

Interactive comment on “Noise characteristics in Zenith Total Delay from homogeneously reprocessed GPS time series” by Anna Klos et al.

Anonymous Referee #1

Received and published: 20 January 2017

This paper investigates the reprocessed ZTD time series of 120 permanent GPS stations spread among different climate zones. The seasonal and diurnal cycles present in the ZTD time series are first studied. But the main point of the paper is then to identify a better noise model for the ZTD time series than the widely used white-noise-only assumption. The authors come to the conclusion that an AR(4) + white noise model has to be preferred and finally discuss the implications of their refined noise model on the uncertainties of the trends of their ZTD series.

While the noise characteristics of GPS-derived tropospheric time series are indeed worthy of investigation, the paper however presents important defects in several methodological and formal aspects. A major revision therefore seems necessary to me. Specific major comments follow. A manuscript annotated with additional minor comments and corrections is also attached to this review.

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A) Why using ZTD series rather than ZWD or IWV series?

At the end of the Introduction (page 3, lines 18-30), the authors recognize that studying ZWD or IWV series rather than ZTD series would be more climatologically meaningful, which is undoubtedly true, especially when focusing on trends. They then give two arguments to justify their choice of nevertheless sticking with ZTD time series:

* “The stochastic properties of the ZWD and ZTD time series are nearly identical” (supported by a single example in the supplementary material).

* “The preferred products for assimilation in NWP models are the ZTD estimates and not the IWV estimates”.

I find the first argument quite questionable. First, even in the only provided example, the ZHD seems to have a comparable power as the ZWD in the monthly to semi-annual frequency band. So it seems likely that removing or not the a priori ZHD from the series (i.e., studying ZWD series rather than ZTD series) would have a noticeable impact on the noise analysis results. Then, what about other stations? Without evidence of the contrary, one could imagine that in some places, the variability of the ZHD may be even higher than that of the ZWD in specific frequency bands, which again would have an impact on the noise analysis results. And apart from the noise analysis itself, the aim of this study, as I understand it, is to eventually provide trends with realistic uncertainties for climate studies. But is there any climatological sense in providing ZTD trends??

I don't think that the authors' second argument holds either, because although ZTD are assimilated in NWP models, they are currently not assimilated in climate models. At present, the long-term noise+trend analysis made by the authors can therefore not be performed on post-assimilation IWV series, but is only possible with “raw” GPS-derived ZWD series, possibly converted to IWV series.

The issues related to the ZWD -> IWV conversion and their potential impacts on the estimation of long-term trends are nicely summarized by the authors and can justify

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working with ZWD series rather than converted IWV series. However, as explained above, I can't see any reason to work with ZTD series rather than ZWD series, and I would encourage the authors to repeat their analyses based on ZWD series.

An alternative would be to provide strong enough evidence than using ZTD series rather than ZWD series has no impact on the noise analysis results *and the estimated trends*, for all stations. But this would require repeating the whole analysis on ZWD series anyway and complicate the paper unnecessarily. So it's probably best to show results for ZWD series only.

B) Homogenization

The procedure used by the authors to homogenize their ZTD time series is not very clearly described. The most disturbing aspect to me is that the authors seem to consider the homogenization of station position time series and ZTD time series as the very same problem (e.g. page 4, lines 41-42; page 5, lines 1-8). And it actually seems that the authors used discontinuities identified in their station position time series to homogenize their ZTD time series (page 5, lines 18-20).

I agree that equipment changes causing position discontinuities are likely to induce ZTD discontinuities as well, although this probably needs to be checked in every single case. On the other hand, I see absolutely no reason why earthquakes would cause discontinuities in ZTD time series. In brief, I don't think that the approach of homogenizing ZTD time series based on discontinuities identified in station position time series is founded.

Another disturbing observation is that many of the estimated discontinuities provided in table S1 appear to be insignificant (or barely significant), even with the very optimistic white-noise-only assumption. This seems to confirm that the homogenization approach used by the authors is not well adapted to their ZTD series.

I would therefore recommend that the authors use a different homogenization ap-

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proach, based on their ZTD (or ZWD) series themselves. It is true that raw ZTD (or ZWD) series are too scattered to allow visual identification of discontinuities, but the authors could use for that purpose the differences between their series and, e.g., ERA-interim series.

Besides the detection of discontinuities, another indispensable step in time series homogenization / modelling is not mentioned at all in the paper: the detection and removal of outliers. How did the authors “clean” their time series? Based on which assumptions and criteria? This information should appear in the paper.

C) Deterministic model

The choice of the authors to estimate periodic signals at 1, 2, 3, 4 cpy and at 1, 2 cpd sounds quite arbitrary, as it is justified with just a figure (Figure 3) showing the PSD of a single station. I think that the least the authors could do would be to show *stacked* periodograms over their 120 stations rather than the periodogram of a single station. This would either confirm that 4 annual harmonics are enough to remove seasonal variations from *all* the series, or might lead the authors to consider higher annual harmonics.

Regarding diurnal variations, the authors justify their choice of considering only two daily harmonics in the caption of Figure 3: “Remaining peaks in high frequencies were found to be non-significant.” A first question that would need to be answered is: which criterion did the authors use to assess the significance of these peaks? But more importantly, does this conclusion hold for all stations? I seriously doubt so when looking at Figure S1, where high spectral peaks really jump out at every daily harmonic from the 1st to the 12th!

The choice of the considered annual and daily harmonics may therefore need to be revised. In any case, it has to be supported by stronger arguments than those presently given in the paper.

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D) Choice of the optimal noise model

Since the main aim of the paper is to identify an “optimal” noise model for ZTD time series, its main defect resides in my opinion in the way this “optimal” noise model is actually selected. It seems that the authors’ initial intention is to explore the ARFIMA model class (page 9, lines 31-33). Why not (although this is a quite ambitious goal)? But then, only a very specific subset of ARFIMA models are investigated and compared, which are even not of successively increasing complexities.

Talking only about the models that include additional white noise (which indeed seems necessary), the authors first consider two of the simplest possible ARFIMA models, namely $AR(1)+WH$ and $PL+WH=ARFIMA(0,d,0)+WH$. But why isn’t the third ARFIMA model with similar complexity (i.e. $MA(1)+WH$) considered? At the next level of complexity, the authors pick out only two specific models: $ARMA(1,1)+WH$ and the so-called “ $ARFIMA(1,0)+WH$ ” which I guess actually refers to $ARFIMA(1,d,0)+WH$ with unknown d . But again, why aren’t the other models of similar complexity (i.e. $AR(2)+WH$, $MA(2)+WH$ and $ARFIMA(0,d,1)+WH$) tested? Last but not least, the authors then completely skip the next level of complexity, pick up a single model at the following level of complexity ($AR(4)+WH$) and conclude, based on a sample of only 5 stations (Table 2) – in which $AR(4)+WH$ is actually the preferred model for only 3 stations! – that $AR(4)+WH$ is “the optimal model for ZTD series”.

I think it’s an understatement to say that this conclusion is not supported by the results, for several reasons. First, if the aim is actually to explore the ARFIMA model class, then **all** ARFIMA models of **successively** increasing complexity levels should have been tested. Then, another methodological mistake is to select the most complex tested model as the “optimal” model, since nothing proves that more complex models (e.g. $AR(5)+WH$) would not have been preferred. The search for the optimal model should actually be made among increasingly complex models, **until the inflection point of the selection criterion (BIC) is reached**.

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If such an exhaustive search of the ARFIMA model class turns out not to be practically feasible, the authors may want to restrict their search for an “optimal” model within a smaller class (e.g. AR models of increasing orders). But even within the AR class, it may turn out that the inflection point of the BIC cannot be reached for computational reasons. If so, then no mention could be made of an “optimal” noise model anymore.

Finally, another obvious reason why it cannot be concluded that AR(4)+WH is “the optimal model for ZTD series” is that in Table 2, it is the preferred model for only 3 stations out of 5! To be fair, and more informative, the authors should present results for their whole set of 120 stations. It would then likely appear that different stations have different preferred noise models, which might be an interesting result in itself. (Maybe the preferred noise model would depend on the climate zone?). But anyway, if a single preferred model needs to be chosen, then this choice should at least be made based on results for all 120 stations.

A last question concerning the noise models tested by the authors is: did they try to consider variable white noise (VW) instead of constant white noise (WH)? Santamaria-Gomez et al. (2011) indeed found VW “significantly superior” to WH when modeling the noise of GPS station position time series.

E) Structure of the paper

Besides the presented results, the organization of the paper would also need to be revised. Different sections are in particular redundant or mixed with each other. More specifically:

* The first two paragraphs on page 3 (lines 1-16; details about GPS reprocessing and homogenization unnecessary in the introduction) should be merged into Sections 2.1 and 2.2. The beginning of the next paragraph (lines 17-20) should similarly be merged into Section 3.1.

* Instead of introducing trivial equations (Eq. 3 to 5), the beginning of Section 2.3

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should rather focus on justifying the chosen deterministic model (cf. comment C). Similarly, instead of defining different well-known noise models, the second part of Section 2.3 should rather introduce in a clear and precise way the approach that will then be followed to test different noised models and eventually select an “optimal” (or preferred) noise model (cf. comment D).

* The first paragraph on page 8 (lines 1-7; justification of the adopted deterministic model) should be revised according to comment C and moved into Section 2.3.

* Most of the results discussed in the rest of Section 3.1 seem to be repetitions of the findings of Jin et al. (2007; 2008). I don't think it would harm the paper to keep a short discussion about the estimated (semi-)annual and (semi-)diurnal signals, as well as Figures 4 to 7 (although they could be moved to the supplementary material). But since this is not the main subject of the paper and no new conclusions are reached compared to the results of Jin et al. (2007; 2008), I think that Section 3.1 could be shortened.

* The beginning of Section 3.2 (page 9, lines 9-37; details about the tested noise models) should be moved into Section 2.3. The rest of Section 2.3 will probably need to be entirely re-written according to comment D.

* Instead of real “Discussion” and “Conclusions”, Sections 4 and 5 basically consist of repetitions of facts stated earlier in the paper and are almost entirely redundant with each other. Those two sections will also likely need to be entirely re-written (and merged into a single section) and should really focus on the main findings of the study, i.e. preferred noise model(s) and consequences for trends and their uncertainties.

F) Language

The paper contains lots of English mistakes, but more importantly, many imprecise and unclear formulations. Some are marked in the attached annotated manuscript. But the paper will nevertheless require a very careful re-reading before being re-submitted.

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Please also note the supplement to this comment:

<http://www.atmos-meas-tech-discuss.net/amt-2016-385/amt-2016-385-RC1-supplement.pdf>

Interactive comment on Atmos. Meas. Tech. Discuss., doi:10.5194/amt-2016-385, 2016.

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