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Fiber optic distributed temperature sensing for the determination of air temperature

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Abstract

abstr This paper describes a method to correct for the effect of solar radiation in atmospheric Distributed Temperature Sensing (DTS) applications. By using two cables with different diameters, one can determine what temperature a zero diameter cable would have. Such virtual cable
would not be affected by solar heating and would take on the temperature of the surrounding air. The results for a pair of black cables and a pair of white cables showed good results given the general consensus that shielding is needed to avoid radiation errors (*WMO*, 2010). The correlations between standard air temperature measurements and air temperatures derived from both colors had a high correlation coefficient (*r*² = 0.99) and a RMSE of 0.38°C, compared to a RMSE of 2.40°C for a 3.0 mm uncorrected black cable. A thin white cable measured temperatures that were close to air temperature measured with a nearby shielded thermometer (RMSE of 0.61°C). The temperatures were measured along horizontal cables with an eye on temperature measurements in urban areas, but the same method can be applied to any atmospheric DTS measurements, also for profile measurements along towers or with balloons and quadcopters.

15 **1 Introduction**

introDistributed Temperature Sensing (DTS) is a technique that allows for measurement of temperature along optical fibers. Laser pulses are shot into the fiber and backscatter from within the fiber is analyzed. The time of flight then gives the position along the fiber from where the backscatter originated. Analysis of the Raman spectrum of the backscatter allows for the calculation of the temperature at the place where the backscatter originated. Depending on the type of DTS machine used, temperatures can be measured continuously at sub-meter intervals along cables of more than 5 km, with laboratory accuracies up to 0.01°C and typical field accuracies of 0.08°C (*Van de Giesen et al.*, 2012). A good introduction to DTS principles and environmental applications can be found in *Selker et al.* (2006) and *Tyler et al.* (2009).

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Over the past decade, DTS has found many environmental applications. Applications vary from temperature profiling of the subsurface (borehole observations (*Freifeld et al.*, 2008), soils

(*Ciocca et al.*, 2012; *Jansen et al.*, 2011; *Sayde et al.*, 2010; *Steele-Dunne et al.*, 2010)), water (estuaries (*Henderson et al.*, 2009), surface/groundwater (*Lowry et al.*, 2007; *Mamer and Lowry*, 2013), solar ponds (*Suárez et al.*, 2011), streams (*Selker et al.*, 2006; *Vogt et al.*, 2010; *Westhoff et al.*, 2007, 2011) and lakes (*Vercauteren et al.*, 2011; *van Emmerik et al.*, 2013)),

⁵ rocks (*Read et al.*, 2013), ice caves (*Curtis and Kyle*, 2011), forests (*Krause et al.*, 2013) and infrastructure (dam surveillance (*Dornstadter*, 1998), sewers (*Hoes et al.*, 2009), electric transmission cables (*Yilmaz and Karlik*, 2006) and gas pipelines (*Tanimola and Hill*, 2009)).

There are only a few experiments where DTS is used to measure atmospheric temperature (*Keller et al.*, 2011; *Petrides et al.*, 2011; *Thomas et al.*, 2012), since solar heating can have a significant effect. *Keller et al.* (2011) experimented during night time to exclude the effect of short-wave radiation. *Petrides et al.* (2011) estimates effective shade and concluded that solar radiation is the driving factor in temperature differences. *Thomas et al.* (2012) observed differences in temperature measurements with black and white cables and suggests that it can be used for setting up an energy balance.

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This paper will describe a method to correct for the effect of solar radiation in atmospheric DTS measurements with the use of fiber optic cables with different diameters. The original objective of the experiment was to test if air temperature differences in urban landscapes can be measured with reasonable accuracies (1 °C).

2 Materials and methods

20 **2.1 Theory**

Solar radiation causes objects to be warmer than the surrounding air. For this reason, thermometers are traditionally shielded by a screen. For accurate measurements, forced ventilation is necessary, which was not provided in our case (*WMO*, 2010). The temperature difference between a heated cylinder (or sphere) and the air that moves around it, scales with the square root of the diameter (*White*, 1988). If the diameter of a cylinder would be zero, the heat generated by solar radiation would also be zero. Such a zero diameter cylinder would take on the temperature

of the surrounding air. One can create a virtual cylinder with zero diameter by extrapolating the temperatures of two cylinders with different diameters. The fiber optic cables used by DTS can be considered to be very long cylinders. When the temperatures of two cables (T_1 and T_2) with different diameters (d_1 and d_2) are measured, then the air temperature can be determined by extrapolating to a zero diameter, which results in 1:

$$T_{air} = T_2 - \frac{T_1 - T_2}{\sqrt{\frac{d_1}{d_2}} - 1} \tag{1}$$

The theory behind this idea, which was first put forward by Dr. Gaylon Campbell, assumes an infinitely long cylinder, instant redistribution of heat within a cross-section of the cylinder, and forced convection on the outside of the cylinder. Forced convection dominates when the buoyancy force parameter, also known as the Archimedes number, Ar, is much smaller than one. For a cylinder of diameter d (m) we have:

$$Ar = \frac{Gr}{Re^2} = g \cdot \frac{T_s - T_{air}}{T_{air}} \cdot \frac{d}{v^2}$$
⁽²⁾

with Gr the Grashof number (-), Re the Reynolds number (-), g the acceleration due to gravity (9.8 ms⁻²), T_{air} the air temperature (K), T_s the surface temperature of the cable (K) and ¹⁵ v the windspeed (ms⁻¹).

2.2 Experimental setup

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The measurements were taken from 27 April 2011 through 3 May 2011 on a grass field near Delft University of Technology, Delft, The Netherlands (51° 59' 45.44" N, 4° 22' 39.56" E). The DTS instrument was a HALO unit (Sensornet, Elstree, UK) with a sampling interval of

20 2 meters and a measurement interval of 20 seconds. The fiber optic cables used in this experiment consisted of single (simplex) multi-mode, bend insensitive, optical fibers, tight packed, protected with Kevlar and a plastic jacket (AFL, South Carolina, USA).

A schematic drawing of the experimental setup is shown in figure 1. The cable existed of four sections, one black with diameter 3.0 mm, one black with diameter 1.6 mm, one white with diameter 3.0 mm and one white with diameter 1.6 mm. Each section had a length of 190 meters. Of each section, 150 meter of fiber optic cable was held in open air, 1 meter above the grass, with the use of pigtail fence posts. The sections were spliced together to enable continuous measurements.

The DTS was operated in a single-ended configuration. For calibration purposes, each section had 20 meter of fiber cable coiled up in a thermally insulated water bath with warm water (average 27 °C) and cold water (average 14 °C). The setup of baths and splices was such that the cable from each stretch went directly through the two baths without first passing through a splice, thereby avoiding step losses within stretches. The signal was checked to ensure sufficient strength, especially towards the end of the cable. Bath temperatures were measured with the two PT100 thermometers that came with the HALO unit, which have a reported accuracy of 0.1 K. Calibration of the fiber optic cable was based on the method described by *Hausner et al.* (2011).

¹⁵ For each measurement period, the bath temperatures from that same measurement period were used for the calibration.

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For this analysis, 62 measurement points of each section hanging in the air were averaged to one time series. To improve further the signal to noise ratio, the DTS measurements were averaged over time using an integration time of five minutes. We assume that heat within the cross section of the cable is distributed equally at this time scale.

As a reference station, a HOBO weather station (Onset Computer Corporation, USA) with rain (mm), temperature (°C), relative humidity (%) and incoming solar radiation (Wm⁻²) was installed next to the experimental setup. The temperature/RH sensor used was a 12-bit Temperature Smart Sensor (S-THB-M002) with a reported accuracy of $\pm 0.13^{\circ}$ C. The reference station had a measurement interval of 5 minutes. The sensor was placed inside a HOBO RS1 radiation shield with only natural ventilation.

Wind velocity data, to determine if the assumption of forced convection was valid, was taken from the closest automated weather station of the Royal Netherlands Meteorological Institute. This station is situated at the airport of Rotterdam (51° 57' 33.66" N, 4° 26' 32.66" E), 6 km

from the experiment location. There can be important differences between the wind measured in Rotterdam and the wind at our site but these data only served as a check to see if there were no periods without wind ($<0.1 \text{ ms}^{-1}$).

3 Results and discussion

⁵ Weather conditions from 27-30 April were partly cloudy with a daily maximum incoming solar radiation between 600-650 Wm⁻². On April 28th there was a rain event with 2.4 mm of rain. Conditions from 1-3 May were clear and sunny with daily maximum incoming solar radiation between 650-750 Wm⁻².

The dominant wind direction was North-East. The wind speed during daytime varied between ¹⁰ 3 - 9 ms⁻¹, making the assumption of forced convection valid (Ar < 0.001). Note that forced convection will dominate in all but the most extreme natural conditions.

Figure 2 shows the average temperature measured by, respectively, the black cables and the white cables. The uncorrected temperatures show a clear temperature rise during daytime due to solar heating. This effect is significantly larger for the black cables than for the white cables.
¹⁵ During daytime, the black cables show a clear temperature rise due to solar heating. The correlation coefficient r², see figure 3, between the uncorrected temperature of the black 3.0 mm and 1.6 mm cable with the reference station is respectively r²=0.77 and r²=0.85 and a RMSE of 2.40°C and 1.80°C. The uncorrected temperature of the white 3.0 and 1.6 mm cable show a correlation of respectively r²=0.97 and r²=0.98 and a RMSE of 0.74°C and 0.61°C. The corrected temperatures of both the white and black cable have a r² of 0.99 and a RMSE of 0.38°C.

The standard deviations of individual measurements within the stretches were 0.29°C for 3.0 mm white, 0.28°C for 1.6 mm white, 0.39°C for 3.0 mm black, and 0.35°C for 1.6 mm black. The standard deviation of the average of the 62 points would then be between 0.04°C and 0.05°C. It should be noted that the accuracy of the instrument is about 0.02°C for a point measurement with perfect calibration and that similar set-ups have given field accuracies of 0.1°C (*Hausner et al.*, 2011). So the measured variation is likely to be also caused by real temperature differences along the cable, caused by uneven heating/cooling.

4 Conclusions

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conclusionsDistributed Temperature Sensing (DTS) of atmospheric temperature profiles is hindered by solar heating, which may lead to significant deviations from the true air temperature. For atmospheric measurements with DTS we showed that it is possible to correct for solar heating and find a good estimation for the air temperature, by using cables with different diameters.

The corrected temperatures matched the temperature measurements of the reference station with a RMSE of 0.38°C. The reference measurement took place without forced ventilation so the RMSE of the reference station could easily account for half the RMSE. The method used to calculate the air temperature is independent of the color of the cable. If it is not possible to apply different sizes of cable in a setup in an atmospheric DTS application, the use of a thin white fiber optic cable is a reasonably good alternative.

The experiment started out with the question if corrected DTS air temperature measurements would have a reasonable accuracy to measure temperatures across urban landscapes. The results show that this is indeed the case and they were actually better than we expected at the

¹⁵ onset (1°C). With hindsight, we would have installed a better reference temperature measurement device because we can not say if the reference was truly better than the DTS derived temperatures. Although we can not conclude this from the results, it may be possible to further reduce systematic errors, in which case this method would become valuable for vertical atmospheric soundings with DTS from balloons, quadcopters, or towers. White would be preferable over black, given the lower standard deviation within stretches.

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Fig. 1. Schematic overview of the experimental setup. The cable exists of four sections (black with diameter 3.0 mm and 1.6 mm and white with diameter 3.0 mm and 1.6 mm). In the measurement section the cables are held in open air above a grass field. figure



Fig. 2. top Comparison between the reference station and the uncorrected averaged temperature of the black (*left*) and white (*right*) cables in the measurement section. **bottom** Comparison between the reference station and the corrected temperatures of the black (*left*) and white (*right*) cable.



Fig. 3. top Correlations between the temperature measurements of the reference station and the uncorrected temperatures of the black (*left*) and white (*right*) cable. **bottom** Correlation between the temperature measurements of the reference station and the corrected temperatures of the black (*left*) and white (*right*) fiber optic cables.