

## ***Interactive comment on “Level 1b error budget for MIPAS on ENVISAT” by Anne Kleinert et al.***

**Anne Kleinert et al.**

anne.kleinert@kit.edu

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We thank Anonymous Referee #2 for reviewing the paper and the valuable comments. Our answers to the comments are given below. Relevant referee comments are inserted *in italics*.

*page(p)1 line(l)18: The examples for clouds comprise only PSCs and PMCs. I'd suggest to also add an example for upper troposphere/ lower stratosphere cirrus clouds e.g. Spang et al., ACP, 2012 or Sembhi et al., ACP, 2012.*

We will add the publication of Sembhi et al. (2012) as reference.

*p2 l17 – 18: Please consider adding a sentence for explanation here. It takes some time studying Fig. 1 to understand how 4 detectors can cover 5 spectral bands even if one detector fails.*

C1

We will give the information on the channels and bands first and then add an explanation on the spectral coverage of the channels by writing:

"The spectra from the 8 detectors are summarized in 5 spectral band (denoted A, AB, B, C, and D in Fig. 1). The spectral coverage of the individual detectors is different for the two ports (see Fig. 1) in order to ensure full spectral coverage even if one detector fails. Channel A2, which is optimized for the spectral range of band A, also covers the range of band AB, and channel B1, which is optimized for band AB, also covers band B."

*p4 l5: Please add some description of the parameters given in Table 1. E.g., what does coadditions per gain measurement mean?*

We will change "number of coadditions" to "number of spectra co-added"

Furthermore we will spend a few more words on the calibration in the text explaining the parameters given in Table 1:

"For radiometric calibration, the instrument points towards the internal blackbody or into deep space, i.e. at a tangent altitude of about 210 km. The radiometric gain is determined from pairs of blackbody and deep space measurements on a daily basis, and additional deep space measurements are performed for offset determination several times per orbit. In order to enhance the signal-to-noise-ratio, several spectra are co-added for the calibration measurements. Gain and offset are determined individually for the two sweep directions of the interferometer."

*p4 l14: What does simple mean here? Is the correction algorithm cutting the spikes?*

If a spike is detected, the values of the affected data points are divided by 2 until they are below a threshold defined by the adjacent points not affected by the spike. We will add this information in the text and add a reference to the Algorithm Technical Baseline Document (ATBD) for MIPAS Level 1B Processing for more detailed information.

*p6 l8: Please state what low means. 10 km, 20 km or 50 km? Is this factor linear from*

C2

*top to bottom?*

"low" means the lowermost tangent altitude, i.e. below 10 km. We will add this information in the text.

The additional contribution to the NESR is due to the photon noise of the atmospheric signal. Therefore this factor is not linear but dependent on the vertical profile of the atmospheric spectral radiance in the respective spectral range.

*p6 18 – 10: Does this have any practical implications? Does this mean that when investigating measurements at e.g 10 km all data points with radiance  $\leq \text{NESR} \times 1.5$  should be discarded / are not significant? Please clarify.*

This information is given here in order to provide an overview of the expected NESR range. The practical implications depend on the setup for the retrieval of atmospheric parameters. The NESR of each spectrum is part of the level 1b product and is considered in the retrieval process.

We will change the text to:

"For atmospheric measurements, the NESR is larger than the NESR<sub>0</sub> because of the increasing photon load on the detectors. The NESR for atmospheric measurements at low tangent altitudes (below 10 km) is about 20 to 50% larger than the NESR<sub>0</sub>, depending on the strength of the atmospheric signal in the different bands (not shown)."

*p7 114: Please add to which value the requirement of the scaling accuracy was relaxed.*

We will add: "was relaxed to 5%"

*p12 14 – 8 Figure 9: There are 3 spectral bands shown in Figure 9 for band A (best visible at 180° Latitude), but the label and text indicate only 2 bands.*

In band A the data was shown separately for channel A1 and A2. Since the offset drift along the orbit is quite similar, we will change the figure such that the mean of the two channels is shown.

C3

*Further, what does Latitude <0, >90, <180, <270 mean? Where is the Equator?*

0° and 180° denote the equator, while 90° and 270° denote the north and south pole, respectively. We will clarify this in the figure by adding to the abscissa "Eq, 90° N, EQ, 90° S" at 0, 90, 180, and 270 degrees, respectively.

*Is each data point representing a single sweep or a scan measurement?*

For each offset measurement, 6 interferograms are acquired in FR mode (3 forward, 3 reverse, see Table 1). Even when co-adding the 6 resulting spectra, the noise of these offset measurements is too high to reveal the offset variation along the orbit. Since the offset measurements are always taken at the same latitude, the offset spectra of 15 orbits of November 2003 were co-added (i.e. 90 spectra per measurement point).

We will add this information in the text.

*In the text it says that in FR mode the variation between two subsequent measurements is below  $2 \text{ nWcm}^{-2} \text{ sr}^{-1} \text{ cm}$  in band A, but in Figure 9 it goes down to  $-4 \text{ nWcm}^{-2} \text{ sr}^{-1} \text{ cm}$ .*

The overall variation along the orbit is up to  $4 \text{ nWcm}^{-2} \text{ sr}^{-1} \text{ cm}$ , but the largest variation between two measurement points (e.g. from point #4 to point #5 between 60 and 80° N) is around  $2 \text{ nWcm}^{-2} \text{ sr}^{-1} \text{ cm}$ .

*Please clarify.*

We will change the paragraph on the temporal variation of the offset to:

"The instrument self emission varies slightly along the orbit. This is well captured by the regular offset measurements. Figure 9 shows the offset variation along the orbit for selected wavenumbers in the different spectral bands in November 2003 (FR mode). The position of the offset measurements within the orbit is represented in terms of latitude. 0° represents the ascending equator crossing, 90° represents the north pole, 180° the descending equator crossing and 270° the south pole. The offset measurements are always taken at the same latitude positions. In order to reduce

C4

the noise level, the offset spectra of 15 orbits have been co-added for each latitude position (i.e. 90 spectra per measurement point, since 6 sweeps (3 forward and 3 reverse) are taken per offset measurement). The variation between two subsequent offset measurements (i.e. between two data points in Fig. 9) is below  $2 \text{ nWcm}^{-2}\text{sr}^{-1}\text{cm}$  in band A and even lower in the other spectral bands. In OR mode, where the time span between two offset calibration measurements is larger, the variation is below about  $4 \text{ nWcm}^{-2}\text{sr}^{-1}\text{cm}$  and still below the offset error due to noise."

*p13 l26 – 28: Did you assume 91 % modulation efficiency for all bands? Or did you derive it using the DC-zero method for all detectors but B1 and B2? Please clarify.*

This assumption is valid for all non-linear channels. We will clarify this by writing:

"Therefore the modulation efficiency is estimated from the optical specifications and instrument properties to be 91 % in all non-linear channels (Kleinert et al., 2015). This is based on the assumption that the instrument is well aligned and the modulation efficiency is rather wavenumber independent in the relevant spectral range of  $685 \text{ to } 1500 \text{ cm}^{-1}$ ."

*p13 l31: And what about bands AB, C, D?*

With "B and A bands" we meant the channels B1 and B2 as well as the channels A1 and A2. In order to make this clear and following a suggestion of reviewer 1, we will rephrase the text and write:

"There are three main sources of uncertainty for the determination of the non-linearity: (1) the assumption, that the detector curve is characterized by a 3rd order polynomial for channels A1 and A2 and by a 2nd order polynomial for channels B1 and B2, ..."

Bands C and D are not subject to non-linearity correction.

*p18 Figure 12: Is my assumption correct that altitude level 1 is low (about 10 km) and altitude level 26 is high (about 65 km) altitude? Please provide a description in the caption.*

C5

We will add the corresponding information in the caption:

"Altitude 26 corresponds to about 67 km, altitude 1 to about 7 km."

*Please consider a change of the color scale to blue/green for excellent agreement (ratio close to 1) and orange/red for slightly reduced agreement (ratio smaller than 1).*

Many people associate red with high and blue with low values, therefore we want to keep the color scale as it is. Instead, we will invert the ratio, i.e. we will show  $A2 / A1$  instead of  $A1 / A2$ . Then the reduced agreement will be represented by orange / red colors. Furthermore this representation is in better agreement with Fig. 11, where also the ratio of  $A2 / A1$  is shown.

*p20 l1 – 3, l6-15: Do you have any idea what is causing the day-night difference, latitudinal and seasonal variation of the offset?*

No. We have searched for correlation with instrument temperatures and cloud cover but we did not find a significant correlation. We will add a corresponding sentence at the end of section 6.2 in the text:

"Also the day/night variation as well as the seasonal, latitude dependent variation of the offset cannot be explained with known instrument effects, but the observed offset variation gives an impression of the expected offset error and its variation."

*p22 l6: Please explain why the spectral accuracy is given like a mixing ratio in ppm. I'd rather expected values in  $\text{cm}^{-1}$  as you provide in line 7.*

The spectral accuracy is driven by the exact knowledge of the laser wavelength, and an error in the laser wavelength corresponds to a scaling error of the spectral axis. Therefore the absolute error (in  $\text{cm}^{-1}$ ) is wavenumber dependent while the relative error is valid for the whole spectral range. The unit ppm is a general relative unit which is widely used for mixing ratios but is also very common in other fields. We think that 0.14 ppm is easier to read than 0.000014%, which would be equivalent.

C6

*p23 l12: Which standard atmosphere did you use (the U.S. Standard Atmosphere or any other)? Is this atmosphere anywhere available?*

The atmosphere used is basically the U.S. Standard Atmosphere with some minor modifications.

*Technical comments*

All technical comments will be addressed in the text.

*Text font and unit font seem to be different throughout the manuscript e.g p1 l13.*

This is the outcome of the Copernicus template.

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Interactive comment on Atmos. Meas. Tech. Discuss., doi:10.5194/amt-2018-185, 2018.