



## 1                    **Comparison of Aircraft Measurements during GoAmazon2014/5 and** 2                    **ACRIDICON-CHUVA**

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26     **Abstract.** The indirect effect of atmospheric aerosol particles on the Earth's radiation balance  
27     remains one of the most uncertain components affecting climate change throughout the industrial  
28     period. This issue is partially a result of the incomplete understanding of aerosol-cloud  
29     interactions. One objective of the GoAmazon2014/5 and ACRIDICON-CHUVA projects was to  
30     improve the understanding of the influence of the emissions of the tropical megacity of Manaus



31 (Brazil) on the surrounding atmospheric environment of the rainforest and to investigate its role in  
32 the life cycle of convective clouds. During one of the intensive observation periods (IOPs) in the  
33 dry season from September 1 to October 10, 2014, comprehensive instrument suites collected data  
34 from several ground sites. In a coordinated way, the advanced suites of sophisticated instruments  
35 were deployed in situ both from the U.S. Department of Energy Gulfstream-1 (G1) aircraft and  
36 the German High Altitude and Long-Range Research Aircraft (HALO) during three coordinated  
37 flights on September 9, 21, and October 1. Here we report on the comparison of measurements  
38 collected by the two aircraft during these three flights. Such comparisons are difficult to obtain,  
39 but they are essential for assessing the data quality from the individual platforms and quantifying  
40 their uncertainty sources. Similar instruments mounted on the G1 and HALO collected vertical  
41 profile measurements of aerosol particles number concentration and size distribution, cloud  
42 condensation nuclei concentration, ozone, and carbon monoxide concentration, cloud droplet size  
43 distribution, and downward solar irradiance. We find that the above measurements from the two  
44 aircraft agreed within the range given by the measurement uncertainties. Aerosol chemical  
45 composition measured by instruments on HALO agreed with the corresponding G1 data collected  
46 at high altitudes only. Furthermore, possible causes of discrepancies between the data sets  
47 collected by the G1 and HALO instrumentation are addressed in this paper. Based on these results,  
48 criteria for meaningful aircraft measurement comparisons are discussed.

49

## 50 1. Introduction

51 Dominated by biogenic sources, the Amazon basin is one of the few remaining continental  
52 regions where atmospheric conditions realistically represent those of the pristine or pre-industrial  
53 era (Andreae et al., 2015). As a natural atmospheric “chamber”, the area around the urban region  
54 of Manaus in central Amazonia is an ideal location for studying the atmosphere under natural  
55 conditions as well as under conditions influenced by human activities and biomass burning events  
56 (Andreae et al., 2015; Artaxo et al., 2013; Davidson et al., 2012; Keller et al., 2009; Kuhn et al.,  
57 2010; Martin et al., 2016b; Pöhlker et al., 2018; Poschl et al., 2010; Salati and Vose, 1984). The  
58 Observations and Modeling of the Green Ocean Amazon (GoAmazon2014/5) campaign was  
59 conducted in 2014 and 2015 (Martin et al., 2017; Martin et al., 2016b). The primary objective of  
60 GoAmazon2014/5 was to improve the quantitative understanding of the effects of anthropogenic



61 influences on atmospheric chemistry and aerosol-cloud interactions in the tropical rainforest area.  
62 During the dry season in 2014, the ACRIDICON (Aerosol, Cloud, Precipitation, and Radiation  
63 Interactions and Dynamics of Convective Cloud Systems)-CHUVA (Cloud Processes of the Main  
64 Precipitation Systems in Brazil) campaign also took place to study tropical convective clouds and  
65 precipitation over Amazonia (Wendisch et al., 2016).

66 A feature of the GoAmazon 2014/5 field campaign was the design of the ground sites'  
67 location, which uses principles of Lagrangian sampling to align the sites with the Manaus pollution  
68 plume (Figure 1: Source location – Manaus (T1 site), and downwind location – Manacapuru (T3  
69 site)). The ground sites were overflown with the low-altitude U.S. Department of Energy (DOE)  
70 Gulfstream-1 (G1) aircraft and the German High Altitude and Long Range Research Aircraft  
71 (HALO). These two aircraft are among the most advanced in atmospheric research, deploying  
72 suites of sophisticated and well-calibrated instruments (Schmid et al., 2014; Wendisch et al.,  
73 2016). The pollution plume from Manaus was intensively sampled during the G1 and HALO  
74 flights and also by the DOE Atmospheric Radiation Measurement (ARM) program Mobile  
75 Aerosol Observing System and ARM Mobile Facility located at one of the downwind surface sites  
76 (T3 site- 70 km west of Manaus). The routine ground measurements with coordinated and intensive  
77 observations from both aircraft provided an extensive data set of multi-dimensional observations  
78 in the region, which serves i) to improve the scientific understanding of the influence of the  
79 emissions of the tropical megacity of Manaus (Brazil) on the surrounding atmospheric  
80 environment of the rainforest and ii) to understand the life cycle of deep convective clouds and  
81 study open questions related to their influence on the atmospheric energy budget and hydrological  
82 cycle.

83 As more and more data sets are merged to link the ground-based measurements with  
84 aircraft observations, and as more studies focus on the spatial variation and temporal evolution of  
85 the atmospheric properties, it is critical to quantify the uncertainties ranges when combining the  
86 data collected from the different platforms. Due to the challenges of airborne operations, especially  
87 when two aircraft are involved in data collection in the same area, direct comparison studies are  
88 rare. However, this type of study is critical for further combining the datasets between the ground  
89 sites and aircraft. Thus, the main objectives of the study herein are to demonstrate how to achieve  
90 meaningful comparisons between two moving platforms, to conduct detailed comparisons  
91 between data collected by two aircraft, to identify the potential measurement issues, to quantify



92 reasonable uncertainty ranges of the extensive collection of measurements, and to evaluate the  
93 measurement sensitivities to the temporal and spatial variance. The comparisons and the related  
94 uncertainty estimations quantify the current measurement limits, which provide realistic  
95 measurement ranges to climate models as initial conditions to evaluate their output.

96 The combined GoAmazon2014/5 and ACRIDICON-CHUVA field campaigns not only  
97 provide critical measurements of aerosol and cloud properties in an under-sampled geographic  
98 region but also provide a unique opportunity to understand and quantify the quality of these  
99 measurements using closely orchestrated comparison flights. The comparisons between the  
100 measurements from similar instruments on the two research aircraft can be used to identify  
101 potential measurement issues and quantify the uncertainty range of the field measurements, which  
102 include primary meteorological variables (Section 3.1), trace gases concentrations (Section 3.2),  
103 aerosol particle properties (number concentration, size distribution, chemical composition, and  
104 microphysical properties) (Section 3.3), cloud properties (Section 3.4), and downward solar  
105 irradiance (Section 3.5). We evaluate the consistency between the measurements aboard the two  
106 aircraft for a nearly full set of gas, aerosol particle, and cloud variables. Results from this  
107 comparison study provide the foundation not only for assessing and interpreting the observations  
108 from multiple platforms (from the ground to low altitude, and then to high altitude) but also for  
109 providing high-quality data to improve the understanding of the accuracy of the measurements  
110 related to the effects of human activities in Manaus on local air quality, terrestrial ecosystems in  
111 rainforest, and tropical weather.

## 112 **2. Measurements**

### 113 **2.1 Instruments**

114 The ARM Aerial Facility deployed several in situ instruments on the G1 to measure  
115 atmospheric state parameters, trace gases concentrations, aerosol particle properties, and cloud  
116 characteristics (Martin et al., 2016b; Schmid et al., 2014). The instruments installed on HALO  
117 covered measurements of meteorological, chemical, microphysical, and radiation parameters.  
118 Details of measurements aboard HALO are discussed in the ACRIDICON-CHUVA campaign  
119 overview paper (Wendisch et al., 2016). The measurements compared between the G1 and HALO  
120 are listed in Table 1.

#### 121 **2.1.1 Atmospheric parameters**



122 All G1 and HALO meteorological sensors were routinely calibrated to maintain measurement  
123 accuracy. The G1 primary meteorological data were provided at one-second time resolution based  
124 on the standard developed by the Inter-Agency Working Group for Airborne Data and Telemetry  
125 Systems (Webster and Freudinger, 2018). For static temperature measurement, the uncertainty  
126 given by the manufacturer (Emerson) is  $\pm 0.1$  K, and the uncertainty of the field data is  $\pm 0.5$  K.  
127 The static pressure had a measurement uncertainty of 0.5 hPa. The standard measurement  
128 uncertainties were  $\pm 2$  K for the chilled mirror hygrometer and  $0.5 \text{ ms}^{-1}$  for wind speed.

129 On HALO, primary meteorological data were obtained from the Basic HALO Measurement  
130 and Sensor System (BAHAMAS) at one-second time resolution. The system acquired data from  
131 airflow and thermodynamic sensors and from the aircraft avionics and a high-precision inertial  
132 reference system to derive the basic meteorological parameters like pressure, temperature, the 3D  
133 wind vector, aircraft position, and attitude. Water vapor mixing ratio and further derived humidity  
134 quantities were measured by the Sophisticated Hygrometer for Atmospheric Research (SHARC)  
135 based on direct absorption measurement by a tunable diode laser (TDL) system. The absolute  
136 accuracy of the primary meteorological data was 0.5 K for air temperature, 0.3 hPa for air pressure,  
137  $0.4\text{-}0.6 \text{ ms}^{-1}$  for wind, and 5% ( $\pm 1$  ppm) for water vapor mixing ratio. All sensors were routinely  
138 calibrated and traceable to national standards (Giez et al., 2017; Krautstrunk and Giez, 2012).

### 139 2.1.2 Gas phase

140 Constrained by data availability, this comparison of trace gas measurements is focused on  
141 carbon monoxide (CO) and ozone (O<sub>3</sub>) concentrations. Those measurements were made aboard  
142 the G1 by a CO/N<sub>2</sub>O/H<sub>2</sub>O instrument (Los Gatos Integrated Cavity Output Spectroscopy  
143 instrument model 907-0015-0001), and an Ozone Analyzer (Thermo Scientific, Model 49i),  
144 respectively. The G1 CO analyzer was calibrated for response daily by NIST-traceable commercial  
145 standards before the flight. Due to the difference between laboratory and field conditions, the  
146 uncertainty of CO measurement is about  $\pm 5\%$  for one-second sampling periods. An ultra-fast  
147 carbon monoxide monitor (Aero Laser GmbH, AL5002) was deployed on HALO. The detection  
148 of CO is based on a vacuum-ultraviolet-fluorimetry, employing the excitation of CO at 150 nm  
149 and the precision is 2 ppb, and the accuracy is about 5%. The ozone analyzer measures ozone  
150 concentration based on the absorbance of ultraviolet light at a wavelength of 254 nm. The ozone  
151 analyzer (Thermo Scientific, Model 49c) in the HALO payload is very similar to the one on the



152 G1 (Model 49i), with an accuracy greater than 2 ppb or about  $\pm 5\%$  for four-second sampling  
153 periods. The G1 ozone monitor was calibrated at the New York State Department of  
154 Environmental Conservation testing laboratory at Albany.

### 155 2.1.3 Aerosol

156 Aerosol number concentration was measured by different condensation particle counters  
157 (CPCs) on the G1 (TSI, CPC 3010) and HALO (Grimm, CPC model 5.410). Although two CPCs  
158 were from different manufacturers, they were designed using the same principle, which is to detect  
159 particles by condensing butanol vapor on the particles to grow them to a large enough size that  
160 they can be counted optically. Both CPCs were routinely calibrated in the lab and reported the data  
161 at one-second time resolution. The HALO CPC operated at  $0.6\text{--}1\text{ L min}^{-1}$ , with a nominal cutoff  
162 of 4 nm. Due to inlet losses, the effective cutoff diameter increases to 9.2 nm at 1000 hPa, and  
163 11.2 nm at 500 hPa (Andreae et al., 2018; Petzold et al., 2011). The G1 CPC operated at  $1\text{ L min}^{-1}$   
164 volumetric flow rate and the nominal cut-off diameter  $D_{50}$  measured in the lab was  $\sim 10$  nm.  
165 During a flight, the cut-off diameter may vary due to tubing losses, which contribute less than 10  
166 % uncertainty to the comparison between two CPC concentrations.

167 Two instruments deployed on the G1 measured aerosol particle size distribution. a Fast  
168 Integrated Mobility Spectrometer (FIMS) inside of the G1 cabin measured the aerosol mobility  
169 size from 15 to 400 nm (Kulkarni and Wang, 2006a, b; Olfert et al., 2008; Wang, 2009). The  
170 ambient aerosol particles were charged after entering the FIMS inlet and then separated into  
171 different trajectories in an electric field based on their electrical mobility. The spatially separated  
172 particles grow into super-micrometer droplets in a condenser where supersaturation of the working  
173 fluid is generated by cooling. At the exit of the condenser, a high-speed charge-coupled device  
174 camera captures the image of an illuminated grown droplet at high resolution. In this study, we  
175 used the FIMS 1 Hz data for comparison. The size distribution data from FIMS were smoothed.  
176 Aside from the FIMS, The airborne version of the Ultra High Sensitivity Aerosol Spectrometer  
177 (UHSAS) was deployed on G1 and HALO. The G1 and HALO UHSAS were manufactured by  
178 the same company, and both were mounted under the wing on a pylon. UHSAS is an optical-  
179 scattering, laser-based particle spectrometer system. The size resolution is around 5% of the  
180 particle size. The G1 UHSAS typically covered a size range of 60 nm to 1000 nm. HALO UHSAS  
181 covered 90 nm to 500 nm size range for the September 9 flight.



182 Based on operating principles, FIMS measures aerosol electrical mobility size and UHSAS  
183 measures aerosol optical equivalent size. Thus, the difference in the averaged size distributions  
184 from those two types of instruments might be linked to differences in their underlying operating  
185 principles, such as the assumption in the optical properties of aerosol particles. The data processing  
186 in the G1 UHSAS assumed that the particle refractive index is similar to ammonium sulfate (1.55),  
187 which is larger than the average refractive index (1.41-0.013i) from a previous Amazon study  
188 (Guyon et al., 2003). The HALO UHSAS was calibrated with polystyrene latex spheres, which  
189 has a refractive index about 1.572 for the UHSAS wavelength of 1054 nm. The uncertainty due to  
190 the refraction index can lead to up to 10% variation in UHSAS measured size (Kupc et al., 2018).  
191 Also, the assumption of spherical particles affects the accuracy of UHSAS sizing of ambient  
192 aerosols.

193 The chemical composition of submicron non-refractory (NR-PM<sub>1</sub>) organic and inorganic  
194 (sulfate, nitrate, ammonium) aerosol particles was measured using a high-resolution time-of-flight  
195 aerosol mass spectrometer (HR-ToF-AMS) aboard the G1 (DeCarlo et al., 2006; Jayne et al., 2000;  
196 Shilling et al., 2018; Shilling et al., 2013). Based on the standard deviation of observed aerosol  
197 mass loadings during filter measurements, the HR-ToF-AMS detection limits for the average time  
198 of thirteen seconds are approximately 0.13, 0.01, 0.02, 0.01 (3 $\sigma$  values)  $\mu\text{g m}^{-3}$  for organic, sulfate,  
199 nitrate, and ammonium, respectively (DeCarlo et al., 2006). A Compact Time-of-flight Aerosol  
200 Mass Spectrometer (C-ToF-AMS) was operated aboard HALO to investigate the aerosol  
201 composition. Aerosol particles enter both the C-ToF-AMS and HR-ToF-AMS via constant  
202 pressure inlets controlling the volumetric flow into the instrument, although the designs of the  
203 inlets are somewhat different (Bahreini et al., 2008). The details about the C-ToF-AMS operation  
204 and data analysis are reported in Schulz's paper (Schulz et al., 2018). The overall accuracy has  
205 been reported as ~30 % for both AMS instruments (Alfarra et al., 2004; Middlebrook et al., 2012).  
206 Data presented in this section were converted to the same condition as the HALO AMS data, which  
207 is 995 hPa and 300 K.

208 The number concentration of cloud condensation nuclei (CCN) was measured aboard both  
209 aircraft using the same type of CCN counter from Droplet Measurement Technologies (DMT,  
210 model 200). This CCN counter contains two continuous-flow, thermal-gradient diffusion  
211 chambers for measuring aerosols that can be activated at constant supersaturation. The  
212 supersaturation is created by taking advantage of the different diffusion rates between water vapor



213 and heat. After the supersaturated water vapor condenses on the CCN in the sample air, droplets  
214 are formed, counted and sized by an Optical Particle Counter (OPC). The sampling frequency is  
215 one second for both deployed CCN counters. Both CCN counters were calibrated using ammonium  
216 sulfate aerosol particles in the diameter range of 20-200 nm. The uncertainty of the effective water  
217 vapor supersaturation was  $\pm 5\%$ . (Rose et al., 2008)

#### 218 2.1.4 Clouds

219 Aircraft-based measurements are an essential method for in situ sampling of cloud properties  
220 (Brenquier et al., 2013; Wendisch and Brenquier, 2013). Over the last 50–60 years, hot-wire probes  
221 have been the most commonly used devices to estimate liquid water content (LWC) in the cloud  
222 from research aircraft. Since the 1970s, the most widely used technique for cloud droplet spectra  
223 measurements has been developed based on the light-scattering effect. This type of instrument  
224 provides the cloud droplet size distribution as the primary measurement. By integrating the cloud  
225 droplet size distribution, additional information, such as LWC can be derived from the high-order  
226 data product.

227 Three cloud probes from the G1 were discussed in this manuscript. The Cloud Droplet Probe  
228 (CDP) is a compact, lightweight forward-scattering cloud particle spectrometer that measures  
229 cloud droplets in the 2 to 50  $\mu\text{m}$  size range (Faber et al., 2018). Using a state-of-the-art electro-  
230 optics and electronics, Stratton Park Engineering (SPEC Inc.) developed a Fast Cloud Droplet  
231 Probe (FCDP), which also use forward-scattering to determine cloud droplet distributions and  
232 concentrations in the same range as CDP with up to 100 Hz sampling rate. The G1 also carried a  
233 two-dimensional stereo probe (2DS, SPEC Inc.), which has two 128-photodiode linear arrays  
234 working independently and electronics produce shadowgraph images with 10  $\mu\text{m}$  pixel resolution.  
235 Two orthogonal laser beams cross in the middle of the sample volume, with the sample cross  
236 section for each optical path of 0.8  $\text{cm}^2$ . The manufacturer claims the maximum detection size is  
237 up to 3000  $\mu\text{m}$  for the 2DS. However, due to the counting statistic issue, the data used in this study  
238 is from 10–1000  $\mu\text{m}$  only (Lawson et al., 2006). 2DS was upgraded with modified probe tips, and  
239 an arrival time algorithm was applied to the 2DS data processing. Both efforts effectively reduced  
240 the number of small (shattered) particles (Lawson, 2011). For G1 cloud probes, the laboratory  
241 calibrations of the sample area and droplet sizing were performed before the field deployment.



242 During the deployment, biweekly calibrations with glass beads were performed with the size  
243 variation of less than 5%, which were consistent with the pre-campaign and after-campaign  
244 calibrations. Comparison between the LWC derived from cloud droplet spectra with hot-wire  
245 LWC measurement was made to estimate/eliminate the coincidence errors in cloud droplet  
246 concentration measurements (Lance et al., 2010; Wendisch et al., 1996)

247 On board of HALO, two cloud probes were operated and discussed in this manuscript, each  
248 consisting of a combination of two instruments: the Cloud Combination Probe (CCP) and a Cloud  
249 Aerosol Precipitation Spectrometer (CAPS, denoted as NIXE-CAPS; NIXE: Novel Ice  
250 Experiment). The CCP is a combination of a CDP (denoted as CCP-CDP) with a CIPgs (Cloud  
251 Imaging Probe with grey scale, DMT, denoted as CCP-CIPgs). NIXE-CAPS consists of a CAS-  
252 Dpol (Cloud and Aerosol Spectrometer, DMT, denoted as NIXE-CAS) and a CIPgs (denoted as  
253 NIXE-CIPgs). CIPgs is an optical array probe comparable to the 2DS operated on the G1. CIPgs  
254 obtains images of cloud elements using a 64-element photodiode array (15 $\mu\text{m}$  resolution) to  
255 generate two-dimensional images with nominal detection diameter size range from 15 to 960  $\mu\text{m}$   
256 (Klingebiel et al., 2015; Molleker et al., 2014). The CCP-CDP detects the forward-scattered laser  
257 light by cloud particles in size range of 2.5 to 46  $\mu\text{m}$ . The sample area of the CCP- CDP was  
258 determined to be  $0.27\pm 0.025 \text{ mm}^2$  with an uncertainty of less than 10% (Klingebiel et al., 2015).  
259 CAS-Dpol (or NIXE-CAS) is a light scattering probe comparable to the CDP but covers the size  
260 range of 0.6 to 50  $\mu\text{m}$  in diameter, thus including the upper size range of the aerosol particle size  
261 spectrum (Luebke et al., 2016). Furthermore, CAS-Dpol measures the polarization state of the  
262 particles (Costa et al., 2017). Correspondingly to the G1 CDP, the performance of the CCP-CDP  
263 and NIXE-CAS were frequently proven by glass beads calibrations. Prior to or after each HALO  
264 flight, CCP-CIPgs and NIXE-CIPgs calibrations were performed by using a mainly transparent  
265 spinning disc that carries opaque spots of different but known size. The data of the CCP measured  
266 particle concentration on board of HALO are corrected to gain ambient conditions using a  
267 thermodynamic approach developed by (Weigel et al., 2016). For NIXE-CAPS, the size  
268 distributions were provided where NIXE-CAS was merged with the NIXE-CIPgs at 20  $\mu\text{m}$ .

#### 269 2.1.5 Solar radiation

270 The G1 radiation suite included shortwave (SW, 400 - 2,700 nm) broadband total upward and  
271 downward irradiance measurements using Delta-T Devices model SPN-1 radiometers. The



272 radiation data were corrected for aircraft tilt from the horizontal reference plane. A methodology  
273 has been developed (Long; et al., 2010) for using measurements of total and diffuse shortwave  
274 irradiance and corresponding aircraft navigation data (latitude, longitude, pitch, roll, heading) to  
275 calculate and apply a correction for platform tilt to the broadband hemispheric downward SW  
276 measurements. Additionally, whatever angular offset there may be between the actual orientation  
277 of each radiometer's detector and what the navigation data say is level has also been determined  
278 for the most accurate tilt correction.

279 The Spectral Modular Airborne Radiation measurement system (SMART-Albedometer) was  
280 installed aboard HALO. Depending on the scientific objective and the configuration, the optical  
281 inlets determining the measured radiative quantities can be chosen. The SMART-Albedometer has  
282 been utilized to measure the spectral upward and downward irradiances; thereby it is called as an  
283 albedometer, as well as to measure the spectral upward radiance. The SMART-Albedometer is  
284 designed initially to cover measurements in the solar spectral range between 300 and 2,200 nm  
285 (Krisna et al., 2018; Wendisch et al., 2001; Wendisch et al., 2016). However, due to decreasing  
286 sensitivity of the spectrometers at large wavelengths, the use of the wavelengths was restricted to  
287 300 – 1,800 nm. The spectral resolution is defined by the full width at half maximum (FWHM),  
288 which is between 2 and 10 nm. In this case, the instruments were mounted on an active horizontal  
289 stabilization system for keeping the horizontal position of the optical inlets during aircraft  
290 movements (up to +/- 6 degrees from the horizontal plane).

## 291 2.2 Flight patterns

292 During the dry season IOP (September 1 – October 10, 2014), two types of coordinated flights  
293 were carried out: one flight in cloud-free condition (September 9) and two flights with clouds  
294 present (September 21 and October 1). In this study, we compare the measurements for both  
295 coordinated flight patterns. The discussion is mainly focused on the flights under cloud-free  
296 conditions on September 9 and the flight with clouds present on September 21, as shown in figure  
297 1. The other coordinated flight on October 1 is included in the supplemental document.

298 For the cloud-free coordinated flight, the G1 took off first and orbited around an area from the  
299 planned rendezvous point until HALO arrived in sight. It then coordinated with HALO and  
300 performed a wing-to-wing maneuver along straight legs around 500 m above sea level, as shown  
301 in Figure 2. The normal G1 average sampling speed is  $100 \text{ m s}^{-1}$ , and the normal HALO average



302 sampling speed is  $200 \text{ m s}^{-1}$ . During the coordinated flight on September 9, both aircraft also  
303 adjusted their normal sampling speed by about  $50 \text{ m s}^{-1}$  so that they could fly side by side.

304 For the second type of coordinated flights, the G1 and HALO flew the stacked pattern at their  
305 own normal airspeed. On September 21, the G1 also took off from the airport first, followed by  
306 HALO 15 minutes later. Then, both aircraft flew above the T3 ground site and subsequently flew  
307 several flight legs stacked at different altitudes. The two aircraft were vertically separated by about  
308 330 m and sampled below, inside, and above clouds. Due to the different aircraft speeds, the flight  
309 distance between two aircraft flight paths continued increasing from 15 min to 1 hour, as shown  
310 in Figure 3. On October 1, the G1 focused on the cloud microphysical properties and contrasting  
311 polluted versus clean clouds. HALO devoted the flight to the cloud vertical evolution and life cycle  
312 and also probed the cloud processing of aerosol particles and trace gases. The G1 and HALO  
313 coordinated two flight legs between 950–1250 m above the T3 site under cloud-free conditions.  
314 Following that, HALO flew to the south of Amazonia, and the G1 continued sampling plume-  
315 influenced clouds above the T3 site, and then flew above the Rio Negro area.

316 In this study, to perform a meaningful comparison of in situ measurements, all the data from  
317 instruments were time synchronized with the aircraft (G1 or HALO) navigation system. For AMS  
318 and CPC data, the time shifting due to tubing length and instrument flow had been corrected. For  
319 the coordinated flight on Sep. 9, the data compared was from the same type of measurements with  
320 the same sampling rate. For the measurements with the different sampling rate, the data were  
321 binned to the same time interval for comparison. For the flight with the cloud presents (Sep.21 and  
322 Oct. 1), the following criteria are used: 1) the data collected by the two aircraft must be less than  
323 30 mins apart from each other; 2) the comparison data was binned to 200 m altitude interval; and  
324 3) the cloud flag was applied to the aerosol measurements, and the data affected by the cloud  
325 shattering are eliminated from the comparisons of aerosol measurements. Moreover, additional  
326 comparison criteria are specified for individual measurements in the following section. Tables 2  
327 shows the total number of points used for the comparison.

### 328 **3. Results**

#### 329 **3.1 Comparison of the G1 and HALO measurements of atmospheric state parameters**

330 The atmospheric state parameters comprise primary variables observed by the research aircraft.  
331 The measurements provide essential meteorological information not only for understanding the



332 atmospheric conditions but also for providing the sampling conditions for other measurements,  
333 such as those of aerosol particles, trace gases, and cloud microphysical properties.

334 For cloud-free coordinated flights, the comparison focused on the near side-by-side flight leg  
335 at around 500 m, as shown in Figure 2. Table 3 shows the basic statistics of the data for primary  
336 atmospheric state parameters. In general, the atmospheric state parameters observed from both  
337 aircraft were in excellent agreement. The linear regression achieved a slope was near 1 for four  
338 individual measurements. The regression is evaluated using the below equation 1.

$$339 \quad R^2 = 1 - \frac{SS_{regression}}{SS_{Total}} \quad (1)$$

340 Where the sum squared regression error is calculated by  $SS_{regression} = \sum(y_i - y_{regression})^2$ ,  
341 and the sum squared total error is calculated by  $SS_{Total} = \sum(y_i - \bar{y})^2$ ,  $y_i$  is the individual data  
342 point,  $\bar{y}$  is the mean value, and  $y_{regression}$  is the regression value. When the majority of the data  
343 points are in a narrow value range, using the mean is better than the regression line and the  $R^2$  will  
344 be negative (Neg in Table 3).

345 The difference between the average ambient temperatures on the two aircraft was 0.5 K, and  
346 the difference between the average dew point temperatures was about 1 K. For temperature and  
347 humidity, the G1 data were slightly higher than the HALO data. The main contributions to the  
348 observed differences include the error propagation in the derivation of the ambient temperature  
349 from the measured temperature, instrumental-measurement uncertainty, and the temporal and  
350 spatial variability. The average horizontal wind speed measured by HALO is  $0.4 \text{ m s}^{-1}$  higher than  
351 the average horizontal wind speed measured by the G1. The uncertainty source of wind estimation  
352 is mainly due to the error propagation from the indicated aircraft speed measurement and the  
353 aircraft ground speed estimation from GPS. The static pressure distribution measured aboard  
354 HALO showed a smaller standard deviation (0.9 hPa) compared to the value of the G1 (1.5 hPa).  
355 The standard deviation (std) was also 0.6 hPa narrower. Part of the reason for this difference is a  
356 more substantial variation of the G1 altitude during level flight legs when G1 flew at around 50  
357 m/s higher than its normal airspeed. Thus, any biases caused by their near side-by-side airspeeds  
358 being different from their normal airspeeds would be undetected during these coordinated flights.

359 For the coordinated flights under cloudy conditions, we used the criteria from Section 2 to  
360 compare ambient conditions measured by the G1 and HALO aircraft. As shown in Figure 4, the  
361 linear regression slopes for ambient temperature, dew point temperature, and pressure were also



362 close to 1 between the G1 and HALO measurements during the September 21 coordinated flight.  
363 The  $R^2$  value is also close to 1. These results suggest that the G1 and HALO measurements  
364 achieved excellent agreements. The dew point temperature from the G1 measurement was  
365 erroneous between 2200–2700 m and above 3700 m (Figure 4(c)) because the G1 sensor was  
366 skewed by wetting in the cloud. The HALO dew point temperature was calculated from the total  
367 water mixing ratio measured by TDL, and that measurement in the cloud was more accurate than  
368 the measurement made by the chilled mirror hydrometer aboard the G1.

369 The lower value of the  $R^2$  value in horizontal wind speed means the ratio of the regression error  
370 and total error in wind measurement is much higher than the temperature and pressure  
371 measurements. The main contributions to this difference are the error propagation during the  
372 horizontal wind speed estimation and also the temporal and spatial variance between two aircraft  
373 sampling location. We observed differences between the two aircraft data of up to  $2 \text{ m s}^{-1}$ , caused  
374 by the increasing sampling distance as the two aircraft were climbing up. For example, the G1  
375 flew a level leg above T3 around 2500 m between 16:20-16:30, while HALO stayed around 2500  
376 m for a short period and kept climbing to a higher altitude. Due to strong vertical motion,  
377 turbulence, and different saturations (evaporation-condensation processes), the variances in the  
378 horizontal wind speed (Figure 4(d)) were also more significant compared to the variances of  
379 temperature and pressure measurements.

### 380 3.2 Comparison of trace gas measurements

381 For the cloud-free coordinated flight, ozone is the only trace gas measurement available on both  
382 aircraft. The linear regression slope shows that the HALO ozone concentration was about 8%  
383 higher than the G1 concentration. The difference between the averaged ozone concentrations was  
384 4.1 ppb. The primary source of bias is probably the different ozone loss in the sampling and transfer  
385 lines.

386

387 The comparison made on September 21 flight in Figure 5 shows good agreement for the  
388 vertically averaged ozone measurements. Comparing the statistics data from September 9, the  
389 ozone measurement is not sensitive to the temporal and spatial changes. The G1 CO measurement  
390 shows a low  $R^2$  value which is mainly from the systematic bias between the two instruments with  
391 different operation principles. The larger variance between 2000-3000 m in CO concentration



392 indicates the spatial variation contribution, while the G1 and HALO were sampling different air  
393 masses, as indicated in Figure S7.

### 394 3.3 Comparison of aerosol measurements

395 Aerosol particles exhibited strong spatial variations, both vertically and horizontally, due to  
396 complex atmospheric processing in the Amazon basin, especially with the local anthropogenic  
397 sources at Manaus. Thus, any spatially resolved measurement is critical to characterizing the  
398 properties of the Amazonian aerosols. The cloud-free coordinated flights provide us with suitable  
399 data to compare the G1 and HALO aerosol measurements and thus will enable further studies  
400 combined with the ground measurements. The vertical profiles obtained using the G1 and HALO  
401 platforms in different aerosol regimes in the Amazon basin have contributed to many studies (Fan  
402 et al., 2018; Martin et al., 2017; Wang et al., 2016).

403 When comparing the measurements from the two aircraft, the inlet system is a critical item,  
404 especially for sampling aerosol particles (Wendisch et al., 2004). Inlet design and characterization  
405 can actively modify the measured aerosol particle number concentration, size distribution, and  
406 chemical composition. The G1 aerosol inlet is a fully automated isokinetic inlet. Based on the  
407 manufacturer wind tunnel test and peer-reviewed publications, this inlet operates for aerosol up to  
408 5  $\mu\text{m}$ , with transmission efficiency around 50 % at 1.5  $\mu\text{m}$  (Dolgos and Martins, 2014; Kleinman  
409 et al., 2007; Zaveri et al., 2010). The HALO sub-micrometer Aerosol Inlet (HASI) was explicitly  
410 designed for HALO. Based on the numerical flow modeling, optical particle counter  
411 measurements, and field study evaluation, HASI has a cut-off size of 3  $\mu\text{m}$ , with transmission  
412 efficiency larger than 90 % at 1  $\mu\text{m}$  (Andreae et al., 2018; Minikin et al., 2017).

#### 413 3.3.1 Aerosol particle number concentration

414 For the cloud-free coordinated flight, the linear regression of CPC and UHSAS between the G1  
415 and HALO measurements are also included in Table 3. Also, the total number concentration of  
416 HALO CPC data was about 20 % lower than the total number concentration from the G1 CPC, as  
417 shown in Figure 6. The typical uncertainty between two CPCs is 5-10%. (Gunthe et al., 2009; Liu  
418 and Pui, 1974) Many factors can contribute to the rest 10-15% difference. Those include  
419 systematic uncertainties, such as systematic instrument drifts, different aerosol particle losses  
420 inside of the two CPCs, and different inlet transmission efficiencies in the two aircraft.



421 The CPC data in Figure 6 are color-coded with UTC time. The general trend is that the aerosol  
422 number concentration increased with aircraft sampling through the Manaus plume between 15:30-  
423 15:40. A similar trend was observed in aerosol particle number concentration (Figure 7) measured  
424 by the Ultra-High Sensitivity Aerosol Spectrometer (UHSAS)-Airborne version (referred to as  
425 UHSAS). The total number concentration data given by UHSAS (Figure 7) is integrated over the  
426 overlapping size range (90 – 500 nm for the September 9 flight) for both the G1 and HALO  
427 UHSAS. The linear regression shows that the total aerosol particle concentration from HALO  
428 UHSAS is about 16.5% higher than the total aerosol concentration from the G1 UHSAS. The  
429 discrepancy between the two UHSAS measurements is mainly due to the error propagation in the  
430 sampling flow, the differential pressure transducer reading, the instrument stability, and calibration  
431 repeatability, which is consistent with the other UHSAS study (Kupc et al., 2018). In the airborne  
432 version of UHSAS, mechanical vibrations have a more significant impact on the pressure  
433 transducer reading than the case for the bench version of UHSAS.

434 For the coordinated flight on September 21, the G1 and HALO data are averaged to a 200 m  
435 vertical altitude interval, as shown in Figure 8. There was a good agreement in the CPC  
436 comparison, especially at altitudes of 200 m and above (<10 % variance). However, the linear  
437 regression slope significantly decreased, which was primarily related to the temporal and spatial  
438 differences in aerosol number concentration. Especially between 2000 – 3000 m altitude, the  
439 difference between the G1 and HALO measurement is largely due to the different aerosol sources,  
440 as shown in Figure S6(a). The size range was integrated from 100–700 nm for UHSAS on  
441 September 21. The change of the size range was because the overlap of size distribution from both  
442 UHSAS instruments was changed. The linear regression slope and the  $R^2$  value slightly decreased  
443 in the UHSAS comparison as shown in Figure 8(b). And we can expect that the main contribution  
444 to the UHSAS measurement difference is from instrument systematic drift and the spatial/temporal  
445 variance of particle concentration in the ambient environment as shown in Figure S6(b). However,  
446 combining with the CPC measurement comparison, it indicates that the smaller size aerosol  
447 particles (< 100 nm) have a more profound variance due to the temporal and spatial change.

### 448 3.3.2 Aerosol particle size distribution

449 For the cloud-free coordinated flight, the averaged aerosol size distribution measured during  
450 one flight leg is compared in Figure 9. Based on the comparison plot, at the size range less than 90



451 nm, the G1 UHSAS overestimated the particle counts, which is due to the error in the counting  
452 efficiency correction. The UHSAS detection efficiency is close to 100% for particles larger than  
453 100 nm and concentrations below  $3000 \text{ cm}^{-3}$  but decreases both for smaller particles and for higher  
454 concentrations considerably (Cai et al., 2008). The aerosol counting efficiency correction  
455 determined from the lab condition does not represent the real correction during the flight operation.  
456 Between 90 nm and 250 nm, FIMS agreed well with the G1 UHSAS, whereas HALO UHSAS is  
457 about 30 % higher than the other two instruments. For the size range of 250–500 nm, FIMS had  
458 good agreement with HALO UHSAS, whereas FIMS is about 30-50 % higher than the G1 UHSAS  
459 depending on the particle size. Because the UHSAS has a simplified “passive” inlet, the large size  
460 aerosol particle loss in the UHSAS inlet was expected to increase with the increase of the aircraft  
461 speed. Thus, the lower G1 UHSAS counts at a larger aerosol particle size are likely related to the  
462 particle loss correction.

463 For the September 21 flight, the aerosol size distribution vertical profiles were averaged into  
464 100 m altitude intervals (Figure 10). Overall, all size distribution measurements captured the mode  
465 near 100 nm between 800–1000 m, which is at the top of the convective boundary layer, as  
466 indicated by the potential temperature (Figure 10(d)), which starts from a maximum near the  
467 ground and then becomes remarkably uniform across the convective boundary layer. With the  
468 increase in altitude, we observe the peak of the aerosol size distribution shifted from 100 nm to  
469 150 nm. Note that due to data availability, the aerosol size distribution data from the HALO  
470 UHSAS has a less spatial resolution.

### 471 3.3.3 A significant contribution of small aerosol particles

472 Comprehensive characterization of aerosol particles, especially small ones (<50 nm)  
473 during GoAmazon2014/5 has demonstrated that high concentrations of those small particles in the  
474 lower free troposphere are transported from the free troposphere into the boundary layer by a  
475 strong convective downdraft and sustain the population of particles in the pristine Amazon  
476 boundary layer. This important observation improved the current understanding of the aerosol  
477 influence on cloud properties and climate under natural conditions (Fan et al., 2018; Wang et al.,  
478 2016). However, the aerosol particle size distribution measurement, especially for sizes less than  
479 50 nm, is very rare due to the lack of high-frequency airborne measurements. The most common  
480 aerosol size spectrometer, UHSAS, covers aerosol particle sizes larger than 60 nm. The scanning



481 mobility particle spectrometer cannot obtain size distribution in 1 Hz time resolution. The other  
482 approach is to estimate particle size distribution by extrapolating the UHSAS or Passive Cavity  
483 Aerosol Spectrometer Probe (size range 100 – 3000 nm) measured aerosol size distribution to  
484 smaller size ranges (down to 10 nm). The accuracy of the third approach is limited by the nature  
485 of the aerosol size distribution, and the aerosol particle concentration can be significantly  
486 underestimated if there is a dominant nucleation mode in the aerosol particle size distribution, such  
487 as during a new particle formation event.

488 As shown in Figure 11, we compared the integrated aerosol number concentrations  
489 between one wet season flight (on March 7), which was influenced by a long-range transport plume  
490 from Africa (Moran-Zuloaga et al., 2018) and one typical dry season flight (September 21). The  
491 agreement of the small aerosol number concentration between the FIMS-measured size  
492 distribution and UHSAS/PCASP estimated size distribution is reasonably good for the dry season  
493 flight when the accumulation mode dominated the aerosol particle size distribution. During the  
494 wet season, there was a strong vertical gradient in the particle size spectrum above central  
495 Amazonia under clean conditions. Thus, we can observe an increase of underestimation of the  
496 small size particle concentration both for the size ranges less than 50 nm and less than 100 nm, as  
497 the filled markers move away from each other with the increase of altitude. Because of the  
498 negligible mass contribution to the total aerosol loading, those ultrafine aerosol particles (< 50 nm)  
499 are conventionally considered too small to affect cloud formation. However, the new observational  
500 evidence and numerical simulation of deep convective clouds outlined a new mechanism, which  
501 suggests an energetic anthropogenic invigoration of deep convective clouds by those ultrafine  
502 aerosol particles in previously pristine regions of the world (Fan et al., 2018). Two newly published  
503 studies (Fan et al., 2018; Wang et al., 2016) emphasize the importance of the airborne observation  
504 and suggest the ultrafine aerosol particles (<50 nm) measurement should be included as a baseline  
505 routine measurement in future airborne experiments.

506 For field studies without the deployment of FIMS, one option to assess the accuracy of  
507 UHSAS/PCASP estimated size distribution is to compare the total number concentration based on  
508 the integration of the UHSAS/PCASP estimated size distribution to the total number concentration  
509 from CPC. For field study focusing on the high concentration and variability of sub-50 or sub-100  
510 nm aerosol particles, such as new particle formation events, it is highly recommended to request



511 the deployment of FIMS. Due to the limited availability of FIMS, one option is to use several  
512 well-characterized CPCs, which operate at the different cut-off sizes, to measure the ambient  
513 aerosol simultaneously, and then use the data-inversion technique to estimate the aerosol size  
514 distribution of sub-50 or sub-100 nm aerosol particles. Another reasonable substitute to the FIMS  
515 might be a Scanning Mobile Particle Sizer (SMPS), but it should be noted that on an airborne  
516 platform an SMPS does not nearly have the same time resolution as a FIMS. To better adapt the  
517 spatial change in aerosol concentration, a residence chamber similar to a system described in  
518 another study (Kotchenruther and Hobbs, 1998) should be deployed with SMPS.

#### 519 3.3.4 Aerosol particle chemical composition

520 Figure 12(a) shows vertical profiles of the total mass concentrations measured by the two  
521 AMS instruments on September 21. Above 2500 m altitude, the agreement between the two  
522 instruments is excellent (mean difference less than 5%). Between 2000 and 2500 m, the agreement  
523 is within the uncertainty range. Below 2000 m altitude, however, the aerosol particle mass  
524 concentrations measured by the AMS operated on HALO are lower than the concentrations  
525 measured by the AMS on the G1. The aerosol volume concentrations from G1 AMS was converted  
526 from the mass concentration from AMS, by assuming the organic compound density was 1.5 g  
527 cm<sup>-3</sup> (Pöschl et al., 2010). The converted aerosol volume concentration agreed well with the  
528 volume concentration calculated based on UHSAS data below 2500 m, as shown in Figure 12(b).  
529 The agreement at lower altitudes suggests that the lower concentration in HALO AMS is due to  
530 the transmission efficiency issue in the constant pressure inlet used by HALO AMS. This inlet was  
531 a prototype, designed and built at MPIC Mainz, and works by changing the size of the critical  
532 orifice that regulates the flow into the aerodynamic lens. The design and transmission  
533 characteristics will be described in an upcoming publication (Molleker, S., in prep.). The AMS  
534 aboard the G-1 used a constant pressure inlet based on the design in Bahreini et al., 2008. Thus,  
535 we conclude that data above 2500 m altitude measured by the AMS aboard HALO in 2014 are  
536 valid, while data below 2500 m need to be corrected using correction factors derived from  
537 laboratory characterization before further study. After 2014, the HALO inlet design was improved  
538 to address the inlet transmission issues specific to this field campaign.

#### 539 3.3.5 CCN number concentration



540 These measurements provide valuable information about the aerosol's ability to form cloud  
541 droplets and modify the microphysical properties of clouds. Numerous laboratory and field studies  
542 have improved the current understanding of the connections between aerosol particle size,  
543 chemical composition, mixing states and CCN activation properties (Bhattu and Tripathi, 2015;  
544 Broekhuizen et al., 2006b; Chang et al., 2010; Duplissy et al., 2008; Lambe et al., 2011; Mei et al.,  
545 2013a; Mei et al., 2013b; Pöhlker et al., 2016; Thalman et al., 2017). In addition, based on the  
546 simplified chemical composition and internal mixing state assumption, various CCN closure  
547 studies have achieved success within  $\pm 20\%$  uncertainty for ambient aerosols (Broekhuizen et al.,  
548 2006a; Mei et al., 2013b; Rissler et al., 2004; Wang et al., 2008).

549 According to earlier studies (Gunthe et al., 2009; Pöhlker et al., 2016; Roberts et al., 2001;  
550 Roberts et al., 2002; Thalman et al., 2017), the hygroscopicity ( $\kappa_{\text{CCN}}$ ) of CCN in the Amazon basin  
551 is usually dominated by organic components ( $\kappa_{\text{Org}}$ ). Long-term ground-based measurements at the  
552 Amazon Tall Tower Observatory also suggested that there were low temporal variability and no  
553 pronounced diurnal cycles in hygroscopicity only under natural rainforest background conditions  
554 (Pöhlker et al., 2018; Pöhlker et al., 2016).

555 Using FIMS and CCN data from both the G1 and HALO collected during the coordinated flight  
556 leg on September 9, the critical dry diameter ( $D_{50}$ ) was determined by integrating FIMS size  
557 distribution to match the CCN total number concentration. Then,  $D_{50}$  was combined with the CCN-  
558 operated supersaturation to derive the effective particle hygroscopicity by applying the k-Köhler  
559 theory. The histogram plots based on the density of the estimated hygroscopicity ( $\kappa_{\text{est}}$ ) from both  
560 aircraft were compared for the flight leg above T3. For the G1 and HALO data, the  $\kappa_{\text{est}}$  value  
561 derived from the flight leg above the T3 site is  $0.186 \pm 0.067$  and  $0.189 \pm 0.083$  separately. That  
562 value is also slightly higher than the overall mean kappa derived from long-term measurements  
563 from the Amazon Tall Tower Observatory, which is  $0.17 \pm 0.06$  (Pöhlker et al., 2016; Thalman et  
564 al., 2017).

565 An example of a comparison of vertical profiles of the CCN concentration at 0.5%  
566 supersaturation on September 21 is shown in Figure 13. The difference between CCN  
567 measurements on the two aircraft is about 20% on average. However, the linear regression slope  
568 increases to 0.9120 if we focused on the data above 2500 m. The main contributions to the



569 difference include the difference in aerosol inlet structure, aerosol particle loss correction in the  
570 main aircraft inlet and the constant pressure inlet, the systematic inlet difference below 2500 m as  
571 shown in AMS data, and the error propagation of CCN measurements.

### 572 3.4 Comparison of cloud measurements

573 In situ cloud measurements help to capture the diversity of different cloud forms and their  
574 natural temporal and spatial variability. The G1 CDP and FCDP were deployed under the different  
575 wing pylons, and also on the different side of the aircraft. The G1 2DS was deployed on the same  
576 side of FCDP. The HALO cloud combination probe (CCP-CDP and CCP-CIPgs) and NIXE-CAPS  
577 (NIXE-CAS and NIXE-CIPgs) were deployed under the different wing pylons but on the same  
578 side of the aircraft. On September 21, 2014, based on the aircraft location and elevation  
579 information as shown in Figure 1(b) and Figure 3, two aircraft were sampling above T3 site and  
580 passing through the same cloud field at ~1600 m flight leg and ~1900 m flight leg as shown in  
581 Figure S8 and Figure S9. We used the cloud probes data from ~1900 m flight leg for the cloud  
582 droplet number concentration comparison. Two size ranges were considered: 3-20  $\mu\text{m}$  from light  
583 scattering probes (CDP vs. FCDP on the G1, CCP-CDP vs. NIXE-CAS on HALO) and 2-960  $\mu\text{m}$   
584 from combined cloud probes.

#### 585 3.4.1 Comparison of cloud droplet number concentration between 3-20 $\mu\text{m}$

586 The primary cloud layer was observed by both the G1 and HALO between 1000-2500 m above  
587 ground. Although the two aircraft have sampled along the same flight path, the instruments  
588 probably observed different sets of the cloud due to cloud movement with the prevailing wind or  
589 different cloud evolution stages. Thus, an initial comparison focuses on the redundant instruments  
590 on the same aircraft, that measured truly collocated and synchronous on board of HALO and of  
591 the G1, respectively. In Figure 14 (a), the data of the CCP-CDP and of the NIXE-CAS are  
592 juxtaposed sampled over about 13 minutes for particles detection size ranges which were  
593 considered as most equivalent. The comparison reveals two ranges of particle number  
594 concentrations at which densification of agreeing measurements become visible. At very low  
595 number concentrations (about  $10^{-1} - 10$  per  $\text{cm}^3$ ) the presence of inactivated (interstitial) aerosols  
596 in the clear air space between the very few cloud elements should be considered. Over specific  
597 ranges, however, the fine structure of varying cloud droplet number concentration may cause the



598 regression's scattering, indicated by cloud particle measured by one instrument whilst respective  
599 antagonist seems to measure within almost clear air – and vice versa. At higher number  
600 concentrations, i.e., between  $10^2$  and  $10^3$  per  $\text{cm}^3$ , the comparison of the highly resolved data  
601 constitutes increasing compactness with respect to the 1:1 line. The overall data scatter of this  
602 comparison, however, may indicate the highly variable structure within clouds as those  
603 investigated over the Amazon basin. The data of the G1 CDP and the FCDP are juxtaposed as the  
604 same as HALO cloud probes. However, the sampled cloud period was much shorter – about 3  
605 minutes. Similar as the HALO cloud probes comparison, we observe two ranges of particle number  
606 concentrations at which a densification of agreeing measurements become visible, especially for  
607 the lower number concentrations, in Figure 14(b). At higher number concentrations, only a few  
608 cloud elements were observed by the G1 cloud probes. That is because the G1 was about 7-23  
609 minutes later to pass the same location as HALO, and experienced much fewer cloud elements.

#### 610 3.4.2 Comparison of cloud droplet size distribution between 2-960 $\mu\text{m}$ from both aircraft

611 Comparing the cloud probes from the G1 and HALO, although it seems that the size  
612 distributions never match better than for the cloud particle diameter size range below 10  $\mu\text{m}$ , the  
613 size distributions from two aircraft are in remarkably good agreement, considering the instance  
614 that the cloud detection on board the G1 occurred 7-23 minutes after the cloud probing on board  
615 of HALO, as shown in Figure 15. On HALO, the CCP and NIXE-CAPS probes agreed very well  
616 between 2-960  $\mu\text{m}$  and both peaked around 10  $\mu\text{m}$ . On the G1, although CDP and FCDP has a  
617 more significant difference in the size range less than 8  $\mu\text{m}$ , both of them showed the peak of the  
618 size distribution was around 15  $\mu\text{m}$ . The difference between the G1 CDP and FCDP may be due  
619 to the data post-processing. Additional coincidence correction and shattering correction were  
620 applied to FCDP, but not to CDP. For cloud elements larger than 10  $\mu\text{m}$ , the difference between  
621 the obtained cloud particle size distributions from two aircraft becomes substantial (up to two  
622 orders of magnitude) which may be indicative for observations of two different stages within the  
623 progressing development of a precipitation cloud which is particularly expressed in elevated  
624 number concentrations of larger cloud elements observed during the G1 measurement that  
625 happened later. We also observed that the general cloud characteristic is similar at different altitude  
626 levels as shown in Figure S10. The first two of three averaged periods were chosen during the  
627 flight leg of  $\sim 1600$  m and the last average period is for the flight leg  $\sim 1900$  m compared in Figure



628 15. Due to the averaging, the fine in-cloud structure gets suppressed. The small scale variabilities  
629 inside a cloud which are illustrated by the scattering of the highly resolved measurement data from  
630 the instrument comparison (cf. Figure 14) and the temporal evolution of in-cloud microphysics are  
631 not ascertainable and furthermore are beyond the scope of this study.

### 632 3.5 Comparison of radiation measurements

633 In this study, the downward irradiance measured by the SPN-1 unshaded center detector  
634 was compared with the integrated downward irradiance from the SMART-Albedometer between  
635 300–1,800 nm wavelengths in Figure 16. Only measurements from flight legs, where the G1 and  
636 HALO flew near side-by-side and at the same altitude were taken into consideration for analysis.  
637 In Figure 16, the top panel shows the time series of SPN-1 measurements, and the bottom panel  
638 shows the time series of SMART-Albedometer measurements. The black dots represented all data,  
639 and the blue circles identified data when the navigation condition was within  $\pm 1$  degree from the  
640 horizontal level. The large scatter in the data between 15:12–15:28 and 15:35–15:40 is mainly due  
641 to the different sensor trajectories during the maneuvering of the aircraft to get to the coordinated  
642 flight position. Because of the difference of each aircraft position from horizontal, the measured  
643 signal varied from the signal of the direct component of sunlight. Each sensor might look at  
644 different directions of the sky or different parts of the clouds. In addition, both aircraft flew under  
645 scattered clouds, and this uneven sunlight blocking is another contribution to the “drop-off”  
646 behavior in the time series plots of the downward irradiance.

647 Comparing the G1 and HALO measurements between 15:15–15:55 using the restricted  
648 navigation criteria in Figure 17, we observed that the G1 SPN1 irradiance is slightly higher than  
649 the integrated irradiance from the SMART-Albedometer. However, the difference in the averaged  
650 irradiance is less than 10 %. That result could be due to the difference in radiometer spectral ranges:  
651 400–2700 nm (SPN1 radiometer) vs. 300–1800 nm (SMART).

## 652 4 Uncertainty assessment

653 As mentioned in the introduction, a low-flying G1 and a high-flying HALO cover the sampling  
654 area from the atmospheric boundary layer, low clouds to the free troposphere, and the sampling  
655 period from the dry and wet seasons (Martin et al., 2016a). This spatial coverage provides the user  
656 community with abundant atmospheric-related data sets for their further studies, such as for remote



657 sensing validation and modeling evaluation. However, one critical step to bridge the proper usage  
658 of the observation with further atmospheric science study is to understand the measurement  
659 uncertainty in this data set, especially the variation between the coexisting measurements due to  
660 the temporal and spatial difference.

661 For the major measurements during this field study, three primary sources contribute to the  
662 measurement variation between the two aircraft: the temporal and spatial variations, the difference  
663 in the inlet characterization, and the limitation of the instrument capability. The difference in the  
664 inlet characterization and the instrument error are the same between the coordinated flights on  
665 September 9 and September 21. Thus, we can examine the sensitivity of each measurement to the  
666 spatial variation by comparing two flights. For the majority of the comparisons of the September  
667 21 flight, there are no significant spatial and temporal variation between two aircraft  
668 measurements. However, we noticed the comparison uncertainty is more significant between 2000  
669 – 3000 m altitude than the other altitudes in the aerosol and trace gas profile, especially for the  
670 aerosol particles smaller than 100 nm. This additional difference occurring between 2000-3000 m  
671 indicates the spatial variation contribution, while the G1 and HALO were sampling different air  
672 masses. The G1 had one flight leg around 2500 m above T3 site, while HALO continued climbing  
673 through 2000-3000 m range to reach the next flight leg around 4500 m. Thus, for the G1  
674 measurements, the data show two modes in the histogram distribution. The large mode was  
675 typically from the data when the G1 passed through the pollution plume, and the small mode  
676 represented the background value. Because the flight path of HALO did not pass through the  
677 plume, their data shows only one mode in the histogram plots, as shown in S6 and S7 in the  
678 supplemental material.

679 For atmospheric meteorological variables, the overall uncertainty is relatively smaller (less  
680 than 1 %) comparing to the other airborne measurements. The main contribution for the three-  
681 dimensional wind measurement is more sensitive to the spatial variation than the ambient  
682 temperature and pressure due to the complex turbulence structure in the boundary layer (see Figure  
683 S5). The other measurement affected mainly by the spatial and temporal variation is the cloud  
684 measurements, which is consistent with a previous study (Andreae et al., 2004). The considerable  
685 variation in the comparison between 2-960  $\mu\text{m}$  indicates the evolution of cloud droplet size



686 distributions (DSDs) over time and space has a more significant influence on the large droplet size,  
687 and it serves as the major contributor for the DSDs comparison.

688 The inlet also significantly affects the aerosol and gas phase measurements. Inlet  
689 characterizations are inherently challenging. However, comparisons as shown here can be used to  
690 assess the performance of the inlets indirectly. In this study, reasonable agreement of the total  
691 number concentration of aerosol particles between two CPCs indicated the uncertainty caused by  
692 the main aerosol inlet difference is less than 15%. In addition to the main aerosol inlet, the particle  
693 losses caused by AMS aerosol constant pressure inlet also affects the AMS comparison below  
694 2500 m altitude. Based on a literature survey, this study, for the first time, compares the non-  
695 refractory particle mass concentration between two aircraft measurements. Although two AMS  
696 sampled different air masses during the majority of the campaign, the excellent agreement between  
697 the two measurements from the comparison flight linked the aerosol chemical composition from  
698 the wet to dry season and from the atmospheric boundary layer to the upper troposphere.

699 We also noticed that the CCN and UHSAS comparisons are associated with more substantial  
700 uncertainties because of the more complex instrument designs. The aerosol flow fluctuation, the  
701 CCN column temperature fluctuation, and the stabilization of the optical particle counter all  
702 contribute to the accurate estimation of the CCN concentration. In a similar sense, the aerosol flow  
703 fluctuation, the difference in the inlet efficiency at different platform speeds, the laser temperature  
704 fluctuation, and the signal-to-noise ratio at lower size range all contribute to the considerable  
705 uncertainty of the UHSAS concentration measurement. However, the CCN hygroscopicity  
706 estimation on the near side-by-side comparison on September 9, 2014, shows very encouraging  
707 agreement. Thus, the spatial variance and the instability of the CCN and UHSAS performance  
708 both led to the variance between two aircraft of up to 50% based on the comparison scenario on  
709 September 21, 2014. This remains the most significant variance we observed during these two  
710 aircraft measurement comparisons.

711 The summary of the major measurement uncertainty contributed by the spatial difference  
712 between the two aircraft is listed in Table 4.

713



## 714      **5 Summary**

715            In situ measurements made by well-characterized instruments installed on two research aircraft  
716 (the G1 and HALO) during the GoAmazon 2014/5 and ACRIDICON-CHUVA campaigns were  
717 compared. Overall, the analysis shows good agreement between the G1 and HALO measurements  
718 for a relatively broad range of atmospheric-related variables in a challenging strophic environment.  
719 Measured variables included atmospheric state parameters, aerosol particles, trace gases, clouds,  
720 and radiation properties. This study outlines the well-designed coordinated flights for achieving a  
721 meaningful comparison between two moving platforms. The high data quality was ensured by the  
722 most sophisticated instruments aboard two aircraft used the most advanced techniques, assisted  
723 with the best-calibrated/characterized procedures. The comparisons and the related uncertainty  
724 estimations quantify the current measurement limits, which provide the guidance to the modeler  
725 to realistically quantify the modeling input value and evaluate the variation between the  
726 measurement and the model output. The comparison also identified the measurement issues,  
727 outlined the associated reasonable measurement ranges, and evaluated the measurement  
728 sensitivities to the temporal and spatial variance.

729            The comparisons presented here were mainly from two coordinated flights. The flight on  
730 September 9 was classified as a cloud-free flight. During this flight, the G1 and HALO flew near  
731 side-by-side within a “polluted” leg, which was above the T3 site and across the downwind  
732 pollution plume from Manaus, and a “background” leg, which was outbound from Manaus to the  
733 west and could be influenced by the regional biomass burning events during the dry season. Both  
734 legs were at 500 m altitude and showed linear regression slopes of ambient temperature and  
735 pressure, horizontal wind speed and dew point temperature near to 1 between the G1 and HALO  
736 measurements. These comparisons provide a solid foundation for further evaluation of aerosol,  
737 trace gas, cloud, and radiation properties. The total aerosol concentration from CPC and UHSAS  
738 were compared for the 500 m flight leg above the T3 site. The UHSAS measurement had a better  
739 agreement than the CPC measurement. That is because of the minor difference in the inlet structure  
740 and instrument design between two UHSAS aboard the two aircraft. The average size distribution  
741 from both UHSAS and one FIMS in the G1 suggests that UHSAS had an over-counting issue at  
742 the size range between 60-90 nm, which was probably due to electrical noise and small signal-to-  
743 noise ratio in that size range. Good agreement in the aerosol size distribution measurement  
744 provides a “sanity” check for AMS measurements. A CCN closure study suggested that FIMS



745 provides valuable size coverage for better CCN number concentration estimation. Based on the  $\kappa$ -  
746 Köhler parameterization,  $\kappa_{\text{eff}}$  observed at 500 m above the T3 site is  $0.18 \pm 0.09$ , which is similar to  
747 the overall mean kappa from long-term ATTO measurements -  $0.17 \pm 0.06$  (Pöhlker et al., 2016).  
748 This similarity suggests that there is no significant spatial variability along the downwind transect,  
749 although the freshly emitted aerosol particles may have much less hygroscopicity. The difference  
750 in the ozone measurement comparison is about 4.1 ppb, which suggests that the bias due to the  
751 sampling line loss inside of the G1 gas inlet. The irradiance from the SPN1 unshaded center  
752 detector in the G1 was compared with the HALO integrated downward irradiance between 300–  
753 1800 nm and achieved a very encouraging agreement with a variance of less than 10%.

754 During the second type of the coordinated flights on September 21 (with cloudy conditions),  
755 HALO followed the G1 after take-off from Manus airport; then the two aircraft flew stacked legs  
756 relative to each other at different altitudes above the T3 site. For atmospheric state parameters,  
757 nearly linear correlations between the G1 and HALO were observed for ambient pressure,  
758 temperature, and dew point temperature measurements at an altitude range from ground to around  
759 5000 m. Cloud presence affected the measurements of dew point temperature in the G1, resulting  
760 in a large discrepancy in the dew point temperature measurement and the derived relative humidity  
761 between 2000–3000 m. The horizontal wind had more variation than the rest of the meteorological  
762 properties, which is mainly due to the temporal and spatial variability. The aerosol number  
763 concentration comparison had an excellent agreement (<15 %) for aerosol particles larger than 10  
764 nm counted by the CPC below 2500 m. While the integrated aerosol number concentration from  
765 UHSAS showed consistent discrepancy at different altitudes, that suggests the significant temporal  
766 and spatial variation of smaller aerosol particles (<100 nm). Although the aircraft-based UHSAS  
767 is a challenging instrument to operate, a reasonable size distribution profile comparison was made  
768 between both UHSAS and FIMS in the G1. The aerosol concentration measured by AMS  
769 instruments showed a mean difference less than 5% above 2500 m during the flight on September  
770 21, although due to the ongoing study, the correction factors allowing for correction of data below  
771 2500 m are not available yet. The difference between CCN number concentration measured on the  
772 two aircraft was on average 20%, and these data show the same altitude behavior as the AMS data.  
773 The main contributions to this difference include the difference in aerosol inlet structure, the  
774 aerosol loss correction in a constant pressure inlet, and the error propagation of CCN  
775 measurements. The ozone and CO vertical profile comparisons show a variation of less than 10%.



776 The ozone measurement variation is mainly from the systematic bias between two instruments  
777 with different operation principles, especially at altitudes higher than 4000 m.

778 Cloud probe comparisons were made for the cloud droplet number concentration between 3–  
779 20  $\mu\text{m}$  for the initial comparison between the redundant instruments on the same aircraft. Then the  
780 comparison of cloud droplet size distribution between 2–960  $\mu\text{m}$  for a flight leg around 1900 m  
781 showed a remarkably good agreement. The major cloud appearance was captured by both aircraft,  
782 although the cloud elements observed were affected by the cloud movement with the prevailing  
783 wind and the different cloud evolution stages. Furthermore, the relatively short time delay of 7–23  
784 minutes between the independent measurements may give a hint for the time scales in which the  
785 cloud droplet spectra develop within a convective cloud over the Amazon basin.

786 The above results provide additional information about the reasonableness of measurements  
787 for each atmospheric variable. This study confirms the high-quality spatial and temporal dataset  
788 with clearly identified uncertainty ranges had been collected from two aircraft and builds a good  
789 foundation for further studies on the remote sensing validation and the spatial and temporal  
790 evaluation of modeling representation of the atmospheric processing and evolution.

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1098 Table 1. List of compared measurements and corresponding instruments deployed aboard the G1  
 1099 and HALO during GoAmazon2014/5. The acronyms are defined in a table at the end of this  
 1100 paper.  $D_p$  indicates the particle diameter.  $\Delta D_p$  refers to the size resolution.

Measurement Variables	Instruments deployed on the G1 (Martin et al., 2016b; Schmid et al., 2014)	Instruments deployed on HALO (Wendisch et al., 2016)
Static Pressure	Rosemount (1201F1), 0-1400 hPa	Instrumented nose boom tray (DLR development), 0-1400 hPa
Static air temperature	Rosemount E102AL/510BF -50 to +50 °C	Total Air Temperature (TAT) inlet (Goodrich/Rosemount type 102) with an open wire resistance temperature sensor (PT100), -70 to +50 °C
Dewpoint temperature	Chilled mirror hygrometer 1011B -40 to +50 °C	Derived from the water-vapor mixing ratio, which is measured by a tunable diode laser (TDL) system (DLR development), 5-40000 ppmv
3-D wind	Aircraft Integrated Meteorological Measurement System 20 (AIMMS-20)	Instrumented nose boom tray (DLR development) with an air data probe (Goodrich/Rosemount) 858AJ and high-precision Inertial Reference System (IGI IMU-IIe)
Particle number concentration	CPC, cut off size ( $D_p$ ) =10 nm	CPC, cut off size ( $D_p$ ) =10 nm
Size distribution*	UHSAS-A, 60-1000 nm. FIMS, 20 nm – 500 nm	UHSAS-A, 60-1000 nm.
Non-Refractory particle chemical composition	HR-ToF-AMS: Organics, Sulfate, Nitrate, Ammonium, Chloride, 60-1000 nm	C-ToF-AMS: Organics, Sulfate, Nitrate, Ammonium, Chloride, 60-1000 nm
CCN concentration	CCN-200, SS= 0.25, 0.5%	CCN-200, SS= 0.13-0.53%
Gas phase concentration	N2O/CO and Ozone Analyzer, CO, O <sub>3</sub> concentration, precision 2 ppb	N2O/CO and Ozone Analyzer, CO, O <sub>3</sub> concentration, precision 2 ppb
Cloud properties*	CDP, 2-50 $\mu$ m, $\Delta D_p$ =1-2 $\mu$ m	CCP-CDP, 2.5-46 $\mu$ m, $\Delta D_p$ =1-2 $\mu$ m
	FCDP, 2-50 $\mu$ m, $\Delta D_p$ =1-2 $\mu$ m	NIXE-CAS: 0.61 -52.5 $\mu$ m
	2DS, 10-1000 $\mu$ m	NIXE-CIPgs, 15-960 $\mu$ m CCP-CIPgs: 15-960 $\mu$ m
Radiation	SPN1 downward irradiance, 400-2700 nm	SMART Albedometer, downward spectral irradiance, 300-2200 nm

1101 \*for an individual flight, the size range may vary.

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1104 Table 2. Summary of the total data points compared between the G1 and HALO instruments.

	SEP 9, 2014		SEP 21, 2014	
	G1	HALO	G1	HALO
<b>Atmospheric parameters</b>	2815	2815	7326	12065
<b>Gas phase, CO</b>	N/A	N/A	7326	12065
<b>Gas phase, Ozone</b>	2815	2815	7110	11766
<b>CPC</b>	2043	2043	8466	11646
<b>UHSAS (FIMS)</b>	2031	2031	5841 (9405)	828
<b>AMS</b>	N/A	N/A	587	818
<b>CCNc</b>	663	531	7982	4546
<b>G1: CDP(FCDP)</b>	N/A	N/A	3627(4439)	2051(2260)
<b>HALO: CCP-CDP (NIXE-CAS)</b>				
<b>G1: 2DS</b>	N/A	N/A	2280	2261 (2260)
<b>HALO: CCP-CIPgs (NIXE-CIPgs)</b>				
<b>RAD</b>	1355	1355	N/A	N/A

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Table 3. Summary of basic statistics of data between in situ measurements

*Comparison of the coordinated flight on Sep. 9*

Variables	G1				HALO				slope	R <sup>2</sup>
	min	max	mean	std	min	max	mean	std		
<i>T, K</i>	297.7	300.2	298.9	0.5	297.2	299.4	298.4	0.4	1.002	Neg.
<i>P, hPa</i>	955	965	960.1	1.5	958	964.9	961.8	0.9	0.998	Neg.
<i>WSpd, m/s</i>	0.3	8.9	3.4	1.2	0.3	7.7	3.8	1.1	0.998	Neg.
<i>T<sub>dew</sub>, k</i>	293	296.5	295.0	0.5	292.9	294.9	294.0	0.3	0.996	Neg.
<i>Ozone, ppb</i>	0.5	58.8	22.2	9.3	18.3	50.8	26.3	6.6	1.082	0.9401
<i>CPC, cm<sup>-3</sup></i>	696.0	3480.6	1591.3	568.7	687.4	2639.4	1313.8	473.5	0.819	0.8508
<i>UHSAS, cm<sup>-3</sup></i>	78.2	1118.	645.5	116.3	504.1	1622.2	756.3	138.6	1.165	0.8193
<i>CCNc (κ)</i>	0.010	0.347	0.1855	0.067	0.012	0.394	0.1890	0.083	0.8937	Neg.

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1111 Table 4. List of compared measurements ranges and measurement variances caused by the spatial  
 1112 variation during the field campaign.

Measurement Variables	Measured Range during the Field Campaign	Measurement Variances between the Two Aircraft
Static Pressure	500 – 1010 hPa	< 1 %
Static air temperature	272 – 310 K	< 1%
Dewpoint temperature	230 -300 K	Without clouds, <1% With clouds, the measurement from the G1 can be up to 5% lower than that of HALO
3-D wind	1-15 m/s	< 40%
Particle number concentration	500 – 15,000 cm <sup>-3</sup>	< 20% for CPC, <50% for UHSAS (size dependent)
Non-Refractory particle chemical composition	< 10 µg·m <sup>-3</sup>	< 10% above 2500 m Up to 50% below 2500 m
CCN concentration	SS=0.25%, 100 – 2000 cm <sup>-3</sup>	< 10% above 2500 m Up to 50% below 2500 m
Gas phase concentration	Ozone: 15-75 ppb CO: 50-200 ppb	Ozone: < 25% CO: < 15%
Cloud droplet number concentration	3- 20 µm	<50 %
Downward irradiance	200 -1500 W·m <sup>-2</sup>	< 10%

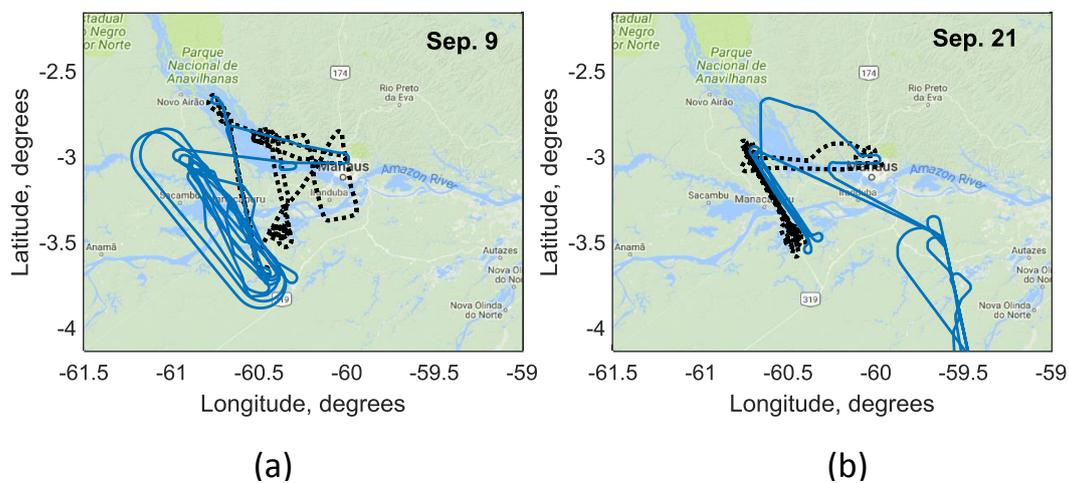
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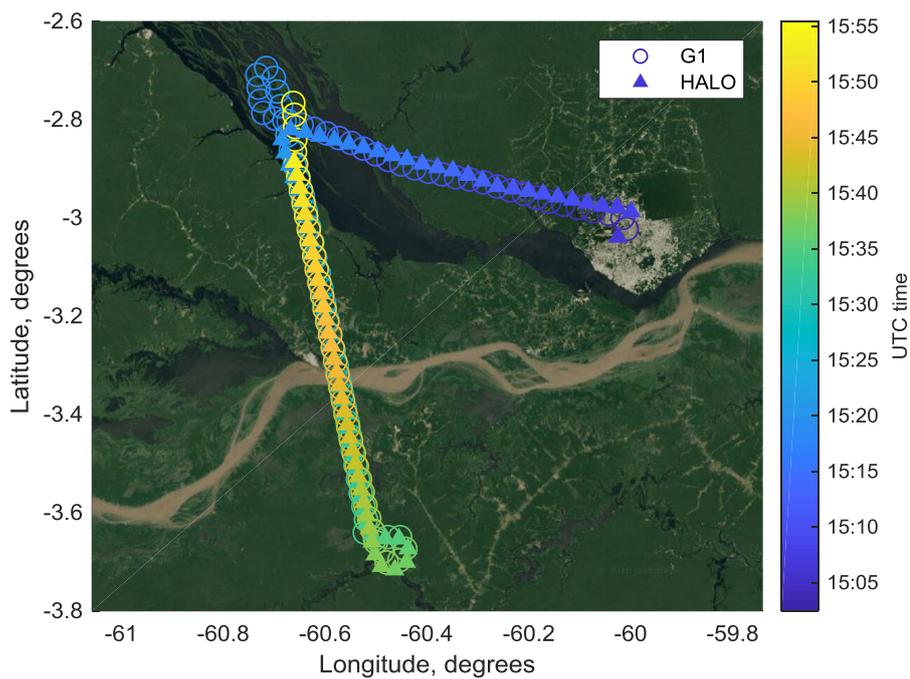
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1118 Figure 1. Coordinated flight tracks for September 9 (a) and September 21 (b). The black dotted  
1119 line is the flight track of the G1, and the blue line is the flight track of HALO.

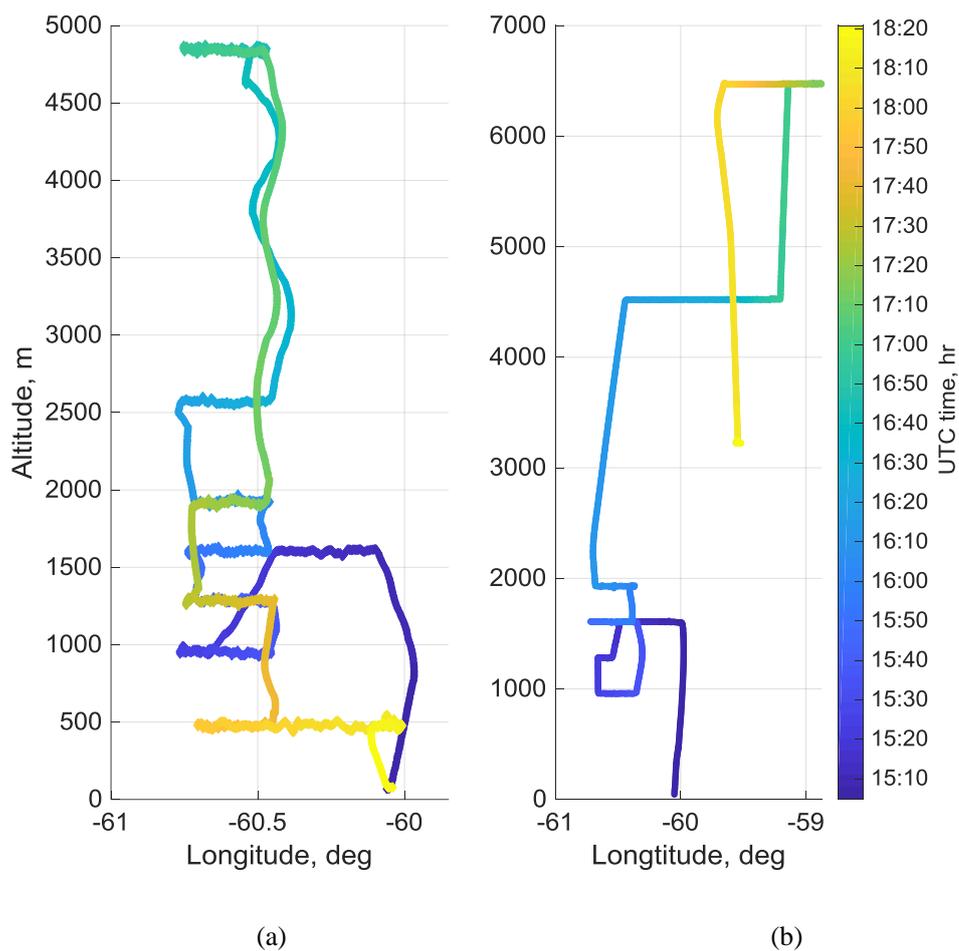
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1122 Figure 2. Time-colored flight track of the G1 (circle) and HALO (triangle) on September 9 during

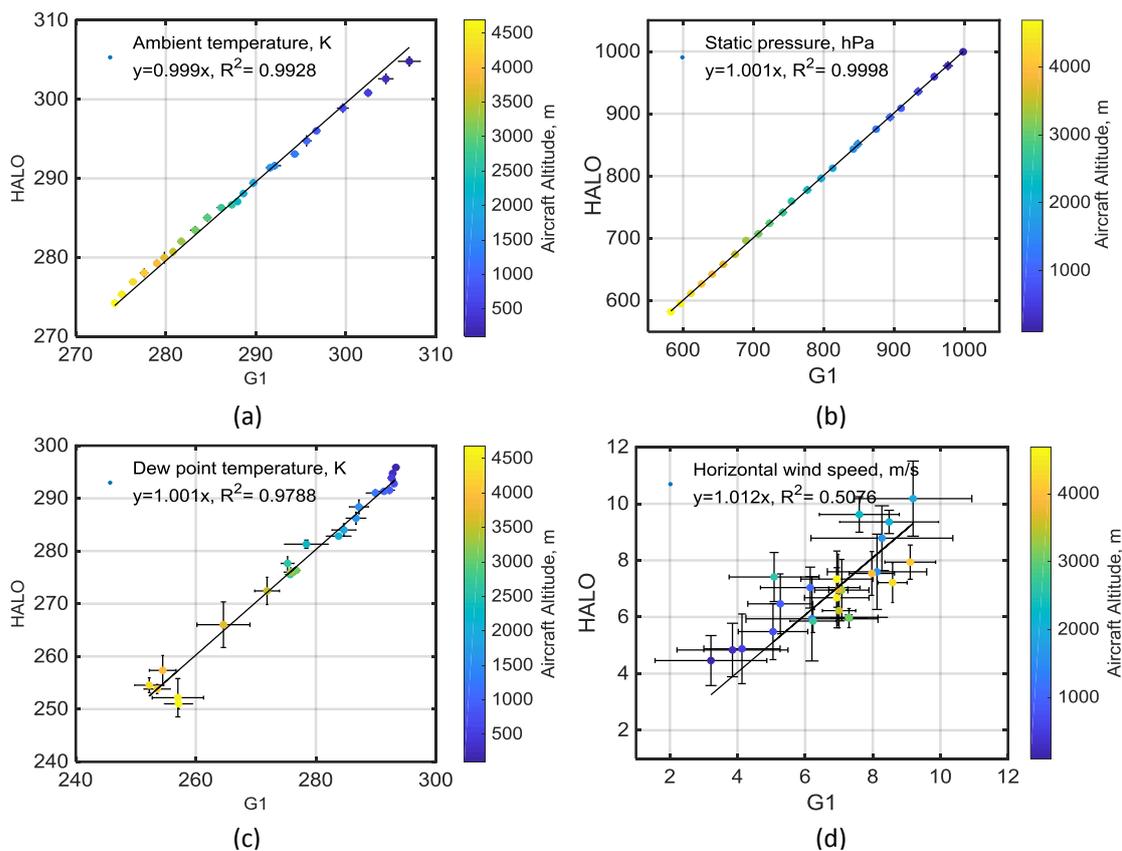
1123 a cloud-free coordinated flight at 500 m above sea level (50 m apart as the closest distance).



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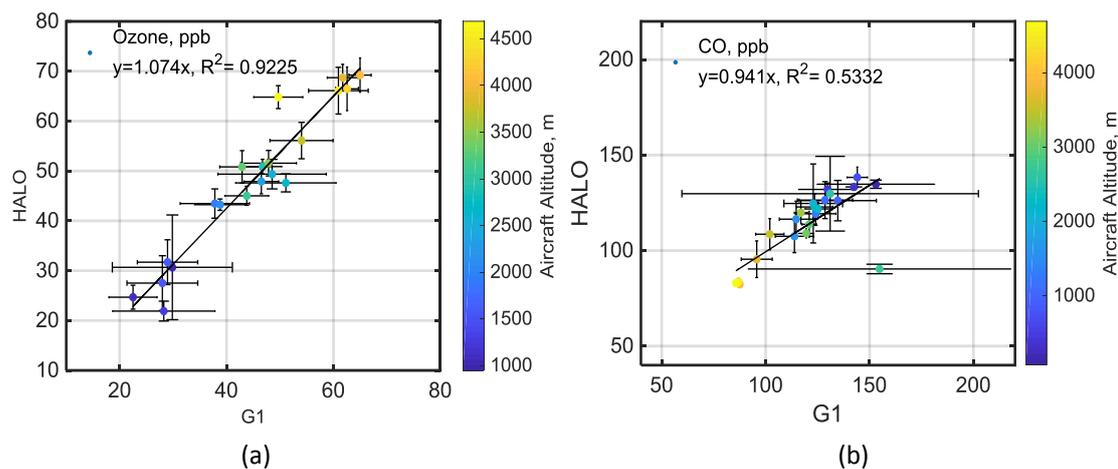
1126 Figure 3. Time-colored flight profile of the G1 (a) and HALO (b) on September 21, during a  
1127 coordinated flight.



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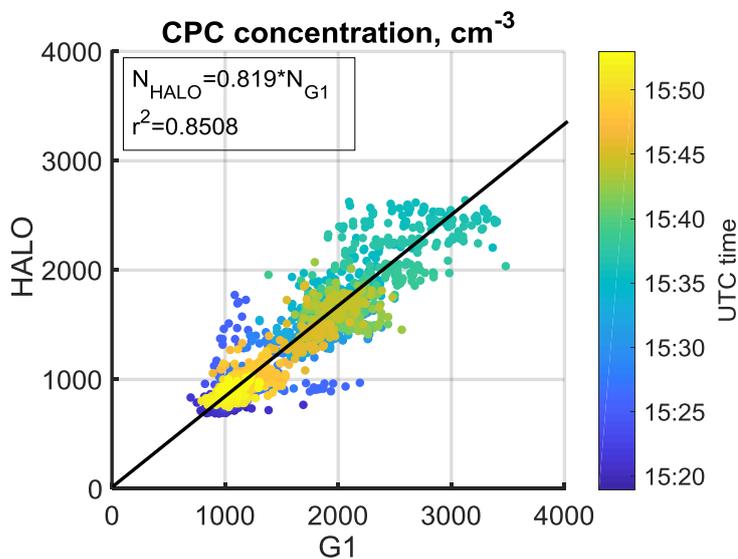
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1130 Figure 4. Aircraft altitude-colored plots of (a) ambient temperature, (b) static pressure, (c) dew  
1131 point temperature, and (d) horizontal wind speed observed by the G1 and HALO on September  
1132 21.



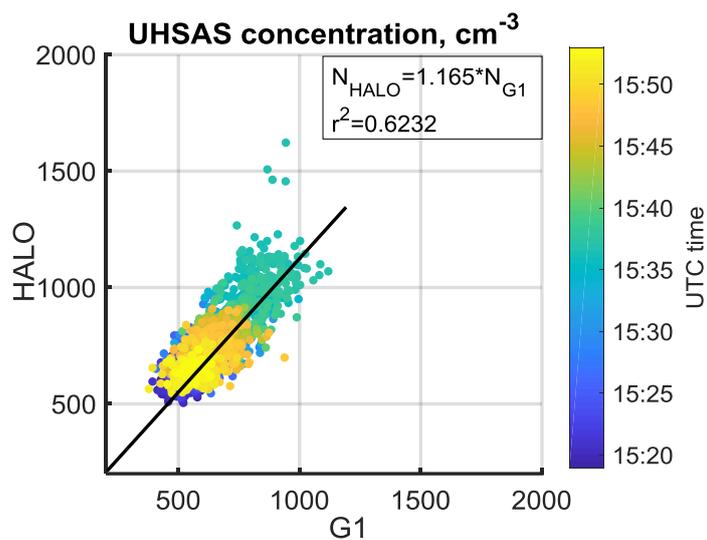
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1134 Figure 5. Aircraft altitude-colored plots of trace gas (a) Ozone, (b) CO, for the coordinated flight  
1135 on September 21.



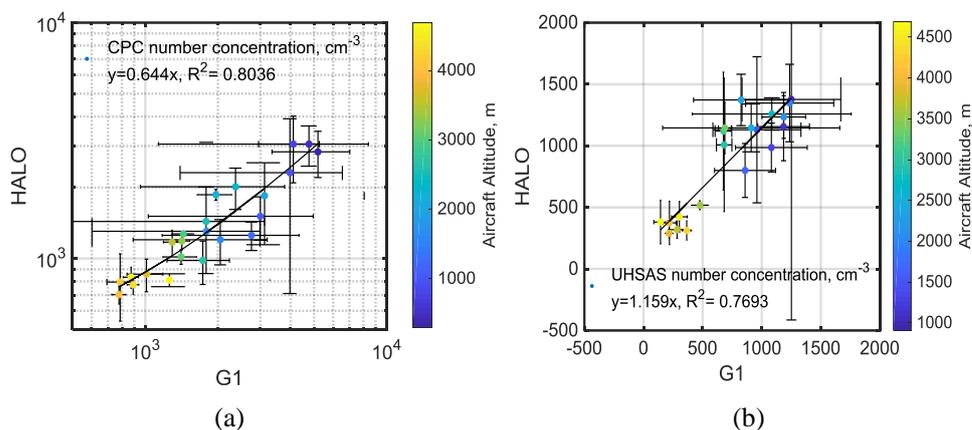
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1137 Figure 6. The G1 and HALO comparison for aerosol number concentration measured by CPC  
1138 (>10 nm) on September 9.



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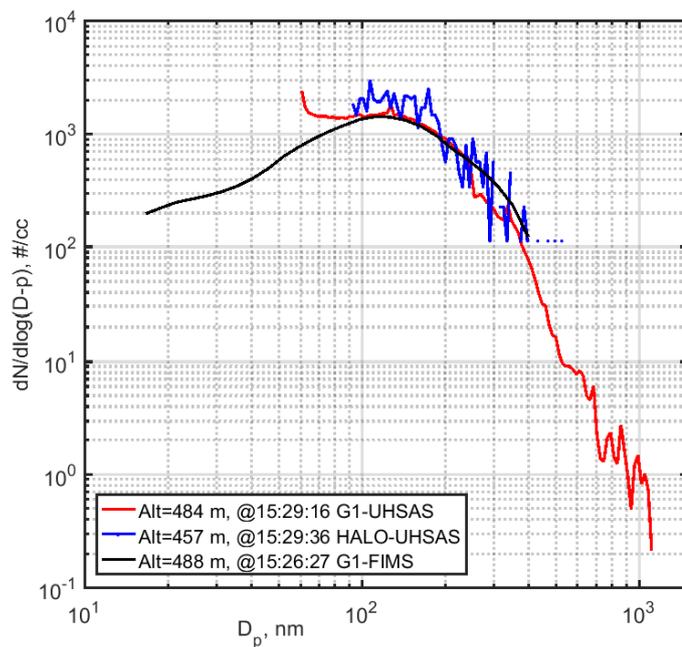
1140 Figure 7. The G1 and HALO comparison for aerosol number concentration measured by  
 1141 UHSAS (90-500 nm) on September 9.



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1144 Figure 8. The G1 and HALO comparison for aerosol number concentration profiling measured  
 1145 by (a) CPC and (b) UHSAS (100-700 nm) on September 21.



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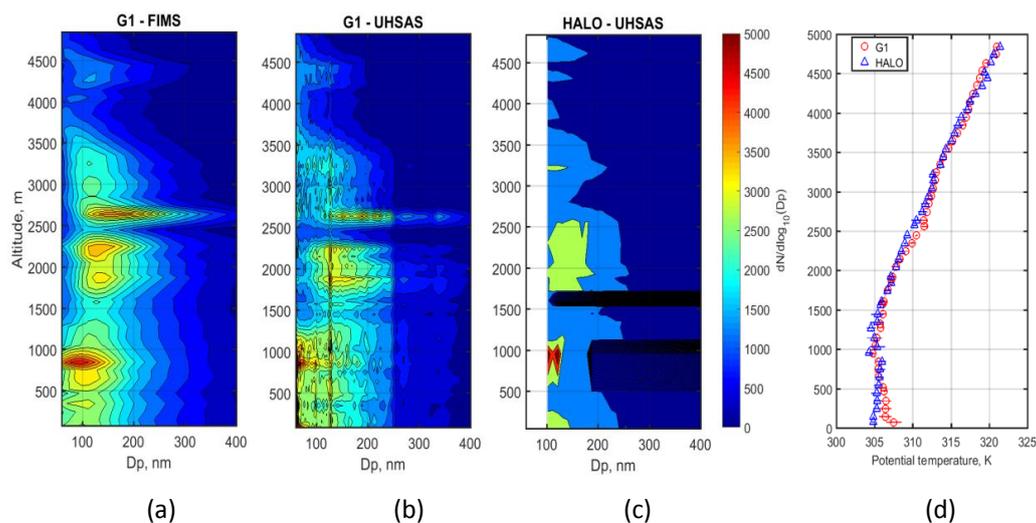
1147 Figure 9. The G1 and HALO comparison for aerosol size distribution measured by UHSAS

1148 (from both aircraft) and FIMS (on the G1) on September 9.

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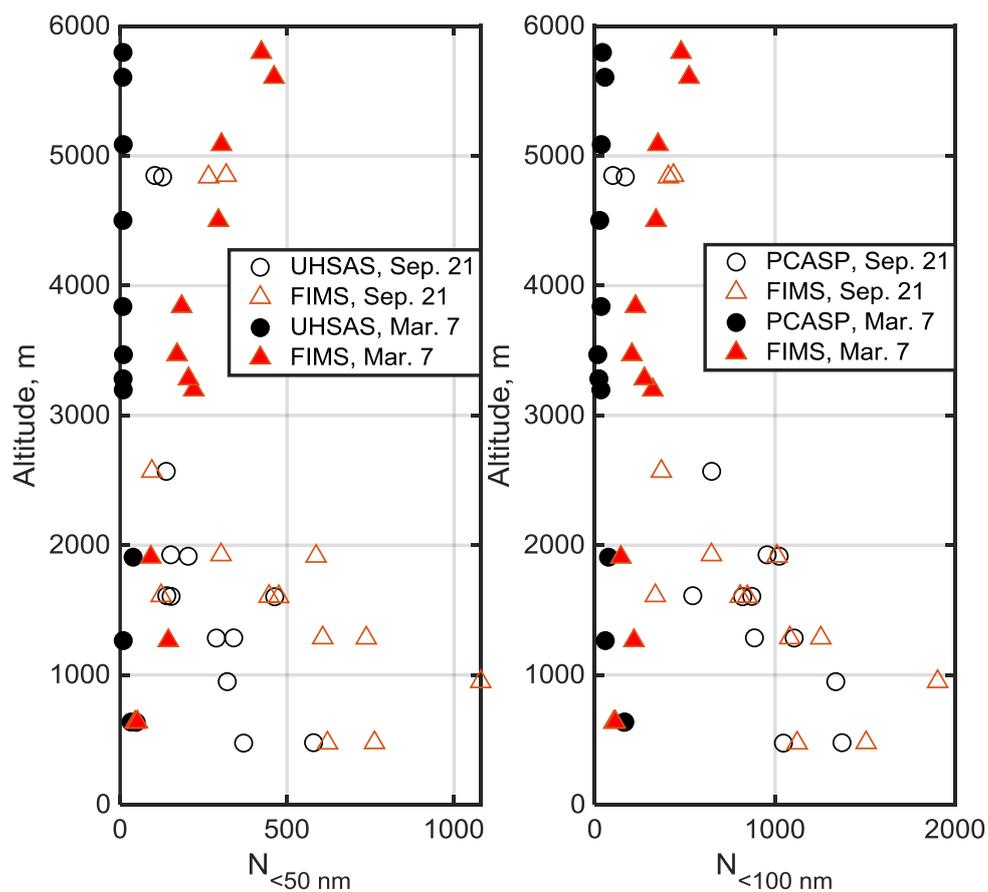


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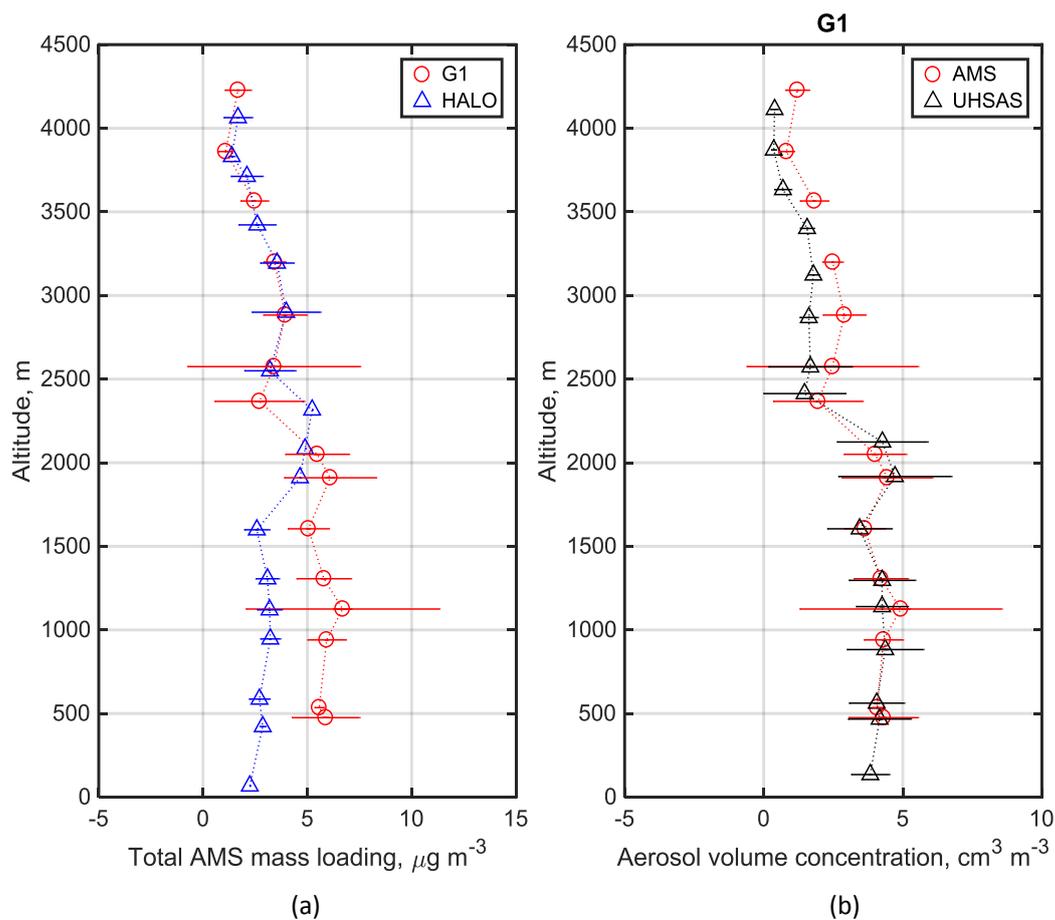
1152 Figure 10. Aerosol size distribution vertical profiles measured by (a) the G1 FIMS, (b) The G1  
1153 UHSAS, (c) the HALO UHSAS, (d) Potential temperature aboard the G1 and HALO on September  
1154 21.



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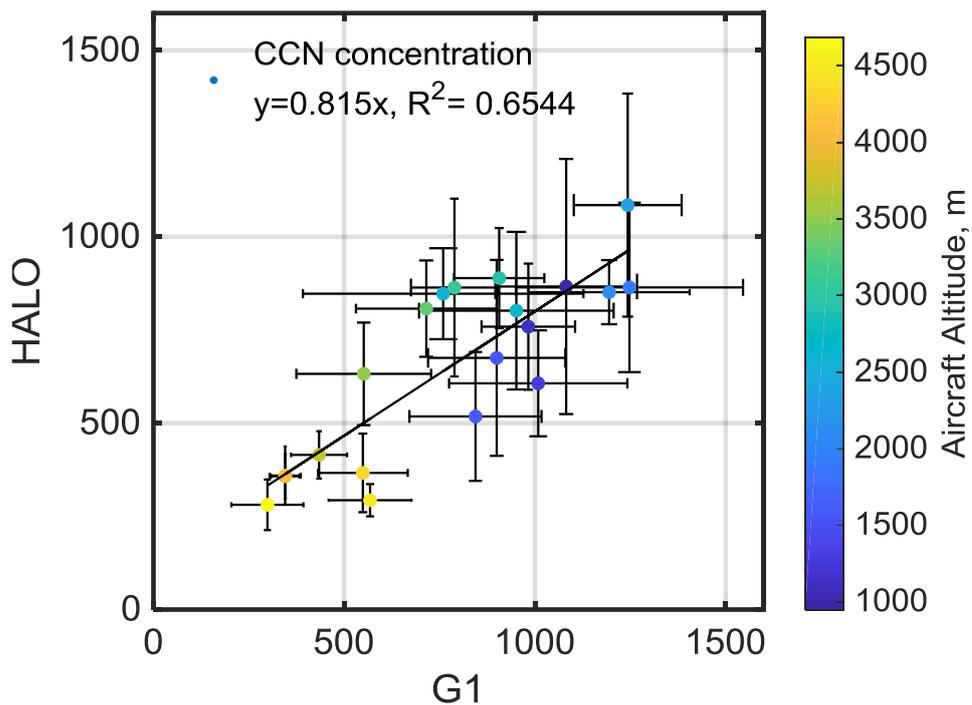
1157 Figure 11. Comparison of the number concentration for (a) sizes less than 50 nm and (b) sizes  
1158 less than 100 nm. FIMS-measured size distribution and UHSAS/PCASP estimated size  
1159 distribution are used.



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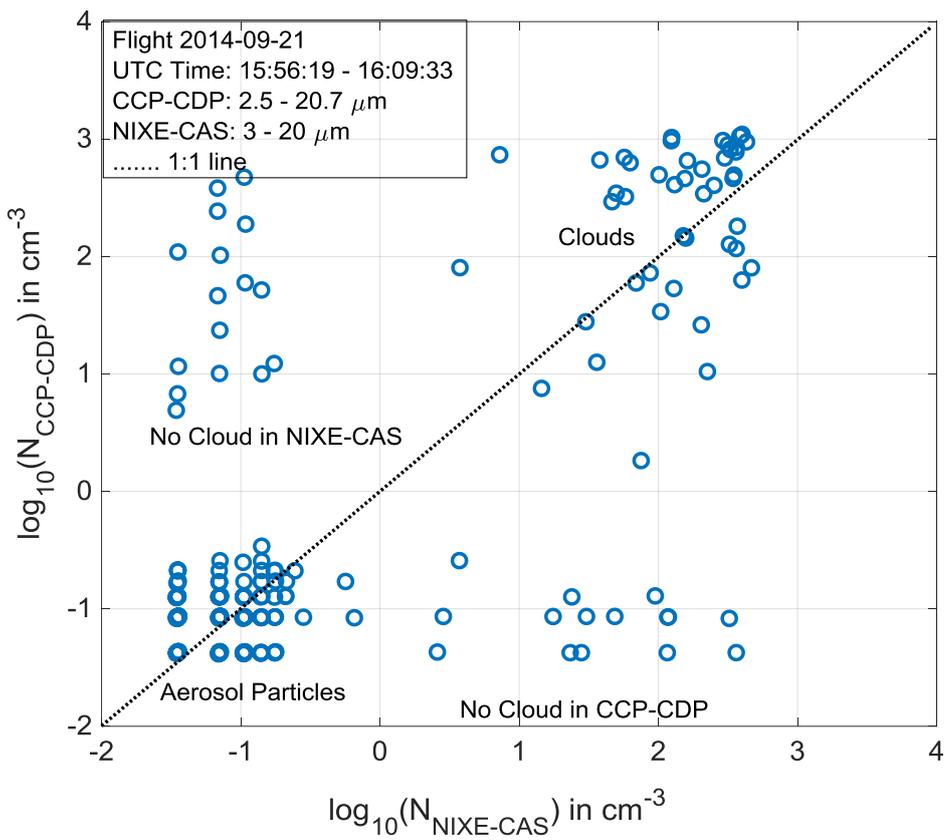
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1162 Figure 12. (a) Comparison of aerosol mass loading measured by the G1 and HALO AMS on  
1163 September 21; (b) aerosol volume concentration comparison from AMS and the integrated  
1164 UHSAS on the G1.



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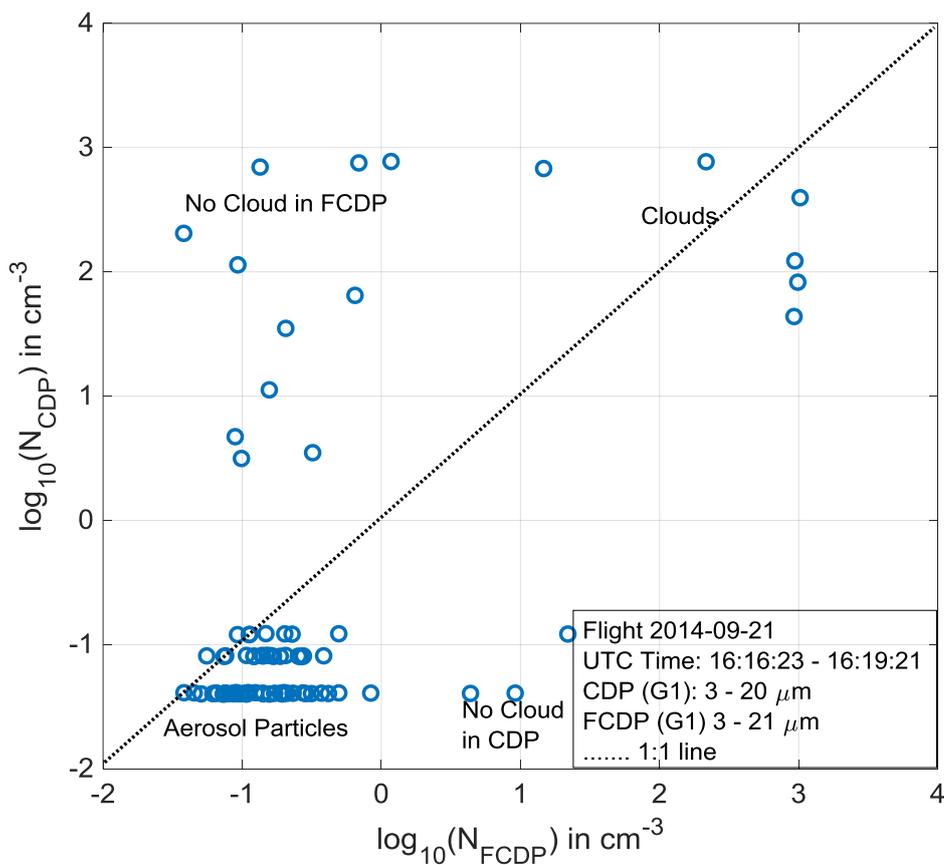
1166 Figure 13. The G1 and HALO comparison of aerosol CCN concentration ( $S=0.5\%$ ) measured  
1167 on September 21.



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(a)



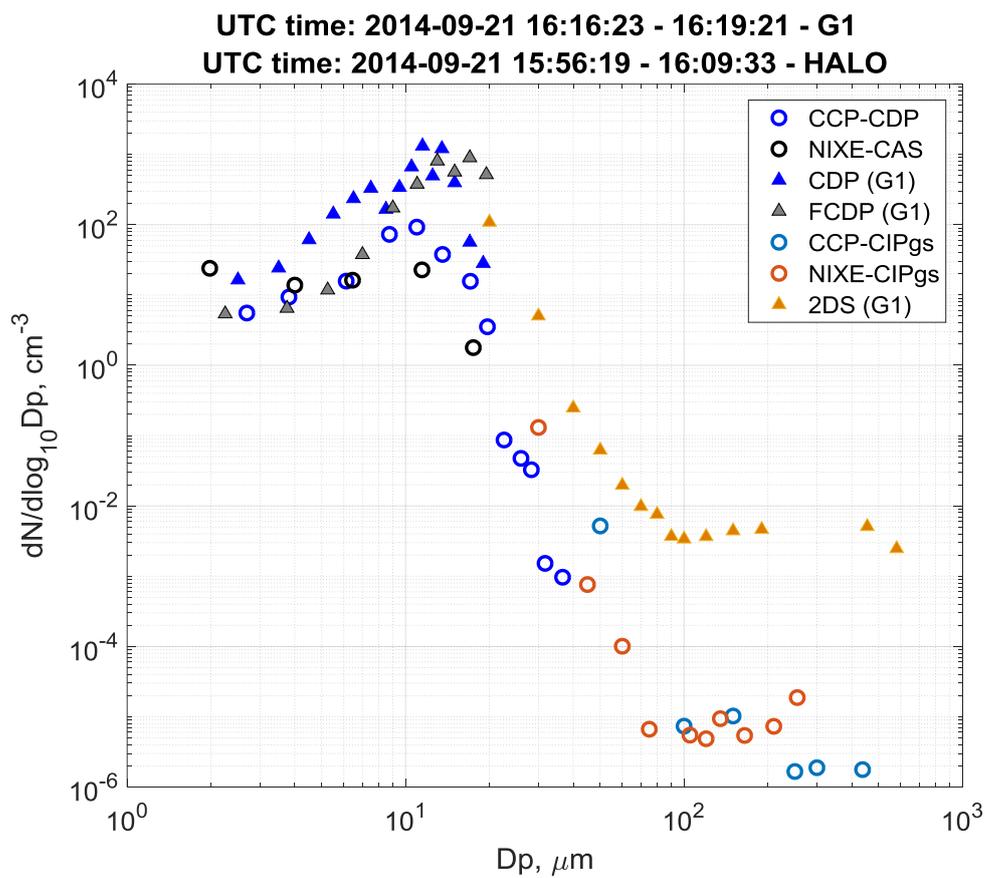
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(b)

1172 Figure 14 The comparison of cloud droplet concentrations in the same aircraft (a) between

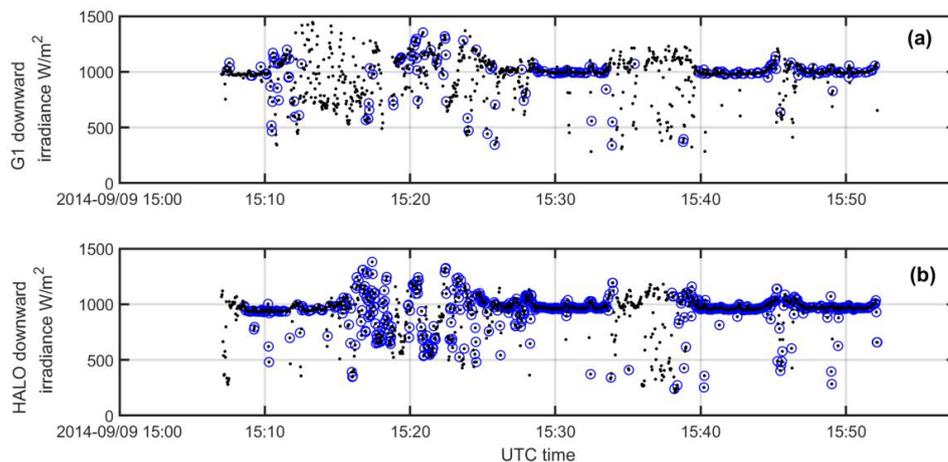
1173 NIXE-CAS and CCP-CDP on board HALO; (b) between CDP and FCDP on board the G1.



1174

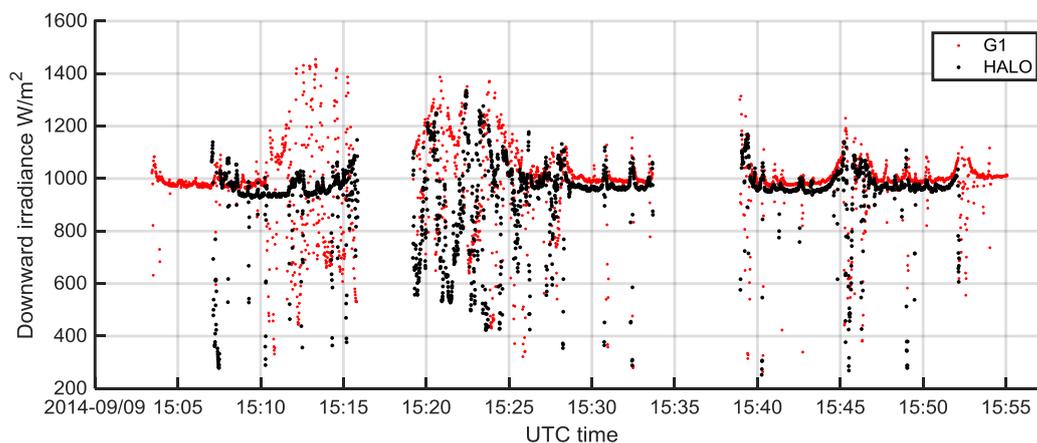
1175 Figure 15. The cloud droplet size distribution from the cloud probes on the G1 and HALO.

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1177

1178 Figure 16. Time series of the G1 and HALO downward irradiance on September 9. The (a)  
1179 by SPN-1 and (b) by SMART-Albedometer. Black dots represent all data under the general inter-  
1180 comparison criteria. The blue circles represent the restricted navigation criteria.



1181

1182 Figure 17. Time series comparison of the G1 (SPN-1) and HALO (SMART-Albedometer)  
1183 radiation measurements on September 9.

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