

## ***Interactive comment on “Comparative analysis of low-Earth orbit (TROPOMI) and geostationary (GeoCARB, GEO-CAPE) satellite instruments for constraining methane emissions on fine regional scales: application to the Southeast US” by Jian-Xiong Sheng et al.***

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This paper presents in a very compact nature a methodology for comparing three different satellite missions working to constrain methane fluxes using Degrees of Freedom for Signal (DOFS) as a metric of the resolvable information content. This methodology is applied in OSSEs looking at the relative performance of TROPOMI, GeoCARB, and GEO-CAPE. The approach is interesting, and provides a slightly different assessment

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than the usual reduction of posterior uncertainty. Nonetheless, I have a few concerns regarding some of the assumptions made (particularly with respect to the influence of cloud cover on measurement yield) and the presentation of the results. While the writing is quite clear and free from errors, some additional information is required to help the reader truly understand the approach. (Perhaps the manuscript is a bit too compact?) Even after reading some of the referenced papers in a search for explanation, the interpretation of the results was somewhat difficult. As such, some additional information is requested, as outlined below. If these points are addressed, I would consider the paper suitable for publication in AMT.

In particular, some physical interpretation of the state vector elements developed using the Gaussian Mixture Method (GMM) with Radial Basis Functions (RBFs) would be helpful. The paper in which this method was developed (Turner and Jacob, 2015) is mathematically rather dense, but does provide some information about what these functions look like for California. Having some idea about the relevant processes and the spatial distributions that might be resolved in the study domain used here would be useful. Was temporal aggregation performed as well, over the week, or was a stationary solution assumed? How would this methodology be extended to different time periods or regions? Would the state vector have significantly more or less elements for other similarly-sized domains?

P3, L7-9: I disagree with the statement that the assumption of randomness in the noise of synthetic measurements does not affect a comparative analysis of different instruments. This is true if the instruments which are being compared are expected to have similarly correlated or uncorrelated errors in their actual measurements, but this may well not be the case. An example of this is active vs. passive sensors, where the former is expected to have considerably less correlation between individual measurements. While such an assumption has often been made in the past, more experience with satellite measurements have proven time and again that systematic (correlated) errors are incredibly important when trying to interpret signals, and they are not identi-

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cal across instruments. Please discuss explicitly the limitations of this assumption.

P4, L3-10: In the discussion of the model transport error variance, the approach seems valid, but I wonder about its broader applicability over the full domain. Other studies (using in situ data) have shown that the uncertainty dominated by transport errors tends to be proportional to the mean mixing ratios for a given period (see e.g. Jeong et al., JGR, 2013). How representative are the signals at Lamont for the whole domain?

P4, L11-17: In this discussion of the temporal correlation of the measurements, please explain the increase at around 12 hours seen in the second panel of Figure 2. Does this have something to do with the fact that the TCCON measurements are made only during the day, and as such there are fewer samples at around 12 hours? Or is this the result of the well-known smily/frowny tendencies of some TCCON sites at high solar zenith angles? Or an airmass dependency that is not properly accounted for when comparing the modelled fields to the TCCON data? This peak in correlation at 12 hours could be the result of neglecting to apply the (solar-zenith-angle-dependent) averaging kernels to the modelled fields before performing the comparison. Was this done? Some more detail is needed here.

P4, L22-P5, L7: The discussion of the cloud cover is probably the most critical point in this manuscript, upon which many of the conclusions rest. I expect that the estimation of number of successful retrievals is overestimated for partially cloudy conditions. The methodology of Remer et al. (2012) required only that the specific 1-km pixels making up a given measurement footprint were cloud-free. In practice, if there is a single gap in the clouds of exactly 7 km x 7 km, it is highly unlikely that TROPOMI would be able to get a successful retrieval. Yes, it is officially "cloud-free", but this is treating clouds like a 2D mask, when in reality they are 3-dimensional, with multiple layers, and the sun is very rarely exactly at nadir, in fact never for this domain, and the geostationary imagers are likewise observing at an angle. Thus the light path requires a larger cloud-free area than the ground footprint would suggest. Most retrieval teams find that it is difficult to get good retrievals from very small gaps in clouds due to these problems as

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well as light path effects related to nearby clouds and cloud shadows that decrease the amount of reflected light from the ground, reducing the signal to noise. Perhaps some of these effects are less critical for aerosol retrievals, the focus of Remer et al. (2012), but for highly exacting retrievals of greenhouse gases they can be critical.

In addition to this, the footprints given are all at nadir, and in fact they may be somewhat larger depending on the viewing angle. This simple geometry requires a larger gap in the clouds than the footprint alone suggests. It seems the numbers used in this study are taken from Figure 6 in Remer et al., (2012); Figure 7 of the same paper addresses the off-nadir difference for spring, which results in a reduction of 4% for 4 km x 4 km footprints (from 0.31 to 0.27 for MAM, a relative decrease of 13% ).

Thus the effective gap size needed for a 3 km x 3 km instrument may well end up being closer to 8 km x 8 km. This inflation of the footprint size is particularly important for single measurements in broken cloud conditions - this extra padding has its greatest impact around the edge of a cloud-free area. This suggests that the number of cloud-free soundings is likely overestimated. The fact that the median number of observations per model pixel is only 3 for TROPOMI suggests that even a slight reduction in acceptable pixels might have very serious effects on the information content for this instrument. The greater "oversampling" relative to the model resolution for the other instruments means that this will likely have a less serious effect. This is consistent with the information in Figure 4.

One final facet to this discussion that may be worth mentioning is the fact that the actual footprint of TROPOMI may well be 3.5 km x 7 km in the end, due to sampling changes to deal with saturation of the optical channels, which only became apparent post-launch. While this reduction in footprint also results in a smaller signal to noise (and presumably a larger measurement uncertainty), the conclusions on P5, L5-7 suggest that this will likely not degrade the result significantly. I would not redo any of the analysis based upon this information, but simply mention it in the discussion.

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Minor comment:

Figure 2: The inclusion of the temporal correlation of cloud cover map in the temporal correlation of modelling error is unnecessarily confusing. Both plots are relevant and worth including, but they should be separated.

Figure 3: The three GeoCARB points should be labelled with x1/day, x2/day, x4/day. The information is contained on the y-axis, but adding this information would make the figure easier to interpret.

Figure 3&4: replot with harmonized colours, so that the same colour always represents e.g. GEO-CAPE, TROPOMI, GeoCARB 1/day, etc.

Watch that the capitalization of GeoCARB is consistent, see e.g. title and legend in Figure 4.

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