

Interactive comment on “EPN Repro2: A reference GNSS tropospheric dataset over Europe” by Rosa Pacione et al.

Response to Review #1.

Overview

As the GNSS tropospheric products are getting longer, it becomes more and more important to create homogenized products, especially for climate applications. From this perspective, the manuscript is timely and important. I think that the manuscript still needs major revision before it is ready for publication. My main comments are two folds. First, I would like to see some more explanation on the differences (esp biases) presented from the comparisons with radiosonde and ERA-Int. There are a few specific comments listed below. Second, it would be great to show how the processed data improve the detection of PW trends, even with just a few examples.

Authors' Response

The authors would like to thank Reviewer #1 for his/her constructive comments. We have considered them in the revised version to improve the quality of the paper.

We have reviewed section 4.1 'Evaluation versus Radiosonde', section 4.2 'Evaluation versus ERA-Interim' and section 5 'Conclusion' as reported below in 'Detailed Comments'.

Detailed Comments

Reviewer # 1

Fig. 10: add a horizontal zero line, so that it would be easy to see the sign of the differences. This applies to other plots too. Any explanation to the statistically significant large biases? How does this compare with prior studies? It would be better to express the biases in percentage.

Authors' Response

We have changed Figure 10 expressing the bias and standard deviation in percentage and adding the zero line as suggested. In Figure 10, we have modified the x-axis adding to the GPS site name the code of the Radiosonde used for the comparison. Moreover, we have compared the obtained results with prior studies available in literature and we have discussed mainly about the bias.

Below the revised version of section 4.1. 'Evaluation versus Radiosonde'. **Lines 286-297 changed:**

“Figure 9 shows an example for the EPN site CAGL (Cagliari, Sardinia Island, Italy). For all the 183 EPN collocated sites, and using all the data available in the considered period, we computed an overall bias and standard deviation (Figure 1). The sites are sorted according to the increasing distances from the nearest Radiosonde launch site. MALL (Palma de Mallorca, Spain) is the closest (0.5 km to Radiosonde code 8301) while GRAZ (Graz, Austria) is the most distant (133 km to Radiosonde code 14015). The amount of data available for the comparisons varies between sites depending on the availability of the GPS and Radiosonde ZTD estimates in the considered epoch and it ranges from 121 for VIS6 (Visby, Sweden, integrated in the EPN since 22-06-2014) up to 21226 for GOPE (Ondrejov, Czech Republic, integrated in the EPN since 31-12-1995).

The bias ranges from -0,87%, which corresponds to -21,2 mm, (at EVPA, Ukraine, and distance from the Radiosonde launch site 96.5 km, Radiosonde code 33946) to 0,68%, which corresponds to 15,4 mm, (at OBER, Germany, and distance from the Radiosonde launch site 90.8 km, Radiosonde code 11120). The mean bias for all sites is -0,6 mm with standard deviation of 4.9 mm. For the more than 75% (178 pairs), the agreement is below 5 mm and only 5.5% (13 pairs) have bias higher than 10 mm. The higher biases concern mostly the pairs over 50 km away from each other, like GPS stations OBER, OBE2 and OBET located in Oberpfaffenhofen (Germany) and collocated with Radiosonde (VRS90L code 11120) launched from Innsbruck Airport in Austria on the opposite side of North Chain in the Karwendel Alps. Our results are at odds with Wang et al. (2007), where authors compared PW from GPS and global Radiosonde. In contrast to them, we received small negative bias - 1.19 mm for Vaisala Radiosondes, which is the most common type used in Europe (81% of all used in this study). For MRZ, GRAW and M2K2 Radiosonde type, which represent 4.6%, 3.4% and 3.0% of compared Radiosondes respectively, we received systematic positive bias. However, Wang et al. (2007) used global Radiosonde data from 2003 and 2004, while we used all available data over Europe from 1994 to 2015. This can partly explain the disagreement even though more analysis deserves to be done. Further investigation is also needed for several near or moved GPS stations. For example in Brussels (Belgium) BRUS station, included in the EPN network since 1996, was replaced by BRUX in 2012. Their bias w.r.t. the same Radiosonde (VRS80L code 6447) has opposite sign (-1.2 mm and 3.4 mm respectively). A possible explanation is the different time span over which the bias has been computed (1996-2012 for BRUS, 2012-2015 for BRUX).

In agreement with Ning et al. 2012, the standard deviation generally increases with the distance from the Radiosonde launch site. It is in the range of [0,16; 0,76] % ,which corresponds to [3; 18] mm, till 15 km (first band in Figure 10); [0,29;0,78] % ,which corresponds to [7; 19] mm, till 70 km (second band in Figure 10) and [10; 33] mm till 133 km (third band in Figure 10). The evaluation of the standard deviation is comparable with previous studies. Haase et al. (2001) showed very good agreement with biases less than 5 mm and the standard deviation of 12 mm for most of analysed sites in Mediterranean. Similar results ($6.0 \text{ mm} \pm 11.7 \text{ m}$) were obtained also by Vedel et al. (2001). Both of them based on non-collocated pairs distant less than 50 km. Pacione et al (2011), considering 1-year of GPS ZTD and Radiosonde data over the E-GVAP super sites network, obtained a standard deviation of 5-14 mm. Dousa et al. 2012 evaluated ZTD and Radiosonde on a global scale over 10-month period and reported a standard deviation of 5–16 mm.

The assessment of the EPN Repro1 ZTD product with respect to Radiosonde using the same period, i.e. 1996-2014 when completed with the EUREF operational product after GPS week 1407 (December 30, 2006), and EPN Repro2 with respect to the Radiosonde data has an improvement of approximately 3-4% in the overall standard deviation.”

Dousa J. and G.V. Bennett: Estimation and Evaluation of Hourly Updated Global GPS Zenith Total Delays over ten Months, GPS Solutions, Online publication date: 12-Oct-2012, doi:10.1007/s10291-012-0291-7, 2012

Haase J.S., H. Vedel, M. Ge, and E. Calais: GPS zenith tropospheric delay (ZTD) variability in the Mediterranean, Phys Chem Earth (A) 26(6–8):439–443, 2001

Ning, T., R. Haas, G. Elgered, and. Willén U: Multi-technique comparisons of 10 years of wet delay estimates on the west coast of Sweden, J Geod 86: 565. doi: 10.1007/s00190-011-0527-2, 2012

Wang, J., Zhang, L., Dai. A., Van Hove, T., Van Baelen, J.: A near-global, 2-hourly data set of atmospheric precipitable water dataset from ground-based GPS measurements, J Geophys Res 112(D11107). doi:10.1029/2006JD007529, 2007

Vedel, H., K. S. Mogensen, and X.-Y. Huang: Calculation of zenith delays from meteorological data comparison of NWP model, radiosonde and GPS delays, Phys. Chem. Earth Pt. A, 26, 497–502, doi: 10.1016/S1464-1895(01)00091-6, 2001.

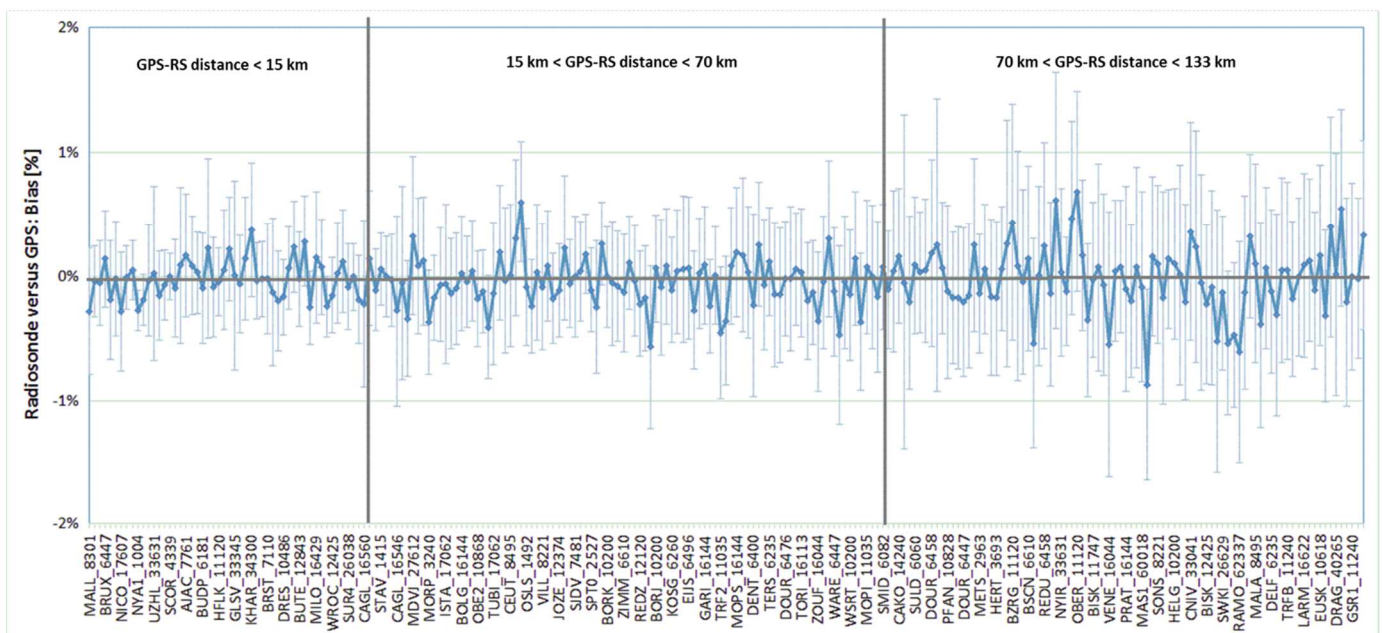


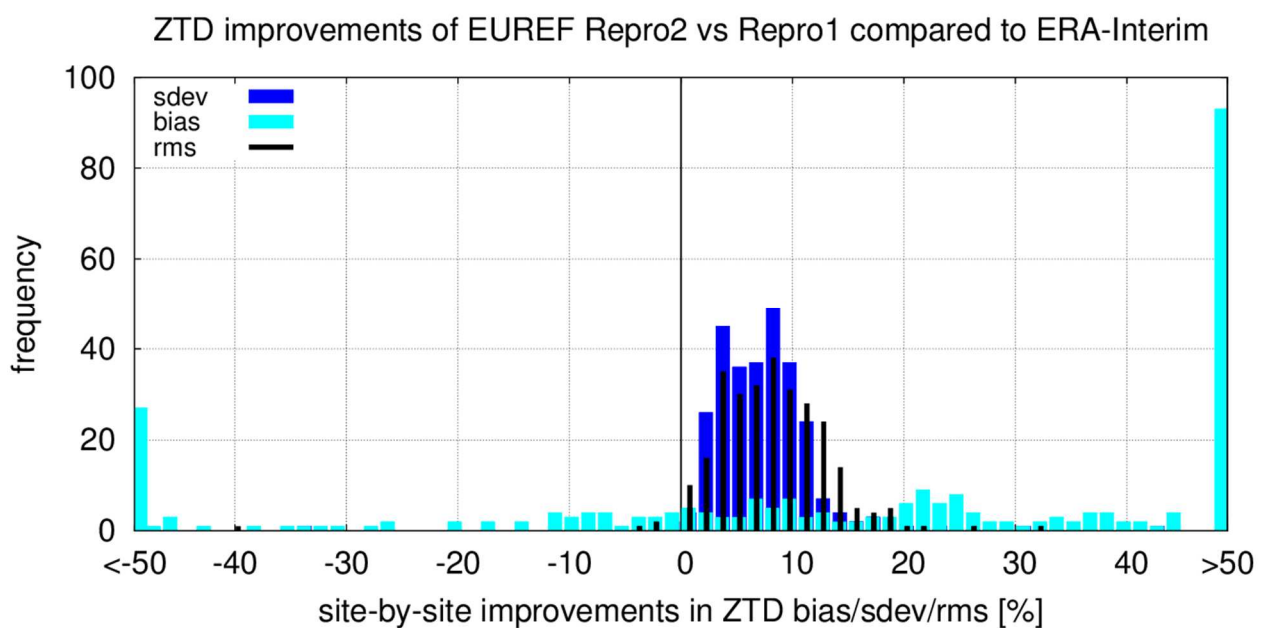
Figure 1 GPS versus Radiosonde Bias. The error bar is the standard deviation. Sites are sorted according to the increasing distances from the nearest Radiosonde launch site. The x-axis reports the GPS station and the Radiosonde code.

Reviewer # 1

Fig. 11: I would recommend to add some quantitative numbers, such as the reduction of biases and SDs, in the text (or Fig.) and the discussion. Based on visual examination, it looks like that it is mainly a shift 3.

Authors' Response

The quantitative number for overall improvement from EUREF Repro1 to Repro2 was enumerated as 8-9 % for ZTD when considering total statistics in Table 4 while Figure 11 shows distributions of ZTD bias, standard deviation over all stations. Using data from Figure 11 we expressed site-by-site improvements of all statistics. Calculated median improvements for bias, standard deviation and RMS reached 21.1 %, 6.8 % and 8.0 %, respectively, which correspond with the value of 8-9 % for an overall improvement. An additional figure (not included in the revised text) shows the distribution of statistics of ZTD improvements over all stations. Degradation of standard deviation was found for three stations only, SKE8 (Skellefteå, Sweden, integrated in the EPN since 28-09-2014), GARI (Porto Garibaldi, Italy, integrated in the EPN since 08-11-2009) and SNEC (Snezka, Czech Republic, former EPN station since 14-06-2009) all of them providing much less data compared to others, 1%, 30% and 3%, respectively. All other 290 stations showed improvements. We found 72 with increased absolute systematic errors in EUREF Repro1 compared to Repro2 while for all others (221 stations, 75%) systematic errors were reduced.



Below the revised version of section 4.2. 'Evaluation versus ERA-Interim'. **Lines 346-352 changed:**

“For completeness, we evaluated also EPN Repro1 ZTD product with respect to the ERA-Interim using the same period, i.e. 1996-2014 when completed with the EUREF operational product after GPS week 1407 (December 30, 2006). Comparing Repro1 and Repro2 with the numerical weather re-analysis showed the 8-9% improvement of the latter in both overall standard deviation and systematic error. Figure 11 shows distributions of station means and standard deviations of EPN Repro1 and Repro2 ZTDs compared to NWM ZTDs using the whole period 1996-2014. Common reductions of both statistical characteristics are clearly

visible for the majority of all stations. From data of the figure, we also expressed site-by-site improvements in terms of ZTD bias, standard deviation and RMS. Calculated medians reached 21.1 %, 6.8 % and 8.0 %, respectively, which corresponds to the abovementioned improvement of 8-9 %. The degradation of standard deviation was found at three stations: SKE8 (Skellefteå, Sweden, integrated in the EPN since 28-09-2014), GARI (Porto Garibaldi, Italy, integrated in the EPN since 08-11-2009) and SNEC (Pod Snežkou, Czech Republic, former EPN station since 14-06-2009) all of them providing much less data compared to others, 1%, 30% and 3%, respectively. All other stations (290) showed improvements. We also found 72 stations with increased absolute bias in EUREF Repro1 compared to Repro2 while all others, 221 stations (75%), resulted in reduced systematic error.”

Reviewer # 1

Fig.12, L357-358: It is not clear to me how “the limited temporal and horizontal NWM resolution as well as corresponding deficiencies in NWM orography” cause the negative differences in ZTD-NWM. Why does it vary with time (generally reduced magnitudes with time)?

Authors' Response

The corresponding sentence was finally removed. We have checked more individual stations at low altitude and the bias of -1 to 2 mm dominated even for those sites. Thus the dependence of an overall mean bias does not seem to be related to the limited spatial resolution or deficiencies in NWM orography as there was no observed significant difference in the Alps and within flat areas. The mean bias remains unknown and the uncertainty is still large and varying depending on a common set of stations.

Reviewer # 1

It would be great to show how the processed data improve the detection of PW trends, even just with a few examples.

Authors' Response

We have reviewed section 5 ‘Conclusion’ and have added examples available in the literature. As an example of application of EPN Repro2 data, we cited, in addition to the assimilation trial ongoing at UK Met Office, comparisons with regional climate model simulations ongoing at Sofia University and Hungarian Meteorologic Service. **Lines 392-395 changed:**

“According to Wang et al. (2007) IGS ZTD products are valuable source of water vapor data for climate and weather studies. The GPS PW is useful also for monitoring the quality of the radiosonde data. However, a better spatial coverage of the GNSS PW data is needed to investigate and reduce systematic biases in comparison with the global radiosonde humidity data (Wang and Zhang, 2009). On the other hand extending the observation period and complement of temporal coverage is necessary to calculate more reliable mean values and trends. As it was pointed by Baldysz et al. (2015, 2016) additional two years of ZTD data can change estimated trends up to 10%. Therefore, data after 2010 and with a better coverage over

Europe are required for improving the knowledge of climatic trends of atmospheric water vapour in Europe. In this scenario, EPN-Repro2 can be used as a reference data set with a high potential for monitoring trend and variability in atmospheric water vapour. Comparisons with regional climate model simulations is one of the application of EPN-Repro2. Ongoing at Sofia University is comparison between GNSS IWV, computed from EPN-Repro2 ZTD data for SOFI (Sofia, Bulgaria), and ALADIN-Climate IWV simulations conducted by the Hungarian Meteorological Service, for the period 2003-2008. The preliminary results show a tendency of the model to underestimate IWV. Clearly, larger number of model grid points need to be investigated in different regions in Europe and the EPN-Repro2 data is well suited for this.”

Baldysz, Z., Nykiel, G., Figurski, M., Szafranek, K., and Kroszczynski, K.: Investigation of the 16-year and 18-year ZTD Time Series Derived from GPS Data Processing. *Acta Geophys.* 63, 1103-1125, DOI: 10.1515/acgeo-2015-0033, 2015

Baldysz Z., Nykiel G., Araszkiewicz A., Figurski M. and Szafranek K.: Comparison of GPS tropospheric delays derived from two consecutive EPN reprocessing campaigns from the point of view of climate monitoring. *Atmos. Meas. Tech.*, 9, 4861-4877, DOI: 10.5194/amt-9-4861-2016, 2016

Interactive comment on “EPN Repro2: A reference GNSS tropospheric dataset over Europe” by Rosa Pacione et al.

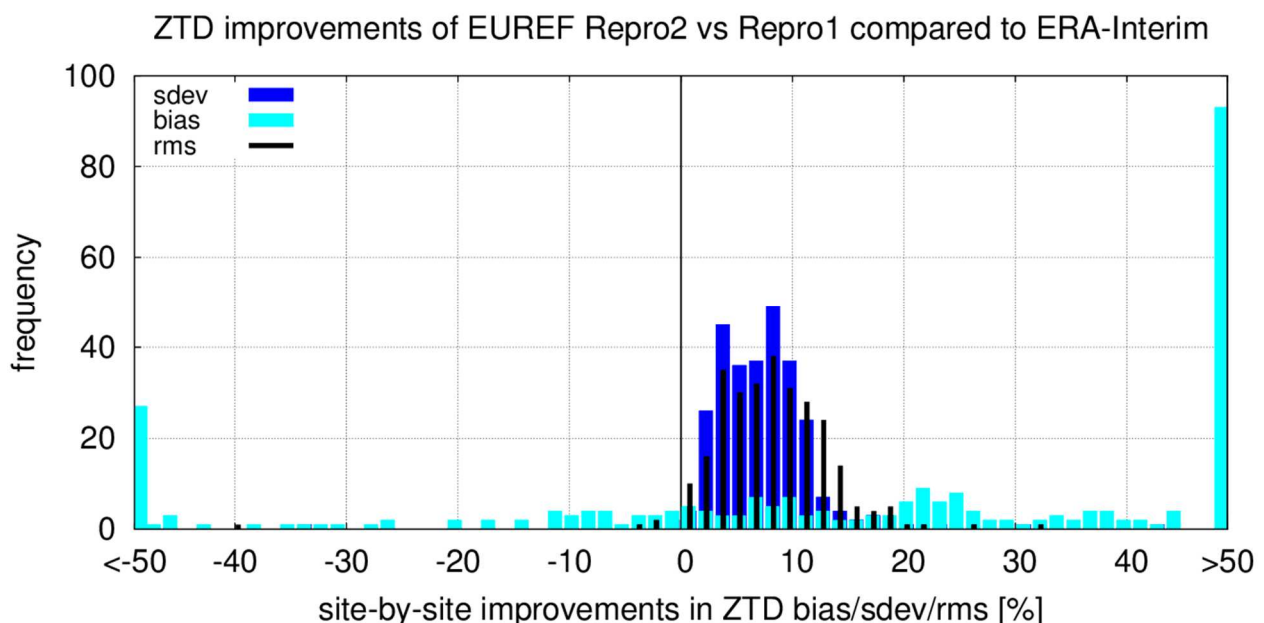
Response to Review #1 (addendum to the response uploaded on 1st February 2017)

Reviewer # 1

Fig. 11: I would recommend to add some quantitative numbers, such as the reduction of biases and SDs, in the text (or Fig.) and the discussion. Based on visual examination, it looks like that it is mainly a shift 3.

Authors' Response

Taking into account what reported in the first response, we have decided to add the additional figure reported below. In the revised text it is Figure 12.



Reviewer # 1

It would be great to show how the processed data improve the detection of PW trends, even just with a few examples.

Authors' Response

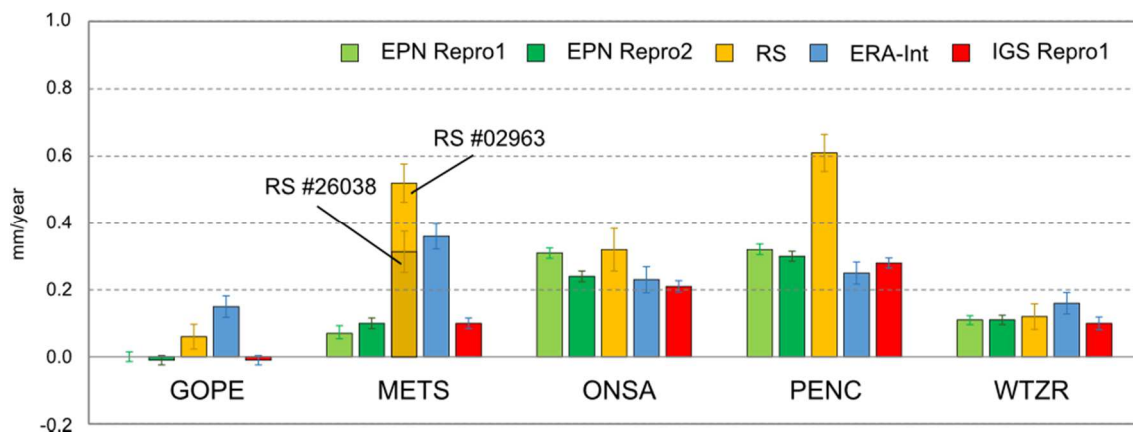
We have reviewed section 5 ‘Conclusion’ and have added examples available in the literature. As an example of application of EPN Repro2 data, we cited, in addition to the assimilation trial ongoing at UK Met Office, comparisons with regional climate model simulations ongoing at Sofia University and Hungarian Meteorologic Service.

As requested, we have computed ZTD trends at five EPN stations: GOPE (Ondrejov, Czech Republic, integrated in the EPN since 31-12-1995), METS (Kirkkonummi, Finland, integrated in the EPN since 31-12-1995), ONSA (Onsala, Sweden, integrated in the EPN since 31-12-1995), PENC (Penc, Hungary, integrated in the EPN since 03-03-1996) and WTZR (Bad Koetzting, Germany, integrated in the EPN since 31-12-1995) using EPN Repro2, EPN Repro1 completed with the EUREF operational products, radiosonde and ERA-Interim data. All of them are also in the IGS Network, for which IGS Repro1 time series is available. IGS Repro1 data completed with the IGS operational products have been extracted from the GOP-TropDB.

We have screened all data sets (classical 3 sigma). Then for all GPS ZTD data sets (EPN Repro2, EPN Repro1 + operational and IGS Repro1 + operational) we have estimated and removed shift related to the antenna replacement. No homogenization has been done for radiosonde since we do not have radiosonde metadata to do this properly. However, we think that this will affect the comparison of ZTD trends in the same way. A LSE method is applied to estimate trends and seasonal component.

Finally, we received trends for EPN Repro2 (GOPE= -0.01 ± 0.014 mm/year; METS= 0.10 ± 0.016 mm/year; ONSA= 0.24 ± 0.016 mm/year; PENC= 0.30 ± 0.015 mm/year; WTZR= 0.11 ± 0.014 mm/year) and other data sets.

ZTD trends for all three GPS ZTD data sets are consistent, as soon as the same homogenisation procedure is applied. The overall RMS is 0.02 mm/year. Among all five ZTD sourced, we find the best agreement for ONSA (RMS=0.04mm/year) and WTZR (RMS=0.02mm/year). For PENC we have good agreement with respect to ERA-Interim (0.05 mm/year), but a large discrepancy versus radiosonde (-0.31 mm/year). This large discrepancy is probably due to the distance to the radiosonde launch site (40.7 km, radiosonde code 12843) and to the lack of the homogenisation stage. Over the five considered stations the agreement with respect to ERA-Interim (RMS = 0.11 mm/year) is better than that with respect to radiosonde (RMS = 0.16 mm/year). An additional figure (included in the revised text as Figure 15) shows the ZTD trend comparisons, the error bars are the formal error of the trend values.



For the considered stations EPN Repro2 do not change significantly the detection of ZTD trends as compared to EPN Repro1 + operational or IGS Repro1 + operational. However, it has generally a better agreement w.r.t. radiosonde and ERA-Interim data than EPN Repro 1 + operational. It has also the best spatial resolution than IGS Repro1 and radiosonde data, which are used today for long-term analysis over Europe. Taking into account the good consistency among trends, EPN Repro2 can be used for trend detection in areas where other data are not available.

Lines 391-395 changed:

“However, this data set is quite sparse over Europe (only 85 stations over the 280 EPN stations) and covers the period 1996-2010. According to Wang et al. (2007) IGS ZTD products are valuable source of water vapor data for climate and weather studies. The GPS PW is useful also for monitoring the quality of the radiosonde data. However, a better spatial coverage of the GNSS PW data is needed to investigate and reduce systematic biases in comparison with the global radiosonde humidity data (Wang and Zhang, 2009). On the other hand extending the observation period and complement of temporal coverage is necessary to calculate more reliable mean values and trends. As it was pointed by Baldysz et al. (2015,

2016) additional two years of ZTD data can change estimated trends up to 10%. Therefore, data after 2010 and with a better coverage over Europe are required for improving the knowledge of climatic trends of atmospheric water vapour in Europe. In this scenario, EPN-Repro2 can be used as a reference data set with a high potential for monitoring trend and variability in atmospheric water vapour. Considering five EPN stations, among those with the longest time span, GOPE (Ondrejov, Czech Republic, integrated in the EPN since 31-12-1995), METS (Kirkkonummi, Finland, integrated in the EPN since 31-12-1995), ONSA (Onsala, Sweden, integrated in the EPN since 31-12-1995), PENC (Penc, Hungary, integrated in the EPN since 03-03-2096) and WTZR (Bad Koetzting, Germany, integrated in the EPN since 31-12-1995), we have computed ZTD trends using EPN Repro2, EPN Repro1 completed with the EUREF operational products, radiosonde and ERA-Interim data. All of them are also in the IGS Network, for which IGS Repro1 completed with the IGS operational products are available and extracted from the GOP-TropDB. First we have removed annual signal from the original time series and marked all outliers according to 3-sigma criteria. Then for all GPS ZTD data sets we have estimated all well-known and recognized shifts related to the antenna replacement. No other unexplained breaks has been removed to be sure that we not introduce any artificial errors. Based on the cleaned and filtered data we have used linear regression model before and after the considered epoch independently. The difference between those two models in specific epoch is considered as a shift. Then, we have removed all the estimated shifts from the original time series. Generally, the size of the shifts is much lower than noise level and depends on the applied method of its estimation. Therefore, the final results are affected by used methodology and cannot be considered as an absolute values. No homogenization has been done for radiosonde since radiosonde metadata are not available. Finally, a LSE method have been applied to estimate linear trends and seasonal component. ZTD trends (Figure 14) for all three GPS ZTD data sets are consistent, as soon as the same homogenisation procedure is applied. Then overall RMS is 0.02 mm/year. Among all five ZTD sourced, we find the best agreement for ONSA (RMS=0.04mm/year) and WTZR (RMS=0.02mm/year). For PENC we have good agreement with respect to ERA-Interim (0.05 mm/year), but a large discrepancy versus radiosonde (-0.31 mm/year). This large discrepancy is probably due to the distance to the radiosonde launch site (40.7 km, radiosonde code 12843) and to the lack of the homogenisation stage. Over the five considered stations the agreement with respect to ERA-Interim (RMS = 0.11 mm/year) is better than that with respect to radiosonde (RMS = 0.16 mm/year). Even though for the five considered stations EPN Repro2 do not change significantly the detection of ZTD trends, it has a better agreement with respect

to radiosonde and ERA-Interim data than EPN Repro1. It has also the best spatial resolution than IGS Repro1 and radiosonde data, which are used today for long-term analysis over Europe. Taking into account the good consistency among trends, EPN Repro2 can be used for trend detection in areas where other data are not available.

Comparisons with regional climate model simulations is one of the applications of EPN-Repro2. Ongoing at Sofia University is comparison between GNSS IWV, computed from EPN-Repro2 ZTD data for SOFI (Sofia, Bulgaria), and ALADIN-Climate IWV simulations conducted by the Hungarian Meteorological Service, for the period 2003-2008. The preliminary results show a tendency of the model to underestimate IWV. Clearly, larger number of model grid points need to be investigated in different regions in Europe and the EPN-Repro2 data is well suited for this.”

Baldysz, Z., Nykiel, G., Figurski, M., Szafranek, K., and Kroszczynski, K.: Investigation of the 16-year and 18-year ZTD Time Series Derived from GPS Data Processing. *Acta Geophys.* 63, 1103-1125, DOI: 10.1515/acgeo-2015-0033, 2015

Baldysz Z., Nykiel G., Araszkiewicz A., Figurski M. and Szafranek K.: Comparison of GPS tropospheric delays derived from two consecutive EPN reprocessing campaigns from the point of view of climate monitoring. *Atmos. Meas. Tech.*, 9, 4861-4877, DOI: 10.5194/amt-9-4861-2016, 2016

Interactive comment on “EPN Repro2: A reference GNSS tropospheric dataset over Europe” by Rosa Pacione et al.

Response to Review #2

Overview

The article contributes to an important issue on homogenization and processing of GNSS tropospheric products for climate research. The article is timely and actual. It gives systematic overview about the reprocessing campaign and combination of data products from different ACs with additional attention on impact of GLONASS data, different antenna calibration models and non-tidal atmospheric loading. The results are evaluated with independent data sources (radiosondes and ERA-Interim) and illustrated with appropriate figures and tables. The article includes adequate references on related scientific research papers. The manuscript needs some minor revision before getting ready for publication.

Authors' Response

The authors would like to thank Reviewer#2 for his/her constructive comments. We have considered them in the revised version to improve the quality of the paper.

Detailed Comments

Reviewer # 2

Figure 1: could look better with smaller markers.

Authors' Response

We have improved Figure 1 as below:

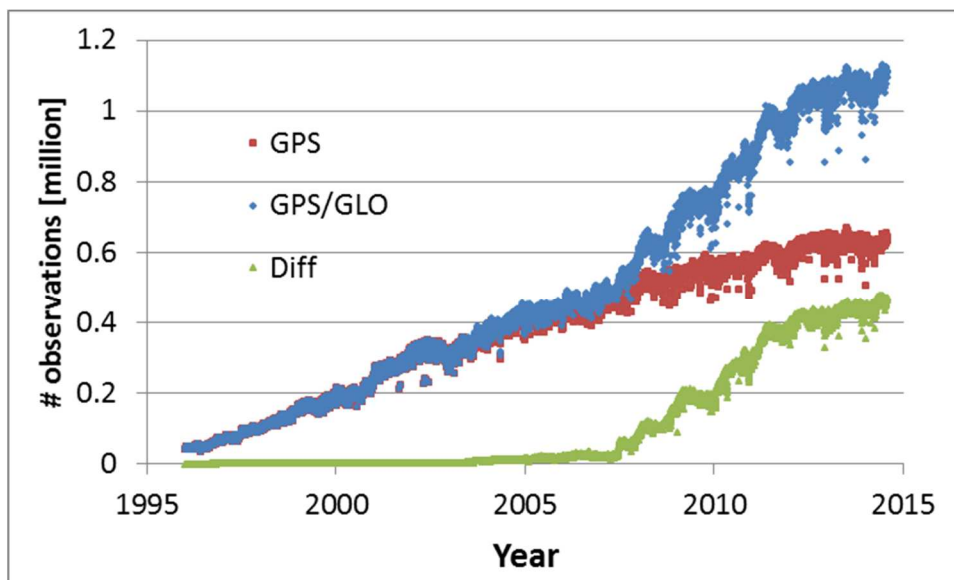


Figure 2. Time series of the number of GNSS observations for the period 1996-2014. GPS observations are shown in red, GPS+GLONASS in blue and their differences in green. The difference is significant starting 2008.

Reviewer # 2

The http-links should be checked. However, they may be broken only in this version of discussion paper due to automatic document processing during its upload. In this case the remark on the next 3 links is not relevant.

Line 36: <https://www.iers.org/ IERS/EN/ Organization/ AnalysisCoordinator/ SinexFormat/ sinex.html>

Line 45: <http://www.euref.eu/ documentation/ MoU/ EUREF-EUMETNET-MoU.pdf>

Line 566: http://www.epncb.oma.be/_documentation/papers/eurefsymposium2011/an_update_on_epn_re_processing_project_current_achievement_and_status

Authors' Response

Thank you for pointing this. We will check http-links in the final version of the manuscript.

Reviewer # 2

Line 230: small TYPO “: : : homogeneously reprocessed solutions (see Table 2)”.

Authors' Response

Correct.

Reviewer # 2

Lines 346-352: Compared Repro1 and Repro2 with ERA-Interim, Figure 11, distribution of station means and standard deviations – over which time period the mean is calculated? ERA-Interim has 6 hrs time resolution, Repro1 and Repro2 have 1 hrs (Table 2). Could the result depend on interpolation made for synchronisation of timestamps for ERA-Interim and Repro2?

Authors' Response

The mean in Figure 11 is computed for the period 1996-2014. The Repro1 dataset was completed with EUREF operational products after GPS week 1406 (December 23, 2006). For the comparison versus ERA-Interim we extracted 4 values per day at 00, 06, 12, 18 from Repro1 and Repro2 GNSS datasets using the linear approximation from values ± 30 min as EUREF solutions stores ZTDs in HR:30 only.

Datasets with different time resolutions affect the final comparison. However, both GNSS ZTD datasets (Repro1 and Repro2) have the same time resolution (1 hour) of values expressed at HR:30 and the interpolation affects both in the same way. Therefore, we can assume that both comparisons are compatible and the inter-comparison reflects principally the quality of products.

The following descriptions were improved in the manuscript:

Lines 305-312 changed:

“... software (Zus et al., 2014). Combined EUREF Repro1 and Repro2 products as well as individual ACs tropospheric parameters were assessed with the corresponding parameters estimated from the NWM re-analysis. The comparisons was done for the period 1996-2014 using the GOP-TropDB (Gyori and Dousa, 2016) via calculating parameter differences for pairs of stations and using values at every 6 hours (00:00, 6:00, 12:00 and 18:00) as available from the NWM product. A linear interpolation from values ± 30 min was thus necessarily applied for all GNSS products providing HH:30 timestamps as required for the combination

process. As all compared GNSS products has the same time resolution (1 hour), the interpolation is assumed to affect all products in the same way. Therefore, we assume all inter-comparisons to a common reference (NWM) principally reflects the quality of the products. No vertical corrections were applied since NWM parameters were estimated for the long-term antenna reference position of each station.”

Lines 346-352 changed:

“For completeness, we evaluated also EPN Repro1 ZTD product with respect to the ERA-Interim using the same period, i.e. 1996-2014 when completed with the EUREF operational product after GPS week 1407 (December 30, 2006). Comparing Repro1 and Repro2 with the numerical weather re-analysis showed the 8-9% improvement of the latter in both overall standard deviation and systematic error. Figure 11 shows distributions of station means and standard deviations of EPN Repro1 and Repro2 ZTDs compared to NWM ZTDs using the whole period 1996-2014. Common reductions of both statistical characteristics are clearly visible for the majority of all stations.”

Reviewer # 2

Lines 353-360: monthly mean biases, ZTD mean biases, Figure 12 – “There is no seasonal signal observed in time series of ZTD mean biases”, but looking at the figure (upper part – monthly mean biases) – if it isn’t a seasonal signal, then what is it?

Authors’ Response

In Figure 12: description of the subplots is swapped. The caption of Figure 12 is correct as follows: “Time series of monthly mean biases (lower part) and standard deviations (upper part) for ZTD differences of EPN Repro2 and NWM re-analysis. Uncertainties are calculated over all the stations”

Lines 359-360 changed:

“There is almost no seasonal signal observed in time series of ZTD mean biases or the uncertainty, but clearly in ZTD standard deviation and the uncertainty.”

1 EPN Repro2: A reference GNSS tropospheric dataset over Europe.

2 Rosa Pacione ⁽¹⁾, Andrzej Araszkiewicz ⁽²⁾, Elmar Brockmann ⁽³⁾, Jan Dousa ⁽⁴⁾

3 ⁽¹⁾ e-GEOS S.p.A, ASI/CGS, Italy

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7 Republic

8 *Correspondence to:* Rosa Pacione (rosa.pacione@e-geos.it)

9 **Abstract.** The present availability of 18+ years of GNSS data belonging to the EUREF Permanent
10 Network (EPN, <http://www.epncb.oma.be/>) is a valuable database for the development of a climate
11 data record of GNSS tropospheric products over Europe. This data record can be used as a reference
12 for a variety of scientific applications and has a high potential for monitoring trend and variability in
13 atmospheric water vapour, improving the knowledge of climatic trends of atmospheric water vapour
14 and being useful for regional Numerical Weather Prediction (NWP) reanalyses as well as climate
15 model simulations. In the framework of the EPN-Repro2, the second reprocessing campaign of the
16 EPN, five Analysis Centres homogenously reprocessed the EPN network for the period 1996-2014.
17 A huge effort has been made for providing solutions that are the basis for deriving new coordinates,
18 velocities and troposphere parameters for the entire EPN. The individual contributions are then
19 combined in order to provide the official EPN reprocessed products. This paper is focused on the
20 EPN Repro2 tropospheric product. The combined product is described along with its evaluation
21 against radiosonde data and European Centre for Medium-Range Weather Forecasts (ECMWF)
22 reanalysis (ERA-Interim) data.

23 1. Introduction

24 The EUREF Permanent Network (Bruyninx et al., 2012; Ihde et al., 2013) is the key geodetic
25 infrastructure over Europe currently made by over 280 continuously operating GNSS reference
26 stations maintained on a voluntary basis by EUREF (International Association of Geodesy Reference
27 Frame Sub-Commission for Europe, <http://www.euref.eu>) members. Since 1996, GNSS data
28 collected at the EUREF Permanent Network have been routinely analysed by several (currently 16)
29 EPN Analysis Centres (Bruyninx C. et al., 2015). For each EPN station, observation data along with
30 metadata information as well as precise coordinates and Zenith Total Delay (ZTD) parameters are
31 publicly available. Since June 2001, the EPN Analysis Centres (AC) routinely estimate tropospheric
32 Zenith Tropospheric Delays (ZTD) in addition to station coordinates. The ZTD, available in daily
33 SINEX TRO files, are used by the coordinator of the EPN tropospheric product to generate each week
34 the final EPN solution containing the combined troposphere estimates with an hourly sampling rate.

35 The coordinates, as a necessary part of this file, are taken from the EPN weekly combined SINEX
 36 ([http://www.iers.org/IERS/EN/Organization/AnalysisCoordinator/Sinex Format/-sinex.html](http://www.iers.org/IERS/EN/Organization/AnalysisCoordinator/Sinex%20Format/-sinex.html)) file.
 37 Hence, stations without estimated coordinates in the weekly SINEX file are not included in the
 38 combined troposphere solution. The generation of the weekly combined products is done for the
 39 routine analysis. Plots of the ZTD time series and ZTD monthly mean as well as comparisons with
 40 respect to radiosonde data are available in a dedicated section at the EPN Central Bureau web site
 41 (http://www.epncb.oma.be/_productsservices/sitezenithpathdelays/). Radiosonde profiles are
 42 provided by EUMETNET as an independent dataset to validate GPS (NAVSTAR Global Positioning
 43 System) ZTD data, and are exchanged between EUREF and EUMETNET for scientific purposes
 44 based on a Memorandum of Understanding between the two mentioned organisations,
 45 (<http://www.euref.eu/documentation/MoU/EUREF-EUMETNET-MoU-.pdf>).
 46 However, such time series are affected by inconsistencies due to updates of the reference frame and
 47 applied models, implementation of different mapping functions, use of different elevation cut-off
 48 angles and any other updates in the processing strategies, which causes inhomogeneities over time.
 49 To reduce processing-related inconsistencies, a homogenous reprocessing of the whole GNSS data
 50 set is mandatory and, for doing it properly, well-documented, long-term metadata set is required.
 51 This paper is focused on the tropospheric products obtained in the framework of the second EPN
 52 Reprocessing campaign (hereafter EPN-Repro2), where, using the latest available models and
 53 analysis strategy, GNSS data of the whole EPN network have been homogeneously reprocessed for
 54 the period 1996-2014. The EPN homogeneous long-term GNSS time series can be used as a reference
 55 dataset for a variety of scientific applications in meteorological and climate research. Ground-based
 56 GNSS meteorology, Bevis et al. (1992), is very well established in Europe and dates back to the 90s.
 57 It started with the EC 4th Framework Program (FP) projects WAVEFRONT (GPS Water Vapour
 58 Experiment For Regional Operational Network Trials) and MAGIC (Meteorological Applications of
 59 GPS Integrated Column Water Vapour Measurements in the western Mediterranean) Project (Haase
 60 et al., 2001). Early this century the ability to estimate ZTDs in Near Real Time was demonstrated
 61 (COST-716, 2005), and the EC 5th FP scientific project TOUGH (Targeting Optimal Use of GPS
 62 Humidity Measurements in Meteorology) funded. Since 2005, the operational production of
 63 tropospheric delays has been coordinated and monitored by the EUMETNET EIG GNSS Water
 64 Vapour Programme (E-GVAP, 2005-2017, Phase I, II and III, <http://egvap.dmi.dk>). Guerova et al.
 65 (2016) report on the state-of-the-art and future prospects of the ground-based GNSS meteorology in
 66 Europe. On the other hand, the use of ground-based GNSS long-term data for climate research is still
 67 an emerging field.

68 To promote the use of reprocessed long-term GNSS-based tropospheric delay data sets for climate
69 research is one of the objectives of the Working Group 3 ‘GNSS for climate monitoring’ of the EU
70 COST Action ES 1206 ‘Advanced Global Navigation Satellite Systems tropospheric products for
71 monitoring severe weather events and climate (GNSS4SWEC)’, launched for the period of 2013–
72 2017. The Working Group 3 enforces the cooperation between geodesists and climatologists in order
73 to generate recommendations on optimal GNSS reprocessing algorithms for climate applications and
74 standardise the method of conversion between propagation delay and atmospheric water vapour,
75 Saastamoinen, (1973), Bevis et al., (1992), Bock et al. (2015), with respect to climate standards. For
76 climate application, maintaining long-term stability is a key issue. Steigenberger et al. (2007) found
77 that the lack of consistencies over time due to changes in GNSS processing could cause
78 inconsistencies of several millimetres in GNSS-derived Integrated Water Vapour (IWV) making
79 climate trend analysis very challenging. Jin et al. (2007) studied the seasonal variability of GPS Zenith
80 Tropospheric Delay (1994–2006) over 150 international GPS stations and showed the relative trend
81 in northern hemisphere and southern hemisphere as well as in coastal and inland areas. Wang and
82 Zhang (2009) derived GPS Precipitable Water Vapour (PWV) using the International GNSS Service
83 (IGS), Dow et al. (2009), tropospheric products at about 400 global sites for the period 1997–2006
84 and analysed PWV diurnal variations. Nilsson and Elgered (2008) showed PWV changes from -0.2
85 mm to +1.0 mm in 10 years by using the data from 33 GPS stations located in Finland and Sweden.
86 Sohn and Cho (2010) analysed GPS Precipitable Water Vapour trend in South Korea for the period
87 2000–2009 and examined the relationship between GPS PWV and temperature, which is the one of
88 the climatic elements. Better information about atmospheric humidity, particularly in climate-
89 sensitive regions, is essential to improve the diagnosis of global warming, and for the validation of
90 climate predictions on which socio-economic response strategies are based with strong societal
91 benefits. Suparta (2012) reported on the validation of PWV as an essential tool for solar-climate
92 studies over tropical region. Ning et al. (2013) used 14 years of GPS-derived IWV at 99 European
93 sites to evaluate the regional Rossby Centre Atmospheric (RCA) climate model. GPS monthly mean
94 data were compared against RCA simulation and the ERA Interim data. Averaged over the domain
95 and the 14 years covered by the GPS data, they found IWV differences of about 0.47 kg/m² and 0.39
96 kg/m² for RCA-GPS and ECMWF-GPS, with a standard deviation of 0.98 kg/m² whereas it is 0.35
97 kg/m² respectively. Using GNSS atmospheric water vapour time series, Alshawaf et al. (2016) found
98 a positive trend at more than 60 GNSS sites in Europe with an increase of 0.3–0.6 mm/decade with a
99 temporal increment correlated with the temporal increase in the temperature levels.

100 In this scenario, EPN Repro2 tropospheric product is a unique dataset for the development of a climate
101 data record of GNSS tropospheric products over Europe, suitable for analysing climate trends and

102 variability, and calibrating/validating independent datasets at global and regional scales. However,
103 although homogeneously reprocessed, this time series suffer from site-related inhomogeneity due, for
104 example, to instrumental changes (receivers, cables, antennas, and radomes), changes in the station
105 environment, which can affect the analysis of the long-term variability (Vey et al. 2009). Therefore,
106 to get realistic and reliable climate signals such change points in the time series needs to be detected
107 (Ning et al, 2016a).

108 This paper describes the EPN-Repro2 reprocessing campaign in Section 2. Section 3 is devoted to the
109 combined solutions, i.e. the official EPN-Repro2 products, while in Section 4 the combined solutions
110 is evaluated w.r.t. Radiosonde and ERA-Interim data. Summary and recommendations for future
111 reprocessing campaign are drown in Section 5.

112 2. EPN second reprocessing campaign

113 EPN-Repro2 is the second EPN reprocessing campaign organized in the framework of the special
114 EUREF project “EPN reprocessing”. The first reprocessing campaign, which covered the period
115 1996-2006, Voelksen (2011), involved the participation of all sixteen EPN Analysis Centres (ACs)
116 reprocessing their own EPN sub-network. This guarantees that each site is processed by three ACs at
117 least which is an indispensable condition for proving a combined product. The second reprocessing
118 campaign covered all the EPN stations, which were operated from January 1996 through December
119 2013. Then, participated ACs decided to extend this period until the end of 2014 for troposphere
120 products. Data from about 280 stations in the EPN historical database have been considered. As of
121 December 2014, 23% of EPN stations are between 18-15 years old, 26% are between 14-10 years old,
122 30% between 10-5 years old, and 21% less than 5 years old. Only five, over sixteen, EPN ACs (see
123 Table 1~~Table 1~~) took part in EPN-Repro2 each providing one reprocessed solution at least. One of
124 the goal of the second reprocessing campaign was to test the diversity of the processing methods in
125 order to ensure verification of the solutions. For this reason, the three main GNSS software packages
126 Bernese (Dach et al., 2014), GAMIT (King et al., 2010) and GIPSY-OASIS II (Webb et al., 1997)
127 have been used to reprocess the whole EPN network and several variants have been provided in
128 addition. In total, eight individual contributing solutions, obtained using different software and
129 settings, and covering different EPN networks, are available. Among them, three are obtained with
130 different software and cover the full EPN network while three are obtained using the same software
131 (namely Bernese) and covering different EPN networks. In Table 2~~Table 2~~Table 2 the processing
132 characteristics of each contributing solution are reported. Despite the software used and the analysed
133 networks, there are a few diversities among the provided solutions, whose impact needs to be
134 evaluated before performing the combination. As far as the GNSS products used in the reprocessing

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campaign all the ACs used CODE Repro2 product (Lutz et al., 2014) with one exception (see [Table 2](#)) where JPL Repro2 products (Desai et al., 2014) are used. For tropospheric modelling two mapping functions are used: GMF (Boehm et al., 2006a) and VMF1 (Boehm et al., 2006b), whose impact has been evaluated in Tesmer et al., 2007.

2.1 Impact of GLONASS data

GPS data are used by all ACs in this reprocessing campaign, while two of them (namely IGE and LPT) reprocessed GPS and GLONASS (Global'naja Navigacionnaja Sputnikovaja Sistema) observations. The impact of GLONASS observations has been evaluated in terms of raw differences between ZTD estimates as well as on the estimated linear trend derived from the ZTD time series. Two solutions were prepared and compared. Both were obtained using the same software and the same processing characteristics except the observation data: one with GPS and GLONASS, and one with GPS data only. GLONASS observations are available since 2003, but only from 2008 onwards the amount of GLONASS data (see [Figure 1](#)) is significant. The difference in terms of the ZTD trends ([Figure 2](#)) between a GPS-only and a GPS+GLONASS solution shows no significant rates for more than 100 stations (rates usually derived from more than 100000 ZTD differences. This indicates that the inclusion of additional GLONASS observations in the GNSS processing has a neutral impact on the ZTD trend analysis. Satellite constellations are continuously changing in time due to satellites being replaced are newly added for all systems. This result is a positive sign that climate trends can be determined independently of the satellite systems used in the processing. In near future the inclusion of additional Galileo (Satellite System in Europe) and BeiDou (Satellite system in China) data will become operational in the GNSS data processing. These data will certainly improve the quality of the tropospheric products but, hopefully, will not introduce systematic changes in terms of ZTD trends as a possible climate indicator.

2.2 Impact of IGS type mean and EPN individual antenna calibration models

According to the processing options listed in the EPN guidelines for the Analysis Centre (http://www.epncb.oma.be/_documentation/guidelines/guidelines_analysis_centres.pdf), when available EPN individual antenna calibration models have to be used instead of IGS type mean calibration models. Currently, individual antenna calibration models are available at about 70 EPN stations. As reported in [Table 2](#) there are individual solutions carried out with IGS type mean antenna calibration models (Schmid et al., 2015) only and others with IGS type mean plus EPN individual antenna calibration models. It may happen that for the same station there are contributing solutions obtained applying different antenna models. To evaluate the impact of using these different antenna calibration models on the ZTD, two solutions were prepared and compared. Both were obtained using

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the same software and the same processing characteristics except the calibration models. First one used the IGS type mean models only, while second one used the individual calibrations whenever it was possible and IGS type mean for the rest of the antennas. An example of the time series of the ZTD difference obtained applying 'Individual' and 'Type Mean' antenna calibration models for the EPN station KLOP (Kloppenheim, Frankfurt, Germany) is shown in ~~Figure 3~~ Figure 3. KLOP station is included in the EPN network since June, 2nd 2002, a TRM29659.00 antenna with no radome was installed. Two instrumentation changes occurred at the station: the first in June 27th 2007, when the previous antenna was replaced with a TRM55971.00 and a TZGD radome, the second in June 28th 2013 with the installation of a TRM57971.00 and a TZGD radome. For all of them the individual calibrations are available through the data sets compiled by the EPN Central Bureau (ftp://epncb.oma.be/pub/station/general/epnc_08.atx). Switching between phase centre corrections from type mean to individual (or vice versa) causes a disagreement in the estimated height of the stations, as it mentioned by Araszkiewicz and Voelksen (2016), as well as in their ZTD time series. Depending on the antenna model, the offset at station KLOP in the up component is -5.2 ± 0.5 mm, 8.7 ± 0.6 mm and 5.6 ± 0.8 mm with a corresponding offset in the ZTD of 0.2 ± 0.5 mm, -1.5 ± 0.5 mm, -1.4 ± 0.8 mm, respectively. Similar situation appears also for all stations/antennas for which individual calibration models are available. The corresponding offset in the ZTD has opposite sign for the antennas with offset in the up component larger than 5 mm (16 antennas) and, generally, not exceeding 2 mm for ZTD. Such inconsistency in the ZTD time series are not large enough to be captured during the combination process (see Section 3) where 10 mm threshold in the ZTD bias (about $1.5 \text{ kg/m}^2 \text{ IWV}$) is set in order to flag problematic ACs or stations.

2.3 Impact of non-tidal atmospheric loading

As reported in the IERS Convention (2010), the diurnal heating of the atmosphere causes surface pressure oscillations at diurnal S1, semidiurnal S2, and higher harmonics. These atmospheric tides induce periodic motions of the Earth's surface (Petrov and Boy, 2004). The conventional recommendation is to calculate the station displacement using the Ray and Ponte (2003) S2 and S1 tidal model. However, crustal motion related to non-tidal atmospheric loading has been detected in station position time series from space geodetic techniques (van Dam et al., 1994; Magiarotti et al., 2001, Tregoning and Van Dam, 2005). Several models of station displacements related to this effect are currently available. Non-tidal atmospheric loading models are not yet considered as Class-1 models by the International Earth Rotation and Reference Systems Service (IERS 2010) indicating that there are currently no standard recommendations for data reduction. To evaluate their impact, two solutions, one without and one with non-tidal atmospheric loading, have been compared for the

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201 year 2013. In the last one, the National Centers for Environmental Prediction (NCEP) model is used
202 at the observation level during data reduction (Tregoning and Watson, 2009).

203 Dach et al. (2010) have already found that the repeatability of the station coordinates improves by
204 20% when applying the effect directly on the data analysis and by 10% when applying a post-
205 processing correction to the resulting weekly coordinates compared with a solution without
206 considering these corrections. However, the effect of applying non-tidal atmospheric loading on the
207 ZTD seems to be negligible. Generally, it causes a difference below 0.5 mm with a scattering not
208 larger than 0.3 mm. The difference is thus below the level of confidence. ~~Figure 4~~Figure 4 shows
209 time series of the differences of the ZTD and up component between two time series obtained with
210 and without non-tidal atmospheric loading for two EPN stations: KIRO (Kiruna, Sweden) and RIGA
211 (Riga, Latvia). There is also no correlation between values of estimated differences and vertical
212 displacements caused by non-tidal atmospheric loading. Correlation coefficients for analysed EPN
213 stations were below 0.2.

214 3. EPN Repro2 combined solutions

215 The EPN ZTD combined product is obtained applying a generalized least square approach following
216 the scheme described in Pacione et al. (2011). The first step in the combination process is reading and
217 checking the SINEX TRO files delivered by the ACs. At this stage, gross errors (i.e. ZTD estimates
218 with formal sigma larger than 15 mm) are detected and removed. The combination starts if at least
219 three different solutions are available for a single site. Then, a first combination is performed to
220 compute proper weights for each contributing solution to be used in the final combination step. In
221 this last step the combined ZTD estimates, their standard deviations and site/AC specific biases are
222 determined. The combination fails if, after the first or second combination level, the number of ACs
223 become less than three. Finally, ZTD site/AC specific biases exceeding 10 mm are investigated as
224 potential outliers.

225 The EPN-Repro2 combination activities were carried out in two steps. First, a preliminary combined
226 solution for the period 1996-2014 was performed taken as input all the available eight homogeneously
227 reprocessed solutions (see [Table 2](#)). ~~The aim of this preliminary combined solution is to assess each~~
228 contributing solution and to investigate site/AC specific biases prior to the final combination, flag the
229 outliers and send a feedback to the ACs. The agreement of each contributing solution w.r.t. the
230 preliminary combination is given in terms of bias and standard deviation (not showed) As far as the
231 standard deviation is concerned, it is generally below 2.5 mm with a clear seasonal behaviour, while
232 the bias is generally in the range of +/- 2 mm. However, there are several GPS weeks for which the
233 bias and standard deviation values exceeded the before mentioned limits. To investigate these outliers,

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the time series of site/AC specific bias has been studied, since it can be a useful tool to detect bad periods of data and provide information useful for cleaning the EPN historical archive. An example is given in [Figure 5](#) for the station VENE (Venice, Italy) for three contributing solutions AS0, GO4 and MU2 (G00 and GO1 are not shown but are very close to GO4). In the first years of acquisition, tracking issues were experienced at VENE, which are clearly mirrored in the bias time series.

All the site/AC specific biases are divided into three groups: the red group contains site/AC specific biases whose values are larger than 25 mm, the orange group contains site/AC specific biases in the range of [15 mm, 25 mm] and the yellow group contains site/AC specific biases in the range of [10 mm, 15 mm]. In [Table 3](#) summarizes percentages of red, orange and yellow biases for each contributing solution. The majority of biases belong to the yellow group; the percentage of biases in the orange group ranges from 12% for LP0 and LP1 solutions to 27% for AS0 solution, while percentage of biases in the red group ranges from 3% for MU4 solution to 22% for IG0 solution.

The final EPN Repro2 tropospheric combination is based on the following input solutions: AS0, GO4, IG0, LP1 and MU2. MUT AC provided the MU2 solution after the preliminary combination, its only difference with respect to MU4 is the use of type mean antenna and individual calibration models, whose effect is shown in section 2.2. The agreement in terms of bias and standard deviation of each contributing solution w.r.t. the final combination is shown in [Figure 6](#). As regard as the standard deviation, there is a clear improvement with respect to the preliminary combination due to the removal of the outliers detected during the preliminary combination. The standard deviation is below 3 mm from GPS week 835-1055 and 2 mm after. This is somehow related to the worse quality of data and products during the first years of the EPN/IGS activities.

The final EPN Repro2 tropospheric combination is consistent to the final coordinate combination performed by the EPN Analysis Centre Coordinator. During the coordinate combination all stations were analyzed by comparing their coordinates for specific ACs and the preliminary combined values. In case where the differences were larger than 16 mm in the up component, the station was eliminated and the whole combination was repeated, up to three times, if necessary. This ensures the consistency of final coordinates at the level of 16 mm in the up component ([Figure 7](#)). As a rule of thumb, 9 mm in the height component (i.e. 3 mm in ZTD as explained in Santerre, 1991) are needed to fulfill the requirement of retrieving IWV at an accuracy level of 0.5 kg/m2 (Bevis et al., 1994), Ning et al (2016b). As shown in [Figure 7](#), only one site, MOPI (Modra Piesok, Slovakia), exceed this threshold on a long term. As reported at the EPN Central Bureau, MOPI has been excluded several times from the routine combined solutions. MOPI has very bad periods of observations in past due to

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radome manipulation that caused jumps in the height component. However, several stations exceeded it temporary during bad periods, as shown in [Figure 8](#) for VENE (Venezia, Italy).

4. Evaluation of the ZTD Combined Products with respect to independent data set

The evaluation with respect to other sources or products, such as Radiosonde data from the E-GVAP and numerical weather re-analysis from the European Centre for Medium-Range Weather Forecasts, ECMWF (ERA-Interim), provides a measure of the accuracy of the ZTD combined products.

4.1 Evaluation versus radiosonde

For the GPS and Radiosonde comparisons at the EPN collocated sites, we used profiles from the World Meteorological Organization provided by EUMETNET in the framework of the Memorandum of Understanding between EUREF and EUMETNET. Radiosonde profiles are processed using the software (Haase et al., 2003) that checks the quality of the profiles, converts the dew point temperatures to specific humidity, transforms the radiosonde profile to correct for the altitude offset between the GPS and the radiosonde sites and determines ZTD, ZWD and IWV compensating for the change of gravitational acceleration, g , with height.

[Figure 9](#) shows an example for the EPN site CAGL (Cagliari, Sardinia Island, Italy). For all the 183 EPN collocated sites, and using all the data available in the considered period, we computed an overall bias and standard deviation ([Figure 10](#)). The sites are sorted according to the increasing distances from the nearest Radiosonde launch site. [MALL is the closest \(0.5 km\) while GRAZ is the most distant \(133 km\). The bias ranges from -21.2 mm \(at EVPA, Ukraine, and distance from the Radiosonde launch site 96.5 km\) to 15.4 mm \(at OBER, Germany, and distance from the Radiosonde launch site 90.8 km\). The standard deviation increases with the distance from the Radiosonde launch site being in the range of \[3; 18\] mm till 15 km, \[7; 19\] mm till 70 km and \[10; 33\] mm till 133 km. The assessment of the EPN Repro1 ZTD product with respect to Radiosonde using the same period, i.e. 1996-2014 when completed with the EUREF operational product after GPS week 1407 \(December 30, 2006\), and EPN Repro2 with respect to the Radiosonde data has an improvement of approximately 3-4% in the overall standard deviation. MALL \(Palma de Mallorca, Spain\) is the closest \(0.5 km to Radiosonde code 8301\) while GRAZ \(Graz, Austria\) is the most distant \(133 km to Radiosonde code 14015\). The amount of data available for the comparisons varies between sites depending on the availability of the GPS and Radiosonde ZTD estimates in the considered epoch and it ranges from 121 for VIS6 \(Visby, Sweden, integrated in the EPN since 22-06-2014\) up to 21226 for GOPE \(Ondrejov, Czech Republic, integrated in the EPN since 31-12-1995\). The bias ranges from -0.87%, which corresponds to -21.2 mm, \(at EVPA, Ukraine, and distance from the Radiosonde launch site 96.5 km, Radiosonde code 33946\) to 0.68%, which corresponds to 15.4](#)

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mm, (at OBER, Germany, and distance from the Radiosonde launch site 90.8 km, Radiosonde code 11120). The mean bias for all sites is -0,6 mm with standard deviation of 4.9 mm. For the more than 75% (178 pairs), the agreement is below 5 mm and only 5.5% (13 pairs) have bias higher than 10 mm. The higher biases concern mostly the pairs over 50 km away from each other, like GPS stations OBER, OBE2 and OBET located in Oberpfaffenhofen (Germany) and collocated with Radiosonde (VRS90L code 11120) launched from Innsbruck Airport in Austria on the opposite side of North Chain in the Karwendel Alps. Our results are at odds with Wang et al. (2007), where authors compared PW from GPS and global Radiosonde. In contrast to them, we received small negative bias -1.19 mm for Vaisala Radiosondes, which is the most common type used in Europe (81% of all used in this study). For MRZ, GRAW and M2K2 Radiosonde type, which represent 4.6%, 3.4% and 3.0% of compared Radiosondes respectively, we received systematic positive bias. However, Wang et al. (2007) used global Radiosonde data from 2003 and 2004, while we used all available data over Europe from 1994 to 2015. This can partly explain the disagreement even though more analysis deserves to be done. Further investigation is also needed for several near or moved GPS stations. For example in Brussels (Belgium) BRUS station, included in the EPN network since 1996, was replaced by BRUX in 2012. Their bias w.r.t. the same Radiosonde (VRS80L code 6447) has opposite sign (-1.2 mm and 3.4 mm respectively). A possible explanation is the different time span over which the bias has been computed (1996-2012 for BRUS, 2012-2015 for BRUX).

In agreement with Ning et al. 2012, the standard deviation generally increases with the distance from the Radiosonde launch site. It is in the range of [0,16; 0,76] % ,which corresponds to [3; 18] mm, till 15 km (first band in Figure 10); [0,29;0,78] % ,which corresponds to [7; 19] mm, till 70 km (second band in Figure 10) and [10; 33] mm till 133 km (third band in Figure 10). The evaluation of the standard deviation is comparable with previous studies. Haase et al. (2001) showed very good agreement with biases less than 5 mm and the standard deviation of 12 mm for most of analysed sites in Mediterranean. Similar results ($6.0 \text{ mm} \pm 11.7 \text{ m}$) were obtained also by Vedel et al. (2001). Both of them based on non-collocated pairs distant less than 50 km. Pacione et al (2011), considering 1-year of GPS ZTD and Radiosonde data over the E-GVAP super sites network, obtained a standard deviation of 5-14 mm. Dousa et al. 2012 evaluated ZTD and Radiosonde on a global scale over 10-month period and reported a standard deviation of 5–16 mm.

The assessment of the EPN Repro1 ZTD product with respect to Radiosonde using the same period, i.e. 1996-2014 when completed with the EUREF operational product after GPS week 1407 (December 30, 2006), and EPN Repro2 with respect to the Radiosonde data has an improvement of approximately 3-4% in the overall standard deviation.

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333 **4.2 Evaluation versus ERA-Interim data**

334 ERA-Interim (Dee et al., 2011) from the European Centre for Medium-Range Weather Forecasts
335 (ECMWF) are used as Numerical Weather Prediction (NWP) model data. The ERA-Interim is a re-
336 analysis product available every 6 hours (00, 06, 12, 18 UTC) with a horizontal resolution of 1×1
337 degree and 60 vertical model levels.

338 For the period 1996-2014 and for each EPN station, ZTD and tropospheric linear horizontal gradients
339 were computed using the GFZ (German Research Centre for Geosciences) ray-tracing software (Zus
340 et al., 2014). Combined EUREF Repro1 and Repro2 products as well as individual ACs tropospheric
341 parameters were assessed with the corresponding parameters estimated from the NWM re-analysis.
342 The evaluation of GNSS and NWM was performed using the GOP-TropDB (Gyori and Dousa, 2016)
343 via calculating parameter differences for pairs of stations using values at every 6 hours (00:00, 6:00,
344 12:00 and 18:00) as available from the NWM product. A linear interpolation from values ± 30 min
345 was thus necessarily applied for all GNSS products providing HH:30 timestamps as required for the
346 combination process. As all compared GNSS products has the same time resolution (1 hour), the
347 interpolation is assumed to affect all products in the same way. Therefore, we assume all inter-
348 comparisons to a common reference (NWM) principally reflects the quality of the products. No
349 vertical corrections were applied since NWM parameters were estimated for the long-term antenna
350 reference position of each station.

351 Table 4 summarizes the mean total statistics of individual (ACs) and combined (EUREF)
352 tropospheric parameters, ZTDs and horizontal gradients, over all available stations. The EUREF
353 combined solution does not provide tropospheric gradients and these could be evaluated for individual
354 solutions only. In Table 4, we can observe a common ZTD bias of about -1.8 mm for all GNSS
355 solutions compared to the ERA-Interim, however still highly varying for individual stations as
356 obvious from estimated uncertainties. ZTD standard deviations are generally at the level of 8 mm
357 between GNSS and NWM products, but for IG0 solution performing about 25% worse than others as
358 already detected during the combination. Two solutions, AS0 and LP1 are slightly better than GO4
359 and MU2 – reaching the standard deviation of 7.7 mm their accuracy is at the level of the EUREF
360 combined solution. The better performance of the AS0 solution can be considered due to its
361 theoretical better capability of the modelling true dynamics in the troposphere as the solution applied
362 a stochastic troposphere modelling using undifference observations sensitive to the absolute
363 tropospheric delays. On the other hand, LP1 included roughly one third from of EPN stations which
364 were properly selected according to the station quality thus making a difficulty to interpret the
365 difference with respect to those processing full EPN.

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366 The comparison of tropospheric linear horizontal gradients (East and North) from GNSS and NWM
367 revealed a problem with the MU2 solution showing a high inconsistency of results over different
368 stations, which is not visible in the total statistics, but mainly in the uncertainties by an order higher
369 compared to all others. Geographical plot (not showed) confirmed this site-specific systematic, but in
370 both positive and negative senses. The impact was however not observed in MU2 ZTD results.
371 Additionally, the GO4 solution performed slightly worse than the others. It was identified as a
372 consequence of estimating 6-hour gradients using the piece-wise linear function and without any
373 absolute or relative constraints. In such case, higher correlations with other parameters occurred
374 raising uncertainties of the estimates. For this purpose, the GO6 solution (not showed) was derived
375 fully compliant with the GO4, but stacking tropospheric gradients into 24 hours piece-wise linear
376 modelling. By comparing the GO6 (Dousa and Vaclavovic, 2016), the standard deviations dropped
377 from 0.38 mm to 0.28 mm and from 0.40 mm to 0.29 mm for East and North gradients, respectively
378 which corresponds to the LP1 solution applying the same settings. Additionally, Dousa and
379 Vaclavovic, 2016 found a strong impact of a low-elevation receiver tracking problem on estimation
380 of horizontal gradients which was particularly visible when compared to the ERA-Interim. Systematic
381 behaviour in monthly mean difference in gradient seems to be a useful indicator for instrumentation-
382 related issues and should be applied as one of the tools for cleaning the EPN historical archive.

383 ~~For completeness, we evaluated also EPN Repro1 ZTD product with respect to the ERA-Interim~~
384 ~~using the same period, i.e. 1996-2014 when completed with the EUREF operational product after~~
385 ~~GPS week 1407 (December 30, 2006). Comparing Repro1 and Repro2 with the numerical weather~~
386 ~~re-analysis showed the 8-9% improvement of the latter in both overall standard deviation and~~
387 ~~systematic error. Figure 11 shows distributions of station means and standard deviations of EPN~~
388 ~~Repro1 and Repro2 ZTDs compared to NWM ZTDs. The reductions are clearly visible as common~~
389 ~~for the majority of the stations.~~

390 For completeness, we evaluated also EPN Repro1 ZTD product with respect to the ERA-Interim
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392 GPS week 1407 (December 30, 2006). Comparing EPN Repro1 and EPN Repro2 with the numerical
393 weather re-analysis showed the 8-9% improvement of the latter in both overall standard deviation
394 and systematic error. Figure 11 shows distributions of station means and standard deviations of EPN
395 Repro1 and EPN Repro2 ZTDs compared to NWM ZTDs using the whole period 1996-2014.
396 Common reductions of both statistical characteristics are clearly visible for the majority of all stations.
397 From data of Figure 11, we also expressed site-by-site improvements in terms of ZTD bias, standard
398 deviation and RMS (Figure 12). Calculated medians reached 21.1 %, 6.8 % and 8.0 %, respectively.

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which corresponds to the abovementioned improvement of 8-9 %. The degradation of standard deviation was found at three stations: SKE8 (Skellefteå, Sweden, integrated in the EPN since 28-09-2014), GARI (Porto Garibaldi, Italy, integrated in the EPN since 08-11-2009) and SNEC (Snezka, Czech Republic, former EPN station since 14-06-2009) all of them providing much less data compared to others, 1%, 30% and 3%, respectively. All other stations (290) showed improvements. We also found 72 stations with increased absolute bias in EUREF Repro1 compared to Repro2 while all others, 221 stations (75%), resulted in reduced systematic error.

Time series of monthly mean biases and standard deviations for ZTD differences of EPN Repro2 and the ERA-Interim is showed in Figure 13. The small negative bias slowly decreases towards 2014, but a high uncertainty of the mean indicates site-specific behaviour depending mainly on latitude and altitude of the EPN station and the quality of both NWM and GNSS products. ~~The former due to the limited temporal and horizontal NWM resolution as well as corresponding deficiencies in NWM orography, the latter depending on quality of a receiver tracking, available antenna phase centre variation models and site environment.~~ There is almost no seasonal signal observed in time series of ZTD mean biases or the uncertainty, but clearly in ZTD standard deviation and the uncertainty. Slightly increasing standard deviation towards 2014 can be attributed to the increase of number of stations in EPN starting from about 30 in 1996 and with more than 250 in 2014. More stations reduces a variability in monthly mean biases, however, site-specific errors then contribute more to higher values of standard deviation.

Figure 14 displays the geographical distribution of total ZTD biases and standard deviations for all sites. Prevailing negative biases seem to become lower or even positive in the mountain areas. There is no latitudinal dependence observed for ZTD biases in Europe, but a strong one for standard deviations. This corresponds mainly to the increase of water vapour content and its variability towards the equator.

5. Conclusion

In this paper, we described the activities carried out in the framework of the EPN second reprocessing campaign. We focused on the tropospheric products homogeneously reprocessed by five EPN Analysis Centres for the period 1996-2014 and we described the ZTD combined products.

Both individual and combined tropospheric products along with reference coordinates and other metadata, are stored in SINEX TRO format, Gendt, G. (1997), and are available to the users at the EPN Regional Data Centres (RDC), located at BKG (Federal Agency for Cartography and Geodesy, Germany). For each EPN station, plots on ZTD time series, ZTD monthly mean, comparison versus

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431 Radiosonde data (if collocated), and comparison versus the ERA-Interim data will be available at the
432 EPN Central Bureau (Royal Observatory of Belgium, Brussels, Belgium).

433 Assessment of the EPN Repro1 and Repro2 with respect to the Radiosonde data has an improvement
434 of approximately 3-4% in the overall standard deviation.

435 Assessment of the EPN Repro1 and Repro2 with respect to the ERA-Interim re-analysis showed the
436 8-9% improvement of the latter over the former in both overall standard deviation and systematic
437 error which was obvious for majority of the stations. Comparisons of the GNSS solutions with the
438 NWM, i.e. independent source, showed the overall agreement at the level of 8-9 mm, however, rather
439 site-specific ranging from 5 mm to 15 mm for standard deviations and from -7 mm to 3 mm for biases
440 considering 99% of results roughly.

441 The use of ground-based GNSS long-term data for climate research is an emerging field. For the
442 assessment of Euro-CORDEX (Coordinated Regional Climate Downscaling Experiment) climate
443 model simulation IGS Repro1, Byun and Bar-Sever, (2009), has been used as reference reprocessed
444 GPS products (Bastin et al. 2016). However, this data set is quite sparse over Europe (only 85 stations
445 over the 280 EPN stations) and covers the period 1996-2010. According to Wang et al. (2007) IGS
446 ZTD products are valuable source of water vapor data for climate and weather studies. The GPS PW
447 is useful also for monitoring the quality of the radiosonde data. However, a better spatial coverage of
448 the GNSS PW data is needed to investigate and reduce systematic biases in comparison with the
449 global radiosonde humidity data (Wang and Zhang, 2009). On the other hand extending the
450 observation period and complement of temporal coverage is necessary to calculate more reliable mean
451 values and trends. As it was pointed by Baldysz et al. (2015, 2016) additional two years of ZTD data
452 can change estimated trends up to 10%. Therefore, dData after 2010 and with a better coverage over
453 Europe are required for improving the knowledge of climatic trends of atmospheric water vapour in
454 Europe. In this scenario, EPN-Repro2 can be used as a reference data set with a high potential for
455 monitoring trend and variability in atmospheric water vapour.

456 Considering five EPN stations, among those with the longest time span, GOPE (Ondrejov, Czech
457 Republic, integrated in the EPN since 31-12-1995), METS (Kirkkonummi, Finland, integrated in the
458 EPN since 31-12-1995), ONSA (Onsala, Sweden, integrated in the EPN since 31-12-1995), PENC
459 (Penc, Hungary, integrated in the EPN since 03-03-2096) and WTZR (Bad Koetzing, Germany,
460 integrated in the EPN since 31-12-1995), we have computed ZTD trends using EPN Repro2, EPN
461 Repro1 completed with the EUREF operational products, radiosonde and ERA-Interim data. All of
462 them are also in the IGS Network, for which IGS Repro1 completed with the IGS operational products
463 are available and extracted from the GOP-TropDB. First we have removed annual signal from the

original time series and marked all outliers according to 3-sigma criteria. Then for all GPS ZTD data sets we have estimated all well-known and recognized shifts related to the antenna replacement. No other unexplained breaks has been removed to be sure that we not introduce any artificial errors. Based on the cleaned and filtered data we have used linear regression model before and after the considered epoch independently. The difference between those two models in specific epoch is considered as a shift. Then, we have removed all the estimated shifts from the original time series. Generally, the size of the shifts is much lower than noise level and depends on the applied method of its estimation. Therefore, the final results are affected by used methodology and cannot be considered as an absolute values. No homogenization has been done for radiosonde since radiosonde metadata are not available. Finally, a LSE method have been applied to estimate linear trends and seasonal component. ZTD trends (Figure 15) for all three GPS ZTD data sets are consistent, as soon as the same homogenisation procedure is applied. Then overall RMS is 0.02 mm/year. Among all five ZTD sourced, we find the best agreement for ONSA (RMS=0.04mm/year) and WTZR (RMS=0.02mm/year). For PENC we have good agreement with respect to ERA-Interim (0.05 mm/year), but a large discrepancy versus radiosonde (-0.31 mm/year). This large discrepancy is probably due to the distance to the radiosonde launch site (40.7 km, radiosonde code 12843) and to the lack of the homogenisation stage. Over the five considered stations the agreement with respect to ERA-Interim (RMS = 0.11 mm/year) is better than that with respect to radiosonde (RMS = 0.16 mm/year). Even though for the five considered stations EPN Repro2 do not change significantly the detection of ZTD trends, it has a better agreement with respect to radiosonde and ERA-Interim data than EPN Repro1. It has also the best spatial resolution than IGS Repro1 and radiosonde data, which are used today for long-term analysis over Europe. Taking into account the good consistency among trends, EPN Repro2 can be used for trend detection in areas where other data are not available.

Comparisons with regional climate model simulations is one of the application of EPN-Repro2. Ongoing at Sofia University is comparison between GNSS IWV, computed from EPN-Repro2 ZTD data for SOFI (Sofia, Bulgaria), and ALADIN-Climate IWV simulations conducted by the Hungarian Meteorological Service, for the period 2003-2008. The preliminary results show a tendency of the model to underestimate IWV. Clearly, larger number of model grid points need to be investigated in different regions in Europe and the EPN-Repro2 data is well suited for this. Climate research is not only limited to comparison with climate model and derivation of trends. At the Met Office, the UK's national weather service, within the framework of the European FP7 project UERRA (Uncertainties in Ensembles of Regional Re-analysis, <http://www.uerra.eu/>), assimilation trials of reprocessed ZTD into a 12 km European climate reanalysis beginning in 1979 are ongoing. To account for any

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497 systematic bias or bias change, the reprocessed ZTDs will have a bias correction applied before
498 assimilation.

499 The reprocessing activity of the five EPN ACs was a huge effort generating homogeneous products
500 not only for station coordinates and velocities, but also for tropospheric products. The knowledge
501 gained will certainly help for a next reprocessing activity. A next reprocessing will most likely
502 include Galileo and BeiDou data and therefore it will be started in some years from now after having
503 successfully integrated these new data in the current operational near real-time and daily products of
504 EUREF. The consistent use of identical models in various software packages is another challenge for
505 the future to be able to improve the consistency of the combined solution. Prior any next reprocessing,
506 it was agreed in EUREF to focus on cleaning and documenting data in the EPN historical archive as
507 it should highly facilitate any future work. For this purpose, all existing information need to be
508 collected from all the levels of data processing, combination and evaluation which includes initial
509 GNSS data quality checking, generation of individual daily solutions, combination of individual
510 coordinates and ZTDs, long-term combination for velocity estimates and assessments of ZTDs and
511 gradients with independent data sources.

512

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517

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695

696 **Table**

697 **Table Captions**

698 ~~Table 1: EPN Analysis Centres providing EPN Repro2 solutions~~
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700 ~~Table 2: EPN Repro2 processing options for each contributing solutions. AS0 solutions provided by~~
701 ~~ASI/CGS (Matera, Italy), GO0, GO1 and GO4 solutions provided by GOP (Pecny, Czech Republic),~~
702 ~~IG0 solution provided by IGE (Madrid, Spain), LP0 and LP1 solutions provided by LPT (Waben,~~
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708 ~~Table 3. Percentage of red, orange and yellow bias for each contributing solution~~
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710 ~~Table 4. Mean statistics and uncertainties, calculated from results of individual stations, provided~~
711 ~~for AC individuals and EUREF combined (Repro1 and Repro2) tropospheric parameters compared~~
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AC	Full name	City	Country	SW	EPN Network
ASI	Agenzia Spaziale Italiana	Matera	Italy	GIPSY-OASIS II	Full EPN
GOP	Geodetic Observatory	Pecny	Czech Republic	Bernese	Full EPN
IGE	National Geographic Institute	Madrid	Spain	Bernese	EPN-Subnetwork
LPT	Federal Office of Topography	Wabern	Switzerland	Bernese	EPN-Subnetwork
MUT	Military University of Technology	Warsaw	Poland	GAMIT	Full EPN

Table 1: EPN Analysis Centres providing EPN Repro2 solutions.

	AS0	GO0	GO1	GO4	IG0	LP0	LP1	MU2	MU4
SW	GIPSY 6.2	Bernese 5.2			Bernese 5.2	Bernese 5.2		GAMIT 10.5	
GNSS	G	G			G + R	G + R		G	
SOLUTION TYPE	PPP	Network			Network	Network		Network	
STATIONS	Full EPN	Full EPN			EPN Subnetwork	EPN Subnetwork		Full EPN	
ORBITS	JPL R2	CODE R2			CODE R2	CODE R2		CODE R2	
ANTENNAS	IGS08	IGS08 + Individual.			IGS08+ Individual.	IGS08	IGS08 + Individual.	IGS08 + Individual.	IGS08
IERS	2010	2010			2010	2010		2010	
GRAVITY	EGM08	EGM08			EGM08	EGM08		EGM08	
TROPOSPHERE Estimated Parameters	ZTD (5min) GRAD (5min)	ZTD (1h) GRAD (6h)			ZTD (1h) GRAD (6h)	ZTD (1h) GRAD (24h)		ZTD (1h) GRAD (24h)	
MAPPING FUNCTION	VMF1	GMF	VMF1	VMF1	GMF	GMF	VMF1	VMF1	
ZTD/GRAD time stamp	hh:30 24 estimates/day	hh:30 (and hh:00) 24(+24) estimates/day			hh:30 24 estimates/day	hh:30 (and hh:00) 24(+24) estimates/day		hh:30 24 estimates/day	
IONOSPHERE	HOI included	CODE, HOI included			CODE (HOI included)	CODE (HOI included)		CODE IONEX + IGRF11 (HOI included)	
REFERENCE FRAME	IGb08	IGb08			IGb08	IGb08		IGb08	
OCEAN TIDES	FES2004	FES2004			FES2004	FES2004		FES2004	
TIDAL-ATMOSPHERIC LOADING	NO	NO			YES	YES	YES	YES	
NON-TIDAL-ATMOSPHERIC LOADING	NO	NO	NO	YES	NO	NO	YES	NO	
ELEVATION CUTOFF	3	3			3	3		5	
Delivered SNX_TRO Files [from week to week]	0834-1824	0836-1824			0835-1816	0835-1802		0835-1824	

Table 2: EPN Repro2 processing options for each contributing solutions. AS0 solutions provided by ASI/CGS (Matera, Italy), GO0, GO1 and GO4 solutions provided by GOP (Pecny, Czech Republic), IG0 solution provided by IGE (Madrid, Spain), LP0 and LP1 solutions provided by LPT (Waben, Switzerland), MU2 and MU4 solutions provided by MUT (Warsaw, Poland).

Solution	%Red bias	% Orange bias	% Yellow bias
AS0	17	27	56
G00	10	22	67
G01	12	23	65
G04	12	23	65
IG0	22	14	64
LP0	10	12	79
LP1	10	12	78
MU2	3	15	82

Table 3. Percentage of red, orange and yellow bias for each contributing solution.

Solution	ZTD bias [mm]	ZTD sdev [mm]	EGRD bias [mm]	EGRD sdev [mm]	NGRD bias [mm]	NGRD sdev [mm]
AS0 (full EPN)	-1.7±2.0	7.7±1.9	0.00±0.06	0.32±0.09	0.09±0.06	0.33±0.10
GO4 (full EPN)	-1.9±2.4	8.1±2.1	-0.04±0.09	0.38±0.10	0.00±0.09	0.40±0.12
MU2 (full EPN)	-1.8±2.0	8.3±2.1	-0.03±0.32	0.35±2.46	-0.01±0.84	0.34±2.37
IG0 (part EPN)	-1.6±2.3	10.7±2.2	-0.05±0.09	0.33±0.11	0.04±0.12	0.36±0.12
LP1 (part EPN)	-1.7±2.4	7.7±1.7	-0.02±0.06	0.28±0.05	0.03±0.09	0.27±0.06
EUR Repro2	-1.8±2.1	7.8±2.2	-	-	-	-
EUR Repro1	-2.2±2.3	8.5±2.1	-	-	-	-

Table 4. Mean statistics and uncertainties, calculated from results of individual stations, provided for AC individuals and EUREF combined (Repro1 and Repro2) tropospheric parameters compared to the ERA-Interim re-analysis.

729 **Figure**

730 **Figure Captions**

731 Figure 1. Time series of the number of GNSS observations for the period 1996-2014. GPS
732 observations are shown in red, GPS+GLONASS in blue and their differences in green. The difference
733 is significant starting 2008. Figure 1. Time series of the number of GNSS observations for the period
734 1996-2014. GPS observations are shown in red, GPS+GLONASS in blue and their differences in
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736 Figure 2. ZTD trend difference GPS – GPS/GLO, computed over 111 sites. The rate in violet (primary
737 y-axis) and the number of used difference is in green (secondary y-axis). Figure 2. ZTD trend
738 difference GPS – GPS/GLO, computed over 111 sites. The rate in violet (primary y-axis) and the
739 number of used difference is in green (secondary y-axis).

740 Figure 3. EPN station KLOP (Kloppenheim, Frankfurt, Germany) ZTD time series difference
741 between ‘individual’ and ‘type mean’ calibration model. Two instrumentation changes occurred at
742 the station (marked by red lines): the first in June 27th 2007, when the previous antenna was replaced
743 with a TRM55971.00 and a TZGD radome, the second in June 28th 2013 with the installation of a
744 TRM57971.00 and a TZGD radome. Figure 3. EPN station KLOP (Kloppenheim, Frankfurt, Germany)
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747 when the previous antenna was replaced with a TRM55971.00 and a TZGD radome, the second in
748 June 28th 2013 with the installation of a TRM57971.00 and a TZGD radome.

749 Figure 4. Left part: Time series of the ZTD and up component differences between two time series
750 obtained with and without Non-Tidal Atmospheric Loading for two EPN stations: KIRO (Kiruna,
751 Sweden) and RIGA (Riga, Latvia). Figure 4. Left part: Time series of the ZTD and up component
752 differences between two time series obtained with and without Non Tidal Atmospheric Loading for
753 two EPN stations: KIRO (Kiruna, Sweden) and RIGA (Riga, Latvia).

754 Figure 5 VENE (Venice Italy) time series of bias and standard deviation for the three contributing
755 solutions AS0, GO4 and MU4 for the period July 21st, 1996 - July 28, 2007 (GPS week 0863-1437).
756 GO0 and GO1 are not shown since they are very close to GO4. Figure 5 VENE (Venice Italy) time
757 series of bias and standard deviation for the three contributing solutions AS0, GO4 and MU4 for the
758 period July 21st, 1996 – July 28, 2007 (GPS week 0863-1437). GO0 and GO1 are not shown since
759 they are very close to GO4.

760 Figure 6 Weekly mean bias (upper part) and standard deviation (lower part) of each contribution
761 solutions w.r.t. the final EPN Repro2 combination. Figure 6 Weekly mean bias (upper part) and
762 standard deviation (lower part) of each contribution solutions w.r.t. the final EPN Repro2
763 combination.

764 Figure 7. The final consistency in up component for all stations. Stations are sorted by name. Figure
765 7. The final consistency in up component for all stations. Stations are sorted by name.

766 Figure 8 VENE (Venice Italy) time series of total consistency in up component for the period July
767 21st, 1996 - July 28, 2007 (GPS week 0863-1437). Figure 8 VENE (Venice Italy) time series of total
768 consistency in up component for the period July 21st, 1996 – July 28, 2007 (GPS week 0863-1437).

769 Figure 9 EPN station CAGL (Cagliari, Sardinia Island, Italy). Upper part: Radiosondes (in red) and
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771 Sardinia Island, Italy). Upper part: Radiosondes (in red) and GPS (in blue) ZTD time series. Lower
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773 Figure 10: GPS versus Radiosonde Bias. The error bar is the standard deviation. Sites are sorted
 774 according to the increasing distances from the nearest Radiosonde launch site.Figure 10: GPS versus
 775 Radiosonde Bias. The error bar is the standard deviation. Sites are sorted according to the increasing
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777 Figure 11: Distributions of station means (left) and standard deviations (right) of EPN Repro1 and
 778 Repro2 ZTDs compared to ERA-Interim ZTDs.Figure 11: Distributions of station means (left) and
 779 standard deviations (right) of EPN Repro1 and Repro2 ZTDs compared to ERA-Interim ZTDs.

780 Figure 12: Site-by-site ZTD improvements of EPN Repro2 versus EPN Repro1 compared to ERA-
 781 Interim

782 Figure 13: Time series of monthly mean biases (lower part) and standard deviations (upper part) for
 783 ZTD differences of EPN Repro2 and NWM re-analysis. Uncertainties are calculated over all
 784 stations.Figure 12: Time series of monthly mean biases (upper part) and standard deviations (lower
 785 part) for ZTD differences of EPN Repro2 and NWM re-analysis. Uncertainties are calculated over all
 786 stations.

787 Figure 14: Geographical display of ZTD biases (left) and standard deviations (right) for EPN Repro2
 788 products compared to the ERA-Interim.Figure 13: Geographical display of ZTD biases (left) and
 789 standard deviations (right) for EPN Repro2 products compared to the ERA-Interim.

790 Figure 15: ZTD trend comparisons at five EPN stations. The error bars are the formal error of the
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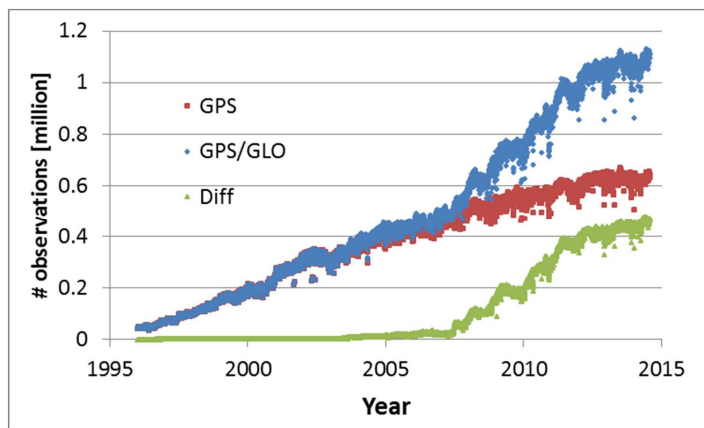
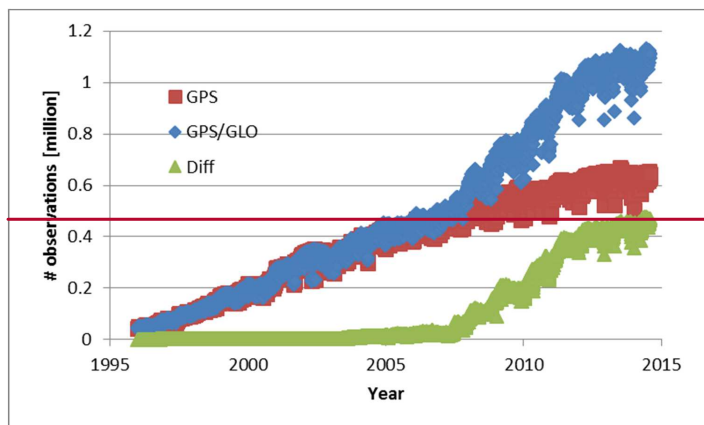


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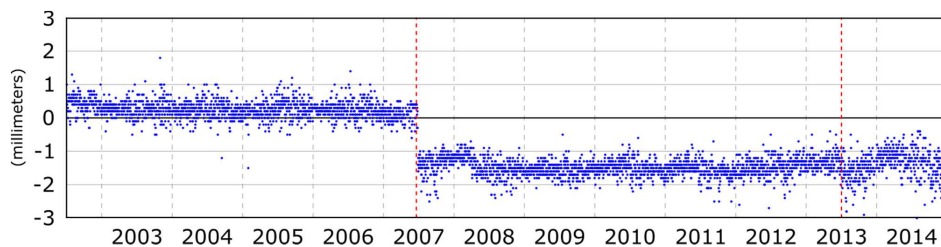


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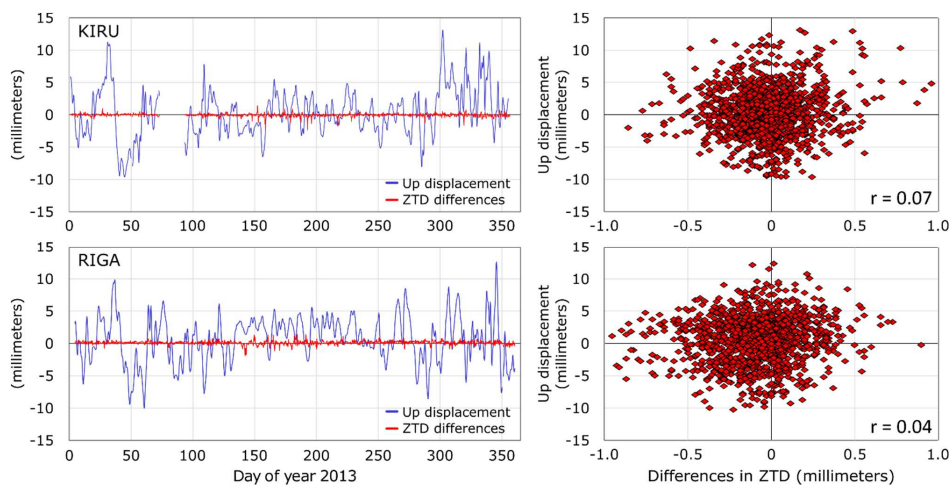
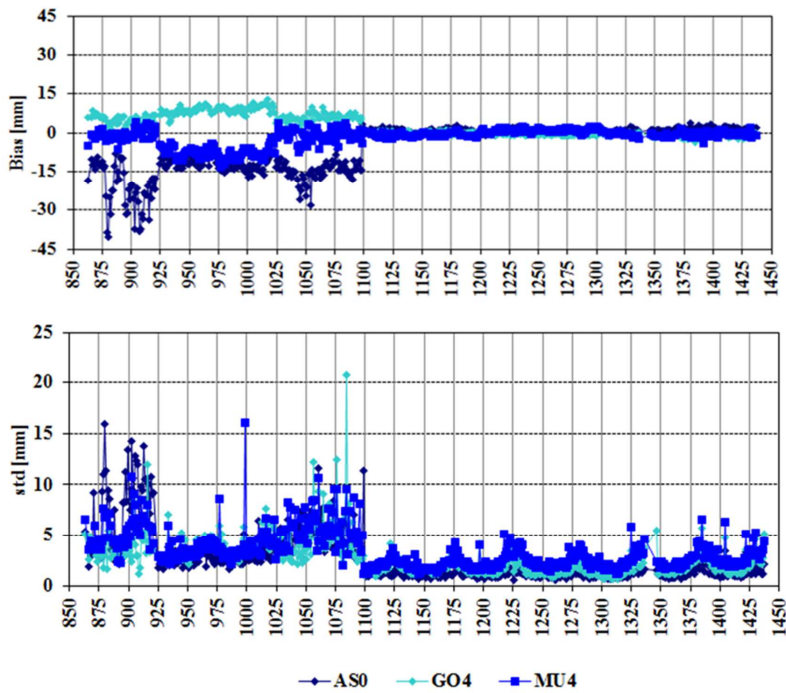
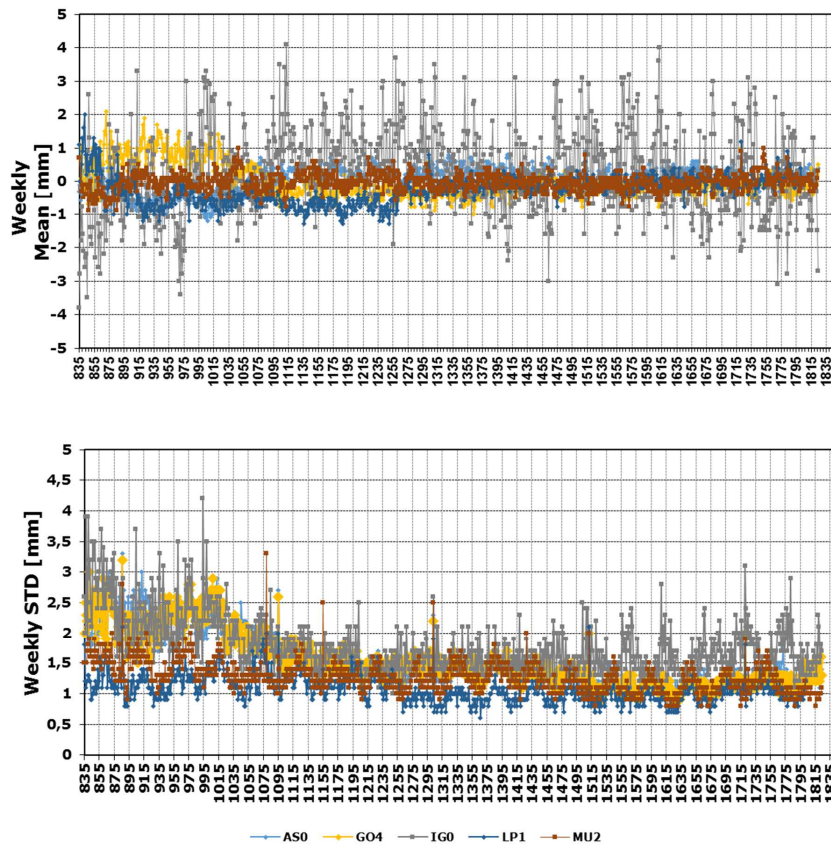


Figure 4. Left part: Time series of the ZTD and up component differences between two time series obtained with and without Non-Tidal Atmospheric Loading for two EPN stations: KIR0 (Kiruna, Sweden) and RIGA (Riga, Latvia). Right part: Correlation between these two parameters.



815
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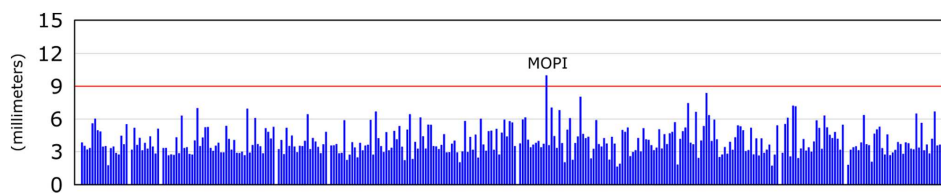
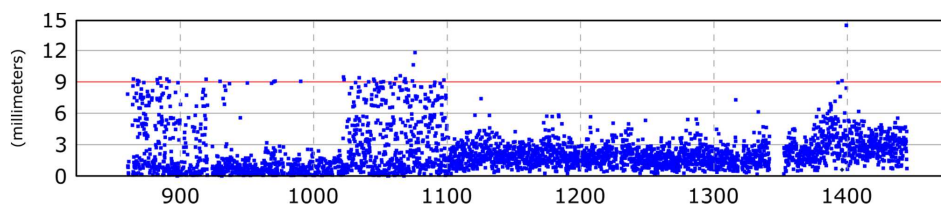


Figure 7. The final consistency in up component for all stations. Stations are sorted by name.



827
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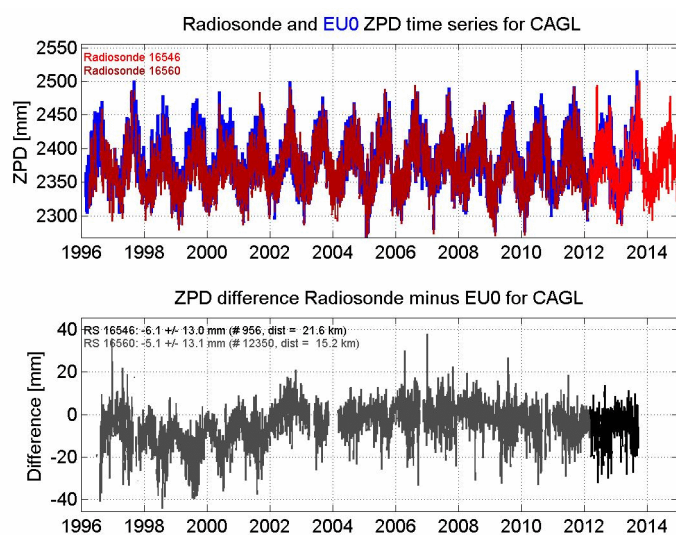
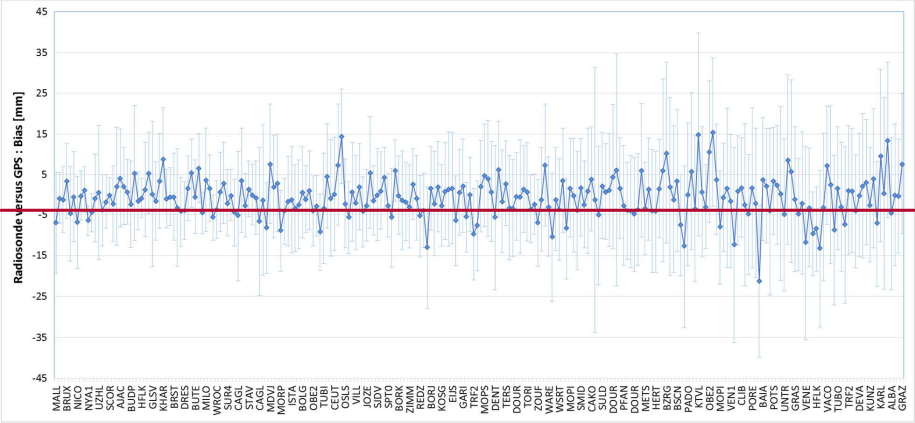
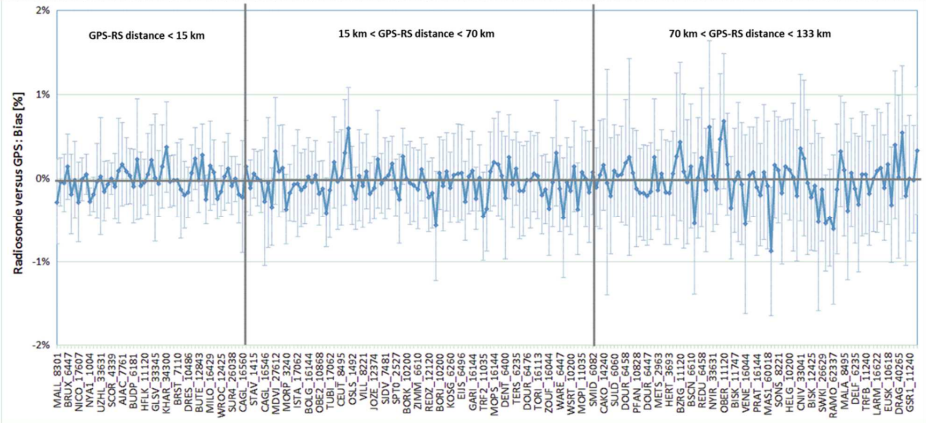


Figure 9 EPN station CAGL (Cagliari, Sardinia Island, Italy). Upper part: Radiosondes (in red) and GPS (in blue) ZTD time series. Lower part differences.

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838 Figure 10 GPS versus Radiosonde Bias. The error bar is the standard deviation. Sites are sorted
839 according to the increasing distances from the nearest Radiosonde launch site. The x-axis
840 reports the GPS station and the Radiosonde code.

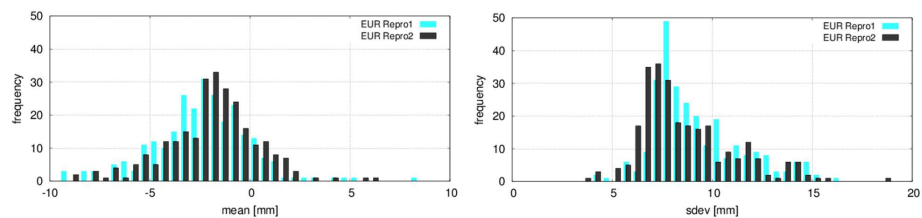
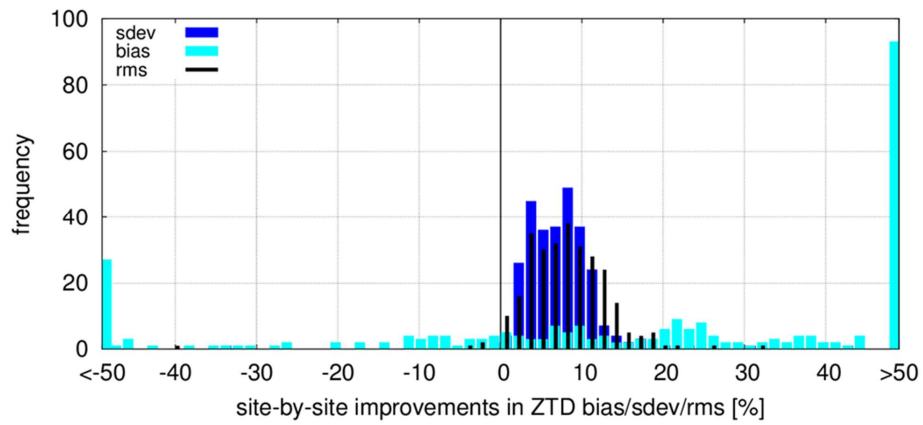


Figure 11: Distributions of station means (left) and standard deviations (right) of EPN Repro1 and Repro2 ZTDs compared to ERA-Interim ZTDs.

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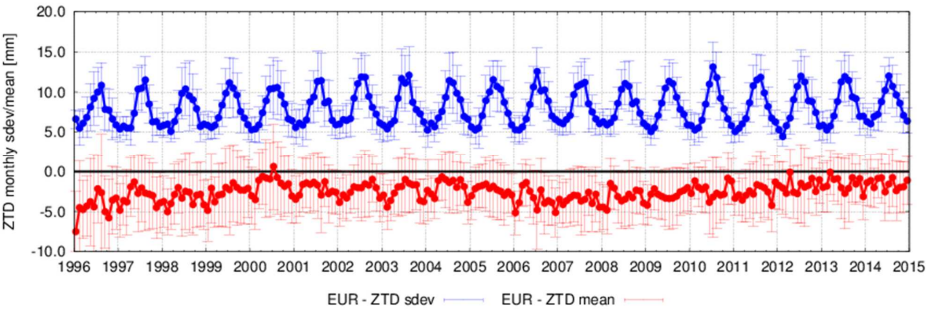


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847 Figure 12: Site-by-site ZTD improvements of EPN Repro2 versus EPN Repro1 compared to ERA-
848 Interim

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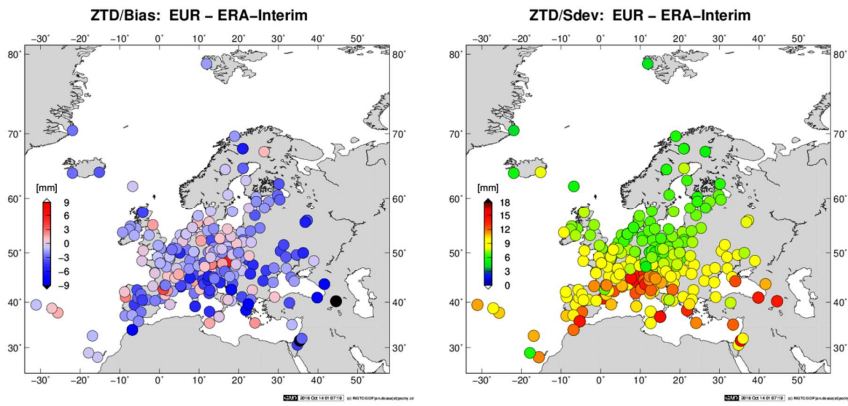
852 Figure 1342: Time series of monthly mean biases (~~upper~~-lower part) and standard deviations (~~lower~~
853 ~~upper~~ part) for ZTD differences of EPN Repro2 and NWM re-analysis. Uncertainties are calculated
854 over all stations.

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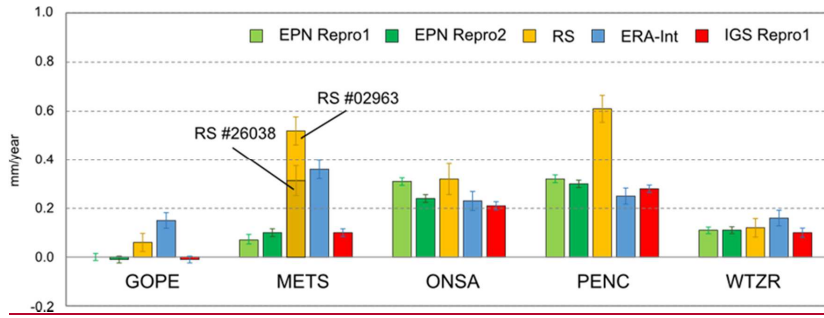
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857 Figure 1443: Geographical display of ZTD biases (left) and standard deviations (right) for EPN
858 Repro2 products compared to the ERA-Interim.

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862 Figure 15: ZTD trend comparisons at five EPN stations. The error bars are the formal error of the
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