Interpretation of observed microwave signatures from ground dual polarization radar and space multi frequency

- 3 radiometer for the 2011 Grímsvötn volcanic eruption.
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16 Abstract

17 The important role played by ground-based microwave weather radars for the monitoring of volcanic ash clouds has been recently demonstrated. The potential of microwaves from 18 19 satellite passive and ground-based active sensors to estimate near-source volcanic ash cloud 20 parameters has been also proposed, though with little investigation of their synergy and the 21 role of the radar polarimetry. The goal of this work is to show the potentiality and drawbacks 22 of the X-band Dual Polarization radar measurements (DPX) through the data acquired during 23 the latest Grímsvötn volcanic eruptions that took place on May 2011 in Iceland. The analysis 24 is enriched by the comparison between DPX data and the observations from the satellite 25 Special Sensor Microwave Imager/Sounder (SSMIS) and a C-band Single Polarization (SPC) 26 radar. SPC, DPX, and SSMIS instruments cover a large range of the microwaves spectrum, operating respectively at 5.4, 3.2, and 0.16-1.6 cm wavelengths. 27

1 The multi-source comparison is made in terms of Total Columnar Concentration (TCC). The 2 latter is estimated from radar observables using the "Volcanic Ash Radar Retrieval for dual-3 Polarization X band systems" (VARR-PX) algorithm and from SSMIS brightness temperature 4 (BT) using a linear BT - TCC relationship. The BT- TCC relationship has been compared with 5 the analogous relation derived from SSMIS and SPC radar data for the same case study. Differences between these two linear regression curves are mainly attributed to an incomplete 6 7 observation of the vertical extension of the ash cloud, a coarser spatial resolution and a more 8 pronounced non-uniform beam filling effect of SPC measurements (260 km far from the 9 volcanic vent) with respect to the DPX (70 km from the volcanic vent). Results show that high-spatial-resolution DPX radar data identify an evident volcanic plume signature, even 10 11 though the interpretation of the polarimetric variables and the related retrievals is not always straightforward, likely due to the possible formation of ash and ice particle aggregates and the 12 13 radar signal depolarization induced by turbulence effects. The correlation of the estimated 14 TCCs derived from DPX and SSMIS BTs reaches -0.73.

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16 **1** Introduction

17 The ability to recognize the signature of volcanic ash clouds on remote sensing data, and 18 therefore to retrieve quantitatively their physical parameters, is of significant importance. The 19 volcanic ash dispersed in the atmosphere after an eruption may have an impact on the 20 environmental, climatic, and socio-economic effects (Cadle et al., 1979). Regular monitoring of volcanic emissions can provide information on the underlying volcanic processes and it can 21 22 serve as an input source for modelling trajectories of airborne ash (Sparks 2003). Many recent 23 research efforts have been focusing on the characterization of volcanic plumes and their 24 dynamics into the atmosphere.

Investigating the ash dispersion in the atmosphere from remote also offers the practical 25 advantage to monitor it in near-real time, thus avoiding impractical or even dangerous 26 27 conditions of in situ sampling. In this perspective, remote sensing observations provided by visible, infrared, and microwave remote sensors on either ground or satellite platforms, are of 28 particular interest. When the observation is close to the volcano vent, remote sensing 29 30 instruments can be used to estimate the *near-source* eruption parameters. The most important 31 near source parameters are the plume height and the tephra eruption rate and mass (Mastin et al., 2009; Marzano et al., 2011, Vulpiani et al., 2011, Maki et al, 2012). The retrieval of these 32

parameters represents an important input for Lagrangian ash dispersion models, which are
 used to predict the geographical areas likely to be affected by significant levels of ash
 concentrations (Webley et al., 2009).

4 Sensors from geostationary Earth orbit (GEO) platforms are exploited for long-range 5 trajectory tracking and for measuring eruptions with low ash content (Rose et al., 2000). GEO 6 imagery is available every 15-30 minutes at 3-5 km spatial resolution. When GEO radiometric 7 measurements at visible-infrared wavelengths are used, water and ice clouds above the ash 8 plume may partially block the sensor field of view, thus making the observations not useful 9 for ash tracking. This feature becomes problematic especially at night, when the lack of 10 visible observations does not allow for ash/water cloud discrimination.

11 Compared to GEO, sensors in low Earth orbits (LEO) have a longer revisit time (more than 12 hours) but enhanced spatial resolutions, which varies from several kilometers down to 13 meters, depending upon the sensor and wavelength used (e.g., Grody et al., 1996; Marzano et 14 al., 2013).

Ground based instruments usually have spatial and temporal resolutions higher than GEOLEO sensors, though their areal coverage may reach few hundreds of kilometers at most.

Either from ground or space, remote sensors operating at infrared and visible wavelengths suffer from strong ash cloud opacity (mixed with water cloud at times) due to the significant radiation extinction, which is often the case in the proximity of the volcanic source. In this respect, the exploitation of passive microwave sensors represents a good opportunity to probe ash clouds, despite some inherent limitations (Delene et al., 1996; Grody et al., 1996, Marzano et al., 2012; Montopoli et al., 2013).

23 In this work the signature of the ash plume at microwave wavelengths is discussed using the available measurements collected during the Grímsvötn eruption in Iceland on May 22nd, 24 25 2011. Retrievals of mass loading from space observations obtained from the LEO passive 26 Special Sensor Microwave Imager/Sounder (SSMIS) are compared with those derived using ground-based radars. Radar data are provided by the X-band Dual Polarization radar (DPX), 27 28 operated in Iceland during 2011 on loan from the Italian Department of Civil Protection to the 29 Iceland meteorological office. SSMIS acquisitions are obtained from the U.S. Defense 30 Meteorological Satellite Program (DMSP) F-17 satellite. Data from the single-polarization 31 radar at C-band (SPC), operated at the Keflakik airport in Iceland, are also considered.

One of the original elements of this work is the use of DPX data to experimentally investigate the role of the radar polarimetry for quantitative estimation of ash plume properties. The analysis of the sensitivity of millimetre-wavelengths to ash content and spatial distribution is discussed to anticipate the potential that will be available in the future with the launch of the first millimeter-wave (frequencies from 183 to 664 GHz) payload aboard the second generation of European polar-orbiting satellites.

The paper is organized into five sections. Section 2 describes the characteristics of the sensors and the definition of measured quantities used here. Section 3 gives the interpretation of the measured quantities for the case study under analysis. Section 4 shows the results of the multi-sensor quantitative estimates of ash and the comparisons between DPX, SPC and SSMIS retrievals. Section 5 provides the summary and final remarks.

12

13 2 Data description

In the following subsections the radar and radiometric variables from DPX and SSMIS are introduced and the characteristics of both sensors are given. Although dual polarization observations are fairly consolidated for meteorological studies they are relatively new for ash volcanic applications. Thus, some basic details of the polarimetric radar variables are given hereafter.

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20 2.1 Ground-based X-band radar measurements

21 The DPX sensor is a mobile compact weather radar that is relatively easy to move to the 22 desired locations in case of an ongoing eruption, due to its deployment on a trailer. For the event of 22nd of May 2011, it has been positioned in the Kirkjubæjarklaustur, southern 23 Iceland, at approximately 70 km away from the Grímsvötn volcano (Petersen et al., 2012). 24 25 The list of the main technical specifications of DPX is in Table 1. Figure 1 gives a representation of the theoretical radar ray paths in a range-height reference system for the 26 27 elevation angles scanned by the radar antenna. A standard atmosphere is assumed to compute 28 the radar ray paths. The DPX data we used have a range and azimuth resolutions of 0.20 km and 1 deg, respectively. The observation geometry is such that the DPX sampling volume 29

1 over the volcano position (i.e., approximately 70 km far from the radar site) is approximately $\frac{1}{2}$

2 0.59 km^3 .

3 2.1.1 Polarimetric radar observables

Being a dual polarization system, DPX transmits and receives electromagnetic energy in two orthogonal polarization states: the horizontal (*H*) and the vertical (*V*) one. The variables, obtained from DPX are the radar reflectivity factors (Z_{VV} and Z_{HH}) in dBZ, the differential reflectivity (Z_{DR}) in dB, the correlation coefficient (ρ_{HV}) and the specific differential phase shift (K_{DP}) in °/km. They are defined as follows (eg. Bringi et al., 2001; Marzano et al., 2012):

9

10
$$Z_{XX} = 10 \log_{10} \left(\frac{4\pi\lambda^4}{\pi^5} < N(D_e) \cdot \left| S_{XX}^{(b)}(D_e, \varphi) \right|^2 > \right)$$
(1)

$$Z_{DR} = Z_{HH} - Z_{VV} \tag{2}$$

12
$$\rho_{HV} = \frac{\langle S_{HH}^{(b)}(D_{e},\varphi) S_{VK}^{(b)}D_{e},\varphi) \rangle}{\sqrt{\langle \left| S_{HH}^{(b)}(D_{e},\varphi) \right|^{2} \rangle \langle \left| S_{VV}^{(b)}(D_{e},\varphi) \right|^{2} \rangle}}$$
(3)

13
$$K_{DP} = 4\pi\lambda \operatorname{Re}\left[< N(D_e) \cdot S_{HH}^{(f)}(D_e,\varphi) > - < N(D_e) \cdot S_{VV}^{(f)}(D_e,\varphi) \right]$$
(4)

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15 In (1) the double subscript XX stands for either HH or VV indicating the received (first index) and transmitted (second index) polarization. The quantities λ , S_{XX} , D_e and φ in (1) – (4), are 16 17 the radar wavelength, the complex scattering matrix, the particle spherical volume-equivalent diameter and the canting angle, which is defined in the plane of polarization of the incident 18 19 wave with respect to its vertical polarization unit-vector, respectively. The angle brackets 20 stand for integral over the Particle Size Distribution (N) and particle orientations within the radar sampling volume. The subscript "b" or "f" of the scattering matrix S, indicates its 21 diffusion components in the backscatter or forward radial directions, respectively. It has to be 22 23 noted that equations (1)-(4) result from the integration of 23 sampled pulses (SP) as listed in 24 table 1. This leads to an integration time of 41.8 ms (=SP/PRF).

High values of Z_{HH} indicate the presence of large particles (compared with the radar wavelength) or a large number of particles with smaller size within a sampling volume. The

1 dynamic range of Z_{HH} at X band is approximately from -20 to 60 dBZ. Z_{DR} is a good indicator of the mean drop size and shape of the particles within the sampling volume. Values of Z_{DR} 2 close to zero indicate spherical particles (e.g.: small hail and drizzle or tumbling large hail) 3 4 whereas positive and negative values indicate horizontally (e.g.; rain, melting hail) and 5 vertically oriented particles (e.g.: some kind of ice crystals), respectively. The typical dynamical range of Z_{DR} is between -2 and 5 dB. ρ_{HV} measures the correlation of the received 6 7 signals in the H and V polarization state within a sampling volume. ρ_{HV} varies between 0 and 1 8 and it is an indicator of the complexity of the scattering effects: ρ_{HV} values close to unity are 9 usually representative of rain or snow; values approximately close to 0.9 are instead associated to hail or wet aggregates; values less than 0.9 are usually associated to non-10 11 meteorological targets or to a mixture of different particles within the same radar sampling 12 volume. The difference between the H and V phase shifts is referred to as the differential 13 phase shift (ϕ_{DP}). Typically, meteorological targets do not show equal shifting in the phase of 14 the received signal at H and V polarization states. This is due to target shape and its 15 concentration. The range derivative of the differential phase shift is the specific differential phase K_{DP} . Like Z_{DR} , K_{DP} is sensitive to the mean drop size and shape of the dominant particle 16 within the sampling volume. Indeed, K_{DP} is sensitive to particle concentration as well. The 17 more particles are in the sampling volume, the more effects will occur on K_{DP} . K_{DP} variations 18 depend from the radar wavelength. At X band variations of K_{DP} can exceed 30 °/km in heavy 19 rain while they drop to -2 °/km in vertically aligned ice crystals. 20

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22 2.1.2 Polarimetric radar data processing

The radar data processing can benefit from the experience matured for the observations of weather phenomena, such as clouds and precipitation. The radar signals are processed following several steps as described hereafter.

The first step is the compensation of the radar reflectivity from the partial beam blocking (PBB) from fixed targets (Doviak and Zrnic, 1993). The PBB map represents the occultation degree at a specific antenna elevation, of the radar rays. The positions where the terrain heights intercept the radar sampling volumes are marked with values from 0 to 1 depending from the degree of occultation of the radar rays (PBB=0 indicates no radar ray path blockage; PBB=1 indicates 100% of radar ray path blockage). PBB is obtained from the visibility map as its complementary to the unity. The PBB map is used to compensate, up to 70% the radar
reflectivity using the simplified obstruction function proposed by (Bech et al., 2003).

To build the theoretical visibility map, an electromagnetic propagation model is used together 3 4 with the Terrain Elevation Model (TEM). In this case, the radar signal is assumed to propagate in the standard atmosphere (Doviak et al., 1993). An empirical approach is also 5 6 used to define an experimental visibility map. The latter is obtained considering 344 radar acquisitions of reflectivity, which include heterogeneous sky conditions (precipitation, clear 7 8 air, ash), then normalizing the average reflectivity in the range [0, 1]. The visibility map used 9 for the PBB compensation is obtained taking the maximum value, for each radar sampling 10 volume, between the theoretical and experimental version of the visibility map. Figure 2 shows the PBB map for the first three elevation angles reported in Figure 1 as well as the 11 TEM map for comparison. 12

13 In the second step, the radar echoes generated by ground clutters, are filtered out applying a threshold on the quality map (Q). Q is generated following the methodology suggested in 14 15 Vulpiani et al., 2012 and it is obtained weighting, with given membership functions, the clutter map (CM) and the textures of Z_{DR} , ρ_{HV} and filtered ϕ_{DP} . CM is obtained in a similar 16 way of PBB as a combination of a theoretical and experimental clutter map. In this case the 17 18 experimental clutter map is obtained considering only the acquisitions in clear sky conditions 19 (i.e. a subset of the 344 acquisition before mentioned) to better identify the radar signals due 20 to non-meteorological targets.

In the third step we discarded the radar sampling volumes having a signal-to-noise-ratio in dB
(SNRdB) smaller or equal than 5 decibels (dB). SNR is calculated as:

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$$SNRdB = C_{SNRdB} + Z_{HH} - 20\log_{10}(r)$$
⁽⁵⁾

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24

where C_{SNRdB} is a constant (in dB) and *r* is the range distance from the radar position (in km) of a given sample volume. Eq. (5) is obtained considering the ratio of the radar received power: $P_r = C_{rad}Z_{HH}r^{-2}$ and the noise power: $P_n = kT_0$ (*F*-1)*B*; with C_{rad} , k, T_0 , *F* and *B* the radar constant, the Boltzman constant, the ambient temperature, the radar receiver figure noise and the equivalent radar receiver band width. C_{SNRdB} in eq. (5) is then defined as $10\log_{10}(C_{rad}P_n^{-1})$. 1 The constant C_{SNR} is found using the correlation coefficient, ρ_{HV} . ρ_{HV} in presence of additive 2 noise depends from SNR thought the following relation (Bringi and Chandrasekar, 2001):

3

$$\rho_{HV} = \rho_{HV}^{n} \left(1 + 10^{-0.1SNRdB} \right) \tag{6}$$

4 5

6 where the apex "*n*" indicates a noisy quantity. Eq. (6) is derived using few mathematical 7 manipulations and the definition of correlation coefficient for a signal added to noise (s+n). It 8 is $\rho^n(l) = R^{s+n}(l)/R^{s+n}(0)$ where *R* is the autocorrelation function at time lag (*l*) and the additive 9 noise is assumed to be white so that $R^n(l) \neq 0$ only for *l*=0. In this context the SNR is 10 conveniently defined as $R^s(0)/R^n(0)$. The optimal C_{SNRdB} in eq (5) is found when ρ_{HV} is 11 independent from *SNRdB* for its values greater than 5 dB. The value of C_{SNRdB} we found for 12 the DPX radar is 40 dB. The equation (6) is also used to correct ρ_{HV} for noise effects.

13 In the forth step, filtered ϕ_{DP} and the specific differential phase K_{DP} are obtained applying a 14 procedure, derived from the retrieval scheme proposed for hydrometeors by Vulpiani et al. 15 (2012) and then tuned for ash targets. The method is iterative and it automatically removes spikes, offset and wrapped values in ϕ_{DP} . With respect to meteorological rain targets, 16 negatives values of K_{DP} are not filter out for ash targets. Moving windows filtering steps are 17 18 applied. A pre-filter is based on a convolutional filter, which uses a 5 km width triangular window. A convolutional filter is applied to estimate of K_{DP} in the final step with a triangular 19 20 window width of 7 km.

21 The last step concerns the calibration of Z_{DR} . It is a challenging process, more complex than 22 compensating Z_{HH} from the partial beam blocking or estimating K_{DP} because both the H and V 23 channels should be calibrated separately. The goal of Z_{DR} calibration is to provide an accuracy at least of ± 0.2 dB of the true value of Z_{DR} . One of the common methods for Z_{DR} calibration is 24 25 to consider an external target assumed as a reference with a known Z_{DR} value (Gorgucci et al, 1999). Usually water clouds in light rain conditions, observed along the zenith direction, 26 should produce $Z_{DR}=0$ due to the spherical shape of the precipitating small water particles. 27 Deviations of Z_{DR} from zero, in the condition just described, provide an estimate of the bias of 28 Z_{DR} . Unfortunately, as evidenced by the scan strategy in Figure 1, 90 deg elevations (looking 29 30 at the zenith) are not present in the data making hardly difficult to calibrate Z_{DR} . On the other

1 hand, rain precipitation is not likely to be present at the heights sampled by the DPX radar in 2 Iceland. For this reason we sampled radar variables in areas likely to be affected by ice where 3 the expected average Z_{DR} is known by model simulations (Marzano et al, 2010). Radar returns 4 due to ice are identified selecting sample volumes where K_{DP} is within the range [0, 2], ρ_{HV} 5 within [0.91, 0.99], Z_{HH} within [10, 25], SNR_{dB} larger than 42 and height of sample volumes within [1.2, 3.5] km. The calibration procedure of Z_{DR} that we applied leads to a bias of 0.74 6 7 dB that is added to the raw values of Z_{DR} . Additionally, a convolutional filter with a moving 8 triangular window 5 km length is applied along each radial direction to filter out noise from Z_{DR} . As discussed later, given the uncertainty that affects the calibration of Z_{DR} we decided 9 not to use it for quantitative analyses. 10

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12 **2.2** Spaceborne microwave radiometer measurements

13 The SSMIS radiometer flights aboard the LEO DMSP platforms orbiting at 833 km height 14 above ground (Yan et al., 2008; Kramer, 2002). SSMIS is a conically scanning passive microwave radiometer with several channels in the 19 to 189 GHz range and a swath of 15 16 approximately 1700 km. The observation angle between the nadir direction and the antenna pointing direction is 45 degrees. SSMIS measures the spectral radiances from the observed 17 18 scene. The spectral radiance is usually described in terms of brightness temperature (BT) 19 through the Planck's law (Ulaby et al., 1981). BT is frequency and polarization dependent so 20 that both horizontally-polarized $BT_{\rm H}$ and vertically-polarized $BT_{\rm V}$ can be available in 21 principle. For the study of ash the SSMIS channels that potentially show an ash signature are 22 those at frequencies and spatial sampling as follows (in [GHz]/[km]): [183±6]/[12.5], 23 $[183\pm3]/[12.5], [183\pm1]/[12.5], [150.0]/[12.5] and [91.6]/[12.5].$

BT data are provided as calibrated geo-referenced data for which the antenna pattern effect is already accounted. The geolocation error is estimated as approximately 1 pixel, and thus a pointing refinement may be applied using the coastline reference. When comparing SSMISbased data with ground-based radar data a spatial averaging is applied to match the SSMIS pixel with the corresponding set of high-resolution radar sampling bins. Some further descriptions of SSMIS characteristics and data processing for ash cloud observations may be also found in Marzano et al. (2012).

1 3 Data interpretation

2 The Grímsvötn volcano, located in the northwest of the Vatnajökull glacier in south-east Iceland, is one of Iceland's most active volcanoes. An explosive subglacial volcanic eruption 3 started in the Grímsvötn caldera in southern Iceland around 19:00 UTC on 21st May 2011. 4 The strength of the eruption decreased rapidly and the plume was below ~10 km altitude after 5 6 24 h. The eruption was officially declared over on 28 May at 07:00 UTC. More details on the 7 Grímsvötn eruption can be found in Petersen et al. (2012), Marzano et al. (2012) and 8 Montopoli et al. (2013). An impressive picture of the plume at the beginning of the Eruption is shown in Figure 3. The left hand side of the picture reports the scale of altitudes, the 9 10 ground reference (Gr) and the tropopause level (Tr). Tr is obtained using the closest radiosounding launched at the Keflavik airport, which is shown on the right panel. Figure 3 11 highlights how the plume starts horizontally spreading once it reaches the tropopause. 12

In the following subsections we will analyze the instants at 07:12 UTC and 07:15 UTC on of 22nd of May 2011 for DPX and SSMIS, respectively. This choice is due to the joint availability of the two measurements.

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17 **3.1 Radar data Interpretation**

18 A graphical representation of the polarimetric variables defined in (1) - (4) is shown in Figure 19 4. In this figure, the positions where Z_{HH} is maximum along each vertical column are 20 identified and used to extract the values of the other variables. This procedure ensures a 21 consistent comparison among the measured variables having them been extracted at the same 22 positions. In Figure 4 (top left panel) a signature of the volcanic plume is clearly evident from 23 values of Z_{HH} of about 40 dBZ. Those values spread circularly close to the Grímsvötn caldera. 24 Areas, which are far away the caldera, show values of Z_{HH} in the interval [5, 35] dBZ. This 25 suggests the presence of small particles in those areas, but it is difficult to discern their nature 26 from Z_{HH} . K_{DP} and Z_{DR} (top right and bottom left panel, respectively) do not exhibit a clear pattern for the ash plume. An increase of K_{DP} and ZDR around the Grímsvötn caldera is 27 28 noticed. Their behavior is analyzed in detail afterward in the paper. The strong depression of 29 ρ_{HV} values (bottom right panel) seems to be another important volcanic plume signature. The reasons of this behavior may be due to the presence of a mixture of non-spherical particles 30

1 randomly moving and rotating because of turbulence effects. A slight depression of ρ_{HV} is also

2 noticed in areas around a longitude and latitude of -16.6° and 64.1°, respectively.

Figure 5 represents the vertical profile of the volcanic plume in terms of the same radar 3 variables discussed before. The vertical profiles refer to the direction highlighted with the 4 cyan radial line in Figure 4, which is the azimuth at 21 deg. Within the plume, Z_{HH} and ρ_{HV} 5 are well correlated to each other (compare the top left and bottom right panels, respectively). 6 7 Values of Z_{HH} larger than 25 dBZ correspond to low values of ρ_{HV} . In the same area, K_{DP} shows positive values of approximately 0.5 $^{\circ}$ /km with a little patch which reaches 1.5 $^{\circ}$ /km. 8 9 Areas outside the core of the plume occasionally show K_{DP} close to zero. The maximum value registered for K_{DP} for the analysed case study, within the whole radar volume, is of 3 °/km. 10 The behaviour of K_{DP} suggests a different particle orientation inside and outside the plume 11 12 core. The analysis of Z_{DR} (bottom left panel) tends to confirm this aspect. Although the calibration of Z_{DR} is not accurately verified and it cannot be used to make quantitative 13 14 conclusions, the spatial variability of its values can still provide some information. Lower 15 values of Z_{DR} inside the core of the plume, where Z_{HH} is larger than 30 dBZ, are quite evident 16 with respect to those outside. Especially in the range distances from 10 to 60 km, the increase 17 of Z_{DR} close to the ground may suggest the aggregation of small ash particles coated by ice. To support the thesis of the presence of ice in the analysed areas of the volcanic plume, the 18 19 radar response model simulations at X band, as reported in Snyder et al. (2010) and Kaltenboecka et al. (2013), show that values of Z_{HH} , Z_{DR} and K_{DP} respectively of 20 dBZ, 0.4 20 dB and 0.4 °/km at a temperature of 26° C can be consistent with small particles of melting 21 22 hail with equivalent size smaller than 5 mm. It is worth noting that, Z_{DR} may be also corrupted by depolarization effects and differential attenuation due to the presence of ice columns that 23 24 align under the effect of the atmospheric electrification (Ryzhkov et al., 2007). Depolarization 25 is the transition of power between the two orthogonal polarizations H and V. In case of depolarization the interpretation of Z_{DR} becomes a complex task. In our case, May 22nd on 26 07:12 UTC, 51 lightnings have been registered within the plume core by the world wide 27 lightning location network (Hutchins et al., 2012). The ice crystal formation is likely at the 28 29 Iceland latitudes and within the 15 km height eruption column such that of the Grímsvötn 30 event here analysed. However, the temporal analysis of the available measurements (not showed) does not evidence a clear correlation between the number of lightning and the radar 31 32 polarimetric signatures. It is worth mentioning that depolarization effects might be due also to strong turbulences, which are plausible to occur within volcanic plumes. 33

1 Figure 6 completes the analysis of the radar dataset. It shows the range profile of the radar polarimetric variables shown in Figure 5 along four selected angles of the radar antenna 2 3 elevation as specified in the title of each panel. The profile of the height of the radar ray paths 4 is also shown by shaded line. A vertical line marks the position of the Grímsvötn caldera. 5 Note that some of the variables are amplified by a constant factor as specified in the figure legend to better appreciate their variations. Z_{HH} strongly decreases with distance although the 6 7 volcanic plume signature is still evident close to the radar position (i.e. approximately 70 km 8 far from the Grímsvötn caldera). The local maxima of Z_{HH} coincide with the local minima of 9 Z_{DR} although this is more evident at 3.1 deg and 6.3 deg (upper left and lower right panels). ρ_{HV} starts decreasing when the maximum of reflectivity is reached. In some cases ρ_{HV} starts to 10 11 increase again at elevation angles equal to 6.30 deg. Overall, in Figure 6 a different behaviour 12 of the radar variables is noted between areas inside (in the range 60-85 km) and outside (10-13 60 km) the core of the plume.

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15 **3.2 Radiometer data interpretation**

In this section the multi-channel images, acquired by the SSMIS scanning radiometer and 16 collocated in time and space with DPX radar measurements, is analysed in terms of BT_H 17 18 signatures. Figure 7, shows BT_H acquired in four channels at 150, 183 ± 1 , 183 ± 3 and 18319 \pm 6 [GHz]. The depression of BT_H corresponding to cold temperatures is evident in all SSMIS 20 channels with different intensity. This is most likely a signature of the volcanic plume produced by upwelling microwave radiation that has been emitted from the surface and 21 22 scattered by ash and ice particles away from the observing directions. The good qualitative correlation between Z_{HH} contours and the BT_H depressions supports this fact. The iso-contours 23 24 of Z_{HH} at 5 and 30 dBZ are superimposed to BT_H to make the comparisons between the two 25 sources of information easier.

The microwave BT_H of this scene is clearly frequency and surface dependent. For example, the sea provides a relatively "cold" background at lower frequencies (e.g. at 37 GHz, not shown). Above 100 GHz, background brightness temperatures increase due to atmospheric water vapour (Wilheit et al., 1994). Below 100 GHz, glaciers can provide an ambiguous signature with respect to ash clouds due to the fact that both are relatively efficient scatterers (Grody et al., 1996). This spurious radiometric signature of the cloud-free ice cap is detected

1 especially to the north-west of the vent, where no ash plume is present. This is still evident at 2 150 GHz (top left panel of Figure 7) where some residual effects of background terrain 3 emissivity are present. Around the strong 183 GHz absorption line, water vapor tends to mask 4 the surface contribution. With increased frequency distance from the water vapor line center 5 at 183 GHz the contrast between BT_H from background and those affected by the scattering induced by the volcanic cloud is increased. This is particularly evident comparing 183±1 GHz 6 7 with 183±6 GHz, where the latter allows for an easier identification of the volcanic cloud. The 8 lower atmosphere channels of SSMIS from 22 GHz to 60 GHz were not used here because of 9 their coarse spatial resolution and relatively lower sensitivity to scattering by small particles. Due to similar weighting functions for the two nearly transparent channels at 37 GHz and 50 10 11 GHz features are similar, though with the different spatial sampling characteristics mentioned earlier (i.e. 25 km and 37.5 km at 37 GHz and 50 GHz, respectively). For the channels from 12 13 22 GHz to 60 GHz the absorption of oxygen strongly mask the observed scene.

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15 4 Retrieval results

16 To derive quantitative results from the radar data we applied the Volcanic Ash Radar 17 Retrieval for dual-Polarization X band systems (VARR-PX) (Marzano et al., 2006; 2012). 18 The input variables that we used for this scheme are the polarimetric measurements Z_{HH} , K_{DP} 19 and ρ_{HV} . The VARR-PX algorithm, in its general configuration, consists of two main steps:

1) Classification of radar echoes with respect to ash particle size (in mm) (fine ash: FA, with
average diameters of 0.01 mm; coarse ash: CA with average diameters of 0.1 mm; small
lapilli: SL, with average diameters of 1 mm; large lapilli: LL, with average diameters of 10
mm) and orientation (prolate: PO, oblate: OO, and tumbling: TO);

2) Estimation of the mass concentration C_a (in g/m³) applying a suitable parametric power law 25 (i.e. in the most general case, $C_a = a \cdot Z_{HH}^{\ b} \cdot Z_{DR}^{\ c} \cdot K_{DP}^{\ e} \cdot \rho_{HV}^{\ f}$) with estimation parameters (i.e., *a*,

26 *b, c, d, e* and *f*) varying according to the results of the previous classification step.

For the Grímsvötn case study, Z_{DR} is not considered due to its calibration problems for DPX. For this reason the discrimination of the particle orientation, as foreseen in the full version of

29 VARR-PX, is not performed since it would be not completely reliable. Additionally, the

30 estimate of C_{a} , after the classification step, is performed considering only Z_{HH} (i.e. the

31 parameters c, d, e, f are set to zero) because its use produces more robust and reliable results.

Note that, even though we estimate the ash concentration for each radar grid point using $C_a=a\cdot Z_{HH}{}^b$, the coefficients "*a*" and "*b*" depend on the predominant ash particle category at the considered grid point. This means that "*a*" and "*b*" depend from Z_{HH} , K_{DP} and ρ_{HV} which are used as input of the ash category classification scheme. **Table 2** lists the values of "*a*" and "*b*" that we used in VARR-PX. In order to make the ash classification more reliable, we further modified the original version of VARR-PX modifying the "a priory" probability of the ash category LL, so that its occurrence is higher at lower altitudes and viceversa.

8 Figure 8 shows the vertical profiles of the predominant ash particle category (right panel) and 9 C_a (left panel), obtained from VARR-PX outputs. Looking at the ash categories (right panel 10 of figure 8), a transition between LL and FA is noted moving from the plume core (distance = 11 70 km) far away toward the radar site (distance =0 km). Some FA is also noted at the flanks 12 of the plume and above height of 16 km. Within the core of the volcanic plume LL seems to coexist with SL particles. The mass concentration C_a (left panel) is higher on the left flank of 13 14 the plume, toward the radar site, than within its core. This behaviour seems to be consistent 15 with the SSMIS images in Figure 7 where the BT_H depression is more shifted toward the 16 radar site than toward the Grímsvötn caldera. This is an encouraging result on the consistency of the VARR-PX approach. To check the sensitivity of the use of polarimetric variables in the 17 18 radar retrievals we tested the case when only Z_{HH} is used for both classification and estimation 19 steps. In this case the vertical profiles of the ash categories in Figure 8, right panel, modifies and the class LL is not anymore recognised. The presence of LL below 8 km of altitude as it 20 21 results when using $Z_{HH} K_{DP}$ and ρ_{HV} seems to be reasonable for the analyzed eruption. In this 22 respect the added value of polarimetry is to make the VARR-PX output qualitatively more reliable. Quantitative experimental validations of radar retrievals would require an external 23 24 reference within the ash cloud in proximity of the volcano vent, which is so far not available 25 to our knowledge.

Similarly to what proposed in Marzano et al. (2013), **Figure 9** shows a quantitative comparison between SSMIS, DPX and SPC in terms of Total Columnar Concentration (*TCC*) of C_a . SPC is the Single Polarization C-band radar in Keflavik (260 km away from the Grímsvötn caldera, Montopoli et al. (2013)). For the comparison of figure 9 we used two vertical cuts from SPC and DPX acquired at 07:10 UTC and 07:12 UTC on May 22nd 2011 at the azimuth of 81 deg and 21 deg from the North, respectively. In the case of SPC, the version of VARR for single polarization radar systems is used considering only Z_{HH} for both steps of ash classification and estimation of *TCC*. To allow a better evaluation of the results, *TCCs* are averaged on the same reference grid of SSMIS to match its coarser grid resolution. The SSMIS channel used for the comparison is that at 183 ± 6 GHz. To convert BT_H [K] into *TCC* $[kg/m^2]$ an inverse linear relation is applied (Marzano et al., 2013):

- 5
- 6

$$TCC = s_1 + s_2 BT_H (183 \pm 6) \tag{7}$$

7

8 where s_1 , s_2 are the empirically-based regression coefficients which are independent of the 9 surface background and the atmospheric scene. The value of these coefficients is s_2 =-1.062 10 and s_1 =262.1 for DPX and s_2 =-2.982 and s_1 =226.8 for SPC radar.

The results are indicated in panel a) of figure 9. The correlation of the SSMIS BT_H at 183 ± 6 11 12 GHz and TCC DPX radar retrieval has been found to be -0.73. Panels b) and c) show the maps of TCC [kg/m²] for SSMIS and DPX in the pixels where radar echoes are registered. 13 The agreement between the two estimates is relatively poor. The differences shown in panel 14 c) with a relatively low average value of -1.85 kg/m^2 but positive and negative peaks reaching 15 values up to ± 20 (kg/m²). This is probably due to a combination of causes, such as geo-16 location uncertainty and non-linearity of the $BT_H - TCC$ relationship. About the differences 17 18 between the two radar estimates from DPX and SPC (Figure 9 panel a), it could be due to 19 three main factors: i) DPX and SPC are positioned at 70 and 260 km from the Grímsvötn 20 caldera, respectively. This implies that the two radars observe the same scene with different 21 geometry of observation. In particular SPC radar, at a distance of 260 km, partially overshoots 22 the volcano plume being its lowest height of the ray path approximately 5 km above the ground. This leads to unavoidable underestimation of columnar integrals; ii) the transverse 23 24 section of the sampling volumes of SPC is 2.8 times larger than that of DPX This means a larger sampling volume of SPC than DPX implying a larger probability to include 25 26 inhomogeneity in the SPC sampling volumes with respect to DPX. This issue is often referred with the term "non-uniform beam filling" as described in (Kitchen and Jackson, 1993) and it 27 28 can contribute to smooth down the reflectivity. This is probably the effect that is shown in 29 Figure 9 panel a); iii) The retrievals of TCC from DPX and SPX are not consistent each other being the first one based on the use of the polarimetric variables while the second uses only 30 Z_{HH} . When DPX estimates are performed using only Z_{HH} (i.e. made consistent with those 31

derived from SPX), the $BT_H - TCC$ relation in figure 9 top left panel remains almost unchanged. The correlation coefficient decreases to 0.67 from 0.73. Nevertheless, the distribution of the difference of *TCC* values (i.e. $TCC(Z_{HH}) - TCC(Z_{HH}, K_{DP}, \rho_{HV})$) ranges over -1 and 8.20 kg/m2. Thus, it seems that the use of the radar polarimetry has an evident impact on the radar-derived integral columnar content of ash even though this does not sensibly affect the correlation between *TCC* and *BTH*.

7

8 **5** Conclusions

9 In this work ground radar and satellite radiometer observations at microwave frequencies are 10 exploited for the study of volcanic eruptions. The case study considered is that occurred on 11 May 22nd 2011 at the Grímsvötn caldera in Iceland. Radar data have the characteristic to be 12 acquired in the two orthogonal vertical and horizontal polarizations. The main conclusions 13 are:

i) radar acquisition at X band can clearly detect the volcanic plume and the cloud spreading in
the surrounding area of the Grímsvötn, which showed an horizontal extension of
approximately 100 x 130 km;

17 ii) dual polarization signatures from X band radar data, DPX, are not easy to interpret. The 18 co-polar reflectivity Z_{HH} shows values greater than 40 dBZ within the plume and values 19 around 15 dBZ away from it. The correlation coefficient ρ_{HV} between the orthogonal 20 polarizations shows an abrupt decrease in the area interested by the core of the volcanic 21 plume. The differential reflectivity Z_{DR} , more than other radar variables, can be affected by 22 factors depending from the radar system (bias) and the observed phenomena (depolarization 23 induced by lightning and/or strong turbulences). This makes its interpretation challenging. Its behavior for the Grímsvötn case study seems to suggest non-spherical particles at the side of 24 25 the plume as well as at lower elevations far from the core of the volcanic plume. Within the core of the volcanic plume, lower values of Z_{DR} are registered, suggesting tumbling or 26 27 spherical particles; the specific differential phase K_{DP} shows positive increments at the plume edges, reaching values up to 3 °/km. Additionally, the use of polarimetric variables has shown 28 29 to provide more reliable results in terms of ash categories provided by VARR-PX output.

30 iii) the comparison of the total columnar concentration from DPX and brightness temperature 31 at horizontal polarization, BT_H , from the satellite SSMIS radiometer, shows high correlation. 1 The derived BT_H - *TCC* relationship was compared with the analogous relationship derived 2 from the SPC weather radar data for the same case study. The two regressions from DPX and 3 SPC denote some differences, which may be mainly explained by the different spatial 4 resolutions of the two radar systems that might induce more pronounced non-uniform beam 5 filling effects in the C-band radar measurements than those at X-band.

Future works should be devoted to deepen the analysis of dual-polarization radar data though
a systematic analysis of a larger number of case studies in order to consolidate the role of
satellite microwave radiometer observations as an ash cloud remote sensing technique.

9

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 Table 1. Technical specifications of the DPX radar used for the analysed case study during

 Grímsvötn 2011 .

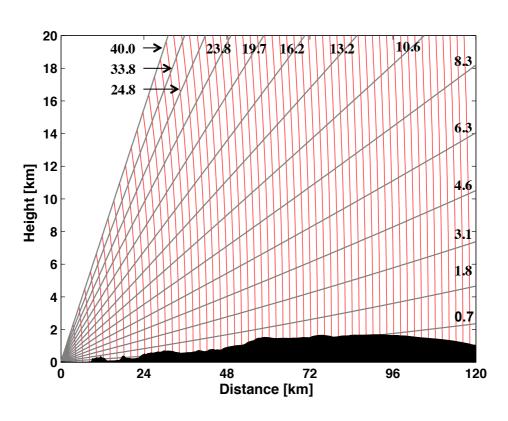
Parameter	Value	
Radar Type	X-band Meteor 50DX (9.4 GHz)	
Transmitter peak power	75 kW	
Pulse duration	1.33 µs	
Pulse repetition frequency	550 Hz	
Minimum detectable signal	-113 dBm	
Sampled pulses	23	
Antenna Type	Parabolic, prime focus reflector	
Minimum antenna Gain	42.5 dB	
Half power beam width	1.3 deg	
Reflector diameter	1.8 [m]	
Duration of 360 deg scan	20 s	
Duration of antenna elevation rising	5 s	

-

$[\mathrm{mm}^{\mathrm{6}}/\mathrm{m}^{\mathrm{3}}]$.				
	Ash category	а	b	
	Fine Ash	4.37	0.437	
	Coarse Ash	0.786	0.312	
	Small Lapilli	0.0837	0.322	
	Large Lapilli	0.00193	0.472	

Table 2. Parameters for the ash concentration retrieval $C_a = a \cdot Z_{HH}^{b}$, C_a in $[g/m^3] Z_{HH}$ in

LIST OF FIGURES





1

2

Figure 1. Radar scan strategy in terms of range-height plot adopted for the mobile X-band radar located at the Iceland site. The antenna elevation angles [deg] are shown close to each theoretical radar ray paths (gray lines). For sake of clarity the radar range gate sizes are shown every 2 km by red lines instead of the original resolution of 0.25 km. The terrain elevation profile along the direction of 21 [deg] clockwise from the North is also displayed in black. The radar is positioned at the origin of the axes and the Grímsvötn caldera is at approximately 70 km away form the radar.

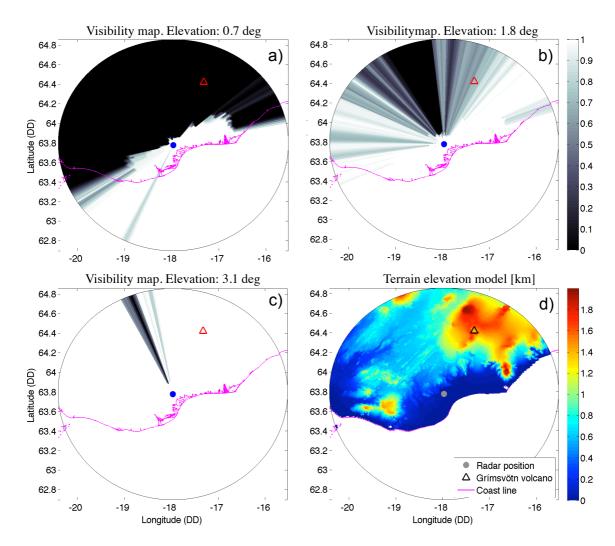
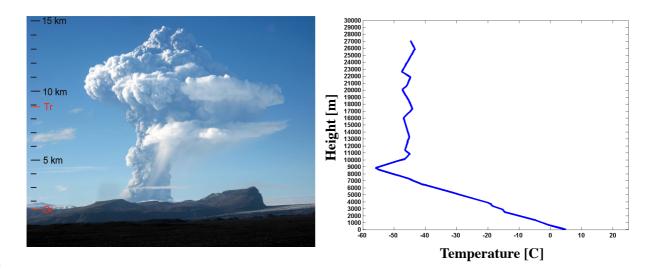


Figure 2. Visibility maps at three elevations angles [deg]: 0.7 (panel a), 1.8 (panel b) and 3.1 (panel c) for the Iceland DPX radar site. Dark and bright patches show areas where the radar signal is obstructed (visibility=0) or free from obstacles (visibility =1) caused by the orography. The terrain elevation model in [km], sampled into the polar coordinates radar reference system, is shown in panel d) for comparison.





2 Figure 3. Left panel: the initial Grímsvötn eruption plume seen from Skeiðarársandur, 50km

3 south of the volcano. The left hand side of the picture reports the scale of altitudes, the ground

4 reference (Gr) at the distance of Grímsvötn and the tropopause level (Tr). Photo by Bolli Val-

5 garðsson, 21 May 2011 at 19:20 UTC (adapted from Petersen et al, 2012). Right panel:

6 radiosounding in Keflavik on May 22nd 2011 at 00:00 UTC. The tropopause level is estimated

- 7 at about 8.9 km.
- 8

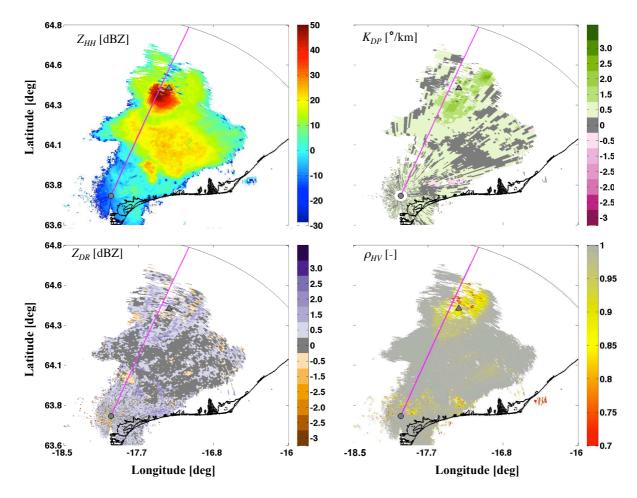
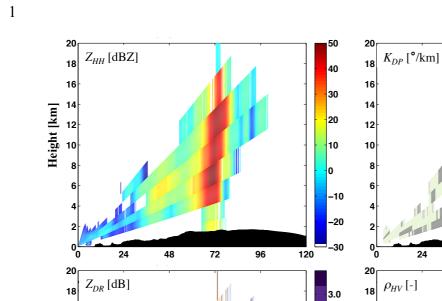


Figure 4. Vertical maximum intensity of radar variables Z_{HH} , K_{DP} , Z_{DR} and ρ_{HV} as specified in the top right corner of each panel for the Grímsvötn case study on 22nd of May 2011, 07:12 UTC. Note the values of all the radar variables here shown are extracted from the positions (range, azimuth, height) where the maximum of the radar reflectivity, Z_{HH} , is registered along each vertical profile. The radar and the volcano vent positions are indicated, in each panel, with the symbols "O" and " Δ ", respectively. The coastline is in black. The magenta colored line shows the azimuth at 21 [deg] clockwise from the North where the vertical cuts in figure 5 are taken.





14

12

10

8

6

2

0

Height [km]

3 **Figure 5**. As in figure 4 but in terms of vertical cuts of radar variables along the azimuth at 21

2.5

2.0

1.5

0.5

-0.5

-1.5

-2.5 -2.0

-2.5

-3

120

0

16

14

12

10

8

6

4

2

0 0

24

48

72

Distance [km]

96

4 [deg] clockwise from the North.

24

48

72

Distance [km]

96

- 5
- 6

3.0 2.5

2.0

1.5

0.5

0 -0.5

-1.5

-2.5

-2.0

-2.5

-3

0.95

0.9

0.85

0.8

0.75

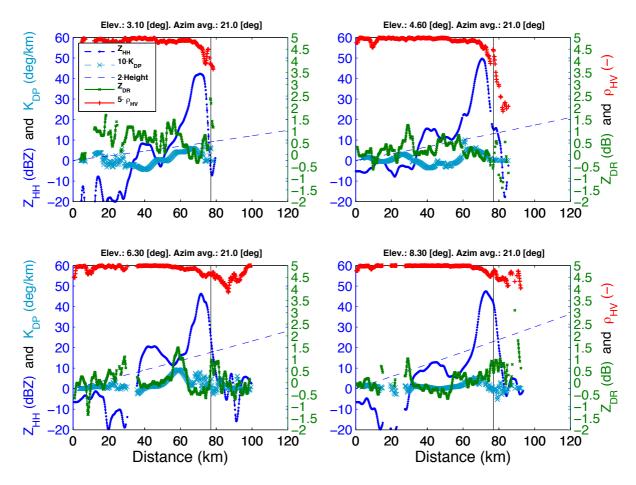
0.7

120

120

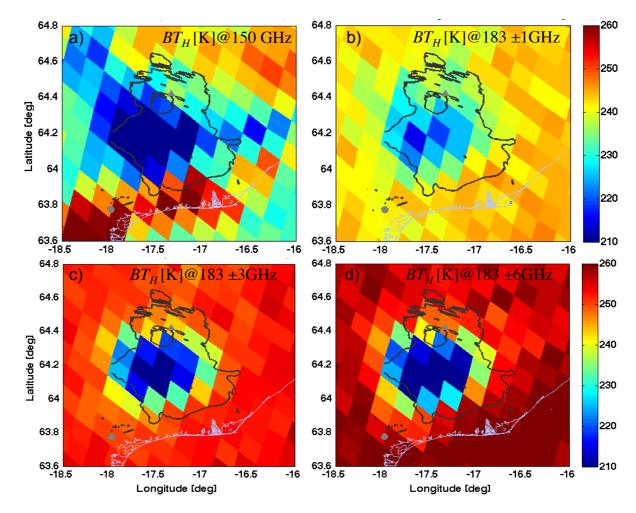
72

48



1

2 Figure 6. Range profile of radar variables for four elevations angles as specified in the legend 3 and in the title of each panel, respectively. The azimuth is fixed at 21 deg. Profile refers to the DPX radar acquisition at 07:12 UTC on May 22nd 2011 at the Grímsvötn site. The vertical 4 5 gray line indicates the position of the Grímsvötn volcano. The values of Z_{HH} and K_{DP} have to be read on the left axes of each panel. Right axes refer to values of ρ_{HV} and Z_{DR} . The height of 6 7 the radar ray as a function of distance is also shown by dashed line and its values read on the 8 left axes. K_{DP} and ρ_{HV} and radar ray heights are amplified by a constant factor of 10, 5 and 2, 9 respectively to better appreciate their variations.



1

Figure 7. Maps of brightness temperature at horizontal polarization (BT_H) in [K] taken from the Special Sensor Microwave Imager/Sounder (SSMIS) carried aboard of the Defense Meteorological Satellite Program (DMSP) F-17. Data were acquired at 07:15 UTC on May 22^{nd} 2011 in the surrounding of the Grímsvötn. Panels a) - d) show BT_Hs at 150, 183 ± 1, 183 ± 3 and 183 ± 6 [GHz], respectively. Contours of the radar reflectivity at 5 and 30 dBZ are shown using black lines. The radar and the volcano vent positions are indicated with the symbols "O" and " Δ ", respectively. Coast lines are indicated by bright gray lines.

- 9
- 10

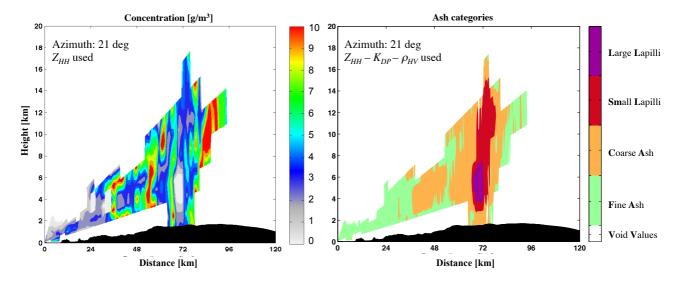
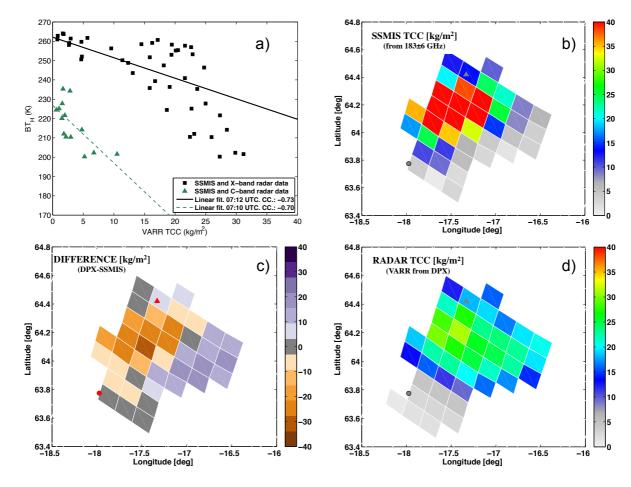




Figure 8. (Left) ash mass concentration in (g/m^3) and (right) ash categories from the DPX radar acquisition at the 07:12 UTC on May 22nd 2011 at the Grímsvötn site (Iceland). Ash categories are Large Lapilli, Small Lapilli, Coarse Ash and Fine Ash with average equivalent diameter in (mm) of 10, 1, 0.1, 0.01, respectively. The ash mass concentration on the left panel is estimated using $C_a=a\cdot Z_{HH}^{\ b}$ with coefficients "*a*" and "*b*" which values depend by the ash categories shown on the right panel.

9



2 Figure 9. Panel a): brightness temperature at horizontal polarization (BT_H) [K] from SSMIS versus the Total Columnar Content (TCC) [kg/m²]. TCC is estimated through the Volcanic 3 Ash Radar Retrieval (VARR-PX) technique using X-band Dual Polarization (DPX) and C-4 band Single Polarization (SPC) radar. DPX and SPC data are acquired at 07:12 UTC and 5 07:10 UTC, respectively on May 22nd 2011 at the Grímsvötn site. Panel b): Retrieval of TCC 6 7 from SSMIS using the channel at 183± 6 [GHz] and the linear relation shown by solid red line in panel a). Panel c): Retrieval of TCC from DPX data using the VARR and Z_{HH} , K_{DP} and 8 9 ρ_{HV} radar variables. Panel d) Difference map: estimates in panel c) minus that in panel b). 10