castellanos et al., 2009; Fuchs et al., 2009, 2010; Osthoff et al., 2006; Brent et al., 2013; Hu et al., 2016), cavity-enhanced absorption spectroscopy (CEAS) (Wu et al., 2009; Gherman et al., 2008; Kasyutich et al., 2006; Wada and Orr-Ewing, 2005), cavity-attenuated phase shift spectroscopy (CAPS) (Kebabian et al., 2008), laser-induced fluorescence (LIF) (Taketani et al., 2007; Matsumi et al., 2010; Sadanaga et al., 2014; Matsumoto et al., 2001), long-path absorption photometry (LOPAP) (Villena et al., 2011) and gasbased sensing (Novikov et al., 2016), with CL being the most widely used for in situ ambient sampling. CL can achieve direct measurement of NO and indirect measurement of NO2. The method is based on the reaction between NO and O_3 , which can form an electronically excited molecule of NO2*. When NO₂* reaches the ground state, it emits fluorescence, which is proportional to the initial NO concentration. NO₂ is measured indirectly by conversion to NO firstly through heated (300 to 350 °C) molybdenum (Mo) surfaces (Ridley and Howlett, 1974) or photolytic NO₂ converters like Xenon lamps or UV-emitting diodes at specific wavelengths (320-400 nm). The CL instruments have typical NO₂ detection limits of 50 ppt min⁻¹ (1 σ) (Wang et al., 2001). By contrast, CRDS, CEAS, CAPS and TDLAS, generally relying on scanning a light source through a range of frequencies of interest, are all direct absorption techniques. It has been demonstrated that these optical methods can achieve a high detection sensitivity and the detection limit is several parts per trillion with a time resolution of several seconds (Li et al., 2004; Wild et al., 2014; Gherman et al., 2008; Kebabian et al., 2008). Among these techniques, CRDS has become a promising technique for ambient NO₂ detection due to its advantages of high time resolution, low detection limit and portability, in which pulsed (Fuchs et al., 2009) or

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continuous-wave (cw) lasers (Wada and Orr-Ewing, 2005) were utilised. Wada and Orr-Ewing (2005) demonstrated a cw diode CRDS system operating at 410 nm for the retrieval of NO₂ mixing ratios in ambient air with a detection limit of 0.1 ppb in 50 s at atmospheric pressure. Osthoff et al. (2006) constructed a pulsed cavity ring-down spectrometer where a pulsed (20-100 Hz, up to 25 mJ) frequency-doubled Nd: YAG laser was used for the simultaneous measurements of NO₂, nitrate radical (NO₃), and dinitrogen pentoxide (N_2O_5) in the atmosphere, and the detection limit of 40 ppt (1σ) for 1 s data was achieved for NO2 with an uncertainty within $\pm 4\%$ under laboratory conditions. Fuchs et al. (2009) used a simple, lightweight, low-power, and commercially available Fabry-Pérot (FP) diode laser with a centre wavelength of 403.96 nm as a light source to detect NO and NO₂ in two separate channels. The limit of detection is 22 ppt (2σ precision) for NO₂ at 1 s time resolution. Karpf et al. (2016) used a high-power, multimode Fabry-Pérot (FP) diode laser with a broad wavelength range ($\Delta \lambda_{\text{laser}} \sim 0.6 \text{ nm}$) to excite a large number of cavity modes, thereby reducing the susceptibility of the detector to vibration and making it well suited for field deployment. A sensitivity of 38 ppt was achieved using an integration time of 128 ms for single-shot detection in their work. To evaluate the uncertainty and the accuracy of the aforementioned individual instruments, a number of intercomparison studies have been carried out (Xu et al., 2013; Dunlea et al., 2007; Villena et al., 2012). The comparison results show that the method based on Mo converters can be affected by significant interferences such as N₂O₅, HONO, HNO₃, PAN, etc., whereas the method based on optical absorption is relatively immune to interferences. Therefore, direct techniques are considered to be more reliable methods than the CL method for the measurement of NO₂ and have been adopted gradually in field experiments (Ayres et al., 2015; Wagner et al., 2013; Sobanski et al., 2016).

In addition to the direct measurement of NO with the CL method, NO concentrations can also be measured directly based on their absorption feature at $1585.282 \,\mathrm{cm}^{-1}$. For example, a tunable infrared laser differential absorption spectroscopy (TILDAS) instrument based on an infrared distributed feedback (DFB) laser emitting sequentially at 1600 and $1900 \,\mathrm{cm}^{-1}$ has been used by Jagerska et al. for the measurement of NO and NO₂ (Jagerska et al., 2015), where an astigmatic multi-pass Herriott cell (Herndon et al., 2004) and a dual-wavelength spectrometer are utilised. The 1 s precision for NO measurement of the TILDAS instrument was 550 ppt, whereas that for the field experiments was 1.5 ppb. Compared with the CL method, it seems that this technique may suffer from low detection sensitivity. Given the rapid changes of nighttime oxidation, i.e. NO₃ radical, the rapid changes of its precursors NO and NO₂ are thus a prerequisite for developing a nighttime atmospheric chemistry model. To achieve high sensitivity and high resolution, conversion to NO_2 by adding excess O_3 may be one of the best methods for NO detection (Fuchs et al., 2009; Wild et al., 2014).

The developments of different technologies provide the potential for NO_x measurements on different platforms such as ground sites, vehicles and aircraft (Yamamoto et al., 2011; Wagner et al., 2011; Castellanos et al., 2009). Due to the rapid economic growth in 2000-2010, China has become the second largest economy in the world. With the rapid growth of energy consumption, NO_x emissions are increasing. Motor vehicles are one of the major sources for NO_x , especially in urban areas (Westerdahl, 2008). Exhaust from on-road vehicles makes up 20 % of total NO_x emissions in China (Shi et al., 2014). So various methods have been used to measure the vehicle emissions to assess exposure to air pollutant and specifical impacts due to traffic-related emissions (Vogt et al., 2003; Carslaw and Beevers, 2004; Herndon et al., 2005; Lal et al., 2005; Burgard et al., 2006a, b; Hueglin et al., 2006; Wild et al., 2017). However, the measurements were usually carried out at several fixed locations in large cities, which is not adequate to show the large scale patterns of the cities. Hence, a direct on-road mobile instrument is needed to obtain the spatial and temporal variations in NO_x pollutants.

In this work, a dual-channel CRDS system has been developed based on the chemical conversion of NO to NO₂, which realises the simultaneous measurement of NO₂ and NO_x. In one channel, only ambient NO₂ is measured. In another channel, the sum of ambient NO₂ and the converted NO₂ from ambient NO is determined to provide a direct measurement of NO_x . Then the difference of the two channels provides a direct measurement of NO. To assess the accuracy of the dual-channel CRDS instrument, contrast measurements and comparison were conducted between the dual-channel CRDS instrument and other instruments. In addition, the instrument was deployed in the measurement of on-road vehicle emission plumes in the city of Hefei, China, on 17 December 2018 and 25 February 2019. The main advantages of this instrument compared with CL instruments are its low detection limit and high sensitivity as well as its potential ability for trace measurements without calibration and interferences.

2 Setup of the instrument

Due to its high detection sensitivity, cavity ring-down spectroscopy has been applied to measurement NO₃ radical and N₂O₅ in our group (Wang et al., 2015; Li et al., 2018a, b). In this work, the technique was applied to measure NO₂ and NO simultaneously. A schematic diagram of the dual-channel CRDS system developed in the present work is shown in Fig. 1. The instrument mainly consists of two identical cavities for NO₂ and NO_x detection, a gas handling system, a NO convertor and an activated carbon device for NO_x removal.

2.1 CRDS systems

A blue diode laser is used as the light source and the wavelength of the laser is monitored in real time by a spectrometer. The output of the diode laser, with a centre wavelength at 403.64 nm and a line width of 0.5 nm, is directly modulated by a square wave signal (on/off) at a repetition of 2 kHz with a duty cycle of 50%. And generally the output power is about 60 mW. The laser beam first passes through an isolator to prevent the reflected light back into the laser cavity, is then divided into two approximately equal beams after a 50/50 beam splitter and enters into two identical cavities separately. Each optical cavity is made of an aluminum tube with an inner diameter of 9.4 cm, which is fixed rigidly by a separate frame. Two high-reflectivity mirrors are held in stable, adjustable mounts. The distance between the two highly reflective mirrors (LGR, 1 in diameter, 1 m radius of curvature) in each channel is 75 cm, which corresponds to the ringdown time constants of 22.90 and 24.12 μ s for NO_x and NO₂ cavities in zero air. The light emitted through the back mirror of the cavity passes through a narrowband filter to filter stray light, and then is directed into a photomultiplier tube (PMT). The signal is amplified firstly, then acquired with a digital acquisition card (NI USB-6361, 16-bit, 2.0 Ms s^{-1}). The sampling frequency for each digital acquisition card is 1 MHz. During a continuous 1.0 s data acquisition period, 2000 decay traces are transferred to the PC using a single transfer command and averaged to get a fitted decay trace at a laser modulation rate of 2 KHz. NO₂ concentrations can be calculated according to Eq. (1) from the ring-down times, τ and τ_0 , the ring-down times when the NO₂ is in the presence and absence of the cavity, respectively; the NO₂ absorption cross section, $R_{\rm L}$, is the ratio of the total cavity length to the length over which the absorber is present in the cavity, and c is the speed of the light.

$$[NO_2] = \frac{R_L}{c\sigma_{NO_2}} \left(\frac{1}{\tau} - \frac{1}{\tau_0}\right)$$
(1)

2.2 NO convertor

NO is measured by its conversion to NO_2 in the presence of excess O_3 . The principle is based on the following chemical equation (Sander et al., 2006).

$$NO + O_3 \rightarrow NO_2 + O_2 \ k_1, \tag{R1}$$

where $k_1 = 3.0 \times 10^{-12} \exp(-1310/T) \text{ cm}^3 \text{ molec.}^{-1} \text{ s}^{-1}$. Ozone is produced from O₂ photolysis at 185 nm by flowing 100 sccm (standard cubic centimetres per minute) of sampling air over a low-pressure discharge mercury lamp. The mercury lamp is inset into a quartz glass tube with a length of 50 mm and an inner diameter of 10 mm. The flow rate passing through the mercury lamp was controlled by a mass flowmeter controller (MFC) and the resulting mixing ratio of O₃ was detected by an O₃ analyser (49i, Thermo



Figure 1. Schematic of the dual-channel cavity ring-down spectroscopy system.



Figure 2. Cross section of the NO₃ radical, NO₂, O₃, water vapour and diode laser spectrum.

Scientific). The O_3 concentration is approximately 11.2 ppm after mixing with the sampled air. A Teflon tubing (length 1 m, i.d. 3.8 mm) serves as a reactor for the NO conversion.

2.3 Activated carbon device

Accurate measurement of the ring-down time, τ_0 , when there is not any absorber in the cavity, is pivotal for accurately retrieving the absorber concentration in a practical measurement as well as for checking the cleanliness of the cavity mirrors. Usually zero air or chemical scrubber is used to acquire zeros (Wada and Orr-Ewing, 2005). In our system, zeros are obtained by passing sampled air through an activated carbonfilled tube with a length of 26.0 cm and an outer diameter of 6.0 cm. The τ_0 is measured for 60 s every 10–16 min. It is found that this frequency of zero measurements is sufficient to track drifts in zero ring-down time constant measurements, i.e. the fluctuation of τ_0 is less than 0.1 % for 15 min intervals.

2.4 Gas handling system

The gas handling system of the instrument consists of a sampling module and a purge flow. The sampled air initially flows through a filter device, where a filtering membrane (1 µm pore size) is loaded to prevent light-scattering aerosols from entering the cavity. And subsequently it will pass through the activated carbon device to provide the background measurement or enter the PFA tube directly just depending on whether the three-way solenoid valve is open or closed. After the PFA tube, the air flow is divided into three lines. The first flow (100 sccm) is introduced into a quartz flow tube equipped with a mercury pen-ray lamp (Oriel 6035) to generate O₃ by air photolysis as mentioned, then it will be merged with the second sampling flow (900 sccm) and pulled into the NO_x cavity. The third one with a flow rate of 1 slm (standard litres per minute) is directed into the NO₂ cavity. The whole system is pumped by a rotary pump (K86KNE) and the flow rates of the different lines are controlled by mass flow controllers separately. To prevent the degradation of the mirror reflectivity, each mirror is continuously flushed with high-purity nitrogen at a rate of $25 \,\mathrm{mL}\,\mathrm{min}^{-1}$ to avoid the potential pollution from the sample flow.

3 Results and discussion

3.1 Determination of absorption cross sections

To retrieve the gas concentration, it is prerequisite to determine the effective absorption cross section at peak absorption of the laser. The output waveforms of the laser, with a centre wavelength of 403.64 nm and full width at half maximum of 0.5 nm, was monitored by a spectrometer (QEPB0828) (red line shown in Fig. 2). The centre wavelength selected can cover the strong absorption of NO₂ and avoid the interference from other species, such as H₂O (pink line in Fig. 2). The effective absorption cross section was determined to be 5.63×10^{-19} cm² molecule⁻¹ by convoluting the NO₂ absorption cross section with the laser spectrum (blue line in Fig. 2) using Voigt profile (Voigt et al., 2002). It is well known that a shift in the laser centre wavelength would re-



Figure 3. Different cavity ring-down signals and fitting results in the absence and presence of NO_2 . The small figure in the upper right corner is the fitting residual.

sult in a change in the effective NO₂ cross section, so the laser output was monitored as the index of the day-to-day variability of the laser centre wavelength. It was shown that the variability is less than 1% during the few experiment days. The largest uncertainty of the absorption cross section is about 3% according to Voigt (Voigt et al., 2002).

3.2 The retrieval of $R_{\rm L}$

Due to the purge gas to the mirrors, the R_L value cannot be simply determined by the ratio of the distance between two mirrors to that between the inlet and outlet. The R_L value of the system was determined from the absorption measurement of various concentrations of NO₂ ranging from 20 to 70 ppb with or without purge flow. The ratio of the two extinction measurements yielded a R_L value, which is independent of the cross section and the concentration of NO₂. The R_L value is determined to be 1.10 ± 0.03 for both the NO_x and NO₂ channels.

3.3 The retrieval of τ_0

In order to accurately determine the concentrations of trace gases by CRDS, it is very important to confirm background cavity loss measurements of τ_0 when the target gases are not inside the cavity. Several alternative background measurement methods have been reported, where various kinds of air were used as background gas, such as zero air, a mixture of oxygen and nitrogen, chemically scrubbed laboratory air (using hydroxyapatite), and laboratory air sampled through the stainless-steel tubing coil (Wada and Orr-Ewing, 2005). In our instrument, an activated carbon device was used for background measurement. The ring-down times when the sampled air pass through the activated carbon device were determined to be 24.12 ± 0.01 and 22.90 ± 0.01 µs in two cavities,



Figure 4. (a, b) Continuous time series measurement when the instrument sampled only zero air, averaged to 1 s for NO₂ and NO_x channels (black dots); the red dots show the data averaged to 30 s. (**c, d**) Allan deviation plots for NO₂ concentration in two channels. The minimum value equals the optimum integration time.

respectively. These values are close to those of measurements of zero air at the same sample rate for a 15 min period.

Two representative ring-down signals corresponding to with and without NO₂ in the cavity for the CRDS system are shown in Fig. 3. And the fitted ring-down times were 24.12 and 20.30 μ s, so that the NO₂ concentration is determined as 20.28 ppb using the constants determined above.

3.4 Detection limit and measurement accuracy of two cavities

The measurement precision of the dual-channel CRDS instrument for NO₂ and NO_x detection was investigated with time series measurement of zero air (Fig. 4). The acquisition time for the spectral data was 1.0 s with an average of 2000



Figure 5. O_3 mixing ratio when the bypass flow passing through the Hg lamp changes.

spectra. In order to analyse the stability of the instrument, the Allan variance had been calculated for the intensity measurements. For the two channels, the 1σ detection limits were 30 and 40 ppt (1 s) for the NO₂ and NO_x channels, respectively. The minima in the Allan plots indicated that the optimum average times for optimum detection performance (Fig. 4c, d) is about 30 s. With 30 s integration time, the 1σ detection limits were 16 and 14 ppt for the NO₂ and NO_x channels, respectively.

The minimum detection can be written as follows:

$$[A]_{\min} = \frac{\sqrt{2R_{\rm L}}}{c\sigma} \left(\frac{\Delta\tau_0}{\tau_0^2}\right). \tag{1}$$

For continuous zero NO₂ measurements, the $\Delta \tau_0$ was 0.008 µs in both NO_x and NO₂ channels and τ_0 was 22.90 and 24.12 µs in NO_x and NO₂ channels, respectively, for 1 s averaging. Given the $R_{\rm L}$ value to be 1.10 and σ to be 5.63 × 10⁻¹⁹ molec. cm⁻², the 1 σ minimum detection limits for the NO_x and NO₂ channels were determined as 39 and 35 ppt, respectively, at an integration time of 1 s, which are close to the Allan variance analysis described above.

The total uncertainty of NO₂ measurement by CRDS is expected to be from the uncertainties on the measurement of the R_L and NO₂ absorption cross section. The uncertainty in R_L was determined to be less than 3 %, and the uncertainty in the NO₂ absorption cross section was about 4 %, so the total uncertainty of NO₂ measurement was estimated to be 5 % for the system in this work.

Compared with the existing field measurement techniques for NO_2 measurements, it seems that the minimum detection and uncertainty of this instrument are superior to the other methods (see Table 1).

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3.5 NO conversion efficiency

The main influence factor on the NO conversion efficiency is the flow rate passing through the mercury pen-ray lamp as it can determine the generated O_3 concentration. The mixing ratio of O_3 in the NO_x channel line was investigated, which changes with the flow rate that passes through the mercury pen-ray lamp. The result is shown in Fig. 5. As a result, the bypass flow passing through the Hg lamp was determined to be 100 sccm. Under this flow rate, when the residence time of O_3 in the cavity is 1 s and the ambient NO₂ concentration is 50 ppb, NO conversion efficiency with different NO concentrations (10–1000 ppb) was simulated and NO conversion efficiency in the range of experimental concentrations is larger than 98 %.

Because the cross section of O_3 is about 4 orders of magnitude smaller than that of NO₂ at the centre wavelength of the laser, the absorption of O₃ generated by mercury photolysis is negligible. According to Fuchs et al. (2009), under conditions when NO is rich, further oxidation of NO₂ to NO₃ and N₂O₅ has only a slight effect on NO_x measurement, which means that the correction of the NO_x measurement can be neglected. However, under conditions when NO is absent, the loss of NO₂ due to oxidation by high concentration of ozone is indeed one of the main factors that is attributed to the errors in the NO_x channel. The reaction equation is expressed as follows:

$$NO_2 + O_3 \rightarrow NO_3 + O_2 \quad k_2, \tag{R2}$$

$$NO_3 + NO_2 \leftrightarrow N_2O_5 \ k_{eq},$$
 (R3)

where $k_2 = 1.2 \times 10^{-13} \exp(-2450/T) \text{ cm}^3 \text{ molecule}^{-1} \text{ s}^{-1}$ (T = 298 K, $k_2 = 3.2 \times 10^{-17} \text{ cm}^3 \text{ molecule}^{-1} \text{ s}^{-1}$) (Sander et al., 2006) and $k_{eq} = (5.1 \pm 0.8) \times 10^{-27}$ $\exp(10871/T)$ cm³ molecule⁻¹ $T = 298 \,\mathrm{K},$ $k_{eq} =$ $3.5 \times 10^{-11} \text{ cm}^3 \text{ molecule}^{-1}$) (Osthoff et al., 2007). The loss rate will increase with the increase in the $NO_2 + O_3$ reaction rate constant when temperature in the cavity increases. Moreover, the loss rate is also sensitive to the NO₂ mixing ratio. Diluted NO2 standard mixture was introduced into the two channels to characterise the effect of high ozone on NO2 measurement. The NO2 concentrations in the two channels and their correlation are shown in Fig. 6. The interference of O_3 in the NO_x channel when NO is absent can be neglected. The discrepancy between two different channels may be the result of the systematic errors in two different channels and can be corrected with the coefficient obtained from Fig. 6b.

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Principle of measurement	Laser power	Wavelength range/nm	Detection limit	Reference
Cw-CRDS	5 mW (1 MHz)	410	80 ppt/50 s (1σ)	Wada and Orr-Ewing (2005)
Nd:YAG laser CRDS	1 mJ	532	40 ppt/1 s (1 σ)	Osthoff et al. (2006)
pDL-CRDS	40 mW (2 KHz - 10 %)	404	11 ppt/1 s (1 σ)	Fuchs et al. (2009)
Fabry–Pérot (FP) pDL-CRDS	1.1 W (4 KHz – 10 %)	400	$38 \text{ ppt/}12 \text{ ms}(1\sigma)$	Karpf et al. (2016)
Commercial DL-CRDS	1.2 KHz	407.38	$20 \text{ ppt/}60 \text{ s} (1\sigma)$	Castellanos et al. (2009)
LED-based commercial CRD	355 mW	397-412 (405)	27 ppt/60 s (1σ)	Brent et al. (2013)
LED-CEAS	340 mW	455	$2.2 \text{ ppb}/100 \text{ s} (1\sigma)$	Wu et al. (2009)
Xe lamp DOAS		295–492 nm	1 ppb/480 s (1 σ)	McLaren et al. (2010)
CAPS		440	$20 \text{ ppt/}10 \text{ s} (1\sigma)$	Kebabian et al. (2008)
Diode-pumped Nd:YAG laser-LIF	15 mW (14 KHz)	473	$70/60 \mathrm{s} (1\sigma)$	Taketani et al. (2007)
Blue LED-IF	17.7 mW (10 KHz)	435	4.9 ppb/60 s (1σ)	Matsumi et al. (2010)
Pulsed blue light LED-LIF	22 mW	430	$3.5 \text{ ppb/60 s} (1\sigma)$	Sadanaga et al. (2014)
pDL-CRDS	60 mW	403.64	$30 \text{ ppt/l s} (1\sigma)$	This work

Table 1. Comparison of NO_2 detection limits based on optical methods.

CRDS: cavity ring-down spectroscopy; CEAS: cavity-enhanced absorption spectroscopy; BB: broadband; DOAS: differential optical absorption spectroscopy; cw: continuous-wave diode laser; LIF: laser-induced fluorescence; CAPS: cavity-attenuated phase shift spectroscopy; pDL: pulsed diode laser.



Figure 6. (a) Time series of NO_2 concentration standard mixtures sampled by the CRDS instrument in two channels with mercury pen-ray lamp switched on. (b) A correlation plot between the data from two channels.



Figure 7. (a) Time series of NO₂ concentration standard mixtures sampled by the CRDS instrument and CL analyser. The time resolution for the CRDS instrument and CL analyser are 1s and 1min, respectively. (b) A correlation plot between the data from the CRDS instrument and the CL analyser (data averaged to 1 min). The fitting result gave a gradient of 1.031 and an intercept of -0.940 ppb, with a linear correlation factor of 0.99.



Figure 8. (a) NO₂ mixing ratios by CEAS (1 min average) and CRDS (1 s average) instruments. (b) Scatter plots for the NO₂ dataset from CRDS and CEAS instrument. The red lines illustrate the linear regression (data averaged to 1 min base).



Figure 9. (a) Time series of NO by dual-CRDS instrument and CL analyser. (b) A correlation between two instruments is shown and data for correlation analysis are averaged in 1 min.



Figure 10. The diagram of the movable van loaded with the CRDS instrument.

4 Field applications

4.1 Contrast measurement of standard mixtures of NO and NO₂

The comparisons of NO₂ measurements between CRDS and the NO_x analyser have been carried out on NO₂ standard mixtures. Different mixing ratios of NO₂ were obtained by gas-phase titration of NO with excess O₃ generated by an ozone generator (OC500). The 10.3 ppm NO standard mixture was initially diluted by N₂ and subsequently oxidised by O₃. The amount of NO₂ generated from excess ozone can be calculated from the known initial concentration of NO. The generated pure NO₂ standards in clean air were in the concentration range of 20–70 ppb. The CL analyser used for comparison in this laboratory experiment was separately calibrated and the linearity of this instrument was checked using a mixture containing NO. Figure 7a shows the concentrations of the standard NO₂ in the laboratory measured by CRDS and a commercial CL analyser (42i, Thermo Scientific, Inc., 0.4 ppb (1 σ) detection limit) simultaneously. A correlation analysis between the data from the two instruments was carried out. The fitting results shown in Fig. 7b indicate that NO_{2(CRDS)} = NO_{2(CL analyser)} × 1.031 – 0.940, with a linear correlation factor (R^2) of 0.99. The results in Fig. 7a also indicate that the CRDS instrument can capture the NO₂ variations more rapidly than CL analyser.

4.2 Ground-based measurements of NO₂ and NO

To verify its performance and applicability, the dual-channel CRDS instrument was further compared with a CEAS instrument (Duan et al., 2018) on ground-based measurement of NO₂ during the period from 3 to 5 November 2017 in the



Figure 11. Results of the NO_x (a), NO₂ (b) and NO (c) concentrations around Hefei, China (data are averaged to 5 s).

western suburb area of Hefei, Anhui, China. The reason why the CEAS instrument not the CL analyser was selected for NO₂ intercomparison is that for CL analyser, NO₂ must be converted to NO first and then can be detected, which exposes the analyser to chemical interferences, while for the CEAS instrument, NO₂ can be detected directly. Measurement precision (1σ) for NO₂ is about 170 ppt in 30 s. The time resolutions of the CRDS and CEAS instruments are 1 s and 1 min, respectively. The CRDS and CEAS instruments were set up on the sixth floor of the building in the Anhui Institute of Optic and Fine Mechanics. The area lies to the northeast of the Dongpu reservoir and is about 1.5 km from the reservoir. The northwest of the area is surrounded by a forest. The significant NO₂ pollution during the measurement was found to be the emission of the cars along the road (100 m radius). The air originating from the sector between the south and east (5 km) may bring anthropogenic emissions to the site. Ambient air was introduced into the instruments through a 6 mm outer diameter Teflon tube. The data for comparison were averaged to 1 min. Figure 8a shows the temporal variations in NO₂ concentrations measured by the CEAS and the CRDS instruments. It was found that the nighttime NO_2 was in the range of 3 to 35 ppb. Generally, the NO₂ concentrations and variations measured by the CRDS instrument show good consistency with those measured by the CEAS instrument, and the slope and intercept of the regression line from the least-squares analysis are 1.042 ± 0.002 and (-0.393 ± 0.040) ppb, respectively, as shown in Fig. 8b. However, the results revealed a discrepancy when rapid NO₂ variations appeared. We attribute this discrepancy to the slight difference between the two inlets of the instruments when large NO₂ was rapidly emitted into the atmosphere. In general, the CRDS instrument has substantive advantages for retrieving rapid variations in NO₂ plums due to its high time resolution and high sensitivity.



Figure 12. The 4 h drive around Hefei, China, coloured by the measured NO (**a**) and NO₂ (**b**) concentrations, respectively.

The comparison of NO concentrations measured by the dual-channel CRDS instrument and CL analyser was conducted under a variety of sampling conditions for a total of 7 d at the site described previously. Both instruments were attached to the same air sample inlet. The datasets from the CRDS instrument and CL analyser were highly correlated over wide concentration ranges of NO (see Fig. 9a). Figure 9b shows the relationship between NO concentrations observed by the CRDS and CL methods. The slope and intercept of the regression line were 0.959 ± 0.007 and 0.352 ± 0.013 ppb. The correlation coefficient is $R^2 = 0.99$. As the CL method is believed to be reliable for NO measurement, the reliability of the dual-channel CRDS instrument was validated for the measurement of NO.

4.3 On-road measurements of vehicle NO₂/NO_x emission

In order to retrieve the vehicle emissions on road, field measurements were performed in Hefei from 15:00 to 16:00 CST on 17 December 2018. The CRDS instrument was powered

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by a lithium battery, and ambient air was pumped into the system though an inlet fixed on the roof of the car. The vehicle speed is about $50 \,\mathrm{km} \,\mathrm{h}^{-1}$. In order to obtain the discrepancy of vehicle emissions in urban and suburban areas, the car travels around the whole area. Figure 10 shows a picture of the movable van loaded with the CRDS instrument, and the position of the sampling inlet is about 1.5 m above the ground. Figure 11 illustrates the route in Hefei and the drive track is coloured logarithmically with respect to measured NO_x , NO_2 and NO. The NO_2 concentration ranged from 1.5 to 133.3 ppb and NO ranged from the detection limit to 554.7 ppb. The mean concentrations of NO and NO₂ were 140 and 54.9 ppb, respectively. On the whole, the NO and NO₂ concentrations in the urban area were higher than those in the suburban area. Large plumes of NO were found at the crossroads with heavy traffic or the sites converged with heavy-duty diesel vehicles. The $[NO_2]/[NO_x]$ ratio was about 19%, which is larger than the results observed in the USA (Wild et al., 2017).

In 25 February 2019 another measurement of vehicle emissions was performed on the road to further verify the instrument performance. A NO analyser (42i), an O₃ analyser (49i) and the CRDS instruments were all placed in the same car. Ambient air was pumped through an inlet fixed on the roof of the car and then divided into three lines to the three instruments. Figure 12 illustrates the 4 h drive track involving highway, urban and suburban area around Hefei, which is coloured with respect to the measured NO and NO₂. Vehicle speeds varied greatly on three different road types and were around 100 km h⁻¹ on the highway. Influenced by the vehicle emissions, the NO_x plumes on urban roads are higher than those on suburban roads and highway.

Figure 13 shows the time series of NO₂, O₃ and NO. NO₂ concentrations ranged from the detection limit to 110.2 ppb and O₃ concentrations ranged from 6.9 to 85.3 ppb. Several NO plumes were observed and the maximum value was up to 767.1 ppb. O₃ and NO showed a significant negative correlation, which is attributed to the quick titration of O₃ by NO. Figure 14 shows the NO data measured by CRDS and the CL analyser (42i, 1 min), Fig. 14a shows the data averaged to 5s for the CRDS instrument and Fig. 14b shows the data averaged to 1min for the CRDS instrument. The good agreement between the measurement results from the two instruments proves that the CRDS instrument can be applied for fast vehicle NO_x emissions.

Because the NO₂-to-NO_x emissions ratio affects ozone production and spatial distribution, more efforts should be made to provide a constraint on emissions inventories used in air quality modelling. The mobile CRDS instrument provides a good method to retrieve the direct vehicle NO_x emissions and NO₂-to-NO_x ratio of plumes due to its easy deployment and high temporal resolution.



Figure 13. Results of the NO₂, NO and O₃ concentrations around Hefei, China.



Figure 14. Time series of NO from the CRDS instrument and CL analyser (42i). (a) Data averaged to 5 s for the CRDS instrument and (b) the data averaged to 1 min.

5 Conclusions

A compact, sensitive and accurate instrument based on diode-laser cavity ring-down spectroscopy with the centre wavelength of 403.64 nm has been demonstrated for detection of trace amounts of NO₂ and NO_x in ambient air. Minimum detection limits of NO₂ and NO_x were estimated to be 0.030 and 0.040 ppb at an integration time of 1 s when zero air is sampled with a measurement accuracy of ± 5 %. Contrast measurements between the dual-channel CRDS instrument and a CL analyser on NO₂ standard mixtures were performed, which showed a good correlation between the two different techniques. In order to confirm the reliability of the dual-channel CRDS instrument in the field atmosphere, continuous measurement was conducted and the stability of the instrument was investigated. During the intercomparison measurements of NO₂ and NO in the field, the dual-channel

CRDS instrument showed a good correlation with the CEAS instrument for NO_2 measurement, and with the CL analyser for NO measurement.

The CRDS instrument was further deployed in a movable car to monitor NO and NO₂ emissions on the road. The advantage of the high time resolution of the instrument has been demonstrated, which means the instrument provides a new direct method for on-road vehicle plume measurement. Meanwhile, the high detection sensitivity of the instrument was also shown in this work, which indicates it can act as a new detection technique for chemistry model verification. It is expected that the instruments developed will lead to the wider application for ambient air quality monitoring and will be useful to investigate photochemistry in the atmosphere more precisely.

Data availability. The data used in this study are available from the corresponding author upon request (rzhu@aiofm.ac.cn).

Author contributions. RH and ZL contributed equally to this work. RH, PX, JL and WL contributed to the conception of the study. ZL and HC built the CRDS instrument. ZL, HC, XL, SL, FW, YW and CL performed the experiments. DW developed the data processing software. ZL performed the data analyses and wrote the paper. RH edited and developed the paper.

Competing interests. The authors declare that they have no conflict of interest.

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