Retrieval of aerosol microphysical and optical properties above liquid clouds from POLDER/PARASOL polarization measurements.

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Abstract :

Most of the current aerosol retrievals from passive sensors are restricted to cloud-free scenes, which strongly reduces our ability to monitor the aerosol properties at a global scale and to estimate their radiative forcing. The presence of Aerosol Above Clouds (AAC) affects the polarized light reflected by the cloud layer, as shown by the spaceborne measurements provided by the POlarization and Directionality of Earth Reflectances (POLDER) instrument on PARASOL satellite. In a previous work, a first retrieval method was developed for AAC scenes and evaluated for biomass burning aerosols transported over stratocumulus clouds. The method was restricted to the use of observations acquired at forward scattering angles (90°-120°) where polarized measurements are highly sensitive to fine mode particles scattering. Non-spherical particles in the coarse mode, such as mineral dust particles, do not much polarize light and cannot be handled with this method. In this paper, we present new developments that allow retrieving also the properties of mineral dust particles above clouds. These particles do not much polarize light but strongly reduce the polarized cloud bow generated by the beneath liquid cloud layer and observed for scattering angles around 140°. The spectral attenuation can be used to qualitatively identify the nature of the particles (i.e. accumulation mode versus coarse mode, i.e. mineral dust particles versus biomass burning aerosols) whereas the magnitude of the attenuation is related to the optical thickness of the aerosol layer. We also use the polarized measurements acquired in the cloud bow to improve the retrieval of both the biomass burning aerosol properties and the cloud microphysical properties. We provide accurate polarized radiance calculations for AAC scenes and evaluate the contribution of the POLDER polarization measurements for the simultaneous retrieval of the aerosol and cloud properties. We investigate various scenes with mineral dust particles and biomass burning aerosols above clouds. For clouds, our results confirm that the droplets size distribution is narrow in high latitude ocean regions and that the droplets effective radii retrieved from both polarization measurements and from total radiance measurements are generally close for AAC scenes (departures smaller than 2 µm). We found that the magnitude of the primary cloud bow cannot be accurately estimated with a plane parallel transfer radiative code. The errors for the modelling of the polarized cloud bow are between 4 and 8 % for homogenous cloudy scenes, as shown by a 3D radiative transfer code. These effects only weakly impact the retrieval of the AOT performed with a mineral dust particles model for which the microphysical properties are entirely known (relative error smaller than 6%). We show that the POLDER polarization measurements allow to retrieve the Aerosol Optical Thickness (AOT), the fine mode particles size, the Ångström exponent and the fraction of spherical particles. However, the complex refractive index and the coarse mode particles size cannot be accurately retrieved with the present polarization measurements. Our complete and accurate algorithm cannot be applied to process large amounts of data, so a simpler algorithm was developed to retrieve the Aerosol Optical Thickness (AOT) and the Ångström exponent above clouds in an operational way. Illustrations are provided for July-August 2008 near the Africa coast. Large mean AOTs above clouds at 0.865 μ m (> 0.3) are retrieved for oceanic regions near the coasts of South Africa that correspond to biomass burning aerosols whereas even larger mean AOTs above clouds for mineral dust particles (> 0.6) are also retrieved near the coasts of Senegal. For these regions and time period, the direct AAC radiative forcing is likely to be significant. The final aim of this work is the global monitoring of the AAC properties and the estimation of the direct aerosol radiative forcing in cloudy scenes.

1- Introduction

Aerosols directly affect the climate of the Earth by interacting with the solar and thermal infrared radiations. These atmospheric particles scatter the sunlight and reflect a part of it back into space. This effect is called the "direct aerosol effect" and cools the Earth's surface. By absorbing the solar light, absorbing aerosols further cool the surface but also warm the corresponding layer of the atmosphere where they reside. This may modify the vertical profile of temperature in the atmosphere, which affects the process of evaporation and cloud formation (Ackerman et al., 2000). This so-called "semi-direct aerosol effect", is currently not well quantified and might partially compensate for the aerosol direct effect at regional scale (Ramanathan et al., 1991). By acting as cloud condensation nuclei, these particles also have significant effects on the cloud microphysical properties (Bréon et al., 2002). Increasing aerosol concentrations results in an increase of cloud condensation nuclei, which can eventually cause a decrease in cloud droplets size; both effects leading to an increase in cloud reflectivity (Twomey, 1977). This process is called the first "aerosol indirect effect" and contributes to cool the Earth atmosphere system. The reduction in cloud droplet size might also modify cloud lifetime and change precipitation efficiency (Rosenfeld, 2000). This process is referred as the second aerosol indirect effect. Only the direct effect and the first indirect effect are currently quantified at a global scale with a level of knowledge qualified as medium and poor, respectively, according to the IPCC (2007).

In order to better understand the role of the aerosols on the Earth's climate, the spatial and temporal variability of their concentrations and microphysical properties have to be accurately measured and modelled. The aerosol microphysical properties are the particle size distribution, shape and composition. The aerosol size distribution is typically bimodal with a coarse and a fine modes (i.e. or accumulation mode). Fine mode particles are associated with size ranging between roughly 0.06 and 0.6 µm whereas coarse mode particles are larger than 0.6 µm (in radius). The aerosol microphysical properties exhibit a high variability at global scale since these particles are produced by various processes and sources and also because their properties evolve along the transport process in the atmosphere. Anthropogenic aerosols can be directly emitted in the atmosphere (e.g. pollutants particles from industrial activities or biomass burning aerosols from man-made vegetation fires) or result from the conversion of anthropogenic gas into particles (e.g. sulphate aerosols). Most of them are in the accumulation mode. Natural processes also generate aerosols, as for instance, the mineral dust particles and the maritime aerosols (i.e. sea salt), which result from the mechanical action of the wind on the desert and ocean surfaces, respectively. Other natural aerosols include volcanic dust aerosols, pollens and ashes from wild vegetation fires. Natural aerosols mainly contribute to the coarse mode with the mineral dust particles being the major contributor to the total amount of natural aerosols present in the troposphere (Kaufman et al., 2002).

Biomass burning fires aerosols are usually injected at high altitude in the atmosphere (> 6 km) and can be transported over considerable distance and sometimes above clouds. Manmade vegetation fires are frequent in South Africa between June and September (Tanré et al., 2001). Smoke plumes are uplifted above the continent at high altitude and, because of local meteorological conditions, transported primarily toward the west over the Atlantic Ocean. Persistent decks of low-level stratiform cloud usually cover this part of the Atlantic Ocean

during the same time period and the transport of biomass burning aerosols above clouds is frequent in this region. The transport of Saharan mineral dust is also frequent across the Atlantic and dust plumes are regularly transported above low-level clouds off the coasts of Senegal (Haywood et al., 2003a). Other types of aerosols such as volcanic dust particles and pollutant particles (Hsu et al., 2003, Coddington et al., 2010) were also observed above clouds in other regions of the world. The most common observed situation corresponds to an elevated aerosol layer suspended above a low-level liquid water cloud but Aerosol Above Clouds (AAC) properties have not been extensively studied yet. Biomass burning aerosols have strong absorption properties due to their high concentration in black carbon (Haywood and Boucher 2000). When located above a cloud, high absorbing particles reduce the brightness of the scene (i.e. the cloud albedo), which causes a local positive radiative forcing that contributes to locally warm the Atmosphere. If regional studies of the AAC radiative forcing were achieved (Chand et al., 2009, Peters et al., 2011, De Graaph et al., 2012). However, this forcing is currently not constrained at a global scale, which explains that the estimation of the direct effect of biomass burning aerosols remains currently poorly estimated (Forster et al., 2007). The presence of biomass burning aerosols above clouds may also affect the dynamical evolution of clouds (Johnson et al., 2004). The induced effects could be a reduction in cloud top altitude and a cloud thickening that might result in an enhancement of the cloud albedo (Wilcox et al., 2010).

In order to better quantify the aerosol radiative forcing in case of Aerosol Above Cloud (AAC) scenes, an accurate knowledge of the properties (primarily load, absorption and size) of the aerosols located above the clouds is required. These properties allow estimating the aerosol optical parameters and their spectral dependence that controls the aerosol radiative forcing. The first optical parameter to be determined is the Aerosol Optical thickness (AOT) that is a measure of the radiation extinction due to particles scattering and absorption, integrated over the atmospheric column. Another important aerosol parameter for determining the sign (cooling or warming) of the effect over bright target is the aerosol Single Scattering Albedo (SSA). To estimate the aerosol radiative forcing (which is the radiative effect due to human activities), the nature of the particles must be identified (natural of anthropogenic), which requires the knowledge of the particles microphysics together with some information on their geographical origin. It is also required to determine the cloud albedo (Keil and Haywood, 2003), and to a lesser extent the respective vertical profiles of the aerosol and cloud layers.

Passive remote sensing by satellite provides observations at a global scale and on a daily basis and therefore constitutes a well-suited tool for aerosol (and cloud) monitoring (Kaufman et al., 2002). However, most of the current passive remote sensing techniques relies on the use of cloud-screening algorithms before retrieving the aerosol properties. This limits our ability to estimate the aerosol direct effects only to cloud-free scenes and restricts our capacity to estimate the total amount of aerosols. Furthermore, the presence of aerosols above clouds can also affect the accuracy of cloud properties retrievals performed from satellite passive sensors, which in turn may perturb the estimation of aerosols indirect effect (Haywood et al., 2004).

The detection of aerosols in cloudy scenes constitutes a new field of research in remote sensing. For passive remote sensing techniques, using total radiance measurements, the challenge is to derive the aerosol contribution while the cloud contribution is much larger. Innovative methods based on the use of spectral radiance measurements were however developed and evaluated for some case studies. The approach described in De Graaf et al., (2007) uses measurements provided by the SCanning Imaging Absorption spectroMeter for Atmospheric CartograpHY (SCIAMACHY) instrument in a continuous broad spectral range

 $(0.28-1.75 \ \mu\text{m})$ to estimate the AOT and the aerosol SSA, under some assumptions made on the aerosol and cloud microphysical and optical properties. The method described by Torres et al., (2012) uses measurements provided by the Ozone Monitoring Instrument (OMI) radiometer in two Ultraviolet (UV) channels to simultaneously retrieve the aerosol and cloud optical thicknesses. Both methods require assumptions on the microphysical properties of the particles. Before retrieving the AOT, the two methods rely on the use of an aerosol index to qualitatively detect the presence of UV-absorbing aerosols in cloudy scenes. A method that allows detecting the height of absorbing aerosol layers present above clouds was also recently developed using absorbing aerosol index data and oxygen A band measurements provided by the Global Ozone Monitoring Experiment (GOME-2) instrument (Wang et al., 2012).

Active remote sensing techniques, based on the use of lidar systems, allow characterizing the vertical profile of the atmosphere (Winker et al., 2004). However, these instruments have limited spatial coverage, which is a clear disadvantage compared to passive sensors in terms of sampling events when aerosol layers are above clouds. Furthermore, current spaceborne lidar systems have limited capabilities to retrieve the aerosol burden without some priori knowledge on aerosol microphysics (Ackermann, 1998, Cattrall et al., 2005). An alternative method was recently developed for the Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) spaceborne lidar that allows retrieving the optical thickness of any transparent layer (cirrus or aerosol) located above an opaque liquid water cloud. This method combines lidar backscattering coefficient measurements with linear depolarization ratio measurements and does not require assumptions on the aerosol microphysical properties (Hu et al., 2007).

Satellite passive remote sensing with polarization capabilities constitutes an alternative tool to study aerosols above clouds. In a general way, spectral angular polarized measurements are sensitive to particle loading, size, shape and composition via sensitivity to the real part of the refractive index (Mishchenko et al., 1997). The presence of aerosols above clouds significantly affects the polarized radiation reflected back to space by the cloud, as shown by the measurements provided by the POlarization and Directionality of Earth Reflectances (POLDER) instrument (Waquet et al., 2009a). An approximate formulation of the cloud-aerosol radiative interaction was developed using single scattering approximation. The method was used to estimate the AOT of a biomass burning aerosol layer originated from South Africa and transported above stratiform low-level clouds in the South Atlantic Ocean. More recent works also outlined the importance of polarization measurements for the retrieval of the aerosol properties in cloudy scenes. Hasekamp et al., (2010) analyzed the contribution of multi-spectral, multi-angular total and polarized radiance measurements for the purpose of the simultaneous retrieval of the aerosol and cloud properties. Their study investigated various types of aerosol-cloud contaminated scenes (AAC scenes and scenes with fractional cloud cover mixed with aerosols). Knobelspiesse et al., (2011) analyzed the sensitivity of polarization measurements to aerosol properties for AAC scenes using the airborne version of the Aerosol Polarimetry Sensor (APS) instrument. An example of the aerosol optical and microphysical properties retrieval is presented in Knobelspiesse et al., (2011), where the case study is relative to a layer of anthropogenic particles suspended above a marine stratocumulus cloud in the Gulf of Mexico.

POLDER aboard Polarization and Anisotropy of Reflectances for Atmospheric Sciences Coupled with Observations from Lidar (PARASOL) was a part of the train of satellites, called A-train. Between March 2006 and Dedember 2009, it acquired data in conjunction with multiple other passive and active sensors. We present a new operational algorithm that allows to retrieve the properties of any aerosol layer (mineral dust particles or biomass burning aerosols) transported above clouds using the polarization measurements provided by POLDER. We study the particle properties observed for different transport events of mineral dust particles and biomass burning aerosols over cloudy scenes and cloud-free ocean scenes using data provided by the POLDER, MODIS (Salomonson et al., 1989) and CALIOP (Winker et al., 2004) instruments. We evaluate the different methods used to model the POLDER signal and to retrieve the particle properties. The strenghts and limitations of each method are pointed out. The properties of the aerosols and clouds observed for various AAC scenes are provided. Limitations and uncertainties are summarized in the conclusion.

2. Background and methods.

2.1 Motivations.

Waquet et al., (2009a) developed a method that allows retrieving the Aerosol Optical Thickness (AOT) above clouds using polarized measurements. A global processing of one year of POLDER data was performed. The analysis of the results pointed out that the method was not able to accurately retrieve the Aerosol Optical Thickness (AOT) when mineral dust particles were present above clouds. Indeed, the AOTs were underestimated (by a factor 2 or 3) compared to the retrieval performed over the nearby clear-sky ocean pixels using the standard POLDER aerosol algorithm (Herman et al., 2005). The reason was that the method developed by Waquet et al., (2009a) was restricted to the use of observations acquired for scattering angles around 90-120° where polarization measurements are highly sensitive to scattering by fine mode aerosols and only weakly sensitive to cloud microphysics. Since nonspherical particles, such as mineral dust particles, do not much polarize light in the selected scattering angle range, it led the algorithm to systematically underestimate the AOT by ignoring the contribution of the coarse mode. The lack of sensitivity of this method to mineral dust particles is the main motivation for the development of a new retrieval method able to retrieve the properties of any type of particles lofted above liquid water clouds. To a lesser extent, this shortcoming was also due to the use of an approximate modeling of the polarized reflectance.

Mineral dust particles do not much polarized light at forward scattering angles but they strongly reduce the magnitude of the polarized cloud bow produced by liquid clouds underneath. The polarized cloud bow is a feature of liquid water cloud that corresponds to an intense and highly directional peak. Figure 1-d shows the angular polarized features typically observed for liquid clouds in pristine conditions. The cloud-bow is observed around a scattering angle of 140°. If aerosols are overlying liquid clouds, they attenuate the cloud bow and this attenuation is directly related to the total optical thickness of the aerosol layer. The peculiar signature obtained for AAC scenes with biomass burning aerosols and mineral dust particles are respectively shown in figures 1-a and figure 1-b. For AAC scenes, an additional polarization signal at side scattering angles (scattering angles smaller than 130°) at 0.865 µm and 0.67 µm and a spectral attenuation of the cloud bow magnitude at 140° is observed that can be revelant of the particle type. Indeed, the attenuation of the primary cloud-bow is spectrally dependent (i.e. colourful) for biomass-burning AAC and almost spectrally neutral for mineral dust particles between 0.67 and 0.865 µm. For the case presented, the primary bow is strongly attenuated but can still be observed around 140° (see figure 1-b), which indicates that a large amount of coarse mode particles was transported above the clouds. We note also that the excess of polarization is much larger for biomass burning aerosols than for mineral dust particles, particularly for 0.67 and 0.865 µm.

With respect to Waquet et al., (2009a), we hereinafter provide more accurate calculations of the polarized radiances and propose a new approach to retrieve the mineral dust AOT. In addition, we use the polarized measurements acquired in the cloud bow directions to improve the retrieval of both the biomass burning aerosol properties and the cloud microphysical properties.

2.2 Retrieval methods.

First, a « research algorithm », that uses all the available polarization measurements provided by the POLDER instrument, was developed in order to parameterize a non spherical aerosol particles model and to evaluate the potential of the POLDER polarization measurements for the simultaneous retrieval of the aerosol and cloud microphysical properties. Indeed, the cloud droplets distribution effective radius primarily controls the magnitude of the cloud bow for a single layer cloud (Bréon et Goloub, 1998). A cloud particles model and an aerosol model must be therefore determined to analyze the POLDER data acquired for AAC scenes. We used also this research algorithm to perform a sensitivity study analysis, which is presented in section 5.

A second algorithm was developed for reducing time computations. It is referred hereafter as the "operational algorithm" and uses a specific strategy to incorporate the observations acquired in the cloud bow as well as auxiliary MODIS and POLDER cloud products to retrieve the AOT and the Ångström exponent above clouds at global scale. Note that the two algorithms are connected since the research algorithm is first used to define the mineral dust particles model that is used in the operational algorithm in a second step.

The next section is dedicated to the description of both algorithms, including the description of the particles models and radiative transfer codes, used to accurately compute the polarized radiances. We present also a study concerning the 3D radiative cloud effects that may impact polarization reflectance magnitude in the cloud bow.

2.2.1 Simultaneous retrieval of the aerosol and cloud properties: the research algorithm.

The simultaneous retrieval of aerosol and cloud properties is performed using an Optimal Estimation Method (OEM), similar to the one described in Waquet et al., (2009b). The particles properties are retrieved by comparing the measured and simulated polarized radiances and by adjusting the parameters in the particles models until the best match is found. The search for the best solution is achieved through the use of an iterative process. We use the Newton-Gauss iteration modified with the Levenberg-Marquadt technique to ensure convergence. We refer to Waquet et al., (2009b) or to Rodgers (2004) for more details concerning the practical implementation of this procedure. The OEM is coupled with a radiative transfer code and a module that allows calculating the optical properties of the particles (described hereafter). This method provides a diagnostic error that accounts for the measurements' sensitivity to the retrieved parameters, the measurement's errors and the modelling's errors as well as any available *a priori* information. The retrieval error covariance matrix C_x is defined as :

$$\mathbf{C}_{\mathrm{x}} = \left(\mathbf{C}_{\mathrm{a}}^{-1} + \mathbf{K}^{\mathrm{T}} \cdot \mathbf{C}_{\mathrm{T}}^{-1} \cdot \mathbf{K}\right)^{-1}, \qquad (1)$$

where C_T is the total error covariance matrix and C_a is the *a priori* error covariance matrix. **K** is the Jacobian matrix and its ith row and jth column element is defined as :

$$\mathbf{K}_{ij}(\mathbf{X}) = \frac{\partial F_i(\mathbf{X})}{\partial X_i},\tag{2}$$

where F is the simulation vector and X is the vector of parameters. K is computed for each observation (*i*) and each parameter (*j*) and represents the sensitivity of the simulated polarized radiances to the particles parameters.

The square root of the diagonal elements of the error covariance matrix provides the standard deviation associated to each retrieved parameter. The error covariance matrices for the optical parameters are derived from the retrieved parameters and computed using Eq. 1 and the formula given in annex (A-1).

2.2.2 Particles models and *a priori* information.

A combination of two lognormal size distribution functions (accumulation and coarse modes) is assumed for the aerosols. A geometric mean radius and a standard deviation are used to describe each lognormal function (r_g and σ). The other aerosol parameters considered in the particles models are the column number density of particles (N, in μ m⁻²) for both modes and the complex refractive index ($m_r - m_i i$) that is assumed to be spectrally invariant and the same for both modes. The effective radius, r_{eff} , is related to the lognormal size distribution parameters using the formula given in annex (A-2). As shown later, the polarization measurements provided by the POLDER instrument do not contain enough information to retrieve all the aerosol parameters previously listed. A sensitivity study analysis presented in section 5 is used to determine the retrieval option (number of retrieved parameters) that is finally preferred to retrieve the aerosol properties in function of the type of AAC scenes (i.e. biomass burning aerosols or mineral dust particles above clouds).

For aerosols, we consider a mixture of spherical and non-spherical particles. Non-spherical particles are spheroid models with various aspect ratios (Mishchenko and Travis, 1994, Dubovik et al., 2006). The aspect ratios distribution model is the one derived by Dubovik et al., (2006) from the analysis of the scattering matrix of mineral dust samples (Volten et al., 2001). The ratio of spherical particles over the total number of particles (SF) is included in the retrieval process for AAC scenes with mineral dust particles.

The cloud droplets size distribution is assumed to follow a gamma standard law, described by the same two parameters, the cloud droplets effective radius, $r_{eff,cld}$, and the cloud droplets effective variance, $v_{eff,cld}$, as defined in Hansen and Travis (1974). Angular polarization measurements are highly sensitive to the real refractive index of large spherical particles due to the presence of bows. We make clear that the droplet real refractive index is primarily included in the retrieval process to ensure an accurate modeling of the cloud bows (angular locations and magnitudes). The real refractive index for cloud droplets, $m_{r,cld}$, is then retrieved in each spectral band. The imaginary refractive index for cloud droplets is less than 5.10^{-7} for the POLDER wavelengths (Hale et al., 1973) and it is therefore neglected and held constant to 0 in the calculations. The droplet effective variance is also included in the algorithm, since this parameter strongly impacts the magnitude of surpernumerary cloud bows. The cloud droplets are modelled as spheres and their optical properties are therefore calculated using the Mie theory.

In Table 1, we provide the values of the *a priori* aerosol and cloud parameters (« starting point for X») and the associated uncertainties (C_a). The subscripts f and c respectively denote parameters that describe the fine mode and coarse mode aerosols. The number of retrieved parameters included in the OEM can be modified and the *a priori* information as well. If so, the corresponding information is provided in the text.

2.2.3 Forward model

a) Transfer radiative code and particles vertical distribution.

The polarized radiances are computed using the Successive Order of Scattering code (SOS) that accounts for the effects of multiple scattering under the assumption of the plane

parallel atmosphere (Lenoble et al., 2007). The SOS code provides the usual three first Stokes parameters and allows including various atmospheric components that are separately described for the optical properties and the vertical profile. The vertical profile for the molecules is defined using a decreasing exponential law with a scale height of 8 km. The molecular optical thickness and the effects of molecular anisotropy are computed using the formulae given in Hansen and Travis (1974). The vertical profile of the aerosol layer is described using a Gaussian distribution function, defined by a standard deviation (0.75) and a mean altitude value, z mean. The cloud droplets are assumed well mixed with the molecules between the surface and the cloud top height. The cloud base height is therefore supposed to be at 0 km. For case studies analysis, the mean altitude of the aerosol layer and the cloud top height are adjusted using the lidar data. When those are not available, we use the "apparent O₂ cloud pressure" to estimate the cloud top height ($z_c_O_2$, see table 2) and assume a mean altitude of 3.5 km for the AAC height. An empirical correction on z_c O₂ accounts for the underestimate of the apparent O_2 cloud pressure method when compared to the lidar. The cloud optical thickness is held constant to 5., which ensures that the polarized radiance reflected by the cloud layer is saturated and does not depend on it. A truncation procedure of the forward scattering peak is implemented in the SOS code, which allows a faster modeling of the radiances. The radiances are therefore calculated using a truncated phase function since the errors induced by this approximation are small (see annex A-4).

b) 3D cloud effects.

It is well known that the homogeneous 1D cloud assumption leads to errors in the retrieved cloud parameters from total visible radiance (Marshak and Davis, 2005). Cornet et al., (2009) show for a cirrus cloud with a Monte-Carlo radiative transfer code that biases exist also on polarized radiance. To assess the errors in our 1D transfer radiative model, we compute 3D and 1D polarized radiance of a stratocumulus cloud with a mean optical thickness of 10, a uniform effective radius of 10 µm and an effective variance of 0.02. The heterogeneity parameter is 7 for the optical thickness (standard deviation associated to the mean optical thickness). The initial resolution of the radiative transfer simulation is 80×80 m^2 . The radiances are then spatially averaged at $10 \times 10 \text{ km}^2$ to simulate the observation of a sensor like POLDER. The differences between the 1D and 3D polarized reflectances as a function of scattering angle are presented in figure 2 for the three wavelengths used in the algorithm and for different sun angles. For most of the scattering angles, and for the case considered here, which does not include microphysical heterogeneity, the differences between the two polarized reflectances are small and inside the statistical error of the Monte-Carlo simulations (not plotted). Exceptions appear however in the forward direction for large sun angle and in the cloud bow regions near 140°, where the 1D simulations systematically overestimate the ones that account for the 3D cloud effects by about 5-8%, depending on wavelength and geometry (θ_s , φ). For computional cost considerations, it is practically impossible to account for those 3D effects in our retrieval procedure so we incorporated these errors in the cloud bow regions into the total error covariance matrix (C_T).

2.2.4 The operational algorithm :

A look-Up-Table (L.U.T) approach is needed to derive the aerosol properties above clouds at large scale. The number of retrieved parameters is then reduced to the AOT, the Ångström exponent and the cloud droplets effective radius. The effects of the droplets effective radius and AOT are illustrated in figure 3. To build the LUT, we calculate the polarized radiances using the SOS code for different combinations of aerosol and cloud

particles models. We consider six accumulation mode for aerosols models ($r_{g,f} = 0.06, 0.08$, 0.10, 0.12, 0.14, 0.16 μ m and $\sigma_f = 0.4$) with a constant complex refractive index of 1.47-0.01i, which is a mean value for polluted and biomass burning aerosols. We also included the mineral dust particles model derived using the research algorithm (see table 5 case 4). The elements of the polarized phase function were shown for similar particles models in previous studies (e.g. see figures 1 and 2 in Waquet et al., 2007). The polarized radiances are calculated for various AOTs and viewing geometries, then interpolation processes are considered. For cloud particles, we consider 22 droplets models with effective radius varying between 5 and 26 μ m by step of 1 μ m, with a constant droplets variance of v_{eff,cld} = 0.06 and a constant real refractive index ($m_{r,cld}(0.490 \ \mu m) = 1.338$, $m_{r,cld}(0.670 \ \mu m)=1.331$ and $m_{r,cld}(0.865 \ \mu m)=1.330$). We assume a cloud top height of 0.75 km and a value of 3.5 km for the aerosol layer mean altitude. POLDER provides polarized radiance measurements at 0.49, 0.67 and 0.865 µm (see section 3.1). The effects of the atmospheric vertical profile on the measured polarized signal are very limited at 0.67 µm and almost negligible at 0.865 µm compared to 0.49 µm and we therefore restrict the operational algorithm to these two longer wavelenghts.

A schematic view of the algorithm is shown in figure 4. A different retrieval strategy is considered depending on the aerosol type and load. We first estimate the AOT above clouds by using all available angular information and by only considering the six fine mode particles models. If the retrieved AOT is larger than 0.1 at 0.865 µm, we then compare the least square error term (see Annex A-3) computed for the mineral dust particles model with ones computed for the six other fine mode particles models and keep the solution obtained with the mineral dust model if this latter model minimizes the error term. The threshold of 0.1 in AOT is justified because the retrieval of the dust AOT becomes difficult (instable) when AAC optical thickness becomes small. This is probably due to the 3D transfer radiative effects that render difficult the modelling of the primary cloud-bow when the atmosphere above clouds is pristine. If the AOT retrieved at the first step is smaller than 0.1 or if the mineral dust particles model fails to reproduce data, we then only consider the six fine mode particles models and restrict the algorithm to observations acquired at scattering angles smaller than 130° since the inclusion of the data acquired in the polarized cloud bow is not critical for the retrieval of the fine mode AOT. The retrieval strategy also incorporates the fact that the POLDER instrument sometimes does not observe the side scattering and forward scattering geometries (data for $\Theta < 130^{\circ}$ unavailable).

The droplet effective radius can be derived as a part of the retrieval process or estimated using the one retrieved by MODIS. We compare both approaches and found only small differences in the retrieved AAC optical thickness. Differences observed between the cloud droplet effective radius retrieved from total radiance measurements and polarized measurements are generally small for AAC scenes (see section 5.2.3), so both approaches lead to small differences in the retrieved AAC optical thickness. We then choose to use the MODIS droplets effective radius since its retrieval does not depend on the availability of a particular viewing geometry. The impacts of the 3D effects on the retrieved AOT for dust particles were evaluated using synthetic data. We simulated polarized radiances for AAC scenes with mineral dust particles. We considered the mineral dust particles model implemented in the operational algorithm and an AOT of 1.04 at 0.865 µm. We decreased by 8% the magnitude of the synthetic polarized radiances in the cloud-bow directions to evaluate the impacts on the AOT due to the uncertainties in modelling the cloud-bow magnitude. We found that the algorithm then overestimates the true AOT by 0.06 (relative error of 6%). Note that this source of error only affects the AOT retrieved for mineral dust particles since the measurements acquired in the cloud bow are not used for the retrieval of fine mode particles properties, for which we only consider data acquired for scattering angles smaller than 130°.

Different filters are eventually applied to the data to obtain a quality assessed product. For example, we only apply the operational algorithm to homogeneous cloudy pixels associated with optically thick liquid water clouds. The criteria and the cloud parameters used to select the cloudy scenes are given in figure 4. We refer to section 3.4 and table 2 for the description of the cloud parameters used. We also added a criterion that allows rejecting pixels for which the POLDER data are not accurately fitted (the least square error term ε must be smaller than 0.005). The AOT is first retrieved at the finest spatial resolution of POLDER (i.e. $6 \times 6 \text{ km}^2$) and it is finally aggregated at a spatial resolution of $18 \times 18 \text{ km}^2$ and we only keep these pixels for which the AOT standard deviation (Δ _AOT) is smaller than 0.1 and contain more than four $6 \times 6 \text{ km}^2$ pixels. This latter procedure allows rejecting the edges of the clouds where our retrieved AOT are generally doubtful and where the radiances should be not modelled with a plane parallel transfer radiative code.

3. Observations.

3.1 POLDER data.

The data provided by POLDER instrument are the normalized total and polarized radiances, L and L_p . The normalized total radiance L is given by

$$L = \frac{\pi L^*}{E_s} \tag{3}$$

where L^* is the spectral radiance $(W.m^{-2}.sr^{-1}.\mu m^{-1})$ and E_s is the spectral solar extraterrestrial irradiance $(W.m^{-2}.\mu m^{-1})$. The quantity L^* is related to the first Stokes parameter I and describes the total radiance measured by the instrument. L_p is given by

$$L_p = \pm \frac{\pi \sqrt{\left(Q^2 + U^2\right)}}{E_s} \tag{4}$$

where Q and U are the second and third Stokes parameters that characterize the linear polarization state of light. The Stokes parameters have the dimension of a spectral radiance $(W.m^{-2}.sr^{-1}.\mu m^{-1})$. The plus or minus sign indicates that the direction of the scattered electric field is preferentially normal or parallel to the scattering plan (Herman et al., 2005). Along the paper, when we discuss radiances, we will be referring to these normalized quantities. The polarized radiances are measured in three spectral bands at 0.490, 0.670 and 0.865 μ m. The POLDER instrument also acquires total radiance measurements in a number of other spectral bands (e.g. 0.765 and 1.02 μ m) and provides images of the scene being viewed on a CCD matrix camera. The spatial resolution of POLDER is equal to 5.3 × 6.2 km² at nadir. Because of the satellite motion and instrument design, the POLDER instrument can see the same scene from multiple angles (up to 16), allowing measuring the angular variability of these radiances. The viewing geometry is characterized by the scattering angle, Θ , that is the angle formed between the incident and scattered directions. We also introduce the sun zenith angle, θ_s , the view angle, θ_v , and relative azimuth angle, φ .

3.2 Errors' measurements.

The error budget in the measurements is taken from Fougnie et al., (2007) and are used to

fill out the total error covariance matrix. We consider a relative error of calibration of 2% in the three polarized spectral bands. The noise associated with the polarized radiances for cloudy scenes is estimated to be 2.5×10^{-3} at 0.49 µm and 0.865 µm and 5×10^{-3} at 0.67 µm. We assume that the different sources of errors are independent and the total covariance matrix is given by the sum of the different error covariance matrices.

3.3 Hyper-pixel data.

The research algorithm is used in section 5 to evaluate the potential of the POLDER aggregated data to simultaneously retrieve the aerosol and cloud microphysical properties for AAC scenes. It requires an homogeneous sampling of the scattering angles in order to retrieve the cloud particles microphysics (Bréon et Goloub, 1998). The results should also be more accurate when a high angular resolution is available. To obtain this required sampling, we use the so-called "hyper-pixel", which refers to POLDER data aggregated at a spatial scale of 200 x 200 km². The specific procedure used for the aggregation of the data is different than the one used in Bréon and Goloub (1998) and it is described below.

Before the retrieval of the aerosol and cloud at the hyper-pixel scale, we first apply a retrieval method that works at the finest spatial POLDER resolution ($6 \times 6 \text{ km}^2$), such as the one described in Waquet et al., (2009a). It allows estimating the spatial variability of the AOT above clouds within the hyper-pixel and to only select homogeneous pixels in terms of both aerosol and cloud properties. The variability of the atmospheric vertical profile within the hyper-pixel is also qualitatively estimated using the apparent O₂ cloud pressure and lidar data when available. Indeed, thin cirrus, multi-layers or broken clouds situations tend to increase the spatial variability of the observed apparent O₂ pressure.

Once selected the homogeneous scenes, we come back to the data and split them using the polar coordinate system and subdivide the range of scattering sampled by POLDER into small intervals of 0.5°. A mean viewing geometry ($\overline{\theta}_s, \overline{\theta}_v, \overline{\varphi}$ and $\overline{\Theta}$) and a mean polarized radiance value are then computed for each 0.5° scattering angle interval using the corresponding information available at the 6 x 6 km² spatial resolution. The scattering angle used to depict the angular behaviour of the mean polarized radiance is referred as $\overline{\Theta}^*$ and it is computed from the mean viewing geometry ($\overline{\theta}_s, \overline{\theta}_v$ and $\overline{\varphi}$).

In addition, precautions must be taken for the calculation of the mean viewing geometry when the multiple scattering effects in the atmosphere have to be accounted for. The data associated with different viewing geometries (θ_v , φ) that correspond to the same value of scattering angle must be separately aggregated since these data show different values of polarized radiance, due to the effects of cloud multiple scattering. We apply a geometric criterion (i.e. $\left|\overline{\Theta}^* - \overline{\Theta}\right| < 0.1^\circ$) that prevents to aggregate together data belonging to the same 0.5° scattering angle interval eventhough they are associated with significant different viewing geometries.

An example of aggregated data is shown in figure 5. Two different "branches of scattering angle" are usually observed by POLDER when an area of 200 x 200 km² is considered (e.g. $97^{\circ} < \Theta < 177^{\circ}$ and $157^{\circ} < \Theta < 177^{\circ}$ in figure 5-a). In the retrieval algorithm, we consider only one branch of scattering angle for sake of simplicity. We select the branch associated with the widest range of scattering angles (e.g. $97^{\circ} < \Theta < 177^{\circ}$ in figure 5-a). Figures 5-a and 5-b show that this procedure allows to obtain rather smooth mean polarized radiances associated with a consistent mean viewing geometry.

3.4 Aerosol and cloud properties from the A-TRAIN.

So far, our algorithm does not allow retrieving aerosols over cloud-free ocean. Therefore, we use the algorithm developed by Herman et al., (2005) to derive these aerosol properties over cloud-free ocean scenes. Total and polarization radiances acquired at 0.670 and 0.865 μ m to derive several aerosol parameters at a resolution of 18.5 km × 18.5 km are used to derive mainly the aerosol optical thickness and the Ångström exponent, a parameter indicative of the particle size. The Ångström exponent is about 0.4 for mineral dust particles and typically larger than 1.8 for biomass burning aerosols (Dubovik et al., 2002). The AOT for the fine and coarse modes can also be retrieved as well as the fraction of non-spherical particles within the coarse mode. This latter parameter is only retrieved when the geometrical conditions are favourable. We refer to Herman et al., (2005) for more details regarding the assumptions used for the particles models and the modelling of the radiances.

In our analysis, we also use collocated cloud properties retrieved from MODIS and POLDER to characterize the cloudy scenes. We take advantage of the high spatial resolution retrieval capabilities of MODIS ($1 \times 1 \text{ km}^2$ at nadir) to estimate within each PARASOL pixel $(6 \times 6 \text{ km}^2)$ the variability of the cloud properties. We compute a mean value for the cloud optical thickness (COT) and for the cloud droplet effective radius (REFF CLD M) as well as a standard deviation for each parameter (Δ COT and Δ REFF CLD). The POLDER and MODIS instruments also provide various estimates for the cloud top heights. The comparison of these estimates provides valuable information for the detection of multi-layer situations (Waquet et al., 2009a). In the following, we use the cloud top altitude retrieved with : (i) the "IR cloud top pressure" method (zc IR), (ii) the "Rayleigh cloud top pressure" method (z_c Rayleigh), and (iii) the apparent O₂ cloud pressure method (z_c O₂). Cloud top pressure values were converted to cloud top heights using a fixed scale height. We also used the cloud phase, derived from a combination of POLDER and MODIS measurements, which is provided as a semi-continuous index, ranging from confident liquid phase only to confident ice only (0 < phase index < 200). The references for each cloud product previously listed are given in table 2. For our retrievals, we only consider cloud phase index values ranging between 0 and 80 (only liquid clouds) and between 80 and 120 ("mixed-phase clouds") since AAC scenes are sometimes improperly classified as mixed-phase clouds. We added another criterion to reject multi-layer scenes with cirrus above liquid clouds. This latter criterion is based on the cloud top pressure anomalies observed for scenes with cirrus above liquid clouds $(z_c O_2 < z_c Rayleigh \ll z_c IR$, see figure 2 in Waquet et al., 2009a). This latter criterion is only applied when the anomaly is strong ($z_c \ IR - z_c \ O_2 > 2 \ km$ and $z_c \ IR - z_c \ Rayleigh > 2$ km).

Finally, the CALIOP lidar data are used when available to characterize the vertical profile of the atmosphere along the A-train orbit track. We use the aerosol/cloud classification that corresponds to the Lidar Level 2 Vertical Feature Mask (VFM) Product (Vaughan et al., 2004).

4. Results.

4.1 Case studies of aerosol transport events.

4.1.1 Biomass burning aerosols.

Figure 6-a is a true color composite image illustrating POLDER total radiance observations, acquired over the tropical southeast part of the Atlantic Ocean on the 4^{th} of August 2008. The CALIOP lidar orbit track is the black line. The transport of biomass burning aerosols over clouds is expected in this region for this time period (e.g. Waquet et al.,

2009a). The region is partially covered by clouds. The total Aerosol Optical Thickness (AOT) retrieved over cloud free pixels is reported in figure 6-b. The largest AOTs (≈ 0.6) are observed over the cloud-free parts of the Gulf of Guinea. The Ångström exponent is about 1 in this region, which indicates that the algorithm retrieves a bimodal size distribution. We know that the algorithm is sensitive to two types of particles, the maritime aerosols (coarse mode particles) located in the boundary maritime layer and the biomass burning aerosols (mainly fine mode particles) located in the elevated layer.

We reported the CALIOP mask results in figure 6-c. An aerosol layer is observed at altitude between 2 km and 4 km above low-level clouds for latitudes ranging between -8.5° and -21°. For northern latitudes, the lidar signal is too attenuated and the particles located in the lower atmosphere cannot be observed. The cloud top heights retrieved from passive observations (IR, O₂ and Rayleigh) are reported in figure 6-c. The selected POLDER and MODIS pixels centers are the closest to the CALIOP pixels. The anomalies observed between the three different estimates of the cloud top heights for latitudes between than -20° and 8.5° are typical of AAC scenes with biomass burning aerosols (Waguet et al., 2009a). The IR and Rayleigh methods both largely overestimate the cloud top height with the largest biases observed on z_c Rayleigh. The apparent O₂ cloud pressure does not appear to be much perturbed by the aerosol layer and tends to slightly underestimate the true cloud top altitude. This last method provides an estimate of the cloud top height, that is in-between the geometric middle of the cloud layer and the cloud top height, as expected for low-level single cloud layers (Ferlay et al., 2010). Most of clouds observed in the POLDER image shown in figure 6-a correspond to low-level optically thick clouds (0.45 km $< z_c$ O₂ < 1.05 km, 3.0 <COT < 18.0) with a cloud thermodynamical phase index of about 10, which means high probability for liquid phase.

In figure 7-b, we compare the AOT retrieved above clouds with the fine mode AOT retrieved by POLDER over cloud-free pixels. Assuming that most of the fine mode particles is located in the elevated biomass burning aerosol layer, we expect that both AOT should be comparable. Therefore, the fine mode AOT retrieved above cloud-free pixels with the ocean algorithm and the AAC optical thickness retrieved with anthropogenic particles models should be rather comparable. Figure 7-b shows a general good qualitative spatial agreement between the AOTs retrieved with the two methods. The largest AAC optical thicknesses (> 0.3) are retrieved over the Gulf of Guinea and are associated with small particles (α of \approx 2.25). In this region, the AAC optical thicknesses are higher than the AOTs retrieved for ocean scene but the spatial variability of the fine mode AOT retrieved over ocean pixels is sometimes questionable. For instance, the fine mode AOT abruptly changes from about 0.16 to 0.24 (from blue to yellow in the AOT map shown in figure 7-a) around the point of coordinates longitude 4° and latitude -9°. This change is associated with a change in the coarse mode microphysical properties (the fraction of non-spherical particles have changed). Biomass burning aerosols are very likely to be strongly absorbing particles. So, we think that the assumption of non-absorbing particles made in the ocean algorithm might lead to slightly overestimate the coarse mode AOT and then to consequently underestimate the fine mode AOT. This hypothesis is supported by the results of the sensitivity analysis presented in section 5.1 showing that the assumption of weak absorption generally leads to the retrieval of a larger coarse mode AOT.

4.1.2 Mineral dust aerosols.

We now reported POLDER images acquired over the north Eastern tropical Atlantic Ocean on the 25th of July 2008 and on the 4th of August 2008, respectively in figures 8-a and 9-a, together with the lidar CALIOP traces. The presence of mineral dust particles above low-

level clouds is expected in this region at that time (De Graaf et al., 2007). The transport of mineral dust particles can be observed in cloud free scenes in figures 8-a and 9-a. An optically thick liquid low-level cloud can be observed (COT > 5. and $z_0_2 < 0.4$ km) on the 25th of July case. The cloud cover is more fractional and optically thinner than on the 4th of August case. The AOTs retrieved by POLDER over cloud-free ocean scenes are reported in figures 8-b and 9-b. Large AOT values can be observed, as large as 1.7, on the 25th of July 2008. The Ångström exponent is close to zero for both days indicating a size distribution dominated by the coarse mode particles. Because of geometrical conditions, the fraction of non-sphericity is only available on the 25th of July 2008. It indicates that the coarse mode mainly consists of non-spherical particles, which is perfectly consistent with origins of the aerosol layer.

The presence of mineral dust particles above clouds cannot be insured with the lidar data for the July case, since the optically thick cloud observed by POLDER is outside the CALIOP track (see figure 8-a). For this thick cloud, the anomalies observed between the three different estimates (not shown) of the cloud top heights remain qualitatively similar to the biomass burning aerosol case ($z_c_O_2 < z_c_IR < z_c_Rayleigh$) with, however, smaller biases noted on $z_c_Rayleigh$, resulting from the lower polarization produced by non-spherical particles. For instance, the average values for $z_c_O_2$, z_c_IR and $z_c_Rayleigh$ computed for box 3 in figure 8a are equal to 0.275, 2.75 and 3.45 km, respectively. The CALIOP mask results are shown in figure 8-c. The CALIOP mask shows a complex situation with aerosols detected at different altitudes between the sea surface and 6 km that are potentially embedded with some optically thin cloudy structures. We observe some abrupt changes in the CALIOP results that we assume to be artificial for the most parts since the CALIOP mask is sometimes subject to misclassification between aerosol and cloud layers, especially when dense dust layers are encountered (Chen et al., 2010).

The CALIOP results obtained for the case study on mineral dust particles acquired on the 4^{th} of August 2008 are reported in figure 9-c, together with the cloud top height estimates retrieved from POLDER and MODIS. The dust plume is observed at altitudes between 2 km and 6 km above low-level clouds for latitudes ranging between 18° and 24°. The same layer is observed above a maritime boundary layer for latitudes ranging between 24° and 27.5°. The results obtained with the Rayleigh method are not available due to unfavorable geometric conditions (i.e. this method requires observations acquired at small scattering angles that are not available here). The results for z_c_0 and z_c_1 R remain qualitatively similar to the ones obtained for the two previous cases.

The spatial variability of the AOT of the mineral dust plume transported above clouds on the 25th of July 2008 is shown in figure 10-a, together with the AOT retrieved over cloud-free ocean. The map shows that the dust plume is blowing east over the ocean and then southeast above low-level clouds. The AAC algorithm retrieves the dust model included in the LUT with a retrieved Ångström exponent of about 0.4. Figure 10-a shows a good qualitative spatial agreement between the AOTs retrieved over cloudy and cloud-free pixels. We however note that The AAC optical thicknesses are systematically smaller than the AOD retrieved over cloud-free ocean pixels, e.g. respectively 1.5 and 1.7. Such a difference is not surprising since the AAC optical thickness cannot include the aerosols observed in the lower atmosphere layer as noted by CALIOP. The results obtained for the mineral dust particles observed on the 4th of August 2008 are reported in figure 10-b. The same observations can be made for this second case study. The fact that the algorithm does not retrieve AOT over clouds that are larger than the total column AOT is also a positive sign of the retrieval consistency.

5. Discussion.

In this section, we further analyze the potential of the POLDER polarization

measurements for the retrieval of the aerosol and cloud microphysical properties for the AAC scenes previously described. We use the research algorithm described in section 2.2.1 and all the available angular and spectral polarized measurements provided by the POLDER instrument. We present a sensitivity study analysis that allows : (1) to examine the sensitivity of the POLDER polarization measurements to the different aerosol and cloud microphysical parameters, (2) to evaluate the impacts of these parameters on the retrieved AOT and (3) to study the impacts of the 3D transfer radiative effects on the retrieved particle microphysics. Then, we explain how we parameterized the mineral dust particles model implemented in the operational algorithm and describe more accurately the microphysical properties of the aerosol and cloud particles, observed for the AAC scenes previously described.

5.1 Sensitivity study analysis.

5.1.1 Sensitivity study from POLDER measurements.

The research algorithm is flexible and the number of retrieved parameters can be increased or decreased as needed. We did several tests with varying numbers of retrieved parameters in order to provide a sensitivity study. We first investigate the AAC scene with biomass burning aerosols, referred as box (1) in figure 6-a. The solutions obtained for the hyper-pixel defined for this area and for various retrieval schemes are reported in table 3. The quantity ε is the mean squared difference error term calculated between measured and simulated polarized radiances (see annex A-3). This quantity gives a simple measure of the difference between measurements and simulations, assuming a diagonal identity matrix for C_x (no weight) and no *a priori* knowledge. Note that the quantity ε is consistent with the definition of the error term considered in the less sophisticated retrieval method described in section 2.2.4. Solution 1 includes the retrieval of the parameters of load and size for the fine particles and the microphysical parameters for the cloud particles. Biomass burning aerosols are considered as spherical particles, which is a reasonable assumption for this type of aerosols. The value for the spherical fraction (SF) (spherical fraction of particles) indicated in table 1 (0.5 \pm 0.5) is therefore modified and held constant to 1. Solution 2 is the same as solution 1 but includes the retrieval of the properties of the coarse mode (load and size parameters). Solutions 1 and 2 both assume a weak absorption. Solution 3 is similar as solution 2 with in addition the retrieval of the imaginary part of the complex refractive index (i.e. absorption). Solution 4 is similar as solution 3 but includes the retrieval of the real part of the refractive index.

All the solutions allow to robustly model the POLDER data (not shown) and confirms that the polarized measurements are primarily sensitive to the fine mode scattering AOT and its spectral dependence as well as the cloud microphysical properties. The measurements are also potentially sensitive to the aerosol Single Scattering albedo (SSA) since the polarization observed at side scattering angles is related to the scattering AOT whereas the effect of attenuation of the aerosol layer on the polarized light reflected by the cloud depends on the total (extinction) AOT. The algorithm shows indeed some sensitivity to the aerosol SSA. We observed that the effect of the absorption on the polarized radiances is rather small but not negligible. Solution 4 includes the most degrees of freedom in terms of retrieved aerosol microphysical parameters and it retrieves an aerosol model for which the size distribution is dominated by fine mode particles (α of about 2.) associated with rather strong absorption properties (m_i of 0.017 ± 0.007). The standard deviation for each parameter is small, excepted for the coarse mode particles effective radius, which tends to indicate that the algorithm is sensitive to most of the parameters considered in solution 4. The least square error term ε is minimized for this solution but other solutions (1, 2, 3) show rather similar low ε values. The

retrieved AOTs at 0.865 μ m are rather similar for all solutions but differences appear for the aerosol microphysical parameters. For instance, the contribution of the coarse mode particles to the total AOT is larger for solution 2 than for solution 4 whereas the absorption is much smaller for solution 2 than for solution 4 (not shown).

These results suggest that the polarization measurements provided by POLDER do not contain enough information to accurately retrieve the coarse mode optical thickness and the aerosol absorption properties together.

5.1.2 Sensitivity study from synthetic data.

To confirm the conclusion obtained in the previous section, we performed a sensitivity study analysis with synthetic data. The particle models and the optical parameters used for the simulations as well as the parameters retrieved with the research algorithm for two different retrieval options are reported in table 4. We use the viewing geometries associated with the hyper-pixel data shown in figure 1-a. We added some noise and calibration errors to the simulations to perform a realistic sensitivity study. We considered 3 cases. For case (1), we ignored the presence of coarse mode particles within the particles size distribution. We considered an AOT of 0.2 at 0.865 μ m. For case (2), we added coarse mode particles in the simulations (coarse mode AOT of 0.05 and fine mode AOT of 0.2 at 0.865 μ m). Case (3) is similar to case (2), but we reduced the cloud-bow magnitude in the simulations respectively by 4%, 7% and 7%, at 0.490, 0.670 and 0.865 μ m, in order to simulate the 3D cloud effects. These values were estimated using the 3D transfer radiative code described in section 2.2.3-b.

When we only consider fine mode particles both in the simulations and in the retrieval method (case 1), the algorithm retrieves aerosol absorption properties (m_i of 0.013 +/- 0.004) that agree well with the ones considered in the simulations ($m_i = 0.015$). The retrieved aerosol SSA is also in good agreement with the one used in the simulations. When we include coarse mode particles both in the simulations and in the retrieval method (case 2), the retrieved absorption properties are underestimated (m_i of 0.006 +/- 0.004 instead of 0.015) and the SSA is overestimated ($0.926 \pm - 0.045$ instead of 0.874 at 0.865 µm). These results indicate that the presence of the coarse mode particles within the particles size distribution perturbs the retrieval of the aerosol absorption properties performed from polarization measurements. These results confirm that the POLDER polarization measurements do not contain enough information to accurately estimate the entire coarse particles properties. This leads to errors on the retrieval of the aerosol absorption properties and then on the retrieved aerosol SSA as the retrieval of the particles size distribution and complex refractive index are connected. The errors on the coarse mode particles properties also affect the retrieval of the complex refractive index. Finally, the 3D cloud effects also impact the retrieval of the aerosol properties. It mainly impacts the retrieval of the AOT (an overestimation of 20% or 0.05 at 0.865 µm) and also slightly affects the retrieval of the aerosol microphysics (e.g. the real refractive index is underestimated).

We note also that the fine mode particles size, the Ångström exponent and the cloud microphysical properties are accurately retrieved for the three cases. These results confirm that the retrieval strategy used in the operational algorithm is well adapted for the retrieval of the biomass burning aerosol properties observed above clouds. For the operational algorithm, we recall that we use a constant value for the complex refractive index and that we only try to retrieve the AOT and the Ångström exponent using fine mode particles models and data acquired for scattering angles smaller than 130°, where the 3D cloud effects are negligible. The main benefit of using the research algorithm to analyze the POLDER data acquired for biomass burning AAC scenes is therefore to obtain an accurate estimate of the microphysical properties of the cloud particles located below the aerosol layer.

5.2 Feasibility study for simultaneous retrieval of aerosol and cloud properties.

5.2.1 Case of biomass burning aerosols above clouds.

We describe hereafter the retrieval option that is finally preferred to simultaneously retrieve the aerosol and cloud properties for biomass burning AAC scenes. Since we cannot accurately retrieve all the aerosol properties, it seems reasonable to consider some assumptions on the aerosol microphysics, for instance on the coarse mode particles properties and on the real refractive index. For solution 5, we made assumptions for the coarse mode particles optical thickness (0.015 at 0.865 μ m), the coarse mode particles effective radius ($r_{eff,c} = 1.97 \,\mu$ m) and for the real refractive index ($m_r = 1.47$). The aerosol parameters included in the vector X are therefore : N_f , $r_{g,f}$, σ_f and m_i . The cloud parameters included in the vector X are therefore : N_f , $r_{g,f}$, σ_f and m_i . The cloud parameters included in the vector X are therefore in the assumptions made for the aerosol properties (e.g. for the size or the coarse mode AOT) directly affects its retrieval. As it is difficult to assess the validity of our assumptions, we test solution 5 to ensure that it can provide an estimate of the aerosol SSA.

We applied this retrieval option to the hyper-pixel defined for the AAC scene with biomass burning aerosols, referred as box (1) in figure 6-a. The results are reported in table 5 as case (1). The hyper-pixel data and the simulations are shown in figure 1-a. Solution 5 provides an estimate of the aerosol SSA equal to 0.815 (+/- 0.045) at 0.865 μ m. This is consistent with biomass burning aerosols in South Africa according to AERONET sunphotometers observations (Dubovik et al., 2002), which gives a mean aerosol SSA of 0.80 +/- 0.004 (at 0.87 μ m) and a mean imaginary part of the complex refractive index of 0.021 +/- 0.004 for biomass burning aerosols observed in the centre of South Africa (Zambia). Our estimate also agrees rather well with the one provided by Leahy et al., (2007), who found an aerosol single scattering albedo of 0.85 +/- 0.02 (regional mean and uncertainty at 0.55 μ m), on the basis of an updated analysis of remote and in situ measurements performed during the Southern African Regional Science Initiative 2000 (SAFARI).

We reported the results obtained for two other hyper-pixels in table 5: case (2) corresponds to an AAC scene encountered for the case study on biomass burning aerosols that is referred as box (2) in figure 6-a and case (3) corresponds to data acquired on the 18th of August 2008 for clouds observed in pristine conditions between South Africa and Antarctica (not shown). Solution 5 was used for both cases. The algorithm retrieves a small value of AOT for case (2) but still retrieves a size distribution dominated by small particles, which suggests a continental origin. The retrieved AOT is also very small (0.022 ± 0.003) for case (3) and the type of particles then cannot be identified since the Ångström exponent cannot be accurately retrieved anymore ($\alpha = 0.88 + 1.08$). Note that some difficulties in the modelling of the polarized radiances can be observed for case (2) for large scattering angles ($\approx 180^\circ$) that are not clearly understood (see figure 1-c). We can only speculate that it could be the result of the scene spatial heterogeneity. In a general way, we note that significant errors in the modeling of the polarized radiances appear in the cloud-bow region when the AAC optical thickness is small (see figures 1-c and 1-d). These are most probably due to 3D cloud effects. Nevertheless, these two results indicate that the AAC optical thickness progressively decreases as we move away from South Africa and that solution 5 remains robust even when the AOT becomes small.

5.2.2 Case of mineral dust particles above clouds.

For mineral dust AAC scenes, we modified solution 5 to include two additional parameters in the retrieval scheme in order to be able to reproduce the POLDER data. Solution 5* is thus similar to solution 5 but includes the retrieval of the coarse mode AOT and the retrieval of the fraction of spherical particles (SF). The aerosol parameters included in the vector X are therefore : N_f, N_c, r_{g,f}, σ_f , m_i and SF. We applied solution 5* to the AAC scene with mineral dust particles, referred as box (3) in figure 8-a, which was observed on the 25th of July 2008. The results are reported in table 5 as case (4).

The algorithm retrieves AOT values larger than 1 and a large amount of non-spherical particles. The algorithm then retrieves a size distribution dominated by non-spherical coarse mode particles that shows much smaller absorption properties than biomass burning aerosols. Mineral dust particles also absorb the solar light due to the presence of iron oxide in their mineral composition (Derimian et al., 2008a). However, dust remains less absorbing than biomass burning aerosols, except probably for cases where it is mixed with carbonaceous material (Derimian et al., 2008b). Note that we should have retrieved the spectral dependence for the imaginary part of the complex refractive index since mineral dust particles typically show slightly higher absorption properties for shorter visible wavelengths (0.67 and 0.865 μ m). We however choose to hold constant this parameter with wavelength to limit the number of retrieved parameters. This would have to be revised in case shorter wavelength observations were to be incorporated.

This particles model is the mineral dust particles model implemented in the operational algorithm. It was used to retrieve the AOT above clouds shown in figures 10-a and 10-b. This is justified since this model allows to reproduce well the POLDER data (see figure 1-b) and also because the retrieved optical and microphysical properties (i.e. Ångström exponent, complex refractive index and shape) are realistic for mineral dust particles according to Dubovik et al., (2002).

5.2.3 Retrieval of cloud droplets properties.

The parameters retrieved with the research algorithm for the cloud droplets are reported in table 5. The retrieved real refractive index values are in good agreement with what we expect for cloud droplets made of pure water (Hale et al., 1973). Our algorithm retrieves droplets effective radii varying between 8 and 12 μ m with no peculiar geographical tendency. The retrieved droplets size distribution is much narrower (small values of effective variance) for the clouds observed southern-eastern of the South Africa (18th of August 2008) than for the clouds observed over the two other oceanic tropical regions located closer to Africa. This is in good agreement with the results of Bréon and Doutriaux-Boucher (2005), who found that the droplets effective variance is generally much smaller for the clouds observed in subtropical and high-latitude oceans, than for continental regions and other oceanic regions. The reasons for this tendency cannot be currently established with confidence. We recall that the droplets effective variance was not much studied from space and that this parameter depends on the dynamical evolution of clouds (Politovich, 1993) and on the origin of the air mass (continental or maritime) (Martin et al., 2004).

We also compared the droplet effective radii retrieved with POLDER with those retrieved by MODIS. Table 6 show some comparisons performed for various scenes with aerosols above clouds and for the fields of clouds observed in pristine conditions. The droplet effective radius reported for MODIS is a mean value computed over the 200 km \times 200 km area. Differences are expected between these two estimates since the polarized measurements are sensitive to droplets located at the top of the cloud layer whereas the MODIS total radiance measurements are sensitive to droplets located deeper in the cloud layer (Bréon and Doutriaux-Boucher, 2005). Another sources of differences are (1) biases expected on the

MODIS retrieved droplets effective radius for AAC scenes with absorbing aerosols and (2) uniqueness of the droplets effective variance in the MODIS algorithm (0.13). Bréon and Doutriaux-Boucher (2005) found a systematic MODIS high bias of 2 μ m in oceanic regions for droplets effective radii larger than 7 μ m. This is close to what we observe for the clouds in pristine conditions. The departures that we observed for AAC scenes are smaller probably because the droplets effective radii retrieved by MODIS are underestimated due to the presence of absorbing AAC (Haywood et al., 2004).

6. Conclusion

This study confirms that passive sensors with angular, spectral and polarized capabilities have a strong potential for retrieving the Aerosol Above Clouds (AAC) optical and microphysical properties. An interesting result of this study is that polarized measurements acquired in the cloud bow can be used to retrieve the optical thickness of the mineral dust particles residing above liquid clouds. These large non-spherical particles do not much polarize light but strongly attenuate the polarized cloud bow generated by the beneath liquid cloud layer. The spectral attenuation can be used to qualitatively identify the nature of the particles (coarse or fine mode particles) whereas the magnitude of the attenuation is related to the optical thickness of the aerosol layer.

We developed two different algorithms to analyze the POLDER data for AAC scenes. The first one, the so-called research algorithm, allows a simultaneous retrieval of the aerosol and cloud properties and uses POLDER data aggregated at a coarse resolution to have a sufficient angular sampling. The method retrieves the mean properties of the observed particles under the assumption of spatial homogeneity. For clouds, this method also allows to accurately retrieve the cloud droplet effective variance and the cloud droplets effective radius. Our results tend to confirm that the droplets size distribution is narrow in high latitude ocean regions and that the droplets effective radius retrieved from polarization measurements is generally slightly smaller than the one retrieved by passive sensors that uses total radiance measurements, such as the MODIS instrument (departures smaller than 2 μ m). In addition, we show that the aerosol parameters that can be retrieved with the research algorithm are: the AOT, the fine mode particles size and the Ångström exponent. The fraction of spherical particles can be also retrieved for mineral dust AAC scenes. The coarse mode particles size, the relative contribution of the two modes to the total AOT as well as the complex refractive index cannot be estimated with confidence with this method.

An operational algorithm was developed to retrieve the aerosol properties for AAC scenes at a finer spatial resolution and at a large scale. This method retrieves the AOT and the Ångström exponent for the fine mode particles and the AOT for mineral dust particles using a non-spherical particles model. With respect to the algorithm described in Waquet et al., (2009a), we improved the accuracy of the modelling, included a realistic mode for mineral dust particles and developed a retrieval strategy that takes advantage of the measurements acquired in the cloud bow direction. The method is however limited to observations acquired for optically thick clouds (optical thickness > 5) and only considers a finite number of aerosol models. We compared the AOTs retrieved above clouds with ones retrieved closely over clear-sky ocean pixels. We found maximal differences of 0.2 in AOT at 0.865 μ m that can be explained either by the assumptions used for the microphysical properties of the aerosols, that are different in the two algorithms or because the algorithm developed for cloud-free ocean scenes measures the aerosol load integrated over the entire atmospheric column whereas the AAC algorithm only retrieves the AOT of the particles residing above the cloud top.

From simulated data, we also showed that the magnitude of the cloud bow in polarization cannot be accurately estimated with a plane parallel transfer radiative code. The errors for the

modelling of the polarized radiances vary between 4 and 8% depending on wavelength and viewing geometry. It impacts the retrieval of the AOT by around 6% when a mineral dust model is used to retrieve the AOT and can reach 20% if the particles microphysical properties and the AOT are simultaneously retrieved. However, according to our results, the 3D effects do not much affect the retrieval of the cloud microphysics performed from polarization measurements. But we considered only one type of heterogeneity (spatial variability in the cloud optical thickness) and a limited number of cases and rather homogenous clouds. More research is therefore needed to better quantify the impacts of the 3D cloud effects on the retrieval of the particles microphysics observed in cloudy scenes.

Any of the two methods described allow the estimation of the aerosol absorption properties and the aerosol single scattering albedo (SSA). However, it is a key parameter for the estimate of the AAC radiative direct forcing. Some assumptions on the aerosol absorption properties will therefore be considered in order to estimate the AAC direct radiative forcing with the data provided by the operational algorithm. For example, a climatology of the aerosol absorption properties derived from ground-based sun-photometer measurements could be used.

In order to better characterize the AAC properties, the AOT retrieved with the lidar CALIOP could be considered in the future to check the coherence of our retrievals made over clouds or to better constrain the retrieval of the aerosol microphysics using innovative synergetic approaches. Other POLDER data could be also potentially included in the method, such as the total radiance measurements, which provide more sensitivity to aerosol absorption properties. We however point out that the present algorithm, solely based on the use of polarization measurements, has the high advantage, with respect to other passive methods, of being independent on the cloud layer albedo.

A rather strong positive radiative forcing as well as significant biases on the retrieved cloud properties is expected when a high loading of strong absorbing aerosols is present above clouds. First results obtained with POLDER indicate large mean AOTs above clouds for oceanic regions near the coasts of South Africa for biomass burning aerosols or even larger mean AOTs above clouds are retrieved near the coasts of Senegal. In order to refine our assement on radiative forcing, more investigations are needed to better describe the spatial and temporal variability of the AAC properties. Our next step is thus the analyze of the complete archive of POLDER data. This would provide a first global estimate of the properties of the aerosols suspended above clouds and so to first estimate the much uncertain aerosol direct forcing over cloudy skies.

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Annex :

The retrieval error covariance matrix for the optical thickness τ .

$$C_{\tau} = K_{\tau} C_X K_{\tau}^T \tag{A-1}$$

where K_{τ} is the Jacobian matrix for τ . The same formula stands for the aerosol single scattering albedo (ω_0) and effective radius (r_{eff}).

The effective radius, r_{eff}, for log normal size distribution is defined as :

$$r_{eff} = r_g \exp\left(\frac{5}{2}\sigma^2\right) \tag{A-2}$$

Mean squared error term $\boldsymbol{\epsilon}$ calculated between the measured and calculated polarized radiances :

$$\varepsilon = \sqrt{\frac{1}{N_{\Theta}N_{\lambda}} \sum_{i=1}^{N_{\Theta}} \sum_{j=1}^{N_{\lambda}} \left[L_{ij}^{mes}(\Theta) - L_{ij}^{calc}(\Theta) \right]^2}$$
(A-3)

where N_{Θ} and N_{λ} are respectively the number of selected viewing directions and the number of channels.

The SOS code requires a Legendre polynomial expansion of the phase matrix. The forward peak of the phase function (i.e. the P11 element of the phase matrix) is generally sharp for large particles such as cloud particles, which requires to increase the number of terms in the expansion of the phase matrix. A truncation procedure of the forward scattering peak is implemented in the SOS code (Potter, 1970, Nakajima and Tanaka, 1998). This procedure allows a faster modelling of the radiances. We however noted that this procedure introduces small errors in the modelling of the upwelling polarized radiance under specific circumstances that are encountered in this paper. Errors appear when large spherical particles are considered and when the polarized radiance is saturated (optical thickness >3.). Significant errors appear in the primary cloud bow region. The magnitude of the primary cloud-bow is overestimated by 7.5% when the procedure of truncation is invoked. Calculations performed for a truncation applied to scattering angles between 0° and 16° , for a droplet effective radius of 10 μ m, a droplet effective variance of 0.06, cloud optical thickness of 5 and a sun zenith angle of 37°. The reasons for this issue are not fully understood and the solving of this technical problem will be attempted in a future effort. In the research algorithm, we use an exact 1D modelling (no truncation) at the end of each step in the iteration to compare the observations to the simulations whereas the intermediate calculations (i.e. the Jacobian matrix elements) are performed using the approximation of truncature.

I apics .	Tables	:
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Parameters	$ au_{\mathrm{f}}$	τ _c	$r_{ m g,f} \ (\mu m) \ \sigma_{ m f}$	r _{g,c} (μm) σ _c	m _r	m _i	Shape (SF)	r _{eff,cld} (µm)	V _{eff,cld}	m _{r,cld} 0.865 μm 0.67 μm 0.49 μm
<i>A priori</i> information	5.10^{-3} (+ ∞)	10^{-3} (+ ∞)	0.15 (0.1) 0.4 (0.2)	$0.8 \\ (0.1) \\ 0.6 \\ (0.3)$	1.47 (0.14)	10 ⁻³ (0.1)	0.5 (0.5)	10.0 (10.0)	0.06 (0.06)	$ \begin{array}{c} 1.330 \\ (0.01) \\ 1.331 \\ (0.01) \\ 1.338 \\ (0.01) \end{array} $

Table 1. *A priori* knowledge of the aerosol and cloud parameters (f=fine mode, c=coarse mode, cld=cloud) and associated uncertainties ().

Symbol	Description	Measurements and method	Product affiliation (when available)		
COT (Δ_COD)	Mean cloud optical thickness and associated standard deviation	MODIS total radiances measurements acquired at 0.865	Level-2 MODIS06 cloud product given at		
REFF_CLD_M (A_REFF_CLD_ M)	Mean cloud droplets effective radius and associated standard deviation (µm)	and 2.13 µm (Platnick et al., 2003).	pixel resolution of 1×1 km ² .(Platnick et al, 2003).		
z _c _Rayleigh	Cloud top height (1) (km)	Rayleigh cloud top pressure method : POLDER polarization signal of the molecules located above the clouds (Goloub et al., 1994).	RB2 (Radiative Budget Level 2) cloud products given at pixel resolution		
z _c _O ₂	Cloud top height (2) (km)	Apparent O2 cloud pressure method: Differential absorption measurements in the oxygen A- band of POLDER (Vanbauce et al., 2003).	of 18.5 km × 18.5 km (Parol et al., 2004).		
z _c _IR	Cloud top height (3) (km)	IR cloud top pressure method : MODIS measurements acquired in the thermal infrared (Menzel et al, 2006).	MYD06 cloud product that provides data at a resolution of 5 km × 5 km (Platnick et al, 2003).		
phase_index	Cloud thermodynamic phase index ranging from confident liquid phase only to confident ice only $(0 < \varphi_{CLD} < 200)$.	POLDER polarization measurements combined with MODIS measurements acquired in the solar spectrum and thermal infrared (Riedi et al., 2010).	PM-L2.v1.00 cloud products that provides data at 6 km x 6km available from icare.univ-lille1.fr		

Table 2. Cloud parameters retrieved by POLDER and MODIS using different standard algorithms used to select the scene for the operational algorithm developed for AAC scenes.

τ(λ) 865nm 670 nm 490nm	α	r _{eff,f} (μm)	r _{eff,c} (μm)	m _i	SSA(λ) 865nm 670 nm 490nm	m _r	Shape (SF)	r _{eff,cld} (μm) V _{eff,cld} m _{r,cld} (λ) 865nm 670 nm 490nm	$\epsilon \times 10^3$	
	Solution 1									
0.25(0.01) 0.46(0.01) 0.82(0.015)	2.32 (0.20)	0.175 (0.001)	No coarse mode particles	0.001	0.992(10 ⁻⁴) 0.9935(10 ⁻⁴) 0.9945(10 ⁻⁴)	1.47	1	8.3(0.3) 0.10(0.01) 1.330(0.001) 1.333(0.003) 1.344(0.003)	1.229	
Solution 2										
0.29(0.015) 0.48(0.02) 0.84(0.02)	2.0 (0.35)	0.171 (0.0015)	1.74 (0.12)	0.001	$\begin{array}{c} 0.988(10^{-4})\\ 0.9902(10^{-4})\\ 0.992(10^{-4}) \end{array}$	1.47	1	8.3(0.3) 0.09(0.015) 1.330(0.002) 1.334(0.003) 1.345(0.003)	1.137	
			•	Se	olution 3			• • • •		
0.31(0.02) 0.51(0.02) 0.87(0.025)	1.90 (0.36)	0.165 (0.002)	2.77 (0.43)	0.014 (.0035)	0.84(0.035) 0.875(0.03) 0.90(0.025)	1.47	1	8.4(0.3) 0.08(0.015) 1.331(0.002) 1.334(0.003) 1.344(0.003)	1.051	
	Solution 4									
0.30(0.025) 0.50(0.02) 0.88(0.025)	1.96 (0.42)	0.171 (0.005)	1.85 (1.2)	0.017 (0.007)	0.835(0.055) 0.865(0.045) 0.895(0.035)	1.45 (0.015)	1	8.3(0.3) 0.08(0.01) 1.330(0.002) 1.333(0.003) 1.343(0.003)	0.997	

Table 3. Aerosol and cloud retrieved parameters for various inversion schemes in case of a biomass burning particles layer located above liquid cloud and associated uncertainties (). The cloudy area is shown in figure 6-a (box 1). The different solutions correspond to the adjustement of a different number of parameters. The parameters that are not adjusted during the retrieval process are indicated in bold. ε is the mean squared error term calculated between the measured and simulated polarized radiances (×10³).

τ(λ) 865nm 670 nm 490nm	α	r _{eff,f} (μm)	r _{eff,c} (μm)	m _i	SSA(λ) 865nm 670 nm 490nm	m _r	Shape (SF)	r _{eff,cld} (μm) ^V eff,cld m _{r,cld} (λ) 865nm 670 nm 490nm	ϵ ×10 ³
Input parameters for case (1) used to create synthetic data									
0.20 0.32 0.49	1.83	0.199	No coarse mode particles	0.015	0.909 0.920 0.924	1.49	1	11.5 0.09 1.330 1.333 1.338	/
			Retrie	ved narai	meters for case (1	1)		1.550	
0.21(0.01) 0.33(0.01) 0.51(0.01)	1.74 (0.26)	0.190 (0.003)	No coarse mode particles	0.013 (0.004)	0.918(0.023) 0.927(0.020) 0.930(0.019)	1.470 (0.001)	1	11.49(0.36) 0.09(0.010) 1.330(0.001) 1.333(0.002) 1.338(0.002)	0.451
		Input	parameters	for case (2	2) used to create	synthetic	data		
0.25 0.37 0.54	1.66	0.199	2.553	0.015	0.874 0.891 0.901	1.49	1	11.5 0.09 1.330 1.333 1.338	/
		I	Retrie	ved para	meters for case (2	2)			
0.27(0.01) 0.38(0.02) 0.56(0.02)	1.38 (0.36)	0.187 (0.009)	2.46 (0.709)	0.006 (0.004)	0.926(0.045) 0.934(0.039) 0.940(0.034)	1.474 (0.013)	1	$ \begin{array}{r} 11.46(0.39)\\ 0.09(0.011)\\ 1.338(0.002)\\ 1.331(0.002)\\ 1.329(0.001) \end{array} $	0.447
Retriev	ed parame	eters for case	(2) when the	synthetic	data also accour	nts for the	e 3D trans	sfer radiative effe	ects
$\begin{array}{c} 0.31(0.01)\\ 0.43(0.02)\\ 0.61(0.02) \end{array}$	1.31 (0.32)	0.194 (0.010)	2.17 (0.530)	0.007 (0.004)	0.924(0.042) 0.931(0.037) 0.936(0.034)	1.458(0.012)	1	11.38(0.41) 0.08(0.011) 1.338(0.002) 1.331(0.002) 1.330(0.001)	0.492

Table 4 : Description of the particles microphysics used to create synthetic data for AAC scenes with biomass burning aerosols and synthetic retrievals obtained for different retrieval options. The parameters that are not adjusted during the retrieval process are indicated in bold. ε is the mean squared error term calculated between the measured and simulated polarized radiances (×10³).

τ at 865nm	a	r _{eff,f} (μm)	r _{eff,c} (μm)	m _i	SSA at 865nm	m _r	Shape ratio	r _{eff,cld} (μm) V _{eff,cld} m _{r,cld} at 865 nm a high loading of a	ϵ $\times 10^3$
Case I . Ca	•		0	-	arized measuren	0		0 0	10103013
0.28 (0.01)	2.17 (0.23)	0.165 (0.0025)	1.97	0.024 (0.0065)	0.815(0.045)	1.47	1	8.5(0.30) 0.09(0.015) 1.331(0.002)	1.028
Case 2 : Cas	Case 2 : Case study with biomass burning aerosols acquired on the 4 of August 2008, with few aerosols above clouds								
	(\$	ee figure 6-a	<u>, box 2). T</u>	he polarized	measurements a	re show	<u>n in figur</u>		
0.063 (0.004)	1.80 (0.48)	0.148 (0.006)	1.97	[0 ; 0.0055]	[1;0.93]	1.47	1	9.21(0.13) 0.045(0.005) 1.341(0.001)	1.584
Case 3 : A	Case 3 : A very clear case with only liquid clouds ; far away from continental sources of aerosols, acquired on the 18 of August 2008 (not shown). The polarized measurements are shown in figure 1-d.								
0.022 (0.003)	0.88 (1.08)	0.19 (0.023)	1.97	[0;0.013]	0.9 (0.1)	1.47	1	10.67(0.12) 0.0087(0.0015) 1.329(0.001)	0.958
Case 4 : ca	Case 4 : case study on mineral dust particles above clouds acquired on the 25 of July 2008 (see figure 8-a, box 3). The polarized measurements are shown in figure 1-b.								
1.05 (0.07)	0.35 (0.5)	0.30 (0.045)	2.55	0.0007 (0.000035)	0.983(0.002)	1.47	0.11 (0.07)	12.3(1.46) 0.11(0.036) 1.329(0.003)	0.950

Table 5. Aerosol and cloud retrieved parameters and associated uncertainties () or min and max values [] retrieved with solution 5 for various situations and with solution 5* for the case related to a dust layer located above clouds. The parameters that are not adjusted during the retrieval process are indicated in bold. ε is the mean squared error term calculated between the measured and simulated polarized radiances (×10³).

	Dust (25 of July 2008)	Biomass (04 of August 2008)	Biomass (04 of August 2008)	Clear case (18 of August 2008)	
τ at 0.865 μm	1.05 (+/- 0.07)	0.28 (+/- 0.01)	0.063 (+/-0.004)	0.022 (+/-0.003)	
MODIS r _{eff,cld} (µm)	12.1	9	10.3	12.9	
POLDER r _{eff,cld} (µm)	12.3 (+/- 1.5)	8.5 (+/- 0.3)	9.21(+/- 0.13)	10.7 (+/- 0.12)	

Table 6. Comparisons between the droplet effective radii ($r_{eff,cld}$) retrieved with MODIS and POLDER and associated uncertainties for POLDER (+/-). Scenes with aerosols above clouds ($0.06 < \tau < 1.05$) and a cloudy scene observed in pristine conditions (τ of about 0.02).

Figures :

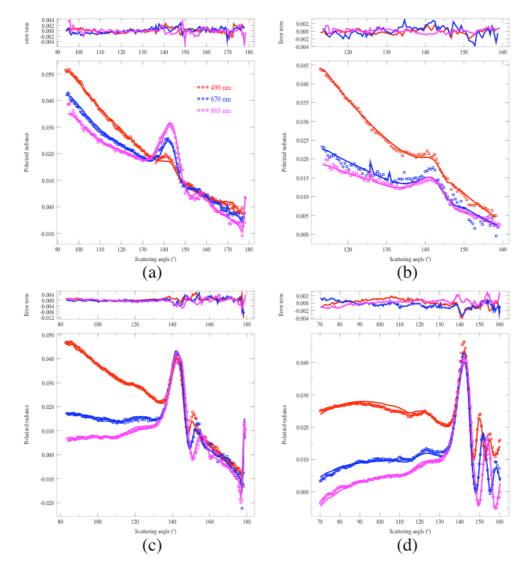


Figure 1. Simulated and measured polarized radiance for various cases : (a) biomass burning aerosols above clouds, (b) mineral dust aerosol above clouds, (c) few biomass burning particles above clouds and (d) only liquid clouds far away from the sources of aerosols. The red, blue and magenta lines are the simulations performed at 0.49, 0.67 and 0.865 μ m whereas the dots are the measurements. The upper figures show the absolute differences between measured and simulated polarized radiances. The measured polarized radiances are aggregated at a spatial scale of 200 x 200 km² (i.e. hyper-pixel). The hyper-pixel shown in figure 1-a, 1-b, and 1-c corresponds respectively to the box 1 in Figure 6-a, to box 3 in figure 8-a, to the box 2 in figure 6-a and the hyper-pixel (d) corresponds to an area located far away from continental sources of aerosols with only liquid clouds (not shown). The aerosol and cloud parameters retrieved for each hyper-pixel are given in table 5.

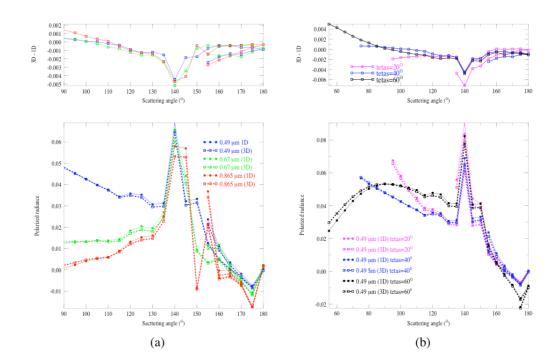


Figure 2. (a) 1D vs 3D simulations of the polarized radiance for a liquid cloud for 3 wavelengths and (b) 3 different sun angles. Dashed lines for 3D calculations and solid lines for 1D calculations. The red, green and blue lines in figure (a) correspond to the wavelengths 0.865, 0.670 and 0.490 μ m and a sun zenithal angle of 40°, whereas the blue, black and magenta lines in figure b correspond to sun zenithal angles of 20, 40 and 60° and to the wavelength 0.49 μ m. The absolute differences between the 3D and 1D calculations are shown in the upper figures.

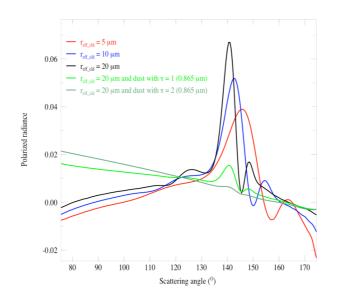


Figure 3. Polarized radiances simulated at 0.865 μ m for liquid clouds as a function of the scattering angle. Three droplets effective radii are considered ($r_{eff,cld} = 5$, 10 and 20 μ m). In green, additional simulations performed with mineral dust particles suspended above liquid clouds for two aerosol optical thicknesses ($\tau = 1$ and 2). The droplets effective radius of the cloud layer located below the aerosol layer is equal to 20 μ m and the cloud optical thickness is equal to 5 for all calculations.

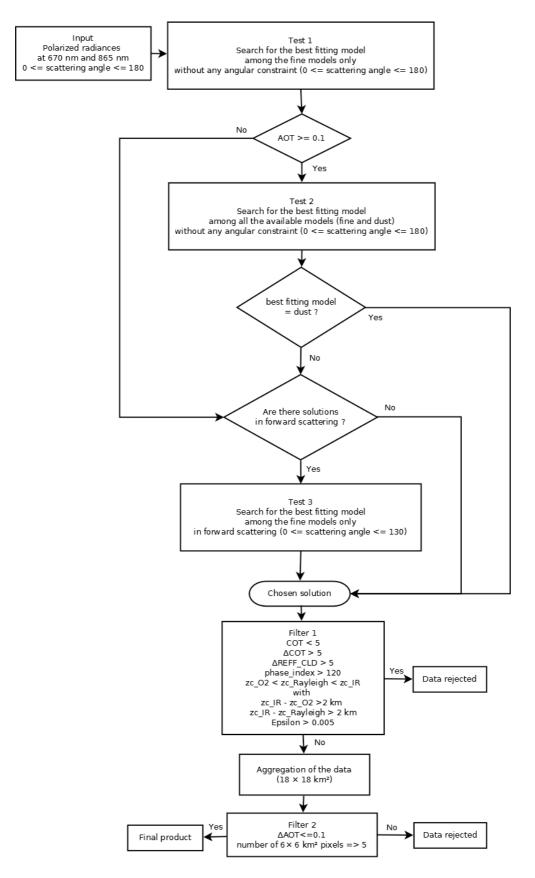


Figure 4. Schematic view of the operational algorithm used to retrieve the aerosol properties above clouds at a global scale from POLDER polarization data acquired at 0.67 and 0.865 μ m and MODIS/POLDER combined cloud products.

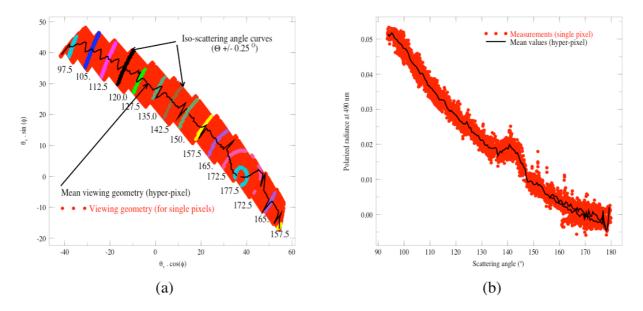


Figure 5. (a) Viewing geometry represented in polar coordinates for each single pixel of 6 km \times 6 km (red dots) observed by POLDER within an area of 200 \times 200 km² (the « hyper-pixel »). The mean viewing geometry for the hyper-pixel is the black line. (b) Polarized radiances measured for each single pixel (red dots) and mean polarized radiance for the hyper-pixel (black line).

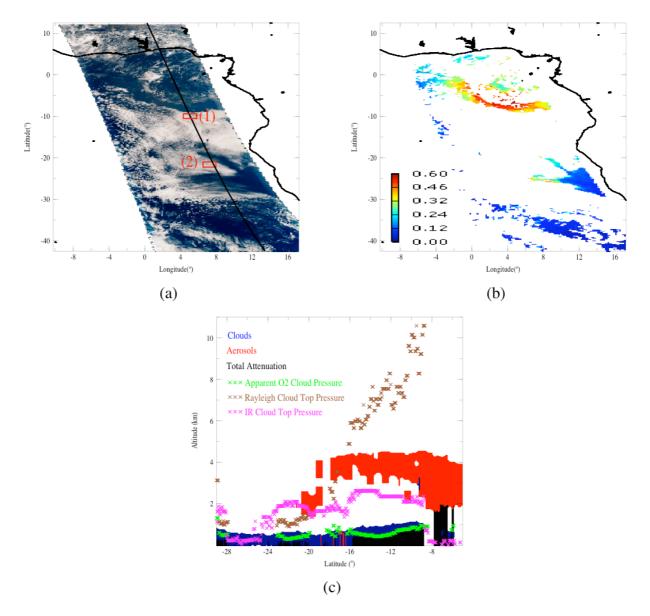


Figure 6. A case study on biomass burning aerosols related to the 4 of August 2008 acquired over the tropical southeast part of the Atlantic Ocean. (a) RGB composites of POLDER/PARASOL measurements in total radiance and lidar CALIOP track (black line). The POLDER image was produced using a combination of the POLDER spectral bands centered on 0.490 μ m, 0.565 μ m and 0.670 μ m. (b) Total aerosol optical thickness retrieved by POLDER at 0.865 μ m using the operational algorithm developed for ocean cloud-free scenes. (c) Vertical distribution of the cloud and aerosol layer structures derived from the CALIOP measurements (VFM products) and different estimations of the cloud top height retrieved using passive remote sensing techniques (crosses), as a function of latitude.

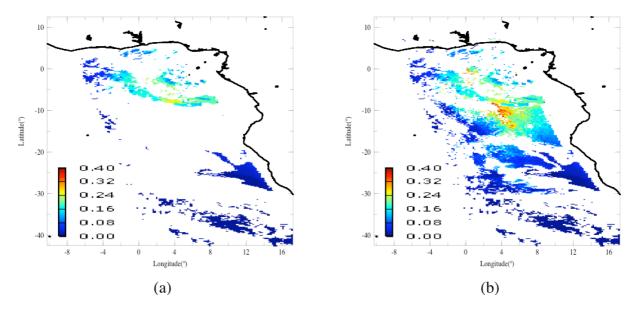


Figure 7. Fine mode scattering optical thickness retrieved by POLDER at 0.865 μ m over (a) cloud-free ocean scenes and (b) over both cloud-free and cloudy scenes. The cloudy structures are visible in figure 6-a. The corresponding total aerosol optical thickness retrieved only for cloud-free scenes is shown in figure 6-b.

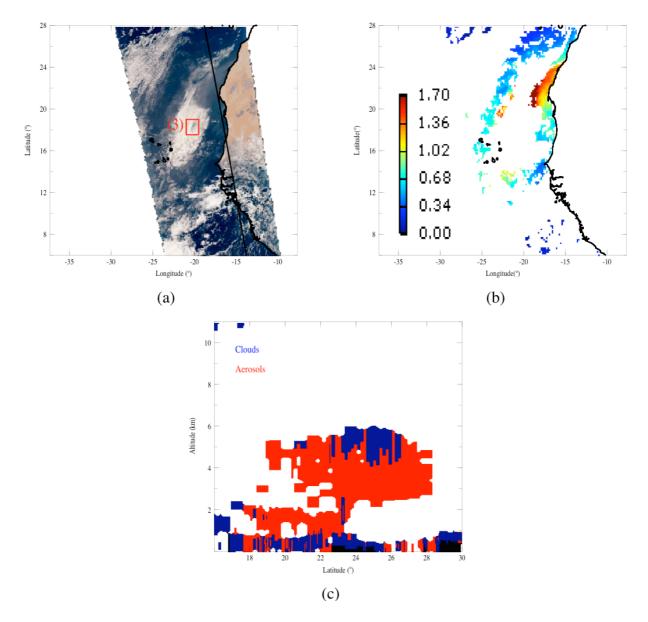


Figure 8. Case study on mineral dust particles related to the 25 of July 2008 acquired over the tropical northeast part of the Atlantic Ocean. Same figures type as the ones shown in figure 6. The cloud top heights retrieved with passive methods are not reported here since the cloud observed by POLDER is outside the CALIOP track.

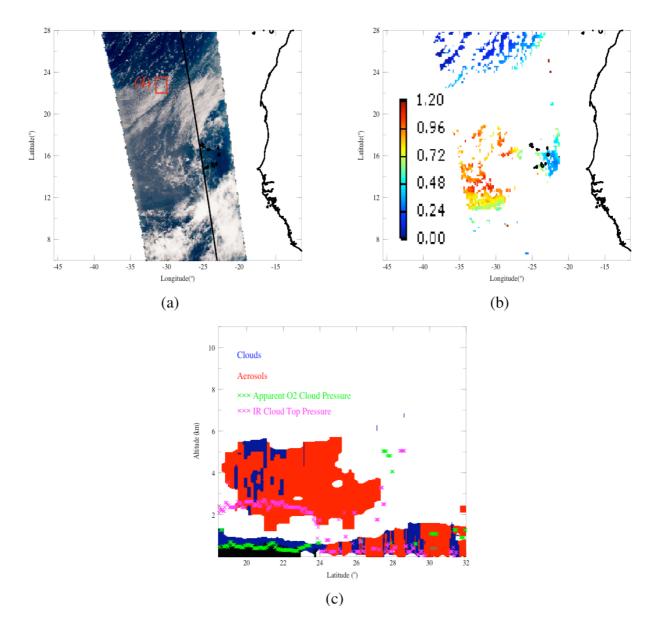


Figure 9. Case study on mineral dust particles related to the 4 of August 2008 acquired over the tropical northeast part of the Atlantic Ocean. Same figures as in figures 6 and 7. The so-called « Rayleigh cloud top pressure » is not available for this case due to unfavorable geometric conditions.

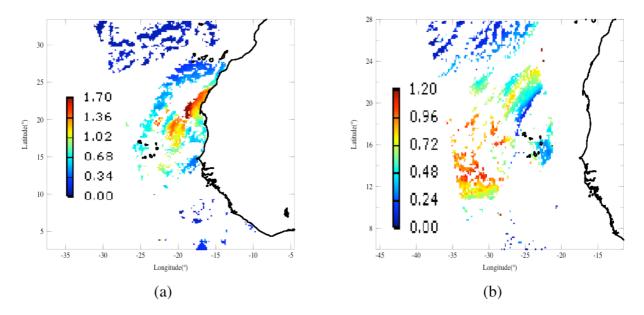


Figure 10. Total optical thickness retrieved by POLDER at 0.865 μ m over both cloud-free ocean scenes and cloudy scenes, for the case studies on mineral dust particles acquired on (a) the 25 of July 2008 and (b) on the 4 of August 2008. The cloudy structures are visible in figure 8-a and 9-a for the 25 of July 2008 and for the 4 of August 2008, respectively. The corresponding total aerosol optical thickness retrieved only for cloud-free scenes is shown in figure 8-b and 9-b, for the 25 of July 2008 and for the 4 of August 2008, respectively.