

The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm

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Abstract. The Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) version 4.10 (V4) level 2 aerosol data products, released in November 2016, include substantial improvements to the aerosol subtyping and lidar ratio selection algorithms. These improvements are described along with resulting changes in aerosol optical depth (AOD). The most fundamental change in V4 level 2 aerosol products is a new algorithm to identify aerosol subtypes in the stratosphere. Four aerosol subtypes are introduced for the stratospheric aerosols: polar stratospheric aerosol (PSA), volcanic ash, sulfate/other, and smoke. The tropospheric aerosol subtyping algorithm was also improved by adding the following enhancements: (1) all aerosol subtypes are now allowed over polar regions, whereas the version 3 (V3) algorithm allowed only clean continental and polluted continental aerosols; (2) a new “dusty marine” aerosol subtype is introduced, representing mixtures of dust and marine aerosols near the ocean surface; and (3) the “polluted continental” and “smoke” subtypes have been renamed “polluted continental/smoke” and “elevated smoke”, respectively. V4 also revises the lidar ratios for clean marine, dust, clean continental, and elevated smoke subtypes. As a consequence of the V4 updates, the mean 532 nm AOD retrieved by CALIOP has increased by 0.044 (0.036) or 52 % (40 %) for nighttime (daytime). Lidar ratio revisions are the most influential factor for AOD changes from V3 to V4, especially for cloud-free skies. Preliminary validation studies show that the AOD discrepancies between CALIOP and AERONET/MODIS (ocean) are reduced in V4 compared to V3.

1 Introduction

The Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) flown aboard the Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations (CALIPSO) platform has been providing unique vertical profile measurements of the Earth’s

atmosphere on a global scale since June 2006 (Winker et al., 2010). Data products derived from the CALIOP measurements are distributed worldwide from the Atmospheric Sciences Data Center (ASDC) located at the National Aeronautics and Space Administration (NASA) Langley Research Center (LaRC). In addition to detailed spatial and optical properties of detected layers, CALIOP also provides essential information on layer types for both clouds and aerosols.

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Currently, CALIOP is the only space-based sensor that observes and reports the vertical distributions of aerosol spatial and optical properties over the globe, and thus CALIOP data products offer substantial research advantages in aerosol studies. For example, CALIOP aerosol data have been widely used to evaluate aerosol model simulations for several aerosol types (e.g., Yu et al., 2010; Ford and Heald, 2012; Koffi et al., 2012; Nabat et al., 2013; [Koffi et al., 2016](#)~~Nowottnick et al., 2015~~), and to

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investigate spatio-temporal distribution and transport of several major aerosol types, such as dust and smoke aerosols (e.g., Mona et al., 2012; Guo et al., 2017; Senghor et al., 2017; Marinou et al., 2017; Wu et al., 2017). ~~Aerosol subtyping is important all by itself for identifying aerosol by type. But it is also important for the CALIOP level 2 retrievals of aerosol optical properties. While CALIOP's aerosol subtype classifications are useful as a wholly independent data product (e.g., Nowottnick et al., 2015; Sun et al., 2018), knowledge of aerosol subtype is also critically important for the CALIOP level 2 retrievals of~~

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~~aerosol optical properties.~~ The aerosol lidar ratio, a key parameter for the extinction retrieval, is determined for each aerosol subtype based on measurements, modeling, and the cluster analysis of a multiyear Aerosol Robotic Network (AERONET) dataset (Omar et al., 2005; Omar et al., 2009). Because the lidar ratio is one of the largest sources of uncertainty in the CALIOP aerosol optical depth (AOD), the CALIOP aerosol classification and lidar ratio selection algorithm plays a critical role in the aerosol extinction retrieval and resulting AOD (Young et al., 2013).

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In version 3 (V3) and earlier, the CALIOP level 2 aerosol classification and lidar ratio selection algorithm defined six aerosol types: clean marine, dust, polluted continental, clean continental, polluted dust, and smoke (Omar et al., 2009). Each type is assigned an extinction-to-backscatter ratio (i.e., lidar ratio) with an associated uncertainty that defines the limits of its expected natural variability. Since the V3 release, several limitations of the V3 aerosol subtyping algorithm have come to light. For instance, mixtures of dust and marine aerosol were frequently classified as polluted dust (Burton et al., 2013), which is intended to be a mixture of dust and smoke or urban pollution. In polar regions, Asian dust and smoke from boreal fires were forced to be classified as either clean continental or polluted continental, as the only aerosol subtypes allowed over snow, ice, or tundra. The algorithm for identifying smoke also caused some layers at the bases of elevated smoke plumes to be misclassified as clean marine ([Nowottnick et al., 2015](#)). Finally, all features detected above the tropopause were generically classified as

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“stratospheric features” and were not given aerosol subtypes, thereby missing an opportunity to identify volcanic aerosol in the stratosphere.

The conclusions from numerous studies assert that the AOD reported in the CALIOP V3 data products typically underestimates coincident AOD measurements and/or retrievals acquired using various space-borne, airborne, and ground-based instruments (e.g., Redemann et al., 2012; Schuster et al., 2012; Kim et al., 2013; Omar et al., 2013; Rogers et al., 2014). Additional CALIOP analyses using opaque water clouds as a constraint in the retrieval (Hu, 2007) show similar results (Liu et al. 2015). However, the Moderate Resolution Imaging Spectroradiometer (MODIS) AOD retrievals (collection 5) are subject to several sources of error which mostly tend to produce high biases in AOD (Kittaka et al., 2011). Campbell et al. (2012) compared with the US Navy Aerosol Analysis and Prediction System (NAAPS), which assimilates a quality-screened version of MODIS AOD, and find that the V3 CALIOP AOD is consistent with NAAPS over ocean and somewhat higher over land.

There are two primary sources for the CALIOP AOD differences relative to other measurements and retrievals: aerosol layer detection failures and inaccurate lidar ratios. Rogers et al. (2014) compared CALIOP AOD with NASA LaRC airborne High Spectral Resolution Lidar (HSRL) and found that the undetected aerosols in the free troposphere introduce a mean underestimate of 0.02 in the CALIOP column AOD in the data set examined. Kim et al. (2017) retrieved aerosol extinction for the undetected aerosol layers and found a global mean undetected layer AOD of 0.031. Toth et al. (2018) reported that 45% of daytime cloud-free V3 level 2 aerosol profiles have no aerosol detected within the profile (AOD = 0). They found the mean collocated MODIS and AERONET AODs at 550 nm are near 0.06 and 0.08, respectively, for the CALIOP profiles without aerosols. Several other studies also suggest that the weakly backscattering aerosols which are undetected by CALIOP's layer detection algorithm can contribute to a low CALIOP AOD estimate relative to other sensors (Kacenelenbogen et al., 2011; 2014; Thorsen et al., 2017). Whereas layer detection failure always contributes to low bias, misclassification of aerosol subtypes and inaccurate aerosol lidar ratios can result in both high and low biases in CALIOP AOD. Burton et al. (2013) compared CALIOP V3 aerosol subtype product with NASA LaRC airborne HSRL measurements. They compared 109 underflights of the CALIOP orbit track and found that 80 % of the CALIOP desert dust layers, 62 % of the marine layers and 54 % of the polluted continental layers agreed with HSRL classification results. However, the agreement was less for smoke (13 %) and polluted dust (35 %) layers. Recent studies suggest that the lidar ratios assigned by the V3 CALIOP aerosol classification and lidar ratio selection algorithm are at least partially responsible for biases in the CALIOP V3 AOD for clean marine (Bréon, 2013; Rogers et al., 2014; Dawson et al., 2015) and dust aerosols (Burton et al., 2012; Schuster et al., 2012; Amiridis et al., 2013; Nisantzi et al., 2015; Liu et al., 2015).

The CALIOP version 4.10 (V4) level 2 aerosol data products, released in November 2016, contain substantial updates to aerosol type classification and to aerosol lidar ratio assignments, made in response to many of the results reported in the studies described above. ~~This paper~~ The primary purpose of this paper is to introduces the V4 updates in the CALIOP level 2 aerosol subtyping algorithms and changes to the characteristic lidar ratios for different aerosol subtypes. This is discussed in Sect. 2. The resulting AOD differences between V3 and V4 are investigated in Sect. 3 by categorizing the factors that can contribute

to the AOD changes. Lastly, [in Sect. 4](#), we compare CALIOP AOD with AERONET and MODIS for both versions as an initial validation of the CALIOP V4 AOD.

2 Algorithm updates for CALIOP version 4 aerosol level 2 products

5 The CALIOP V4 level 2 data products contain substantial refinements over V3 and earlier releases (Liu et al., 2018; Avery et al., 2018; Young et al., 2018). The most fundamental changes in V4 level 2 aerosol products are the introduction of a new ‘dusty marine’ aerosol subtype in the troposphere, and the addition of new aerosol subtypes to classify aerosol layers newly identified in the stratosphere. Because the cloud aerosol discrimination (CAD) algorithm is now applied to all layers detected (Liu et al., 2018), those features that were previously classified as generic “stratospheric” layers in V3 and earlier are now
10 identified as either clouds or aerosols. Consequently, the V4 level 2 aerosol subtyping algorithm now distinguishes between tropospheric and stratospheric aerosols. An entirely new algorithm has been implemented to identify aerosol subtypes in the stratosphere, and the algorithm for identifying tropospheric aerosol types has been substantially updated. The changes made to the tropospheric algorithm are described in detail first, followed by details on the new stratospheric aerosol subtyping algorithm.

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2.1 Aerosol subtypes in the troposphere

The CALIOP V3 aerosol classification algorithm uses altitude, location, surface type, estimated particulate depolarization ratio (δ_p^{est}), and integrated attenuated backscatter (γ') to identify the aerosol subtype (Omar et al., 2009). Figure 1 shows the decision tree used to determine the V3 and V4 tropospheric aerosol subtypes. The major updates implemented in the V4
20 tropospheric aerosol subtyping algorithm include: introducing the dusty marine aerosol subtype (by adding the red shaded part in Fig. 1), allowing all aerosol subtypes over polar regions (by removing blue shaded part in Fig. 1), and revising the operational definitions for the polluted continental and smoke aerosol types.

At this time the integrated attenuated color ratio ($\chi' = \gamma'_{1064}/\gamma'_{532}$) is not used for aerosol subtyping in the troposphere because
25 the low signal to noise ratio (SNR) for optically thin layers, especially in the daytime, makes it an inconsistent discriminator among tropospheric aerosol types. However, it is useful for stratospheric aerosol typing where the number of types is fewer (Sect. 2.2).

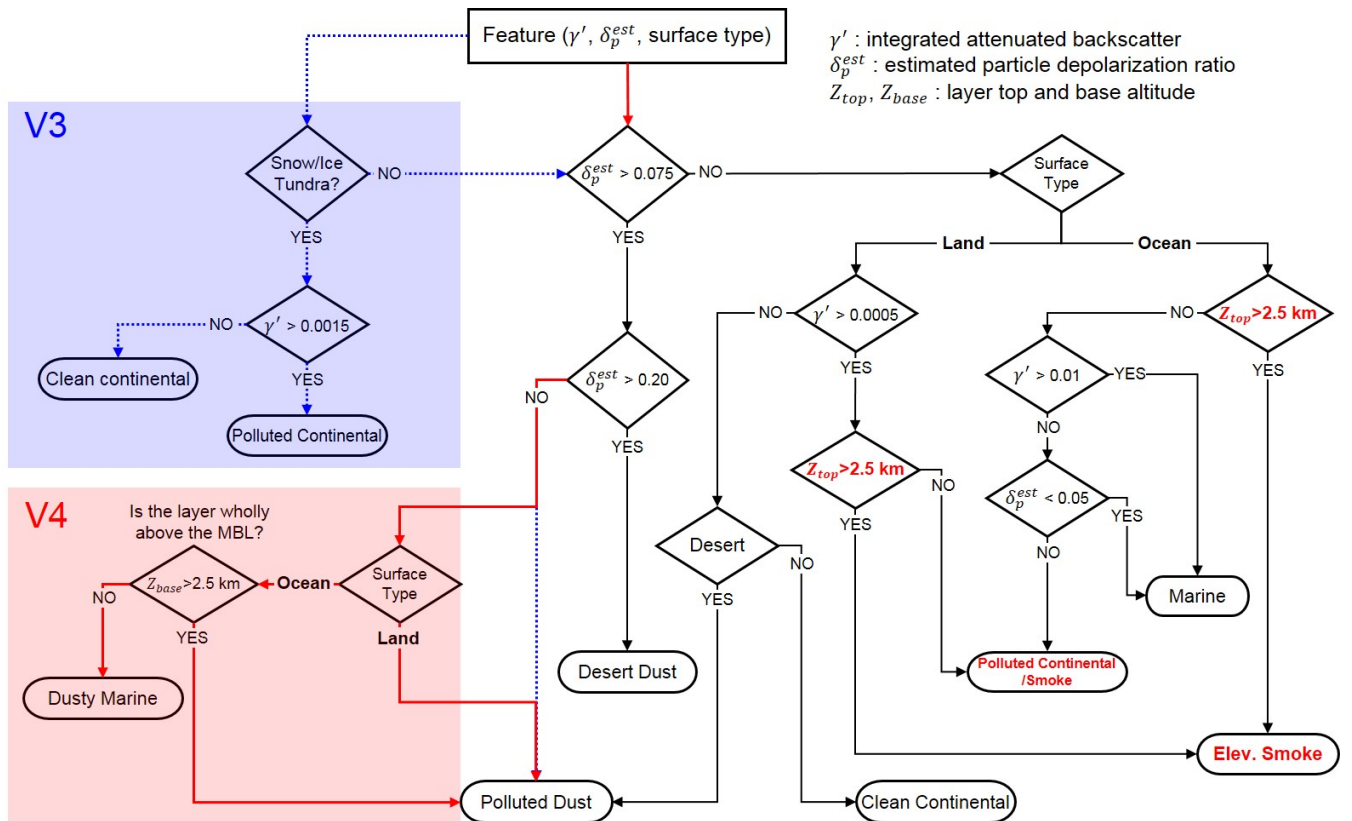


Figure 1: Flowchart of the CALIPSO aerosol subtype selection scheme for tropospheric aerosols. Blue-shaded part and blue-dotted arrows are used in V3 but removed in V4. Red shaded parts with thick red arrows are newly added in V4. The nomenclatures for “polluted continental” and “smoke” are revised to “polluted continental/smoke” and “elevated smoke” V4. The definition for “elevated” is revised in V4 to mean layers with tops higher than 2.5 km above ground level (see Sect 2.1.3).

2.1.1 A new aerosol subtype: dusty marine

In V4, a new “dusty marine” aerosol type is introduced to identify mixtures of dust and marine aerosol and thus account for the frequent occurrence of mixtures of dust and marine aerosols that are misclassified as polluted dust over global oceans in V3. Dusty marine occurs most frequently when Saharan dust is transported across the Atlantic Ocean and settles into the marine boundary layer (MBL) as it approaches North and Central America (Liu et al., 2008; Groß et al., 2016; Kuciauskas et al., 2018). In V3, many of these layers are misclassified as polluted dust, an aerosol type intended to represent mixtures of dust + smoke and dust + polluted continental aerosols. In both V3 and V4, polluted dust is assigned a lidar ratio of 55 ± 22 sr. Using data acquired during CALIPSO validation flights over the Caribbean Sea, Burton et al. (2013) compared CALIOP V3 aerosol classifications with measurements made by the NASA LaRC airborne HSRL on the NASA B200 aircraft. For those layers that

CALIOP V3 classified as polluted dust, the HSRL measured a median lidar ratio 35 sr, thus strongly suggesting that these aerosols were a combination of dust + marine aerosol, and not the combination of dust + smoke modeled by the CALIOP polluted dust type. As shown in Fig. 2(a), 40 % to 50 % of aerosol samples over the Caribbean in JJA at night are classified as polluted dust in V3. During the daytime in V3 (Fig. 2(b)), polluted dust accounts for 10 % to 30 % of aerosol samples identified over remote oceanic regions (e.g., the South Pacific Ocean) where the occurrence of mixtures of dust and smoke is less probable.

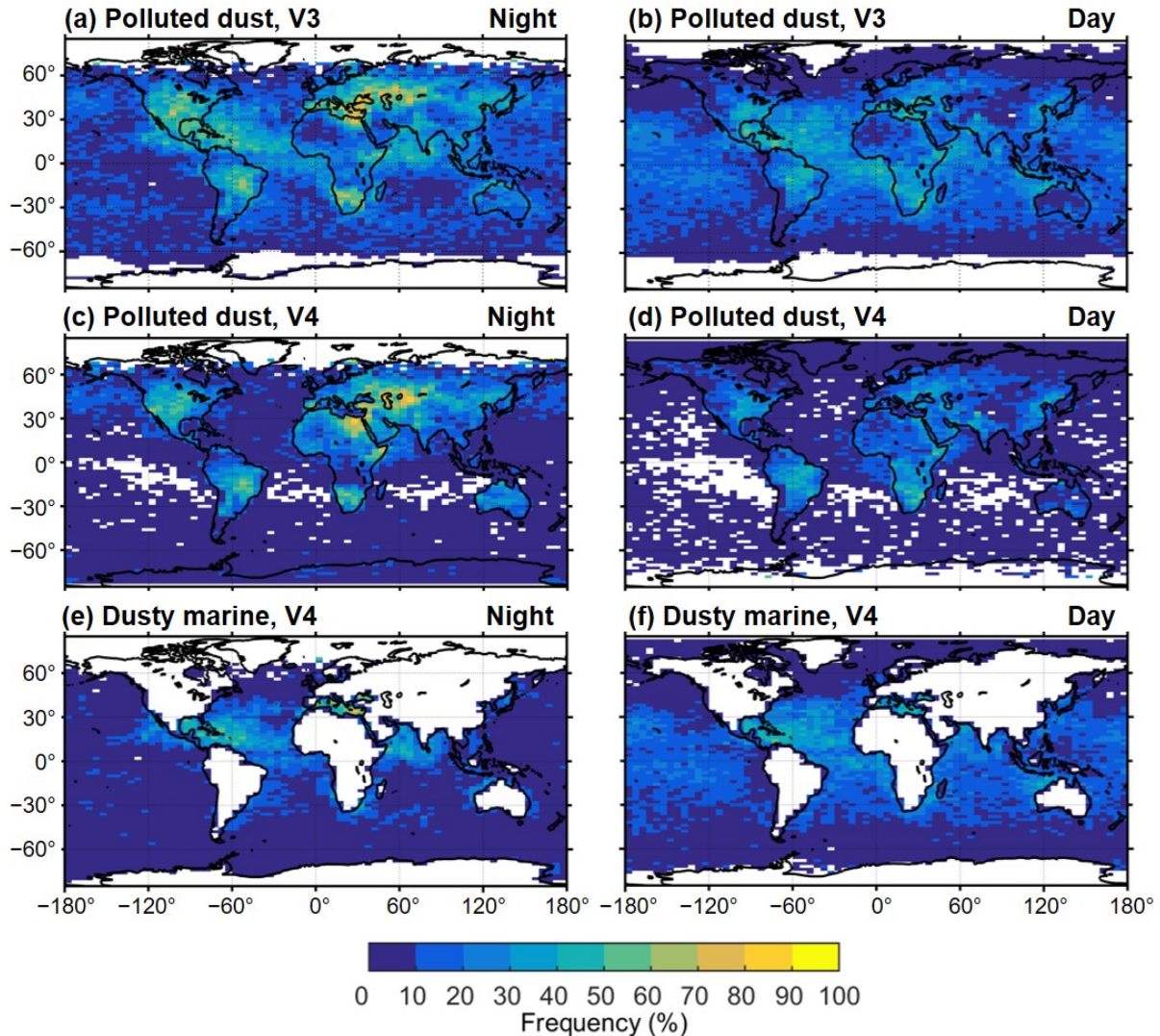


Figure 2: Frequency of occurrence of aerosol samples classified as polluted dust in V3 at night and day (a, b), polluted dust in V4 at night and day (c, d) and dusty marine in V4 at night and day (e, f). June-August 2007.

The polluted dust classification occurred in V3 because these layers are mildly depolarizing, having estimated particulate depolarization ratios (δ_p^{est}) between 0.075 and 0.20 (Omar et al., 2009). The estimated particulate depolarization ratio is layer-integrated volume depolarization ratio which is corrected to account for the molecular contribution, defined as

$$\delta_p^{est} = \frac{\delta'_v[(R_{mas}-1)(1+\delta_m)+1]-\delta_m}{(R_{mas}-1)(1+\delta_m)+\delta_m-\delta'_v}, \quad (1)$$

where δ'_v is the layer-integrated volume depolarization ratio, R_{mas} is the mean attenuated scattering ratio and δ_m is the molecular depolarization ratio (Omar et al., 2009). Here, δ'_v is defined as

$$\delta'_v = \frac{\sum_{z_{base}}^{z_{top}} [\beta'_\perp(z)]}{\sum_{z_{base}}^{z_{top}} [\beta'_\parallel(z)]}, \quad (2)$$

where z is altitude and the subscripts ‘top’ and ‘base’ refer to the top and base of the detected aerosol layer.

When a dust layer, having $\delta_p^{est} > 0.20$, mixes with non-depolarizing marine aerosol, the layer-averaged δ_p^{est} decreases below 0.20 and the aerosol is classified as polluted dust in V3. This explains the enhanced frequency of V3 polluted dust classifications over the Caribbean in JJA (Fig. 2(a)). In other oceanic regions where dust + marine or dust + smoke mixtures are less probable (again, the remote South Pacific Ocean), the frequency of polluted dust is overestimated in V3 for at least two reasons. First, δ_p^{est} is a noisy quantity that ~~has a positively skewed distribution that is exacerbated by asymmetrically distributed, with a large positively skewed tail that can be considerably increased~~ by solar background noise during the daytime. Additionally, occasional high biases can arise from residual single-shot resolution cloud contamination within the MBL. This makes the 0.075 lower δ_p^{est} threshold easier to exceed in these situations. Second, δ_p^{est} is overestimated in V3 because attenuation from overlying layers was not accounted for in the δ_p^{est} computation (Burton et al., 2013) in V3. This oversight has been corrected in V4.

To identify dust + marine aerosol mixtures in V4, dusty marine layers are defined as moderately depolarizing ($0.075 < \delta_p^{est} < 0.20$) aerosol layers over ocean having base altitudes below 2.5 km above mean sea level (an upper limit for the MBL; Winning et al., 2017). After implementation of this new aerosol subtype, the frequency of oceanic layers classified as polluted dust decreased substantially. Given that the CALIOP polluted dust subtype is explicitly modeled as a mixture of dust and smoke (Omar et al., 2009), the V4 spatial distributions of polluted dust over the Caribbean and remote Pacific Ocean shown in Figs. 2c and 2d present a more likely scenario than the V3 distributions shown in Figs 2a and 2b. 30-50 % of aerosol samples over

the Caribbean are classified as dusty marine in JJA as shown in Figs. 2(e-f). Note that the dusty marine frequency is enhanced over remote oceanic regions during the daytime (Fig. 2(f)). This is due to the noisiness of δ_p^{est} in daytime. The AOD differences from misclassifying pure marine (lidar ratio of 23 sr) as dusty marine (37 sr) are substantially less than they would otherwise be if these same layers were instead misclassified as polluted dust (55 sr).

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2.1.2 Aerosol subtypes in polar regions

As indicated in Fig. 1, the V3 aerosol classification algorithm allows only clean continental and polluted continental subtypes over the polar regions when the surface type is either snow, ice, or tundra. This was based on the assumption that the aerosol found in the polar regions – particularly in the Arctic in winter – are pollutants from industrialized areas transported poleward (Stohl, 2006; Stone et al., 2008). During the spring phase of the ARCTAS campaign (Jacob et al., 2010), however, the poleward transport of multiple plumes of Asian dust and smoke from boreal fires were observed, highlighting the importance of these other aerosol types. The contribution of smoke to the aerosol found in the Arctic – primarily from boreal forest fires and high latitude agricultural fires – is now well documented (e.g., Stohl et al., 2007; Warneke et al., 2010; Di Pierro et al., 2011; Markowicz et al., 2016). Records in polar ice and snow cores show that dust has been transported to the Arctic and Antarctic since geologic times (e.g., Lunt and Valdes, 2001; Fischer et al., 2007). While there are dust sources at high latitudes in both the northern (Alaska, Canada, Greenland, and Iceland) and southern (Antarctica, New Zealand, and Patagonia) hemispheres (Bullard et al., 2016), they are minor sources and the primary source of dust transported to the Arctic is the Asian deserts. Huang et al. (2015) investigate a large-scale dust storm that occurred in East Asia using ground-based and space-borne remote sensing measurements, NCEP/NCAR reanalysis data and a HYSPLIT trajectory analysis. They found that the dust storm was rapidly transported to the Arctic from its source region within 5 days.

Because of the recent realization of the importance of smoke and dust over the Arctic, the V4 aerosol classification algorithm no longer uses snow, ice, and tundra as decision points, but instead uses uniform aerosol typing criteria for the entire Earth (Fig. 1). As a consequence, all CALIOP aerosol subtypes may now be identified in polar regions. Figure 3 shows the dust plume reported by Huang et al. (2015). The plume is well captured by CALIOP, as shown in total attenuated backscatter (Fig. 3(a)) and depolarization ratio (Fig. 3(b)) with the white dashed ellipse. However, the V3 algorithm identifies the plume as dust/polluted dust at latitudes less than 56°N but as polluted continental/clean continental above 56°N (Fig. 3(c)). The sea surface changes from open water to ice at this point, and hence the aerosol subtyping is forced by the V3 polar region loop (Fig. 1). In V4, this plume is correctly classified as dust (Fig. 3(d)). Note too that the V3 analysis fails to detect a substantial fraction of the plume, whereas the V4 algorithm captures the whole plume well (Fig. 3(d)), thus demonstrating the layer detection improvements in V4 (Sec. 3.2).

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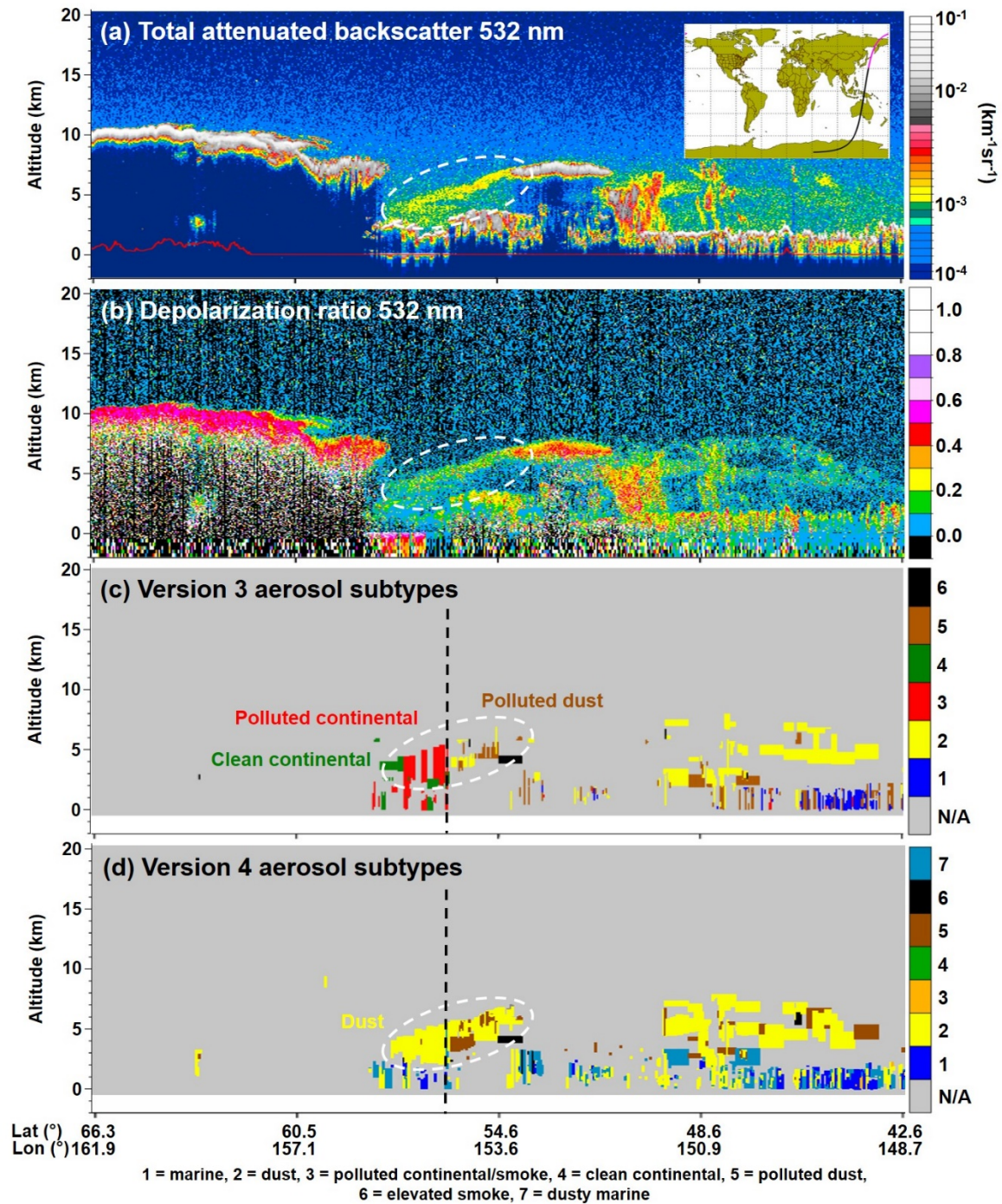


Figure 3. CALIOP observations of dust plume on March 22, 2010 between 16:11-16:25 UTC. (a) Total attenuated backscatter 532 nm, (b) depolarization ratio 532 nm, and aerosol subtypes in (c) V3 and (d) V4. White dashed ellipse shows dust plume and black dashed line represents the boundary for “snow/ice, tundra” used for polar regions in V3.

2.1.3 Revised aerosol subtype: elevated smoke and polluted continental/smoke

The interpretation and nomenclature of layers identified in V3 as smoke and polluted continental has been revised in V4. As in previous versions, elevated non-depolarizing aerosols are assumed to be smoke that has been injected above the planetary boundary layer (PBL). The definition for “elevated” is revised in V4 to mean layers with tops higher than 2.5 km above ground level (i.e., a simple approximation of a region above the PBL ([McGrath-Spangler, E. L., and Denning, 2013](#))). For clarity, the name of the smoke aerosol subtype is changed to “elevated smoke” to emphasize that these layers are identified as smoke because they are elevated above the PBL. Within the PBL, the optical properties measured by CALIOP (depolarization and color ratio) are practically identical for the smoke and polluted continental subtypes, making them indistinguishable. To acknowledge the optical similarity of polluted continental and smoke, the name of this aerosol type is changed in V4 to “polluted continental/smoke”. The V4 lidar ratios used in the CALIOP retrieval algorithm are identical for polluted continental/smoke and elevated smoke (70 sr at 532 nm and 30 sr at 1064 nm). However, one limitation of identifying smoke layers according to altitude is that pollution lofted by convective processes or other vertical transport mechanisms can be misclassified as elevated smoke.

2.2 Stratospheric aerosols

In V4, the CAD algorithm is applied at all altitudes, including in the stratosphere. By contrast, previous versions only applied the CAD algorithm below the tropopause, classifying layers detected above the tropopause as “stratospheric features” rather than as clouds or aerosols. As a consequence, aerosol existing above the tropopause was not identified explicitly as aerosol. However, it is well documented that certain aerosol types exist in the stratosphere. Volcanic eruptions inject ash and sulfate to high altitudes (e.g., Vernier et al., 2011; Bourassa et al., 2012). Smoke due to intense combustion or from pyro-cumulonimbus events can also breach the tropopause (e.g., Fromm et al., 2005; 2010; Trentmann et al., 2006). In the polar winter, polar stratospheric clouds (PSCs) form and the PSC composed of supercooled ternary solution (STS) is an aerosol (Pitts et al., 2009). In V4, features identified by the CAD algorithm as aerosol having 532 nm attenuated backscatter centroids (Garnier et al., 2015) above the tropopause from the Modern-Era Retrospective analysis for Research and Applications, Version 2 (MERRA-2) reanalysis data (Gelaro et al., 2017) outside of the polar regions are classified as “stratospheric aerosols”. Distinguishing among the different types of stratospheric aerosol relies primarily on latitude, temperature, and the measured properties of each layer: γ' and δ_p^{est} at 532 nm and ~~integrated attenuated total color ratio, χ' ; where χ' is the layer mean attenuated backscatter at 1064 nm divided by the layer mean attenuated backscatter at 532 nm (Liu et al., 2018).~~

V4 identifies four stratospheric aerosol subtypes: volcanic ash, sulfate/other, elevated smoke, and polar stratospheric aerosol (PSA). Volcanic ash is defined as an aspherical volcanic aerosol that depolarizes the 532 nm backscatter, whereas sulfate/other is defined primarily as a non-depolarizing volcanic aerosol. The “other” component of this aerosol type is the catch-all for stratospheric aerosol layers that are either weakly scattering or cannot be classified as any other type within the stratospheric aerosol algorithm. Weakly scattering layers are not evaluated by the stratospheric aerosol subtyping algorithm because the noisy values of δ_p^{est} and χ' at low signal levels inhibit robust classifications with the threshold-based technique employed. The PSA subtype is introduced in V4 to assign a reasonable aerosol type for features detected in the polar regions during polar winter, and subsequently classified as aerosol by the CAD algorithm due to their low values of χ' and γ' . Comparison with the CALIOP L2 PSC mask product shows that PSAs are spatially correlated with the STS PSC composition class (Pitts et al., 2009; Liu et al., 2018). However, layers assigned the PSA subtype should be interpreted carefully. For in-depth studies, the CALIPSO team recommends using the CALIOP L2 PSC mask product for analyses related to PSC composition since it is a more specialized product (Pitts et al., 2009).

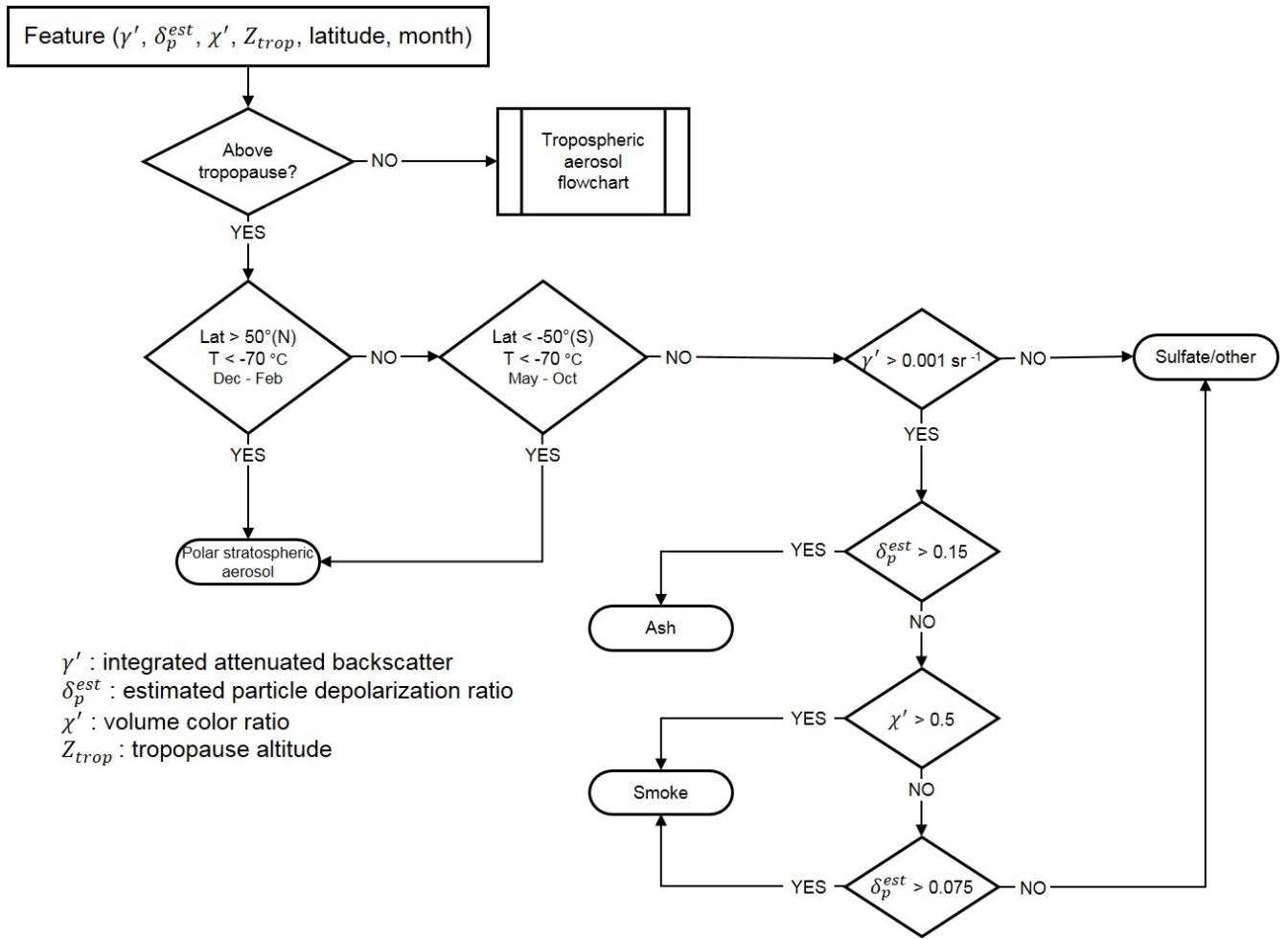


Figure 4: Flowchart of the CALIPSO aerosol subtype selection scheme for stratospheric aerosols.

The stratospheric aerosol subtyping algorithm is summarized by the flowchart in Fig. 4. PSAs are identified first by
 5 determining if the stratospheric aerosol layer's latitude, season, and temperature at its 532 nm attenuated backscatter centroid
 altitude are consistent with that of PSCs. A centroid altitude temperature threshold of -70°C is implemented based on the
 occurrence frequency distribution of aerosol mid-layer temperatures during the [Arctic and Antarctic PSC season in 2008](#) (Fig.
 5). The -70°C temperature threshold captures the increased aerosol occurrence frequency at colder temperatures,
 corresponding to PSC misclassified as aerosol (e.g., temperatures of less than -75°C corresponds to temperatures consistent
 10 with PSC formation in this region (Rosen et al., 1997)). Latitude and seasonal constraints are applied to ensure the PSA type
 is assigned where and when PSC formation occurs. PSA classification is only allowed for latitudes poleward of 50°S or N ,

and PSC seasons for the Arctic and Antarctic regions are assumed to be December – February and May – October, respectively (Poole and Pitts, 1994).

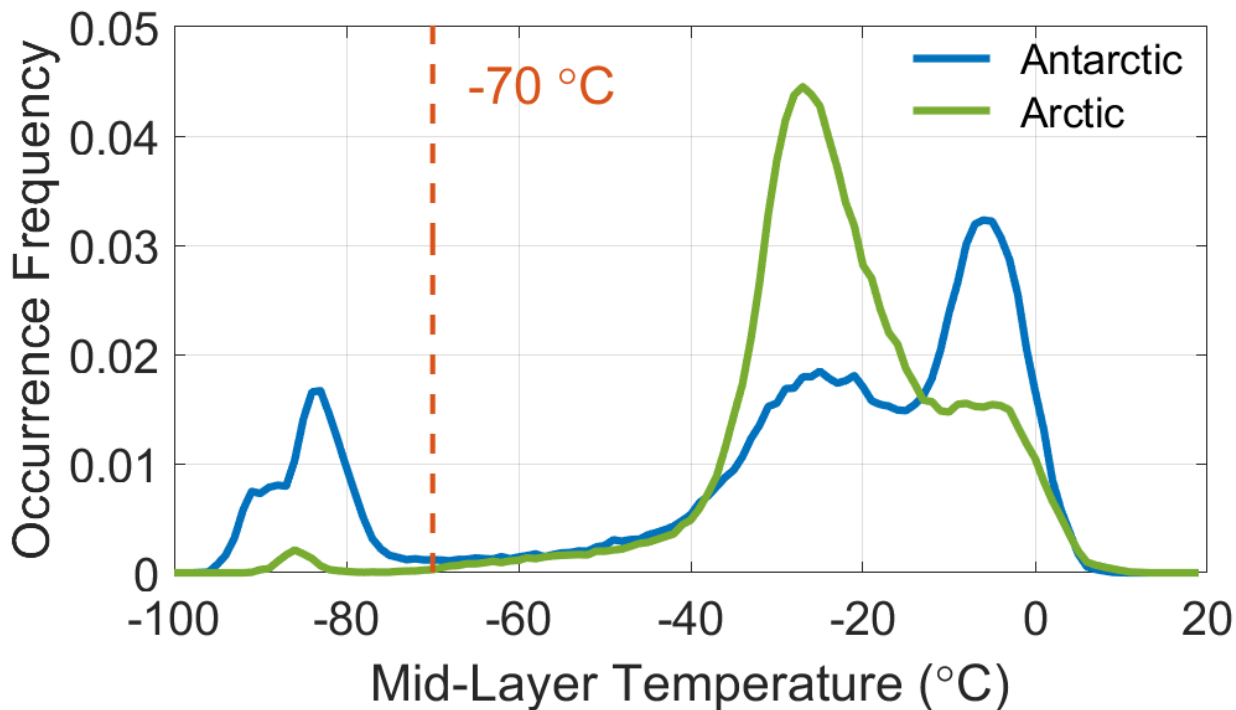


Figure 5: Occurrence frequency of mid-layer temperatures for V4 stratospheric aerosol layers south-poleward of 50°S during Antarctic-PSC season, June – September 2008 for Antarctic and December 2007 – February 2008 for Arctic at night.

Next, in order to discriminate between volcanic ash, sulfate, and elevated smoke, the stratospheric aerosol typing algorithm evaluates layer-averaged δ_p^{est} and χ' against empirically derived thresholds. These thresholds were derived from frequency distribution analysis of δ_p^{est} and χ' measurements obtained from a manually identified subset of volcanic ash, sulfate, and high-altitude smoke layers (Fig. 6). The number of unique layers detected by CALIOP, geophysical events, and dominant aerosol types contributing to this subset are summarized in Table 1. Note that, as previously mentioned, weakly scattering stratospheric aerosol layers (layers with $\gamma' < 0.001 \text{ sr}^{-1}$) are directly classified as sulfate/other due to their low signal-to-noise ratio (SNR). As shown in Figs. 6(a-c), volcanic ash and volcanic sulfate are fairly well separated with respect to δ_p^{est} , with ash typically having $\delta_p^{est} > 0.15$ and sulfate with $0.075 < \delta_p^{est} < 0.15$. Smoke layers are less depolarizing than volcanic ash (Fig. 6(d)), with $\delta_p^{est} < 0.15$. However, smoke layers can either be non-depolarizing or moderately depolarizing (Figs. 6(e-f)). An example of a moderately depolarizing smoke event is the February 2009 “Black Saturday” Australian bush fire where δ_p^{est}

exceeds 0.10 for many layers detected by CALIOP. Non-depolarizing smoke layers ($\delta_p^{est} < 0.075$) typically have $\chi' > 0.5$, whereas χ' is more frequently lower for moderately depolarizing smoke layers ($0.075 < \delta_p^{est} < 0.15$). Based on this analysis, the stratospheric aerosol typing algorithm depicted in Fig. 4 was constructed using the thresholds indicated by the red lines in Fig. 6.

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Table 1: Number of layers detected by CALIOP used to determine V4 stratospheric aerosol typing thresholds. Dominant aerosol type for volcanic events determined according to references in the table.

| N Layers | Geophysical Event | Dominant Aerosol Type |
|----------|---|--|
| 2274 | Puyehue-Cordón Caulle eruption, June 2011 | Volcanic ash (Bignami et al., 2014) |
| 69 | Okmok eruption, July 2008 | Volcanic ash (Prata et al., 2010) |
| 58 | Chaiten eruption, May 2008 | Volcanic ash (Prata et al., 2010) |
| 2439 | Kasatochi eruption, August 2008 | Volcanic sulfate (Krotkov et al., 2010) |
| 256 | Nabro, June 2011 | Volcanic sulfate (Theys et al., 2013) |
| 813 | Siberian fires, May-June 2012 | Smoke |
| 399 | Canadian fires, July-August 2007 | Smoke |
| 1624 | Australian bush fire, February 2009 | Smoke, depolarizing (de Laat et al., 2012) |
| 161 | Canadian fires, May 2007 | Smoke, depolarizing |

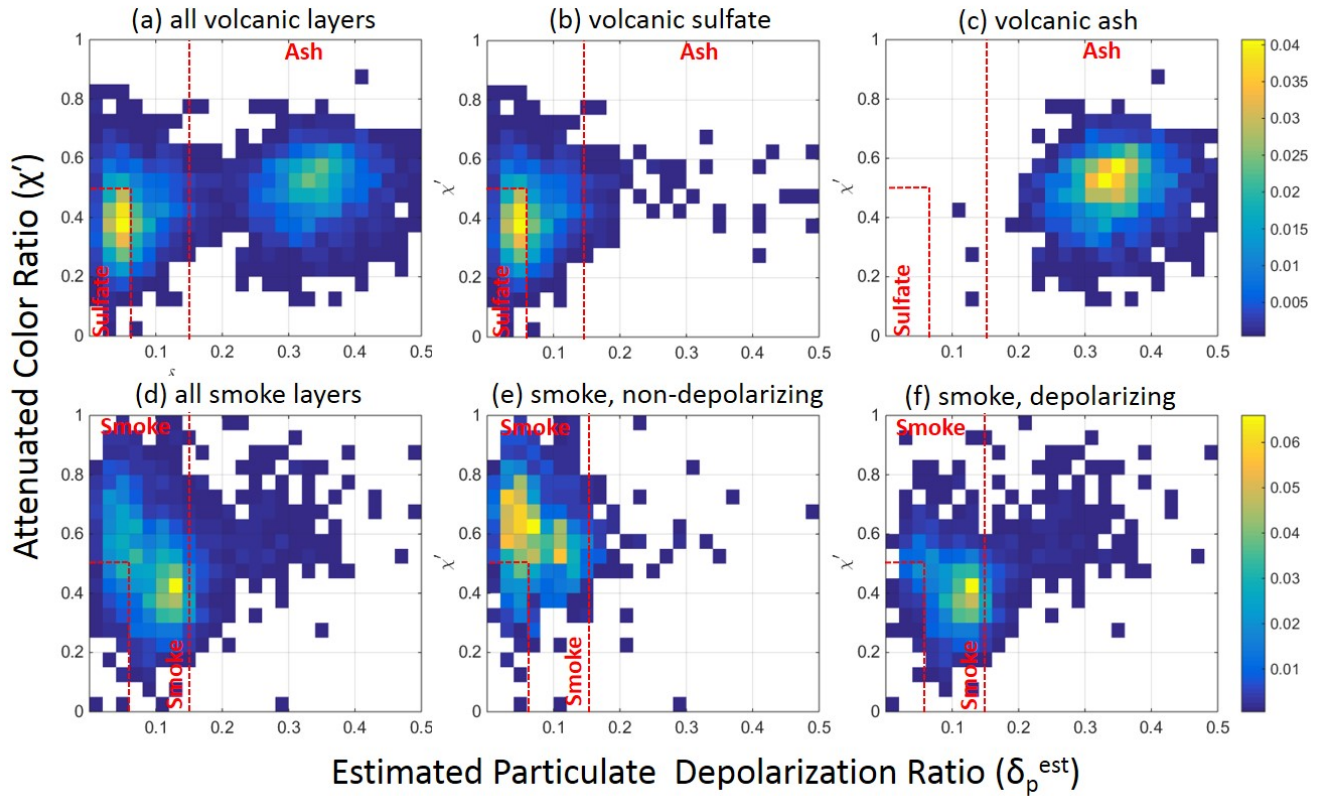


Figure 6: Two-dimensional frequency distributions of attenuated total color ratio and estimated particulate depolarization ratio for layers in Table 1. Distributions are normalized independently by the sum of samples in the subset: (a) all volcanic layers, (b) volcanic sulfate, (c) volcanic ash, (d) all smoke layers, (e) non-depolarizing smoke, and (f) depolarizing smoke. Only layers having integrated attenuated backscatter $> 0.001 \text{ sr}^{-1}$ contribute. Red dashed lines denote the V4 stratospheric aerosol typing thresholds.

The following examples demonstrate the strengths and limitations of the stratospheric aerosol typing algorithm. Volcanic ash is well-separated from the other types in terms of δ_p^{est} and χ' , which often leads to robust subtype classifications. Figure 7 shows a scene where the algorithm correctly classifies the bulk of a volcanic ash plume from the Puyehue-Cordón Caulle eruption in June 2011. Though the northern-most layers near 42° - 45° S are automatically classified as sulfate/other due to their low γ' , these layers are optically thin and the more optically thick layers of the ash plume are classified correctly. Also note that portions of the ash plume having backscatter centroids below the tropopause are misclassified as dust. This occurs because aerosol layers below the tropopause are assigned tropospheric aerosol subtypes which do not include ash. Because the noise-broadened distributions of δ_p^{est} for ash and dust measured by CALIOP have very similar characteristics, we know of no robust way to discriminate the two within the troposphere (Winker et al., 2012). However, the lidar ratio assigned for ash is identical to that for dust (Table 2) so potential misclassifications will have minimal impact on the extinction products.

Figure 8 presents a scene where the bulk of the Nabro volcano plume from June 2011 (Theys et al., 2013) is correctly classified as sulfate. In this example, most of the layer has $\gamma' > 0.001$ and low depolarization, yielding a sulfate classification for the more optically-thick segments. However, a small number of layers within the plume are misclassified as smoke. This is expected because of the overlap in the frequency distributions of δ_p^{est} and χ' for sulfate (Fig. 6(b)) and smoke (Fig. 6(d)). The optical properties used for these two types are not as well separated from each other as they are from volcanic ash, so some misclassifications can occur. Additionally, volcanic sulfate within the troposphere will be assigned a tropospheric aerosol type, usually elevated smoke or clean continental if weakly scattering. The last example in Fig. 9 shows an observation of a depolarizing smoke plume from the Black Saturday Australian bush fire in February 2009 (Pumphrey et al., 2011; de Laat et al., 2012). The majority of the plume above the tropopause is correctly classified as smoke, with the minority misclassified as ash due to δ' exceeding 0.15. The remainder of the plume below the tropopause is misclassified as dust and polluted dust, again due to elevated depolarization. In all of these examples, the V3 data products classified the layers detected above the tropopause as a generic 'stratospheric layer' without applying any further subtyping. In V4, these same layers are most often correctly classified as aerosols by the new CAD algorithm (Liu et al., 2018). Similarly, the new stratospheric aerosol subtyping algorithm is largely successful in identifying the correct aerosol subtype.

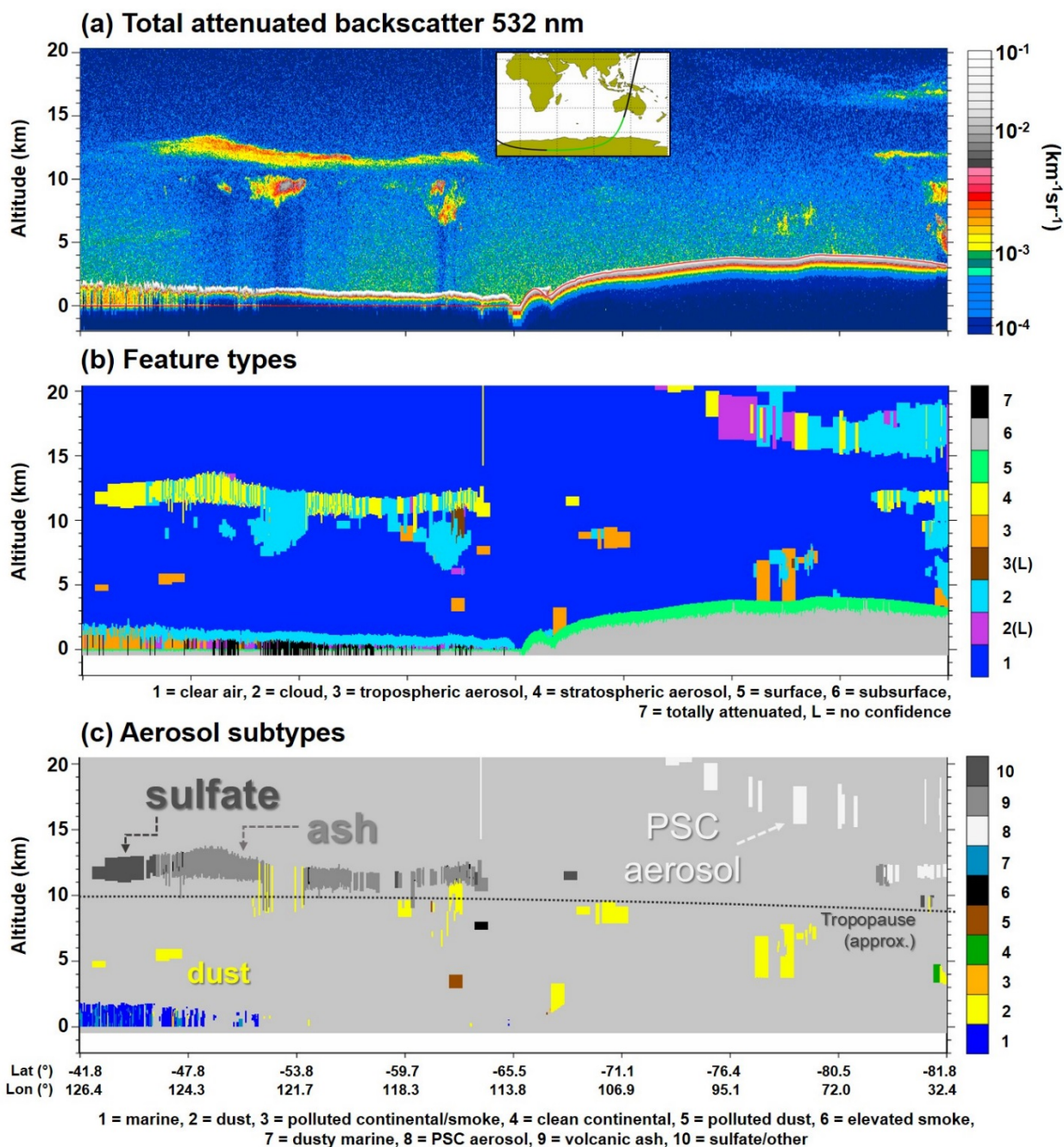


Figure 7: CALIOP observations of the Puyehue-Cordón Caulle volcano plume on June 20, 2011 between 16:50-17:00 UTC. (a) Total attenuated backscatter 532 nm, (b) V4 feature type classification, and (c) V4 aerosol subtypes, where the dashed line indicates the approximate location of the tropopause. The satellite ground track is indicated by the green section on inset map in panel (a). [Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at](#)

https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2011-06-20&orbit_time=16-22-13&page=3&granule_name=CAL_LID_L1-Standard-V4-10.2011-06-20T16-22-13ZN.hdf

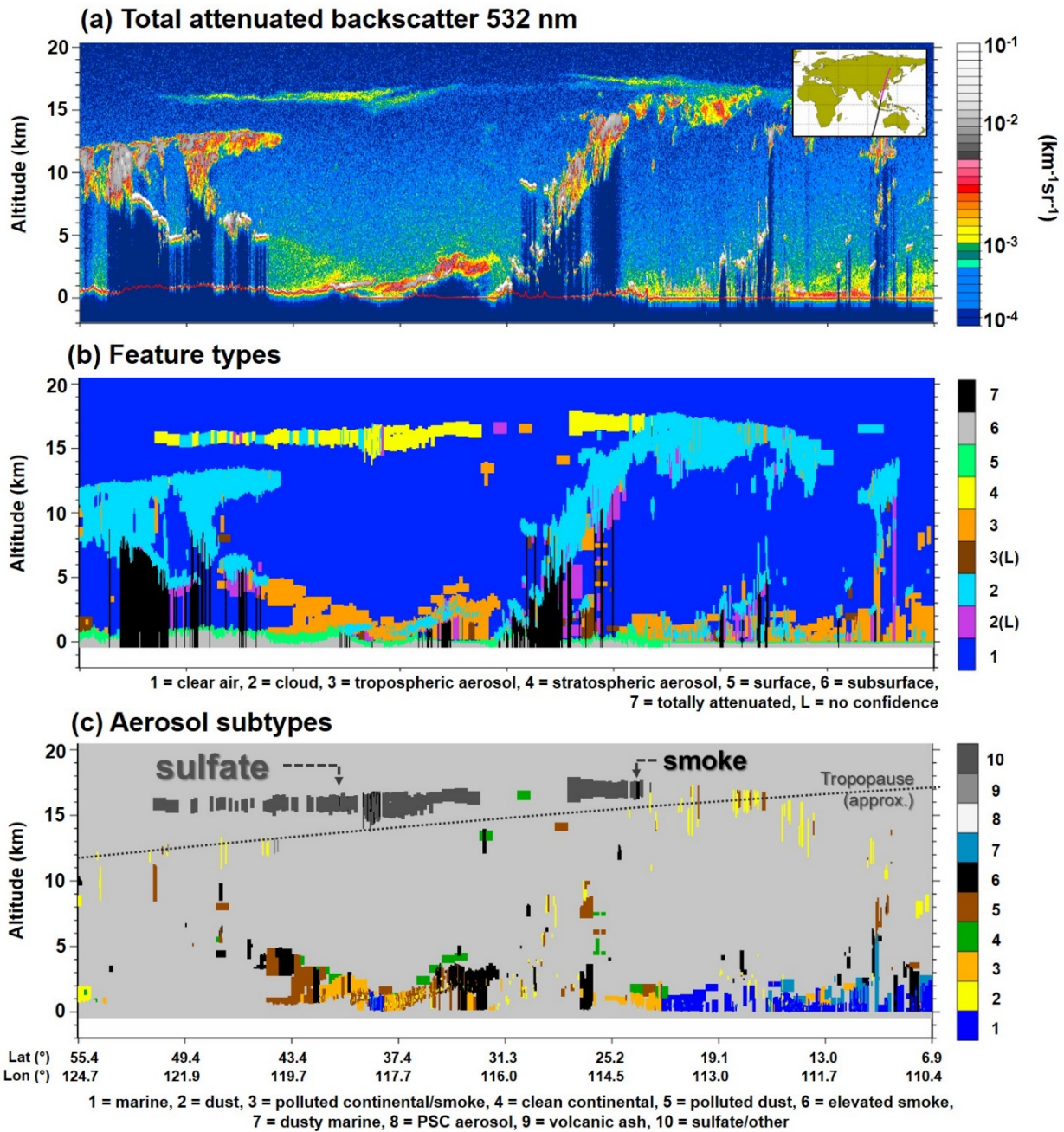


Figure 8: CALIOP observations of the Nabro volcano plume on June 18, 2011 between 18:13-18:26 UTC. (a) Total attenuated backscatter 532 nm, (b) V4 feature type classifications, and (c) V4 aerosol subtypes; dashed line indicates approximate location of the tropopause. The satellite ground track is indicated by the magenta section on inset map in panel (a). [Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2011-06-18&orbit_time=18-13-27&page=1&granule_name=CAL_LID_L1-Standard-V4-10.2011-06-18T18-13-27Z.hdf](https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2011-06-18&orbit_time=18-13-27&page=1&granule_name=CAL_LID_L1-Standard-V4-10.2011-06-18T18-13-27Z.hdf)

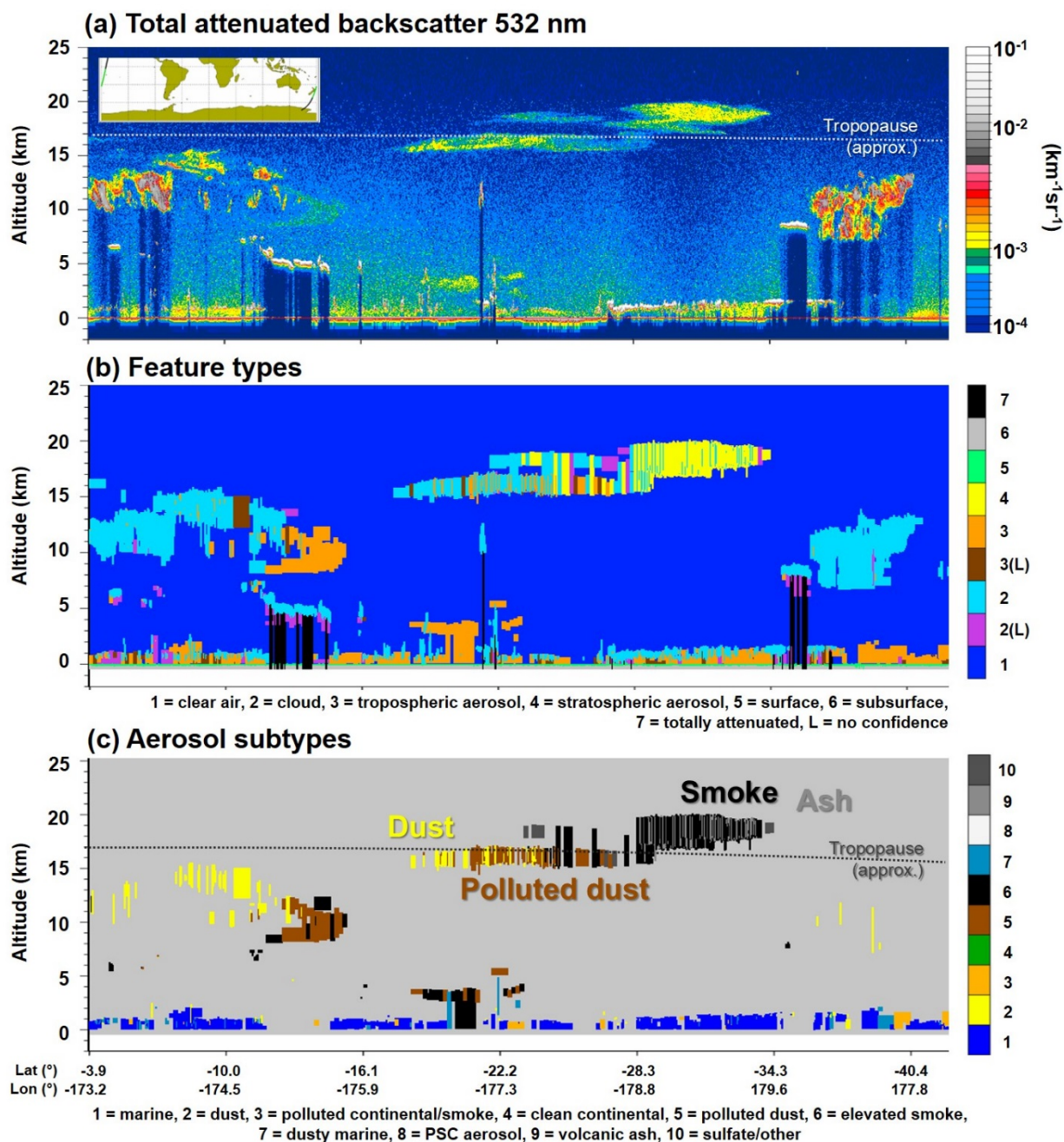


Figure 9: CALIOP observations of smoke plumes from the Australian bush fire on February 15, ~~2009~~ 2012 between 13:19-13:32 UTC. (a) Total attenuated backscatter 532 nm, (b) V4 feature type classification, and (c) V4 aerosol subtypes, where the dashed line indicates the approximate location of the tropopause. The satellite ground track is indicated by green section on inset map in panel (a). Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found

2.3 Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF)

- 5 In previous data releases~~releases~~, “fringes” at the bases of dense aerosol plumes were at times misclassified as an aerosol subtype inconsistent with the parent plume. These fringes typically lie below rapidly attenuating aerosol layers, and are detected at ~~20 km or 80 km horizontal resolution~~the coarser horizontal resolutions (20 km and 80 km) employed by CALIOP’s iterated, multi-resolution layer detection scheme (Vaughan et al., 2009). An example is shown in Figs. 10(a-b), where fringes at the base of an elevated smoke plume are misclassified as clean marine aerosol. In this case, the fringes are misclassified
- 10 because the layers are non-depolarizing and have top altitudes just below the 2.5 km altitude threshold that would have otherwise caused them to be correctly classified as elevated smoke according to the revised definition of “elevated” in V4 (Sect. 2.1.3). Given that this is an elevated plume not in contact with any aerosol beneath, it is reasonable to expect that the misclassified fringes at the base of the plume have the same aerosol subtype as the adjacent smoke layers. This same argument can be made for other aerosol types that contiguously span large horizontal distances (e.g., dust plumes, marine aerosol,
- 15 volcanic ash, and volcanic sulfate).

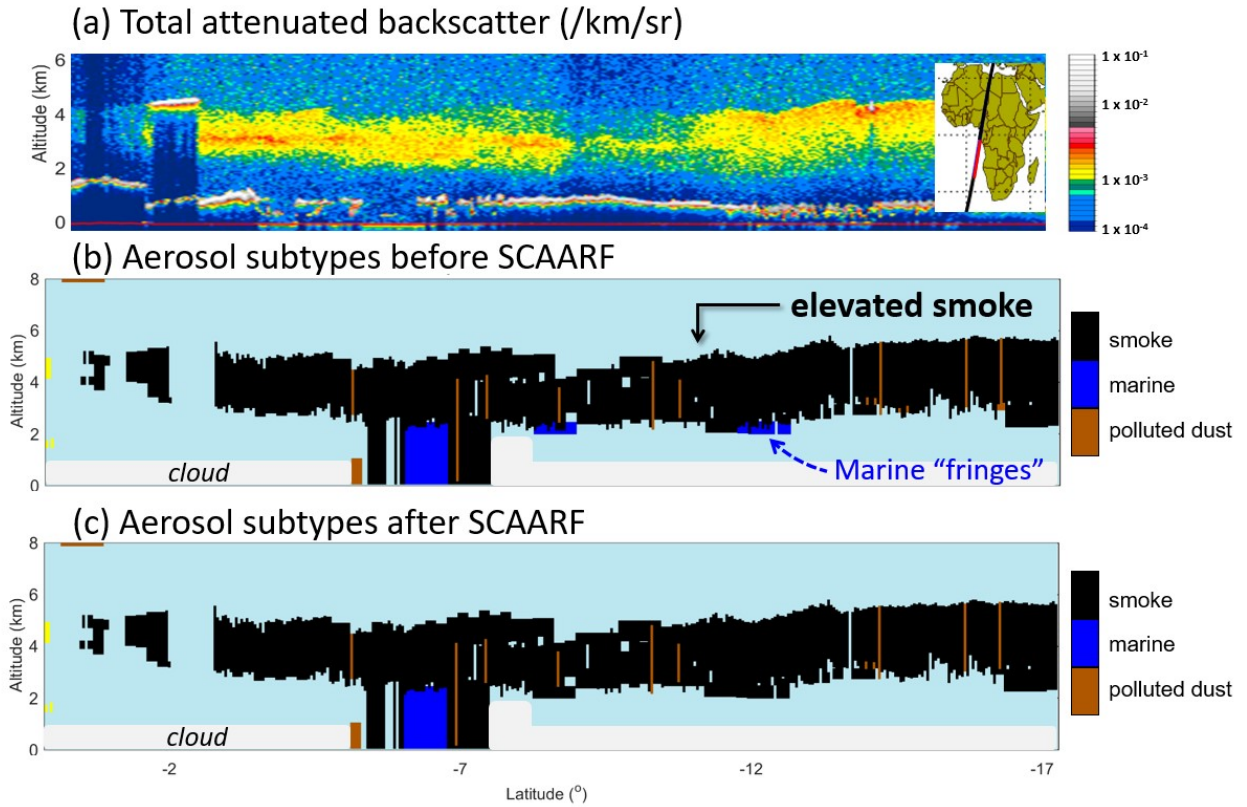


Figure 10: CALIOP observations of a smoke plume off the west coast of Africa on September 14, 2008 from approximately 1:08 to 1:10 UTC. (a) Total attenuated backscatter 532 nm and aerosol subtype classification (b) before and (c) after SCAARF is implemented. Inset map in panel (a) shows CALIOP ground track shown in red. Aerosol subtypes: elevated smoke (black), clean marine (blue), polluted dust (brown).

In general, aerosol layers detected by CALIOP that are in contact with other aerosol layers are assumed to be of the same aerosol type. For this reason, V4 implements the Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF), which reclassifies the aerosol subtype of these lower fringes to match the dominant subtype of the adjacent overlying layers. According to SCAARF, fringes are defined as aerosol layers detected at 20 km or 80 km horizontal resolutions that are vertically adjacent to the base(s) of aerosol layers detected at finer spatial resolution (i.e., they are adjacent to more strongly scattering features). At least 50 % of the horizontal extent of the fringe candidate must be in contact with aerosol overhead. SCAARF is applied to all tropospheric and stratospheric aerosol layers meeting this “fringe” criteria. The dominant adjacent aerosol subtype is determined from the number of 5 km resolution samples vertically adjacent to the fringe. When two adjacent aerosol subtypes exist with equal frequency (i.e., neither is dominant in terms of number), the fringe is changed to match the subtype of the adjacent layers that are most similar to the fringe in terms of δ_p^{est} and χ' . This is the subtype with the minimum Euclidian distance r_i between $\bar{\delta}_p^{est}$ and $\bar{\chi}'$ of the parent and δ_p^{est} and χ' of the fringe; i.e.,

$$r_i = \sqrt{(\delta_{p,fringe}^{est} - \bar{\delta}_{p,subtype\ i}^{est})^2 + (\chi'_{fringe} - \bar{\chi}'_{subtype\ i})^2}, \quad \text{for } i \in [1, 2]. \quad (3)$$

Here, $\bar{\delta}_{p,subtype\ i}^{est}$ and $\bar{\chi}'_{subtype\ i}$ are the average values of δ_p^{est} and χ' for all adjacent layers having unique subtypes $i \in [1, 2]$.

- 5 The fringe is changed to match subtype i where $r_i = \text{minimum}(r_1, r_2)$. If three or more unique subtypes are adjacent to the fringe with equal frequency, SCAARF is not applied.

In effect, SCAARF aids in vertically homogenizing aerosol subtype classification along plume bases. Figure 10(c) demonstrates that the fringes misclassified as clean marine have been correctly classified as elevated smoke after SCAARF is implemented. Similar improvement occurs for volcanic ash layers straddling the tropopause. Lower fringes of these plumes below the tropopause would otherwise be misclassified as dust (Sect. 2.2), yet SCAARF helps retain the volcanic ash classification.

2.4 Aerosol lidar ratios in version 4

- 15 Table 2 shows the lidar ratios that characterized the V3 aerosol types, and the revised values used in V4 for tropospheric aerosols and the newly introduced stratospheric aerosols. Except for polluted continental and polluted dust, V4 aerosol lidar ratios have been updated to reflect the improved knowledge from measurements reported in recent literature. In addition, lidar ratios have been defined for the new aerosol types: dusty marine and the stratospheric aerosol types. The modifications and new lidar ratios are based on the latest available measurements, both from CALIPSO and from other researchers and field measurements campaigns.

Table 2: Aerosol lidar ratios with expected uncertainties for tropospheric and stratospheric aerosol subtypes at 532 nm and 1064 nm in CALIOP version 3 and 4 aerosol retrieval algorithms.

| Aerosol subtype | S_{532} (sr) | | S_{1064} (sr) | |
|------------------------------|-----------------------|-------------|-----------------|-------------|
| | Tropospheric aerosols | | | |
| | V3 | V4 | V3 | V4 |
| Clean marine | 20 ± 6 | 23 ± 5 | 45 ± 23 | 23 ± 5 |
| Dust | 40 ± 20 | 44 ± 9 | 55 ± 17 | 44 ± 13 |
| Polluted continental / smoke | 70 ± 25 | 70 ± 25 | 30 ± 14 | 30 ± 14 |
| Clean continental | 35 ± 16 | 53 ± 24 | 30 ± 17 | 30 ± 17 |
| Polluted dust | 55 ± 22 | 55 ± 22 | 48 ± 24 | 48 ± 24 |
| Elevated smoke | 70 ± 28 | 70 ± 16 | 40 ± 24 | 30 ± 18 |

| | | | | |
|----------------------------------|---|---------|---|---------|
| Dusty marine | - | 37 ± 15 | - | 37 ± 15 |
| V4 Stratospheric aerosols | | | | |
| Polar stratospheric aerosol | | 50 ± 20 | | 25 ± 10 |
| Volcanic ash | | 44 ± 9 | | 44 ± 13 |
| Sulfate / other | | 50 ± 18 | | 30 ± 14 |
| Smoke | | 70 ± 16 | | 30 ± 18 |

2.4.1 Clean marine

The lidar ratio and uncertainties for clean marine aerosol are modified from 20 ± 6 sr in V3 to 23 ± 5 sr at 532 nm in V4. This change is consistent with results reported from numerous field campaigns since the launch of CALIPSO. Papagiannopoulos et al. (2016) report lidar ratio of 23 ± 3 sr for marine aerosol from the European Aerosol Research Lidar Network (EARLINET), based mainly on multi-wavelength Raman lidar systems. Müller et al. (2007) also show that mean lidar ratio for marine aerosols in the PBL is 23 ± 3 sr from the Second Aerosol Characterization Experiment (ACE 2) and 23 ± 5 sr from the Indian Ocean Experiment (INDOEX). In an analysis of collocated HSRL measurements acquired during dedicated CALIPSO underflights, Rogers et al. (2014) find that the median lidar ratio for layers identified as marine aerosol is 23 sr. [Haarig et al. \(2017b\)](#) observed lidar ratios for marine aerosols as a function of relative humidity with a multi-wavelength polarization Raman lidar and found that the 532 nm lidar ratios increased from 23 sr for spherical sea salt particles to 25 sr for cubic-like particle ensembles.

With respect to marine lidar ratios at 1064 nm, Josset et al. (2012) applied the Synergized Optical Depth of Aerosols (SODA) technique (Josset et al., 2011) to CALIOP measurements at both 532 nm and 1064 nm, and found no spectral dependence in the retrieved lidar ratios. Similarly, Sayer et al. (2012) calculate lidar ratios for marine aerosols from AERONET island sites, spread throughout the world's oceans, and find little spectral dependence. Based on these studies, the CALIOP lidar ratio for clean marine at 1064 nm is changed from 45 ± 23 sr in previous versions to 23 ± 5 sr, which is same value used at 532 nm in V4.

2.4.2 Dust

There are multiple studies reporting dust lidar ratios larger than 40 ± 20 sr at 532 nm, the value used in previous versions of CALIOP algorithm (e.g., Liu et al., 2002; Müller et al., 2007; Wandinger et al., 2010; Schuster et al., 2012; Papagiannopoulos et al., 2016; [Haarig et al., 2017a](#)). Liu et al. (2015) derive dust lidar ratio directly from the CALIOP measurements using a constrained opaque water cloud technique (Hu, 2007) and find mean/median lidar ratios of $45.1/44.4 \pm 8.8$ sr for moderately

dense Sahara dust layers. Furthermore, from measurements of ground-based Raman lidars and airborne HSRL, no wavelength dependence of dust lidar ratio is found among 355, 532, and 1064 nm (Teschke et al., 2009). Based on these studies, dust lidar ratios in V4 are modified to 44 ± 9 sr at 532 nm and 44 ± 13 sr at 1064 nm. Though lidar ratios for dust show regional variability ranging mostly from 35 to 60 sr (Cattrall et al., 2005; Schuster et al., 2012; Mamouri et al., 2013; Nisantzi et al., 2015), only a single value is used in the V4 algorithm. Implementing a regionally varying lidar ratio for dust is complicated due to uncertainties in determining the dust source regions for transported dust, and introducing unnatural discontinuities in global dust AOD. The uncertainty in V4 dust lidar ratio of 20 % (30 %) at 532 nm (1064 nm) accounts for the regional variability.

2.4.3 Polluted continental and elevated smoke

Polluted continental lidar ratios at 532 nm and 1064 nm are unchanged from V3 to V4, at 70 ± 25 sr and 30 ± 14 sr respectively. For elevated smoke, the 532 nm lidar ratio is the same in both versions, but, based on a study by Liu et al. (2015), the uncertainty is reduced from 70 ± 28 sr in V3 to 70 ± 16 sr in V4. The lidar ratio at 1064 nm for elevated smoke is changed from 40 ± 24 sr in V3 to 30 ± 14 sr in V4 (Sayer et al., 2014), so that the V4 value for smoke now matches that of polluted continental. Elevated smoke detected in the stratosphere also uses these same lidar ratios.

2.4.4 Clean continental

In V3, the lidar ratios used for the clean continental subtype were 35 ± 16 sr at 532 nm and 30 ± 17 sr at 1064 nm. The 532 nm value is generally consistent with the background aerosol lidar ratios being reported in the literature available at the start of the mission (e.g., Voss et al., 2001; Ansmann et al., 2001). However, in an extensive CALIPSO validation study, Rogers et al. (2014) found that the mean 532 nm lidar ratio measured by the LaRC HSRL in layers identified by CALIOP as clean continental was 53 ± 11 sr. In V4, the 532 nm lidar ratio for clean continental aerosols is therefore changed to 53 ± 11 sr. Because the LaRC HSRL only measures lidar ratio at 532 nm, no additional information on lidar ratios at 1064 nm is available from Rogers et al. (2014). Consequently, the V4 lidar ratio for clean continental aerosol at 1064 nm remains unchanged from V3.

2.4.5 Polluted dust and dusty marine

Validation with MODIS and airborne HSRL measurements show that CALIOP V3 AODs and lidar ratios appear to be biased high for layers in some regions which are classified as polluted dust (Kim et al., 2013; Burton et al., 2013; Rogers et al., 2014). This is especially true over the ocean. Since CALIOP V3 did not account for mixtures of dust and sea salt which are frequent in the MBL, the bias is likely a result of dust + marine misclassified as dust + smoke. For this reason, the lidar ratios for

polluted dust remains same in V4 as in V3, and a new aerosol subtype, dusty marine, is introduced to reflect the correct mixture. The lidar ratios for polluted dust are unchanged from their V3 values, at 55 ± 22 sr at 532 nm and 48 ± 24 sr at 1064 nm. Based on an assumed external mixture of dust and marine aerosol ([mixing ratio of 65:35](#) by surface area), the lidar ratios for dusty marine are 37 ± 15 sr at both wavelengths using mean lidar ratios of 44 sr and 23 sr for pure dust and clean marine, respectively.

5 Using the NASA HSRL in the MBL in the Caribbean region, Rogers et al. (2014) found lidar ratios of 37 ± 11 sr for mixtures of dust and marine aerosols. As is the case for both dust and marine, the lidar ratios for dusty marine combination are spectrally independent. However, the lidar ratio uncertainties ascribed to the dusty marine type are larger than either dust or marine alone. The range of uncertainty of the dusty marine lidar ratio in V4 (15 sr) is greater than the uncertainty for these mixtures in Rogers et al. (2014) and accounts for a large range of possible surface area mixing ratios of dust and marine aerosols in the ambient

10 MBL.

2.4.6 Volcanic ash

Default lidar ratios for volcanic ash are set in V4 to match that of the dust subtype: 44 ± 9 sr at both 532 nm and 1064 nm. These lidar ratios were selected following Winker et al. (2012), where it is shown that the size distribution, composition, and

15 shape of transported volcanic ash particles are similar to desert dust. This was based on comparisons of in-situ aircraft measurements by Schumann et al. (2011) during the April 2010 Eyjafjallajökull volcano eruption and Saharan dust properties described by Omar et al., (2010). In reality, lidar ratios for volcanic ash vary depending on the composition of the plume and circumstances of the eruption (water vapor content, mineralogy, plume age, injection height, etc.). Recent studies have found higher lidar ratios for volcanic ash (Table 3). For example, lidar ratios of 50 ± 10 sr were retrieved for volcanic ash transported

20 over Europe during the April 2010 Eyjafjallajökull volcano eruption (Ansmann et al., 2011; Groß et al., 2012), with mean lidar ratios of 60 ± 5 sr at Leipzig on 16 April 2010 (Ansmann et al., 2010). Recently, Prata et al. (2017) used constrained CALIOP retrievals to estimate mean particulate lidar ratios of 69 ± 13 sr for volcanic ash from the June 2011 Puyehue-Cordón Caulle eruption. The results of these studies suggest that 44 sr is likely near the lower limit of natural variability. Given the large variability in lidar ratios for volcanic ash and the evolving state of knowledge, the CALIPSO team is further studying the

25 representativeness of this lidar ratio based on information gained since the 2016 release of the version 4 level 2 products.

Table 3: Mean 532 nm lidar ratios reported in the literature for volcanic ash and volcanic sulfate.

| Mean lidar ratio (532 nm) | Volcanic Eruption | Reference |
|---------------------------|-----------------------------|---|
| Ash dominant aerosol | | |
| 50 ± 10 sr | Eyjafjallajökull, 2010 | Ansmann et al., 2011; Groß et al., 2012 |
| 60 ± 5 sr | Eyjafjallajökull, 2010 | Ansmann et al., 2010 |
| 69 ± 13 sr | Puyehue-Cordón Caulle, 2011 | Prata et al., 2017 |

| Sulfate dominant aerosol | | |
|--------------------------|--------------------------------------|-------------------------|
| 30 – 50 sr | Kasatochi, 2008; Sarychev Peak, 2009 | Mattis et al., 2010 |
| 48 sr | Nabro, 2011 | Sawamura et al., 2012 |
| 55 sr | Mt. Etna, 2002 | Pappalardo et al., 2004 |
| 55 ± 4 sr | Sarychev Peak, 2009 | O'Neill et al., 2012 |
| 63 ± 14 sr | Sarychev Peak, 2009 | Prata et al., 2017 |
| 65 ± 10 sr | Kasatochi, 2008 | Hoffmann et al., 2010 |
| 66 ± 19 sr | Kasatochi, 2008 | Prata et al., 2017 |

2.4.7 Sulfate/other

Default lidar ratios for sulfate/other are 50 ± 18 sr and 30 ± 14 sr at 532 nm and 1064 nm, respectively. Researchers have previously reported independent lidar measurements of sulfate-rich volcanic plumes from Mt. Etna 2002, Kasatochi 2008, Sarychev Peak 2009, and Nabro 2011 eruptions, summarized in Table 3. Lidar ratios from these studies range from 30 – 66 sr, with CALIOP-constrained lidar ratio retrievals reported by Prata et al. (2017) on the high end: 63 ± 14 sr and 66 ± 19 sr for the Kasatochi and Sarychev Peak eruptions, respectively. The 532 nm lidar ratio for sulfate is consistent with these studies given the variability of measured lidar ratios and the 35 % uncertainty implemented with the default lidar ratio, yielding 50 ± 18 sr. Independent measurements of 1064 nm lidar ratios for volcanic sulfate are sparse in the literature. The default lidar ratio value of 30 sr, however, is consistent with Jäger and Hofmann (1991) which reported measured background stratospheric aerosol levels of 35 sr and 39 sr for years 1979-1980 and 1986-1987, respectively. The 1064 nm lidar ratio is also consistent with that of the CALIOP model for polluted continental aerosol which is, in part, modelled after sulfate (Omar et al., 2009).

2.4.8 Polar stratospheric aerosol

Default lidar ratios for PSA are 50 ± 20 sr at 532 nm and 25 ± 10 sr at 1064 nm. As discussed in Sect. 2.3, these aerosol layers exhibit a qualitative spatial correlation with the supercooled ternary solution (STS) composition class in the CALIPSO level 2 PSC mask product. These lidar ratios and their wavelength dependence are consistent with theoretical Mie scattering calculations for STS droplets at pressures typical of the Arctic stratosphere.

3 Aerosol subtyping changes from version 3 to version 4

The performance and final results delivered by the V4 aerosol subtyping algorithm are affected by V4 changes to several other algorithms that occur earlier in the level 2 processing scheme. The CALIOP V4 level 1 data significantly improved the

calibration of the CALIOP attenuated backscatter coefficients (β') at both 532 nm and 1064 nm (Getzewich et al., 2018; Kar et al., 2018; Vaughan et al., 2018a). In particular, calibration coefficients at 532 nm decreased by $\sim 3\%$ to $\sim 12\%$, depending on latitude and season, resulting in a concomitant increase in β' at 532 nm. The increased magnitude of β' at 532 nm subsequently yields an increase in the number of tenuous layers detected by the CALIOP feature finder. The V4 CAD algorithm features entirely new probability distribution functions (PDFs) that are now more sensitive to the presence of lofted aerosols (Liu et al., 2018). As a consequence, the V4 data products show improvements in the identification of high altitude smoke plumes and Asian dust layers, which in earlier versions were often classified as cirrus clouds. Also, the V4 analyses use a completely new algorithm to detect the Earth's surface detection (Vaughan et al., 2018b). This new technique demonstrates an improvement over the V3 method in turbid atmospheres, while maintaining equal or better performance in clear skies. As a result of this improved surface detection scheme, there are fewer opaque layers identified in V4 than there were in V3, especially at night. Because regions below layers previously classified as opaque are now scanned for the presence of atmospheric features, there is also a slight increase in the number of cloud and aerosol layers reported. Taken together, these changes yield an increase in the absolute number of layers classified as aerosols in V4 relative to V3.

The feature type changes from/to aerosol, aerosol subtypes changes, and resulting AOD changes between V3 and V4 are analyzed using the atmospheric volume description (AVD) reported in level 2 aerosol profile product. AVD reports both feature type and aerosol/cloud subtype for each 5 km x 60 m (5 km x 180 m for above 20.2 km) range bin. The feature types include clear air, cloud, tropospheric aerosol, stratospheric feature/aerosol (V3/V4, respectively), surface, subsurface, and totally attenuated regions (i.e., beneath layers classified as opaque in V3 but reclassified as transparent in V4). Table 4 shows changes in feature type and aerosol subtype between V3 and V4 using the AVD data in the level 2 profile products. Though the table contains all changes among feature types and aerosol subtypes, in this study we focus solely on changes in the distribution of aerosol subtypes and the downstream effects of these changes in the global and regional distributions of AOD.

Table 4: Feature type and aerosol subtype changes in the CALIOP level 2 atmospheric volume description (AVD) between version 3 (V3) and version 4 (V4) from 2007 to 2009. Each (i,j) component of the Table represents what fraction (expressed as a percentage) of type i in V3 changes to type j in V4, thus the summation of each column equals to 100 (%). Since the total number of each type is different, relative total amounts for each type are shown as normalized total for both columns and rows which are normalized to total number of bins for V3 aerosol.

| V4 \ V3 | Total Atten. | Clear | Cloud | Surface | Aerosol | CM* | Dust | PC* | CC* | PD* | Smoke | Strato. Feature | Normalized Total |
|-----------------------|---------------------|--------------|--------------|----------------|----------------|--------------|--------------|--------------|--------------|--------------|--------------|------------------------|-------------------------|
| Total Atten. | 84.30 | 0.03 | 1.42 | 12.98 | 0.09 | 0.13 | 0.06 | 0.06 | 0.01 | 0.11 | 0.02 | 0.00 | 2.09 |
| Clear | 7.14 | 98.97 | 1.92 | 7.81 | 6.28 | 4.43 | 4.99 | 8.88 | 14.87 | 7.10 | 8.61 | 4.11 | 34.18 |
| Cloud | 3.49 | 0.34 | 92.39 | 7.76 | 6.99 | 5.35 | 4.64 | 9.59 | 11.56 | 7.85 | 13.29 | 61.56 | 3.08 |
| Surface | 3.68 | 0.03 | 0.23 | 56.45 | 0.35 | 0.15 | 0.51 | 0.70 | 0.38 | 0.43 | 0.35 | - | 0.17 |
| Tropo. Aerosol | 1.40 | 0.48 | 3.76 | 15.00 | 85.22 | 89.94 | 89.78 | 80.66 | 63.86 | 84.37 | 70.90 | 0.30 | 1.18 |

| | | | | | | | | | | | | | |
|-----------------------------|-------------|-------------|-------------|-------|--------------|-------------|-------------|-------------|-------------|-------------|-------------|--------------|-------------|
| CM* | 0.35 | 0.10 | 0.50 | 10.63 | 33.78 | 80.83 | 0.40 | 21.99 | 11.60 | 6.15 | 0.12 | - | 0.41 |
| Dust | 0.35 | 0.09 | 1.68 | 0.90 | 17.16 | 0.19 | 73.25 | 1.74 | 5.02 | 6.63 | 0.89 | 0.10 | 0.26 |
| PC*/ Smoke | 0.08 | 0.04 | 0.18 | 0.84 | 5.66 | 0.93 | 0.48 | 33.08 | 9.69 | 5.20 | 18.13 | - | 0.08 |
| CC* | 0.01 | 0.02 | 0.02 | 0.11 | 0.66 | 0.00 | 0.05 | 0.58 | 8.82 | 0.54 | 0.65 | 0.02 | 0.01 |
| PD* | 0.16 | 0.11 | 0.75 | 0.66 | 10.81 | 0.02 | 10.45 | 5.45 | 11.26 | 32.36 | 6.94 | 0.07 | 0.17 |
| Elev. Smoke | 0.15 | 0.07 | 0.36 | 0.11 | 7.53 | 4.09 | 0.27 | 11.60 | 10.17 | 4.72 | 43.67 | 0.11 | 0.12 |
| DM* | 0.31 | 0.05 | 0.27 | 1.76 | 9.62 | 3.87 | 4.89 | 6.23 | 7.31 | 28.78 | 0.50 | - | 0.13 |
| Strato. Aerosol | 0.00 | 0.16 | 0.27 | - | 1.07 | 0.00 | 0.01 | 0.11 | 9.31 | 0.14 | 6.84 | 34.03 | 0.13 |
| PSA | 0.00 | 0.02 | 0.11 | - | 0.06 | - | - | 0.01 | 1.21 | 0.00 | 0.01 | 13.84 | 0.04 |
| Volcanic Ash | 0.00 | 0.00 | 0.01 | - | 0.00 | - | 0.00 | - | 0.01 | 0.00 | 0.00 | 0.25 | 0.00 |
| Sulfate/ other | 0.00 | 0.13 | 0.14 | - | 1.00 | 0.00 | 0.01 | 0.11 | 8.06 | 0.13 | 6.81 | 19.73 | 0.10 |
| Smoke | 0.00 | 0.00 | 0.01 | - | 0.01 | - | - | 0.00 | 0.04 | 0.01 | 0.02 | 0.21 | 0.00 |
| Total | 100 | 100 | 100 | 100 | 100 | 100 | 100 | 100 | 100 | 100 | 100 | 100 | |
| Normalized Total | 2.40 | 34.22 | 2.90 | 0.11 | 1.00 | 0.38 | 0.21 | 0.06 | 0.05 | 0.22 | 0.08 | 0.18 | 40.82 |

* CM=clean marine, PC=polluted continental, CC=clean continental, PD=polluted dust, DM=dusty marine, PSA=polar stratospheric aerosol.

3.1 Feature type changes

Feature type changes between V3 and V4 are predominantly due to extensive changes in the calibration coefficients reported the CALIOP level 1 product, which in turn required major revisions of the probability distribution functions (PDFs) that drive the CAD algorithm (Liu et al., 2018). Changes to the surface detection algorithm (Vaughan et al., 2018b) also contribute, but to a significantly lesser extent. In order to quantify how the occurrence frequency of aerosol types has changed, Table 4 reports the percent changes in “feature type” and “aerosol subtype” between V3 and V4 for all 60 m range bins in the CALIOP level 2 profile product from 2007 to 2009. Salient statistics drawn from Table 4 are given here and in subsequent sections. Within the three year analysis period, the classification of 13.7 % of the layers identified as tropospheric aerosols in V3 has changed to totally attenuated (0.1 %), clear air (6.3 %), cloud (7.0 %), or surface (0.4 %) in V4. In spite of this reduction, however, tropospheric aerosols in V4 increase by 18 % due to newly identified aerosols from regions that were identified in V3 as totally attenuated layer, clear air, cloud, or surface. The V3 CAD algorithm did not separate aerosols from clouds for layers detected in the stratosphere; instead, it identified these layers generically as “stratospheric features”. In V4, however, the CAD algorithm is applied in both the troposphere and stratosphere, and thus aerosol layers are identified and classified in the stratosphere. When including newly introduced stratospheric aerosol layers (13 %), aerosols increase by 31 % in V4 compared to V3. The CALIOP V4 algorithm detects more aerosol resulting in an increase AOD. Additionally, the improved surface detection scheme of V4 results fewer opaque layers than in V3 (Vaughan et al., 2018b). Thus, regions below layers previously classified

as opaque are now scanned for the presence of atmospheric features. This leads to an increase in the number of aerosol layers reported near the surface.

3.2 Aerosol subtype changes

5 The spatial distribution and frequency of occurrence of aerosols has changed from V3 to V4 for reasons described in Sect. 3.1. Similarly, enhancements to the aerosol subtyping algorithm described in Sect. 2 are responsible for changes in the spatial distributions and occurrence frequencies of the different aerosol subtypes. The net effect of these changes is demonstrated by Fig. 11, which shows the difference in aerosol type detection frequencies for JJA 2007, day and night combined. For context, Fig. 12 shows the number of aerosol samples detected during the same time period. The frequency of clean marine aerosol is slightly reduced in V4 except for in the oceans around Antarctica (Fig. 11(a)), with most changed layers becoming dusty marine. Table 4 shows that 3.9 % of V3 clean marine aerosol is reclassified as dusty marine in V4. The increase of clean marine aerosol in V4 over the Antarctic Ocean mainly comes from clean continental and polluted continental aerosols due to the changes in aerosol subtyping algorithm over the polar regions (Fig. 1). 4.1 % of clean marine aerosol off the southwest African coast became elevated smoke in 2007-2009 (Table 4).

15

The revised definition for elevated smoke (Sect. 2.1.3) and the implementation of SCAARF (Sect. 2.3) are responsible for correcting the frequency of elevated smoke classifications in this region in V4 (Fig. 11(f)). Additionally, the revised elevated smoke definition is responsible for the changes in polluted continental/smoke and elevated smoke classifications over southern Africa in Fig. 11(c) and Fig. 11(f), respectively. During JJA, smoke from biomass burning is ubiquitous in this region, so a smoke aerosol type classification is expected most often. Because the top altitudes of smoke layers within this region are often below 2.5 km above the ground level, many layers do not meet the V4 “elevated” definition, causing an increase in the frequency of polluted continental/smoke classifications and a reduction in the frequency of elevated smoke classifications as compared to V3.

20

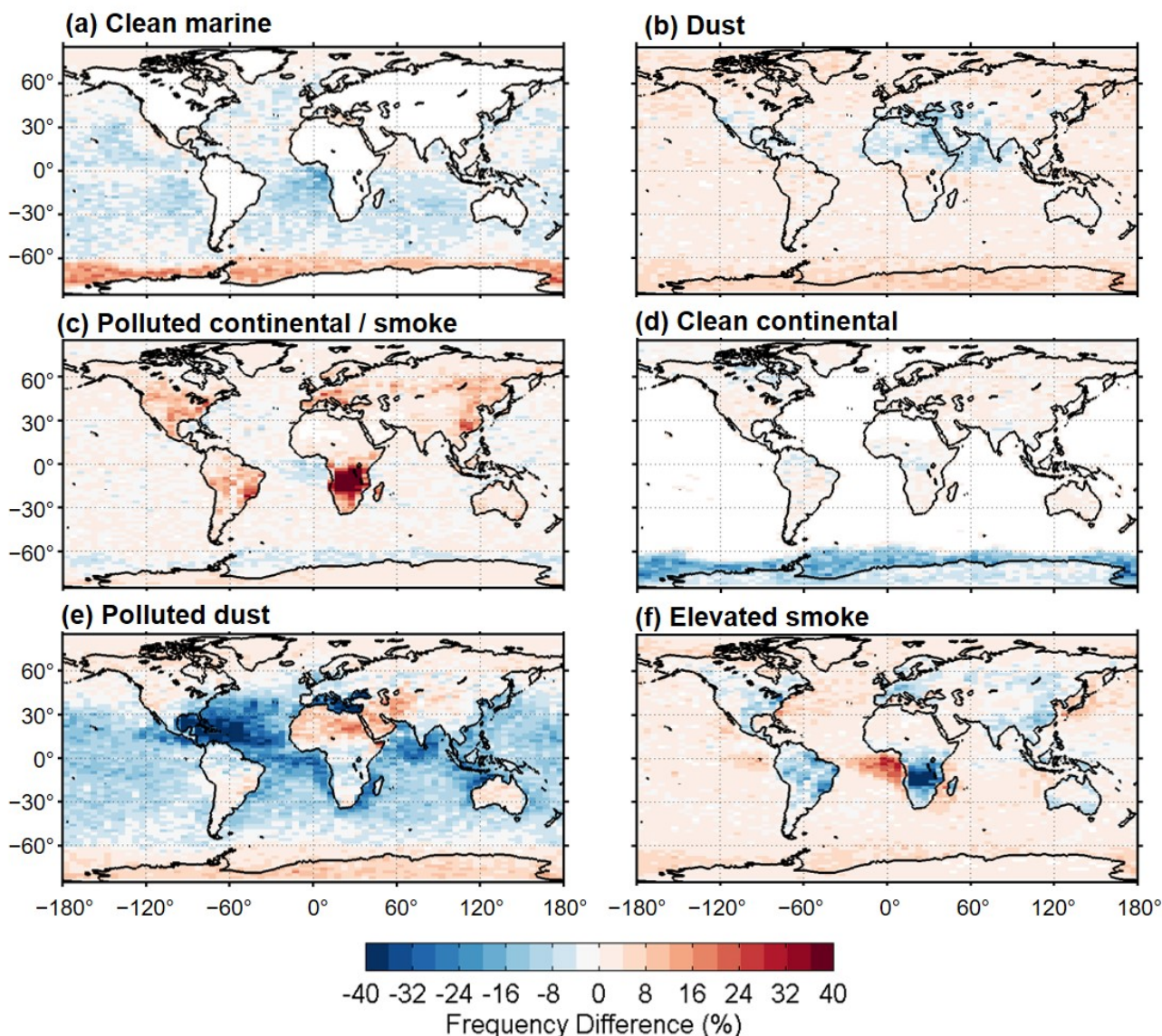


Figure 11: Differences in frequency of occurrence of indicated aerosol type from V3 to V4 (fV4 - fV3) for aerosol subtypes common to both versions, JJA 2007 day & night. Frequencies are computed from level 2 aerosol profile products as the number of aerosol samples with the indicated aerosol type divided by the total number of aerosol samples.

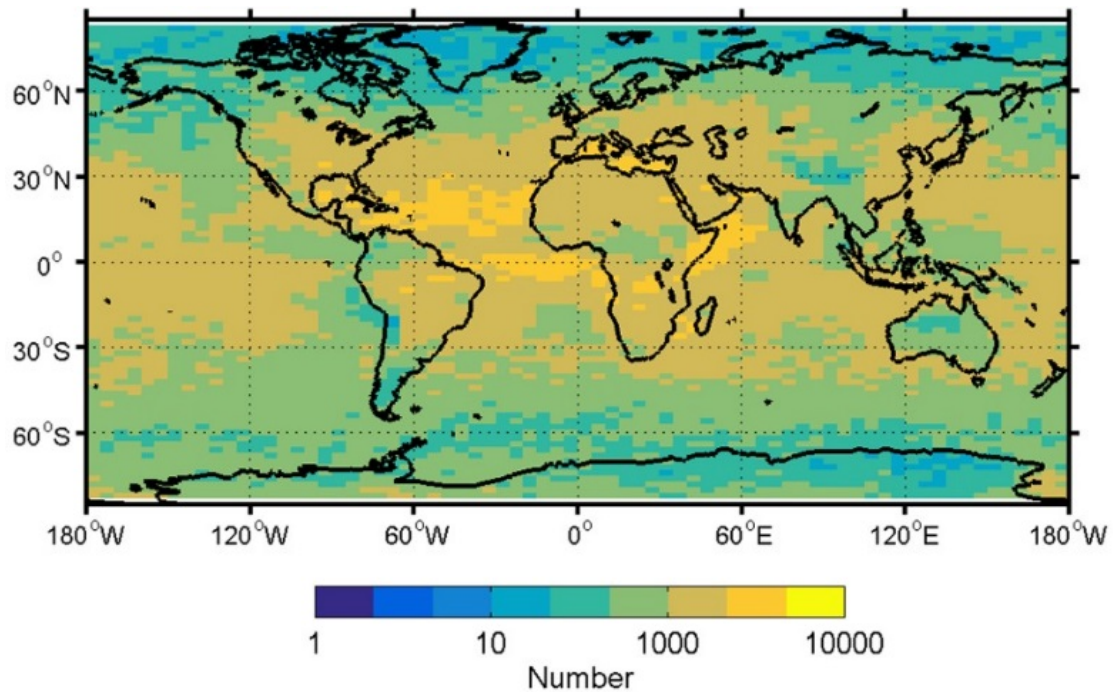


Figure 12: Number of aerosol samples detected in V4 for JJA day & night combined, computed from level 2 aerosol profile product.

5 As expected and intended, the introduction of the new dusty marine aerosol type (Sect. 2.1.2) has improved the aerosol subtyping over oceans in regions where mixtures of dust and urban pollution are not expected (e.g., mid-Atlantic and mid-Pacific Oceans). This is shown by a decreased frequency of polluted dust aerosol layers in V4 (Fig. 11(e)). Over the north African/Arabian dust region, the frequency of polluted dust has increased while the frequency of dust has decreased (Fig. 11(b)), in part due to correcting the overestimate of δ_p^{est} that existed in V3. This correction in δ_p^{est} also caused about 4.9 % of
10 V3 dust to become dusty marine in V4 (Table 4). Though the fraction of aerosol classified as dust has changed by a small amount, the number of dust layers at high altitudes has increased due to changes in CAD, which shows an improved ability to correctly classify lofted dust layers as aerosols rather than cirrus clouds (Liu et al., 2018).

The frequency of clean continental aerosol has decreased over regions characterized by snow, ice and tundra (Fig. 11(d))
15 because all aerosol type classifications are allowed in V4 over these surface types (Sect. 2.1.1). Clean continental aerosols have mainly changed to clean marine (11.6 %), polluted dust (11.3 %), elevated smoke (10.2 %), and polluted continental/smoke (9.7 %). The increase in dust and polluted dust classifications over the Antarctic reflect type misclassifications of tenuous ice clouds and blowing snow. Only 8.8 % of clean continental aerosol layers are unchanged in V4 (Table 4).

As a global summary, Fig. 13 shows frequency distributions of aerosol subtypes for daytime and nighttime in V3 and V4, normalized by the total number of bins (day and night together for each version) that were classified as aerosol according to the AVD data from the level 2 aerosol profile products. More aerosol layers are detected at night for both V3 and V4 (Liu et al., 2018). This is expected since a higher SNR at night means the CALIOP layer detection algorithm detects more weakly scattering features during nighttime (Vaughan et al., 2009). Clean continental is only rarely identified in V4. Clean continental was common in the polar regions, especially over the Antarctic in V3. Because V4 allows all aerosol types in the poles, the dominance of clean continental is significantly reduced, as shown in Fig. 11(d). The frequency for polluted dust is reduced for both day and night. While ~~While~~ part of this reduction is due to the layer attenuation corrections mentioned in Sect. 2.1.1, the predominant reason is because layers previously classified as polluted dust are now ~~correctly~~ more realistically classified as dusty marine in V4. Since the frequency of occurrence of polluted dust aerosols is larger for daytime compared to nighttime over ocean in V3, as shown in Fig. 3(b), the change from polluted dust to dusty marine is relatively more frequent for daytime than nighttime. In fact, 59 % of the daytime dusty marine in V4 is polluted dust in V3, but only 42 % of the nighttime dusty marine is polluted dust in V3. The generic stratospheric features previously identified in V3 are now classified as clouds or aerosol in V4. During the daytime, these V3 stratospheric features are more frequently identified as clouds, rather than aerosols. At night the situation is reversed: nighttime V3 stratospheric features are most often classified as aerosols. Stratospheric features detected in V3 are classified as cloud or stratospheric aerosol in V4. Stratospheric features in V3 are changed to cloud more frequently for nighttime. Similarly to tropospheric aerosols, stratospheric aerosol in V4 is moreless at nighttime than daytime compared to stratospheric features in V3.

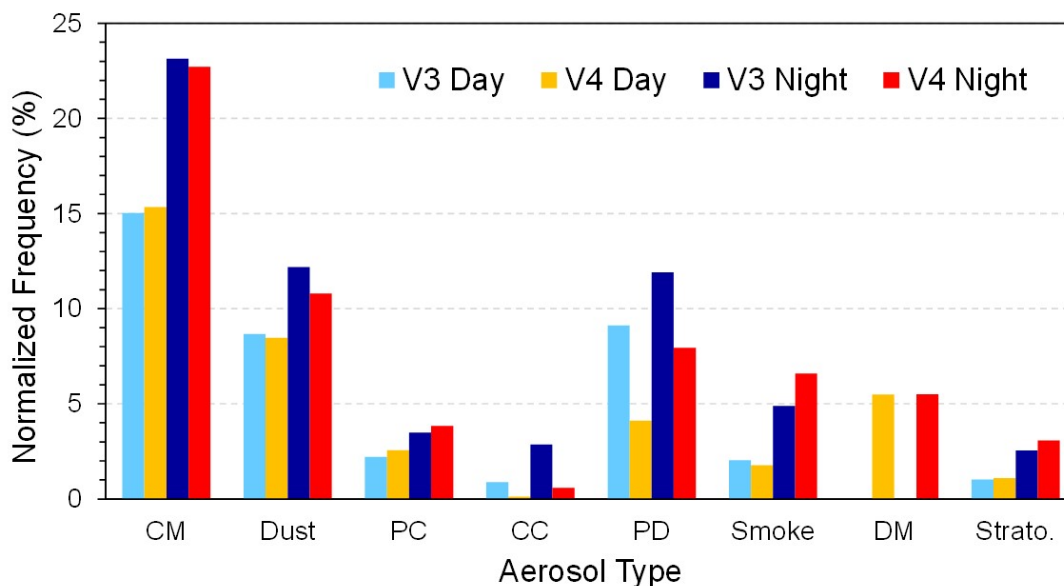


Figure 13: Normalized frequencies of aerosol subtypes in V3 and V4 for daytime and nighttime. Note that “strato.” is stratospheric feature for V3 but stratospheric aerosol for V4. CM=clean marine, PC=polluted continental, CC=clean continental, PD=polluted dust, DM=dusty marine.

5

3.3 AOD changes

In order to compute the change in AOD from V3 to V4, CALIOP level 2 aerosol extinction profiles are vertically integrated and compared profile to profile between the two versions. Only profiles where either ~~both~~ V3 or V4 contained aerosol are included in the average (in cases where only one version reports aerosol, the other version is assumed to have AOD = 0).

10 Furthermore, only aerosol bins with the extinction quality control (QC) flags of 0, 1, 16, and 18 are used (excluding 6 % of aerosol samples), which represent unconstrained retrievals which do not change the lidar ratio (0), constrained retrievals which derive an optimized lidar ratio (1), opaque layers for which the lidar ratio was not changed (16), and opaque layers where the lidar ratio was reduced to prevent the retrieval from diverging (18), respectively (Tackett et al., 2018). For 2007 to 2009, the total change in mean nighttime (daytime) CALIOP level 2 column AOD has increased from 0.084 (0.090) in V3 to 0.128 (0.126) in V4 (Table 5). Day and night AOD become more comparable in V4 whereas daytime AOD is larger than nighttime in V3. Note that the mean AOD computed here is not meant to represent global conditions, but instead examines AOD changes only where AOD is detected by CALIOP.

Table 5: Mean column AODs (\pm standard deviation) for CALIOP V3 and V4, computed from aerosol extinction profiles, for all-sky condition from 2007 to 2009. Profiles where either/both V3 or V4 contained aerosol layers are included in the average.

| | Night | Day |
|----|-------------------|-------------------|
| V3 | 0.084 \pm 0.162 | 0.090 \pm 0.150 |
| V4 | 0.128 \pm 0.242 | 0.126 \pm 0.202 |

5 The AOD increase from V3 to V4 is due to various factors. Using the feature types and aerosol subtypes ~~in~~ reported in the
 level 2 AVD, AOD changes attributed to layer detection, CAD, totally attenuated layers, surface detection, stratospheric
 aerosol classification, aerosol type, and lidar ratio are identified using the procedure diagrammed in Fig. 14. This strategy
 isolates changes in AOD due to each of these factors using CALIOP level 2 products from 2007 to 2009. All range bins whose
 feature type is determined as aerosol by either V3, V4 or both are selected for the analyses. If a bin is identified as aerosol in
 one of V3 or V4 and the other is clear the corresponding AOD change is regarded as the change due to the difference of layer
 10 detection in the two versions (pathway 1 in Fig. 14). Similarly, an aerosol bin that changed from/to cloud, totally attenuated
 layer, surface, and stratospheric feature is counted in the AOD changes due to the updates of CAD, totally attenuated signals,
 surface detection, and stratospheric aerosol in V4, respectively (pathways 2-5). When feature types in both V3 and V4 are
 aerosol, AOD differences can be due to aerosol subtype changes (pathway 6) or lidar ratio adjustments without changing
 subtype (pathway 7). If aerosol subtype is identified as polluted continental, polluted dust, or smoke in both V3 and V4, there
 15 are no changes in the aerosol subtyping (pathway 8). However, the AOD can be different between V3 and V4 even when there
 are “no changes” in their subtype and lidar ratio. The most likely source of these differences is changes in the magnitude of
 β' , either due to level 1 calibration improvements (Kar et al., 2018; Getzewich et al., 2018) or to changes in the two-way
 transmittances estimated for overlying cloud and/or aerosol layers (Young et al., 2018).

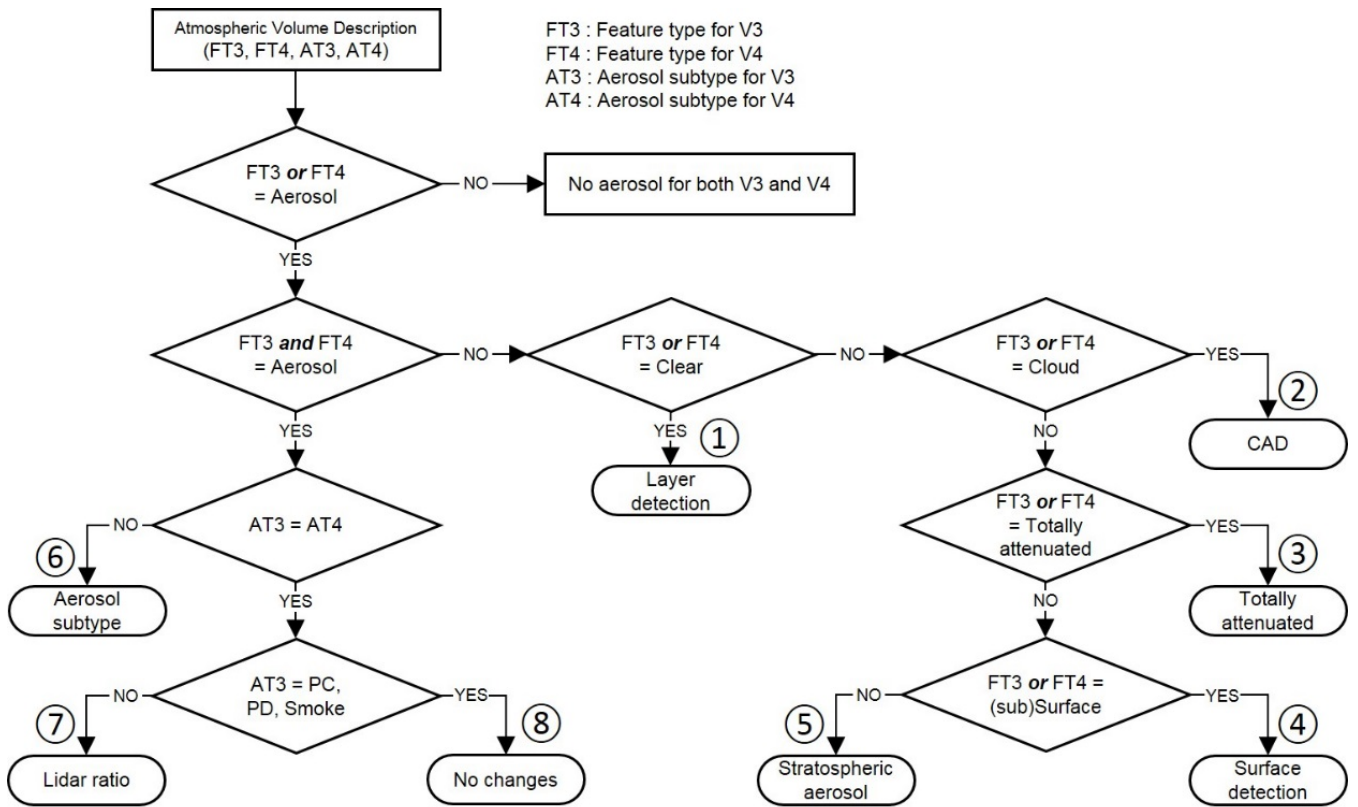


Figure 14: Flowchart to categorize factors that impact on the AOD change between V3 and V4. Note that changes between polluted continental and smoke are treated as no changes because the lidar ratios at 532 nm for those aerosols are same as 70 sr. FT3 and FT4 are feature types in V3 and V4. AT3 and AT4 are aerosol subtypes in V3 and V4.

5

Table 6 quantifies the AOD changes from V3 to V4 for “all sky” conditions for the different factors categorized in Fig. 14; i.e., layer detection, CAD, surface detection, stratospheric aerosol, aerosol subtype, lidar ratio, and no change. Here, the all sky analysis includes all profiles which contain identified aerosol regardless of the presence of clouds. All of the factors listed above contribute to the increase in AOD in V4 and the magnitudes of the AOD changes are strongly related to their occurrence

10

frequencies (Table 6).

Table 6: Mean column AOD changes (\pm standard deviation) from CALIOP V3 to V4 (defined as $V4 - V3$) and their bin frequencies for different reasons described in Fig. 5 for all-sky condition from 2007 to 2009.

| | Frequency (%) | | AOD change | |
|-----------------|---------------|------|-------------------|-------------------|
| | Night | Day | Night | Day |
| Layer detection | 20.9 | 17.5 | 0.007 ± 0.050 | 0.005 ± 0.061 |
| CAD | 11.7 | 12.2 | 0.007 ± 0.159 | 0.014 ± 0.121 |

| | | | | |
|------------------------|-------------------|-------------------|-------------|--------------|
| Total Attenuated | 1.7 | 1.3 | 0.008±0.075 | 0.003±0.047 |
| Surface detection | 1.5 | 1.5 | 0.001±0.025 | 0.002±0.015 |
| Stratospheric aerosol | 5.5 | 4.0 | 0.001±0.020 | 0.002±0.017 |
| Aerosol subtype | 16.5 | 18.7 | 0.003±0.081 | -0.004±0.068 |
| Lidar ratio | 31.5 | 36.8 | 0.013±0.067 | 0.012±0.060 |
| No change | 10.7 | 8.0 | 0.003±0.040 | 0.003±0.032 |
| Total (number of data) | 100 (868,893,575) | 100 (492,266,349) | 0.044±0.225 | 0.036±0.183 |

Global maps of AOD changes for each factor are shown in Fig. 15. CALIOP AOD has increased by 0.007 and 0.005 for nighttime and daytime, respectively, because of changes in layer detection (Table 6 and Fig. 15(b)). This implies that the CALIOP V4 layer detection algorithm finds tenuous layers that were not found in V3. Note that no significant changes were made to the CALIOP layer detection algorithm in V4. The increased detection of faint layers is attributed primarily to changes in the 532 nm calibration coefficients that generally increase β' . The CAD algorithm classifies most of these new layers as aerosols.

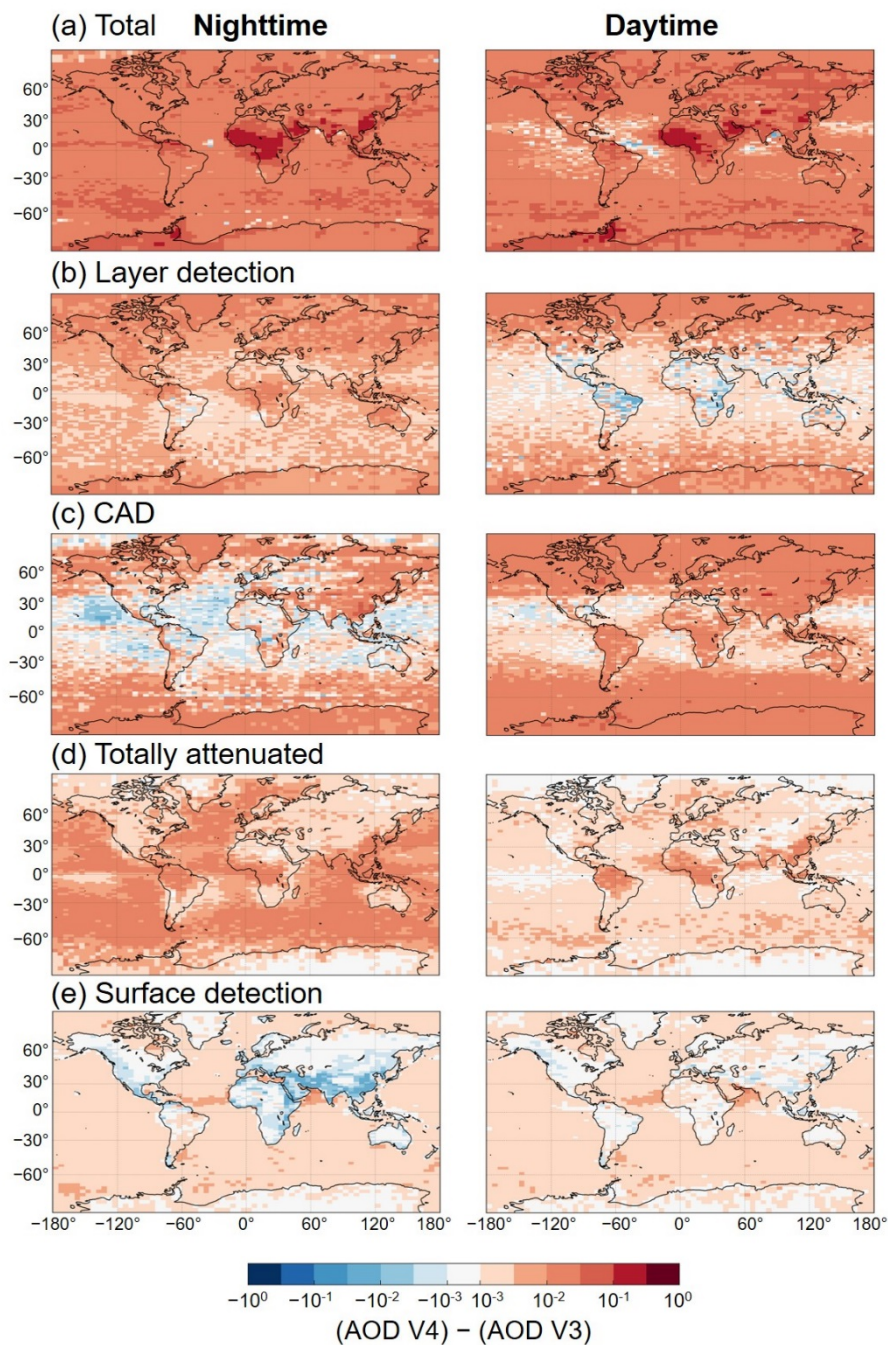


Figure 15: Global maps of mean AOD differences between V3 and V4 for each factor categorized in Fig. 14 from 2007 to 2009; (a) total, (b) layer detection, (c) CAD, (d) totally attenuated, (e) surface detection, (f) stratospheric aerosol, (g) aerosol subtype, (h) lidar ratio, and (i) no changes. Left and right columns are for nighttime and daytime, respectively.

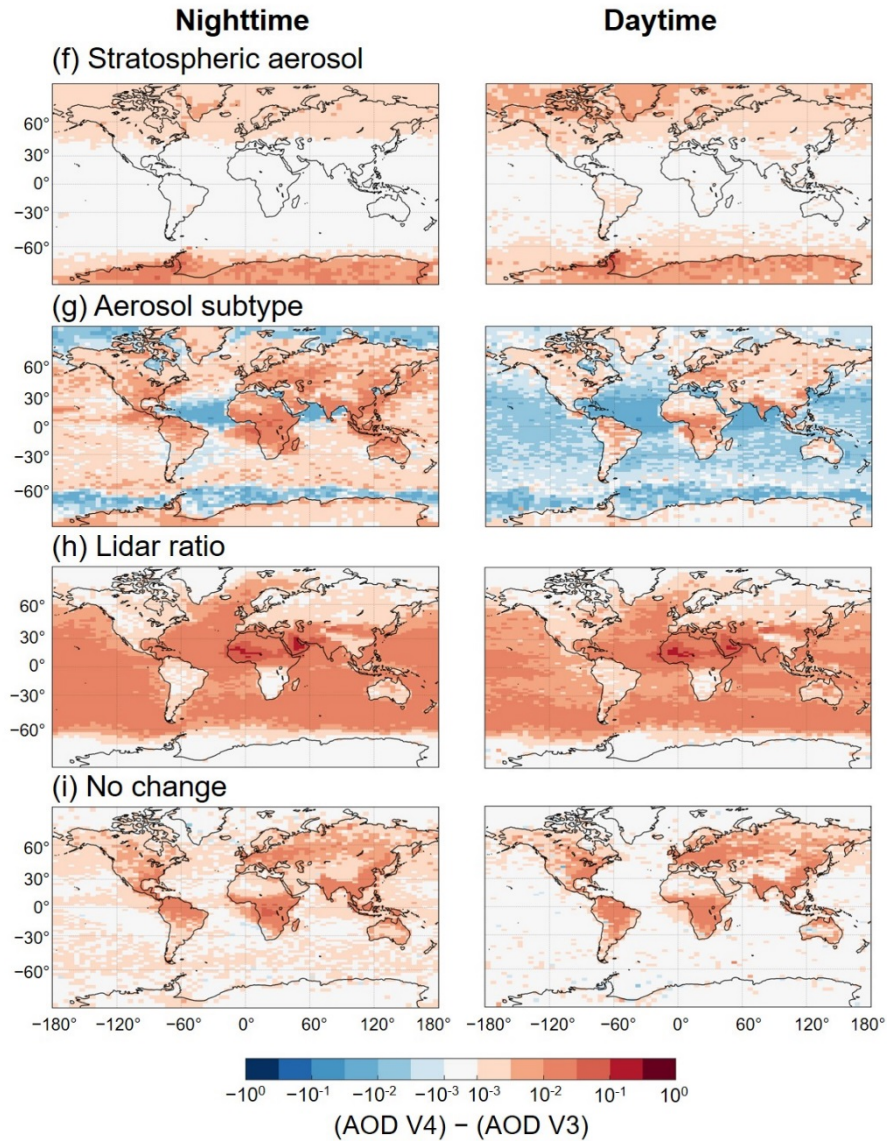


Figure 15: (continued)

- 5 Figure 15(c) shows that AOD changes due to CAD have a day and night difference. The mean daytime AOD increase is twice that for the nighttime (Table 6). The daytime AOD increase is due primarily to a net increase in the number of V4 aerosols. The number of new aerosols in V4 (i.e., layers that were classified as clouds in V3) is much larger (~ 3.4 times) than the converse (i.e., the aerosols in V3 that were classified as clouds in V4) at daytime. Among these new aerosols, the subtypes

dust and polluted dust account for more than 50 %. The V4 CAD PDFs were deliberately tuned to be more sensitive to aerosol presence in the upper troposphere and lower stratosphere, resulting in improved performance in distinguishing high altitude Asian dust plumes from cirrus (Liu et al., 2018). However, as a side effect, some fraction of the “cirrus fringes” detected along the edges and lower boundaries of cirrus clouds that were classified as clouds in V3 are now classified as aerosols in V4. Most of these fringes are subsequently identified as dust or polluted dust by the aerosol subtyping algorithm. These increases in misclassified dust and polluted dust at high altitudes contribute the most to the daytime AOD increase due to CAD. Although the misclassification of cirrus fringes as aerosols also occurs in the V4 nighttime aerosol products, the gain and loss in the total aerosol number due to CAD are about the same and hence the change in nighttime aerosols cannot fully explain the increase in the nighttime mean AOD increase in Table 6. It appears that the change in V4 level 1 data calibration also plays an important role. As discussed below for Fig. 15(i), changes in the V4 level 1 data calibration alone can cause a nighttime AOD increase of 0.003, as shown in Table 6, about half the nighttime AOD change of 0.007 due to CAD. However, the net change for each aerosol subtype varies largely and may play an important role in the regional AOD changes as seen in the left panel of Fig. 15(c).

15 If a bin is previously identified as totally attenuated in V3 and becomes aerosol in V4, the most likely cause is difference in surface detection. The V4 surface detection algorithm (Vaughan et al., 2018b) is considerably more effective than the V3 algorithm in detecting the Earth’s surface after penetrating atmospheric layers of substantial optical depth (e.g., cirrus clouds with optical depths of 2.5 or larger). As a result, regions where the signal was considered totally attenuated in V3 are now searched for the presence of features, and the aerosol layers detected in these regions contribute to an increase in AOD in V4 (Fig. 15(d)).

Changes in the surface detection and the newly introduced stratospheric aerosol types also contribute to AOD increases in V4, but not significantly. Figure 15(e) shows that some surface signals misclassified as aerosols in V3 are ~~correctly detected~~ now classified as surface in V4. This leads to a decrease in AOD especially in the southern Asian continent. Since the surface returns are much stronger than backscatter signals for aerosols, AOD changes appear relatively large. AOD increases due to newly introduced stratospheric aerosols in V4 are found mainly in the Arctic and Antarctic regions where the STS compositions of PSCs are ubiquitous in the polar winter and can be classified as stratospheric aerosol in V4 (Fig. 15(f)).

There is a decrease in ~~the~~ mean ~~of~~ AOD due to aerosol subtype changes for daytime, but an increase for nighttime (Table 6). Figure 15(g) shows that AOD changes due to the aerosol type changes generally have opposite signs at day and night over oceans. The dominant aerosol type over oceans is clean marine, which has the smallest lidar ratio among the CALIOP aerosol models. Therefore, any changes from clean marine to other types of aerosol can lead to an AOD increase in V4. This is the dominant type change over ocean for the nighttime. For the daytime, on the other hand, a type change from polluted dust to

dusty marine occurs more frequently, as explained earlier (Sect. 3.2). The reduction in lidar ratio from polluted dust (55 sr) to dusty marine (37 sr) leads to a decrease in the mean daytime AOD. AODs decrease for both day and night over the mid-Atlantic and Indian Oceans as well as over the Arctic and Antarctic Oceans, as shown in Fig. 15(g). Dust can be frequently transported to the Atlantic and Indian Oceans from the Saharan and Arabian Deserts. Aerosol type changes from dust or polluted dust to dusty marine dominate in these regions and lead to the AOD decreases in these regions. The AOD decreases over the Arctic and Antarctic Oceans are because the V4 aerosol subtyping algorithm now allows all aerosol types over these regions rather than solely the clean continental and polluted continental subtypes (Sect. 2.1.1).

Updates in lidar ratio led to an AOD increase of 0.013 and 0.012 for nighttime and daytime, respectively. The 532 nm lidar ratios for three aerosol subtypes were changed in V4: clean marine, dust, and clean continental. Since the lidar ratios for these subtypes were all increased, AOD increased correspondingly. Figure 15(h) shows the AOD increases due to the lidar ratio updates. The AOD increase over oceans was due to the lidar ratio change for clean marine. The most significant AOD increase is seen over North Africa and the Arabian Peninsula where pure dust is a dominant aerosol type. The change was caused by the lidar ratio update for dust from 40 sr to 44 sr. Due to the nonlinear behavior of the AOD retrieval, this 10 % increase in lidar ratio yields an increase of up to 20 % in AOD for dust layers as shown by AOD retrieval above opaque water clouds (Liu et al., 2015). Some of the AOD increases are even larger over North Africa and the Arabian Peninsula, where the dust is generally denser than that over the East Atlantic, thus further amplifying the nonlinear response of AOD to lidar ratio.

Figure 15(i) shows AOD changes even if there are no changes in aerosol subtype and lidar ratio. AOD is slightly increased especially over land. These changes are due to differences in calibration and two-way transmittance for upper layers between V3 and V4.

AOD changes between V3 and V4 for “cloud-free” conditions are typically smaller than in the all-sky cases discussed above. Cloud-free cases are restricted to those profiles where no clouds were detected for both V3 and V4 from the level 2 5 km profile product. Table 7 shows occurrence frequencies and AOD changes for cloud-free conditions. The frequencies for layer detection are substantially reduced compared to all-sky. This implies that, when compared to V3, the V4 aerosol detection frequency is higher in cloudy-skies but relatively unchanged for clear-skies. This behavior is not unexpected, and can be at least partially explained by the improved surface detection in V4 that identifies more transparent air columns compared with V3. This behavior can also be attributed partially that the presence of more misclassified cirrus fringes in V4 (Liu et al., 2018). Comparing Tables 6 and 7, a larger fraction of aerosols maintains their subtype in the cloud-free conditions than in the all-sky conditions (i.e., the lidar ratio category in Table 7 is 45.9 % night and 50.7 % day vs. 30.2 % night and 35.9 % day in Table 6). Due to the largely increased frequencies, AOD increases by the lidar ratio updates in V4 overwhelm all the other factors for cloud-free skies compared to cloudy skies.

Table 7: Same as Table 6 but for cloud-free sky.

| | Frequency (%) | | AOD change | |
|------------------------|-------------------|-------------------|-------------|--------------|
| | Night | Day | Night | Day |
| Layer detection | 17.3 | 13.2 | 0.006±0.030 | 0.003±0.042 |
| CAD | - | - | - | - |
| Total Attenuated | 0.1 | 0.2 | 0.000±0.014 | 0.001±0.022 |
| Surface detection | 2.2 | 2.1 | 0.001±0.029 | 0.003±0.014 |
| Stratospheric aerosol | 2.9 | 1.6 | 0.001±0.009 | 0.001±0.008 |
| Aerosol subtype | 18.2 | 22.8 | 0.000±0.076 | -0.008±0.071 |
| Lidar ratio | 46.1 | 50.6 | 0.016±0.056 | 0.013±0.057 |
| No change | 13.2 | 9.7 | 0.003±0.030 | 0.002±0.028 |
| Total (number of data) | 100 (362,664,890) | 100 (249,431,801) | 0.027±0.113 | 0.015±0.115 |

4 Preliminary validation with AERONET and MODIS

5 A low bias of the V3 CALIOP AOD estimates relative to both MODIS and AERONET has been established in a number of
previous publications (Kacenelenbogen et al., 2011; Oo and Holz, 2011; Redemann et al., 2012; Schuster et al., 2012; Kim et
al., 2013; Omar et al., 2013). In this study, CALIOP AODs for both V3 and V4 are compared with AERONET and MODIS
using collocation methods similar to Omar et al. (2013) and Kim et al. (2013). The collocation criteria adopted for CALIOP
and AERONET (level 2) require data acquisition times within ±30 min and spatial matching of the CALIOP footprint to within
10 a 40 km radius of the AERONET site. Enforcing these criteria yields 736 data pairs from 176 sites over the globe from 2007
to 2009. MODIS level 2 AOD and CALIOP level 2 column integrated AODs whose distance from the center of MODIS grid
is less than 10 km are selected as collocated data pairs for the same period. CALIOP level 2 data with extinction QC flags of
0, 1, and 16 are used for both V3 and V4. MODIS collection 6 Dark-Target AODs (Levy et al., 2013),
“Effective_Optical_Depth_Average_Ocean” over ocean and “Corrected_Optical_Depth_Land” over land at 550 nm, with
15 “Quality_Assurance_Ocean” of 1 (marginal) or higher and “Quality_Assurance_Land” of 3 (very good) are used for
comparison. To remove cloud contamination, data pairs with CALIOP cloud column optical depths greater than 0 or MODIS
cloud fractions greater than 0 % are rejected.

Global maps of AOD differences between CALIOP and AERONET/MODIS (CALIOP – AERONET/MODIS) are shown in
20 Fig. 16. The color-coded maps show AOD differences relative to MODIS, while differences relative to AERONET are shown
as individual filled circles on the map. The AOD differences between CALIOP and AERONET are generally similar between

the two versions. Likewise, regional CALIOP – MODIS AOD differences over oceans are generally similar for V3 and V4, except for the southern oceans ($< 30^\circ$ S), where the V4 AOD differences are slightly larger. Another noticeable difference between the two versions is that the AOD difference is reduced in V4 off the southwest African coast. This is mostly related to aerosol type changes from correcting the classifications of elevated smoke plumes previously misclassified as clean marine over this region in V3 (Sect. 2.3). Over land, AOD differences relative to MODIS typically increase in V4 compared to V3. The increases over tropical and southern Africa are, in part, due to corrections in δ_p^{est} which were overestimated in V3 (Sect. 2.1.2). These corrections tend to change aerosol subtype classifications to aerosol subtypes with higher lidar ratios (e.g., dust to polluted dust). Differences between CALIOP and MODIS are most noticeable in Africa and South Asia, whereas agreement with AERONET in these regions tends to be much better.

Resolution of the inconsistency between the comparisons with AERONET and MODIS points to the need for further validation studies, especially over land. Since the MODIS over-ocean algorithm is generally more accurate than over-land (Levy et al., 2013), AOD differences between CALIOP and MODIS over land are excluded from further consideration in our analyses. Global mean and median of AOD differences between CALIOP and AERONET/MODIS for V3 and V4 are shown in Table 8. Both V3 and V4 show that the mean CALIOP AODs are smaller than AERONET and MODIS (ocean), but the mean (median) discrepancies are reduced from -0.064 (-0.052) to -0.051 (-0.045) for AERONET and from -0.010 (-0.012) to -0.006 (-0.008) for MODIS over ocean. The [absolute difference in AOD over global oceans between CALIPSO V3 and MODIS collection 6](#) is smaller compared to previous studies (e.g., Oo and Holz, 2011; Redemann et al., 2012; Kim et al., 2013). These earlier studies used MODIS collection 5 and global AOD for MODIS collection 6 has decreased by 0.02 over ocean compared to collection 5 (Levy et al., 2013).

Table 8: Mean (\pm standard deviation) and median (\pm median absolute deviation) of AOD difference between CALIOP and AERONET/MODIS (defined as CALIOP – AERONET/MODIS) for V3 and V4 from 2007 to 2009.

| | CALIOP V3 | | CALIOP V4 | | Number of data pairs |
|---------------|--------------------|--------------------|--------------------|--------------------|----------------------|
| | mean | median | mean | median | |
| AERONET | -0.064 \pm 0.087 | -0.052 \pm 0.028 | -0.051 \pm 0.085 | -0.045 \pm 0.025 | 736 |
| MODIS (Ocean) | -0.010 \pm 0.070 | -0.012 \pm 0.025 | -0.006 \pm 0.068 | -0.008 \pm 0.025 | 911,376 |
| MODIS (Land) | 0.069 \pm 0.195 | 0.062 \pm 0.091 | 0.121 \pm 0.225 | 0.090 \pm 0.098 | 38,142 |

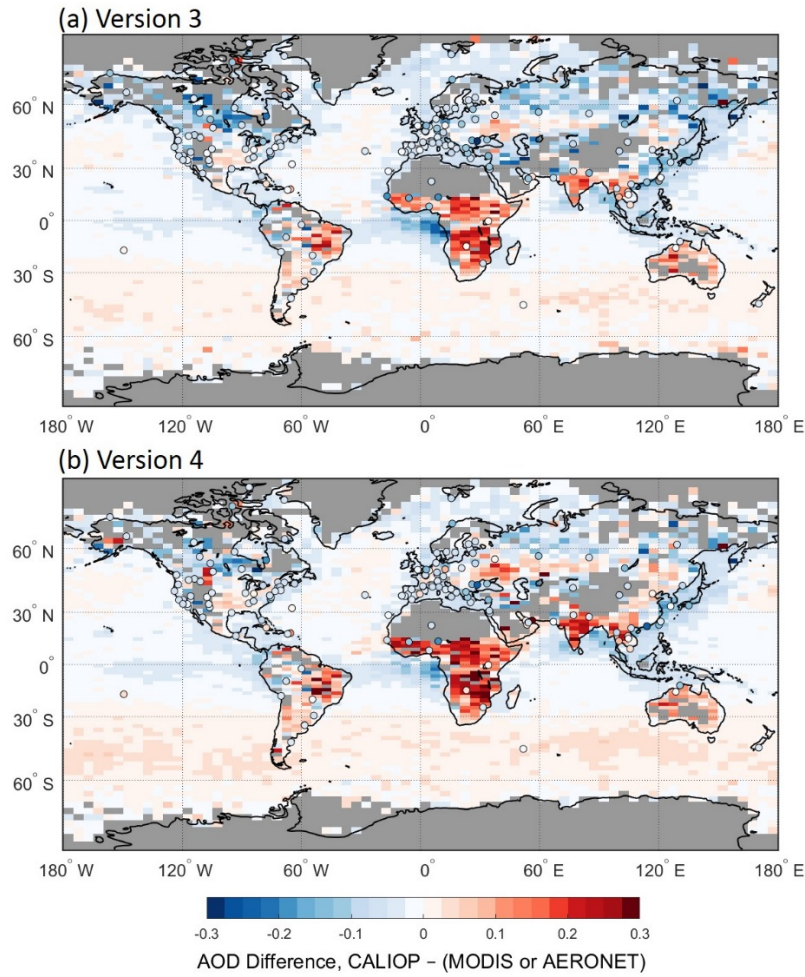


Figure 16: Global maps of mean AOD difference between CALIOP and MODIS. CALIOP data for (a) V3 and (b) V4 and MODIS collection 6 from 2007 to 2009. Mean AOD difference between CALIOP and AERONET are shown in circles.

- 5 Figure 17 compares the V3 and V4 CALIOP AOD differences with respect to MODIS over ocean from 2007 to 2009. Points on the one to one line (black dotted) correspond to no AOD change between V3 and V4. Points closer to the x-axis ($y=0$) represent AOD biases that are smaller in V4 compared to V3, while points closer to the y-axis ($x=0$) represent AOD biases that are larger in V4. The linear trend line has a slope less than 1 which means that the overall AOD bias is reduced in V4 (perfect agreement between V4 and MODIS would yield a slope of zero.). AOD biases with respect to MODIS for V3 and V4
- 10 have a distribution close to the one to one line. The slope of the linear trend is 0.82, indicating a small reduction in the AOD bias from V3 to V4.

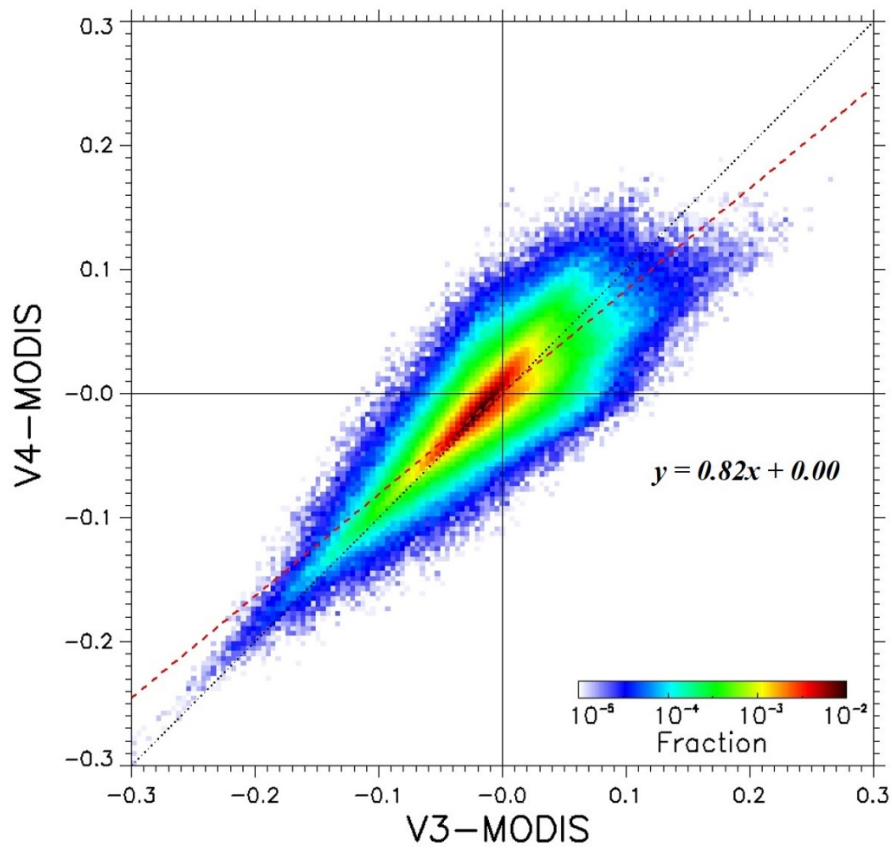


Figure 17: Distribution of V3 CALIOP AOD difference from MODIS versus V4 CALIOP AOD difference over ocean from 2007 to 2009. A linear regression line is shown in red dashed line with equation.

5 5 Summary

The CALIPSO version 4.10 (V4) lidar level 2 data products were released in November 2016. V4 is the first wholly new set of data products since the initial release of the Version 3 (V3) series of products in May 2010. Algorithm updates and data product changes for V4 aerosol subtyping algorithms are discussed in this study. The most significant algorithm updates in V4 are as follows.

- All aerosol subtypes are now allowed over snow, ice, and tundra surfaces, whereas only clean continental and polluted continental aerosols were allowed in previous versions.

- A new aerosol subtype, dusty marine, has been introduced. The wide-spread occurrence of layers misclassified as polluted dust over the ocean in previous versions has been rectified, and these layers are now correctly-realistically classified as dusty marine.
- The polluted continental and smoke aerosol types in previous versions have been renamed in V4 to “polluted continental/smoke” and “elevated smoke”, respectively.
- A new scheme, the Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF), is applied to re-evaluate the aerosol subtype of aerosol layers detected at coarse resolutions below overlying horizontally adjacent layers.
- Stratospheric aerosol subtypes have been introduced for ash, sulfate/other, smoke and polar stratospheric aerosol.
- Aerosol lidar ratios have been updated for clean marine, dust, clean continental, and elevated smoke to represent the current state of knowledge for these types.

Feature type and aerosol subtype changes between V3 and V4 are investigated. Tropospheric aerosol occurrence frequency has increased by 18 % in V4 compared to V3, which implies that the V4 algorithm detects more weakly scattering layers that are subsequently classified as aerosols. Moreover, including stratospheric aerosols in V4, aerosol occurrence frequency increases by 31 % relative to V3. As consequence, the occurrence frequency of most aerosol subtypes also increases. The sole exceptions are polluted dust and clean continental. Layers previously classified as polluted dust that have base altitudes less than 2.5 km are now classified as dusty marine in V4. Similarly, the clean continental aerosols that were ubiquitous in the polar regions in the V3 and earlier data sets are now classified as other subtypes in V4.

The CALIOP level 2 mean column integrated AOD at 532 nm has increased by 0.044 for nighttime and 0.036 for daytime for all sky in V4 from 2007 to 2009. The most significant reasons for the AOD increase in V4 are changes in lidar ratio, CAD and layer detection. For cloud-free skies, however, the contribution of CAD and aerosol layer detection is not as pronounced. Initial comparison of AERONET and MODIS with both versions of CALIOP shows that mean AOD differences with AERONET and MODIS (ocean) are reduced in V4 compared to V3. However, the CALIOP AOD estimates remain low relative to MODIS, and this disparity will not be reconciled based solely on future modifications to the CALIOP aerosol typing and lidar ratio selection algorithms. MODIS makes multi-spectral total column measurements from which AOD estimates can be derived, but cannot provide height-resolved estimates of extinction. In principal, CALIOP has the capacity to deliver these height-resolved estimates of aerosol extinction coefficients on a global scale. But, to date, CALIOP has limited the retrieval of aerosol optical properties to those regions where the layer detection algorithm and cloud-aerosol discrimination algorithm have positively identified the presence of aerosol in the atmosphere. No attempt is currently being made to retrieve aerosol optical properties in those regions where the aerosol loading lies below the CALIOP detection limits, and hence many of the differences seen between the CALIOP and MODIS estimates of AOD should be expected. Should the CALIOP retrieval strategy change in future data releases, comparisons with MODIS will need to be thoroughly and rigorously re-examined.

Competing Interests

The authors declare that they have no conflicts of interest. Coauthor Charles R. Trepte is a one of the guest editors for the “CALIPSO version 4 algorithms and data products” special issue in *Atmospheric Measurement Techniques* but did not participate in any aspects of the editorial review of this paper.

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Interactive comment on “The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm” by Man-Hae Kim et al.

Anonymous Referee #1

Received and published: 25 July 2018

We thank the referee for their careful reading of our manuscript and their thoughtful comments. We have reproduced the referee's comments below (in black) and included our responses in-line (in blue).

Review: The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm

Authors: Man-Hae Kim, Ali H. Omar, Jason L. Tackett, Mark A. Vaughan, David M. Winker, Charles R. Trepte, Yongxiang Hu, Zhaoyan Liu, Lamont R. Poole, Michael C. Pitts, Jayanta Kar, and Brian E. Magill

General comments:

The document clearly describes the steps taken in the algorithm and the changes made between the different versions, in that sense it is a very readable version of the ATBD and will be important for the users of the data to read. The paper is very lengthy but that is by no means a bad thing for this type of article which has to describe all the changes and the impacts of each.

I was very lucky to have a pro-active editor who made a large number of substantial comments resulting in a revised version before I had to go through the paper, making the task a lot easier. I will not add comments from my side which touches those discussions, knowing that some of the specific details have been looked at in detail. For the remainder the authors only need to look at some minor comments from my side.

I personally very much like the change in the concept in V4 of retrieving the subclasses for stratospheric aerosols and allowing the more general aerosols over polar regions. The main part which I am still wondering about is why the 1064nm channel provides you with no additional information in the troposphere. It is mentioned that within the PBL the color ratio does not help with the classification, however I did not notice a similar remark for the remainder of the troposphere. Please include a small discussion on why the color ratio has no impact on the classification in the troposphere since now only 2 of the three signals are used in this regime.

> The CALIPSO scene classification algorithm uses 1064 nm channel for cloud and stratospheric aerosols but not for tropospheric aerosol. It is mainly because low signal to noise ratio (SNR) for 1064 nm especially for aerosol layers during daytime. It might be available to use 1064 nm for some dense aerosol layer. But, the returned lidar signal is relatively weak for (faint) aerosols compared to cloud. In order to apply uniform criteria for all detected aerosol layers, the algorithm does not use 1064 nm for aerosol subtyping. We added some comments on this in the text (Sec. 2.1).

In a lot of places within the document the effects of the new Earth's Surface detection scheme (Vaughan 2018b) is discussed. Sadly enough I do not have a draft version available of this paper, making it impossible to understand the why's of any changes. There is enough information provided to 'trust' the results, so I will do without for this review.

Minor comments:

Page 2, Line 25: compare → compared Line 26: Even though it is obvious please add V3 to CALIOP AOD

> It is corrected.

Page 6, Line 12: AOD differences

> It is corrected.

Page 10, Figure 5: would it be possible to overplot the Arctic PSC season (winter that year) to show that the -70 is consistent for both absolute high latitude regions.

> We updated figure 5 for the Arctic and Antarctic PSC seasons.

Page 14, Line 7: two releases. Also add a bit more information/origin on the 20 and 80km resolution

> It is corrected and simple explanation and reference are added.

Page 20, Line 4: demonstrates an
> It is corrected.

Page 21, Line 20: Can you explain the 31% quoted there. My guess is that it is the normalized values of 1.18 and 0.13 combined, but a bit more explanation here would make it a lot easier to comprehend
> We added 13% of newly introduced stratospheric aerosol in the text.

Page 22, Line 7: Add what the averaging boxes are 1 deg x 1deg ?
> We compared profile to profile for every Level 2 aerosol profile products which have 5 km x 60 m (5 km x 180 m for above 20.2 km) range bin. It is described in the second paragraph of Sec. 3.

Page 24, Line 2 : anan Line 13: give full name of AVD (maybe I missed it earlier) Line 18: WhileWhile
> They are corrected. The full name of AVD is introduced earlier in Sec. 3.

Page 24 Line19 & Page 30 line 15 : Remove correctly from ‘correctly classified & correctly detected’. The word correct should not appear in this text as the absolute truth is not available. You can maybe use ‘more realistically’ or something like that if you would like to add an adverb. I agree that for surface detection one could consider it, however in the previous version the surface was also thought to be correct.
> They are changed from ‘correctly’ to ‘realistically’.

Page 24 Line24: Rewrite sentence ‘Similarly . . .in V3’.
> The sentence is rewritten to make it clear.

Page 25, Table 5. Most of the work is a comparison between the two versions where we now have absolute values in this table. What is clearly noticeable is not only the change in mean value but also the larger standard deviations for the V4. Since we are looking at the 0, 1, 16 and 18 QC flags only, I would like to see the subdivision of the mean and std deviations for these four individual flagged pixels and see where the std deviation has increased most and a small discussion why. Please add the values for the four QC flags individually to the table.

> We note that the standard deviations (STDs) in table 5 are not related with their uncertainties. They show broadness (shape) of AOD distribution. Larger standard deviations (STDs) in V4 are strongly related to the AOD increase. If AODs increase with same amount for all data points, STD remains unchanged in V4 (only the mean will increase). However, if all AODs increase by 10%, for example, STD should also increase by 10%. (If σ is STD for x_i ($i=0,1,2,\dots,n$), STD for $a x_i + b$ is $a\sigma$.) Below table shows % difference from V3 to V4 for both mean and STD. As shown in the table, the % differences for mean and STD are comparable. We thought it is expectable and there is no specific relation with QC flags for STD increase in V4. Thus, we didn't modify the text.

| | Mean | | Standard Deviation | |
|----------------|-------|-------|--------------------|-------|
| | Night | Day | Night | Day |
| V3 | 0.084 | 0.090 | 0.162 | 0.150 |
| V4 | 0.128 | 0.126 | 0.242 | 0.202 |
| Increased in % | 52.4 | 40.0 | 49.4 | 34.7 |

Also, more detailed description about aerosol QC flags can be found in Young et al. (2018), another paper of our AMT special issue about the CALIPSO Version 4 updates. In Table 3(b) from Young et al. (2018), the majority of QC flags falls into QC=0 (95.32% for V3 and 92.97% for V4).

Young, S. A., Vaughan, M. A., Garnier, A., Tackett, J. L., Lambeth, J. B., and Powell, K. A.: Extinction and Optical Depth Retrievals for CALIPSO's Version 4 Data Release, *Atmos. Meas. Tech. Discuss.*, <https://doi.org/10.5194/amt-2018-182>, in review, 2018.

Page 30 Line 21: a decrease in the mean AOD
> It is corrected.

Page 32 Lines 27-29: The discussion is hard to follow, mostly due to the word smaller (I think). I guess you mean smaller in absolute value here or not. In any case please rephrase this sentence to make it crystal clear what you mean
> The sentence is modified to make it clear.

Page 34, Line 13: are now correctly classified as ! are more realistically classified as Line 19 : have been updated
> It is corrected.

Figure 17: By eye it looks like there are two distributions combined (heart shaped distribution) with one above and the other below the 1:1 line. Is there a reason for this, one day and the other night?

> The reviewer's comment is correct. The core (heart shaped distribution) is nearly parallel to 1:1 line, just above it. And minor branch is below (and right) the 1:1 line with the slope of <1 . The former is mainly due to increase of the lidar ratio for clean marine and dust. As shown in Figure 13, (clean marine + dust) counts for ~60% of whole aerosol layers. Due to the lidar ratio increase for these two aerosols, CALIOP V4 AOD increases and the heart shaped distribution in Figure 17 located just above the 1:1 line. The latter corresponds mainly to dusty marine aerosol in V4. The most of dusty marine aerosols come from polluted dust in V3. Because the lidar ratios for polluted dust and dusty marine are 55 sr and 37 sr, respectively, V4 AOD decreases, shown as the minor branch in Figure 17.

This is a simple description, but in fact, it is much more complicated. We compared every single MODIS pixel with collocated CALIPSO data points, which means each collocated data pair is consist with one MODIS data pixel and 3~5 CALIPSO data points. Therefore, multiple aerosol layers with different types may coexist. Aerosol types may change from one to another or a new aerosol layers can be detected in V4. Because we averaged column AOD for collocated CALOPSO data points to compare with MODIS, it is difficult to separate those different contributions in Figure 17. Many figures and tables with additional analysis are needed for this discussion, and it is beyond the main topic of this paper.

Figures: The axes font-sizes of Figures 2, 3, 7, 8, 9, 11, 15 are extremely small, I think it would improve reading/glancing of the figures enormously if these would be increased.

> We adjusted figure sizes and font sizes.

Interactive comment on “The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm” by Man-Hae Kim et al.

Anonymous Referee #2

Received and published: 2 August 2018

We thank the referee for their careful reading of our manuscript and their thoughtful comments. We have reproduced the referee's comments below (in black) and included our responses in-line (in blue).

The authors have put together a very well-written and easy-to-follow description of the CALIPSO Version 4 automatic aerosol classification and lidar ratio selection algorithm. There have been some significant changes from the previous version including: updates to the lidar ratios for several aerosol types, the inclusion of a new dusty marine subtype, full use of the aerosol classification algorithm over all surfaces, aerosol classification in the stratosphere, and the addition of a new algorithm, SCAARF, to homogenize aerosol types when "fringes" occur. Additionally, the manuscript validates the updated algorithm by showing how the resulting AOD is in closer agreement with both MODIS and AERONET.

The authors must be applauded for presenting such a strong manuscript, that there is not much to be asked in way of revisions. If I were to make one complaint (and I won't... at least not fully) it is the use of 2.5 km as a standard approximation for the planetary boundary layer without regard to latitude, surface, time of day, or season. Understandably, there are some practical reasons for doing so, and the decision is based on results from published literature and largely consistent with Version 3. Each change in the aerosol classification and lidar ratio selection algorithm from V3 to V4 is justified and appropriately referenced based on the most current understanding within the aerosol community. The manuscript should be published after some very minor technical corrections.

Page 6, Line 12: "AODdifferences" should be "AOD differences"

> It is corrected.

Figure 3: Upon my first inspection of this figure, I was drawn to the differences in the number of aerosol retrievals both within and without the white dashed ellipse. Fortunately, the causes of these differences are thoroughly discussed later in section 3.3. However, as a courtesy for the inquisitive reader, it would be nice to add a sentence to the text informing that this topic will be addressed later in the manuscript.

> We added a sentence.

Page 11, Line 20: "aa" should be "a"

Page 12, Line4: .. should be .

Page 14, Line7: "releasesreleases" should be "releases"

Page 15, Line 22: ;; should be ;

Page 15, Line 22: The overlines should be removed for the fringe variables delta and chi to match the format in equation 3

Page 20, Line 4: "demonstratesan" should be "demonstrates an"

Page 24, Line 18: "WhileWhile" should be "While"

Page 25, Line 21: "subtypes in reported in" should be "subtypes reported in"

> They are all corrected.

Interactive comment on “The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm” by Man-Hae Kim et al.

Anonymous Referee #3

Received and published: 15 August 2018

We thank the referee for their careful reading of our manuscript and their thoughtful comments. We have reproduced the referee's comments below (in black) and included our responses in-line (in blue).

This paper introduces CALIPSO V4 updates in the L2 aerosol subtyping algorithms, investigates the resulting AOD differences between V3 and V4, and compares CALIOP AOD with AERONET and MODIS. This paper adequately summarizes information on the updates of the algorithms and characteristics of the products, includes useful information on them, and is well written. Thus this paper will be published after some minor revisions.

(1) Title of this paper seems to be inadequate. The key topic of this paper is to evaluate the algorithm to create the Version 4 L2 subtyping products by comparing with Version 3 products. The current title rather gives us impression that this study developed the algorithm.

> This paper is submitted as a part of the AMT special issue, “CALIPSO version 4 algorithms and data products” which introduces new algorithm updates for the CALIPSO version 4 products. The primary purpose is to introduce the new elements and refinements to the V4 algorithm that were developed by this study. The current title is also consistent with the title of Omar et al. (2009) which introduce the aerosol subtyping algorithm for the previous version (V3). For these reasons, we did not change the title.

(Omar, A., D. Winker, C. Kittaka, M. Vaughan, Z. Liu, Y. Hu, C. Trepte, R. Rogers, R. Ferrare, R. Kuehn, C. Hostetler, 2009: “The CALIPSO Automated Aerosol Classification and Lidar Ratio Selection Algorithm”, *J. Atmos. Oceanic Technol.*, 26, 1994-2014, doi:10.1175/2009JTECHA1231.1.)

(2) "Section 2" Section 2 seems to be too long and may mislead. The key part of this paper is thought to be section 3 (and section 4), however, section 2, which explains the updates of the algorithms and products and is not essential to this paper, looks the key of this paper.

> Section 2 is key topic of this study rather than Sections 3 and 4 as mentioned above. Sections 3 and 4 evaluate the consequences of changes described in Section 2 and seeks to demonstrate that improvements were made. We think that the order and importance of section 2 is fine the way it is. We slightly modified the last paragraph in Section 1 to make the purpose of the paper clear.

(3) minor comments and typos

P2 L6: "(AOD" => (AOD)

> It is corrected.

P11 L20: "aa" => "a"

> It is corrected.

P14 Fig 9 (b): X-axis of Fig. (b) seems different from the other figures (a and b).

> It is corrected.

P14 L7 "releasereleases" => release

> It is corrected.

P18 L13: "Based on an assumed external mixture of ~~~(65:35 by surface area)" What is 65:35? You should explain more on this point.

> We added “mixing ratio of 65:35” instead of “65:35”.

P21 Table 4: This table is very complicated and it is difficult to understand it. You need to explain more to let readers understand this table.

> We think the title of the table explains fully about the table.

P24 L15: "WhileWhile"

> It is corrected.

P32 Table 8 :Are the values of the MODIS (Land) negative? (e.g., 0.069 => -0.069)

> Positive values are correct. The mean CALIOP AOD is larger than the mean MODIS AOD over land for both V3 and V4 in this study. Large differences over the mid and south Africa (CALIOP is much larger as shown in Figure 16) are responsible for these results. But as mentioned in the text, the values in Table 8 are averaged values for all collocated data points between CALIOP and MODIS. They are not the mean values for gridded-averaged AOD differences. Further studies for the validation should be followed as mentioned in the last paragraph of Conclusion.

Interactive comment on “The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm” by Man-Hae Kim et al.

Anonymous Referee #4

Received and published: 19 September 2018

We thank the referee for their careful reading of our manuscript and their thoughtful comments. We have reproduced the referee’s comments below (in black) and included our responses in-line (in blue).

Review of “The CALIPSO Version 4 Automated Aerosol Classification and Lidar Ratio Selection Algorithm” by Kim et al.

This manuscript details and evaluates changes to the new version 4 CALIOP aerosol classification algorithm. Major highlights, the inclusion of a “dusty marine” type and improvements to smoke classification in the troposphere, and a new stratospheric aerosol subtyping algorithm. Changes in the algorithm lead to improved extinction retrievals when compared to AERONET and MODIS over the ocean. The manuscript is well written and thoroughly details modifications to the algorithm. Therefore, I recommend that this manuscript be accepted following minor revision.

Major Comments:

1. For evaluating CALIOP extinction using MODIS, why not include MODIS deep blue AOD, which provides AOD over land, including bright surfaces?

The MODIS Deep Blue retrievals would undoubtedly be useful in evaluating CALIOP extinction and AOD estimates over desert regions and other highly reflective land surfaces. However, investigating regional variations in CALIOP AOD (or regional AOD differences between CALIOP and MODIS) is not an integral part of this study. Instead our primary goals are to (i) explain the mechanics of the V4 algorithm and highlight the ways that the V4 algorithm differs from the V3 algorithm; and (ii) illustrate the effects of the algorithm changes on the CALIOP data products. As part of doing part (ii), we use MODIS as a “constant external reference”. And as long as we consistently use the same reference value (i.e., as long as we always compare V3 and V4 to the same MODIS data product), it really shouldn’t matter which reference we choose.

Two factors motivate our choice of the MODIS Dark Target data set as our reference.

1. As noted in the discussion paper (see lines 24–25 on page 31), numerous previous publications have compared MODIS and CALIOP V3 AOD estimates. All of these studies used Dark Target; none used Deep Blue. By choosing Dark Target as our reference, we readily facilitate comparisons between our results and those published previously.
2. In discussing the reviewer’s suggestion, we find ourselves highly persuaded by the Deep Blue vs. Dark Target comparison done by Sayer et al., 2014.

Due to the complexity of the global Earth (surface and atmospheric) system, and the optimization of the algorithms for global rather than regional applications, neither algorithm consistently performs better than the other. To make some general comments, over much of the global land surface, the AOD retrieved by the algorithms and the level of agreement with AERONET are similar, such that it may not matter for many applications which of DB or

DT a user chooses. DT often has a better correlation with AERONET than DB, but DB has (outside of tropical regions) greater spatial coverage, and tends to have smaller error compared to AERONET values in low-AOD conditions. DB and DT often exhibit much smaller AOD differences than would be expected given their estimated individual uncertainties, which should not be taken to mean that they have converged on the truth, but is a reminder that they should not be considered to be independent data sets.

(The additional emphasis simply reinforces the point made earlier; i.e., ‘as long as we consistently use the same reference value, it really shouldn’t matter which reference we choose.’)

In particular, this might help to validate the impacts of improved surface detection in Figure 15e.

The “improved surface detection” in V4 allows CALIOP to retrieve estimates of aerosol extinction coefficients and optical depths in regions where the signal was previously considered to be totally attenuated by overlying layers that were mistakenly identified as being opaque. A huge majority of these overlying layers are clouds. Since MODIS cannot detect the aerosol layers below these clouds, MODIS data products cannot help evaluate the accuracy of CALIOP’s subtype assignments in these aerosols.

Minor Comments:

Page 2, Line 2: “Aerosol subtyping...” This sentence doesn’t make sense to me.

The original text was “Aerosol subtyping is important all by itself for identifying aerosol by type. But it is also important for the CALIOP level 2 retrievals of aerosol optical properties.”

The revised text is “While CALIOP’s aerosol subtype classifications are useful as a wholly independent data product (e.g., Nowottnick et al., 2015; Sun et al., 2018), knowledge of aerosol subtype is also critically important for the CALIOP level 2 retrievals of aerosol optical properties.”

Page 2, Lines 12 – 16: These findings (dust in marine boundary layer and smoke layers classified as marine) were also reported in Nowottnick et al., 2015. Consider adding a reference to this paper.

Done

Page 5, Line 11: Is R_{mas} is defined as the ratio of the total attenuated backscatter to the molecular backscatter or the ratio of total attenuated backscatter to molecular attenuated backscatter? Some clarification would be useful to the reader. Also, is the molecular depolarization ratio assumed to be the same as in Omar et al., 2009? If so, please refer to that or provide to the reader.

Equation (1) in this manuscript is identical to equation (11) in Omar et al., 2009, as are the definitions of all quantities therein. As suggested, we have added a reference to the Omar paper.

Page 5, Lines 21-22: “First, . . .” This sentence is confusing, please consider revising.

The original text was “First, δ_p^{est} is a noisy quantity that has a positively skewed distribution that is exacerbated by solar background noise during the daytime.”

The revised text is “First, δ_p^{est} is a noisy quantity that is asymmetrically distributed, with a large positively skewed tail that can be considerably increased by solar background noise during the daytime.”

Page 6, Lines 9 – 12. In both V3 and V4 versions, why is polluted dust reduced over land compared to night? I’m assuming it’s due to better signal-to-noise at night, but an explanation might be useful.

The dominant source of this difference is the day-night differences in depolarization ratio SNR. See our reply to the previous comment; larger daytime δ_p^{est} values result in more dust relative to polluted dust.

Page 6, Line 12: “AODdifferences”. Missing a space.

Fixed

Page 7, Line 9: I agree that a simple assumption of the PBL height is sufficient, but some justification for the threshold value (2.5 km) from literature or a figure that shows 2.5 km is a good global approximation should be included here.

We added a reference to this paper: McGrath-Spangler, E. L., and A. S. Denning (2013), Global seasonal variations of midday planetary boundary layer depth from CALIPSO space-borne LIDAR, *J. Geophys. Res. Atmos.*, 118, 1226–1233, doi:10.1002/jgrd.50198.

Page 7, Lines 9-15: If I’m understanding the new modification to the algorithm correctly, polluted continental cannot be classified if the top of a layer is greater than 2.5 km. How does this impact the identification of long-range sulfate transport (ex. Asian pollution reaching North America)? This limitation might be noted here.

The more general limitation is that pollution which is lofted above 2.5 km will be misclassified as smoke – or clean continental if the integrated attenuated backscatter is very low. To acknowledge this limitation, the following sentence was added to the end of section 2.1.3: “A limitation of identifying smoke layers according to altitude is that pollution lofted by convective processes or other vertical transport mechanisms can be misclassified as elevated smoke.”

Page 8, Line 14: What is the integrated color ratio threshold for cloud vs. aerosol discrimination? The same as in Omar et al., 2009? Please include this in the discussion.

The color ratio threshold in the CALIOP cloud-aerosol discrimination (CAD) algorithm is not a single value, but is instead a function of latitude, longitude, and altitude. See Liu et al., 2009 and Liu et al., 2018 for details.

Page 9, Line 6: Consider explicitly stating the CALIPSO data and what version were used to make Figure 5.

We added “V4.1” to the modified caption for Figure 5. Note that figure 5 shows mid-layer temperatures for layers specifically identified as stratospheric aerosols (i.e., at temperatures below -70°C). As stated in the opening sentences of section 2.2, the classification of stratospheric layers as aerosols and clouds is a new feature first introduced in the version 4.1 data products. Previous releases did not report a stratospheric aerosol layer type.

Page 11, Lines 13-14. Is the tropopause altitude coming from GEOS output?

Yes

Page 11, Line 20. “aa”, replace with “a”.

Done

Page 11, Lines 20-22. Does this misclassification have a significant impact on the extinction product?

The lidar ratios currently specified for volcanic ash and dust are identical at 44 sr for both wavelengths, so in this situation the extinction coefficient and optical depth estimates will be identical irrespective of the aerosol type assigned.

Page 12, Line 4. “..”, replace with “.”

Done

Page 14, Line 7. “releasesreleases”, replace with “releases”.

Done

Page 16, Lines 6-9. Nice results using SCARF in the vertical. Is applying SCARF horizontally possible?

Perhaps...but that's something we wouldn't consider attempting until the version 5 data release at the very earliest

Page 19, Lines 23-24. Could you provide an example of detection of a tenuous layer?

See Figure 13 in Liu et al., 2018

Page 20, Line 4. “demonstratesan”, replace with “demonstrates”

Done

Page 22, Lines 19-20. There also is regions where polluted continental is the dominant aerosol type over southern Africa. So, the catch-all “PC/smoke” type works well in the region.

Page 23, Lines 11-12. Why does the overestimation of the estimated particulate depolarization ratio primarily affect dust/polluted dust over land?

This happens because the relative fraction of dust and polluted dust detected over land is typically much higher than over water.

Page 24, Line 18. “Whilewhile”, replace with “While”.

Done

Page 24, Line 19. Consider omitting “correctly”, since the occurrence of “dusty marine” cannot be independently validated.

We replaced “correctly” with “more realistically”

Page 24, Line 24-25. What are there less nighttime stratospheric aerosol features than during the day in V4?

To reduce/eliminate potential confusion, we have rewritten lines 23–25. The original sentences read as follows: “Stratospheric features detected in V3 are classified as cloud or stratospheric aerosol in V4. Stratospheric features in V3 are changed to cloud more frequently for nighttime. Similarly, stratospheric aerosol in V4 is less at nighttime than daytime compared to stratospheric features in V3.” This is the new text: “The generic stratospheric features previously identified in V3 are now classified as clouds or aerosol in V4. During the daytime, these V3 stratospheric features are more frequently identified as clouds, rather than aerosols. At night the situation is reversed: nighttime V3 stratospheric features are most often classified as aerosols.”

Page 25, Line 8. “V3 or V4”. Should this be “V3 and V4”?

The original text was “either/both V3 or V4”. The revised text is “either V3 or V4”.

Page 25, Line 22. What is “AVD”?

Atmospheric volume description; see page 20, line 12 in the discussion paper

Page 28 – Why does the daytime AOD decrease from V3 to V4 over parts of the ocean, while the nighttime does not?

In V3, mixtures of dust and marine aerosol were misclassified as polluted dust more frequently in the daytime relative to night. This is because of the noisiness of the daytime signal. These dust/marine mixtures were reclassified as dusty marine in V4, with a smaller lidar ratio. Since more layers changed from polluted dust to dusty marine in the daytime relative to night, the reduction in AOD is greater in the day over some parts of the ocean. During the night, the change in AOD is dominated by the increase in marine lidar ratio.

Page 30, Line 18. What is “STS”?

Supercooled ternary solution; see page 8, line 8 in the discussion paper

Page 32, Lines 21-23. “Resolution. . .CALIOP and MODIS over land are excluded from further consideration in our analyses.” However, MODIS over land is compared to CALIOP in Table 8 and CALIOP AODs are biased higher in V4. Consider adding a sentence to explain this result. Also, see Major Comment #1 regarding the possible inclusion of MODIS deep blue in this evaluation.

We made some initial comparisons of CALIOP, MODIS, and AERONET AODs retrieved over land. These comparisons are illustrated in Figure 16 and summarized in Table 8. As we state in the paper, “the inconsistency between the comparisons with AERONET and MODIS points to the need for further validation studies, especially over land.” This is the justification provided for limiting additional CALIOP–MODIS comparisons to over oceans only, where MODIS retrievals are considerably more reliable. We revisited our reasoning in light of your comments, and remain convinced that our initial choice was (and is) appropriate.

Page 33, Line 8. Consider omitting “(perfect agreement. . .).”

The phrase is correct as written; “perfect agreement” would indeed result in a slope of zero.

Figure 16: What is causing the AOD hotspots in V4 over Alaska and central North America? The lidar ratios from V3 to V4 for elevated smoke are similar and improvements to the surface detection in this region show a decrease in AOD (Figure 15e).

Figure 15e only shows the changes in AOD that can be attributed to improved surface detection (i.e., as determined according to the flowchart in Figure 14). With regard to Figure 16, the more relevant panel in Figure 15 is the daytime (right-hand) panel of 15a, which shows the total CALIOP AOD change from V3 to V4. (The nighttime panel of 15a is irrelevant in this context, because Figure 16 shows comparisons to MODIS, which only estimated AOD during the daytime.) According to the color scale in Figure 15, the increases in CALIOP daytime AOD in the “hot spot” regions are somewhere between 0.05 and 0.10. This seems to us to be consistent with the changes shown in Figure 16; e.g., the V3 AODs in central North America range between ~0.050 lower than MODIS (pale blue color) to 0.125 higher (reddish brown color), whereas the V4 AODs are between ~0.05 and ~0.15 higher.

Figures & Tables:

Figure 1: Caption – Consider forward referencing the justification for using 2.5 km as a threshold in the manuscript (page 6 in section 2.1.1 and section 2.1.3).

We added a reference to section 2.1.3

Table 1: Last line – “Canadians”, replace with “Canadian”.

We changed “Canadians fire” to “Canadian fires”

Figure 7: Since depolarization and color ratio are inputs to the new stratospheric typing algorithm, consider adding those quantities to the figure.

It’s our opinion that Figures 7, 8, and 9 provide sufficient information to illustrate our points, and would be made overly-complicated by adding even more panels. Instead we have added text to the captions of these figures saying that “Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at [https://www-calipso.larc.nasa.gov/...](https://www-calipso.larc.nasa.gov/)”

Table 4: Consider adding “Tropo.” to the “Aerosol” header in the 5th column.

Since V3 did not separately identify stratospheric aerosols, this additional notation would be redundant.

Figure 15: Is it possible to adjust the color bar to resolve differences in V3 and V4 AOD more clearly (use a finer delta AOD)?

We experimented with **LOTS** of different color bars for this figure, and the one we’ve used, while still not perfect, was nevertheless the best of the bunch.

References

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