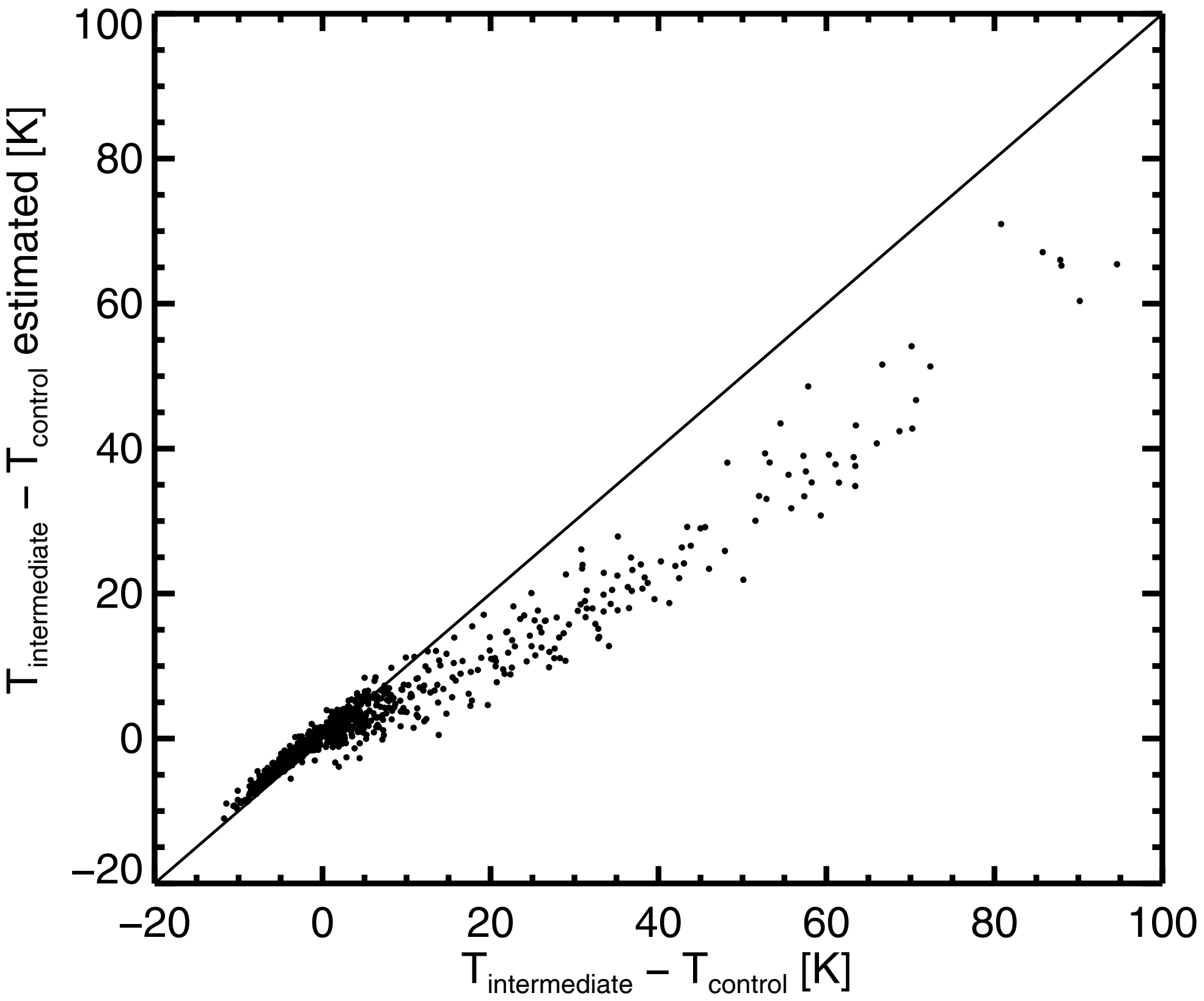
100
80
60
40
20
0
−20
−20
0
20
40
60
80
100
$T_{intermediate} - T_{control}$ estimated [K]
$T_{intermediate} - T_{control}$ [K]