# **Response to RC2**

The authors thank the reviewer for the time and consideration given this manuscript. We appreciate your overall view that the paper will benefit the community and are appry that the description

The reviewers comments have been listed below in **bold** and responded to individually (where needed) in *italics*.

This is one of those "necessary" papers to document a community resource so that others can cite and reference when using the system.

**The paper is well written and despite the documentary nature it reads well.** *Response: We very much appreciate this feedback from the reviewer.* 

The main issue I would like to see addressed is better documentation of the sensitivity. At the start of section two phenomena detectable by the radar are discussed but no examples of minimum detectable signal (MDS) are given.

Please add (at a minimum) information about the pre-integration (single pulse) MDS at 10km (for example) to table 2 for the same waveform configuration.

Response: As was requested by RC1 we have added this information.

In addition please modify line 58 as insects are not clear air returns. This can mislead some audiences to thinking you can see Bragg returns with the radar. Use words like non-meteorological or Aeroplankton.

*Response: We agree with the reviewer and have changed the use of "clear air" to nonmeteorological in all instances.* 

My last comment is a suggestion and not a requirement: The colormaps used in your manuscript are very unfriendly to scientists with Color Vision Deficiency (CVD). I would recommend using perceptually uniform colormaps. I fully concede this is not common practice within the radar community 8% of the male population have CVD including (from my study) many well known radar meteorologists. For an interesting discussion on the introduction of a CVD colormap to Py-ART see: https://github.com/ARM-DOE/pyart/issues/713

Response: We have attempted to comply with this suggestion to the best of our ability in all figures. In particular we have switch from using 'pyart\_NWSRef' to the newly created 'pyart\_HomeyerRainbow' mentioned in the threads referenced above.

#### The NCAS Mobile Dual-Polarisation Doppler X-Band Weather 1

#### **Radar (NXPol)** 2

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### 27 1 Introduction

28 Polarimetric radars are powerful tools for meteorological studies. The diverse quantities observed by polarimetric radars can 29 provide significant insights into the evolution of clouds and precipitation (e.g. Fabry, 2015). Thus, small and or mobile dual-30 polarisation Doppler X-band radars have become popular tools for examining cloud microphysics and dynamics as well as 31 making quantitative precipitation estimates (QPE) in mobile applications (Wurman et al. 1997; Matrosov et al. 2005; Wang 32 and Chandrasekar, 2010). Currently, a significant number of such radars exist in the operational and research sectors to 33 address a broad range of scientific goals pertaining to atmospheric physics and hydrometeorology (Maki et al. 2005; Bluestein et al. 2007; 2014; Kato, A. and Maki, 2009; Pazamny et al. 2013; Forget et al. 2016; Mishra et al. 2016; Antonini 34 35 et al. 2017). Use of such radars notably includes recent field campaigns such as PECAN (Plains Elevated Convection At 36 Night, Geerts et al., 2016), where a variety of mobile radars (both X-band and C-band) from multiple institutions were used 37 collaboratively to achieve complex goals successfully. In the United States, where mobile research radars are more numerous, large multi-institution observational campaigns, similar to PECAN, occur several times a decade (e.g. the second 38 39 Verification of the Origins of Rotation in Tornadoes Experiment (VORTEX-2), Wurman et al. (2012)). Mobile radars are 40 also used as a teaching resource, for example, the University of Oklahoma SMART (Shared Mobile Atmospheric Research 41 and Teaching) radar (Biggerstaff et al., 2005). Thus, it is difficult to understate the role of such instrumentation in 42 hydrometeorology and atmospheric research. 43 44 Here we describe the NCAS Mobile X-band dual-polarisation Doppler weather radar (NXPol) shown in Figure 1 and the 45 supporting infrastructure structure that has been developed to support the radar when on deployment. The NXPol is the first

supporting infrastructure structure that has been developed to support the radar when on deployment. The NXPol is the first dual-polarisation mobile radar in the United Kingdom. The supporting infrastructure has been developed to create a robust facility that may be operated remotely with minimal staff. As such, the NXPol has developed into a semi-operational observing system facility that has the significant capabilities present in both traditional research radars used for intensive operational periods (IOPs) and radars operated as part of national networks. In addition to the technical description, examples of NXPol in 3 differing campaigns are shown, as well as an example of its ongoing use at the National Facility for Atmospheric Radar Research (NFARR) located at the Chilbolton Observatory. The NXPol is part of the pool of mobile instruments that make up the UK NCAS Atmospheric Measurement Facility (NCAS-AMF,

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- 54 <u>https://www.ncas.ac.uk/index.php/en/about-amf</u>) so it is available for use by the community according to the procedures set
  - <image>

57 Figure 1: Photograph of the NXPol collecting data at Burn Airfield near Selby, UK. Here the NXPol is deployed using only its 58 trailer as a platform.

#### 59 2 Technical Summary of the NXPol

The NXPol is a modified mobile Meteor 50DX (Selex ES GmbH) X-band, dual-polarisation, Doppler weather radar. The 60 61 radar is a magnetron based system and operates at a nominal frequency of 9.375 GHz (~3.2 cm). A detailed description of the development of this class of Selex radars is given by Borgmann et al. (2007). The radar is capable of measuring areal 62 63 precipitation, radial winds and properties of cloud and precipitation particles. It can also detect\_non-meteorological echoes, 64 including biota, at close range by scanning at slower speeds and optimising the transmitter and receiver. Similar radars 65 (including the newer Meteor 60DX) are utilised by national weather services and research centres throughout the world. 66 Table 1 provides a summary of the technical characteristics of the NXPol. 67 68 Like all standard mobile Meteor 50/60DX radars, NXPol is transportable. The radar is constructed on a wheeled platform 69 that is approved for towing on roads in the European Union by a 4x4 vehicle and can also be lifted by a crane. This trailer 70 includes a generator to provide necessary power and the communications infrastructure to operate and monitor the radar 71 remotely for up to 24 hours. This mobility makes NXPol a highly versatile tool for studying a diverse array of atmospheric 72 phenomenon across the globe. The main difference between NXPol and the standard mobile Meteor 50/60DX is that the 73 NXPol has been fitted with a larger 2.4 m diameter antenna that produces a 0.98° half-power beam width. The NXPol is operated without a radome, which is beneficial for eliminating radome attenuation effects, but extra care is required during 74 75 transport, and long-distance shipping may need the antenna and external waveguides to be removed. The decision to fit 76 NXPol with a larger antenna was made to support the ability to make higher resolution observations of convective clouds. 77 In comparison, the standard mobile Meteor 50/60DX has a 1.8m antenna that produces a 1.3° half-power beam width and is 78 usually operated with a radome. In addition to its increased spatial resolution, NXPol is also advantageous for use in the 79 observation of cloud evolution because of its rapid scanning capabilities; up to 36 degs-1.

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#### 81 Table 1. Technical characteristics of the NXPol.

Parameter	Specifications
Frequency	9.375 GHz
Transmitter Type	Coaxial Magnetron
Pre-Split Peak Transmit Power,	~75 kW (half to each channel),
Average Power	~80W
Dual-Polarisation Mode	Simultaneous H & V
Digital Receiver and Signal Processor	GDRX®4
Receiver Linearity	90 dB +/- 0.5 dB
Antenna Diameter	2.4m
Half Power Antenna Beam Width	0.98°
Antenna Gain	44dB
Minimum Discernible Signal (2µs pulse)	<u>H: -118dBm</u> V: -117dBm
Sensitivity (2µs pulse at 100km)	<u>~-11dBZ</u>
Radome	None
Elevation Scan Range	-1 to 181°
Azimuthal Scan Range	0 to 360°
Position Accuracy	±0.1°

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### 82 2.1 Operations

83 The NXPol can be operated via a remote computer (e.g. a laptop or server) that connects by wireless, ethernet or 3G to PCs

84 onboard the NXPol's trailer unit. The operational software allows the user to set up the radar for deployment and schedule

85 the scanning sequence. <u>Ravis®</u> is the maintenance and calibration software used for system diagnostics and testing, as well

86 as real-time data visualisation. Ravis® includes an automatic sun tracking tool for alignment of the system. Rainbow®5 is

87 the scan scheduling, data visualisation and analysis software, providing near real-time product and image generation. As

shown in Table 2, the NXPol is highly configurable with regards to the pulse width, PRF and scan pattern and can be tailored

89 to address the specific scientific question being examined. Bold values in Table 2 indicate the typical parameter settings used

90 in the examples shown in Section 3. Signal retrieval, analysis and data storage are performed by the GDRX®4 digital
 91 receiver and signal processor.

- 94
- 95

## 96 Table 2. Parameter settings. Boldface indicates settings typically used for operations.

Parameter	Specifications
Pulse Width	0.5µs, 1µs, 2µs ( <b>1µs</b> )
Pulse Repetition Frequency (PRF; Single or Dual Modes)	250-2000 Hz (1000 Hz single-PRF mode, 1000Hz/800Hz dual-PRF mode)
Dual PRF Mode	3/2, 4/3, 5/4 (5/4)
Unambiguous Velocity using single-PRF	±8m/s - ±16 m/s (±8m/s)
Unambiguous Velocity using dual-PRF	±8m/s - ±64 m/s (± <b>32m/s</b> )
Range Resolution	50m-300m (150m)
Maximum Range Gates	2000 (2000)
Maximum Operating Range	600 km ( <b>150 km</b> )
Antenna Speeds	0 to 36° s <sup>-1</sup> (~ <b>13-24° s</b> <sup>-1</sup> )

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98 Note that the NXPol operates only using the hybrid polarisation basis, also known as the simultaneous transmit and receive

99 (STAR) mode (i.e. it splits the transmitted signal into two parts and simultaneously transmits and receives horizontal (H) and

00 vertical (V) polarisations) (Chandrasekar and Bharadwaj, 2009). This mode operates under the assumption that the cross-

01 polarisation signals are weak in comparison to the co-polar signals and are therefore negligible (Wang and Chandrasekar,

2006)). As the cross-polar signals are not measured, observations of the linear depolarisation ratio (LDR) are not available.
 The benefit of STAR mode is that the NXPol has a much simpler and robust hardware design because it avoids switching

04 between H and V polarisation on a pulse-to-pulse basis (Doviak et al. 2000; Bringi and Chandrasekar 2001). STAR mode

05 operations also lead to less noisy measurements of differential reflectivity (Z<sub>DR</sub>) and other quantities while operating at rapid

06 scan speeds.

07 The dual-polarisation capability of the NXPol allows for the retrieval of many additional geophysically-related variables.

08 This additional information helps to provide insight into the size and shape of precipitation, enhanced target identification as

09 well as the assessment of attenuation and propagation effects (Bringi and Chandrasekar, 2001; Kumjian 2013a;b;c; Fabry,

10 2015). The NXPol's polarimetric ability also enables many alternative methods for quantitative precipitation estimation,

11 which are demonstrated in Section 3 (Deiderich et al. 2015; 2015). <u>In addition to the standard polarimetric variables</u>

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13 provided by most operational dual-polarisation radars, NXPol also provides the of the degree of polarisation (DOP) of the 14 backscattered signal. DOP is a relatively unexplored variable with respect to atmospheric phenomenon, but previous 15 examinations have shown that it has similar properties as the co-polar correlation coefficient when classifying hydrometeors 16 (Galletti et al. 2007; 2012). Galletti et al. (2012) note that DOP is advantageous compared to the co-polar correlation 17 coefficient for STAR mode radars like the NXPol because it retains its physical meaning even when observing scatterers that 18 are cross polarising (i.e. with linear depolarisations ratios that are greater than zero). 19 20 During operations, scan strategies are tailored to the application but typically sample a volume out to 150 km in range every 21 5 minutes. The typical volume includes ~10 PPI scans between 0.5° and 30° of elevation and a calibration scan at 90°. All 22 data are recorded as moments in Selex's Rainbow®5 format (a flavour of XML). This format is easily utilised by common 23 open-source analysis software packages (Heistermann et al. 2015) such as the LIDAR RADAR Open Software Environment 24 (LROSE) that is provided by the Earth Observing Laboratory within the U.S.'s National Center for Atmospheric Research 25 (NCAR) (Dixon et al. 2012; 2013), the Python Atmospheric Measurement Radiation (ARM) Climate Research Facility 26 Radar Toolkit (PyART) (Helmus and Collis, 2016) and the Open Source Library for Weather Radar Data Processing 27 (wradlib) (Heistermann et al. 2013). The NXPol has the capability of collecting raw IQ data for post-processing, but this is 28 typically not done due to the size of the dataset. 29 30 Once a volume is collected, the raw data are backed up locally and transferred to a central NCAS data storage facility if internet capacity allows as described in Section 2.2. In addition to storing the data for later analysis, Rainbow®5 generates 31 32 several quick-look images in real-time (tailored to the application of the radar). The quick-look images are transferred to a 33 central server where they are uploaded onto a web catalogue to disseminate the observations in near real-time and enable 34 easy examination of past observations. Figure 2 depicts an example of a real-time image and corresponding catalogue page. 35 Such near-real-time quick-look charts were crucial in the two field campaigns discussed later for changing scan patterns and 36 directing aircraft. The <u>quick-look images</u> were also <u>helpful</u> to the NXPol's operators and forecasters at the Scottish 37 Environmental Protection Agency and the U.K.'s Met Office during the six-month-long Radar Applications in Northern 38 Scotland (RAINS) campaign in 2016 (Section 3.3) for assessing the impact that a radar in this location would have on

39 observational quality in near-real-time conditions in comparison to existing observations.

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- 45 Figure 2. Example of the data catalogue used to monitor the NXPol observations in near-real time during the RAINS project
- 46 described in Section 3.3. The background shows a collection of a set of images from a single day while the foreground highlights an

47 example of a near-real-time image produced by Rainbow®5.



## 49 2.2 Deployment Setup

50 The operational requirements dictated by the strategic and project-specific scientific goals of the NXPol have led to the 51 development of bespoke infrastructure to support the radar during operations. The primary requirements for deploying the 52 NXPol radar are visibility, security, power and internet access. Considering these options, the NXPol may be deployed using 53 solely its integrated trailer (as in Figure 1) or in conjunction with a platform structure as depicted in Figure 3. The platform 54 setup is based on a similar scheme employed by Selex ES GmbH for the NXPol's deployment during the Single European 55 Sky ATM (Air Traffic Management) Research (SESAR) campaign in 2015 at Braunschweig Airport near Hanover, 56 Germany. The setup has the major advantage of lifting the radar off the ground to provide greater visibility. It also makes 57 security and public safety issues (See Section 2.3) less problematic, 58 59 The platform consists of a 20-foot standard shipping container and a 20-foot office container set side by side along their long axis. To provide the necessary structural strength to support the weight of the NXPol, on top of each of the containers is a 60 61 20-foot platform container (also known as a 'flat rack'). Using standard shipping containers and platforms dramatically 62 reduces engineering time and cost during deployments. Also, because of their global ubiquitousness, the elements needed to construct a similar platform can be sourced locally. This further reduces deployment costs. To provide safe access to the 63 64 radar while it is on the platform, a staircase and railing are constructed from standard scaffolding materials as shown in Figure 3. Also attached to the platform structure are the various pieces of hardware that support a long-term autonomous 65 deployment of the NXPol; lightning protection, a satellite internet connection, security camera and local weather station. 66 67 68 In addition to providing a platform for the NXPol, the office unit provides space for the additional IT infrastructure needed 69 for NXPol's autonomous operation (described below). The office also provides a base of operations for staff while on site 70 during remote fieldwork. The office is particularly useful during observational campaigns that involve the coordinated

71 operation of the radar and an aircraft (such as the ICE-D campaign described in Section 3.2). During such campaigns, staff

can monitor and direct the radar's observations in real-time and communicate with the aircraft to help target the

73 observations.

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- 75 Figure 3. NXPol deployed at Chilbolton Observatory, Hampshire, UK. Seen in the picture is the 20' shipping container, 20' office
- 76 container, two 20' platform containers and scaffolding used to construct a platform for the radar.



There is also the need in the scientific community for the collection of statistically meaningful observations over a wide

range of synoptic conditions. This requirement has necessitated the move to semi-permanent, continuous and autonomous

81 operations that last for many months. The RAINS project and on-going work at NFARR (where the NXPol will operate for

82 several months at a time between campaign deployments) in particular demonstrate the need for this type of facility to 83 support the radar in its long-term operations,

84

85 Table 3 summarises the operational requirements of the NXPol. Data and power availability vary depending on the

86 deployment. Typically, when the NXPol is deployed for less than 24 hours, the onboard generator supplied by an 80 L fuel

87 tank provides all electricity. An onboard 3G mobile data connection or satellite link provide internet connectivity. When the

88 NXPol is deployed using the container platform, mains electricity is connected to the radar's electrical grid and the onboard 89

generator acts as a backup power supply that is automatically started upon loss of mains power. Additionally, the 3G mobile

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- 93 data connection is supplemented with a local area network connection or a satellite internet connection. This allows for
- 94 more robust autonomous and remote operation of the system.
- 95

#### 96 Table 3. Operational conditions and logistical requirements of the NXPol.

Conditions	Specifications
Max Operational Wind Speed without Radome	56 mph (90km/h)
Electrical Supply	3-phase 32A Service or Onboard Diesel Generator
Power Consumption	8kW (average), 12kW (max)
Operating Temperatures	-10C to 35C
Total Weight, Nose weight	2800kg, 120kg
Width (without supports, with supports)	2.550m, 3.560m
Height (0 degs, 90 degs)	3.995m, 4.250m
Max drive Speed	50mph (80km/h)

97

98 The IT infrastructure needed for the NXPol's autonomous operation includes a server that provides a gateway for

99 communicating with the radar and data backup. Figure 4 summarises the IT strategy. In addition to communications, the

infrastructure includes a local weather station to primarily monitor wind speeds, a video camera to monitor the radar's

.01 movement and an Uninterruptible Power Supply (UPS) for the server. Data production is on the order of between 5 and 9 Gb

.02 per day. During long-term remote operations the data can be backed-up using a commercial satellite internet system if

available, although it may be cost-prohibitive if there is not an unmetered period (typically in the early hours of the morning

local time). The onboard 3G connection provides redundancy and/or remote control, if local signal strength permits, but it is

not practical to backup bulk data via this route. If near-real-time remote raw data access is required, a suitable Internet

connection is necessary. Quick-look charts as shown in Figure 2 use considerably less data and are therefore logistically

107 simpler, potentially allowing selective download of raw data over a lower-bandwidth connection. Data are backed-up locally

to a Network Attached Storage (NAS) system in the office container in medium- to long-term deployments.

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# Figure 4. Schematic of the IT infrastructure used by the NXPol when on deployment.

:11

# 12 2.3 Safety

:13	An important consideration when deploying the NXPol radar is the protection of both operators and the public from
:14	exposure to transmissions. The location of the deployment site is determined in conjunction with the required safety distance
:15	specified by a radiation exposure assessment. The International Commission on Non-Ionizing Radiation Protection
:16	(INCIRP) specifies that the maximum continuous exposure to radiation at frequencies between 2 GHz and 300 GHz should
:17	not exceed 10Wm <sup>-2</sup> in areas where the general population has access and 50 Wm <sup>-2</sup> for occupational exposure, averaged over
18	a period of 6 minutes (Ahlbom et al. 1998). When deployed on the ground, a safety barrier must be constructed or measures
:19	put in place to prevent access within the distance which the exposure threshold would be exceeded as determined by the
:20	radiation assessment (e.g. if the radar dish stops scanning). When NXPol is situated on a platform and is scanning and
:21	operating as scheduled, there is no risk to people (including those with implanted medical devices) on the ground 15m from
:22	the radar and, hence, this is another benefit of this method of deployment. If the radar is unmanned on the platform, then
:23	access must be restricted to the distance at which public exposure limits (10W/m <sup>2</sup> ) are reached in the event the NXPol
:24	malfunctions and stops scanning but continues to transmit.
:24 :25	malfunctions and stops scanning but continues to transmit.
:24 :25 :26	malfunctions and stops scanning but continues to transmit.
:24 :25 :26 :27	malfunctions and stops scanning but continues to transmit.  The second major safety consideration is the operation of the system in high winds. Without a radome the maximum
24 25 26 27 28	malfunctions and stops scanning but continues to transmit.  The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text
24 25 26 27 28 29	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators
:24 :25 :26 :27 :28 :29 :30	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators closely monitor the conditions during forecasted events and, in the case of significant winds, interrupt the scan schedule to
:24 :25 :26 :27 :28 :29 :30 :31	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators closely monitor the conditions during forecasted events and, in the case of significant winds, interrupt the scan schedule to move the antenna into the vertical position (which provides the least wind resistance) and activate the locking stow pin to
:24 :25 :26 :27 :28 :29 :30 :31 :32	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators closely monitor the conditions during forecasted events and, in the case of significant winds, interrupt the scan schedule to move the antenna into the vertical position (which provides the least wind resistance) and activate the locking stow pin to prevent movement. In addition to winds, NXPol's temperature must be monitored carefully to avoid operations below -10C
:24 :25 :26 :27 :28 :29 :30 :31 :32 :33	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators closely monitor the conditions during forecasted events and, in the case of significant winds, interrupt the scan schedule to move the antenna into the vertical position (which provides the least wind resistance) and activate the locking stow pin to prevent movement. In addition to winds, NXPol's temperature must be monitored carefully to avoid operations below -10C and above 35C as there is no radome to provide a conditioned environment for the transmitter and receiver equipment boxes
:24 :25 :26 :27 :28 :29 :30 :31 :32 :33 :34	malfunctions and stops scanning but continues to transmit. The second major safety consideration is the operation of the system in high winds. Without a radome the maximum operational wind speed is 56mph. The weather station continuously monitors the wind speed and notifies operators via text and email alerts when a set threshold (typically below the 56mph maximum limit to allow for gusts) is exceeded. Operators closely monitor the conditions during forecasted events and, in the case of significant winds, interrupt the scan schedule to move the antenna into the vertical position (which provides the least wind resistance) and activate the locking stow pin to prevent movement. In addition to winds, NXPol's temperature must be monitored carefully to avoid operations below -10C and above 35C as there is no radome to provide a conditioned environment for the transmitter and receiver equipment boxes located behind the antenna. This operational range also limits the regions where the NXPol may be deployed.

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**Deleted:** When NXPol is situated on a platform and is scanning and operating as scheduled, there is no risk to people on the ground at any distance from the radar and hence is another benefit of this method of deployment. If the radar is ummanned, a contingency plan must be considered in the event the system malfunctions and stops scanning but continues transmitting.

### 43 3 Example Deployments and Observations

Below, four examples of the use of NXPol are given. Descriptions are provided to highlight the utilisation of the radar to
 achieve the scientific aims of each project.

#### 46 3.1 COPE

:47 NXPol was utilised for the first time in the COnvective Precipitation Experiment (COPE) held in the vicinity of Davidstow, Cornwall during July and August, 2013. Three aircraft, including the Facility for Airborne Atmospheric Measurement :48 :49 (FAAM) BAe-146 aircraft, and other ground-based instruments were also deployed; see Leon at al., (2015). The principal :50 aim of the project was to understand the physical processes involved in the production of heavy convective precipitation that could result in flash flooding. Ultimately, predictions of heavy precipitation and potential flash floods by Numerical Weather :51 Prediction (NWP) models will be improved as a result of the new knowledge and understanding of physical processes. :52 :53 Several flash flooding events have previously occurred in the region, the most notable in recent years being the Boscastle :54 flood of 2004 (Golding et al. 2005). The role of the radar was to determine (a) the altitude of the first echoes; (b) the rate of development of the reflectivity echoes; (c) the spatial and temporal distribution of the main echoes; (d) the particle types :55 :56 from dual-polarisation parameters (e.g. warm rain or graupel), and (e) the maximum intensity of the precipitation. 57 :58 NXPol collected data during 16 IOPs covering a variety of synoptic and microphysical conditions including heavy :59 precipitation from shallow clouds (warm rain only) and several cases of deep convection along semi-organised convective :60 lines with similarities to the Boscastle event. An example of the convective clouds that formed along a convergence line (at 61 20 km range between S and SE) and observed elsewhere on 3 August, 2013 is shown in Figure 5. Note that Figure 5 and all following figures were created using software developed in NCAS that is based on the Py-ART software suite (Helmus and 62 63 Colis, 2016). The rainfall rates (Figure 5d) were derived from the unfiltered and uncorrected calibrated horizontal 64 reflectivity (Z<sub>H</sub>, Figure 5a) by first applying a second trip filter and a fuzzy logic clutter filter as described by Dufton and Collier (2015). In addition to these corrections, a correction for partial beam blocking and attenuation (AH) have also been :65 applied. From this corrected  $Z_{H}$ , rainfall rate was retrieved using the Marshall-Palmer relation (R(Z)=aZ<sup>b</sup>, with a=200 and :66 67 b=1.6 as is used by the UK Met Office) to derive rain rate for their operational network of C-band radars (Marshall and

Palmer, 1948). For access to the observations made with the NXPol during COPE, please see the Centre for Environmental





72 Figure 5. Example of observations made by NXPol (located at the centre black dot) at 0.5° elevation on 3 August 2013 at 1332

173 UTC showing: a) calibrated but unfiltered and uncorrected horizontal reflectivity (Shown as to display the importance and impact

 $\frac{of \text{ the data processing), b) calibrated, filtered and corrected differential reflectivity, c) specific horizontal attenuation (A_{H}) and d)}{rainfall rates derived using the Marshall-Palmer relation (R(Z)=aZ<sup>b</sup>, with a=200 and b=1.6. The missing spokes of data in A_{H} are$ 

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in d) shows an expanded section of the line of intense rainfall (>120mm/hr in some pixels; please note the expanded colorbar to the





15

Deleted: Figure 5. Example of observations made by NXP01 (located at the centre black dot) at  $0.5^\circ$  elevation on 3 August 2013 at 1332 UTC showing: a) calibrated but unfiltered and uncorrected horizontal reflectivity (Shown as to display the importance and impact of the data processing), b) calibrated, filtered and corrected differential reflectivity, c) specific horizontal attenuation (A<sub>ii</sub>) and d) rainfall rates derived using the Marshall-Palmer relation (R(Z)=aZ<sup>b</sup>, with a=200 and b=1.6. The sub-panel in d) shows an expanded section of the line of intense rainfall (>120mm/hr in some pixels; please note the expanded colorbar to the top of the sub-panel) to the southeast of the radar. Range rings are drawn every 10km.

#### .94 3.2 ICE-D

- NXPol was deployed at Praia, Cape Verde (14°55'N 23°31'W) during July and August 2015 in the UK's Ice in Clouds
- 96 Experiment-Dust (ICE-D). The goal of ICE-D was to determine how desert dust affects primary nucleation of ice particles in
- .97 convective and layer clouds and the subsequent development of precipitation and glaciation of the clouds. In addition to
- 98 NXPol, the FAAM BAe-146 research aircraft and the University of Manchester ground-based aerosol laboratory were
- .99 deployed. <u>All data from this campaign may be found on CEDA at</u>
- 00 http://catalogue.ceda.ac.uk/uuid/55b5d76a7edb42e39933c1edc37f7b90.
- 01
- 02 The main objective of NXPol was to provide the spatial and temporal distribution of the clouds, to identify suitable cloud
- 03 regions for the aircraft to sample and to provide coordinated observations of the development of precipitation within about
- 100 km of the island. Two modes of data collection were implemented dependent on the synoptic conditions and location of
- 05 cloud development. In "surveillance mode", NXPol was configured to maximise its observable range. In this mode,
- 06 observations were made out to 300 km at several low elevations. An example surveillance mode PPI observed on 23 August
- 07 2015 using the surveillance mode is given in Figure 6. Use of the radar in this mode was found to be invaluable for near-term
- 08 mission planning and directing the use of the FAAM once it was airborne. For suitable clouds at closer range, NXPol
- 09 operated in "data-collection mode", providing higher spatial and temporal resolution observations; volumes of 12 elevations
- 10 from 0.5 up to 12 degrees were collected out to a range of 150 km similar to COPE.



- 13 Figure 6. Example of a surveillance mode PPI observed by NXPol at 2019UTC on 23 August 2015 while on the ICE-D deployment
- 14 in Praia, Cape Verde. Range rings are drawn every 50km. The thick black outlines are the islands of Cape Verde.



Deleted: Figure 6. Example of a surveillance mode PPI observed by NXPol at 2119UTC on 23 August 2015 while on the ICE-D deployment in Praia, Cape Verde. Range rings are drawn every 50km.¶ ....[2]

#### 15

#### 16 **3.3 Radar Applications in Northern Scotland (RAINS)**

17 COPE and ICE-D are examples of the use of the NXPol for traditional IOP based operations. This section highlights the use

of the NXPol for semi-permanent operations. Previous studies have shown the value of operating a mobile polarimetric X-

band radar in coastal regions to fill gaps in the coverage of national operational radar networks (Matrosov et al. 2005).

20 Matrosov et al. (2005) found that the NOAA X-band radar (9.34 Hz, 30kW peak power) was effective in covering an area up

21 to 40–50 km in radius offshore adjacent to a region that is prone to flooding during wintertime land landfalling Pacific

22 storms. More recently, the Collaborative Adaptive Sensing of the Atmosphere (CASA) Engineering Research Center's X-

23 band dual-polarisation radar network has shown the utility of short-range radars at making high-resolution observations of

rainfall that are close to the ground over a variety of conditions (Wang and Chandrasekar, 2010).

25

30 During the RAINS campaign, the NXPol was installed at Army Base 39 Engineer Regiment, Kinloss, northeast Scotland 31 from January 2016 to August 2016. This deployment was a joint project between NCAS, the Scottish Environment Protection Agency (SEPA), the University of Leeds and the UK Met Office with the goal of examining the value of 32 33 additional and higher-resolution radar observations in this region for creating more accurate QPE and flood forecasts. Beyond just improving radar coverage in Northern Scotland, the data collected from the NXPol is also being used to 34 35 examine the specific improvements in QPE that dual-polarisation observations can provide hydrological models in this 36 region, which is characterised by low melting levels (i.e. low bright bands) and mountainous terrain. In Figure 7 we show an 37 example of two differing QPEs during a typical precipitation event during the deployment. The observations and the two 38 rainfall rate retrievals are shown here to highlight the potential differences in rainfall rate methods that are being explored as 39 part of RAINS. In particular we highlight the difference between the rainfall rate calculated using the Marshall-Palmer 40 relation (R(Z)=aZ<sup>b</sup>, with a=200 and b=1.6) which is used by the UK Met Office and rainfall rates calculated using the 41  $R(Z_{H},K_{DP})$ . The  $R(Z_{H},K_{DP})$  is described in Diederich et al. (2015b) and here we use a = 16.9 and b = 0.801. The entire 42 RAINS dataset may be requested from the author as it is still undergoing primary analysis with SEPA and has not been 43 released publically. Once this analysis has been concluded the dataset will be available on CEDA. 44 45 As part of the work in RAINS, a set of software tools was created to convert NXPol data into the Met Office NIMROD

As part of the work in RAINS, a set of software tools was created to convert NXPol data into the Met Office NIMROD
 format using a combination of gridding software (Py-ART or LROSE) and bespoke scripts developed by NCAS. Many UK
 agencies (i.e. the Environment Agency and SEPA) use this format in their modelling and analysis tools such as HyRAD,

18

48 developed by the UK's Centre for Ecology and Hydrology (CEH). These scripts may be requested from the authors.

49

- 51 Figure 7. Observations and derived rainfall rates from the RAINS campaign on 20 July 2016 at 0409 UTC at 1.5° elevation: NXPol
- 52 is located at the black dot and range rings are drawn every 25km. (a) calibrated, corrected and filtered  $Z_{\rm H}$  classified as
- 53 precipitation echoes; (b), (c) and (d) calibrated, corrected and filtered Z<sub>DR</sub>, K<sub>DP</sub>, and A<sub>H</sub>, (e) rainfall rate calculated using the
- 54 Marshall-Palmer relation (R(Z)=aZ<sup>b</sup>, with a=200 and b=1.6) and (f) rainfall rates calculated using R(Z<sub>H</sub>,K<sub>DP</sub>). NXPol is located at
- 55 the black dot and range rings are drawn every 25km.







58	4 Ongoing Work at <u>NFARR</u>	
59	In between major field deployments, the NXPol makes continuous observations at the National Facility for Atmospheric	
60	Radar Research (NFARR), located near Chilbolton in Hampshire, UK. This enables NXPol to work in coordination with the	
61	other state-of-the-art radar facilities located at the observatory to make novel observations of high impact wintertime storms	
62	and summertime convective events using an array of ground-based remote sensing and in situ observations. The goal of this	
63	work is to improve flood forecasting in the UK by using these novel observations to drive the development of physical	
64	parameterisations in high-resolution numerical weather prediction models.	
65		
66	Most significantly, this work includes NXPol making coincidental RHI scans of frontal events with the Chilbolton Advanced	
67	Meteorological Radar (CAMRa), which is the largest steerable meteorological radar in the world. CAMRa operates at S-	
68	band (~3 GHz), and its 25m antenna creates a beam width of only 0.25°. This results in the ability to make high-resolution	
69	observations at far ranges (i.e. at 100 km from the dish, the resolution of a 0.25° beam is 0.4 km). Like the NXPol, CAMRa	
70	has dual-polarisation and Doppler capabilities. For a full description of CAMRa, please see Goddard et al. (1984). An	
71	example of coincidental observations from CAMRa and the NXPol on January 12th, 2017 at 13:36 UTC are shown in Figure	
72	8. Currently, observations from both radars may be requested from the authors as they still undergoing its primary analysis.	
73	The datasets will also become public on CEDA by 2020 after the 2 year embargo period for this campaign is over.	
74		
75	As part of the ongoing research with NXPol, the use of hydrometeor classification algorithms (HCAs; also referred to as	
76	particle identification or PID) to explore cloud microphysics is being pursued. Such an HCA has been initially implemented	
77	for the NXPol using the framework provided by LROSE (Dixon et al. 2012). The HCA is a fuzzy logic approach, and the	
78	membership functions are based largely on the work of Dolan and Rutledge (2009) and Thompson et al. (2014). An	
79	example result of the HCA applied to NXPol and CAMRa observations from May 17th, 2017 at 12:24 UTC is shown in	
80	Figure 9. The NXPol's HCA results are part of on-going research and have not yet been fully validated. As such, Figure 9 is	
81	shown only to demonstrate the type of on-going investigations enabled by the NXPol's observations. Nevertheless, the	
82	comparison shows good qualitative agreement between the algorithms applied to the two radars. Future work will include	
83	validation with in situ observations made with FAAM. We hope that the use of multiple frequencies will help constrain and	
84	reduce uncertainty associated scattering parameters within the retrieval.	

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Figure 8. Coincident RHIs of Z<sub>H</sub> (a and b) and Z<sub>DR</sub> (c and d) from the NXPol (a and c) and CAMRa (b and d) on 12 January 2017
 at 13:36 UTC.





90 Figure 9. Coincident RHIs from the NXPol (a) and CAMRa (b) on 17 May 2017 at 12:24 UTC with the HCA applied to both.

### 92 5 Summary

- 93 Here we have summarised the key technical characteristics of the NXPol and the infrastructure used to deploy the system
- 94 autonomously at remote locations. We have also shown examples of its successful use in four differing scientific campaigns.
- As is shown in the examples, the NXPol is a highly capable and flexible instrument for use in examining the microphysics of
- elouds and producing QPE. As described in Section 4, in between bespoke deployments to remote locations, the NXPol will
- 97 be located at NFARR to make continuous observations in conjunction with other instruments at this site. The NCAS and
- .98 Leeds University Radar Group welcomes any collaborations that utilise the NXPol and its observations.
- .99

.03

00 For further information on the use of the NXPol including instrument access policies, data format, NXPol specific analysis

- 01 software and availability, please see the NXPol instrument homepage at: https://www.ncas.ac.uk/index.php/en/about-
- 02 amf/263-amf-main-category/amf-x-band-radar/1098-x-band-radar-overview.

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Ryan Neely III

#### 12/07/2018 06:44:00

Figure 5. Example of observations made by NXPol (located at the centre black dot) at  $0.5^{\circ}$  elevation on 3 August 2013 at 1332 UTC showing: a) calibrated but unfiltered and uncorrected horizontal reflectivity (Shown as to display the importance and impact of the data processing), b) calibrated, filtered and corrected differential reflectivity, c) specific horizontal attenuation (A<sub>H</sub>) and d) rainfall rates derived using the Marshall-Palmer relation (R(Z)=aZ<sup>b</sup>, with a=200 and b=1.6. The sub-panel in d) shows an expanded section of the line of intense rainfall (>120mm/hr in some pixels; please note the expanded colorbar to the top of the sub-panel) to the southeast of the radar. Range rings are drawn every 10km.



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12/07/2018 06:51:00

Figure 6. Example of a surveillance mode PPI observed by NXPol at 2119UTC on 23 August 2015 while on the ICE-D deployment in Praia, Cape Verde. Range rings are drawn every 50km.

