

Interactive comment on “Combined wind measurements by two different lidar instruments in the Arctic middle atmosphere” by J. Hildebrand et al.

J. Hildebrand et al.

hildebrand@iap-kborn.de

Received and published: 29 August 2012

abstract: reiterate time averaging of 1 h when discussing inhomogeneity

Actually for this issue the time averaging was nearly 4 h, we will state this in the abstract.

line 7: add Tepley, 1994 to list of references

done

C1998

page 4, line 22: change “is” to “are”

done

pages 6–7: beam divergence of Na lidar greater than its field of view

we used wrong numbers: actually FOV ($600\text{ }\mu\text{rad}$) is bigger than beam divergence ($450\text{ }\mu\text{rad}$).

page 4, line 17 and page 7, line 13: confusing symbols for frequency (ν) and wind velocity (v)

we will use f for frequency

page 7, line 16: record length 33 s instead of 33 ms

done

page 9, third paragraph: clearer writing

We revised this section seriously. The wind and temperature dependence of Doppler ratio (including Fig. 5) is now discussed in Sect. 2.1. This allows us to shorten the discussion in Sect. 4.1.

page 10: introduction of ECMWF

included in manuscript: “The European Center for Medium-Range Weather Forecasts (ECMWF) provides an operational forecast model (Integrated Forecast System, IFS) which assimilates real data. We use IFS version Cy35r1, T799, extracted for 69.28°N , 16.01°E .”

C1999

page 10, lines 20–24: is this paragraph needed?, typo

This paragraph is needed, it mentions shortly why we use another method of calibration.

Changed “this” to “that”.

page 11, line 3: typo (change “were” to “where”)

done

page 12, line 20: better word for “wrong”

changed to “inaccurate”

page 14, line 14: equation for amplitude of gravity wave

Actually we want to add an offset to the exponential growth of the amplitude. We considered also the form $\hat{u} = a \cdot \exp(z/H_{\hat{u}})$, but this was not sufficient, especially for lower altitudes. So, we used additional offsets for amplitude and altitude: $\hat{u} = a + \exp((z + b)/H_{\hat{u}})$. This form matches the data better and includes a constant scaling factor as well: $a + \exp((z + b)/H_{\hat{u}}) = a + \exp(b/H_{\hat{u}}) \cdot \exp(z/H_{\hat{u}})$.

page 14, line 17: weak conclusions

done: “we may conclude”

page 17: downward phase progressions in meridional wind at 96 to 87 and 109 to 95 km altitude might be semidiurnal tides

we included this consideration

C2000

page 17: are the authors working on a follow-up study of inhomogeneity of wind field?

This is not scheduled yet.

page 18, line 1: typo (change “looses” to “loses”)

done

page 18, line 7 typo (change “the extend of” to “the extent of”)

done

page 18, line 9 vs. page 7, line 5: comparable size of sounding volumes

Compared to much larger sounding volumes of radars (≥ 100 km at 85 km altitude) the sounding volumes of both lidars have comparable sizes (15 and 48 m at 85 km altitude). Also the separation (40 m at 85 km altitude) is quite small. Structures with smaller scales are beyond the scope since we use integration times of 1 h. We include in the manuscript: “For the applied integration time of 1 h this is fulfilled in our study: the sounding volumes of both lidars are in the order of tens of meters, separated by the same order of magnitude.”

Interactive comment on Atmos. Meas. Tech. Discuss., 5, 4123, 2012.

C2001