



A semi-empirical error estimation for PWV derived from atmospheric radiosonde data at the Canary Islands.

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Abstract. An unbiased method to estimate the error and the optimum number of sampled levels in Precipitable Water Vapour (PWV) determinations from atmospheric radiosoundings is proposed. Two components have been considered, the uncertainties in the measures and the sampling error. The sampling component has been modelled from an empirical dataset of 64 high vertical resolution

- 5 radiosounding profiles equipped with sondes Vaisala RS80 and RS92. The balloons were launched at the astronomical Roque de los Muchachos Observatory (ORM, ~ 2200 masl), during intensive and unique site testing runs carried out in 1990 and 1995, and from the neighbour operational station of Güímar, in Tenerife (TFE, ~ 105 masl) in 2013 – 2014. The PWV values ranged between ~ 0.9 mm and ~ 41 mm. The method takes into account the dependence on the number of samples measured,
- 10 after sub-sampling the profile for error minimization, and was tested by comparison with a dataset of 42 extremely low resolution profiles only sampling the standard levels (~ 15 levels).

The results show that errors are larger for the wettest atmosphere conditions. On the other hand, drier conditions requires a larger optimum number of samples. The optimum number of samples N_0 is less than 200 for PWV $\gtrsim 10$ mm. For drier conditions, as in astronomical sites, N_0 grows up to \sim

- 15 550 levels. This result may be important for PWV determinations in astronomical observatories. The absolute errors are always < 0.6 mm, with a median relative error of $2.4 \pm 0.8\%$ and extreme value of 7.9% in the driest condition (PWV= 0.89 mm). These errors reduce the uncertainties previously reported in the literature. Nevertheless, errors grow up to 30% in poorly sampled profiles (the number of samples being less than N_0) for dry atmospheres.
- 20 Alternative equations for direct error estimation, specifically for PWV from radiosoundings equipped with Vaisala RS80 and RS92 sensors, are also provided.





1 Introduction

Water Vapour (WV) accounts only for a 0-4% of all atmospheric molecules. Nevertheless, it is a powerful Greenhouse Gas, with strong lines of absorption and emission in the Infrared (IR). Atmospheric

- 25 WV also participates in processes affecting the global climate (Elliott and Gaffen, 1995; Ahrens, 2003) and is the principal molecule responsible for the atmospheric extinction in IR astronomical observations, specially at wavelengths longer than ~15 microns (Far IR), in several bands in the Mid and Short Wavelength IR and also in the submillimeter and microwave range (Selby and Mampaso, 1991; Hammersley, 1998; García-Lorenzo et al., 2010; Otárola et al., 2010).
- 30 The total amount of WV above a particular location is highly variable and can be expressed as the Precipitable Water Vapour (PWV), that is defined as the total water column height if integrated from the surface to the top of the atmosphere with unit cross-sectional¹. PWV is commonly expressed in mm, in terms of the height to which that water would stand if completely condensed and collected in a vessel with a cross section of 1 m^2 .
- 95 PWV can be measured by equipped radiosounding balloons, radiometers both from ground (Fowle, 1912; Guiraud et al., 1979; Carilli and Holdaway, 1999; Smith et al., 2001) or satellites (Grody et al., 1980; Menzel et al., 1998; Gao and Kaufman, 2003; Deeter, 2007; Wong et al., 2015), sun photometers (Bird and Hulstrom, 1982; Volz, 1983; Plana-Fattori et al., 1998; Firsov et al., 2013), lunar photometers (Barreto et al., 2013), GPS receivers (Bevis et al., 1992, 1994), Fourier Transform Infrared
- 40 spectrometers (Kurylo, 1991; Schneider et al., 2006) and others (Schneider et al., 2010). Among them, atmospheric radiosoundings are a direct *in situ* measurement and one of the most accurate techniques to retrieve the PWV. Radiosoundings are also one of the current standards for atmospheric research and are widely used as a valid reference for comparisons or calibrations. An error estimation of PWV from radiosoundings is therefore extremely important. Previous works have dealt
- 45 with the issue of accuracy of radiosonde measurements of PWV including experimental errors, differences in sensors output because variations of wetness in the column or comparison of different sensor types, see for example Miloshevich et al. (2006) or Romero-Campos et al. (2011). Nevertheless, as radiosondes provide a discrete profiling of the atmosphere column, other important factors impacting the final error in PWV measurements are the error propagation and the vertical sampling
- 50 (Liu et al., 2000). These last error sources have not been so much explored and are the issue of the present work.

1.1 Rationale and objectives

An accurate error estimation of PWV from radiosoundings is essential while making regression analyses in comparisons or calibration studies. In this sense, special care is needed when radiosoundings

⁵⁵ from different sources and characteristics are being included or when working in dry environments.

¹http://glossary.ametsoc.org/wiki/Precipitable_water





This is the case in Pérez-Jordán et al. (2015), where we used a set of 23 high vertical resolution balloons to validate the Weather Research and Forecasting mesoscale numerical model (WRF) for a dry astronomical location (Roque de los Muchachos Observatory, ORM hereafter; see Sect. 1.2 for a detailed description of all the locations and datasets). The possibility of making use of these radiosounding datasets supposed an opportunity, as no other atmospheric balloons have been launched

60 diosounding datasets supposed an opportunity, as no other atmospheric balloons have been launched at ORM and they provide a very high vertical resolution dataset with 2500 to 7000 datapoints per balloon flight.

A second sample of 42 radiosoundings were also included in Pérez-Jordán et al. (2015) for verification and control. The point selected was the radiosounding operational station located close to the sea level in the neighbour island of Tenerife (TFE, hereafter). The data were downloaded from the

- repository at the Department of Atmospheric Science of the University of Wyoming² (WYO hereafter). Both datasets, ORM and TFE-WYO, showed strong differences in sampling (~ 100 levels at TFE-WYO versus more than 2500 at ORM) as a consequence of the re-encoding applied at WYO. In the present work, we took the opportunity of using the data from the high vertical resolution
- 70 radiosounding flights at ORM to model the error in PWV calculations from balloons and suggest a method to retrieve it. To extend the validity of the model, we have added the dataset of 42 radiosoundings at TFE described in Pérez-Jordán et al. (2015). In this work we obtained the data from the Spanish State Meteorological Agency³ (AEMET, following the spanish acronym) to include all the available operational datapoints (> 2500). The model covers a wide variety of conditions origi-
- 75 nated by the different path lengths (departures from 105 masl and ~ 2200 masl) and PWV content ($\sim 10 40$ mm at TFE and $\sim 1 13$ mm at ORM).

The method takes into account the propagation of uncertainty and the sampling error. The result also includes an estimation of the optimum number of sampled levels needed to fit into the minimum error as a function of the expected PWV content. To validate the model, we have selected only the standard operational levels from the TFE dataset (~ 15 datapoints each radiosounding), applied the

method and compared with the full dataset.

1.2 Locations and datasets

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The balloons were launched at two separated locations (see Fig. 1): ORM at the summit of La Palma Island and the World Meteorological Organization (WMO) station 60018^4 at Güímar, Tenerife Island (TFE), both in the Canary Islands. ORM is one of the most competitive astronomical observatories in the world, hosting, among others, the current largest optical-IR telescope, the 10.4 m Gran Telescopio Canarias (GTC)⁵. The altitude at ORM ranges from ~ 2200 masl to ~ 2400 masl, being the launching point of the balloons in the lowest level. TFE station is the closest radiosounding opera-

²http://weather.uwyo.edu/upperair/sounding.html

³http://www.aemet.es/en/

⁴http://weather.gladstonefamily.net/site/60018

⁵http://www.gtc.iac.es





tional station, located 155 km away and close to the sea level (105 masl). The balloons at TFE are routinely launched twice a day (00 and 12 UTC) by the AEMET.

Because of their latitude, the strong influence from the Azores high and the cold oceanic stream, the lower troposphere of the Canary Islands exhibits a vertical structure with an almost constant thermal inversion layer (IL). The altitude of the IL ranges on average from 800 m in summer to 1600 m in winter, well below the altitude of the ORM (Dorta-Antequera, 1996). The IL separates the

- 95 moist marine boundary layer and the dry free atmosphere, inducing very high atmospheric stability above it. Therefore, the PWV condition at both locations, TFE and ORM, are strongly uncorrelated and show wide differences in atmospheric conditions. The average mesoscale conditions in the Canary Islands show a relative humidity profile drastically drooping with altitude. Temperatures below -40°C are typically reached above 8 km in the troposphere.
- 100 The ORM data comes from a very unique dataset obtained during intensive site testing assessments performed in April 1990, July 1990 and November 1995 in a join run carried out by the Instituto de Astrofísica de Canarias and the University of Nice with support of the Centre National de Recherches Météorologiques (Météo-France). The details of these campaigns are described in Vernin and Muñoz-Tuñón (1992, 1994). A total of 23 balloons were launched from the Observatory,
- 105 22 of them were selected to model the error, after rejecting the one that did not ranged the whole troposphere. The data from TFE covers one year of data with a total of 42 operational soundings from May 2013 to April 2014. Therefore, the join dataset used in the model includes 64 radiosounding with more than 2500 vertical levels each (~ 2 s of time resolution) and PWV contents ranging between < 1 mm and > 40 mm.
- 110 The radiosondes used were Vaisala RS80 at ORM (1990 and 1995) and Vaisala RS92 for the operational soundings at TFE (2013-2014). In both cases, the sondes were calibrated in the ground check immediately before the balloon release. The Vaisala standard procedure for sonde preparation and sistematic errors sources minimization were followed, besides the different corrections for day time solar heatings, etc. For an extensive characterization of both radiosonde set-ups see
- 115 Miloshevich et al. (2001, 2009). In the particular case of TFE, more details on the corrections applied are in Romero-Campos et al. (2011).

The uncertainties assumed in this work for both radiosondes are $\pm 0.5^{\circ}C, \pm 5\%$ and $\pm 1~hPa$ for temperature, relative humidity and atmospheric pressure. These values are in agreement with the estimates for the RS92 obtained within the extensive network of the GCOS (Global Climate Observing

120 System) Reference Upper-Air Network⁶ (GRUAN) by Dirksen et al. (2014). Future improvements on sensors uncertainties can be easily implemented, as for example, the inclusion of vertically resolved profiles of uncertainties (Dirksen et al., 2014) that the new binary encodings for radiosonde data, as BUFR (Dragosavac, 2007) are introducing.

⁶http://www.gruan.org





2 PWV from radiosondes

125 The PWV is obtained from the temperature *T* (°C), atmospheric pressure *p* (hPa) and relative humidity RH (%) measured by the radiosondes (Curry and Webster, 1999). Following the definition given in Sect. 1, the PWV can be expressed by:

$$PWV = \frac{10^3}{\rho} \int_{z=0}^{z=\infty} \rho_w dz \qquad (mm), \tag{1}$$

where z is the height in m and ρ and ρ_w are the liquid water and WV densities, both in kg/m³. The 130 definition of WV mixing ratio r is

$$r = \frac{m_w}{m_d} = \frac{\rho_w}{\rho_d},\tag{2}$$

where m_w and ρ_w are the mass and density of WV and m_d and ρ_d are the corresponding values for dry air. We can assume hydrostatic balance $(dp = -\rho_d \cdot g \cdot dz)$ and write Eq. 1 in the form

$$PWV = \frac{10^5}{\rho g} \int_{p_t}^{p_s} r dp \qquad (mm),$$
(3)

135 where g is the Earth gravity (m/s^2) and p_s and p_t are the pressure at surface and top of the sampled atmospheric column in hPa. We can now apply the ideal gas law and the Dalton's law of partial pressures to Eq. 2 resulting,

$$r = 0.622 \left(\frac{e}{p-e}\right),\tag{4}$$

where the coefficient 0.622 is the molecular mass ratio of WV in dry air and e is the partial vapour 140 pressure that can be obtained from the definition of relative humidity as

$$e = e_{sat} \cdot \frac{\mathrm{RH}}{100} \qquad (\mathrm{hPa}),\tag{5}$$

where the saturation vapour pressure e_{sat} can be expressed as an empirical polynomial fit, following Curry and Webster (1999):

$$e_{sat} = a_0 + T \left(a_1 + T \left(a_2 + T \left(a_3 + T \left(a_4 + T \left(a_5 + T a_6 \right) \right) \right) \right)$$
 (hPa). (6)

145 The coefficients a_i have been taken from Flatau et al. (1992) (see Table 1).

3 Error budget for PWV from radiosonde data

The integral in Eq. 3 is computed as a discrete summation over all the levels sampled by the radiosonde after a trapezoidal method. In this sense, the error will have two components, one associated to the uncertainty of the measure (σ) and other to the sampling (ϵ_s). Let ϵ_f be the final error associated to the PWV determination from radiosondes, then we can separate ϵ_f in:

$$\epsilon_f^2 = \sigma^2 + \epsilon_s^2. \tag{7}$$





3.1 Uncertainty propagation

Let σ_p , σ_T and σ_{RH} be the instrumental uncertainties associated to the direct measure of atmospheric pressure *p*, temperature *T* and relative humidity RH. The uncertainty of PWV can be obtained by 155 error propagation over all the sampled levels *N*. Applying the chain rule to the trapezoidal method in Eq. 3 leads to:

$$\sigma^{2} = \left(\frac{10^{5}}{\rho g}\right)^{2} \sum_{i=0}^{N-1} \left[\frac{1}{4} \left(\Delta p_{i}\right)^{2} \left(\sigma_{r,i+1}^{2} + \sigma_{r,i}^{2}\right) + 2 \cdot \sigma_{p}^{2} \cdot r_{i,avg}^{2}\right] \quad (mm), \tag{8}$$

where p_i is the pressure at level i, $\Delta p_i = p_{i+1} - p_i$, $r_{i,avg} = (r_{i+1} + r_i)/2$ and r_i is the mixing ratio at level i. Replace $(2 \cdot \sigma_p^2)$ by $(\sigma_{p,i+1}^2 + \sigma_{p,i}^2)$ for vertically resolved sensor uncertainties. By a recursive

160 use of the error propagation rules in Eqs. 4, 5 and 6, the following expressions are obtained for the uncertainties of water vapour mixing ratio $\sigma_{r,i}$, partial vapour pressure $\sigma_{e,i}$ and saturation vapour pressure $\sigma_{esat,i}$, all at level *i*.

$$\sigma_{r,i}^2 \approx \left(0.622 \cdot \frac{\sigma_{e,i}}{p_i}\right)^2,\tag{9}$$

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$$\sigma_{e,i}^2 = 10^{-4} \cdot \left[\left(\mathrm{RH}_i \cdot \sigma_{esat,i} \right)^2 + \left(e_{sat,i} \cdot \sigma_{\mathrm{RH}} \right)^2 \right] \qquad (\mathrm{hPa}), \tag{10}$$

$$\sigma_{esat,i}^2 = \sum_{j=0}^{6} \left[\left(T_i^j \cdot \sigma_{a,j} \right)^2 + \left(a_j \cdot j \cdot T_i^{j-1} \cdot \sigma_T \right)^2 \right] \qquad (hPa),$$
(11)

where a_j and $\sigma_{a,j}$ are the saturation vapour pressure coefficients and the associated uncertainties (see Table 1; use $\sigma_{RH,i}$ and $\sigma_{T,i}$ for vertically resolved sensor uncertainties). The contribution of

170 the covariances in the propagation of errors was specifically calculated leading to negligible values, less than 10^{-7} mm and 10^{-3} mm, for ORM and TFE, respectively, and therefore, not included in the Eqs. 8 to 11.

3.2 Sampling error

The number of levels included for PWV determinations from atmospheric radiosondes may range 175 from tens (when only standard levels are available) to thousands (full profile). The 64 balloons considered in this work range from ~ 2500 to ~ 7000 data points, dense enough to neglect the sampling error. This circumstance allowed to empirically approximate an analytical expression for ϵ_s as a function of the number of sampled levels N, following a recursive sub-sampling process.

Each profile was uniformly sub-sampled at equal intervals by taking one point in two, one in
three, etc, up to obtain 800 different realizations of PWV for the same profile (any other uniform sub-sampling is valid). The dispersion of the residuals increases in a logarithm fashion as the number of levels N decreases (see Fig. 2a), with the residuals defined as,

$$\operatorname{res}_N = I - \widetilde{I}_N,\tag{12}$$





where I and *I*_N are the integral in eq 3 calculated with all the levels in the profile (N_{max}) and with
the different realizations of N levels after the sub-sampling process. The residuals were grouped in slices for intervals of N to fit in a model. The size of the slices was selected following a quasi-logarithm scale to overcome the differences in variance (heteroscedasticity) while conserving the statistical significance (see Fig. 2a for details on the slices and the number of residuals included for each). The sample error was then obtained as the RMSE of the residuals for each slice. The RMSE
190 was calculated as the square root of the sum of the variance and the squared bias for every interval.

The dependence on N of res_N come from the integrals \tilde{I}_N in Eq. 12 in the form,

$$\widetilde{I}_N = \widetilde{\mathrm{PWV}}(N^{-1}) + E(N^{-2}),\tag{13}$$

where the first term, \widetilde{PWV} , is the composite trapezoidal sum of Eq. 3 sub-sampled to N levels and the second one is the associated error. Therefore, taking N as the middle point of each slice interval

in Fig. 2a we modelled the residuals (Eq. 12) behaviour by fitting a function A/N + B/N² + C to the RMSEs, with the coefficient C = 0, as lim_(N→∞) res_N = 0. Finally, we applied a gradient-expansion algorithm to compute a non-linear least squares fit, obtaining the following equation (red line in Fig. 2).

$$\epsilon_s = \frac{30}{N} + \frac{234}{N^2}; \quad (N \gtrsim 10).$$
 (14)

200 This equation assumes that the radiosounding is uniformly sampling the whole atmosphere where the PWV concentrates (mainly the lower and mid troposphere).

4 Optimized error

The integrated PWV is a summation and then, the uncertainty propagates with the contribution of all the addends. Therefore, σ increases with the number of levels in the profile. On the other hand,

205 the sampling error is on the opposite direction and ϵ_s increases as the number of sampled levels decreases. This behaviour is described in Fig. 2b, which shows the sampling error ϵ_s fitted in Eq. 14 and the median σ calculated as a function of the sampling levels *N* for each slice of sub-sampled data.

Therefore, it is always possible to uniformly sub-sample the profile, obtaining $\epsilon_f(N, \text{PWV})$ by 210 use of Eq. 7 for different values of N ($N \le N_{max}$). Hence, the optimized error ϵ will result in minimizing ϵ_f whilst reducing N (see Fig. 2b).

$$\epsilon^{2} = \min[\epsilon_{f}^{2}(N, \text{PWV})]$$

= $\min[\sigma^{2}(N, \text{PWV}) + \epsilon_{s}^{2}(N)],$ (15)

where ϵ_f is the final error defined in Eq. 7, σ is the propagated uncertainty (Eq. 8) and ϵ_s is the sampling error (Eq. 14). The optimum number of samples N_0 will be defined as the argument of the





minimum in Eq. 15.

$$N_0 = \arg\min[\epsilon_f]. \tag{16}$$

Finally, we can calculate the individual contribution of the uncertainty and the sampling error to the optimized error by means of,

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$$\sigma_0 = \sigma(N_0, \text{PWV}),$$

 $\epsilon_{c0} = \epsilon_c(N_0).$ (17)

5 Results

We have applied the optimization described in Sect. 4 to all the available radiosondes (both ORM and TFE), recursively computing Eq. 7 while sub-sampling the profile and carrying out the minimization

in Eq. 15. Fig. 3 shows six particular examples, two from ORM (Fig. 3a,b) and two from TFE (Fig. 3c,d), with different PWV concentrations that contain the extremes. Additionally, we have included the same two profiles showed for TFE ($N_{max} \gg N_0$) with the re-encoded sampled data downloaded from the WYO repository (see section 1.1), where $N_{max} \approx N_0$ (Fig. 3e,f). In all the cases, the residuals oscillate inside the range defined by the sampling error model (red line in Fig.

230 3) while converging. For $N_{max} \gg N_0$, the error is being dominated by σ , whereas for $N_{max} \approx N_0$ the sample error ϵ_s becomes significant. We sub-sampled the data in the profiles from WYO by extracting $N, N-2, N-4, \dots$ points, uniformly distributed, for each iteration, to obtain a sufficient number of realizations close to N_{max} .

Fig. 4 shows all the results. The parameters ϵ and N_0 are plotted together for all the available radiosondes (ORM and TFE) as a function of PWV. The optimized error ϵ is proportional to PWV whereas N_0 is the reverse. Therefore, lower amounts of PWV require more richly sampled profiles for an accurate estimation. The optimum sampling number N_0 is less than 200 for PWV $\gtrsim 10 \text{ mm}$ (see Fig. 4) while, for drier conditions, as in astronomical sites, N_0 grows up to $\gtrsim 550$ levels. All the numerical results are listed as an appendix in Tables 3 to 5.

We obtained errors less than ~ 0.6 mm for all the cases, that is significantly lower than the 1.3 mm error published by Liu et al. (2000), also taking into account the sampling effect in the error, but with no deeper analyses onto the dependence on N. Specifically for the sampling component ϵ_{s0} , we also obtained a lower average value of 0.2 mm, with a maximum of 0.34 mm, in comparison with 0.50 mm and ≈ 1 mm, respectively, obtained by Liu et al. (2000) after analysing the residuals

245 between the smoothed data (the standard output) and the much denser real-time records from 50 PWV radiosoundings at Hong Kong.

The best fits to the data are also included in Fig. 4:

$$N_0 = (615 \pm 45) \cdot \text{PWV}^{(-0.51 \pm 0.01)}; \quad (RMSE = 31), \tag{18}$$





250 $\epsilon = (0.09 \pm 0.01) \cdot \text{PWV}^{(0.53 \pm 0.01)}$ (mm); (*RMSE* = 0.02 mm). (19)

Equation 18 may be used for an *a priori* estimation of the optimum number of levels N_0 to be sampled by the radiosonde for measuring certain amount of PWV within the minimum error ϵ , while Eq. 19 gives a direct estimation of such an error if $N_{max} \ge N_0$. Therefore, these equations may be used instead of the more time-consuming sub-sampling minimization of Sect. 4. Nevertheless, Eqs. 18 and 19 are estimators of ϵ and N_0 only for radiosondes with Vaisala RS80 or RS92 sondes with

255 18 and 19 are estimators of ϵ and N_0 only for radiosondes with Vaisala RS80 or RS92 sondes with the instrumental uncertainties described in Sect. 1.2. Other experimental set-ups will require new curves to be fitted after propagating the uncertainties (see Sect. 3.1) and applying Eq. 15.

Figure 5 and Table 2 summarize the statistical results for the relative errors (ϵ_{rel} hereafter) from the whole dataset of 64 radiosoundings (ORM + TFE). Relative errors behave opposite than absolute

- 260 optimized errors ϵ , in the sense that the drier the atmosphere, the larger the ϵ_{rel} (see Fig. 5a). The median error is $2.4 \pm 0.8\%$, with ninetieth percentile $P_{90} = 5.0\%$ and an extreme value of 7.9% for the driest condition (PWV= 0.89 mm). The complete list of ϵ_{rel} is also included in the appendix, (Tables 3 to 5). These results reduce in more than a half the uncertainty of $\approx 5\%$ ($\approx 15\%$ for extremely drier conditions) published by Schneider et al. (2010) following the mixing ratio uncertainties ob-
- 265 tained by Miloshevich et al. (2009) from the vaisala RS92 RH sensors, and bring out the importance of an optimized sampling in the PWV determinations from radiosoundings.

5.1 Validation with poorly sampled radiosonde data $(N_{max} < N_0)$

To validate the model, we have selected only the standard operational levels from the TFE dataset (TFE-STD, hereafter) and compared with the high resolution profiles (see Tables 4 and 5), used

270 as the reference. The ~ 15 standard levels are the minima and mandatory levels reported by the radiosondes, but it constitutes a poorly sampled scenario $(N_{max} < N_0)$. In this case, Eq. 19 underestimates the error and the sampling component dominates. Therefore, $\epsilon \approx \epsilon_s$ and the error can be directly estimated from Eq. 14 with $N = N_{max}$.

The results of the comparison⁷ are shown in the Fig. 6, where both series are plotted with the calculated errors. The high resolution PWV series falls inside the TFE-STD error margin and, therefore, the modelled errors statistically represent the differences between the calculated PWV and the best available estimation.

The relative errors for the TFE-STD series range between 7.1% and 33.6%, with a median of \sim 17.7%. Fig. 6 also evidences the ability of the standard levels to reproduce the tendencies in long term

280 PWV monitoring programs. A poorly sampled scenario may be also found when estimating the PWV from low resolution operational radiosoundings in dry atmospheres as, for example, astronomical observatories, where the balloons are usually launched below the observatory height and thence, the lowest levels must be trimmed.

⁷The flight 13335A has been removed from the TFE-STD series because the first standard level is missed.





6 Conclusions

- We have considered two components in the error estimation for PWV obtained from radiosoundings, the uncertainties in the measures σ and the sampling error ε_s (the whole atmospheric column must be uniformly sampled). The uncertainty contribution (Eq. 8) has been estimated by means of analytical error propagation through all the levels sampled by the balloon. The sampling component has been modelled from an empirical dataset of 64 high vertical resolution radiosounding profiles (Eq. 14)
 with PWV values ranging between ~ 0.9 mm and ~ 40 mm. The model is based on the dependence
- on the number of samples of the composite trapezoidal formula for numerical integration.

The uncertainty σ increases and ϵ_s decreases as the number of sampled levels grow. Therefore, we have optimized the error whilst reducing the number of samples N. The optimization (Eq. 15) leads to the calculation of the minimum error and may be considered an appropriate estimator of the

final error in the PWV determination. The value of N in the minimum error is the optimum number of samples N_0 (Eq. 16).

The sub-sampling minimization was applied to all the radiosounding datasets. The results show a coherent behaviour with no differences or bias as a function of the profile. The largest errors were found for the wettest atmosphere conditions. On the other hand, the drier the conditions, the larger

300 the optimum number of samples N_0 needed to fit into the minimum error. The value of N_0 is less than 200 for PWV $\geq 10 \text{ mm}$ (see Fig. 4). For drier conditions, as in astronomical sites, N_0 grows up to > 550 levels. The absolute errors are always < 0.6 mm, with the sampling component $\epsilon_{s0} < 0.35 \text{ mm}$.

Two different scenarios arise after the determination of N_0 , whether the actual number of levels in 305 the profile N_{max} is greater or equal than N_0 or not. For $N_{max} \ge N_0$ is always possible to reach N_0 by sub-sampling and, therefore, the minimum error. The error behaviour with the PWV value, in this case, is shown by the Eqs. 18 and 19 from data obtained with the Vaisala RS80 and RS92 sondes. In particular, for $N_{max} \gg N_0$, the uncertainties rule the error and the sampling component may be discarded. For $N_{max} < N_0$ the sampling component dominates and the final error can be obtained 310 directly from the ϵ model (Eq. 14).

310 directly from the ϵ_s model (Eq. 14).

The model was validated by comparison of poorly sampled profiles (only standard levels) and high resolution data. The result showed that the errors estimated for the low resolution profiles contain the high resolution values, considered the reference. The errors grew up to > 30% with poorly sampled profiles for dry atmospheres.

The median error is $2.4 \pm 0.9\%$, with ninetieth percentile $P_{90} = 5.0\%$ and an extreme value of 7.9% for the driest condition (PWV= 0.89 mm). These results reduce in more than a half the uncertainties previously reported in the literature.

Therefore, not only the uncertainties are going to define the error in PWV estimations from radiosoundings, but the sampling is also playing an important role. Here we have proposed that it is 320 possible to optimize the number of sampled levels to minimize the error within the instrumental





uncertainty. Whereas a radiosounding samples at least N_0 uniform vertical levels, that is depending on the dryness of the atmosphere, the error in the PWV estimation is likely to stay below $\approx 3\%$ (P₇₅ = 4.1%) even for dry conditions. Considering more samples than N_0 increase the noise and no the the information and, therefore, the accuracy in the estimation.

325 Appendix A: Data compilation

The following tables show the PWV and associated errors for each sounding at TFE and ORM.

Acknowledgements. This work has been funded by the Instituto de Astrofísica de Canarias (IAC). The radiosonde balloons were launched at ORM by the IAC and the University of Nice with support from the Centre National de Recherches Météorologiques (Météo-France). Soundings at Güímar are launched by the Spanish

330 Agencia Estatal de Meteorología (AEMET). Special thanks are due to the AEMET members Sergio Rodríguez, Ricardo Sanz and Ernesto Barrera for their valuable discussions and suggestions. Low resolution radiosounding data are available through the page of the Dept. of Atmospheric Science at the University of Wyoming⁸. We finally would like to acknowledge the constructive suggestions of an anonymous referee that clearly contributed to improve the paper.

⁸http://weather.uwyo.edu/upperair/sounding.html





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Table 1. Saturation vapour p	ressure coefficients and as	ssociated uncertainties	(Flatau et al.,	1992)
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a_j	Coefficient	Uncertainty
a_0	6.11176750	$4.44010270\cdot 10^{-01}$
a_1	$4.43986062 \cdot 10^{-01}$	$2.86175435 \cdot 10^{-02}$
a_2	$1.43053301 \cdot 10^{-02}$	$7.95246610\cdot 10^{-04}$
a_3	$2.65027242 \cdot 10^{-04}$	$1.20785253 \cdot 10^{-05}$
a_4	$3.02246994 \cdot 10^{-06}$	$1.01581498\cdot 10^{-07}$
a_5	$2.03886313\cdot 10^{-08}$	$3.84142063 \cdot 10^{-10}$
a_6	$6.38780966 \cdot 10^{-11}$	$6.69517837\cdot 10^{-14}$

Table 2. Relative errors ϵ_{rel} statistics (%): main percentiles (P_{xx}), median (med), minimum (min), maximum (max) and dispersion (s). The dispersion has been estimated robustly by means of $1.4826 \times MAD$, where MAD is the median absolute deviation and 1.4826 is the scale factor between MAD and the standard deviation for perfect gaussian distributions.

min	P_{10}	P_{25}	med-s	med	med+s	P_{75}	P ₉₀	max
1.4%	1.8%	1.9%	1.6%	2.4%	3.2%	4.1%	5.0%	7.9%



Figure 1. Location and characteristics of the two radiosounding launching points in the Canary Islands (ORM and TFE), separated by ≈ 155 km, and the orographic profile linking the sites (the step in the altitude isolines of the orographic profile is 500m).





Table 3. PWV data and optimized error ϵ (see Eq. 15) for the 22 radiosoundings from ORM. N_{max} is the actual number of sampled levels, H_t (m) and p_t (hPa) are the top height and pressure reached by the balloon, while p_s (hPa) is the surface pressure at the launching point. The surface launching height is ~ 2200 m for all the flights. The parameters σ_0 and ϵ_{s0} are the uncertainty and sampling components of the error (Eqs. 17) and N_0 is the optimum number of levels (Eq. 16). The brackets in the last column are the relative errors ϵ_{rel} .

#	Ref	Date – Time (Y/M/D – UTC)	N_{max}	H _t (m)	p _t (hPa)	p _s (hPa)	σ_0 (mm)	ϵ_{s0} (mm)	N_0	PWV (mm)	$\epsilon (\epsilon_{rel})$ (mm; %)
1	VOL13	1990/04/02 - 02:03	3223	22685	37.4	790	0.06	0.04	806	0.89	0.07 (7.9)
2	VOL14	1990/04/02 - 05:45	3234	19757	60.1	789	0.08	0.07	462	1.84	0.11 (6.0)
3	VOL15	1990/04/03 - 00:08	3482	22455	38.7	790	0.15	0.12	268	4.53	0.19 (4.2)
4	VOL16	1990/04/03 - 03:03	3625	23284	33.7	788	0.15	0.12	259	4.64	0.19 (4.1)
5	VOL17	1990/04/05 - 04:26	2210	21429	45.6	782	0.21	0.16	201	6.29	0.26 (4.1)
6	VOL18	1990/07/13 – 22:00	2657	17797	83.7	793	0.24	0.18	178	7.94	0.30 (3.8)
7	VOL19	1990/07/17 – 02:22	7002	25537	24.2	792	0.25	0.18	171	9.68	0.31 (3.2)
8	VOL20	1990/07/18 - 00:20	4549	22648	37.9	790	0.13	0.10	304	3.25	0.16 (4.9)
9	VOL21	1990/07/20 - 02:45	4077	22749	37.2	789	0.18	0.14	227	4.45	0.22 (4.9)
10	VOL22	1990/07/21 - 00:00	2512	19646	61.3	791	0.18	0.14	229	3.56	0.22 (6.2)
11	VOL23	1990/07/21 – 03:21	3482	20683	51.6	791	0.16	0.12	249	4.52	0.20 (4.4)
12	VOL24	1990/07/21 – 22:57	4672	22542	38.5	793	0.16	0.10	312	3.81	0.19 (5.0)
13	VOL25	1990/07/22 - 03:06	3325	25818	23.1	792	0.12	0.09	333	2.63	0.15 (5.7)
14	VOL26	1990/07/22 – 22:10	4879	23126	35.2	792	0.11	0.07	444	2.59	0.13 (5.0)
15	VOL27	1990/07/23 - 01:41	4729	23793	31.7	791	0.08	0.06	526	2.04	0.10 (4.9)
16	VOL92	1995/11/01 – 11:00	3398	27987	15.7	790	0.18	0.10	309	3.83	0.20 (5.2)
17	VOL93	1995/11/03 – 00:50	3466	29257	12.9	793	0.08	0.05	578	1.83	0.09 (4.9)
18	VOL94	1995/11/03 – 22:20	2876	28593	14.4	793	0.29	0.21	152	12.9	0.36 (2.8)
19	VOL95	1995/11/04 - 02:00	2968	22755	35.5	791	0.31	0.21	149	12.9	0.37 (2.9)
20	VOL97	1995/11/08 – 23:08	3933	29481	12.1	763	0.13	0.09	328	3.68	0.16 (4.3)
21	VOL98	1995/11/09 - 01:30	3705	27971	15.6	783	0.17	0.14	218	5.44	0.22 (4.0)
22	VOL99	1995/11/09 - 04:00	4116	30828	10.2	782	0.19	0.14	229	6.85	0.23 (3.4)





Table 4. PWV data and optimized error ϵ (see Eq. 15) from the first 21 radiosoundings of 42 launched at TFE. See the caption of Table 3 for description.

#	Ref	Date – Time (Y/M/D – UTC)	N_{max}	H _t (m)	p _t (hPa)	p _s (hPa)	σ_0	ϵ_{s0} (mm)	N_0	PWV (mm)	$\epsilon (\epsilon_{rel})$ (mm: %)
	12/007D	2012/01/07 12:00	20.40	21122	(in u)	1014	()	0.15	202	()	0.00 (0.0)
1	13/00/B	2013/01/07 - 12:00	3040	31132	9.1	1014	0.24	0.15	203	9.90	0.29 (2.9)
2	13/135B	2013/05/15 - 12:00	2530	28793	14.1	1003	0.30	0.20	159	16.53	0.36 (2.2)
3	13/136A	2013/05/16 - 00:00	2611	29672	12.4	1003	0.34	0.24	131	20.25	0.41 (2.0)
4	13/148B	2013/05/28 - 12:00	2629	29995	11.9	1006	0.27	0.19	165	13.62	0.33 (2.4)
5	13/149A	2013/05/29 - 00:00	2866	30415	11.2	1009	0.30	0.22	144	17.06	0.37 (2.2)
6	13/153B	2013/06/02 - 12:00	2628	29319	13.1	1004	0.25	0.19	165	11.81	0.31 (2.6)
7	13/154A	2013/06/03 - 00:00	2333	25585	23.3	1004	0.31	0.23	138	15.32	0.38 (2.5)
8	13/165B	2013/06/14 - 12:00	2473	27297	18.0	1005	0.33	0.24	131	22.50	0.41 (1.8)
9	13/166A	2013/06/15 - 00:00	2657	28438	15.3	1004	0.23	0.14	222	10.84	0.27 (2.5)
10	13/182B	2013/07/01 - 12:00	2829	29560	12.9	1004	0.27	0.20	158	14.17	0.34 (2.4)
11	13/183A	2013/07/02 - 00:00	2908	31220	10.1	1005	0.30	0.24	133	22.61	0.39 (1.7)
12	13/203B	2013/07/22 - 12:00	2729	29786	12.5	1005	0.37	0.25	125	23.31	0.45 (1.9)
13	13/204A	2013/07/23 - 00:00	2744	30442	11.4	1005	0.35	0.25	125	22.45	0.43 (1.9)
14	13/213B	2013/08/01 - 12:00	2639	29736	12.6	1001	0.31	0.24	132	19.53	0.39 (2.0)
15	13/214A	2013/08/02 - 00:00	2557	25626	23.6	1004	0.35	0.24	135	23.15	0.42 (1.8)
16	13/233B	2013/08/21 - 12:00	3221	31950	9.0	1003	0.45	0.34	95	41.08	0.57 (1.4)
17	13/249B	2013/09/06 - 12:00	2229	27485	17.5	1003	0.36	0.30	107	26.60	0.47 (1.8)
18	13/250A	2013/09/07 - 00:00	2474	29406	13.1	1005	0.36	0.26	124	23.44	0.44 (1.9)
19	13/273B	2013/09/30 - 12:00	2638	29176	13.4	1005	0.47	0.27	120	29.30	0.54 (1.8)
20	13/274A	2013/10/01 - 00:00	2892	31355	9.7	1002	0.37	0.29	112	25.23	0.47 (1.9)
21	13/288B	2013/10/15 - 12:00	2731	29125	13.3	1008	0.34	0.22	144	17.24	0.40 (2.3)





Table 5. PWV data and optimized error ϵ (see Eq. 15) from the last 21 radiosoundings of 42 launched at TFE. See the caption of Table 3 for description.

#	Ref	Date – Time (Y/M/D – UTC)	N_{max}	H _t (m)	p _t (hPa)	p _s (hPa)	σ_0 (mm)	ϵ_{s0} (mm)	N_0	PWV (mm)	$\epsilon (\epsilon_{rel})$ (mm; %)
22	13/289A	2013/10/16 - 00:00	2847	29637	12.3	1006	0.31	0.22	143	16.69	0.38 (2.3)
23	13/329B	2013/11/25 - 12:00	2647	27989	15.4	1001	0.32	0.25	127	20.40	0.41 (2.0)
24	13/330A	2013/11/26 - 00:00	2541	27461	16.6	1000	0.30	0.21	150	16.92	0.36 (2.1)
25	13/334B	2013/11/30 - 12:00	2433	28148	15.1	1001	0.40	0.29	111	32.85	0.50 (1.5)
26	13/335A	2013/12/01 - 00:00	2511	27390	17.0	999	0.44	0.31	105	35.15	0.54 (1.5)
27	13/340B	2013/12/06 - 12:00	2078	23451	31.2	1003	0.42	0.28	116	25.39	0.50 (2.0)
28	13/341A	2013/12/07 - 00:00	2453	26832	18.5	1007	0.40	0.30	107	28.81	0.50 (1.7)
29	13/361B	2013/12/27 - 12:00	2645	30235	11.3	1010	0.32	0.20	156	16.15	0.38 (2.4)
30	13/362A	2013/12/28 - 00:00	2656	28921	13.7	1012	0.25	0.20	157	13.86	0.32 (2.3)
31	14/013B	2014/01/13 - 12:00	2782	31080	9.9	1015	0.28	0.21	147	17.25	0.36 (2.1)
32	14/014A	2014/01/14 - 00:00	2612	30027	11.6	1011	0.29	0.18	175	16.40	0.34 (2.1)
33	14/022B	2014/01/22 - 12:00	2708	26329	20.0	1010	0.35	0.23	136	21.80	0.42 (1.9)
34	14/023A	2014/01/23 - 00:00	2766	30428	10.6	1010	0.26	0.18	173	12.49	0.32 (2.6)
35	14/045B	2014/02/14 - 12:00	2695	29279	13.0	1008	0.28	0.20	159	10.98	0.34 (3.1)
36	14/046A	2014/02/15 - 00:00	2495	28342	14.8	1006	0.22	0.14	227	9.34	0.26 (2.8)
37	14/049B	2014/02/18 - 12:00	2776	31016	9.8	1009	0.23	0.19	164	11.30	0.30 (2.7)
38	14/050A	2014/02/19 - 00:00	2448	26572	19.5	1013	0.28	0.19	164	14.20	0.34 (2.4)
39	14/100B	2014/04/10 - 12:00	3094	29384	12.4	1002	0.28	0.19	163	17.38	0.34 (2.0)
40	14/101A	2014/04/11 - 00:00	2610	29792	11.8	1002	0.34	0.25	125	23.02	0.42 (1.8)
41	14/104B	2014/04/14 - 12:00	2927	29719	12.0	1002	0.36	0.24	134	22.84	0.43 (1.9)
42	14/105A	2014/04/15 - 00:00	2823	30473	10.8	1004	0.35	0.24	135	19.78	0.42 (2.1)







Figure 2. (a) Sampling error of radiosonde PWV as a function of the number of levels. The profiles were gradually sub-sampled to obtain 51200 realizations of PWV (grey circles). The error was fitted (red solid lines; see Eq. 14) to the RMSE of the residuals (see Eq. 12). The sampling levels were sliced (dotted lines). The error bars show the RMSE per slice and the "x" dots are the bias. (b) Sub-sampling error optimization. The solid black line is the experimental sample error as a function of the number of levels and the red line is the model (same as in panel (a) but with trimmed *y* axis). The blue line is the median of the propagated uncertainties (Eq. 8) for all the profiles and the dashed line is the final error (Eq. 7). The arrows show the optimized number of samples for the minimum error.







Figure 3. Six examples of sub-sampling error optimization for ORM (a) and (b) and TFE (c) and (d), with different PWV concentrations and $N_{max} \gg N_0$. Panels (e) and (f) show the same profiles that (c) and (d) but from data downloaded from the WYO repository (see section 1.1), where $N_{max} \approx N_0$. The solid grey line shows the residual between the sub-sampled PWV estimation and the best value with all the levels available. The vertical dotted lines are the optimized number of samples for the minimum error. The PWV and errors in the legend are in mm.







Figure 4. Optimized error ϵ (blue pluses and left axis) and optimum number of samples N_0 (red squares and right axis) for all the available radiosondes (ORM and TFE) as a function of the PWV value. The analytical equations are the best exponential fit to each data.







Figure 5. Relative error ϵ_{rel} statistics. Panel (a) shows all the PWV values (black), plotted together with their absolute (blue) and relative errors (red) in a logarithm scale. The thin horizontal line and shadow show the median relative error and dispersion. The dispersion has been estimated robustly by means of $1.4826 \times MAD$, where MAD is the median absolute deviation and 1.4826 is the scale factor between MAD and the standard deviation for perfect gaussian distributions. Panel (b) shows the histogram of the distribution of relative errors. The vertical lines show the median value and dispersion range (dashed). The main statistics is in the legend.







Figure 6. Comparison between the PWV series and errors (shadow) obtained from the TFE data with high resolution radiosoundings (> 2500 levels) and with the standard levels (~ 15 levels). The colours are in the legend. The labels in the x axis are the references for each balloon flight (see tables 4 and 5).