Dear Dr. Saverio Mori,

Thank you very much for kindly inviting us to submit a revised manuscript titled "Simulating precipitation radar observations from a geostationary satellite" to Atmospheric Measurement Techniques. We would also appreciate the time and effort you and the reviewers have dedicated to providing insightful feedback on the ways to strengthen our paper.

We would like to submit our revised manuscript. We have incorporated changes that reflect the suggestions you and the reviewers have provided. We hope that the revisions properly address the suggestions and comments.

Sincerely,

A. Okazaki, T. Honda, S. Kotsuki, M. Yamaji, T. Kubota, R. Oki, T. Iguchi, and T. Miyoshi

The reviewer comments are in blue and italic and the replies are in black.

Anonymous Referee #1

The manuscript presents the usefulness of a "feasible" Ku-band precipitation radar for a geostationary satellite (GeoSat/PR). It is an effort ongoing at JAXA to overcome two limitations of orbiting radar-based systems such as TRMM or GPM, namely, the limited swath and revisit time. A geostationary satellite needs a larger antenna than TRMM PR and GPM KuPR. A 20-m antenna for a 20 km footprint is considered in the study for its feasibility. The scan of the radar is within 6° that makes measurements available for a circular disk with a diameter of 8400 km.

Effects of Non Uniform Beam Filling (NUBF) and clutter are presented using an extremely simple cloud model. The impact of coarse resolutions of the GeoSat/PR is quantified on 3-D Typhoon observations obtained with realistic simulations. The subject of is important and the manuscript is, in general, well written. Therefore it can be recommended for publication. I have some comments and suggestions that should result in a minor revision work for the authors.

1. What is the need of the approximation of equation 4? (moreover, tetab is not defined in the text).

We made the approximation to truncate the edge of the Gaussian function and to confine the calculation domain for Pr and Ps. Nevertheless, we changed the beam pattern from Gaussian to the uniform distribution to consider the impact of sidelobe clutter. We also added the definition of theta_b. Thank you.

2. The model of NRCS of ocean surface does not take into account the modification due to impinging rain. Authors should provide evidence of the fact that this contribution can be neglected.

We appreciate the suggestion. As previous studies show (e.g. Braun et al., 1999; Contreras et al., 2003), the impact of impinging rain is negligible at high wind speed (10 m s⁻¹~). Because the main target of this study is a typhoon which accompanies strong winds, we did not account for the modification due to impinging rain. We included the reason for the assumption of the study in the revised manuscript.

3. Lines 233-234: I guess that the case of a 5 km beamwidth is given provided to make something similar to TRMM PR as reference. The text should better explain why the authors choose the different spatial resolutions. Also the "feasibility" of a 20x20 m antenna should better justified.

We simulated the case with 5 km beam width to see the sensitivity of the result to radar resolution. We included the reason why we show the case in the revised manuscript.

For the latter point, we cited a study by Meguro et al. (2009) and Joudoi et al. (2018) on the feasibility of 20m-by-20m size antenna in the revised manuscript.

4. Lines 350-351: Authors guess that Ku attenuation can be corrected. Do they think that SRT method can be applied with this configuration? (maybe some references are needed; the same is for sidelobe correction)

We are not sure if the SRT method is applicable to this radar measurement because of its relatively large scattering volume: it is possible that scattering from the surface is not affected by the attenuation because of NUBF. However, development of the attenuation correction method is out of the scope of this study. Therefore, we would like to leave this point for future work. Nevertheless, we added discussion on the impact of the attenuation and the attenuation correction in the revised manuscript. We also included discussion on the sidelobe clutter.

5. Figure 6: please report in the caption that "distance" in the panel is referred to the nadir.

We defined the term "distance" explicitly in the revised manuscript. Thank you.

6. Figure 8, 9, 11, 12: The captions report "Note that the areas where reflectivity form precipitation larger than 0 dBZ are shaded". It is not clear. In figure 9 and 12, close to ground we can see some darker grey that maybe are due to the resolution of the manuscript available to reviewers.

We revised the caption as "Area where reflectivity from precipitation less than 0 dBZ are left blank". To make the point clear, we also modified the figure in the revised manuscript.

7. Figure 8: I suggest to remove wind from panel (a) because it just clutters the "true" reflectivity image.

Removed.

References:

Braun, N., Gade, M., & Lange, P. A., Radar backscattering measurements of artificial rain impinging on a water surface at different wind speeds, paper presented at 1999 International Geoscience and Remote Sensing Symposium (IGARSS), Inst. Of Elect. And Elect. Eng., New York, 1999.

Conteran, R. F., Plant, W. J., Keller, W. C., Hayes, K., & Nystuen, J., Effects of rain on Ku-band backscatter from the ocean, J. Geophys, Res., 108(C5), 3165, 2003.

Joudoi, D., Kuratomi, T., & Watanabe, K., The construction method of a 30-m-class large planar antenna for Space Solar Power Systems, 69th International Astronautical Congress, Bremen, Germany,

1-5, October 2018.

Li, X., He, J., Wang, C., Tang, S., & Hou, X., Evaluation of surface clutter for future geostationary

spaceborne weather radar, atmosphere, 8, 14.

Meguro, A., Shintate, K., Usui, M., & Tsujihata, A., In-orbit deployment characteristics of large

deployable antenna reflector onboard Engineering Test Satellite VIII, Acta Astronautica, 65(9-10),

1306-1316, 2009.

Anonymous Referee #2

The manuscript "Simulating precipitation radar observations from a geostationary satellite" details a

theoretical study of the performance of a hypothetical geostationary weather radar using both a

uniform rain layer and more realistic cloud model output. Offering a cogent analysis of the challenges

of observing precipitation in the presence of surface clutter due to the coarse resolution of a

geostationary platform, the paper is straightforward, well-written, and highly relevant, and should

be published after minor revisions.

Specific Comments

There is one point that is really lacking from the discussion: sidelobe clutter. The idealized antenna

pattern in the paper neglects antenna sidelobes. Given the attention focused on realistic distributions

of precipitation, such analysis can be considered outside of the scope of the paper; however,

 $discussing\ the\ results\ presented\ in\ this\ manuscript\ in\ the\ context\ of\ other\ studies\ that\ look\ at\ sidelobe$

clutter (Kubota et al., 2016; Li et al., 2017) would add more depth to the conclusions of the paper.

Thank you for the comments and the helpful references. We included the discussion on the impact

of sidelobe clutter and sidelobe clutter correction. Although the impact is not negligible, the

correction method proposed by Kubota et al. (2016) should be applicable after a reasonable number

of observations are collected.

Technical Corrections

Throughout the paper, "incident" should be "incidence."

Corrected in the revised manuscript.

Lines 44-45: contaminations from the surface clutters -> contamination from surface clutter

Corrected

Line 51: the surface clutters -> surface clutter

Corrected

Line 122: The word "power" should come between "path" and "beam"

Corrected

Line 182: The word "image" after "schematic" is unnecessary.

Removed

Line 227: Include "the" before "Marshall Islands."

Included

Line 228: Remove "the" before "generation."

Removed

1	
2	
3	
4	Simulating precipitation radar observations from a geostationary satellite
5	
6	Ву
7	
8	Atsushi Okazaki ¹ , Takumi Honda ¹ , Shunji Kotsuki ^{1,2} ,
9	Moeka Yamaji ³ , Takuji Kubota ³ , Riko Oki ³ ,
10	Toshio Iguchi ⁴ ,
11	and Takemasa Miyoshi ^{1,2,5,6,7}
12	
13	¹ RIKEN Center for Computational Science, Kobe, Japan
14	² RIKEN interdisciplinary Theoretical and Mathematical Sciences Program, Kobe, Japan
15	³ Earth Observation Research Center, Japan Aerospace Exploration Agency, Tsukuba, Japan
16	⁴ National Institute of Information and Communications Technology, Koganei, Japan
17	⁵ Department of Atmospheric and Oceanic Science, University of Maryland, College Park,
18	College Park, Maryland
19	⁶ Japan Agency for Marine-Earth Science and Technology, Yokohama, Japan
20	⁷ Prediction Science Laboratory, RIKEN Cluster for Pioneering Research, Kobe, Japan
21	
22	
23	
24	
25	
26	To be submitted to the Atmospheric Measurement Technique
27	
28	
29 30 31	Corresponding authors: Atsushi Okazaki and Takemasa Miyoshi, RIKEN Center for Computational Science, 7-1-26 Minatojima-minami-machi, Chuo-ku, Kobe, Hyogo 650-0047, Japan (atsushi okazaki@riken ip. takemasa miyoshi@riken ip.)

Abstract

 Spaceborne precipitation radars, such as the Tropical Rainfall Measuring Mission (TRMM) and the Global Precipitation Measurement (GPM) Core Observatory, have been important platforms to provide —a direct measurement of three-dimensional precipitation structure globally. Building upon the success of TRMM and GPM Core Observatory, the Japan Aerospace Exploration Agency (JAXA) is currently surveying the feasibility of a potential satellite mission equipped with a precipitation radar on a geostationary orbit. The quasi-continuous observation realized by the geostationary satellite radar would offer a new insight into meteorology and would advance numerical weather prediction (NWP) through their effective use by data assimilation.

Although the radar would be beneficial, the radar on the geostationary orbit measures precipitation obliquely at off-nadir points. Besides, the observing resolution will be several times larger than those onboard TRMM and GPM Core Observatory due to the limited antenna size that we could deliver. The tilted sampling volume and the coarse resolution would result in more contaminations from the surface clutters clutter. To investigate the impact of these limitations and to explore the potential usefulness of the geostationary satellite radar, this study simulates the observation data for a typhoon case using an NWP model and a radar simulator.

The results demonstrate that it would be possible to obtain three-dimensional precipitation data. However, the quality of the observation depends on the beam width, the beam sampling span, and the position of precipitation systems. With a wide beam width and a coarse beam span, the radar cannot observe weak precipitation at low altitudes due to the surface cluttersclutter. The limitation can be mitigated by oversampling (i.e., a wide beam width and a fine sampling span). With a narrow beam width and a fine beam sampling span, the surface clutter interference is confined to the surface level. When the precipitation system is located far from the nadir, the precipitation signal is obtained only for strong precipitation.

1. Introduction

57

58

59

60

61

62

63

64

65

66

67

68

69

70

71

72

73

74

75

76

77

78

79

80

81

Knowing the distribution of precipitation in space and time is essential for scientific developments as precipitation plays a key role in global water and energy cycles in the Earth system. Such knowledge is also indispensable to our daily lives and disaster monitoring and prevention. However, observing precipitation globally is not an easy task. Ground-based observations may not adequately represent the rainfall amounts of a broader area since the vast surface of the earth remains unobserved (Kidd et al., 2016). Alternatively, satellites provide an ideal platform to observe precipitation globally. There are three types of methods to observe or estimate precipitation from satellites: visible and infrared, passive microwave, and active microwave (radar). Among them, radar is the most direct method and is the only sensor that can provide three-dimensional structure of precipitation. The first satellite equipped with precipitation radar was the Tropical Rainfall Measuring Mission (TRMM) launched in 1997 (Kummerow et al., 1998; Kozu et al., 2001), and the first satellite-borne dual-frequency precipitation radar onboard the Global Precipitation Measurement (GPM) Core Observatory was launched in 2014 (Hou et al., 2014; Skofronick-Jackson et al., 2017). The observations produced by the precipitation radars onboard the low-earth-orbiting satellites have been contributing to enhance our knowledge on meteorology. For instance, their ability to see through clouds helps understand storm structures (Kelly et al., 2004) and the nature of convection (e.g. Takayabu 2006; Hamada et al., 2015; Houze et al., 2015). Building upon the success of the TRMM and GPM Core Observatory, the Japan Aerospace Exploration Agency (JAXA) is currently studying the feasibility of a geostationary satellite equipped with precipitation radar (hereafter, simply "GeoSat/PRGPR"). The main advantage of GeoSat/PRGPR over the existing ones with precipitation radar is the observation frequency. Because the previous satellites are low earth orbiters, they cannot observe the same area frequently. For instance, TRMM overpasses a 500 by 500 km² box 1-2 times a day on average (Bell et al., 1990). To make the situation worse, it is difficult to capture the whole figure of a large-scale precipitation

system (e.g. tropical cyclone) at once due to the narrow scan swath (e.g. 245 km for KuPR on GPM Core Observatory). Alternatively, GeoSat/PRGPR stays at the same location all the time and continuously measures precipitation in its range of observation. Those data are expected to help understand important scientific issues. Furthermore, those frequent data could improve the skill of numerical weather prediction (NWP) through data assimilation, leading to more accurate and timely warnings of floods and landslides.

82

83

84

85

86

87

88

89

90

91

92

93

94

95

96

97

98

99

100

101

102

103

104

105

106

Although GeoSat/PRGPR would be beneficial, it has potential disadvantages. Since GeoSat/PRGPR measures precipitation from the geostationary orbit, it measures precipitation obliquely at off-nadir points. It is unclear how severely this may degrade the observation. In addition, the tilted sampling volume worsens the contamination of the precipitation echo by the surface clutter. Takahashi (2017) showed that the clutter height monotonically increases with the incidence angle from the wide swath observation during the end-of-mission experiment of the TRMM. The impact of the surface clutter interference with a large incident angle would be large if the horizontal resolution of the radar is coarse, and that is the case for GeoSat/PRGPR. The horizontal resolution is limited by the antenna size and wavelength. A larger antenna is needed for higher resolution. However, it is challenging to construct a large antenna on a geostationary orbit. Currently consider a 20 m by 20The JAXA has launched a satellite with a relatively large antenna of 19 m by 17 m (ETS-VIII, Meguro et al., 2009). Based on the experience and further efforts (Joudoi et al, 2018), currently we consider a 30-m-by-30-m square antenna as a feasible choice, whose spatial resolution is 20 km at nadir, that is several times larger than that of TRMM/PR (4.3 km). To investigate the mission feasibility of GeoSat/PRGPR, it is important to simulate observation of GeoSat/PRGPR and to find its potential usefulness and weakness.

In the past decade, a geostationary radar instrument known as the Next Generation Weather Radar (NEXRAD) In Space (NIS; Im et al., 2007) has been proposed. A few studies demonstrated the capability of NIS. Lewis et al. (2011) examined the feasibility of a 35 GHz Doppler radar to observe

the wind field. They showed that the direct measurement of winds from the geostationary orbit would be possible for a hurricane case. Li et al. (2017) evaluated the impact of surface clutter for the same radar assuming a uniform rain layer. They showed that most of rain echoes at off-nadir scanning angles will not be contaminated by the surface clutter, when rain intensity is greater than 10 mm h^{-1} .

However, the impact of the surface clutter and the oblique measurement would depend on the shape and position of the precipitation system. This study extends Li et al. (2017) for a realistic case. By considering the importance to societal and scientific benefit, we chose a typhoon as a test case in this study. We investigate the impact with various typhoon locations and radar parameters such as radar beam width and sampling span for realistic scenarios of a simulated typhoon case.

This paper is structured as follows. Section 2 describes the proposed specifications of GeoSat/PRGPR and presents the newly-developed radar simulator. Section 3 describes the characteristics of the observation with GeoSat/PRGPR for an idealized case. Section 4 presents the results of applying the radar to a typhoon case. Section 5 provides the sensitivity results to the location of the typhoon. Section 6 shows the impact of attenuation and sidelobe clutter. Finally, Section 6 provides conclusions.

2. Radar simulator

2.1. Radar specifications

The specifications of GeoSat/PRGPR are summarized in Table. 1. The GeoSat/PRGPR is anticipated at 13.6 GHz, the same as KuPR onboard GPM Core Observatory. We assume a 2030-m-by-2030-m square phased array radar with the half-power beam width (-3 dB) of 0.032°, with which we can achieve horizontal resolution of 20 km at the nadir point on the earth surface. The range resolution is 500 m. Though shorter-range resolution is technically viable, we adopt this value by considering the balance to the horizontal resolution. The number of the range bins is 60; the

corresponding height of the beam center ranges from the surface to 30 km at nadir. The scan angle is $\pm 6^{\circ}$, which covers a circular disk with a diameter of 8400 km on Earth's surface. If GeoSat/PRGPR were placed at 135°E of the equator, it would cover from Sumatra to New Caledonia, and from Australia to the southern half of Japan.

We assume that the satellite can complete the full disk scan within one hour. In addition to the normal mode, it is expected to have several modes and can observe a targeting precipitation system intensively as in Himawari-8 (Bessho et al., 2016). In this study, we focus only on snap-shots and do not consider the time for GeoSat/PRGPR to complete the full disk scan.

2.2. Precipitation reflectivity

This subsection describes how to calculate reflectivity measured by GeoSat/PR (Z_m).GPR (Z). First, we convert model hydrometeors (cloud water, cloud ice, rain, snow, and graupel) to reflectivity on the total backscattering ($\overline{\sigma}_b$) and extinction coefficients (\overline{k}_{ext}) at every model grid (\overline{Z}_e)point using an existing software called Joint Simulator for Satellite Sensors (Joint-Simulator; Hashino et al., 2013). The Joint-Simulator is a suite of software that simulates satellite observations based on atmospheric states simulated by cloud-resolving models. The computation of reflectivity in Joint-Simulator is based on Masunaga and Kummerrow (2005)The total backscattering and extinction coefficients are obtained respectively by summing single-particle backscattering (σ_b^s) and extinction coefficients (k_{ext}^s) for the i th hydrometeor specie following its drop size (D) distribution (N(D)) as follows:

$$\underline{Z_e} = \frac{\lambda^4}{\pi^5 |K|^2} \overline{\sigma}_{br} \overline{\sigma}_b = \sum_{i=1}^{n_{spec}} \int_0^\infty \sigma_{b,i}^s(D) N(D) dD, \tag{1}$$

$$\overline{k}_{ext} = \sum_{i=1}^{n_{spec}} \int_0^\infty k_{ext,i}^s(D) N(D) dD, \qquad (2)$$

with

$$\overline{\sigma}_{b} = \sum_{i=1}^{5} \int_{0}^{\infty} \sigma_{b,i}^{s}(D) N(D) dD, \tag{2}$$

where λn_{spec} is the wavelength, K the function number of the complex reflractivity index of scattering particles, and $\overline{\sigma}_B$ the total backscattering coefficient per unit volume. Following Masunaga and Kummerow (2005), $|K|^2$ is assumed to be a constant (0.925) in this study. The total backscattering coefficients are obtained by summing single particle backscattering (σ_B^s) for the i th hydrometeor specie following its drop size (D) distribution (N(D)). hydrometeor species. In this study, up to five hydrometeor species, i.e., cloud water, cloud ice, rain, snow, and graupel, were considered. The Mie approximation is assumed used to calculate the single particle backscattering $\sigma_{b,i}^s$ and $k_{ext,i}^s$ for all the species (Masunaga and Kummerow, 2005).

153

154

155

156

157

158

159

160

161

162

163

164

165

166

167

168

After calculating the reflectivity on the $\overline{\sigma}_b$ and \overline{k}_{ext} at every model grid, they point, the grid point values are integrated over the scattering volume following the antenna pattern. The radar-received

power from precipitation (P_n) of the beam pointing range r_0 and scan angle θ_0 and ϕ_0 is given by

$$=\frac{P_{t}\lambda^{2}}{(4\pi)^{3}}\int_{r_{0}-c\tau/4}^{r_{0}+c\tau/4}\int_{\theta_{0}-\pi}^{\theta_{0}+\pi}\int_{\phi_{0}-\pi/2}^{\phi_{0}+\pi/2}f^{4}(\theta,\phi)r^{-2}Z_{e}(r,\theta,\phi)\cos\theta\ d\phi\ d\theta\ dr\int_{r_{0}-c\tau/4}^{r_{0}+c\tau/4}\int_{\theta_{0}-\pi}^{\theta_{0}+\pi}\int_{\phi_{0}-\pi/2}^{\phi_{0}+\pi/2}f^{-2}(r,\theta,\phi)\cos\theta\ d\phi\ d\theta\ dr$$

where P_t is the transmitted power, c the speed of light, τ the pulse duration, and f^4 the two-way effective beam weighting function. Here weWe assumed the uniform antenna pattern as the Gaussian function, which, whose sidelobe level is approximated by the following fifth order polynomial (Fig. 1; Gaspari and Cohn, 1999):-13.26 dB:

$$f^{\frac{2}{2}}(\psi) = \begin{cases} -\frac{1}{4}\psi^{5} + \frac{1}{2}\psi^{4} + \frac{5}{8}\psi^{3} - \frac{5}{3}\psi^{2} + 1 & (0 \le \psi < 1) \\ \frac{1}{4}\psi^{5} - \frac{1}{2}\psi^{4} + \frac{5}{8}\psi^{3} + \frac{5}{3}\psi^{2} - 5\psi + 4 - \frac{2}{3}\psi^{-1} & (1 \le \psi < 2) \end{cases} f^{2}(\psi)$$

$$= \left(\frac{\sin\psi}{\psi}\right)^{2} \tag{4}$$

where $\psi = \sqrt{(\theta - \theta_0)^2 + (\phi - \phi_0)^2}/\Psi$, and Ψ is obtained by solving the equation $f\left(\frac{\theta_B}{2}\right)$

Formatted: Indent: First line: 0 ch

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto
Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto
Formatted: Font color: Auto

Formatted: Font color: Auto

Formatted: Font color: Auto

Farmenttad. Forst color: Auto

Formatted: Font color: Auto

169 $\left| \frac{\Psi}{2} \right| f^2 \left(\frac{\theta_B}{2} / \Psi \right) = 0.5$ for Ψ . The, and θ_B is the half-power beam width (-3 dB). $A_P(r, \theta, \phi)$ is the

attenuation factor from the radar reflectivity measured by GeoSat/PR is to range r in the direction of

 (θ, ϕ) and calculated as follows: by

170

171

172

173

174

175

176

177

178

179

180

181

183

184

$$Z_{\mathbf{m}} = \frac{\int_{r_{0}}^{r_{0}+\frac{\epsilon r}{4}}^{\frac{\epsilon r}{4}} \int_{\theta_{0}-\pi}^{\theta_{0}+\pi} \int_{\phi_{0}-\frac{\pi}{2}}^{\phi_{0}+\frac{\pi}{2}} f^{4}(\theta,\phi) r^{-2} Z_{e}(r,\theta,\phi) \cos\theta \,d\phi \,d\theta \,dr}{\int_{r_{0}-\frac{\epsilon r}{4}}^{r_{0}+\frac{\epsilon r}{4}} \int_{\theta_{0}-\pi}^{\theta_{0}+\frac{\pi}{2}} \int_{\phi_{0}-\frac{\pi}{2}}^{\theta_{0}+\frac{\pi}{2}} f^{4}(\theta,\phi) r^{-2} \cos\theta \,d\phi \,d\theta \,dr} - \mathbf{A}_{P}(r,\theta,\phi)$$

$$= \exp\left[-0.2\ln(10)\int_{0}^{r} \bar{k}_{ext}(r',\theta,\phi) dr'\right].$$
(5)

Formatted: Centered, Indent: First line: 0 ch

Formatted Table

Formatted: Font color: Auto

The radar reflectivity measured by GPR is calculated as follows:

$$Z = \frac{\lambda^4}{\pi^5 |K|^2} \frac{\int_{r_0 - \frac{c\tau}{4}}^{r_0 + \frac{c\tau}{4}} \int_{\theta_0 - \pi}^{\theta_0 + \pi} \int_{\phi_0 - \frac{\pi}{2}}^{\phi_0 + \frac{\pi}{2}} f^4(\theta, \phi) \bar{\sigma}_b(r, \theta, \phi) A_P(r, \theta, \phi) \cos\theta \ d\phi \ d\theta \ dr}{\int_{r_0 - \frac{c\tau}{4}}^{r_0 + \frac{c\tau}{4}} \int_{\theta_0 - \pi}^{\theta_0 + \pi} \int_{\phi_0 - \frac{\pi}{2}}^{\phi_0 + \frac{\pi}{2}} f^4(\theta, \phi) r^{-2} \cos\theta \ d\phi \ d\theta \ dr}, \tag{6}$$

where λ is the wavelength, K the function of a complex refractivity index of scattering particles.

Following Masunaga and Kummerow (2005), |K|² is assumed to be a constant (0.925) in this study.

We do not consider the impact of attenuation ($A_p = 1.0$ everywhere) as it can be corrected with

proper methods (e.g. Iguchi et al., 2000) for Sects. 3, 4, and 5.

2.3. Surface clutter

Surface clutter echoes contaminate the precipitation signals. In this study, we assumed that the

surface is completely covered by the ocean for simplicity. Radar-received power from the sea surface

(P_s) was calculated by

$$\frac{P_{s}}{P_{s}} = \frac{\frac{P_{t}\lambda^{2}}{(4\pi)^{3}} \iint_{A} \frac{f^{4}(\theta, \phi)\sigma_{\theta}}{r^{4}} dA P_{s} = \frac{P_{t}\lambda^{2}}{(4\pi)^{3}} \iint_{S} \frac{f^{4}(\theta, \phi)\sigma_{0}A_{P}(r, \theta, \phi)}{r^{4}} dS$$
 (6)(7)

where σ_0 is the normalized radar cross section (NRCS) of the ocean surface, and AS the scattering

area. We obtained σ_0 using a model proposed by Wentz et al. (1984) based on observations from a

microwave scatterometer onboard the Seasat satellite. The model expresses σ_0 as,

$$\sigma_0 = b_0 (U_{10})^{b_1} \tag{7)(8)}$$

where U_{10} is the 10-m wind speed, and b_0 and b_1 are fitted parameters. The NRCS for various wind speed is shown in Fig. 22. When raindrops hit the ocean surface, they change the properties of the surface and the scattering signals (Bliven et al., 1997). The impact of impinging rain is negligible at high wind speed (e.g. Braun et al., 1999; Contreras et al., 2003). Since this study focuses on a typhoon case accompanying strong winds, we do not consider the impact of impinging rain. Also, we do not consider the impact of sidelobe clutter as it can be filtered with proper methods (e.g. Kubota et al., 2016) for Sects. 3, 4, and 5.

To understand the characteristics of the radar observation, we first show the results from an

Formatted: Indent: First line: 0 ch

3. Homogeneous case

idealized case, in which we assume the atmosphere below 2 km is uniformly filled with a certain amount of hydrometeor. We tested five cases: 20, 30, 40, 50, and 60 dBZ. The corresponding precipitation intensity is roughly 1, 2, 5, 20, and 60 mm h⁻¹ if the hydrometeor consists of only rain. The 10-m wind speed was fixed at 10 m s⁻¹ uniformly for all cases. The horizontal resolution of the radar was assumed to be 20 km at the nadir point.

Figure 3a shows P_r for the case of 60 dBZ. Two features are apparent in the figure. The first is that the precipitation signal is beyond the precipitation area and becomes taller along with the distance from the nadir, and the second is that P_r decreases monotonically with height. Here and hereafter, the distance was measured along the earth surface.

Before discussing the reason for these, first we explain the scattering volume of the GeoSat/PRGPR. Here, the scattering volume of the beam pointing range r_0 and scan angle θ_0 and ϕ_0 is defined as the area where r, θ , and ϕ satisfy both $r_0 - \frac{c\tau}{4} \le r \le r_0 + \frac{c\tau}{4}$ and $\frac{f^2(\psi)}{2} \ge 0.\psi$ less than the first null point (Fig. 1). Note that sidelobe area is not included in the scattering volume in this section. Figure 4 shows a schematic image—of the scattering volume. At the nadir, the

incidentincidence angle is zero, and the scattering volume is nearly parallel to the earth surface (Fig.

4a). As the <u>incidentincidence</u> angle increases, the scattering volume becomes tilted against the earth surface (Fig. 4b). As a result, the upper edge of the scattering volume reaches as high as 2016 km when the beam center of the GeoSat/PRGPR is at a point 4000 km away from the nadir even in the lowest range bin (range bin number 1 in Fig. 5b). In the same angle but the highest range bin, the scattering volume ranges from 24 km to 4438 km in height (range bin number 60 in Fig. 5b). The range of the scattering volume is even larger with sidelobe area.

When the beam center is at the level higher than the precipitating area, there is no precipitation around the beam center. On the other hand, the tip of the scattering volume may touch the precipitating area with the tilted scattering volume at off-nadir. In such a case, the scattering volume is not fully filled with precipitation. Such nonuniform beam filling (NUBF) results in the reduction of P_r with $Z_e \overline{\sigma}_b = 0$ in the upper part of the volume compared with the fully filled case. Although the value is small, still GeoSat/PRGPR catches the signal of precipitation, and thus P_r has a value even when the beam center is at the point higher than the precipitating area. As the scattering volume becomes more tilted against the earth surface along with the distance from the nadir (Fig. 5a), the maximum height at which the beam gets a signal from precipitation becomes higher along with the distance from the nadir. Hence, we have the signal beyond the precipitation area and the area becomes taller along with the distance from the nadir.

The P_r magnitude dependence on the height is also explained by the NUBF. Due to the experimental setting where precipitation exists only in the atmosphere below 2 km, the beam with the scattering volume touching the level higher than 2 km are is not fully filled with precipitation. The higher the GeoSat/PRGPR observes, the less the scattering volume is filled with precipitation. Accordingly, P_r decreases with height.

The pattern of P_s is similar to that of P_r , showing dependence on the distance from the nadir (Fig.

3b) because σ_0 is a function of the incidentincidence angle (Fig. 2).

Figure 6 shows signal-to-clutter ratio (SCR) defined as P_r/P_s (dB). The larger SCR, the less

contaminated by the clutter. In the figure, areas where the reflectivity from precipitation exceeds 0 dBZ are shaded. For all the cases, SCR is the largest at nadir and high altitudes. The minimum SCR is found at the surface level around 500 km away from the nadir reflecting the peak of the echo from the surface clutter. As expected, SCR becomes large when precipitation is strong since the received power from the precipitation becomes larger while P_s is the same for all the cases. The GeoSat/PRGPR can perceive precipitation only at the nadir point and high altitudes in the case of 20 dBZ (Fig. 6a), but SCR is larger than zero over the whole precipitating area in the case of 60 dBZ (Fig. 6e) except for the surface level in 0 to 1000 km away from the nadir. The comparison of the two cases also suggests that the surface clutter contaminates the precipitation signal from high altitudes for weak precipitation. On the other hand, if the precipitation is strong enough, the clutter interference is very-limited, and we should get the signal even at the surface level.

The simulated results are consistent with Takahashi (2017) and Li et al. (2017), suggesting that both results be plausible.

4. Typhoon case

Section 3 presented the characteristics of reflectivity of GeoSat/PRGPR. However, what we can observe will depend on the size and structure of the target precipitation system. To investigate the capability of GeoSat/PRGPR in detail, we ran an atmospheric model and applied the radar simulator to produce synthetic observations of reflectivity. As an example, we chose Typhoon Soudelor in 2015, which was the strongest typhoon in that year. Soudelor, generated on 1 August 2015 around the Marshall Islands, rapidly intensified to Super Typhoon equivalent to Category 5 Hurricane within 24 hours from the generation and dissipated on 11 August 2015. In this study, we focused on the mature stage of Soudelor at 0000 UTC 5 August 2015.

In this section, we focus on the sensitivity to two radar parameters: beam width and beam sampling span. Three cases were examined: the first adopts the beam width and sampling span of 20

km, the experiment named "bw20bs20.—". The second—uses the 5 km beam width and span (bw05bs05), and the third uses 20-km resolution of beam width, but the beam span is chosen to be 5 km (bw20bs05), representing an over-sampling case. The The third uses the 5-km beam width and span (bw05bs05). Although it is unrealistic to assume a radar with the 5-km beam width at this moment, exploring what kind of observations we can get with the 5-km beam width would be beneficial for the antenna design in the future. The radar settings are summarized in Table 2.

4.1. SCALE-RM simulation

We used a regional cloud-resolving model, SCALE-RM version 5.0.0 (Nishizawa et al., 2015; Sato et al., 2015) to simulate Soudelor. SCALE-RM is based on the SCALE library for weather and climate simulations. The source code and documents of the SCALE library including SCALE-RM are publicly available at http://r-ccs-climate.riken.jp/scale/. The moist physical process is parameterized by a 6-class single-moment bulk microphysics scheme (Tomita et al., 2008), and the five species of hydrometeors (rain, cloud water, cloud ice, snow, and graupel) were used to calculate the radar reflectivity. We use the level-2.5 closure of the Mellor-Yamada-Nakanishi-Niino turbulence scheme to represent subgrid-scale turbulences (Nakanishi and Niino 2004). For shortwave and longwave radiation processes, the Model Simulation Radiation Transfer code (MSTRN) X (Sekiguchi and Nakajima, 2008) is used. See http://r-ccs-climate.riken.jp/scale/ for more detail.

We performed an offline nesting simulation. The horizontal grid spacings and the number of vertical levels for the outer (inner) domain were 15 km (3 km) and 36 levels (56 levels), respectively. Hereafter, the simulation for the outer (inner) domain is referred to as D1 (D2) (Fig. 7a). The initial and lateral boundary conditions for D1 were taken from the National Centers for Environmental Prediction (NCEP) Global Forecasting System (GFS) operational analyses at 0.5° resolution every 6 hour. The initial and lateral boundary conditions for D2 were taken from D1. The simulation covers the period from 0000 UTC 28 July 2015 (0000 UTC 28 July 2015) to 0000 UTC 9 August 2015

(0000 UTC 7 August 2015) for D1 (D2).

Figure 7 shows the Soudelor's track and minimum sea level pressure (MSLP) at the typhoon center from the best track of the Japan Meteorological Agency (JMA) and the D1 and D2 simulations. The JMA best track shows a rapid decrease of MSLP during the three days from 1 August. D1 captures the rapid intensification while D2 shows a slightly slower intensification than the best track. As for the track, both D1 and D2 closely follow the best track albeit slightly shifted northward. We used D2 as a reference to simulate radar observations.

4.2. Results

Figures 8 and 9 show radar reflectivity near the surface level and its vertical cross section in a mature stage of the simulated Soudelor (0000 UTC 5 August 2015). The results are shown in the longitude-latitude coordinate for Fig. 8 (a) and in the scan-angle coordinate of the GeoSat/PRGPR for Fig. 8 (b-d) covering the same domain as Fig. 8 (a). As in the homogeneous case, areas where the reflectivity from precipitation exceeds 0 dBZ are shaded by grey.

Figure 8 (a) and 9 (a) show the reflectivity of the full-resolution nature run for reference. The figures show the typical structure of a tropical cyclone characterized by no rainfall within the eye, heavy rainfall in the eye wall, and the spiral outer-rainband structure.

The bw20bs20 captures the spatial distribution well but without fine structures. The difference is noticeable in the outer rainband (gray-colored area) in which the shape of the bands is different from the reference. With the tilted and relatively large scattering volume, the radar catches the signal of precipitation that is in the level higher than the level shown in the figure. The bw20bs20 also misses the local maxima of precipitation. For instance, the strongest precipitation south of the eye (red area in Fig. 8a) was not well captured by bw20bs20. This is because the echo from sharp and strong precipitation was averaged out due to NUBF within the relatively large scattering volume. For the vertical cross-section, the observation roughly captures the structure albeit in a jaggy and discretized

manner because of the tilted and relatively large scattering volume (Fig. 9b). The tilted scattering volume also results in the precipitation echo taller than the reference as discussed in Sect. 3.

On the other hand, the satellite observes precipitation accurately for both spatial and vertical cross-sections in bw05bs05 (Fig. 8d and Fig. 9d).

In the case of bw20bs05 (i.e. oversampling case), the radar inherited the shortcomings in bw20bs20 due to the wide beam width: the larger precipitated area in the outer rainband (Fig. 8c) and taller precipitation pattern (Fig. 9c) compared with the reference. On the other hand, the results were arguably improved thanks to the fine sampling span compared with bw20bs20. For instance, the strong precipitation south of the eye was well captured compared with bw20bs20 (Fig. 9c). Furthermore, individual convective cells south of the typhoon were observed as individual cells although they were blurred due to NUBF within the large scattering volume. This is because the finer sampling span increased the probability for the beam center to hit the area of heavy rainfall.

To compare the skills quantitatively, we computed the threat scores with a threshold of 20, 30, 40, and 50 dBZ for all the experiments. Figure 10 shows that bw05bs05 is the best and also shows the benefit of oversampling. Namely, the score of bw20bs05 increased by more than 20 % on average for all the thresholds compared with that of bw20bs20.

Figures 9 and 10 also shows the impact of the surface clutter. The hatched area in Fig. 9 shows the area where SCR is less than or equal to zero. Assuming that the SCR of zero is the minimum threshold to indicate whether the clutter interference will be serious (Li et al., 2017), the hatched area is considered as unobservable. The unobservable area was confined up to 3-km in bw05bs05, while they reached as high as 7 km in bw20bs20 and bw20bs05. Thus, to reduce the impact of the surface clutter, the beam width needs to be narrow enough.

5. Dependence on the position of typhoon

At other than the nadir point, the radar observes precipitation obliquely and consequently the

precipitation echo is easy to be contaminated by the surface clutter. As mentioned in Sect. 3, how severely surface clutter contaminates the precipitation echo depends on the incidentincidence angle of the beam, which corresponds to the distance from the nadir. Therefore, the location of the target precipitation system should have an impact on the quality of the observations. This section investigates the sensitivity to the location of the typhoon.

We used the simulated Typhoon Soudelor as the reference as in Sect. 4. We picked out the mature stage of the typhoon whose center is in 18° N, 136° E as an example and moved it north and south to represent typhoons whose center is in 10° N, 20° N, and 30° N. We assumed the longitudinal position of the typhoon centers were the same as the sub-satellite point for all the cases to compare the difference originating from the latitudinal position of the typhoon center. The radar used in this section was the same as the one in the bw20bs05.

Figure 11 shows the precipitation echo at the near surface level for the three cases together with the reference. Among them, the precipitation pattern in 10° N was the most similar to the reference, and the threat score was the highest (Fig. 13). As the typhoon position is away from the sub-satellite point, the precipitation is observed weaker with the outer-rainband area more expanded, and the threat score becomes lower (Fig. 13). As discussed in the previous sections, those are due to the widely tilted scattering volume with which the beam captures the signal of precipitation in high altitude whose intensity is weaker than that in the level shown (cf. Fig. 12). The tilted scattering volume also resulted in vertically extended precipitation echo (Fig. 12). The further away from the nadir, the more vertically extended the precipitation echo. This is also true for the clutter height (SCR \leq 0): the further away from the nadir, the higher the clutter height. However, this is only the case for the area with weak precipitation. In the area with heavy precipitation at a higher latitude, the impact of the surface clutter is limited to the near surface level. For instance, the strongest precipitation in the south of the eye is not affected by the surface clutter at all in the case of 30° N (Fig. 12d), while those are masked by the clutter in the cases of 10° N and 20° N (Fig. 12b and 12c).

Those results are also evident in the threat score (dashed line in Fig. 13). The surface clutter is determined by cross section σ_0 integrated over the scattering area A, and both σ_0 and A decrease along with the incident incidence angle in this area. Therefore, the echo from the sea surface clutter becomes smaller and SCR becomes larger along with the latitude.

We obtained the similar results as shown in Sect. 3 with the typhoon case. When the observation target is in low latitude (i.e. close to the nadir), the clutter height is low, and the radar can observe weak precipitation free from clutter at high altitudes. It should be difficult to observe precipitation at the near surface level, even if the precipitation is strong. In case the radar observes precipitation in mid-latitudes (i.e. away from the nadir), the radar cannot observe weak precipitation at most of the altitude while it is easier to observe strong precipitation at any altitude.

6. Impact of attenuation and sidelobe clutter

In the previous sections, we did not consider the impact of attenuation and sidelobe clutter, assuming that they can be corrected (e.g. Iguchi et al., 2000) or filtered (e.g. Kubota et al., 2016). In this section, we investigate the impact of attenuation and sidelobe clutter. To consider attenuation, the attenuation coefficient is included in the calculation of P_r , P_s , and Z (Eqs. 3, 6, and 7). The attenuation coefficients are calculated with Eq. (5), and the extinction coefficients are calculated by Joint-Simulator (Hashino et al., 2013). To investigate the impact of sidelobe clutter, the observation volume is expanded to include the sidelobe area up to the fifth null point (Fig. 1).

Figure 14 shows the cross-section of the typhoon with various radar parameters; bw20bs20, bw20bs05, and bw05bs05. Due to the attenuation, reflectivity from heavy rain is weakened for all the cases (c.f. the reflectivity at south of the eye). This feature is also evident in the threat score for the case with bw20bw05 (Fig. 15). Figure 15 compares three cases: The first case ("main") does not consider the impact of attenuation, and its observation volume does not include sidelobe area, i.e., the same as the bw20bs05 in Fig. 10. The second case ("main+side") does not consider the impact of

attenuation, but its observation volume includes sidelobe area, i.e., considering the impact of sidelobe clutter. The third case ("main+atten.") considers the impact of attenuation, but its observation volume does not include the sidelobe area. Figure 15 shows that the threat score of "main+atten." is almost identical to that of "main" and the impact of attenuation is negligible with the thresholds of 20, 30, and 40 dBZ. On the other hand, the threat score of "main+atten." with the threshold of 50 dBZ is zero at all heights. Therefore, the attenuation makes it difficult to obtain rain echoes from strong precipitation.

On the other hand, the sidelobe clutter contaminates the weak to moderate rain echoes. For example, the top of convection at around 17°N is masked by the sidelobe clutter for the cases with low resolution beam (Figs. 14a and 14b). Figure 15 also shows that threat scores of "main+side" are smaller than that of "main" for the thresholds of 20, 30, and 40 dBZ while the impact is negligible with the threshold of 50 dBZ. Therefore, the sidelobe clutter contaminates weak to moderate rain.

6.7. Summary

We examined the feasibility of radar observation for precipitation from a geostationary satellite. The results demonstrated that it would be possible to obtain three-dimensional precipitation data. However, the quality of the observation was found to depend on the beam width, the beam sampling span, and the position of targeting precipitation systems. With the wide beam width and coarse beam span, the radar cannot observe weak precipitation at low altitudes. The limitations can be somewhat mitigated by oversampling (i.e., a wide beam width but a fine sampling span). With the narrow beam width and fine beam sampling span, the surface clutter interference was confined to the surface level. For the position of the target precipitation system, the larger (smaller) the off-nadir angle, the easier (more difficult) it is to obtain the precipitation signal if the precipitation is strong (weak).

In this This study, we did not consider also investigated the impact of attenuation, assuming that it can be corrected (e.g. and sidelobe Iguchi et al., 2000). Also, we assumed that the area where SCR

The attenuation hinders to obtain rain echoes from strong precipitation while the sidelobe clutter contaminates signals from weak precipitation. An attenuation correction method like the surface-reference method (e.g. Iguchi et al., 2000; Meneghini et al., 2000) and a clutter filter should be developed in the future(e.g. Kubota et al., 2016) must be devised to mitigate the detrimental impacts. One possible idea for the filter may be to distinguish an echo from precipitation and surface by using Doppler shift, but this remains to be a subject of future research.

If the wide beam width of 0.032° is used, the raw product may be prohibitively coarse for a specific purpose. One possible way to effectively downscale such observations is to assimilate the data for NWP. By doing this, the information can be treated properly, and we can get precipitation information in the prediction model coordinate. However, it is not trivial whether assimilation of such data is useful for NWP. In the future, an observing system simulation experiment (OSSE) will be conducted using precipitation measurements simulated with the simulator developed in this study to evaluate the potential impacts of the GeoSat/PRGPR on NWP. Given that wind field observation may be possible from a geostationary satellite as shown in Lewis et al. (2011), the combined use of both observations would be an attractive option.

Acknowledgement

This study was partly supported by the Japan Aerospace Exploration Agency (JAXA); and the FLAGSHIP2020 Project of the Ministry of Education, Culture, Sports, Science and Technology Japan. The experiments were performed using the K computer at the RIKEN R-CCS (ra000015, hp160229, hp170246, hp180194).

Reference

434

446 447

448

- 435 Bessho, K., Date, K., Hayashi, M., Ikeda, A., Imai, T., Inoue, H., Kumagai, Y., Miyakawa, T., Murata,
- 436 H., Ohno, T., Okuyama, A., Oyama, R., Sasaki, Y., Shimazu, Y., Shimoji, K., Sumida, Y., Suzuki,
- 437 M., Taniguchi, H., Tsuchiyama, H., Uesawa, D., Yokota, H., Yoshida, An introduction to
- Himawari-8/9: Japan's new-generation geostationary meteorological satellites, J. Meteorol. Soc.
- 439 JPN., 94, 151-183, 2016.
- Bliven, L. F., Sobieski, P. W., and Craeye, C., Rain generated ring-waves: Measurements and
 modelling for remote sensing, Int. J. Remote. Sens., 18, 221-228, 1997.
- Braus, N., Gade, M., and Lange, P. A., Radar backscattering measurements of artificial rain impinging on a water surface at different wind speeds, paper presented at 1999 International
 Geoscience and Remote Sensing Symposium (IGARSS), Inst. of Elect. and Elect. Eng., New York, 1999.
 - Cho, H.-K., Bowman, P. B., and North, G. R., Equatorial waves including the Madden-Julian Oscillation in TRMM rainfall and OLR data, J. Climate, 17, 4387-4406, 2004.
 - Contreras, R. F., Plant, W. J., Keller, W. C., Hayes, K., and Nystuen, J., Effects of rain on Ku-band backscatter from the ocean, J. Geophys. Res., 108, C5,3165, 2003.
- Gaspari, G., and Cohn, S., Construction of correlation functions in two and three dimensions, Q. J. Roy. Meteor. Soc., 125, 723-757, 1999.
- Hashino, T., Satoh, M., Hagihara, Y., Kubota, T., Matsui, T., Nasuno, T., and Okamoto, H.,
 Evaluating cloud microphysics from NICAM against CloudSat and CALIPSO, J. Geophys. Res.
- 454 Atmos., 118, 7273-7292, 2013.
- Hamada, A., Takayabu, Y. N., Liu, C., and Zipser, E. J., Weak linkage between the heaviest rainfall and tallest storms, Nat. Commun, doi: 10.1038/ncomms7213, 2015.
- Hou, A. Y., R. K. Kakar, S. Neeck, A. A. Azarbarzin, C. D. Kummerow, M. Kojima, R. Oki, K. Nakamura, and T. Iguchi, 2014: The global precipitation measurement mission. Bull. Amer.
- 459 Meteor. Soc., 95, 701-722.
- Houze, R. A., Rasmussen, K. L., Zuluaga, M. D., and Brodzik, S. R., The variable nature of
 convection in the tropics and subtropics: A legacy of 16 years of the Tropical Rainfall
 Measuring Mission satellite, Rev. Geophys., 53, 994-1021, 2015.
- Iguchi, T., Kozu, T., Meneghini, R., Awaka, J., Okamoto, K., Rain-profiling algorithm for the TRMM precipitation radar, J. Appl. Meteorol., 39, 2038-2052, 2000.
- Im, E., Smith, E. A., Chandrasekar, V. C., Chen, S., Holland, G., Kakar, R., Tanelli, S., Marks, F., and
- 466 Tripoli, G., Workshop report on NEXRAD-In-Space -A geostationary satellite doppler weather
- radar for hurricane studies, 33rd Conf. on Radar Meteorology, Cairns, QLD, Australia, Amer.
- 468 Meteor. Soc., 4B.5, 2007 [Available online at
- http://ams.confex.com/ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/123726.pdf.]-http://ams/pdfpapers/pdfpape
- 469 http://ams.comex.com/ams/pdrpapers/123/26.pdr.j.nttp://ams.comex.com/ams/pdrpapers/123/.
 470 6.pdf.].
- 471 Joudoi, D., Kuratomi, T., and Watanabe, K., The construction method of a 30-m-class large planar

- 472 antenna for Space Solar Power Systems, 69th International Astronautical Congress, Bremen, 473 Germany, 1-5, October 2018.
- 474Kelley, O. A., Stout, J., and Halverson, J. B., Tall precipitation cells in tropical cyclone eyewalls are 475 associated with tropical cyclone intensification, Geophys. Res. Lett., 31, L24112, 2004.
- Kidd, C., Becker, A., Huffman, G. J., Muller, C. L. Joe, P., Skofronick-Jackson, G., and Kirschbaum, 476 477 D. B., So, how much of the earth's surface is covered by rain gauges?, B. Am. Meteorol, Soc., 478 doi: 10.1175/BAMS-D-14-00283.1, 2016.
- Kozu, T, T. Kawanishi, H. Kuroiwa, M. Kojima, K. Oikawa, H. Kumagai, K. Okamoto, M. Okumura, 479 H. Nakatshka, and K. Nishikawa, Development of precipitation radar onboard the Tropical 480 Rainfall Measuring Mission (TRMM) satellite. IEEE Trans. Geosci. Remote Sens., 39, 102-116, 481 482 2001.

484

485

487

488

489

498 499

500

501

502

- Kubota, T., Iguchi, T., Kojima, M., Liao, L., Masaki, T., Hanado, H., Meneghini, R., and Oki, R., A statistical method for reducing sidelobe clutter for the Ku-band precipitation radar on board the GPM Core Observatory, J. Atmos. Oceanic Technol., 33, 1413-1428, 2016.
- 486Kummerow, C., W. Barnes, T. Kozu, J. Shiue, and J. Simpson, The Tropical Rainfall Measuring Mission (TRMM) sensor package, J. Atmos. Oceanic Technol., 15, 808-816, 1998.
 - Lewis, W. E., Im, E., Tanelli, S., Haddad, Z., Tripoli, G. J., Smith, E. A., Geostationary doppler radar and tropical cyclone surveillance, J. Atmos. Ocean. Tech., 28, 1185-1191, 2011.
- 490 Li, X., He, J., Wang, C., Tang, S., Hou, X., Evaluation of surface clutter for future geostationary 491 spaceborne weather radar, Atmosphere, 8, 14, doi: 10.3390/atmos8010014, 2017.
- 492 Kubota, T., Shige, S., Hashizume, H., Aonashi, K., Takahashi, N., Seto, S., Hirose, M., Takayabu, Y. 493 N., Ushio, T., Nakagawa, K., Iwanami, K., Kachi, M., Okamoto, K., Global precipitation map 494 using satellige-borne microwave radiometers by the GSMaP Project: Production and validation, IEEE T. Geosci. Remote., 45, 7, 2259-2275, 2007. 495
- 496 Masunaga, H., and Kummerow, C., Combined radar and radiometer analysis of precipitation profiles 497 for a parametric retrieval algorithm, J. Atmos. Ocean. Tech., 22, 909-929, 2005.
 - Meguro, A., Shintate, K., Usui, M., and Tsujihata, A., In-orbit deployment characteristics of large deployable antenna reflector onboard Engineering Test Satellite VIII, Acta Astronautica, 65(9-10), 1306-1316, 2009.
 - Meneghini, R., Iguchi, T., Kozu, T., Liao, L., Okamoto, K., Jones, J. A., and Kwiatkowski, J., Use of the surface reference technique for path attenuation estimates from the TRMM radar, J. Appl. Meteorol., 39, 2053-2070, 2000.
- Morita, J., Takayabu, Y. N., Shige, S., Kodama, Y., Analysis of rainfall characteristics of the 504 Madden-Julian oscillation using TRMM satellite data, Dynam. Atmos. Oceans, 42, 207-126, 505 506
- Nakanishi, M., and Niino, H., An improved Mellor-Yamada level-3 model with condensation 507 508 physics: Its design and verification, Bound.-Lay. Meteorol., 112, 1–31, 2004.
- 509 Okamoto, K., Aonashi, K., Kubota, T., Tashima, T., Experimental assimilation of the GPC Core

- Observatory DPR reflectivity profiles for Typhoon Halong (2014), Mon. Weather Rev., 144, 2307-2326, 2016.
- Otsuka, S., Kotsuki, S., Miyoshi, T., Nowcasting with data assimilation: A case of global satellite mapping of precipitation, Weather Forecast., 31, 1409-1416, 2016.
- Sekiguchi, M., and Nakajima, T., A k-distribution-based radiation code and its computational optimization for an atmospheric general circulation model, J. Quant. Spectrosc. Ra.,J. Quant.
- 516 Spectrosc. Radiat. Transfer, 109, 2779–2793, 2008.

- 517 Skofronick-Jackson, G., Petersen, W. A., Berg, W., Kidd, C., Stocker, E. F., Kirschbaum, D. B.,
- Kakar, R., Braun, S. A., Huffman, G. J., Iguchi, T., Kirstetter, P. E., Kummerow, C., Meneghini,
 - R., Oki, R., Olson, W. S., Takayabu, Y., Furukawa, K., Wilheit, T., The global precipitation
- measurement (GPM) mission for science and society, B. Am. Meteorol. Soc., 98, 1679-1695, 2017.
- Takahashi, N., Surface echo characteristics derived from the wide swath experiment of the precipitation radar onboard TRMM satellite during its end-of-mission operation, IEEE T. Geosci. Remote., 55, 4, 1988-1993, 2017.
- Takayabu, Y. N., Rain-yield per flash calculated from TRMM PR and LIS data and its relationship to the contribution of tall convective rain, Geophys. Res. Lett., 33, L18705, 2006.
- Tomita, H., New microphysical schemes with five and six categories by diagnostic generation of cloud ice, J. Meteorol. Soc. JPN., 86A, 121-142, 2008.
- Wentz, F. J., Peteherych, S., Thomas, L. A., A model function for ocean radar cross sections at 14.6 GHz, J. Geophys. Res., 89, c3, 3689-3704, 1984.

532 Tables

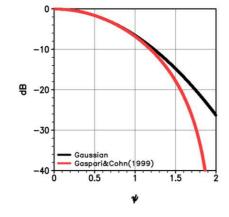
Table 1 Specifications of the precipitation radar aboard geostationary satellite

Parameter	Value
Frequency	13.6GHz
Scan angle	±6°
Range resolution	≤500m
Horizontal resolution	20km at nadir
Observation range	30km at nadir

 $\label{thm:condition} \textbf{Table 2} \ \textbf{Radar settings}. \ \textbf{The figures show the resolution at the nadir point}.$

Experiment	Beam width	Beam span
bw05bs05	5km	5km
bw20bs05	20km	5km
bw20bs20	20km	20km

539 Figures



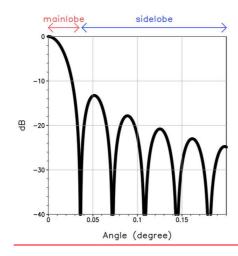


Figure 1 Beam pattern (dB) as a function of normalized-beam direction angle. Black and red curves show the Gaussian function and the fitted fifth order polynomial (Gaspari and Cohn, 1999), respectively. (degree).

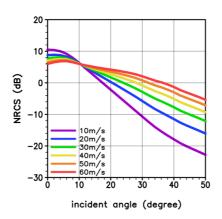
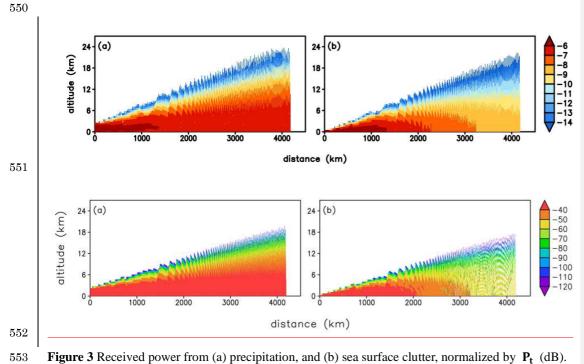


Figure 2 Normalized radar cross section (dB) as a function of incident angle for six cases of 10-m wind speed.



 $Figure \ 3 \ \text{Received power from (a) precipitation, and (b) sea surface clutter, normalized by} \ P_t \ (\text{dB}).$

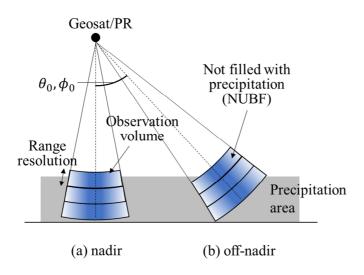


Figure 4 Schematic image of the scattering volume at (a) nadir, and (b) off-nadir.

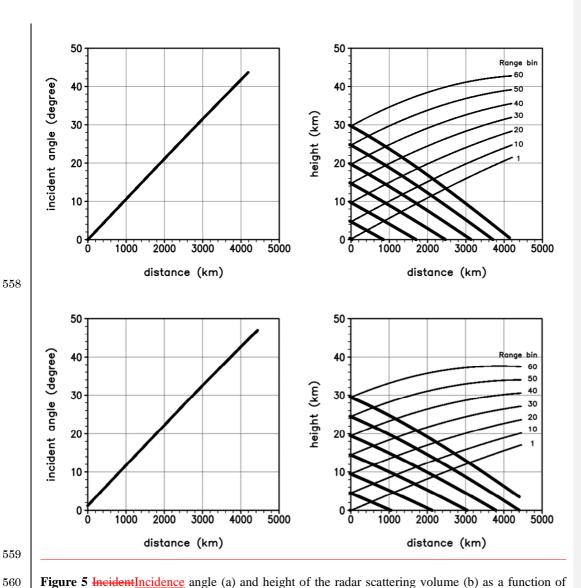


Figure 5 IneidentIncidence angle (a) and height of the radar scattering volume (b) as a function of the distance from the nadir. Thick and thin lines in (b) shows the lower and upper bound, respectively.

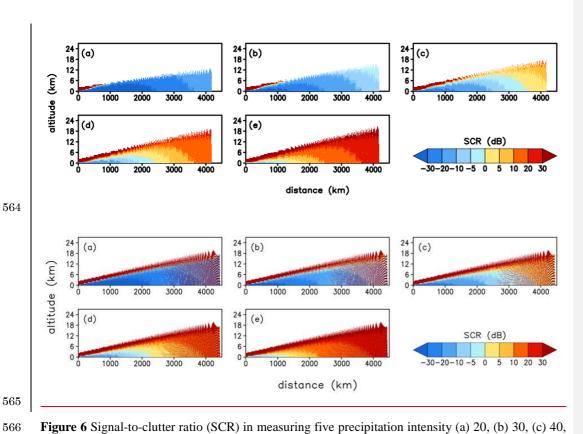
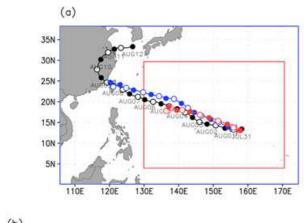


Figure 6 Signal-to-clutter ratio (SCR) in measuring five precipitation intensity (a) 20, (b) 30, (c) 40, (d) 50, and (e) 60 dBZ₇ as a function of the distance from the nadir (km). It is assumed that the altitude lower than 2 km is filled with homogeneous precipitation.



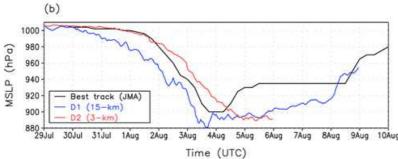


Figure 7 (a) Model domains for D1 (blue) and D2 (red) and typhoon tracks, and (b) time series of minimum sea level pressure (MSLP). Black, blue, and red colors show the JMA best track data, D1 simulation, and D2 simulation, respectively. Closed and open circles in (a) denote the typhoon positions at 0000 UTC and 1200 UTC, respectively.

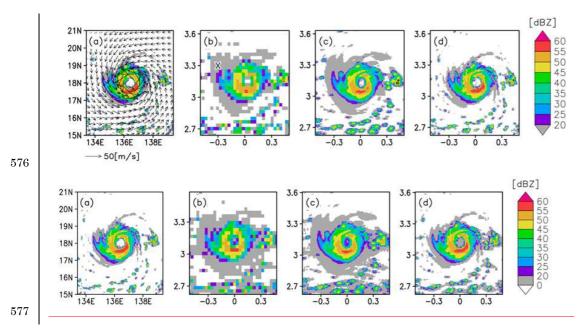


Figure 8 Radar reflectivity (dBZ) near the surface in the typhoon mature stage (0000 UTC, 5 August 2015) for (a) the truth, (b) bw20bs20, (c) bw20bs05, and (d) bw05bs05. 10-m wind speed is overlaid in (a). Note that the areasThe area where reflectivity formfrom precipitation largerless than 0 dBZ are shadedleft blank.

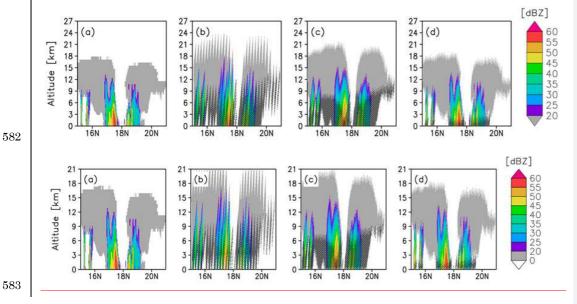


Figure 9 Precipitation reflectivity (dBZ) along 136.4°E longitude line passing through the typhoon

center in the mature stage (0000 UTC, 5 August 2015) for (a) the truth, (b) bw20bs20, (c) bw20bs05, and (d) bw05bs05. The area in which SCR < 0 is hatched in (b d). Note that the areas where reflectivity formfrom precipitation largerless than 0 dBZ are shaded left blank and the area in which SCR < 0 is hatched in (b-d).

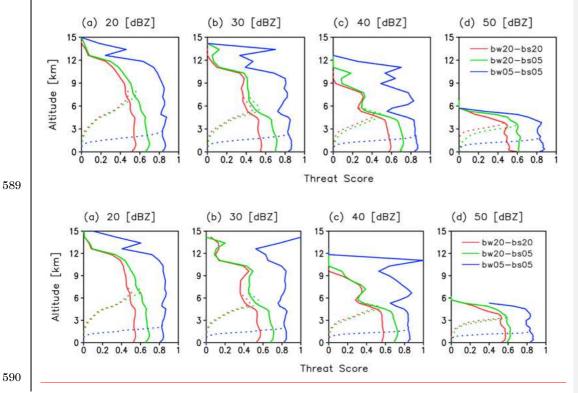


Figure 10 Threat score with a threshold of (a) 20, (b) 30, (c) 40, and (d) 50 (dBZ) for bw20bs20 (red), bw20bs05 (green), and bw05bs05 (blue). The dotted and solid lines show the threat score with and without considering the impact of surface clutter, respectively.

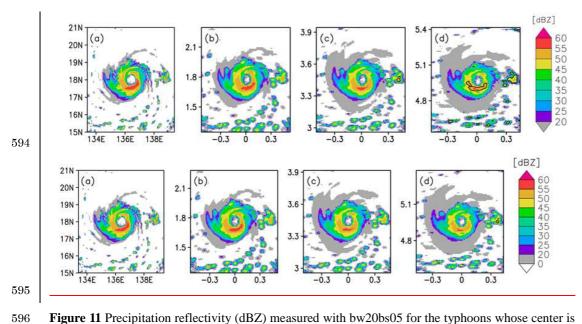


Figure 11 Precipitation reflectivity (dBZ) measured with bw20bs05 for the typhoons whose center is in (b) 10° N, (c) 20° N, and (d) 30° N. Contour in (b-d) corresponds to the area SCR > 0. Panel (a) shows the truth. Note that the areas The area where reflectivity form from precipitation largerless than 0 dBZ are shadedleft blank.

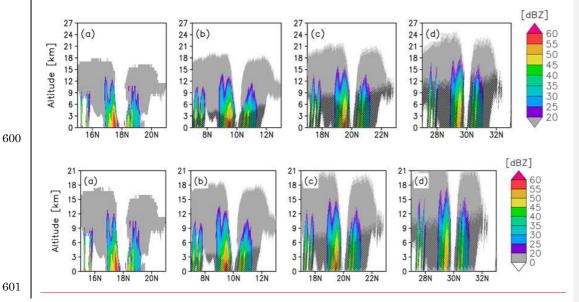


Figure 12 Precipitation reflectivity (dBZ) along 136.4°E longitude line passing through the typhoon

center measured with bw20bs05 for the typhoons whose center is in (b) 10°N, (c) 20°N, and (d) 30°N. The area in which SCR < 0 is hatched in (b-d). Panel (a) shows the truth. Note that the areas The area where reflectivity formfrom precipitation largerless than 0 dBZ are shaded.left blank and the area in which SCR < 0 is hatched in (b-d).

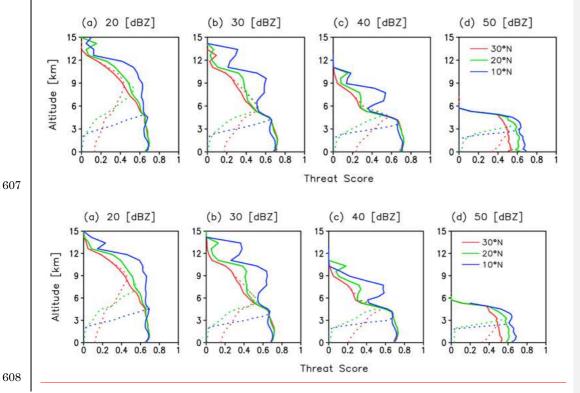


Figure 13 Threat score with a threshold of (a) 20, (b) 30, (c) 40, and (d) 50 (dBZ) for the typhoons whose centers are at 30°N (red), 20°N (green), and 10°N (blue). The dotted and solid lines show the threat score with and without considering the impact of surface clutter, respectively.

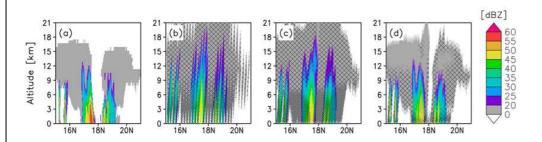


Figure 14 Precipitation reflectivity (dBZ) along 136.4°E longitude line passing through the typhoon center in the mature stage (0000 UTC, 5 August 2015) for (a) the truth, (b) bw20bs20, (c) bw20bs05, and (d) bw05bs05. The area where reflectivity from precipitation less than 0 dBZ are left blank and the area affected (SCR<0) by main lobe (sidelobe) clutter is densely (sparsely) hatched in (b-d).

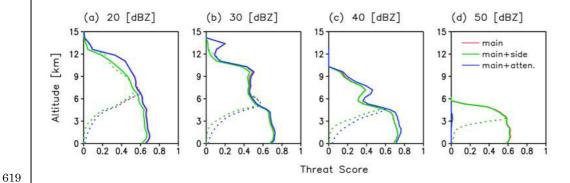


Figure 15 Threat scores with thresholds of (a) 20, (b) 30, (c) 40, and (d) 50 (dBZ) for bw20bs05. Red line overlaps blue line for (a), (b), and (c) and green line for (d). The dotted and solid lines show the threat score with and without considering the impact of surface clutter, respectively.