



GPSRO impacts on typhoon predictions over Northwest Pacific

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Systematic evaluation of the impacts of GPSRO data on the prediction of typhoons over the Northwestern Pacific in 2008–2010

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originating from the western North Pacific Ocean. The Western Pacific Subtropical High (WPSH) has a profound influence on the track of typhoons. The growth and decay of both the oceanic warm-core Subtropical High over the western Pacific and continental cold-core Siberian High affect the position and movement of frontal systems in the vicinity of Taiwan. In addition, the circulation of WPSH affects not only the position of the East Asian summer monsoon trough but also the track of typhoons over the western North Pacific.

A successful forecast of a numerical model depends not only on the dynamics and physical processes of the model but also on the quality of the model initial condition. In particular, the latter can be improved through the assimilation of available observation. Since conventional radiosonde observations are mostly available only over land, there are very few in-situ sounding data over the ocean, which makes it difficult to accurately analyze and predict the WPSH. The use of non-traditional sounding observations over the tropical ocean is very important.

Radio occultation (RO) is a limb sounding technique which tracks the radio signals transmitted from the satellites of the Global Navigation Satellite System (GNSS) by using receivers on board a low earth orbit (LEO) satellite. By measuring the changes in phase caused by the refraction of Earth's atmosphere on the electromagnetic wave, the bending angle of the rays and the refractivity of Earth's atmosphere are derived (Ware et al., 1996). With the advantage of high vertical resolution (~ 10 's of m to 1 km, from surface to stratosphere), global coverage, all-weather sensing, Global Positioning System (GPS) radio occultation data can complement conventional sounding data and microwave and infrared satellite observations.

Since the launch of GPS/MET (GPS Meteorology; Ware et al., 1996) in 1995, a proof-of-concept mission, the advantages of GPSRO measurement technique have been demonstrated by several subsequent missions, including the Challenging Minisatellite Payload (CHAMP) of Germany (Wickert et al., 2001), the Satellite de Aplicaciones Cientificas-C (SAC-C) of Argentine (Hajj et al., 2004), the joint Germany-US Gravity Recovery And Climate Experiment (GRACE) (Wickert et al., 2008), the TerraSAR-X of

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Germany (Wickert et al., 2008), and the Meteorological Operational (MetOp) satellites of European Organization for the Exploitation of Meteorological Satellites (EUMETSAT) (Larsen et al., 2004). The joint Taiwan-US FORMOSAT-3/Constellation Observing System for Meteorology, Ionosphere, and Climate (COSMIC; Anthes et al., 2008) launched in 2006 is the first GPSRO mission with a constellation of 6 satellites, providing full global coverage. Since launch, COSMIC has been providing 1500 ~ 2500 GPSRO soundings per day in near real time, supporting operational numerical weather prediction around the world. All major operational centres have reported significant positive impacts from the assimilation of GPS RO data (Healy, 2008; Buontempo et al., 2008; Cucurull and Derber, 2008; Aparicio et al., 2009; Poli et al., 2010).

In recent years, several studies have assessed the impact of GPSRO observation on the prediction of tropical cyclones. Huang et al. (2005) used the MM5 3DVAR system to assimilate the GPSRO refractivity data from CHAMP and SAC-C to investigate its impact on the forecast of Typhoon Nari (2001) and Nakri (2002). They showed that the assimilation of GPSRO improves the track and intensity forecast of Typhoon Nari. In the simulation of Typhoon Nakri, assimilating GPSRO observations reduces the rainfall over southeastern Taiwan, bringing it closer to the observed amount. Kueh et al. (2009) performed sensitivity tests for the simulation of Typhoon Bilis (2006) with only two COSMIC GPSRO soundings and found that the one to the east of the typhoon produced a significant positive impact on the track forecast. Kuo et al. (2009) assimilated the refractivity of COSMIC GPSRO with WRF-3DVAR and WRF-DART data assimilation systems and showed that the track forecast of Typhoon Shanshan (2006) was significantly improved. In particular, they showed that the ensemble Kalman filter data assimilation system was able to extract the information provided by GPSRO more effectively than the 3-D variational data assimilation system to improve typhoon prediction. More recently, Liu et al. (2012) showed that the assimilation of GPSRO refractivity was critical in capturing the genesis of Hurricane Ernesto (2006), by correcting the dry bias of model initial condition, which was based on the NCEP (National Centers for Environmental Prediction) global analysis.

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Most previous researches investigating the impact of GPSRO observations on typhoon forecast are case studies. There are few systematic evaluations based on a large number of cases. Therefore, statistical significance of the impact of GPSRO on typhoon prediction has been lacking. Shen (2011) assessed the impact of GPSRO data on typhoon track forecast over the Northwestern Pacific using the Global Forecast System of Taiwan's Central Weather Bureau (CWB). Their study showed that the assimilation of GPSRO can effectively reduce the track error for recurving typhoons, and the reduction in cross-track errors is more significant than along-track errors. However, for operational regional model systems, a systematic evaluation of the impact of GPSRO data on typhoon forecasts has not been reported.

Typhoon Weather Research and Forecasting (TWRf) is a typhoon forecast model, which has been in operation at CWB since 2010 and has been shown to possess good skills in typhoon forecasting (Hsiao et al., 2012). In this study, we perform a systematic evaluation of the impact of GPSRO data on typhoon track forecast on eleven typhoons occurring over the Northwestern Pacific between 2008 and 2010 using the TWRf modelling system.

2 Experiment design

The TWRf model is based on the Advanced Research core of the WRF (WRF-ARW) and has a horizontal resolution of 45 km with a 221×127 grid mesh (Fig. 1). It has 45 vertical layers, with the model top placed at 30 hPa. The analysis component of TWRf is the WRF-3DVAR data assimilation system; an incremental formulation is used to produce multivariate incremental analyses for surface pressure, wind, temperature, and relative humidity at the model grid points. The “cv5” background error covariance is used in this study that formulates the background error statistics in terms of physical-space control variables including streamfunction, unbalanced velocity potential, unbalanced surface pressure, unbalanced temperature, and “pseudo” relative humidity. With a 12 h partial cycling assimilation strategy (Hsiao et al., 2012), the anal-

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ysis begins with a cold-start data assimilation using the NCEP Global Forecast System (GFS) analysis as the first guess, followed by two update cycles using the 6 h WRF forecasts from the previous cycle as the first guess. The physical parameterizations used by the TWRP model include the Goddard microphysics scheme (Tao et al., 2003), the Kain–Fritsch cumulus parameterization scheme (Kain and Fritsch, 1990), the Yonsei University (YSU) planetary boundary layer scheme (Hong et al., 2006), the Noah land surface model (Chen and Dudhia, 2001), and the Rapid Radiative Transfer Model (RRTM) longwave (Mlawer et al., 1997) and Goddard shortwave (Chou and Suarez, 1994) radiation schemes.

In this study, we assimilate GPSRO refractivity processed with CDAAC (COSMIC Data Analysis and Archive Center) (Kuo et al., 2004; Ho et al., 2009) software version 3.0 obtained from UCAR (University Corporation for Atmospheric Research) CDAAC, which is defined as:

$$N = 77.6 \frac{P}{T} + 3.73 \times 10^5 \frac{e}{T^2} \quad (1)$$

where P is the pressure (hPa); T is the temperature (K); and e is the partial pressure of water vapor in the air (hPa). With this local refractivity operator, the assimilation of GPSRO observations directly affects those fields that are related to mass (temperature, pressure, and water vapor), and indirectly affect the kinematic variables (u , v components of wind fields) through the background error covariance. In these data assimilation and forecast experiments, the typhoon center is relocated before each assimilation cycle, whereas the TC bogus is applied only at the cold start. The first set of experiments (Partial cycle With GPSRO, PWG) uses all available observation data; the second set (Partial cycle with No GPSRO, PNG) uses all other available data except GPSRO.

The primary factor affecting typhoon movement is the environmental steering flow (Galarneau and Davis, 2013). Over the Northwestern Pacific, the circulation associated with the WPSH provides the primary environmental steering for typhoons. The internal circulation of a typhoon and its interaction with the environment also affect its

motion. However, the steering of the environmental wind field is still the dominant factor. Therefore, in the subsequent discussion on the impact of the assimilation of GPSRO on typhoon forecasting we will pay special attention to the impact on the environmental flow.

In this paper, we study eleven typhoon cases in the Northwestern Pacific between 2008 and 2010 as listed in Table 1, for which the CWB issued typhoon warning and the storm intensity was stronger than the category of a tropical storm. Restricting to the period of 2008 to 2010 allows us to conduct this study with a relatively homogeneous experiment setting (a stable number of RO soundings, on changes in the assimilation system). For these cases, forecast experiments are initiated every 6 h within the time range given in Table 1 and the best track for each typhoon is shown in Fig. 1. The number of forecast cases for both PNG and PWG is 284, including 43 cases in which there are two typhoons within the model domain, therefore, the total number of typhoon cases for the statistics is 327.

Before proceeding to the results section, it is important to confirm that the GPSRO data assimilation functions as expected. In Fig. 2 we show the statistics of observation-background (6 h forecast) deviation (O_mB) and observation-analysis deviation (O_mA) averaged over all the cases. The results indicate that the background (6 h forecast) deviation (from observation) is significantly reduced following the assimilation of GPSRO data, both in terms of SD and mean. It indicates that the WRF 3DVAR properly assimilates the RO refractivity observations.

3 Results

3.1 Verification against ECMWF analysis

In order to assess the impact of RO observations on the analysis and forecast of tropical cyclones, we verify the PNG and PWG grid-point fields against the ECMWF high-

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resolution analysis. The RMSE (root-mean-square error) of temperature (T), water vapor mixing ratio (Q), zonal wind (U) and meridional wind (V) are calculated.

Figure 3 shows the average difference in RMSE between PNG and PWG for various variables on each forecast day. A positive value means that the assimilation of GPSRO has a positive impact, if we regard the ECMWF high-resolution analysis as the “truth”. From top to bottom, the four rows of figures are for T , Q , U , and V , respectively. Each row has four panels, from left to right, which show the results of 0, 12, 24, 48, and 72 h forecast. The vertical axis is pressure levels, and the horizontal axis is the difference in RMSE between PNG and PWG averaged over all cases. The blue line is the mean difference, and the area enclosed by the two pink lines surrounding the blue line represents the 95 % confidence interval derived from the T distribution (Student’s T test).

The significant positive impact of GPSRO observations on temperature analysis is quite apparent, and this impact increases with height. The impact is slightly negative below 400 hPa for the analysis. As forecast progressing, the positive impact at the upper level decreases with time. The slight negative impact below 400 hPa at the initial analysis (0 h forecast) becomes positive after one day. The contribution of GPSRO to the water vapour analysis is concentrated in the middle and lower levels, because the water vapour content is relatively low at high altitudes. In the lower troposphere the assimilation of GPSRO data gives a negative impact below 850 hPa, and remains negative for the first and second day. A significant positive impact in moisture is found between 700 and 200 hPa, with the largest impact at 700 hPa. By 72 h, GPSRO assimilation gives a positive impact on moisture throughout the entire troposphere. We suspect that the slight negative impact of GPSRO assimilation below 850 hPa may be affected by differences in data quality control between ECMWF and TWRP data assimilation systems. Also, moisture is the most challenging variable for models to analyse and predict. There may be considerable uncertainties in the ECMWF moisture analysis. We anticipate that further improvement in GPSRO data quality control may improve its use in the lower troposphere. For the U wind field, GPSRO assimilation gives a sig-

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nificant positive impact only at upper levels (above 300 hPa). As forecast progresses, the positive impact on the U wind gradually extends to the lower levels. By 72 h, the U wind component exhibits strong positive impact throughout the troposphere. The impact of GPSRO assimilation on the V wind component behaves very similarly to that of the U wind component. These results suggest that impacts of GPSRO on the analysis mainly occur at the upper levels. This implies that the TWRf model's short-range forecast (first guess for cycling assimilation) has larger uncertainty in upper levels, and the GPSRO can provide useful information to correct the first guess. The improved analysis at the upper levels then propagates to the lower levels, and improves the TWRf model forecast throughout the troposphere.

Through the local refractivity observation operator, the assimilation of GPSRO observations directly affects the analysis of the temperature and water vapour. Our experiments show that the GPSRO observations provide statistically significant positive contribution to water vapour analysis above 700 hPa and temperature analysis above 500 hPa. The value of GPSRO observations for improving meteorological analysis in the upper troposphere and lower stratosphere is quite evident. The improvement in temperature analysis indirectly affects the analysis of the wind field through the background error covariance and the subsequent forecast through geostrophic adjustment. As a result, the wind field exhibits a similar behaviour to that of the temperature field, i.e., a significant improvement in the low stratosphere initially, followed by positive impact throughout the troposphere, and the positive impact continues to increase with time through 72 h forecast. As will be shown later, the robust positive impact on the wind fields provides more accurate environmental steering flows, leading to improved track forecast.

3.2 Impacts to typhoon track errors

Figure 4 shows the track error, verified against the CWB best track analysis, averaged over all 327 cases for eleven typhoons for PNG and PWG, respectively. The results show that the assimilation of GPSRO does not make a significant difference in typhoon

track error for the first 24 h forecast. However, after 36 h, the difference becomes progressively larger with time, and the forecast track error of PWG is statistically significantly smaller than that of PNG by the end of 72 h forecast.

The difference in mean track error between PNG and PWG at the 72 h forecast is approximately 12 km. Although this is only a modest improvement, it is statistically significant. In Fig. 5, the blue solid line shows the mean difference in track errors between PNG and PWG; a positive value indicates that, on average, the assimilation of GPSRO has a positive impact on forecast track error. The light blue area gives the 95% confidence interval of mean difference of track error derived from the Student's *T* test. If the lower bound of the confidence interval is positive, then the positive impact of GPSRO assimilation is statistically significant. Figure 5 shows that the assimilation of the GPSRO observation has a positive impact on the initial analysis of the typhoon position, a neutral impact at 12 h forecast, and a slight positive impact between 24 to 36 h forecast. From 48 h forecast onward, the positive impact becomes increasingly more significant as the forecast progresses.

To gain further insights on the impact of GPSRO assimilation, we decompose the total track error into components that are along and perpendicular to the direction of the typhoon movement in the past 6 h, respectively. The separation of these two components allows us to assess whether the impact on the forecast of the typhoon track is related primarily to the speed of the typhoon (indicated by along-track error) or the direction of the typhoon (indicated by cross-track error). The red columns and green columns of Fig. 5 illustrate the difference in along-track error and cross-track error between PNG and PWG, respectively. The assimilation of GPSRO contributes to a small increase in along-track error at the 12 and 36 h forecast. After 48 h forecast, GPSRO assimilation consistently reduces the along-track error. On the contrary, GPSRO assimilation reduces cross-track error throughout the entire 72 h forecast. The impact is the largest at 72 h forecast. As will be shown later, the large positive impact on cross-track error may be attributed to the improved analysis and prediction of environmental steering flow associated with WPSH.

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analysis than PNG does. The ECMWF-PNG difference wind fields (right column of Fig. 9) show an anti-cyclonic gyre on the western periphery of the WPSH (east of Taiwan) at the 0 h, and the difference wind speed on the south and west edge of WPSH becomes progressively stronger with time. This suggests that WPSH as predicted by PNG is weaker than the ECMWF analysis (Fig. 8b). The PWG-PNG (left column of Fig. 9) difference wind fields give a pattern very similar to that of ECMWF-PNG, and the wind speed of PWG in the area southeast of Taiwan is also larger than PNG after 48 h forecast. Although the area with anti-cyclonic wind difference from PWG-PNG is smaller than that of ECMWF-PNG, its location is very close to that of ECMWF-PNG. The area to the southeast of Taiwan is particularly important, as this is the region where most of the typhoons in this study pass through (Fig. 1). It is clear that the assimilation of GPSRO refractivity improves the forecast of synoptic-scale circulation, which in turn leads to improved typhoon track forecasts.

The motion of typhoons is largely dictated by the environmental steering flow and the beta effect of the intrinsic dynamics of typhoon circulation. For the majority of typhoon cases, the environmental steering flow is the dominating factor. The steering flow is often represented by the deep layer mean (from 1000 to 200 hPa) of the averaged asymmetrical wind inside the typhoon circulation. To assess the impact of GPSRO data assimilation on the prediction of steering flow, we compare the respective absolute error in steering flow between PWG and PNG (verified against the steering flow calculated from the ECMWF analysis). We define the difference between the two such that a positive difference indicates that the assimilation of GPSRO has a positive impact on the steering flow. Figure 10a shows that there is no clear systematic difference in the speed of the steering flow. However, for the direction of the steering flow, the assimilation of GPSRO clearly has a positive impact throughout the 72 h forecast, except for the 24 h forecast. This is consistent with the results, shown in Fig. 5, that the improvement in typhoon track forecast is mainly associated with the reduction of cross-track error.

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Franklin (2013), the best track uncertainty should not pose a problem for assessing improvement on a three-day track forecast. (d) The Student T test has demonstrated that the impact of GPSRO assimilation on typhoon track forecast is statistically significant. (e) Our subsequent analysis of the results demonstrate that the improvement due to GPSRO assimilation can be attributed to improved prediction of WPSH and the steering flow. Therefore, there is solid physical explanation supporting the robustness of the impact of GPSRO assimilation on typhoon track forecast.

Further analysis shows that the assimilation of GPSRO data improves the analysis and prediction of the WPSH, such that it is further extended westward and southward, consistent with the ECMWF analysis. The wind fields over the southwestern periphery of WPSH are improved as a result of GPSRO data assimilation. The improved environmental steering flow associated with the WPSH, in turn, leads to improved track forecast.

Although the assimilation of GPSRO data only produces a very modest improvement in track forecast, these results are very encouraging, given the relatively small number of GPSRO soundings assimilated and the limitations of the current experiment framework. With a 12 h partial cycling analysis, only about 100 GPSRO soundings are used over a domain of 9945 km \times 5670 km. Most data impact studies using a global model are performed with a fully cycling analysis over a period of at least two weeks. This would allow a significantly larger amount of data being assimilated. Also, the impact of the data is allowed to accumulate with time. With a fresh cold start of each cycle for a partial cycling strategy, there is no accumulation of the impact of GPSRO. The TWRP has a horizontal resolution of 45 km, which cannot properly capture the mesoscale circulation of a tropical cyclone. Also the assimilation of GPSRO data using a 3-D-Var system with a simple local refractivity operator is sub-optimal. The FORMOSAT-7/COSMIC-2, which is expected to be launched in May 2016, will provide an order of magnitude increase in GPSRO soundings over the tropics. The assimilation of FORMOSAT-7/COSMIC-2 using an advanced data assimilation system with a sophisticated observation operator and a high-resolution mesoscale model is

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Table 1. List of typhoon cases between 2008 and 2010 over the western North Pacific Ocean.

Typhoon	Date-Time	Intensity
Kalmaegi	07/15/2008 06:00:00–07/19/2008 18:00:00	typhoon
Fung-Wong	07/25/2008 06:00:00–07/29/2008 06:00:00	typhoon
Nuri	08/18/2008 00:00:00–08/22/2008 18:00:00	typhoon
Sinlaku	09/08/2008 18:00:00–09/19/2008 18:00:00	super typhoon
Hagupit	09/19/2008 12:00:00–09/24/2008 06:00:00	typhoon
Jangmi	09/24/2008 12:00:00–09/28/2008 00:00:00	super typhoon
Morakot	08/03/2009 18:00:00–08/10/2009 12:00:00	typhoon
Parma	09/29/2009 00:00:00–10/14/2009 06:00:00	typhoon
Melor	09/29/2009 12:00:00–10/08/2009 12:00:00	super typhoon
Fanapi	09/15/2010 12:00:00–09/20/2010 12:00:00	typhoon
Megi	10/13/2010 12:00:00–10/23/2010 00:00:00	typhoon

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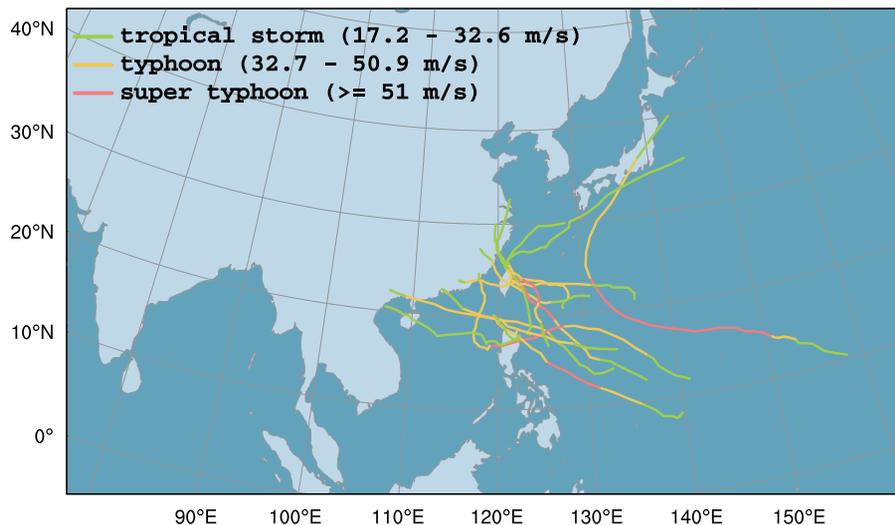


Figure 1. Domain of the TWRP and CWB best tracks of typhoons listed in Table 1. The curves indicate the track for each typhoon during its life cycle. Colors of different segments of each curve designate different stages of the corresponding storm.

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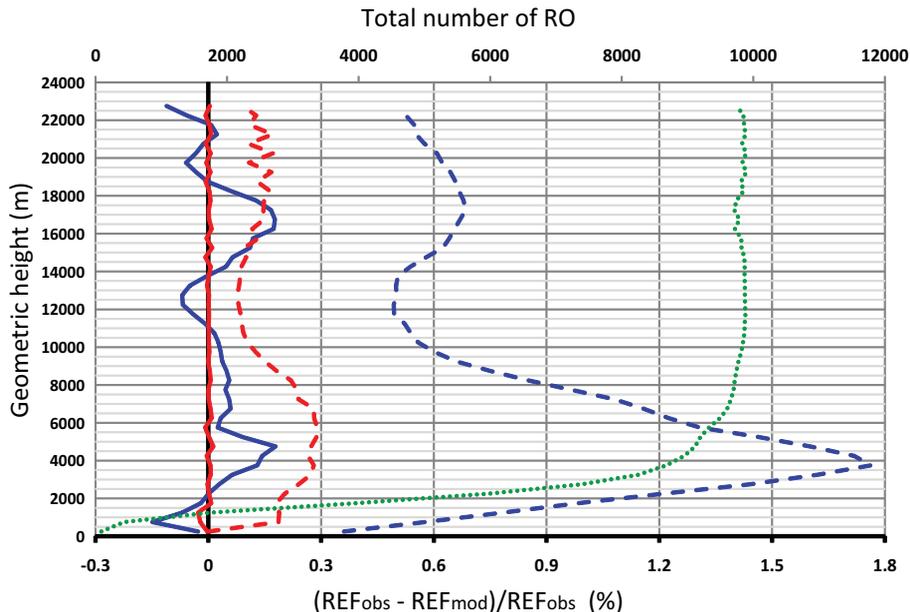


Figure 2. The solid lines are the observation-background (6 h forecast) deviation (OmB, blue) and observation-analysis deviation (OmA, red) and the dash line are their SD (blue for OmB and red for OmA) averaged over all the cases. The green line represents the total number of assimilated RO soundings. The bottom horizontal axis gives the percentage, normalized by observation refractivity, and the top horizontal axis shows the number associated with the green line.

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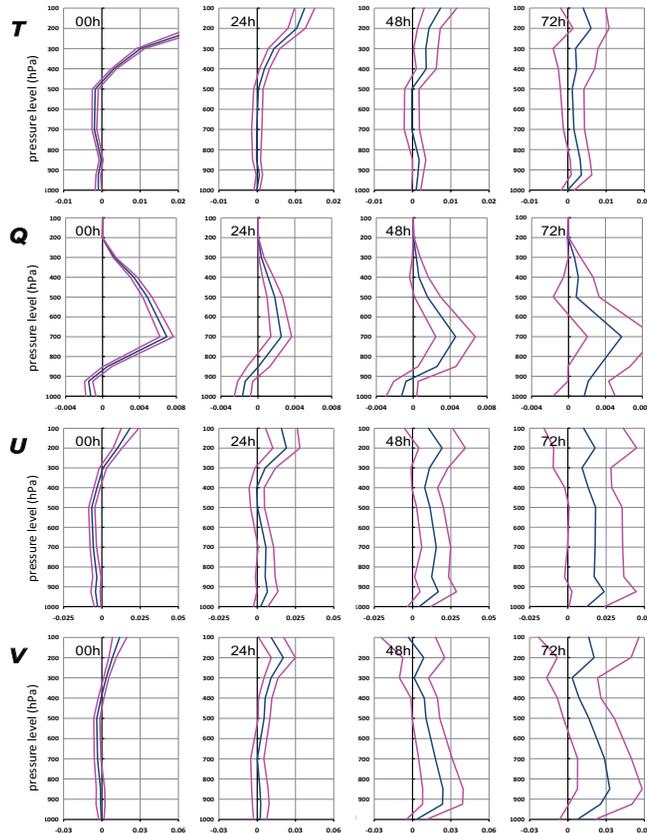


Figure 3. Mean difference in RMSE between PNG and PWG (blue line). From top to bottom: temperature (T , unit: K), mixing ratio of water vapor (Q , unit: kg kg^{-1}), zonal wind (U , unit: m s^{-1}) and meridional wind (V , unit: m s^{-1}). The vertical axis is pressure level (unit: hPa) and the area enclosed by the pink lines in each panel is the 95 % confidence interval.

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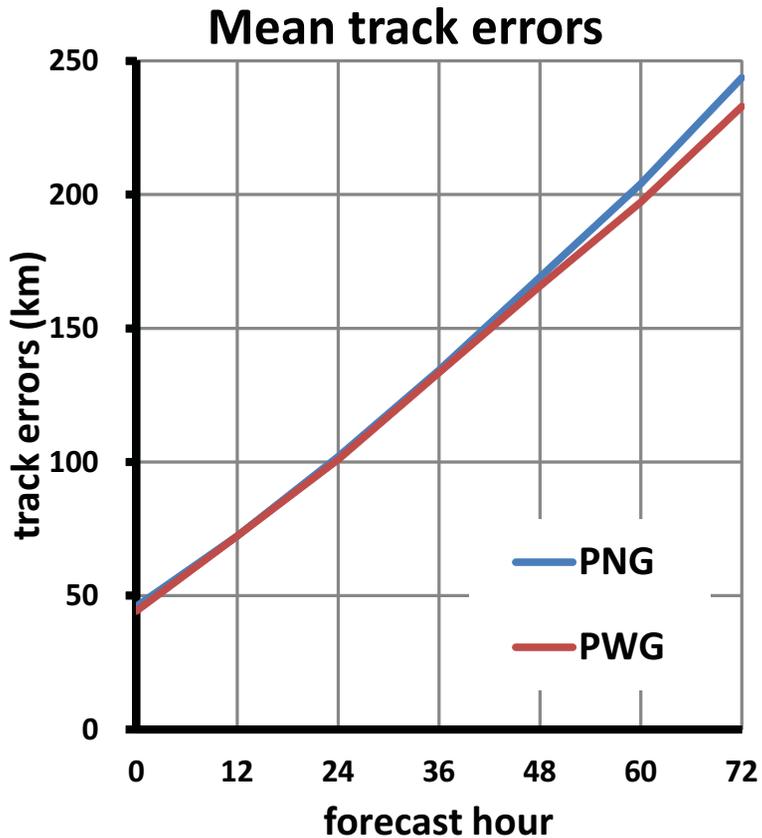


Figure 4. Mean track errors for PNG (blue line) and PWG (red line).

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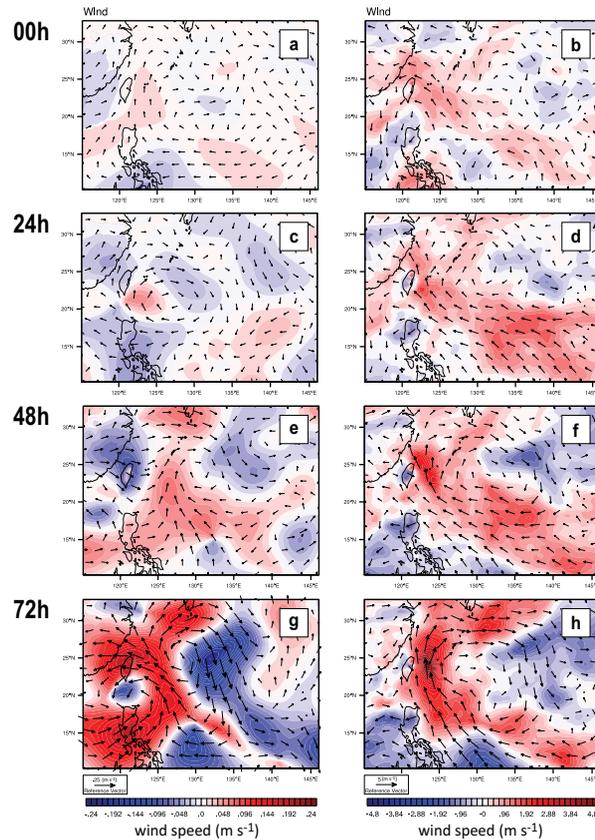


Figure 9. Mean differences of wind speed (shading) and wind vectors at 700 hPa between PWG and PNG (left column), and between ECMWF and PNG (right column) at forecast time from 0 to 72 h.

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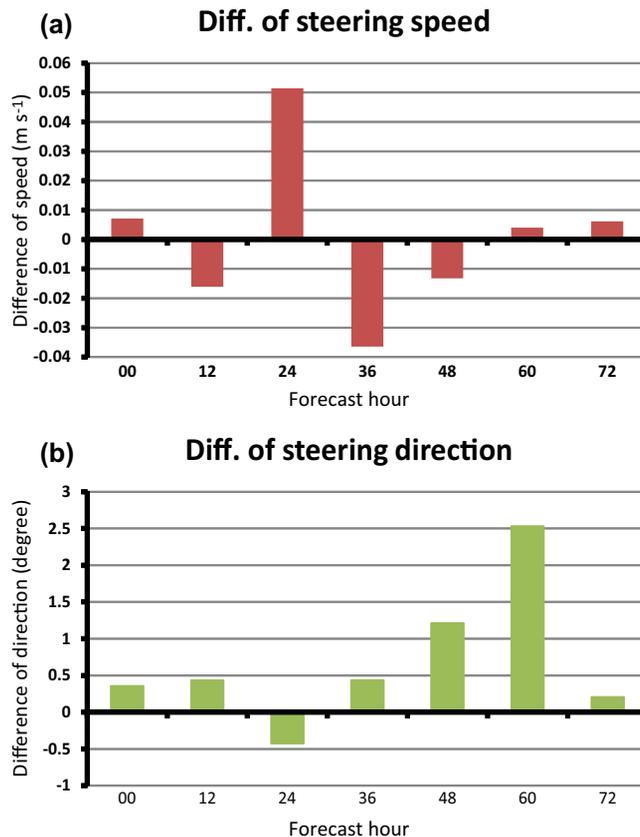


Figure 10. Difference of absolute error (against the steering flow derived from analysis of ECMWF) on steering flow **(a)** speed and **(b)** direction between PNG and PWG.

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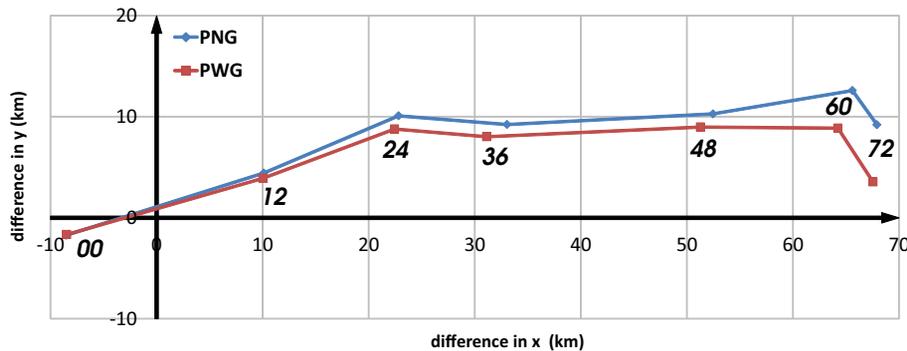


Figure 11. Mean track bias in longitude (x axis) and latitude (y axis) direction.

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