

## **Response to comments of Referee #1**

We thank the referee for his or her thoughtful comments, which we have addressed as follows:

### **Referee comments**

I would like to see a bit more discussion on the temporal and spatial availability of the measurements. Consistent (Zenith-sky and Global-Umkehr) naming conventions would be nice to avoid any confusion. I would also like to see some discussion of the local times that MLS passes over summit and seasonal change in the averaging kernel (if any).

### **Response**

The new version of the manuscript now uses the terms “standard zenith-sky Umkehr method” and “Global-Umkehr method” consistently. Other issues noted in this general comment are discussed below.

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### **Referee comment**

Page 1, line 26: I would like to see a short explanation of what this measurement (the direct sun plus upper hemisphere) is typically used for.

### **Response:**

The following was added to the manuscript:

“Such measurements were started by several groups in the early 1990s to monitor changes in UV radiation at the Earth’s surface. These activities were motivated by concerns that decreases in atmospheric ozone concentrations, which were caused by ozone depleting substances released by man into the atmosphere, could lead to increases in UV radiation with detrimental effects on human health, and terrestrial and aquatic ecosystems (e.g., Bais et al., 2015).”

### **The following reference was added:**

Bais, A. F., McKenzie, R. L., Bernhard, G., Aucamp, P. J., Ilyas, M., Madronich, S., and Tourpali K.: Ozone depletion and climate change: impacts on UV radiation, *Photochem. Photobiol. Sci.*, 14(1), 19-52, 2015.

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### **Referee comments**

Considering that this paper may lead to retrieval of more historical ozone information in addition to what is already available (ozonesondes, Dobson Umkehr, etc.). I would like to see a bit more discussion on the temporal and spatial availability of the measurements.

and

Page 2, line 2 and line 21 and Section 2.2: You mention that there are other sites that have these UV detectors. It would be nice to have some general information about how many potential sites there are, their temporal measurement range, are there any Southern Hemisphere sites, and there many locations where there are not any Umkehr measurements, etc. It is briefly mentioned in the conclusions that there are many sites with time series of greater than 25 years, but this is not mentioned anywhere else.

### **Response**

The majority of instruments that provide global spectral UV irradiance measurements suitable for the Global-Umkehr method are part of the UV monitoring networks mentioned in the introduction. While it is beyond the scope of this manuscript to assess the suitability of each of these systems, we estimate that about 25 instruments meet the accuracy requirements for the Global-Umkehr method and could potentially be utilized. The following was added to the manuscript:

“We estimate that about 25 spectroradiometers that are part of the various UV monitoring networks mentioned earlier provide data of sufficient quality for the Global-Umkehr method. Some of these instruments were established in the early 1990s at locations around the globe, including the Arctic, North America, Hawaii, Europe, New Zealand, Australia, and Antarctica.”

We also added a link to the European UV Database, which also includes quality-controlled spectral UV measurements that are potentially suitable for the Global-Umkehr method.

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### **Referee comment**

Page 3, line 4: Why not use the more recent ozone cross section studies?  
<https://www.atmos-meas-tech.net/7/609/2014/>

### **Response**

We note that Referee 2 had a similar comment.

We are aware that more accurate ozone absorption cross sections than those published by Bass and Paur (1985) are now available and recommended. Nonetheless, we decided to use the Bass and Paur (1985) data because OMI total ozone data are based on B&P. Using a different cross section would have complicated the validation of our results with OMI data. We added the following to the manuscript:

“While more accurate ozone absorption cross sections are now available (Gorshchev et al., 2014; Orphal et al., 2016), we used Bass and Paur (1985) data to facilitate validation with OMI total ozone column measurements, which are also based on Bass and Paur (1985).”

### **The following references were added:**

Gorshchev V., Serdyuchenko A., Weber M., Chegade W., and Burrows J.P.: High spectral resolution ozone absorption cross-sections–Part 1: Measurements, data analysis and comparison with previous measurements around 293K, *Atmos. Meas. Tech.*, 7, 609-624, doi:10.5194/amt-7-609-2014, 2014.

Orphal J., Staehelin J., Tamminen J., Braathen G., De Backer M. R., Bais A., Balis D., Barbe A., Bhartia P. K., Birk M., and Burkholder J. B.: Absorption cross-sections of ozone in the ultraviolet and visible spectral regions: Status report 2015, *J. Mol. Spectrosc.*, 327, 105-121, doi:10.1016/j.jms.2016.07.007, 2016.

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**Referee comment**

Page 4, line 19: You mention on line 14 that a  $\sigma_a$  value of .1 is small and therefore very sensitive to the a priori. However, you go on to say on line 19 that  $\sim .1$  is the standard deviation of the MLS profiles. I feel this needs clarification as you mention that  $\sigma_a$  is the anticipated variability (standard deviation) and therefore using a value higher than .1 (for example .4) means you are expecting a larger variability in the retrieval.

**Response**

As discussed in great detail in the manuscript,  $\sigma_a$  is an important parameter to optimize the solution. At the onset of the study, the optimal value for  $\sigma_a$  was not known, although a value of 0.1 is supported by the standard deviation of the MLS profiles. We therefore performed calculations with two settings, 0.1 and 0.4. We feel that the pros and cons of using either 0.1 or 0.4 are discussed in sufficient detail (in particular in the “Discussion” section), and think that lengthening the discussion further is not necessary. No change to manuscript.

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**Referee comments**

I would also like to see some discussion of the local times that MLS passes over Summit.

and

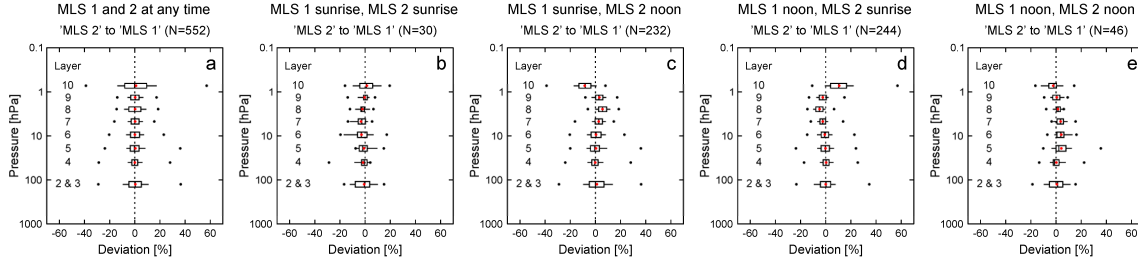
Page 10, line 1: What two times of day are MLS measurements taken at the latitude of Summit? Are there any inconsistencies here, diurnal effects, polarisation?, etc?

**Response**

MLS data that we have downloaded from [http://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP\\_Prof/O3/Summit/](http://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP_Prof/O3/Summit/) are measured either between 5:28 and 6:26 UTC or between 14:11 and 15:10 UTC. These period concur roughly with sunrise and local solar noon at Summit, respectively. There is only one file per day provided by the Aura Validation Data Center, either from the earlier or later time range. There is no obvious difference in the timing between spring and fall. Of note, spectra used for the Global-Umkehr method were measured between 15:00 and 20:00 UTC.

MLS 1 data (i.e., MLS measurements taken before the period of Umkehr observations) and MLS 2 data (i.e., MLS data taken after this period) discussed in the manuscript were not filtered for time-of-day. The difference of MLS 2 and MLS 1 data showed virtually no bias (e.g., Figure 51 of manuscript), but there is some variability, which we attributed to several potential causes, including a real change in the ozone profile from one day to the next, variations in the horizontal distance between the locations of Summit and the MLS pixel from one day to the next, and random errors in MLS data.

Prompted by the referee’s comment, we have now filtered and analyzed MLS data also by time-of-day. Specifically, we have calculated the difference in MLS profiles from one day to the next in dependence of the time-of-day when MLS 1 and MLS 2 measurements take place. Results are shown in the figure below.



Panel a is identical with Figure 5l of the manuscript and shows statistics of the difference of MLS 2 and MLS 1 data irrespective of time-of-day. It can be seen that there is virtually no bias between the two datasets.

Panel b is based on a subset of these data where both MLS 1 and MLS 2 are from the sunrise period. For Panel c, MLS 1 data were from the sunrise and MLS 2 data from the noon period. For Panel d, MLS 1 data were from the noon period and MLS 2 data from the sunrise period. Finally, Panel e shows the difference where both MLS 1 and MLS 2 data were filtered for the noon period.

A comparison of Panels b – e indicates that there is a bias between MLS 1 and MLS 2 measurements depending on whether data from the sunrise or noon periods are used. We did not consider this bias when submitting the original version of the manuscript. This bias agrees qualitatively with the difference of day – night profiles measured independently by several instruments at Mauna Loa, Hawaii (Parrish et al., 2014), and Bern, Switzerland (Studer et al., 2014). Specifically, data from Mauna Loa indicate 2-3% *higher* ozone concentrations during the day for pressure levels between 2 and 10 hPa (~ Umkehr layers 6 – 8) and 5-10% *lower* concentrations during the day for pressure levels between 0.5 and 1 hPa (Umkehr layer 10). At Bern, ozone concentrations between 3 and 10 hPa are highest in the afternoon, exceeding midnight concentrations by 3-5%. Above 2 hPa (~43 km), the pattern reverses with ozone concentrations being lower during the day than at night. Differences observed at Mauna Loa and Bern are by and large consistent with those shown in Panel c above and small differences between the three datasets may be explained by the different latitudes of Summit, Mauna Loa, and Bern.

As a result of these new findings, the manuscript was changed as follows:

- In Section 2, we added:
 

“MLS measurements at Summit take place either between 5:28 and 6:26 UTC (period close to sunrise) or between 14:11 and 15:10 UTC (period close to local solar noon). There is only one data file per day in the NASA archive.”
- The following was added to the Discussion:
 

“Further analysis revealed that the difference between the MLS 1 and MLS 2 datasets depends also on the time when the daily MLS observation takes place. For example, when MLS 2 data are from the observation period close to local solar noon (14:11 to 15:10 UTC) and MLS 1 data are measured close to sunrise (5:28 to 6:26 UTC), MLS 2 data for Layers 7 – 9 are biased high by 3-6% relative to the MLS 1 dataset, while MLS 2 data for Layer 10 are biased low by 8%. This time-of-day dependency and its variation with altitude is by and large consistent with diurnal variations of the ozone profile measured by various instruments at Mauna Loa, Hawaii (Parrish et al., 2014), and by a microwave radiometer at Bern, Switzerland (Studer et al., 2014). This suggests that the

time-of-day effect observed at Summit is caused by actual diurnal changes of the ozone profile rather than potential time-dependent systematic errors in the MLS dataset. ”

**The following references were added:**

- Parrish, A., Boyd, I. S., Nedoluha, G. E., Bhartia, P. K., Frith, S. M., Kramarova, N. A., Connor, B. J., Bodeker, G. E., Froidevaux, L., Shiotani, M., and Sakazaki, T.: Diurnal variations of stratospheric ozone measured by ground-based microwave remote sensing at the Mauna Loa NDACC site: measurement validation and GEOSCCM model comparison, *Atmos. Chem. Phys.*, 14(14), 7,255-7,272, doi:10.5194/acp-14-7255-2014, 2014.
- Studer, S., Hocke, K., Schanz, A., Schmidt, H., and Kämpfer, N.: A climatology of the diurnal variations in stratospheric and mesospheric ozone over Bern, Switzerland, *Atmos. Chem. Phys.*, 14(12), 5,905-5,919, doi:10.5194/acp-14-5905-2014, 2014.
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**Referee comment**

Page 15, Fig. 4: It would be interesting to see if the change in season (thus, the vertical structure of the ozone profile) modifies the structure of the relative averaging kernels, especially, as fall and spring statistics are compared later on in Table 2.

**Response**

As stated in the text (e.g., P13, L18) the relative averaging kernels do not depend much on season. For the sake of simplicity, we therefore decided not to show the RAKs in Figure 3 and 4 at the time of the initial submission. Prompted by the referee’s comment, we have now added the RAKs to the two figures.

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**Referee comment**

Page 15, Fig 4: Also, why are the  $\sigma_a = .4$  plots not shown in this figure? It would be interesting to see if the inversion agrees well in this case when it has more freedom due to a larger a priori covariance. If you have the results, they could also just be mentioned in the text.

**Response**

The effect of changing  $\sigma_a$  from 0.1 to 0.4 is very similar for spring and fall profiles. For sake of brevity, we therefore did not include results for  $\sigma_a = .4$ , and still feel that this is the appropriate decision. This is also supported by the small difference in the statistics for spring and fall shown in Table 2.

We added the following to Sect. 3.1.3:

“The effect of changing  $\sigma_a$  from 0.4 to 0.1 are similar for spring and fall profiles and results for  $\sigma_a = 0.4$  were therefore omitted in Fig. 4.”

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**Referee comment**

At the beginning of the paper, you define Umkehr to refer to the standard zenith sky Umkehr technique and Global-Umkehr to refer to direct sun plus upper hemisphere. However, throughout the text and especially in the discussion you refer to Global-Umkehr as just Umkehr which is confusing. I suggest keeping the naming conventions consistent throughout the text.

## Response

The naming convention was homogenized throughout the manuscript.

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### Technical corrections

Page 1, line 11: Substitute ultraviolet for UV.  
Changed.

Page 1, line 18: The OMI acronym does not need to be included here as it is not repeated in the abstract. It is redefined in the main text.  
“OMI” deleted.

Page 2, line 4: Double closed bracket.  
The second bracket belongs to “(e.g.,” of the preceding line. No change.

Page 7, line 2: Is the AFGL acronym defined (Air Force Geophysics Laboratory)?  
“Air Force Geophysics Laboratory” included in text.

Page 14, line 11: suggest changing identical to virtually identical as there is a small difference of 1 DU as seen in Figure 4.  
“virtually” included.

Page 15, line 7: Confusing sentence, suggest to change: ...they do not allow to assess the Global-Umkehr technique comprehensively. to something like they do not allow the comprehensive assessment of the Global-Umkehr technique.  
Changed as suggested.

Page 5, line 10: Spaces seem to be present between all equations and symbols and full stops, commas. This can be misleading in some instances. For example, Page 5, line 10 may be interpreted as a dot product.  
All equations will be reformatted by AMT before publication according to their guidelines. No change to manuscript.

Table 1. There are spaces on either side of the endashes which are not consistent with endash ranges throughout the text.  
The entire manuscript, including the table, will be reformatted by AMT before publication according to their guidelines. No change to manuscript.

Page 10, line 1: typo - MLS measure(s) thermal... - remove "s"  
Grammar corrected.

Page 10, line 15: space after second open bracket.  
Space removed.

Page 10, line 24: Suggest remove therefore or move to the start of the sentence -  
Therefore,...  
“Therefore” moved to front.

Page 17, line 15: should N be in parenthesis?  
N enclosed in parentheses.

Page 19, line 8: Change Table 2 allows to assess retrievals... to something like Table 2 allows the assessment of retrievals...  
Changed as suggested.

Page 19, lines 12 and 13: change to to between -6 % to 4 % and to between -5 % to 2 %  
“between” inserted.

Page 19, line 18: remove is  
“is” removed.

Page 19, lines 19 and 21: insert a space after the equals sign  
Spaces inserted.

Page 19, line 19: Change to but it is consistent  
“it” included.

Page 19, line 20: remove comma after standard  
comma removed.

Page 20, line 8: Is (/2) meant to be there?  
Yes. This is the way the SBUV instruments are identified by Miyagawa et al., 2014.

Page 20, line 23: change resembles to "resemble"  
Grammar corrected.

Page 22, line 8: change to ...have to be...  
“be” included.

Page 22, line 24: change to ...2–3 % of those... (use an endash?)  
Corrected as suggested.

## Response to comments of Referee #2

We thank the referee for his or her thoughtful comments, which we have addressed as follows:

### Referee comment

1. It is good to provide more details about how to derive a priori profiles from MLS and ozonesonde data. Are MLS data collocated with ozonesonde data around the Summit station? How MLS and ozonesonde data are merged as they cover different altitude ranges? Have other ozone profile climatologies such as McPeters et al. (2007) and McPeters and Labow (2012) been considered?

### Response

MLS data are “overpass” data provided by the Aura Validation Data Center at [https://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP\\_Prof/O3/Summit/](https://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP_Prof/O3/Summit/) as indicated in the manuscript. Data files provide the distance between the locations of Summit and the MLS profile. On average, the distance is 160 km. This was added to the manuscript.

As stated in the manuscript, “*A priori* state vectors  $\mathbf{x}_a$  were constructed by combining balloon sonde profiles for altitudes below 10 km and profiles measured by the Microwave Limb Sounder (MLS) on NASA’s Aura satellite for altitudes above 10 km [...] Profiles for both seasons were constructed by calculating the median of a large number of sonde and MLS profiles measured during the two periods using data from the years 2004 to 2014.” We believe that this description is sufficiently clear to indicate how the profiles were constructed.

We have not considered the ozone profile climatologies such as McPeters et al. (2007) and McPeters and Labow (2012) because we felt that *a priori* profiles constructed specifically for the location at Summit, separately for the spring and fall periods and using only data from the time period of relevance (2004 - 2014) are the most appropriate profiles.

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### Referee comment

2. Instead of using fixed a priori error of 0.1 and 0.4, you mentioned the use of altitude-dependent a priori errors in the discussion (P21 L18), which is likely more appropriate as the ozone variability is relatively small in most of the stratosphere, ~10% based on your analysis, but increases significantly in the lower stratosphere and upper troposphere to ~40%. You can modify Eq 4 to be more generic, allowing for altitude-dependent a priori errors:  $[S_a]_{mn} = \sigma_a^2 * [X_a]_m * \sigma_a^2 * [X_a]_n * \exp(-|m-n|/d)$

### Response

We agree that the altitude-dependence of the ozone variability could be considered when setting up the covariance matrix  $S_a$ . For this reason, we mentioned this possibility in the Discussion as one of the options to optimize the Global-Umkehr method further. However, considering that the results obtained with  $\sigma_a = 0.1$  and 0.4 are fairly similar (see Table 2), we feel that the minor effect does not warrant a recalculation of all results.

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**Referee comment**

3. P5, L8, one of the most important diagnostics is averaging kernels  $A$ , which is described in section 2.4. I suggested moving section 2.4 to in front of L8 as  $d_s$  is typically derived from  $A$ , as the trace of  $A$ . The diagonal elements of  $A$  are the  $d_s$  at each layer.

**Response**

The contents of Sect. 2.4 were moved to the place suggested by the referee. We are aware that there are different methods to calculate  $d_s$ , all resulting in the same value for  $d_s$ . We describe the method suggested by Goering et al. (2005) because this is the method that was actually used in our calculations.

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**Referee comment**

4. P6, Equation 8 is confusing. Looks like  $D_c(\theta(t))$  is not based on actual measurement, but based on the parameterization of clear sky measurement as a function of SZA. You may change “ $D_c(\theta(t))$  is the measurement : ” to “ $D_c(\theta(t))$  is the modeled photodiode measurement at time  $t$  that would be observed during clear skies, parameterized a function of SZA after filtering cloudy measurements.” Also what criteria are used to filter cloudy measurements?

**Response**

The sentence was replaced with:

“ $D_C(\theta(t))$  is the hypothetical clear-sky photodiode measurement at time  $t$ . The function was parameterized as a function of SZA using measurement of the photodiode obtained during clear skies. Clear-sky periods were determined based on temporal variability using the method described by Bernhard et al. (2008).”

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**Referee comment**

5. It is better to switch sections “Retrieval method” and “Measurements” as the section of retrieval method depends on the description of measurements.

**Response**

We prefer to keep the original sequence of the manuscript, which starts with the fundamental equation of the optimal estimation approach (Gauss-Newton method) developed by Rodgers (2000). If we were to move the “Measurement” section to the front, we would also have to move the “Forward Model” section because the retrieval method also depends on the model. We feel that it is better to present the principle of the method first before discussing the various parameters that go into Eq. (1).

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**Referee comment**

6. P6, L18-21, what is the main motivation of interpolating measurements to a common SZA grid that has 8 SZAs other than reducing the computation time. What is the typical number of spectra during the collection period (SZA change form 70 to 90)? Looks like it is much larger than 8, so interpolating it to 8 SZAs only while keeping the same measurement error can reduce the available information content and increase the measurement error. Have retrievals been conducted using the measurements at individual SZAs and compared with retrievals interpolated to 8 common SZAs?

## **Response**

The interpolation of measurements to a common SZA grid is a common procedure for any Umkehr technique. For example, Petropavlovskikh et al. (2000) uses 14 fixed SZA between 60° and 90°. Using a common grid simplifies calculations greatly. Note that our data always have to be interpolated because measurements at 310 and 337 nm are not performed at the same time and are therefore measured at slightly different SZAs. When developing our method, we also tried retrievals with up to eleven fixed SZAs. We found that there is virtually no benefit by increasing the number of SZAs beyond eight that would justify the greater computation time. This is not surprising because the “number of degrees of freedom for signal”  $d_s$  is typically less than 3.1, suggesting that eight SZAs are more than sufficient to characterize the information content provided by the observations.

The number of spectra recorded during the observation time varied between 17 and 52, so there are enough spectra for accurate interpolations. Because we use approximating (smoothing) splines for interpolations, random errors are reduced, so even though retrievals are only based eight SZAs, we take advantage of the much larger number of spectra.

We have not conducted retrievals using the measurements at individual SZAs, but as noted above, results did not change significantly by using more than eight SZAs.

We added the following sentence to the manuscript:

“Tests indicated that retrieval results do not change significantly by adding measurements at additional SZAs.”

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## **Referee comment**

7. P6, L30, why not using more recent ozone cross sections based on the activities of ACSO (Absorption Cross-Sections of Ozone) summarized in Orphal et al. (2016), which recommends that the BP data should not be used. Is this for consistency with the OMI TOC retrieval, which also used the BP data?

## **Response**

Note that Referee 1 had a similar comment.

We are aware that more accurate ozone absorption cross sections than those published by Bass and Paur (1985) are now available and recommended. Nonetheless, we decided to use the Bass and Paur (1985) data because OMI total ozone data are based on B&P. Using a different cross section would have complicated the validation of our results with OMI data. We added the following to the manuscript:

“While more accurate ozone absorption cross sections are now available (Gorshchev et al., 2014; Orphal et al., 2016), we used Bass and Paur (1985) data to facilitate validation with OMI total ozone column measurements, which are also based on Bass and Paur (1985).”

## **The following references were added:**

Gorshchev V., Serdyuchenko A., Weber M., Chehade W., and Burrows J.P.: High spectral resolution ozone absorption cross-sections—Part 1: Measurements, data analysis and comparison with previous measurements around 293K, *Atmos. Meas. Tech.*, 7, 609-624, doi:10.5194/amt-7-609-2014, 2014.

Orphal J., Staehelin J., Tamminen J., Braathen G., De Backer M. R., Bais A., Balis D., Barbe A., Bhartia P. K., Birk M., and Burkholder J. B.: Absorption cross-sections of ozone in the

### Referee comment

8. Are both SDISORT and MYSTIC RTMs based on scalar (rather than vector) radiative transfer models? If so, this is another source of forward model bias. What are the impacts of neglecting polarization (i.e., assuming scalar) on the calculated radiances? Just check if any such analysis has been done for either SIDOSRT and MYSTIC RTM.

### Response

Yes, both SDISORT and MYSTIC were run in scalar mode. We agree with the referee that the MYSTIC results may be biased relative to the “truth” by neglecting polarization (i.e., by not using a vector model). Errors arising from neglecting polarization in radiative transfer calculations have been quantified by Lacis et al. (1998). The authors conclude that errors for radiances can be as large as 10% for a purely Rayleigh scattering atmosphere. However, most of these errors cancel when integrating over viewing angles to calculate global spectral irradiance. Fig. 1 below is reproduced from the top-right panel of Fig. 3 of Lacis et al. (1998) and shows error in irradiance for a Rayleigh atmosphere that result from the omission of polarization.

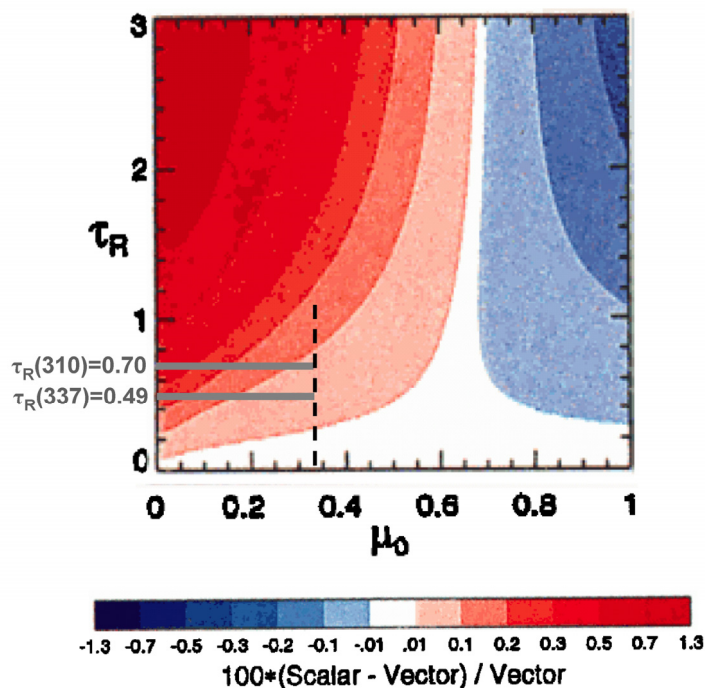


Fig. 1. (Scalar – Vector)/Vector errors for a Rayleigh atmosphere adapted from Fig. 3 of Lacis et al. (1998). Rayleigh optical depths of relevance for Umkehr retrievals are indicated by grey horizontal lines.

Errors are plotted as a function of the cosine of the SZA (abscissa),  $\mu_0$ , and the Rayleigh optical depth,  $\tau_R$ , (ordinate). Relative errors range between  $-1.3$  and  $1.3\%$ . For our Umkehr retrievals, only the difference in errors between measurements at 310 and 337 nm is relevant. For the altitude of Summit,  $\tau_0(310)$  is 0.7 and  $\tau_0(337)$  is 0.49. These optical depths are indicated by grey horizontal lines in the figure below. Further, SZAs range only between  $90^\circ$  and  $70^\circ$ ,

corresponding to  $0 \leq \mu_0 \leq 0.34$  (vertical broken line in the Fig. 1). It is apparent from Fig. 1 that the difference in irradiance errors for 310 and 337 nm is about 0.1% for all SZAs of relevance. According to Lacis et al. (1998), these errors are further reduced by a Lambertian surface, which is the case for Summit (snow surface with albedo of about 0.97).

Based on this analysis, we added the following to the Discussion:

“Finally, the MYSTIC Monte Carlo model, which was used to calculate the correction function  $R(\theta)$  (see Fig. 1b), was run with a scalar radiative transfer solver, which did not take polarization into account. Lacis et al. (1998) calculated that modelling errors for irradiance resulting from the omission of polarization in these calculations can be as large as 1.3% for a Rayleigh atmosphere. However, errors for 310 and 337 nm (i.e., the wavelengths used in the Global-Umkehr method) agree to within 0.1%. We therefore conclude that the omission of polarization is not an important error source in our calculations.”

**Reference:**

Lacis, A.A., Chowdhary, J., Mishchenko, M.I., and Cairns, B.: Modeling errors in diffuse-sky radiation: Vector vs. scalar treatment, *Geophys. Res. Lett.*, 25(2), 135-138, 1998.

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**Referee comment**

9. P10, L12, how is this threshold of 20 DU be determined?

**Response**

We assumed that changes in ozone occur linearly over time, so a 20 DU change over one day (as measured by OMI) translates to about 5 DU change over the course of the ~6 hours required for the Umkehr measurements. At Summit, the total ozone column varies between 250 and 350 DU during the spring period and between 320 and 480 DU during the fall period. So 5 DU make up about 1.6% of the column in spring and 1.3% in fall. Considering that day-to-day variations in the ozone profile occur mostly in the troposphere and lower stratosphere, relative ozone variations in these levels may exceed the percentages calculated for the column by a factor of about 2 to 3, resulting in relative variations of about 4% in these levels. Thus, by choosing a threshold of 20 DU, we ensure that variations in ozone over the course of the Umkehr observations are not a important uncertainty when comparing our results with MLS measurements. However, 20 DU is not a “magic number”, and the criterion could be relaxed for operational processing.

We added the following to the manuscript:

“This criterion ensures that changes in the ozone profile remain below about 4% for all Umkehr layers.”

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**Referee comment**

10. P11, MLS measurements from consecutive days are used to quantify the temporal variation of ozone. It should be noted that the MLS measurements from consecutive days will be measured at different locations, maybe ~100 km apart. So some of the MLS1/2 difference is due to spatial variability. What is the average distance between MLS 1 and 2?

**Response**

We are aware of this problem and the following sentence had therefore been included in the Discussion of the original manuscript:

“However, a portion of the change in the MLS profile from one day to the next may be caused by the relatively poor horizontal resolution of MLS profiles of about 200 km. For example, some variability in the MLS overpass dataset can be attributed to the slightly different geolocation of two consecutive overpass profiles.”

In response to the referee’s comment, we have added the following:

“For example, the average horizontal distance between the locations of Summit and the MLS overpass is 160 km.”

The number was calculated from the “Distance to the station” field provided in the MLS data files.

Of note, in addition to distance, the different viewing geometry of MLS 1 and 2 data and diurnal variations of the ozone profiles in the upper stratosphere are also important sources of variability. This point was raised by Referee #1. Please see our reply in response to the remark of Referee #1.

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**Referee comment**

11. P12, L3-15, a lot of the description can be reduced as this has been described in the figure caption.

**Response**

The description was slightly reduced in length (see annotated manuscript).

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**Referee comment**

12. P21 L20, you may consider using some recent cross sections as suggested in Orphal et al. (2016), and use meteorological data (e.g., temperature profiles) to account for the temperature dependence of the ozone absorption cross section. To reduce the impact of Ring effect, you may consider optimizing not only wavelengths, but also the magnitude of bandpass (currently 2 nm) used to degrade the spectral resolution. In addition, you can also mention the correction of forward model errors due to the neglect of polarization as commented earlier.

**Response**

The following was added:

“More current ozone absorption cross section data could be used (e.g., Orphal et al., 2016) than the Bass and Paur (1985) data implemented in this work and by OMI. If temperature profile data are available, these could be utilized to account for the temperature dependence of the ozone absorption cross section.”

and

“For example, by degrading the spectral resolution (currently set to 2 nm), the impact of the Ring effect could be reduced. Finally, the MYSTIC Monte Carlo model, which was used to calculate the correction function  $R(\theta)$  (see Fig. 1b), was run with a scalar radiative transfer solver, which did not take polarization into account. Lacis et al. (1998) calculated that modelling errors for irradiance resulting from the omission of polarization in these calculations can be as large as 1.3% for a Rayleigh atmosphere. However, errors for 310 and 337 nm (i.e., the wavelengths used in the Global-Umkehr method) agree to within 0.1%. We therefore conclude that the omission of polarization is not an import error source in our calculations.”

**Referee comment**

13. P22 L8, multiple scattering effect is also important for zenith sky measurements. You may say multiple scatterings effects become more important and the sphericity of the viewing geometry should be taken into account.

**Response**

Sentence changed to:

“Compared to the standard zenith-sky Umkehr method, multiple scattering effects become more important when exploiting global irradiance measurements, which also include contributions from photons received from directions close to the horizon. Therefore, the sphericity of the viewing geometry needs to be taken into account.”

---

**Referee comment**

14. P24, L21, The poor sensitivity of the Umkehr method to ozone retrieval at layer 0 & 1 was mentioned here. Because only 2 wavelengths are used in the retrievals, measurements at other wavelengths especially the global irradiance spectrum can be used to improve the retrieval sensitivity in the first few layers as shown in Liu et al. (2005). You may add a few sentences about the possibility of exploring this for future studies.

**Response**

This comments seems to refer to P22, L21.

When we started working on the Global-Umkehr method, we were aware that tropospheric ozone profiles can be retrieved from off-axis radiance measurement by using more than two wavelengths in the UV. In addition to Liu et al. (2005), this method has for example also been used by Tzortziou et al. (2008). When developing our method we therefore explored retrievals with additional UV wavelengths, specifically combinations of E(305)/E(337); E(310)/E(337); E(325)/E(337), see P3, L5 of manuscript. We were hopeful that the tropospheric resolution of the Global-Umkehr method could be improved by including this additional spectral information. Unfortunately, adding these additional wavelength pairs did not lead to a significant improvement. We are therefore not hopeful that tropospheric ozone profiles can be retrieve from global spectral irradiance spectra without adding additional viewing angles, which is not possible for our instrument. We therefore do not think that it is appropriate to raise hopes. No change to manuscript.

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**Technical comments**

1. P2, L20, change “a.s.l” to “a.s.l.”

Period added.

2. The section of “1 Method” should be “2 Method” and “1.1 Retrieval method” should be “2.1 Retrieval method”

Corrected.

3. P2, L25, change “depends” to “depend”

Changed. (Typo was on P4, L25).

4. P5, L17, “and is part of... :”

No change because the sentence is an enumeration with the phrase in question being the second of three phrases.

5. P5, L27, change “wavelengths shifts” to “wavelength shifts”  
Extra “s” removed.

6. P6, L17, this sentence can be grouped to the above paragraph.  
Paragraph break removed.

7. P6, L28, change “result are” to “results are”  
“s” inserted.

8. P7, L6, change “reference” to “references”  
“s” inserted.

9. P7, L24, change “considered” to “considered as”  
“as” inserted.

10. P15, L18, add “,” before “interquartile”  
Comma inserted.

11. P19, L28, change “decreased” to “has decreased” or “decreases”  
“has” inserted (but on P18, L28)

12. P19, L18, change “is varies” to “varies”  
“is” deleted.

13. P19 L26ij~N change to “compared”  
“McElroy and Kerr (1995) compare Umkehr profiles” changed to “McElroy and Kerr (1995)  
compared Umkehr profiles”

14. P20, L1, L2, L5, L6, change to “compared”, “found”, “concluded”, “compared”  
Changed to past tense as suggested.

15. P23 L10, change to “on a weekly basis”  
“a” inserted.

16. P24, L17, add “,” after “Phys.”  
Comma inserted.

17. P24, L18, add “,” after “Res.”  
Comma inserted.

18. P26, last line, use normal font for the journal title.  
Italic formatting removed.

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# Retrieving Vertical Ozone Profiles from Measurements of Global Spectral Irradiance

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**Abstract.** A new method is presented to determine vertical ozone profiles from measurements of spectral global (direct Sun plus upper hemisphere) irradiance in the [ultraviolet](#). The method is similar to the widely used Umkehr technique, which inverts measurements of zenith sky radiance. The procedure was applied to measurements of a high-resolution spectroradiometer installed near the centre of the Greenland ice sheet. Retrieved profiles were validated with balloon sonde observations and ozone profiles from the space-borne Microwave Limb Sounder (MLS). Depending on altitude, the bias between retrieval results presented in this paper and MLS observations ranges between  $-5\%$  and  $+3\%$ . The magnitude of this bias is comparable, if not smaller, to values reported in the literature for the standard Dobson Umkehr method. Total ozone columns (TOCs) calculated from the retrieved profiles agree to within  $0.7\pm 2.0\%$  ( $\pm 1\sigma$ ) with TOCs measured by the Ozone Monitoring Instrument onboard the Aura satellite. The new method is called the “Global-Umkehr” method.

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## 1 Introduction

The “Umkehr” method for determining the vertical distribution of ozone in the atmosphere was first introduced in the 1930s (Götz et al., 1934) and is now routinely applied to measurements of Dobson (e.g., Dütsch, 1959, Mateer and DeLuisi, 1992; Petropavlovskikh et al, 2005) and Brewer (McElroy and Kerr, 1995; Petropavlovskikh et al., 2011) spectrophotometers. The method is typically based on analyzing ratios of zenith-sky radiances at two wavelengths in the ultraviolet (UV), one strongly and one weakly attenuated by ozone, that are measured at solar zenith angles (SZAs) between  $60^\circ$  and  $90^\circ$ . Here we explore a similar optimal statistical approach to obtain vertical ozone information from measurements of spectrally resolved global irradiance, i.e., the irradiance received by a horizontal “cosine” collector from direct Sun and sky (upper hemisphere, from zenith to horizon). Such measurements [were started by several groups in the early 1990s to monitor changes in UV radiation at the Earth’s surface. These activities were motivated by concerns that decreases in atmospheric ozone concentrations, which were caused by ozone depleting substances released by man into the atmosphere, could lead to increases in UV radiation with detrimental effects on human health, and terrestrial and aquatic ecosystems \(e.g., Bais et al.,](#)



1 | [2015](#). [Measurements of global spectral irradiance](#) ~~have been~~ routinely performed by several UV monitoring networks  
2 | sponsored by the NSF (<http://uv.biospherical.com/>), NOAA (<http://www.esrl.noaa.gov/gmd/grad/antuv/>), the Network for  
3 | the Detection of Atmospheric Composition Change (NDACC; <http://www.ndsc.ncep.noaa.gov/>), Environment Canada  
4 | (<http://exp-studies.tor.ec.gc.ca/e/ozone/ozonecanada.htm>), [the European Union](#) (<http://uvdb.fmi.fi/uvdb/>), ~~and~~ others. The  
5 | proposed method has the potential to make these long-term data sets available for assessing vertical ozone information in an  
6 | approach similar to [standard zenith-sky](#) Umkehr retrievals. This is particularly interesting for locations where zenith-sky  
7 | observations are not available.

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8 | Compared to other methods (e.g., Lidar observations (Megie et al., 1977), balloon sondes, and microwave spectrometers  
9 | (Parrish et al., 1992; Waters et al., 2006)), the Umkehr technique provides a relatively inexpensive way of measuring the  
10 | vertical distribution of ozone in the atmosphere. The method is most sensitive to the altitude range of 20 to 45 km and has a  
11 | resolution of about 10 km within this range. For mid-latitude sites, Brewer Umkehr data have a precision of about 15 % in  
12 | the 20- to 40-km region, with larger departures outside this altitude range (McElroy and Kerr, 1995). Umkehr data are  
13 | routinely used for monitoring the drift of sensors measuring the vertical distribution from ozone from space (Newchurch et  
14 | al. 1987; DeLuisi et al, 1994; Miller et al. 1997; Krzyściński et al, 2009; Petropavlovskikh et al., 2005; Petropavlovskikh et al,  
15 | 2011).

16 | The use of measurements of global irradiance instead of zenith-sky radiance for Umkehr retrievals is of no advantage *per se*.  
17 | First, global irradiance includes the direct solar beam, which is attenuated according to Beer's law and therefore does not  
18 | contain information on the profile. Second, global irradiance includes photons received from directions close to the horizon  
19 | and multiple-scattering effects are therefore not negligible. We will show that both challenges can be overcome, resulting in  
20 | profiles of similar accuracy than those inverted from zenith-sky observations. The main advantage of the method presented  
21 | here is that the vertical distribution of ozone can be derived for locations where no other ground-based data exist from which  
22 | profiles could be calculated. The new method is called the "Global-Umkehr" method.

23 | The Global-Umkehr method was tested using data from the NSF UV Monitoring Network (Booth et al., 1994), which has  
24 | been measuring UV and visible global spectral irradiance (290 – 600 nm) at six high-latitude sites since 1990. For this study  
25 | we used data from Summit, Greenland (72° 35' N, 38° 27' W, 3,202 m a.s.l.) where ozone profiles have been routinely  
26 | measured also by balloon sondes. The method can also be applied to measurements at lower latitude sites. [We estimate that  
27 | about 25 spectroradiometers that are part of the various UV monitoring networks mentioned earlier provide data of sufficient  
28 | quality for the Global-Umkehr method. Some of these instruments were established in the early 1990s at locations around the  
29 | globe, including the Arctic, North America, Hawaii, Europe, New Zealand, Australia, and Antarctica.](#)

## 2 Method

### 2.1 Retrieval method

The retrieval method is based on the optimal estimation approach (Gauss-Newton method) developed by Rodgers (2000). In brief, the solution (i.e., the ozone concentration as a function of altitude or pressure) is determined iteratively with the matrix equation:

$$\mathbf{x}_{i+1} = \mathbf{x}_i + \mathbf{S}_{i+1} [\mathbf{K}_i^T \mathbf{S}_\varepsilon^{-1} (\mathbf{y} - \mathbf{F}(\mathbf{x}_i)) - \mathbf{S}_a^{-1} (\mathbf{x}_i - \mathbf{x}_a)] \quad (1)$$

where

$$\mathbf{S}_{i+1} = (\mathbf{S}_a^{-1} + \mathbf{K}_i^T \mathbf{S}_\varepsilon^{-1} \mathbf{K}_i)^{-1}. \quad (2)$$

Eqs. (1) and (2) contain the following parameters:

- $\mathbf{x}_i$  is the “state vector” of iteration  $i$ . In our implementation, it is defined as the average ozone concentration in eleven layers with a layer thickness of 5 km.
- $\mathbf{y}$  is the “measurement vector,” which is composed of ratios of global spectral irradiance  $E(\lambda)$  measured at 310 nm (a wavelength strongly attenuated by ozone) and 337 nm (a wavelength weakly attenuated by ozone) for SZAs ranging between 70° and 90°.
- $\mathbf{F}(\mathbf{x}_i)$  is the solution of the forward model (Sect. 2.3), which simulates the measurements using the state vector as input.
- $\mathbf{K}_i$  is the Jacobian matrix of the partial derivatives of the forward model results and the state vector.
- $\mathbf{S}_\varepsilon$  is the covariance matrix quantifying the uncertainty of the measurements.
- $\mathbf{x}_a$  is the *a priori* state vector. The iteration starts by setting  $\mathbf{x}_0 = \mathbf{x}_a$ .
- $\mathbf{S}_a$  is the covariance matrix pertaining to the *a priori* state vector.
- $\mathbf{S}_{i+1}$  is the solution error covariance matrix at iteration  $i+1$ , which can be exploited to calculate the uncertainty of the retrieval.

We chose 310 nm as the lower wavelength because measurements at this wavelength are at least a factor of 50 larger than the spectroradiometer’s detection limit of 0.001 mW m<sup>-2</sup> nm<sup>-1</sup> for all SZAs and ozone columns of interest. The upper wavelength of 337 nm was chosen because the temperature sensitivity of the ozone absorption cross section has a local minimum at about this wavelength (Bass and Paur, 1985). We also tested other wavelength pairs or combinations of several pairs of wavelengths (e.g., combinations of  $E(305)/E(337)$ ;  $E(310)/E(337)$ ;  $E(325)/E(337)$ ) when developing the method. We found that the use of multiple pairs improved the information content only minimally but increased the computational time considerably.

The SZA range chosen for Umkehr observation is a trade-off between the additional information content resulting from a larger range and the risk that environmental conditions (e.g., clouds, ozone profile) may change substantially over the longer observation time that a larger SZA range requires. During development, we tried several SZA ranges and found that a range

1 of 70° to 90° is a good compromise. This observation is consistent with the conclusion of Petropavlovskikh et al. (2005) that  
 2 information in the upper layers is not degraded by changing the SZA range from 60°–90° to 70°–90° in the standard [zenith-  
 3 sky](#) Umkehr method. We also omitted observations with SZAs larger than 90° because of potential systematic errors in the  
 4 forward model results (Sect. 2.3) when the Sun is below the horizon. At the latitude of Summit, a SZA range of 70° to 90° is  
 5 available in spring between 27 March and 8 May and in fall between 4 August and 15 September.

6 The Jacobian matrix  $\mathbf{K}_i$  has the elements  $[\mathbf{K}_i]_{mn} = [\partial \mathbf{F}(\mathbf{x}_i)]_m / [\partial \mathbf{x}_i]_n$  and is calculated for every iteration step.

7 The measurement error covariance matrix  $\mathbf{S}_\varepsilon$  is a diagonal matrix and is constructed by assuming that elements of the  
 8 measurement vector have an uncertainty of  $\sigma_\varepsilon = 3\%$  and are independent of wavelength and SZA:

$$9 \quad [\mathbf{S}_\varepsilon]_{mn} = \begin{cases} \sigma_\varepsilon^2 [\mathbf{y}]_m [\mathbf{y}]_n & \text{for } m = n \\ 0 & \text{for } m \neq n \end{cases} \quad (3)$$

10 The value of 3% was chosen based on the uncertainty budget of the spectroradiometer installed at Summit (Sect. 2.2). The  
 11 choice of 3% was further supported by analyzing the residuals of the retrieval results  $(\mathbf{y} - \mathbf{F}(\hat{\mathbf{x}}))$  where  $\hat{\mathbf{x}}$  indicates the  
 12 solution state vector after the final iteration.

13 *A priori* state vectors  $\mathbf{x}_a$  were constructed by combining balloon sonde profiles for altitudes below 10 km and profiles  
 14 measured by the Microwave Limb Sounder (MLS) on NASA's Aura satellite for altitudes above 10 km (see Sect. 2.5 for  
 15 additional information on these profiles). Separate *a priori* profiles were used for processing data from spring (27 March – 8  
 16 May) and fall (4 August – 15 September). Profiles for both seasons were constructed by calculating the median of a large  
 17 number of sonde and MLS profiles measured during the two periods using data from the years 2004 to 2014.

18 The covariance matrix pertaining to the *a priori* state vector,  $\mathbf{S}_a$ , was constructed as suggested by Bhartia et al. (2013):

$$19 \quad [\mathbf{S}_a]_{mn} = \sigma_a^2 [\mathbf{x}_a]_m [\mathbf{x}_a]_n \exp(-|m - n|/d). \quad (4)$$

20 The parameter  $\sigma_a$  specifies the anticipated variability of the retrieved profiles about the *a priori* profile and can be  
 21 interpreted as the relative standard deviation of the profiles' distribution. The correlation length  $d$  was set to two, which is  
 22 equivalent to 10 km for our definition of the state vector.

23 When  $\sigma_a$  is set to a small value (e.g., 0.1), the solution of the inversion becomes very sensitive to the *a priori* profile. In  
 24 contrast, when  $\sigma_a$  is set to a large value, the solution is mostly determined by the measurements. Choosing the optimum  
 25 value for  $\sigma_a$  is a trade-off between two competing effects: a large value of  $\sigma_a$  ensures correct inversion result even if the  
 26 true profile deviates greatly from the *a priori* profile. On the other hand, a small value of  $\sigma_a$  reduces the risk that the  
 27 retrieval result is grossly incorrect if measurements are affected by unanticipated errors.

28 We calculated profiles for  $\sigma_a = 0.1$  and 0.4, and compare the results in Sect. 3. The value of  $\sigma_a = 0.1$  was chosen by  
 29 analyzing the variability of MLS profiles relative to the spring and fall *a priori* profiles introduced above. For Umkehr layers  
 30 3 through 7 (the layers for which the Umkehr method is most sensitive) the relative standard deviations calculated from the

1 MLS profiles vary between 0.05 and 0.15; averaged over layers 3 though 7, the relative standard deviation is 0.12 for the  
 2 spring and 0.09 for the fall period. The value of  $\sigma_a = 0.4$  was chosen as the other extreme. With this value, the *a priori*  
 3 profile has little influence on the inversion result and the effect of errors in the measurement vector  $\mathbf{y}$  becomes more  
 4 prominent. Of note, the retrieval results depend technically on the ratio  $\gamma \equiv (\sigma_\varepsilon / \sigma_a)^2$  as opposed to  $\sigma_a$  (Bhartia et al.,  
 5 2013). Because the measurement uncertainty  $\sigma_\varepsilon$  is well defined, we discuss the results using  $\sigma_a$  instead of  $\gamma$ .

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6 The iteration is repeated until two conditions are met: first, the norms of  $\mathbf{x}_{i+1}$  and  $\mathbf{x}_i$  must differ by less than 0.5 %, and  
 7 second, the values of consecutive results of the cost function  $\Psi(\mathbf{x})$  must agree to within 5.0 %, where

$$8 \quad \Psi(\mathbf{x}) = (\mathbf{y} - f(\mathbf{x}))^T \mathbf{S}_\varepsilon^{-1} (\mathbf{y} - f(\mathbf{x})) + (\mathbf{x}_a - \mathbf{x})^T \mathbf{S}_a^{-1} (\mathbf{x}_a - \mathbf{x}). \quad (5)$$

9 These convergence criteria were adopted from Tzortziou et al. (2008). We confirmed that these criteria are also appropriate  
 10 for our application by analyzing changes of the two convergence metrics as a function of iteration  $i$ . The two criteria are  
 11 always met in two to four iterations.

12 The uncertainty  $e_m$  of each element of the solution's state vector was calculated according to Goering et al. (2005) from the  
 13 diagonal elements of the solution error covariance matrix and the solution state vector:

$$14 \quad e_m = \frac{\sqrt{[\hat{\mathbf{S}}]_{mm}}}{[\hat{\mathbf{x}}]_m}, \quad (6)$$

15 where the caret (^) above the symbols  $\mathbf{x}$  and  $\mathbf{S}$  indicates the values of  $\mathbf{x}_i$  and  $\mathbf{S}_i$  of the final iteration.

16 The performance of an inversion based on the optimal estimation approach is often assessed with the averaging kernel matrix  
 17  $\mathbf{A} \equiv \hat{\mathbf{S}} \mathbf{K}_i^T \mathbf{S}_\varepsilon^{-1} \mathbf{K}_i$ , which quantifies the sensitivity of the retrieved state  $\hat{\mathbf{x}}$  to perturbations in the true state  $\mathbf{x}$ . For an ideal  
 18 observing system,  $\mathbf{A}$  is the identity matrix. In reality, the rows of the averaging kernel matrix are peaked with a finite width,  
 19 which can be regarded as a measure of the vertical resolution of the retrieved profile. Similarity to the identity matrix  
 20 indicates that the retrieval solution has been determined using the observations rather than the *a priori* information, and as  
 21 such, the retrieval has provided new information about the actual state.

22 Elements of  $\mathbf{A}$  can have large positive and negative values for layers where the ozone concentration is close to zero. To  
 23 prevent this predicament, Bhartia et al. (2013) suggested to illustrate the performance of the algorithm with “relative  
 24 averaging kernels” (RAK or  $\mathbf{A}_R$ ), which quantify the relative change of the retrieved state  $\hat{\mathbf{x}}$  to the perturbations in the true  
 25 state  $\mathbf{x}$ .  $\mathbf{A}_R$  is defined by

$$26 \quad [\mathbf{A}_R]_{mn} = [\mathbf{A}]_{mn} \frac{[\hat{\mathbf{x}}]_n}{[\hat{\mathbf{x}}]_m}. \quad (7)$$

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27 The optimal estimation technique provides several diagnostics [in addition to the averaging kernels](#) about the quality of the  
 28 retrieved profile. The diagnostic used here is  $d_s$ , which expresses the “number of degrees of freedom for signal” and

1 indicates the number of useful independent observations in the measurement vector  $\mathbf{y}$ .  $d_s$  was calculated as suggested by  
2 Rodgers (2000) and Goering et al. (2005) from the singular values  $\lambda_m$  of the “error-weighted weighting function matrix”

3  $\tilde{\mathbf{K}} \equiv \mathbf{S}_\varepsilon^{-1/2} \mathbf{K} \mathbf{S}_a^{-1/2}$  via:

4 
$$d_s = \sum_m \frac{\lambda_m^2}{m + \lambda_m^2}. \quad (8)$$

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5 The diagnostic  $d_s$  depends on  $\mathbf{S}_a$  and in turn on  $\sigma_a$ . We will show in Sect. 3 that  $d_s$  is considerably smaller for profiles  
6 calculated with  $\sigma_a = 0.1$  than 0.4.

## 7 2.2 Measurements

8 The method was tested using measurements of global spectral irradiance performed at Summit with a SUV-150B  
9 spectroradiometer designed by Biospherical Instruments Inc. The instrument has a spectral resolution of 0.63 nm, is part of  
10 the U.S. National Science Foundation’s Arctic Observing Network, and contributes data to NDACC. The expanded  
11 uncertainty (coverage factor  $k = 2$ , equivalent to uncertainties at the  $2\sigma$ -level or a confidence interval of 95 %) of global  
12 spectral irradiance measurements for wavelengths between 310 and 337 nm is between 6.0 and 6.7 %. More information on  
13 the instrument is provided by Bernhard et al. (2008) and a detailed uncertainty budget is available at  
14 [http://uv.biospherical.com/Version2/Uncertainty\\_SUV150B.pdf](http://uv.biospherical.com/Version2/Uncertainty_SUV150B.pdf).

15 Data used in this paper are from the “Version 2” data edition (Bernhard et al., 2004) and are corrected for the cosine error of  
16 the instrument’s entrance optics. The wavelength mapping was determined with a Fraunhofer-line correlation method and  
17 the wavelength uncertainty ( $k = 2$ ) of processed data is 0.02 nm. Measured spectra and spectra calculated with the forward  
18 model (Sect. 2.3) were convolved with a triangular function of 2 nm bandwidth to further reduce uncertainties resulting from  
19 potential wavelength shifts between measured and modelled spectra.

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20 The SUV-150B is a scanning instrument, which measures each wavelength at a different time. The time required to scan  
21 between 310 and 340 nm is about 140 seconds. Changing cloud condition will therefore affect the ratio of measurements at  
22 these wavelengths, and in turn the accuracy of the retrieval result. The effect of clouds on the ratio of  $E(310)/E(337)$  can be  
23 reduced using measurements of a filtered photodiode, which is illuminated via a beam splitter located between the entrance  
24 optics and monochromator of the SUV-150B system. The sensitivity of the diode is centred at 330 nm and measurements are  
25 performed continuously during the recording of spectra. Because attenuation of thin clouds is fairly uniform in the 310 to  
26 337 nm range (Seckmeyer et al., 1996), measurements of the photodiode can be used to correct for variable cloud  
27 attenuation. Specifically, spectral measurements at  $\lambda = 310$  nm or  $\lambda = 337$  nm are multiplied with a correction factor  
28  $C(\lambda, t)$ , defined as:

29 
$$C(\lambda, t) = \frac{D_C(\theta(t))}{D(t)}, \quad (9)$$

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1 where  $t$  is the time of the spectral measurement,  $\theta(t)$  is the SZA at time  $t$ ,  $D(t)$  is the measurement of the photodiode at  
2 time  $t$ .  $D_C(\theta(t))$  is the hypothetical clear-sky photodiode measurement at time  $t$ . The function was parameterized as a  
3 function of SZA using measurement of the photodiode obtained during clear skies. Clear-sky periods were determined based  
4 on temporal variability using the method described by Bernhard et al. (2008). The correction takes into account that the SZA  
5 changes between measurements at 310 and 337 nm. Of note, this technique cannot be applied in the presence of optical thick  
6 clouds which enhance ozone absorption of tropospheric ozone due to path length enhancement (Mayer et al., 1998). This  
7 restriction does not apply to Summit where clouds are always optically thin (Bernhard et al., 2008). Measurement vectors  
8 were inverted both with and without the cloud correction and results are compared in Sect. 3.2.  
9 Spectral irradiances at 310 and 337 nm were calculated for all spectra measured during a given period of Umkehr  
10 observations and interpolated to a common SZA grid (70, 75, 80, 85, 87, 88, 89, and 90°) using an approximating  
11 (smoothing) spline. Compared to an interpolating spline, an approximating spline has the advantage to reduce noise in the  
12 measurement vector further. Tests indicated that retrieval results do not change significantly by adding measurements at  
13 additional SZAs.  
14 The measurement vector is only constructed from spectra measured in the afternoon (between 15:00 and 20:00 UTC)  
15 because solar measurements have gaps in the morning when the system performs diagnostics scans with internal lamps  
16 (wavelength and irradiance standards).

### 17 2.3 Forward model

18 Forward modelling was performed with Version 1.01 of the pseudospherical discrete ordinate (SDISORT) radiative transfer  
19 solver of the UVSPEC/libRadtran model (Mayer and Kylling, 2005). The number of streams was set to 12. The model's  
20 results are spectra of global irradiance. Model input parameters include the extraterrestrial spectrum as defined by Bernhard  
21 et al. (2004) and available at [http://uv.biospherical.com/Version2/Paper/2004JD004937-ETS\\_GUEYMARD.txt](http://uv.biospherical.com/Version2/Paper/2004JD004937-ETS_GUEYMARD.txt); surface  
22 albedo; atmospheric pressure; and the ozone absorption cross section (Bass and Paur, 1985). While more accurate ozone  
23 absorption cross sections are now available (Gorshchev et al., 2014; Orphal et al., 2016), we used Bass and Paur (1985) data  
24 to facilitate validation with OMI total ozone column measurements, which are also based on Bass and Paur (1985). The  
25 surface albedo at Summit was set to 0.97 in good agreement with recent measurements (Carmagnola et al., 2013). Aerosol  
26 optical depth was set to stratospheric background conditions. Atmospheric pressure and profiles of gases other than ozone  
27 ( $O_2$ ,  $H_2O$ ,  $CO_2$ , and  $NO_2$ ) were taken from the [Air Force Geophysics Laboratory \(AFGL\)](#) atmospheric constituent profile for  
28 subarctic summer (Anderson et al., 1986), which defines the atmosphere at 51 levels. The vertical distribution of ozone in  
29 this standard profile was replaced with the profile defined by the state vector  $\mathbf{x}_i$  and updated in every iteration.  
30 The SDISORT solver has been successfully validated using data of the NSF UV Monitoring Network (e.g., Bernhard et al.,  
31 2004, 2008) and for a large range of conditions at other sites (e.g., Mayer and Kylling, 2005, and references therein).  
32 However to the best of our knowledge, a rigorous validation for the large SZAs required for Umkehr retrievals has not been

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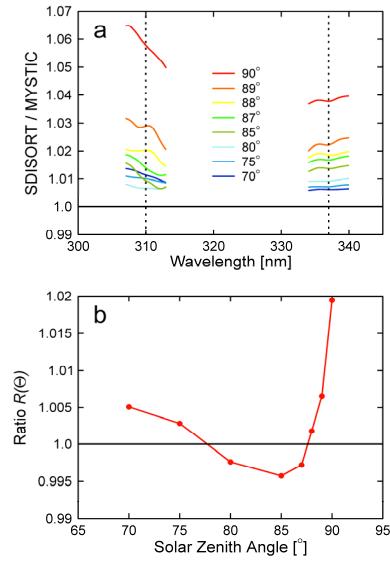
1 conducted. The pseudospherical approximation used by SDISORT correctly describes the attenuation of the direct beam in  
2 spherical geometry but the diffuse radiance is computed in plane-parallel geometry (Mayer et al., 2015). This approximation  
3 can lead to significant errors at large SZAs (Petropavlovskikh et al., 2000; Emde and Mayer, 2007). To quantify these errors  
4 for our application, we have compared spectra of global irradiance calculated with SDISORT with the spherical solver of the  
5 MYSTIC (Monte Carlo code for the phYSically correct Tracing of photons In Cloudy atmospheres) model, which fully  
6 solves the spherical geometry without any approximations (Mayer, 2009). Both models were run with the same set of input  
7 parameters (AFGL subarctic summer with *a priori* ozone profile for spring at Summit) for wavelengths between 307 and  
8 313 nm and between 334 and 340 nm in 0.5 nm steps. The MYSTIC model was run with 84 million photons per wavelength  
9 and per SZA, resulting in photon noise of less than 0.5 % at SZA=90° (worst case). Resulting spectra of both models were  
10 convolved with a triangular function of 2 nm bandwidth to further reduce noise and to be consistent with the method used in  
11 the Umkehr code.

12 Fig. 1a shows the ratio of SDISORT and MYSTIC spectra calculated for the eight SZAs used in our [implementation of the](#)  
13 [Global-Umkehr method](#). SDISORT overestimates spectral irradiances relative to MYSTIC at all wavelengths and SZAs. For  
14 SZA  $\leq 88^\circ$ , the bias is less than 2 % but increases to up to 6.5 % for SZA = 90°. For the Umkehr retrieval, only the ratio

15  $q(\theta) \equiv \frac{E(310, \theta)}{E(337, \theta)}$  is important where  $\theta$  indicates again the SZA. The ratio  $R(\theta) \equiv \frac{q_{SDISORT}(\theta)}{q_{MYSTIC}(\theta)}$  resulting from calculating

16  $q(\theta)$  with SDISORT and MYSTIC is shown in Fig. 1b.  $R(\theta)$  ranges between 0.998 at 80° to 1.019 at 90°. Calculations  
17 with the MYSTIC model can be considered [as](#) the most accurate results attainable because the Monte Carlo code does not  
18 use approximations. The model has been validated by comparison to other spherical radiative transfer models and by  
19 simulating the radiance distribution of the sky during a total solar eclipse. For such calculations, a spherical solver without  
20 approximations is required because light entering the atmosphere more than 1000 km away may impact the radiance in the  
21 centre of the umbral shadow (Emde and Mayer, 2007).

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2 Fig. 1. Comparison of results calculated with the SDISORT and MYSTIC  
 3 spectra calculated for eight SZAs (see legend). (b) Ratio  $R(\theta)$ . See text for definition.

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5 Relative to MYSTIC, SDISORT overestimates  $q(\theta)$  for SZA larger than 88°. In our Umkehr code, we scale the results of  
 6 the forward model with  $1/R(\theta)$  to account for the bias of the SDISORT model. Note that the MYSTIC model is too slow to  
 7 be used for Umkehr retrievals: the calculation of the eight spectra used for Fig. 1a required a run time of over three days.

8 The forward model requires that the vertical structure of the atmosphere is defined as a function of altitude. The association  
 9 between altitude and pressure is defined in the AFGL profile and this relationship may differ from the actual pressure profile  
 10 at the time of Umkehr observation. Because our measurements do not allow to reconstruct the pressure profile, we report all  
 11 ozone profiles as a function of pressure, and compare the retrieved profile with sonde and MLS profiles, which are also  
 12 provided as a function of pressure. The standard [zenith-sky](#) Umkehr technique (Petropavlovskikh et al., 2005) uses a similar  
 13 approach. Table 1 provides altitude and pressure ranges for each Umkehr Layer. Note that Layer 0 starts at the elevation of  
 14 Summit (3,202 m).



1 Table 1. Assignment of Umkehr Layers.

Umkehr Layer	Altitude range forward model [km]	Pressure range [hPa]
10	50.0 – 55.0	0.987 – 0.537
9	45.0 – 50.0	1.82 – 0.987
8	40.0 – 45.0	3.40 – 1.82
7	35.0 – 40.0	6.61 – 3.40
6	30.0 – 35.0	13.4 – 6.61
5	25.0 – 30.0	27.8 – 13.4
4	20.0 – 25.0	59.0 – 27.8
3	15.0 – 20.0	126.0 – 59.0
2	10.0 – 15.0	267.7 – 126.0
1	5.0 – 10.0	541.0 – 267.7
0	3.202 – 5.0	664 – 541

2

3 **2.4 Validation method**

4 The retrieved Umkehr profiles were validated using ozone profiles measured at Summit with balloon sondes by  
 5 NOAA/GMD (Oltmans et al., 2010) and ozone profiles provided by MLS on Aura. Sondes are typically launched between  
 6 12:00 and 20:00 UTC. MLS measures thermal emissions from rotational lines of ozone through the limb of the atmosphere.  
 7 Ozone measurements have a vertical range of 12–73 km with a vertical resolution of 2–3 km below 65 km. The horizontal  
 8 resolution is about 200 km and the accuracy is about 5–10 % between 16 and 60 km (Froidevaux et al., 2008). [The average](#)  
 9 [horizontal distance between the locations of Summit and MLS data is 160 km.](#) Sonde and MLS profiles were downloaded  
 10 from <ftp://ftp.cmdl.noaa.gov/ozwv/Ozonesonde/Summit,%20Greenland/> and  
 11 [http://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP\\_Prof/O3/Summit/](http://avdc.gsfc.nasa.gov/pub/data/satellite/Aura/MLS/V04/L2GPOVP_Prof/O3/Summit/), respectively. Sonde profiles are  
 12 only available for 2 to 4 days per month whereas MLS profiles are available on a daily basis. [MLS measurements at Summit](#)  
 13 [take place either between 5:28 and 6:26 UTC or between 14:11 and 15:10 UTC. There is only one data file per day in the](#)  
 14 [NASA archive.](#)

15 The total ozone column (TOC) was calculated from the retrieved Umkehr profiles and compared with measurements of the  
 16 Ozone Monitoring Instrument (OMI) on board NASA’s Aura spacecraft. OMI overpass data were downloaded from  
 17 <http://avdc.gsfc.nasa.gov/index.php?site=1593048672&id=28>. OMI data use the Bass and Paur (1985) ozone absorption  
 18 cross section (pers. comm., David Haffner, NASA), like the forward model.

19 Good validation results can only be expected if the actual ozone profile does not change over the period of Umkehr  
 20 observations. We therefore only considered periods where the TOC measured by OMI did not change by more than 20 DU

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1 | between 15:00 UTC on the day of the comparison and the first observation on the following day. [This criterion ensures that](#)  
2 | [changes in the ozone profile remain below about 4% for all Umkehr layers.](#) Retrieved Umkehr profiles were compared with  
3 | the sonde profile measured on the same day (if available) and with the MLS profiles measured on this day (labelled “MLS 1”  
4 | in the following) as well as the next day (labelled “MLS 2”).

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### 5 | 3 Results

6 | We first show retrieval results for three sample days with greatly different conditions and compare these results with profiles  
7 | measured by balloon sondes and MLS (Sect. 3.1). We then discuss in Sect. 3.2 statistics for all profiles that were retrieved  
8 | under sufficiently stable conditions (variation in total ozone of less than  $\pm 20$  DU).

### 9 | 3.1 Comparison with balloon sonde and MLS profiles – sample profiles

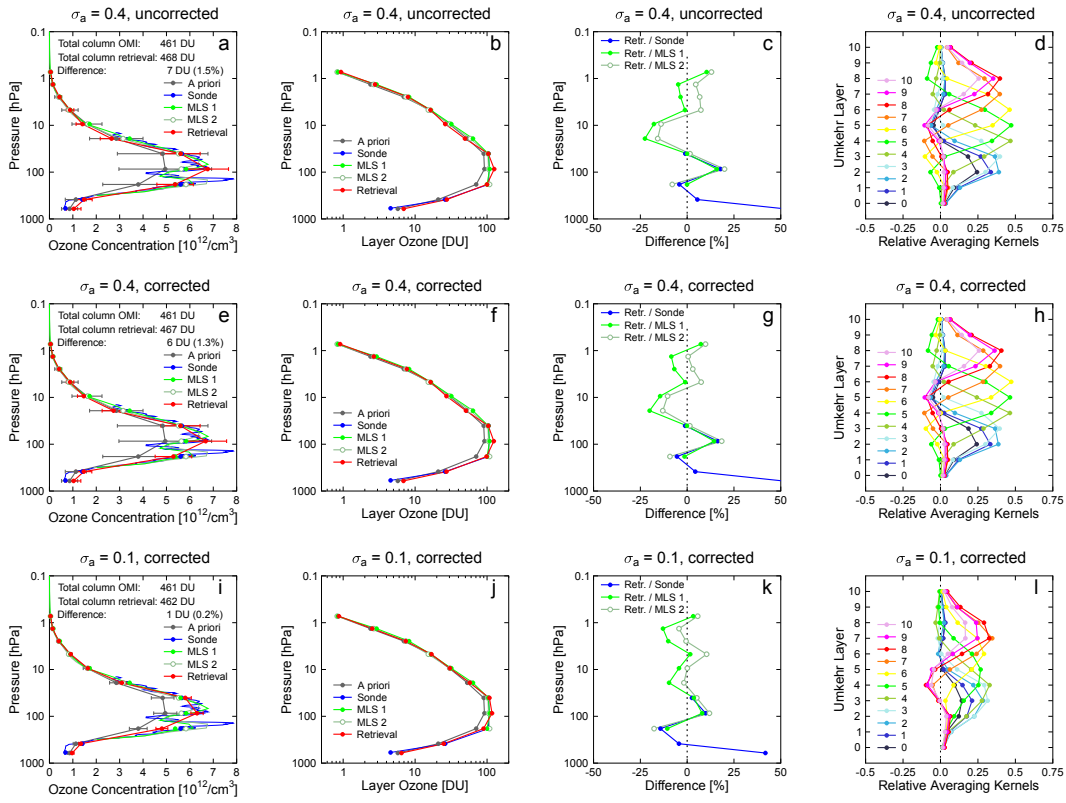
#### 10 | 3.1.1 Validation for 19 April 2014

11 | Fig. 2 compares the retrieved ozone profile for 19 April 2014 with the *a priori*, balloon sonde and MLS profiles. OMI  
12 | measured a TOC of 461 DU on this day, which was the third highest TOC of the dataset and the highest TOC of days when  
13 | balloon sonde data were available. [Therefore, the profile represents one of the highest departures from the spring \*a priori\*](#)  
14 | profile.

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3 Fig. 2. Validation of ozone profile retrieved for 19 April 2014. Top row: results for  $\sigma_a = 0.4$  and uncorrected forward  
 4 model. Centre row: results of  $\sigma_a = 0.4$  and corrected forward model. Bottom row:  $\sigma_a = 0.1$ , and corrected forward model.  
 5 1<sup>st</sup> column: ozone concentration as a function of pressure for *a priori* profile (grey), balloon sonde profile (blue), MLS  
 6 profile for day of retrieval (MLS 1, dark green), MLS profile of the following day (MLS 2, light green), and retrieved profile  
 7 (red). Solid or open circles indicate for each dataset ozone concentrations averaged over each of the eleven Umkehr layers  
 8 defined in Table 1. Grey error bars indicate the diagonal elements of  $S_a$ . Red error bars indicate the uncertainty of the  
 9 retrieval  $e_m$ . TOCs measured by OMI and calculated from the retrieved profile are indicated in the legend. 2<sup>nd</sup> column: layer  
 10 ozone as a function of pressure for *a priori* profile, balloon sonde profile, MLS profile for day of retrieval, MLS profile of  
 11 the following day, and retrieved profile. 3<sup>rd</sup> column: difference between the retrieval and sonde, MLS 1 and MLS 2  
 12 averaged over each Umkehr layer. 4<sup>th</sup> column: relative averaging kernels.

1 Results are shown for three sets of retrieval parameters: (1)  $\sigma_a = 0.4$ , forward model not corrected (top row of Fig. 2); (2)  
2  $\sigma_a = 0.4$ , forward model corrected by scaling with  $1/R(\theta)$  (centre row of Fig. 2); and (3)  $\sigma_a = 0.1$ , forward model  
3 corrected (bottom row of Fig. 2). For each set of parameters, we show profiles of ozone concentrations (1<sup>st</sup> column of Fig.  
4 2), layer ozone (2<sup>nd</sup> column of Fig. 2), the difference between the retrieved profile and the profiles measured by sondes and  
5 MLS (3<sup>rd</sup> column of Fig. 2), and the relative averaging kernels (RAKs) of the retrieval (4<sup>th</sup> column of Fig. 2).

6 Layer ozone (Fig. 2b, f, and j) was calculated by integrating average ozone concentrations of each Umkehr layers over  
7 height. Note that ozone concentrations (Fig. 2a, e, and i) are plotted on a linear scale to highlight differences in the  
8 troposphere and lower stratosphere, while layer ozone (Fig. 2b, f, and j) is plotted on a logarithmic scale to better distinguish  
9 differences in the upper stratosphere.

10 Fig. 2c, g, and k show differences of the average ozone concentrations for the 11 Umkehr layers. Two MLS datasets are  
11 considered. The dataset labelled “MLS 1” is from the same day as the retrieval while the dataset labelled “MLS 2” is from  
12 the following day.

13 When plotting ozone concentrations on a linear scale (Fig. 2a, e, i), results for the three sets of parameters look similar. As  
14 expected, the resolution of the retrieval is not sufficient to capture the large fluctuation in the ozone concentrations between  
15 about 100 and 300 hPa indicated by sonde and MLS measurements. Furthermore, the retrieved profiles overestimate the  
16 ozone concentration at the peak of the profile at about 100 hPa and underestimates the profile in the 7 to 28 hPa range  
17 (Layers 5 and 6). The difference of  $-22.5\%$  between the retrieval and MLS 1 seen in Fig. 2c for Layer 5 is one of the largest  
18 negative biases of all profiles processed. This large bias may partially be caused by errors in the measurement vector due to  
19 clouds (The photodiode used for cloud correction was not available on this day). The large deviation for Layer 0 of  $52\%$   
20 is not surprising considering that this layer is only 1.8 km thick and the sensitivity of the Umkehr method to ozone  
21 concentrations close to the surface is poor.

22 The bias of the retrieval becomes smaller when the forward model is corrected for the systematic error resulting from the  
23 pseudospherical approximation (compare Fig. 2c and Fig. 2g), indicating that the correction is appropriate.

24 The smallest difference between the retrieval on one hand and sonde and MLS measurements on the other is observed for  
25  $\sigma_a = 0.1$  (Fig. 2k). This suggests that a relatively small value for  $\sigma_a$  is advantageous even though the sample profile  
26 deviates considerably from the *a priori* profile. For Layers 5 to 9, the magnitude of the bias is comparable in magnitude to  
27 the difference between the two MLS profiles, suggesting that a portion of the bias could be due to changes in the ozone  
28 profile occurring during the period of Umkehr observations.

29 When  $\sigma_a$  is set to 0.4, the RAKs of Layers 3 to 7 peak at the correct layer and drop to zero within two layers, suggesting  
30 that ozone concentrations in this altitude range can be well resolved (Fig. 2d, h). In contrast, RAKs for layers 0, 1, and 2 are  
31 similar and peak at about the same altitude. Hence, ozone concentrations in these layers cannot be separated well. The  
32 altitude resolution of the standard [zenith-sky](#) Umkehr method is also poor in these layers, and results for layers 0 and 1 are  
33 typically combined when reporting data. RAKs for layers 8 – 10 peak at the same altitude, indicating that ozone

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1 concentrations above the 3 hPa level (about 45 km) cannot be resolved and the retrieval is predominantly driven by the *a*  
2 *priori* profile. This is not surprising considering the small ozone concentrations in these layers. Also the traditional [zenith-](#)  
3 [sky](#) Umkehr method has little sensitivity at these altitudes.  
4 When  $\sigma_a$  is set to 0.1, the RAKs become rather broad (Fig. 2l). The solution is therefore more determined by the *a priori*  
5 profile than the observations. The reduced importance of the measurements is also reflected in the value of  $d_s$  :  $d_s$  is 3.02  
6 for  $\sigma_a = 0.4$  and 2.15 for  $\sigma_a = 0.1$ .  
7 TOCs calculated from the retrieved profiles agree well with the OMI measurements and depend only little on the choice of  
8 retrieval parameters: absolute and relative biases are 7 DU (1.5 %) for parameter set (1), 6 DU (1.3 %) for set (2), and 1 DU  
9 (0.2 %) for set (3).

### 10 3.1.2 Comparison for 11 April 2007

11 Fig. 3 shows results for 11 April 2007. On this day, ozone concentrations measured by sonde and MLS were consistently  
12 below the *a priori* profile between 5 and 100 hPa, but between 100 and 300 hPa, the actual profile exceeded the *a priori*. Fig.  
13 3a – [d](#) show results calculated with  $\sigma_a = 0.4$  while calculations used for [Fig. 3e – h](#) used  $\sigma_a = 0.1$ . The forward model was  
14 corrected by scaling with  $1/R(\theta)$  in both cases. Note that the MLS 1 and MLS 2 datasets are almost identical, indicating that  
15 the actual ozone profile was constant over the observation period. RAKs are very similar to those for 19 April 2014  
16 ([Compare Fig. 2h with Fig. 3d and Fig. 2l with Fig. 3h](#)).  
17 For both settings of  $\sigma_a$ , the retrieved profile is narrower than the *a priori* profile and matches the MLS profile almost  
18 ideally for Layers 3 – 9. This is an example that the retrieval result is not simply the *a priori* profile scaled with a constant  
19 factor. Instead, the information contained in the measurement vector is sufficient to modify the shape of the profile to match  
20 the actual, narrower shape. However, like in the case of the first example, the resolution of the Umkehr method is not  
21 sufficient to reproduce the fluctuation of the actual ozone profile between 70 and 300 hPa. The most obvious difference  
22 between the results calculated with  $\sigma_a = 0.4$  and 0.1 is the difference at 183 hPa (Layer 2). Because the Umkehr method has  
23 little sensitivity at this pressure level, the retrieved ozone concentration is mostly determined by the *a priori* profile for  $\sigma_a =$   
24 0.1 (Fig. 3g). In contrast, when setting  $\sigma_a = 0.4$ , measurements “pull” the retrieval to the higher concentrations of the actual  
25 profile, resulting in a smaller bias relative to sonde and MLS data (Fig. 3c). The TOCs of both retrievals agree to within 7  
26 DU (or 2.1 %) with OMI.

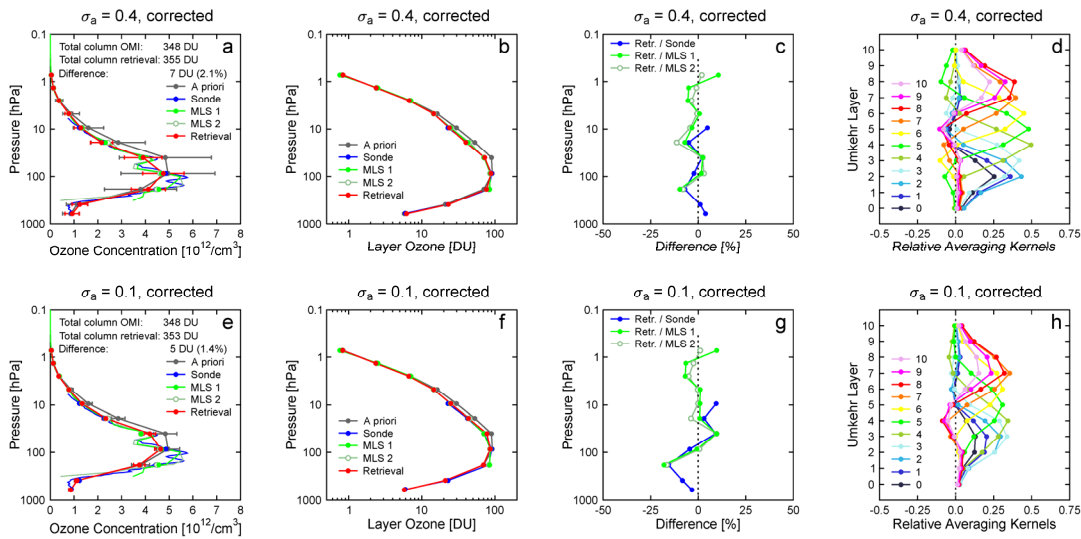
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Fig. 3. Validation of ozone profile retrieved for 11 April 2007. Top row: results of  $\sigma_a = 0.4$  and corrected forward model. Bottom row:  $\sigma_a = 0.1$ , and corrected forward model. 1<sup>st</sup> column: ozone concentration as a function of pressure. 2<sup>nd</sup> column: layer ozone as a function of pressure. 3<sup>rd</sup> column: difference between the retrieval and sonde, MLS 1 and MLS 2 datasets averaged over each Umkehr layer. 4<sup>th</sup> column: [relative averaging kernels](#). Labelling of the different datasets is identical to that of Fig. 2.

### 3.1.3 Comparison for 14 August 2009

The third example (Fig. 4) shows results from 14 August 2009 when the ozone profile was almost identical with the fall *a priori* profile. Note that this *a priori* profile is considerably below that for spring (e.g., Fig. 3d). Calculations were performed with  $\sigma_a = 0.1$  and the corrected forward model. Results agree with sonde and MLS profiles to within  $\pm 13\%$  for Layers 1 – 10 and the TOC of the retrieval is [virtually](#) identical to the OMI measurement. [The effect of changing  \$\sigma\_a\$  from 0.4 to 0.1 are similar for spring and fall profiles and results for  \$\sigma\_a = 0.4\$  were therefore omitted in Fig. 4.](#)

In summary, Umkehr profiles replicate the general pattern in the sonde and MLS data but cannot resolve the fine structure in the ozone distribution, in particular below 100 hPa. The relatively poor resolution in the troposphere and lower stratosphere is similar for the standard [zenith-sky](#) Umkehr method.

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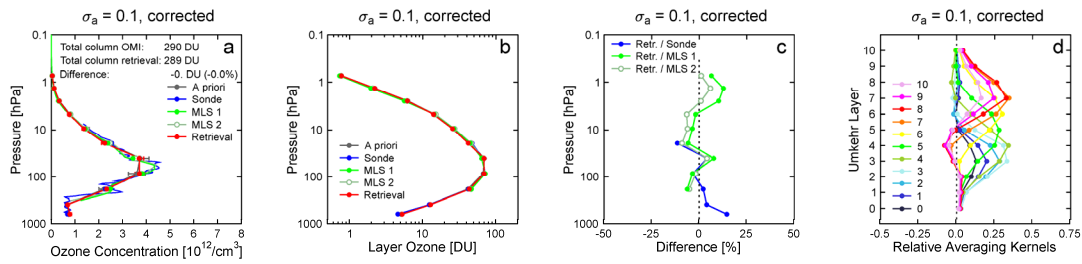


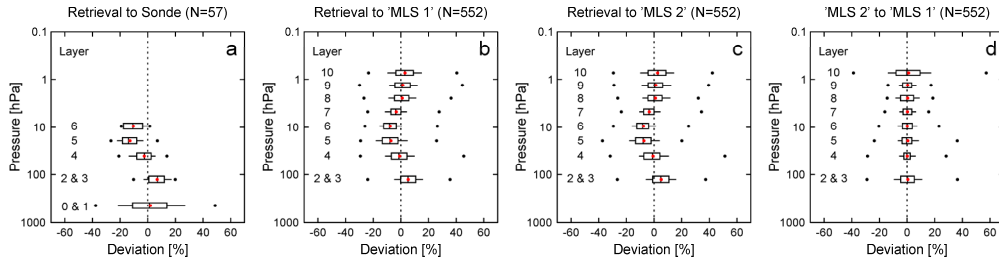
Fig. 4. Validation of ozone profile retrieved for 14 August 2009. The retrieved profile was calculated with  $\sigma_a = 0.1$  using the corrected forward model. (a) ozone concentration. (b) layer ozone. (c) difference between the retrieval and sonde, MLS 1 and MLS 2 datasets averaged over each Umkehr layer. (d) [relative averaging kernels](#). Labelling of the different datasets is identical to that of Fig. 2.

### 3.2 Comparison with balloon sonde and MLS profiles – statistics

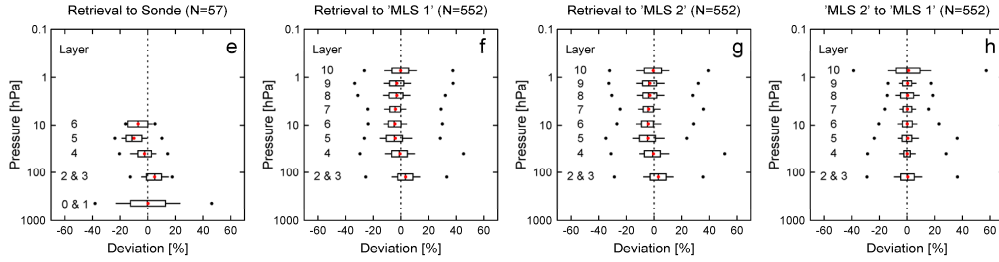
While the results for the three profiles discussed above are promising, they do not allow [a comprehensive assessment of the Global-Umkehr technique](#). To fully validate the method, we compared a large number of sonde and MLS profiles with our retrievals using measurements from the years 2004 to 2014, and calculated statistics. We only considered periods when the TOC was constant to within  $\pm 20$  DU as indicated by OMI. This criterion restricted the number of comparisons with sonde profiles to 57 and with MLS profiles to 552. Data were processed with and without the model correction discussed in Sect. 2.3 and with and without the cloud correction discussed in Sect. 2.2. The latter correction requires measurements of the photodiode internal to the SUV-150B instrument. Unfortunately, these measurements were not available during all days, reducing the number of retrieval/sonde and retrieval/MLS comparisons to 38 and 396, respectively. Results from Layers 0 and 1 and Layers 2 and 3 were combined because of the poor vertical resolution of the Umkehr methods in the troposphere and lower stratosphere discussed earlier. Differences between retrieval and sonde, MLS 1, and MLS 2 data are illustrated with box-whisker plots (Fig. 5), which show the minimum and maximum difference (black dots), median (black line), average (red dot), interquartile (i.e., 25<sup>th</sup> – 75<sup>th</sup> percentile) range (box), and the 10<sup>th</sup> – 90<sup>th</sup> percentile range (whiskers) for each layer or combination of layers. We also plotted statistics for the difference of the MLS 1 and MLS 2 datasets to indicate the variability of the actual ozone profile over the course of one day. Fig. 5 includes results from spring and fall combined. Table 2 provides statistics calculated separately for spring and fall.

**Deleted:** to assess the Global-Umkehr technique comprehensively

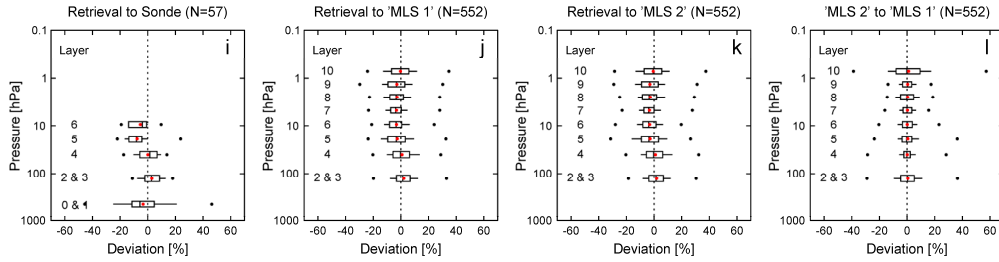
No model correction, no cloud correction,  $\sigma_a = 0.4$



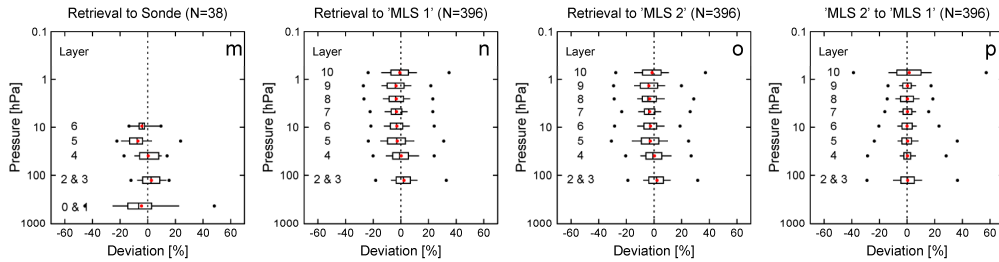
Model correction, no cloud correction,  $\sigma_a = 0.4$



Model correction, no cloud correction,  $\sigma_a = 0.1$



Model correction, cloud correction,  $\sigma_a = 0.1$





1 Fig. 5. Box-whisker plots showing the difference between Umkehr retrieval results and sonde measurements (1<sup>st</sup> column),  
2 MLS observations for day of retrieval ('MLS 1' dataset, 2<sup>nd</sup> column), and MLS observations for the following day ('MLS 2'  
3 dataset, 3<sup>rd</sup> column). The 4<sup>th</sup> column illustrates the difference of the 'MLS 2' and 'MLS 1' datasets. Each plot shows the  
4 minimum and maximum difference (black dots), median (black line), average (red dot) interquartile range (box) and the 10<sup>th</sup>  
5 – 90<sup>th</sup> percentile range (whiskers) for each layer. Results for Layers 0 and 1 and Layers 2 and 3 were combined. The N-  
6 number in the headers of each plot indicates the number of profiles used for computing the statistics. Results in each row  
7 were calculated with a different set of parameters: 1<sup>st</sup> row (panels a–d): forward model not corrected, no cloud correction,  
8  $\sigma_a = 0.4$ . 2<sup>nd</sup> row (panels e–h): forward model corrected by scaling with  $1/R(\theta)$ , no cloud correction,  $\sigma_a = 0.4$ . 3<sup>rd</sup> row  
9 (panels i–l): forward model corrected, no cloud correction,  $\sigma_a = 0.1$ . 4<sup>th</sup> row (panels m–p): forward model corrected, cloud  
10 correction using data of photodiode,  $\sigma_a = 0.1$ .

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13 Table 2. Bias and interquartile range (in parenthesis) of retrieval/MLS 1 comparison; average and standard deviation of the  
14 difference between total ozone calculated from retrieved profiles and measured by OMI (TOC); and average number of  
15 degrees of freedom for signal ( $\langle d_s \rangle$ ) for spring and fall periods. The second column provides the number of profiles ( $N$ )  
16 contributing to the statistics.

Season	$N$	Bias and interquartile range of retrieval/MLS 1 comparison for Layer								TOC	$\langle d_s \rangle$
		2 & 3	4	5	6	7	8	9	10		
<i>No model correction, no cloud correction, <math>\sigma_a = 0.4</math></i>											
Spring	197	4% (14%)	-1% (10%)	-8% (9%)	-10% (8%)	-4% (9%)	-1% (11%)	0% (10%)	4% (15%)	0.2% (1.9%)	3.1
Fall	355	6% (10%)	-1% (12%)	-8% (12%)	-7% (9%)	-3% (7%)	1% (9%)	1% (11%)	3% (11%)	0.7% (1.8%)	3.0
<i>Model correction, no cloud correction, <math>\sigma_a = 0.4</math></i>											
Spring	197	2% (13%)	-1% (10%)	-6% (10%)	-6% (8%)	-4% (10%)	-5% (11%)	-5% (10%)	0% (14%)	0.0% (1.9%)	3.1
Fall	355	4% (10%)	-1% (12%)	-4% (13%)	-4% (9%)	-4% (7%)	-3% (9%)	-3% (11%)	0% (11%)	0.5% (1.8%)	3.0
<i>Model correction, cloud correction, <math>\sigma_a = 0.4</math></i>											
Spring	142	3% (13%)	-2% (12%)	-6% (10%)	-6% (8%)	-5% (10%)	-6% (12%)	-6% (10%)	-1% (15%)	0.0% (2.0%)	3.1
Fall	254	3% (10%)	-1% (11%)	-4% (12%)	-3% (9%)	-4% (8%)	-3% (10%)	-3% (10%)	-1% (11%)	0.5% (1.9%)	3.0
<i>Model correction, no cloud correction, <math>\sigma_a = 0.1</math></i>											
Spring	197	1% (12%)	-1% (12%)	-4% (12%)	-5% (10%)	-4% (10%)	-4% (12%)	-4% (13%)	1% (14%)	-0.2% (1.8%)	2.2
Fall	355	2% (9%)	0% (12%)	-3% (14%)	-3% (8%)	-4% (7%)	-3% (9%)	-3% (12%)	0% (12%)	0.3% (1.7%)	2.1
<i>Model correction, cloud correction, <math>\sigma_a = 0.1</math></i>											
Spring	142	1% (12%)	-1% (13%)	-4% (12%)	-5% (10%)	-4% (11%)	-4% (12%)	-5% (13%)	-1% (16%)	-0.2% (1.9%)	2.2
Fall	254	2% (8%)	-1% (11%)	-2% (14%)	-2% (8%)	-3% (7%)	-4% (9%)	-4% (12%)	-1% (11%)	0.3% (1.7%)	2.1

5 The 1<sup>st</sup> row (panels a–d) of Fig. 5 shows results calculated without the model and cloud corrections;  $\sigma_a$  was set to 0.4. The average and median biases between retrieval and MLS data vary between –8 % and +5 % (Fig. 5b, c). The largest negative bias is observed for Layers 5 and 6 while the largest positive bias of 5 % is observed closest to the surface (Layer 2&3). Biases relative to the sonde measurements (Fig. 5a) are by and large consistent with biases relative to MLS data, although the comparatively small number of sonde observations makes statistics less robust. Fig. 5d confirms that there is no systematic difference between the MLS measurements on the day of Umkehr observations (MLS 1) and the following day (MLS 2).

10 For the retrieval/MLS comparisons, the interquartile ranges vary between 7 % and 12 % and depends only modestly on the layer. With the exception of the results for the highest layer, the interquartile ranges for the MLS 2 to MLS 1 comparison vary between 5 % and 10 %. Differences between the 10<sup>th</sup> and 90<sup>th</sup> percentiles vary between 14 % and 24 % for the retrieval/MLS comparisons (whiskers in Fig. 5b, c) and between 12 % and 17 % for the MLS 2 / MLS 1 comparison, excluding the highest layer (Fig. 5d). The similarity of the ranges for the retrieval/MLS and MLS 2 / MLS 1 comparisons suggests that a large portion of the observed retrieval/MLS differences can be attributed to changes in the actual ozone profile over the time periods relevant for these comparisons. Lastly, the large interquartile range for the retrieval/sonde comparison observed in Layer 0&1 (Fig. 5a) is again a manifestation of the fact that the Umkehr method has little sensitivity for the layers closest to the surface.

20 To assess the effect of the forward model correction on our Umkehr retrievals, we repeated the calculations with this correction. Results are presented in the 2<sup>nd</sup> row (panels e–h) of Fig. 5. As before, no cloud correction was applied and  $\sigma_a$  was set to 0.4. By comparing the original results (Fig. 5b, c) with the corrected results (Fig. 5f, g) it can be observed that the bias between retrieval and MLS data has diminished and now varies between –5 % (Layers 5 and 6) and +3 % (Layer 2&3), suggesting that the model correction is justified. The interquartile ranges with and without the correction are virtually indistinguishable. Note that the correction has no effect on the MLS 2 / MLS 1 comparison and Fig. 5d and h are therefore identical.

25 To explore the effect of  $\sigma_a$  on the results, we repeated the calculations using  $\sigma_a = 0.1$  instead of  $\sigma_a = 0.4$ . Results are shown in the 3<sup>rd</sup> row (panels i–l) of Fig. 5. For  $\sigma_a = 0.1$ , the bias between retrieval and MLS data has decreased further and now varies between –4 % and +1 % (Fig. 5j, k). Differences between retrieval and sondes (Fig. 5i) have also decreased compared to calculations with  $\sigma_a = 0.4$ , except for Layer 0&1. The observation that biases are larger for a larger value of  $\sigma_a$  could be caused by systematic errors in the measurement vector or an incomplete correction of the forward model

results. Changing  $\sigma_a$  from 0.4 to 0.1 had almost no effect on the interquartile range, however, minimum and maximum differences (black dots) contracted somewhat.

Finally, the calculations were repeated with the cloud correction turned on (4<sup>th</sup> row of Fig. 5, panels m–p). For the retrieval/MLS comparison, biases and interquartile ranges with and without the cloud correction agree to within 1 %. Results for the retrieval to sonde comparison (Fig. 5m) are affected by the small sample size of N=38. (Note that results shown for Layer 6 are only based on eight samples because most balloons burst before they reach this layer).

The difference between uncorrected and cloud-corrected statistics is very small, suggesting that clouds affect the accuracy of the retrievals only marginally. However, this conclusion may not apply to locations with thicker clouds and should be tested if the method is used at other sites.

Table 2 allows the assessment of retrievals for spring and fall periods separately. Because statistics are more robust for the retrieval/MLS than retrieval/sonde comparisons, Table 2 only presents results for the former. Biases and interquartile ranges are provided with and without the model and cloud corrections, and with  $\sigma_a$  set to either 0.4 or 0.1. Biases for spring and fall agree to within 3 % for all layers. When no corrections are applied and  $\sigma_a = 0.4$ , biases range between –10 % (Layer 6 for spring) to +6 % (Layer 2&3 for fall). The model correction decreases this range to between –6 % to 4 %. By reducing  $\sigma_a$  from 0.4 to 0.1, the range decreases further to between –5 % to 2 %. The cloud correction has a negligible ( $\leq 1$  %) effect on the biases. Interquartile ranges vary from 7 % to 16 % and depend only little ( $\leq 3$  %) on  $\sigma_a$  and on whether or not corrections are applied.

Table 2 also includes a column comparing TOCs derived from the retrieved profiles with measurements by OMI. Depending on  $\sigma_a$  and the correction method, the average difference between the retrieved and OMI TOCs varies between –0.2 % and 0.7 %, and the standard deviation varies between 1.7 % and 2.0 %.

Lastly, the average value of  $d_s$  is about 3.0 for  $\sigma_a = 0.4$  and 2.1 for  $\sigma_a = 0.1$ . A value of  $d_s = 3.0$  may seem low, but it is consistent with values of  $d_s$  resulting from the standard zenith-sky Umkehr technique. For example, Stone et al. (2015) reported a value of  $d_s = 3.1$  for Dobson zenith-sky Umkehr retrievals using the Dobson C wavelength pair (311.4 and 332.4 nm) and the standard Dobson SZAs ranging from 60° to 90°.

#### 4 Discussion

When the forward model is corrected, the bias of our retrievals relative to MLS data is smaller than  $\pm 6$  % for all layers. This level of agreement compares favourably with published results of the standard zenith-sky Umkehr method. For example, McElroy and Kerr (1995) compared Umkehr profiles derived from a Brewer spectrophotometer with concurrent measurements of a lidar, a microwave radiometer and ozone sondes, which were performed during a one-month campaign at the Table Mountain Observatory in California. The mean bias between the Brewer zenith-sky Umkehr results and the mean

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of the other instruments varied to within  $\pm 10\%$  for altitudes between 20 and 35 km. Between 37 and 47 km, the Brewer data were low by 15 to 20 % (Fig. 9 of McElroy and Kerr, 1995).

Nair et al. (2011) compared stratospheric ozone vertical distribution measured by a large number of ground-based and satellite sensors at the Haute-Provence Observatory, France. They found that zenith-sky Umkehr data from an automated Dobson spectrophotometer systematically underestimate the stratospheric ozone concentration with a near-zero bias at about 30 km, but increasing to 7 % at 21 km and 34 km, and to 14 % at 40 km (Fig. 8 of Nair et al., 2011). Despite of these large biases, Nair et al. (2011) concluded that Umkehr data are useful for studies of the long-term ozone evolution and for detecting drifts in satellite observations.

Miyagawa et al. (2014) compared Dobson zenith-sky Umkehr measurements with homogenized NOAA SBUV (Solar Backscatter Ultraviolet Instrument)(/2) 8.6 overpass data measured between 1977 and 2011. The mean bias between Dobson and SBUV partial ozone column varied between -12 % for Layer 7 to +3 % for Layer 2 (Fig. 1a of Miyagawa et al., 2014).

The biases reported in the three studies quoted above are comparable or larger than the differences between our Global-Umkehr retrievals and MLS and sonde measurements, suggesting that Umkehr results derived from global spectral irradiance can provide data of similar accuracy than the established zenith-sky method. A portion of the retrieval/MLS difference could also be caused by systematic errors in the MLS dataset, considering that the MLS accuracy specified by Froidevaux et al. (2008) is in the 5 to 10 % range.

Results presented in Fig. 5 illustrate that interquartile and 10<sup>th</sup> – 90<sup>th</sup> percentile ranges for the retrieval/MLS comparison on one hand and the MLS 2 / MLS 1 comparison on the other are similar for most layers. This suggests that a large portion of the observed retrieval/MLS differences can be attributed to actual changes in the ozone profile over the time periods relevant for these comparisons. However, a portion of the change in the MLS profile from one day to the next may be caused by the relatively poor horizontal resolution of MLS profiles of about 200 km. In addition, some variability in the MLS dataset can be attributed to the slightly different geolocation of two consecutive overpass profiles. For example, the average horizontal distance between the locations of Summit and the MLS overpass is 160 km. Further analysis revealed that the difference between the MLS 1 and MLS 2 datasets depends also on the time when the daily MLS observation takes place. For example, when MLS 2 data are from the observation period close to local solar noon (14:11 to 15:10 UTC) and MLS 1 data are measured close to sunrise (5:28 to 6:26 UTC), MLS 2 data for Layers 7 – 9 are biased high by 3-6% relative to the MLS 1 dataset, while MLS 2 data for Layer 10 are biased low by 8%. This time-of-day dependency and its variation with altitude is by and large consistent with diurnal variations of the ozone profile measured by various instruments at Mauna Loa, Hawaii (Parrish et al., 2014), and by a microwave radiometer at Bern, Switzerland (Studer et al., 2014). This suggests that the time-of-day effect observed at Summit is caused by actual diurnal changes of the ozone profile rather than potential time-dependent systematic errors in the MLS dataset.

Another source of variability in the retrieval/MLS and retrieval/sonde comparisons is the different vertical resolutions of MLS (about 2-3 km), sondes (0.1 km) and our Umkehr retrievals (about 10 km for  $\sigma_a = 0.4$  and about 25 km for  $\sigma_a = 0.1$ ).

If measurement and forward model were without error, an Umkehr profile would resemble the actual profile smoothed by the

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AKs. To reduce the effect of the differing resolution, the higher-resolution MLS profiles could be convolved with the AKs of the Umkehr profile prior to comparing the two profiles. This technique has for example been applied by Nair et al. (2011) when comparing lidar and SBUV profiles. We did not use this method because it artificially reduces the true difference that is observed when comparing a high-resolution (sonde, MLS) with a low-resolution (Umkehr) profile. Of note, Nair et al. (2011) found that the smoothing technique does not make a significant difference in seasonally averaged data such as those presented in Fig. 5 and Table 2.

The bias between Umkehr retrievals and MLS or sonde data is reduced when correcting the forward model for the systematic error presented by the pseudospherical approximation. It is interesting to note that the correction is only in the  $-0.5$  to  $2.0$  % range (Fig. 1b) but reduces the retrieval bias by up to  $4$  % (Layer 6 in spring, see Table 2). Considering that the uncertainty of our measurements is  $3$  % ( $1\sigma$ ), systematic errors in the measurement vector in the  $2$ - $3$  % range could conceivably be responsible for the remaining bias of Umkehr and MLS profiles indicated in Fig. 5 and Table 2. To test this hypothesis, we modified the measurement vector within reasonable limits and recalculated the profiles. We found that the bias between Umkehr and MLS profiles cannot be significantly reduced further, suggesting that the bias cannot be attributed to measurement errors alone.

The difference between results corrected for cloud effects and uncorrected results is very small, implying that clouds affect the accuracy of the retrievals only marginally. However, this conclusion may not apply to locations with thicker clouds or locations affected by aerosols and should be tested if the method is used at other sites.

If  $S_e$  is well defined, the most important parameter to optimize the results is  $\sigma_a$ . The objective is to find the right balance between sensitivity to the *a priori* profile on one hand and sensitivity to (unavoidable) errors in the measurement vector or forward model on the other. We chose  $\sigma_a = 0.1$  and  $0.4$ . The smaller value quantifies the standard deviation of the actual variability of the ozone profile at Summit. While calculations with this value lead to good results, the solution may not be optimal for profiles at the fringe of the distribution (e.g., result for Layer 3 in Fig. 3). A small  $\sigma_a$  also results in a small value of  $d_s$ . However, statistics for results calculated with  $\sigma_a = 0.1$  and  $0.4$  are quite similar (Table 2), suggesting that any value for  $\sigma_a$  between  $0.1$  and  $0.4$  leads to acceptable profiles. Determining the best value for sites other than Summit requires consideration of the measurement system and variability of the ozone profile at this site.

There are various ways to optimize the Global-Umkehr method for specific applications or locations. For example, if two instruments were to measure side by side, the uncertainty used to set up  $S_e$  could be better estimated by comparing the measurements of the two systems. Furthermore, the method to set up  $S_a$  could be modified to take into account that the

variability of the ozone profile depends on altitude (Eq. (4) uses the same standard deviation  $\sigma_a$  for all layers). [More current ozone absorption cross section data could be used \(e.g., Orphal et al., 2016\) than the Bass and Paur \(1985\) data implemented in this work and by OMI. If temperature profile data are available, these could be utilized to account for the temperature dependence of the ozone absorption cross section. Wavelengths, bandpass, and SZAs used for the measurement](#)

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vector could be further optimized to reduce uncertainties related to the Ring effect or the temperature dependence of the ozone absorption cross section. For example, by degrading the spectral resolution (currently set to 2 nm), the impact of the Ring effect could be diminished. Finally, the MYSTIC Monte Carlo model, which was used to calculate the correction function  $R(\theta)$  (see Fig. 1b), was run with a scalar radiative transfer solver, which did not take polarization into account.

5 Lacis et al. (1998) calculated that modelling errors for irradiance resulting from the omission of polarization in these calculations can be as large as 1.3% for a Rayleigh atmosphere. However, errors for 310 and 337 nm (i.e., the wavelengths used in the Global-Umkehr method) agree to within 0.1%. We therefore conclude that the omission of polarization is not an import error source in our calculations.

10 We used *a priori* profiles that are independent of the total ozone column. Zenith-sky Umkehr retrievals from Dobson instruments that have historically been processed with the algorithm developed by Mateer and DeLuisi (1992) used TOC-dependent *a priori* profiles to constrain the retrieval. While this practice can lead to artefacts when calculating trends (Petropavlovskikh et al., 2005; Stone et al., 2015), the approach may be the best choice if a profile with the smallest uncertainty possible is sought for a specific purpose.

15 The Global-Umkehr method was tested with spectroradiometric measurements from a polar location because we only operate instruments at high-latitude sites. Inversions using high-latitude data are more challenging compared to retrievals for lower latitudes because of the limited range of SZAs at polar regions, the long time that is required to scan the range of SZAs necessary for the retrieval, and the high short- and long-term variability of the ozone profile. We have therefore confidence that the method would work well for mid- and low-latitude locations. Confirmation of this assertion is subject of future tests.

## 20 5 Conclusions

An optimal estimation method has been developed to retrieve vertical ozone profiles from measurements of global spectral irradiance in the UV. The method is similar to the widely used zenith-sky Umkehr technique, which inverts measurements of zenith sky radiance. To our knowledge, this is the first time that the Umkehr technique was applied to measurements of global irradiance. High-quality measurements of global spectral irradiance are now available for more than 25 years at

25 several NDACC locations (De Mazière et al., 2017), and the Global-Umkehr method has the potential to make these long-term datasets available for studying changes in the vertical distribution of ozone.

Compared to the standard zenith-sky Umkehr method, multiple scattering effects become more important when exploiting global irradiance measurements, which also include contributions from photons received from directions close to the horizon. Therefore, the sphericity of the viewing geometry needs to be taken into account. We have shown that this

30 challenge can be overcome by using a forward model with pseudospherical approximation plus additional corrections.

The method was evaluated with spectroradiometric measurements from Summit, Greenland, and validated with balloon sonde and MLS observations. For calculations using the corrected forward model, the bias between our retrieved profiles and

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MLS observations ranges between  $-5\%$  (Layers 5 and 6) and  $+3\%$  (Layer 2&3). The magnitude of this bias is comparable, if not smaller, to values reported in the literature for the standard [zenith-sky](#) Umkehr method. The distribution of the difference between retrieval and MLS observations was quantified with the interquartile and 10<sup>th</sup> – 90<sup>th</sup> percentile ranges. Depending on altitude, the interquartile ranges vary between 7 % and 13 % and the 10<sup>th</sup> – 90<sup>th</sup> percentile ranges run between 14 % and 24 %. Of note, interquartile ranges calculated from the differences of two MLS profiles that were measured on consecutive days vary between 5 % and 10 %, suggesting that a considerable portion of the retrieval/MLS differences can be attributed to real changes in the ozone profile. For Umkehr Layer 2 and higher, retrieval/MLS and retrieval/sonde differences are by and large consistent. The poor sensitivity of the Umkehr method to the altitude range of Layer 0&1 leads to are relatively large scatter (e.g., the interquartile range is 25 %) of the retrieval/sonde differences for this layer.

The effect of the parameter  $\sigma_a$ , which controls the sensitivity of the solution on the *a priori* profile, was extensively assessed. It was found that results calculated with a small value of  $\sigma_a = 0.1$  (emphasis on *a priori*) generally agree to within 2–3 % of those calculated with a large value of  $\sigma_a = 0.4$  (emphasis on measurements). By setting  $\sigma_a$  to a large value, retrieval errors may occasionally become large if the measurement vector is affected by unforeseen conditions (e.g., changing ozone, variable clouds). For example, the maximum retrieval/MLS difference was 50 % for  $\sigma_a = 0.4$  but only 32 % for  $\sigma_a = 0.1$ .

The retrieved ozone profiles were integrated over altitude. The resulting TOCs agreed almost ideally with TOCs measured by OMI: depending on the correction method, the retrieval/OMI bias ranged between  $-0.2\%$  and  $0.7\%$  with a standard deviation of less than 2.0 %.

While the Global-Umkehr method was only tested for a high-latitude site, we are confident that it will also work at lower latitudes, but this assertion requires confirmation by future tests.

#### Data availability

“Version 2” spectra from the SUV-150B spectroradiometer at Summit are available from the Arctic Data Center at <https://arcticdata.io/>.

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