



1 **Potential of next-generation imaging spectrometers to detect and quantify** 2 **methane point sources from space**

3 Daniel H. Cusworth^{1,3}, Daniel J. Jacob¹, Daniel J. Varon¹, Christopher Chan Miller², Xiong Liu², Kelly Chance²,
4 Andrew K. Thorpe³, Riley M. Duren³, Charles E. Miller³, David R. Thompson³, Christian Frankenberg^{3,4}, Luis
5 Guanter⁵, and Cynthia A. Randles⁶

6 ¹School of Engineering and Applied Sciences, Harvard University, Cambridge, MA, USA

7 ²Atomic and Molecular Physics Division, Harvard Smithsonian Center for Astrophysics, Cambridge, MA, USA

8 ³Jet Propulsion Laboratory, California Institute of Technology, Pasadena, CA, USA

9 ⁴Division of Geology and Planetary Sciences, California Institute of Technology, Pasadena, CA, USA

10 ⁵Centro de Tecnologías Físicas, Universitat Politècnica de València, Camí de Vera s/n, 46022 València, Spain

11 ⁶ExxonMobil Research and Engineering Company, Annandale, NJ, USA

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13

14 **Abstract**

15 We examine the potential for global detection of methane plumes from individual point sources with the new
16 generation of spaceborne imaging spectrometers (EnMAP, PRISMA, EMIT, SBG) scheduled for launch in 2019-2025.
17 These instruments are designed to map the Earth's surface with a sampling distance as fine as $30 \times 30 \text{ m}^2$ but they have
18 spectral resolution of 7-10 nm in the 2200-2400 nm band that should also allow useful detection of atmospheric
19 methane. We simulate scenes viewed by EnMAP (10 nm spectral resolution, 180 signal-to-noise ratio) using the
20 EnMAP End-to-End Simulation Tool with superimposed methane plumes generated by large-eddy simulations. We
21 retrieve atmospheric methane and surface reflectivity for these scenes using the IMAP-DOAS optimal estimation
22 algorithm. We find an EnMAP precision of 4-13% for atmospheric methane depending on surface type, allowing
23 effective single-pass detection of 100+ kg h^{-1} methane point sources depending on surface brightness, surface
24 homogeneity, and wind speed. Successful retrievals over very heterogeneous surfaces such as an urban mosaic require
25 finer spectral resolution. We simulated the EnMAP capability with actual plume observations over oil/gas fields in
26 California from the airborne AVIRIS-NG sensor ($3 \times 3 \text{ m}^2$ pixel resolution, 5 nm spectral resolution, SNR 200-400).
27 We spectrally and spatially downsampled AVIRIS-NG images to match EnMAP instrument specifications and found
28 that we could successfully detect point sources of $\sim 100 \text{ kg h}^{-1}$ over bright surfaces. Estimated emission rates inferred
29 with a generic Integrated Mass Enhancement (IME) method agreed within a factor of 2 between EnMAP and AVIRIS-
30 NG. Better agreement may be achieved with a more customized IME method. Our results suggest that imaging



31 spectrometers in space could play a transformative role in the future for quantifying methane emissions from point
32 sources on a global scale.

33

34 **1 Introduction**

35 Methane is a powerful greenhouse gas, yet its sources are highly uncertain. Quantifying methane emissions
36 from different sources is critical for developing strategies to reduce atmospheric methane levels. Anthropogenic
37 emissions originate from a large number of point sources (coal mine vents, oil/gas facilities, livestock operations,
38 landfills, wastewater treatment plants) that are individually small, spatially clustered, often intermittent, and difficult to
39 quantify (Allen et al., 2013; Frankenberg et al., 2016). Here we investigate the unique potential of new-generation
40 satellite instruments designed to map the Earth's surface (imaging spectrometers) to also detect methane point sources
41 in the shortwave infrared (SWIR).

42 There has been considerable interest in using SWIR satellite observations of atmospheric methane columns by
43 solar backscatter to detect methane sources and test emission inventories (Jacob et al., 2016). These observations are
44 traditionally made by atmospheric sensors with high spectral resolution (<1 nm) to capture the fine structure of
45 methane absorption lines (Table 1). The requirement of high spectral resolution has generally implied a coarse pixel
46 resolution (>1 km) to achieve satisfactory signal-to-noise ratios (SNR), but this limits the ability to localize and
47 quantify individual point sources. Inverse analyses of observations from the SCIAMACHY instrument with 60 km
48 pixel resolution, and from the GOSAT instrument with sparse sampling at 10 km pixel resolution, have quantified
49 emissions over regional scales (Bergamaschi et al., 2009; Kort et al., 2014; Turner et al., 2015). The recently launched
50 TROPOMI instrument with global daily coverage at 7 km pixel resolution (Hu et al., 2018) will refine the regional
51 characterization but still cannot resolve point sources (Sheng et al., 2018). Planned instruments with ~ 1 km pixel
52 resolution (MethaneSat, Propp et al., 2017; Geo-FTS, Xi et al., 2016) should be able to detect large point sources after
53 inversion of several days of observations (Cusworth et al., 2018; Turner et al., 2018) but would not resolve densely
54 clustered or temporally variable sources.

55 Atmospheric sensors for methane generally focus on achieving high precision ($<1\%$) and low relative bias
56 ($<0.3\%$), appropriate for regional characterization of sources (Buchwitz et al., 2015). However, these requirements can
57 be relaxed if the focus is to observe individual plumes. Precision can be traded for pixel resolution because methane
58 plumes are generally sub-kilometer in scale (Frankenberg et al., 2016), so that plume enhancements are larger when the
59 pixel resolution is finer (Jacob et al., 2016). In a theoretical simulation study for the GHGSat microsatellite instrument



60 with 50×50 m² pixel resolution, Varon et al. (2018a) found that a 1-5% precision would be adequate for single-pass
61 observation of plumes to quantify point sources of magnitude ~100 kg h⁻¹. This would account for most of the total
62 methane emitted by point sources in the United States reporting to the Greenhouse Gases Reporting Program (Jacob et
63 al., 2016). A demonstration GHGSat instrument (GHGSat-D) launched in 2016 with an estimated precision of 13%
64 limited by instrument imperfections, has proven able to detect large point sources in excess of 1000 kg h⁻¹ (Varon et al.,
65 2018b).

66 Here we examine the potential of a different class of satellite instruments, imaging spectrometers, to provide
67 global snapshots of individual methane point sources. These instruments are designed for global coverage of land
68 surfaces, but they may be used for atmospheric sensing as well. They have fine spatial sampling, or pixel resolution
69 (<100 m), with coarser spectral sampling to measure vibrational overtone absorptions in surface reflectance. Some
70 current imagers such as Landsat (Roy et al., 2014) and WorldView-3 (<http://worldview3.digitalglobe.com>) have
71 observing bands in the SWIR intended to infer soil moisture, mineral composition, and vegetation traits (Cleemput et
72 al., 2018). However, the SWIR spectral resolutions for Landsat (100 nm) and WorldView-3 (40-50 nm) are too coarse
73 to usefully observe methane. The Hyperion instrument onboard NASA Earth Observing-1 had 10 nm spectral
74 resolution in the SWIR but a very low signal to noise ratio (SNR) of 20 (Folkman et al., 2001).

75 A new generation of imaging spectrometers set for launch over the next few years (EnMAP, PRISMA, EMIT,
76 and an anticipated SBG investigation) will achieve ~10 nm or better spectral resolution in the SWIR with pixel
77 resolution in the range 30-60 m and SNR of 180-400 or beyond (Table 1). Experience with airborne imaging
78 spectrometers of comparable specifications suggests that these satellite instruments should be able to usefully observe
79 methane plumes. The Airborne Visible/Infrared Imaging Spectrometer (AVIRIS-C), with a 10 nm spectral resolution
80 and SNR of 70 (Green et al., 1998), was able together with Hyperion to detect the massive Aliso Canyon methane leak
81 in California (Thompson et al., 2016). The next generation AVIRIS instrument (AVIRIS-NG), with a finer spectral
82 resolution of 5 nm and SNR of 200 (Thorpe et al., 2014), was able to detect a range of methane plumes over the Four
83 Corners region of New Mexico including from gas processing facilities, storage tanks, pipeline leaks, well pads, and
84 coal mine venting shafts (Frankenberg et al., 2016). AVIRIS-NG was flown over 272000 potential methane emitting
85 facilities in California between 2016 and 2018 (CARB, 2017).

86

87 **2 Imaging spectrometer spectra including methane plumes**



88 The next generation of spaceborne imaging spectrometers in Table 1 includes PRISMA (launched March
89 2019), EnMAP (2020), EMIT (2022), SBG (2025-2027). The AMPS instrument (proposed) would bridge the gap
90 between surface imagers and methane sensors, by providing 1 nm SWIR spectral resolution while maintaining 30 m
91 spatial resolution (Thorpe et al., 2016). We will focus our baseline analysis on EnMAP, for which detailed
92 documentation is available (Guanter et al., 2015), and examine other instruments through sensitivity analyses. EnMAP
93 is a push-broom style instrument with 10 nm resolution in the SWIR and an expected 180 SNR at 2300 nm. PRISMA
94 (<http://www.prisma-i.it/>) has very similar instrument specifications as EnMAP. The EMIT instrument will fly on the
95 International Space Station. It is slated to have a 7-10 nm spectral resolution and 60 m pixel resolution (Green et al.,
96 2018). Other investigations, such as SBG, are called for in the NASA Earth Science and Applications Decadal Survey
97 (National Academies, 2018).

98 Figure 1 shows simulated transmission spectra in the weak (~1650 nm) and strong (~2300 nm) SWIR methane
99 absorption bands at the spectral resolutions of TROPOMI (0.25 nm FWHM), AVIRIS-NG (5 nm), and EnMAP (10
100 nm). EnMAP spectra are sampled following the precise wavelength positions given in Guanter et al. (2015). The 1650
101 nm methane band has the advantage of being near a CO₂ band, so that joint retrievals of methane and CO₂ can be
102 combined with independent knowledge of the CO₂ column mixing ratio to remove joint errors in surface reflectivity
103 and atmospheric scattering (the so-called “CO₂ proxy” method; Frankenberg et al. 2005a). However, the 1650 nm band
104 is much weaker than the 2300 nm band and only the 2v Q-branch could be detected at coarser spectral resolution.
105 Sampling the transmission spectra at the EnMAP spectral resolution yields only 8 data points in the 1650 nm band as
106 compared to 25 in the 2300 nm band. The 2300 nm band also exhibits more resolved structure. Our early attempts to
107 use the CO₂ proxy method in the 1650 nm band with EnMAP synthetic spectra were unsuccessful. In what follows we
108 focus on the 2300 nm band as sampled in the useful 2210 - 2410 nm range.

109 We examined the sensitivity of EnMAP to atmospheric methane variability by generating synthetic top of
110 atmosphere (TOA) EnMAP scenes with variable methane over a variety of surface types. We used for this purpose the
111 EnMAP End-to-End Simulation Tool (EeteS; Segl, 2012), developed to generate EnMAP TOA spectra with expected
112 instrument error included. EeteS takes surface information from another imaging instrument (e.g., SPOT-5), and passes
113 the image through spatial, atmospheric, spectral, and radiometric modules to generate EnMAP spectra. The
114 atmospheric module is based on the MODTRAN5 radiative transfer code. It assumes a horizontally invariant 1800 ppb
115 dry air column methane mixing ratio (X_{CH_4}) and here we add methane plumes simulated with the Weather and Research
116 Forecasting Model Large Eddy Simulation (WRF-LES) at 30 × 30 m² resolution (Varon et al., 2018a).



117 Figure 2 shows a simulated red-blue-green (RGB) EeteS image over Berlin. We consider four scenes within
118 this domain to add WRF-LES methane plumes and perform subsequent retrievals. The scenes - Grass, Dark (water),
119 Bright, Urban - have mean SWIR surface reflectances of 0.09, 0.02, 0.30, 0.13, respectively. The urban scene is highly
120 heterogeneous. The WRF-LES simulation is conducted with $30 \times 30 \text{ m}^2$ resolution (the EnMAP pixel resolution), 100
121 W m^{-2} sensible heat flux (moderately unstable meteorological conditions), and a mean wind speed of 3.5 m s^{-1} . We
122 generate an ensemble of 15 instantaneous plumes by sampling the WRF-LES simulation at five time slices and for
123 three source rates of 100, 500, and 900 kg h^{-1} . This range is typical of large (but not unusually large) point sources
124 (Jacob et al., 2016).

125 We compute the optical depth of the methane plume $\tau(\lambda)$ at wavelength λ by multiplying HITRAN absorption
126 cross sections (σ_H ; Kochanov et al., 2016) by the methane mixing ratio enhancement (ΔVMR) and density of dry air
127 (VCD) in the 72-layered atmosphere of the MERRA-2 meteorological reanalysis (Gelaro et al., 2017):

128
$$\tau(\lambda) = \sum_{i=1}^{72} \Delta VMR_i VCD_i \sigma_{H,i}(\lambda). \quad (1)$$

129
130 The plume transmission $T(\lambda)$ is the negative exponential of $\tau(\lambda)$ weighted by the geometric airmass factor A (AMF) for
131 the backscattered solar radiation:

132
133
$$T(\lambda) = \exp\{-A\tau(\lambda)\}. \quad (2)$$

134
135 Each pixel's EeteS radiance spectrum is multiplied by this additional plume transmission. We do not add noise or
136 aerosol effects to the plume transmission spectra because the EeteS scene already accounts for those in the computation
137 of back-scattered radiances, and the plume transmission is just a multiplicative factor on these back-scattered radiances.
138 Figure 3 shows an example WRF-LES plume (500 kg h^{-1} source rate) superimposed over the Grass and Urban scenes.

139 EnMAP has a specific spectral resolution and SNR. We examined the sensitivity of the retrieval to these
140 parameters by generating synthetic spectra for different spectral resolutions and SNRs, thus extending our analysis to
141 other new-generation imaging spectrometers (Table 1). For this purpose, we interpolated EeteS surface radiance spectra
142 to the desired spectral resolution assuming no instrument noise. We then multiplied these radiance spectra by the
143 standard atmosphere plus WRF-LES plume transmission spectra and added uncorrelated instrument noise as per the
144 specified SNR.



145 To test our EnMAP retrievals on actual data, we also downsampled AVIRIS-NG images taken from aircraft
146 over California (CARB, 2017) to match EnMAP spatial resolution, and further convolved these spectra with a 10 nm
147 Gaussian filter to match EnMAP spectral resolution and wavelength positions. AVIRIS-NG flew at 3-4 km above the
148 ground, so we simulated additional extinction at higher altitudes based on the U.S standard atmosphere (Kneizys et al.,
149 1996). We compared the retrieved methane from AVIRIS-NG and the synthetic EnMAP to determine the ability of
150 EnMAP to detect and quantify the methane point sources identified by AVIRIS-NG.

151

152 **3 Methane retrieval**

153 We retrieved methane from the synthetic imaging spectrometer spectra by adapting the Iterative Maximum A
154 Posteriori - Differential Optical Absorption Spectroscopy (IMAP-DOAS) algorithm developed for AVIRIS
155 (Frankenberg et al., 2005b; Thorpe et al., 2017; Ayasse et al., 2018). DOAS retrievals isolate higher frequency features
156 resulting from gas absorption from lower frequency features that include surface reflectance as well as Rayleigh and
157 Mie scattering (Bovensmann et al., 2011). A polynomial term accounts for the low frequency features (Thorpe et al.,
158 2017).

159

160 *3.1 State vector*

161 In addition to methane (CH₄), the retrieval must account for variable absorption by water vapor (H₂O) and
162 nitrous oxide (N₂O) over the 2210-2400 nm spectral region. We parameterize low frequency spectroscopic features as a
163 sum of Legendre polynomials of order $k = [0, K]$ with coefficients a_k . The state vector (\mathbf{x}) optimized through the
164 retrieval is therefore composed of the following elements:

$$165 \quad \mathbf{x} = (s_{CH_4}, s_{H_2O}, s_{N_2O}, a_0, \dots, a_K)$$

166 where s is a scaling factor applied to the column mixing ratio of each gas from the U.S standard atmosphere (Kneizys et
167 al., 1996). We do not include aerosols in the retrieval as they play little role at the relevant spatial and spectral
168 resolution (Ayasse et al., 2018). Methane point sources generally do not co-emit aerosols.

169

170 *3.2 Optimal estimation*

171 To retrieve the state vector from the Eetes TOA radiances, we use a forward model similar to previous IMAP-
172 DOAS algorithms (Thorpe et al., 2017, Ayasse et al., 2018), with a modification to the polynomial term for surface
173 reflectance:



174
$$F^h(\mathbf{x}, \lambda) = I_0(\lambda) \exp \left(-A \sum_{n=1}^3 s_n \sum_{l=1}^{72} \tau_{n,l} \right) \sum_{k=0}^K a_k P_k(\lambda) \quad (3)$$

175 Here F^h is the high-resolution backscattered TOA radiance at wavelength λ , $I_0(\lambda)$ is the incident TOA solar intensity,
176 $\tau_{n,l}$ is the default optical depth from the US standard atmosphere for trace gas element $n = [1,3]$ of the state vector at
177 vertical level $l = [1,72]$, s_n is the scaling factor to that default optical depth optimized in the retrieval, $P_k(\lambda)$ is the k^{th}
178 Legendre polynomial, and the a_k are coefficients optimized in the retrieval. The optical depth $\tau_{n,l}$ is computed in the
179 same fashion as Equation 1, using information from the MERRA-2 reanalysis and HITRAN absorption cross sections.
180 For satellite retrievals, the AMF is a scalar describing the optical path through the atmosphere. In Section 4.3, we apply
181 the IMAP-DOAS algorithm to airborne AVIRIS-NG scenes and use a vector-valued AMF that depends on the height of
182 the aircraft.

183 Previous IMAP-DOAS algorithms used a simple polynomial approximation for the surface reflectance, but
184 here we use Legendre polynomials to exploit their orthogonality. We find that $K = 4$ provides sufficient spectral
185 resolution whereas previous applications using simple polynomials required $K = 6$ (Ayasse et al., 2018).

186 We compute the TOA backscattered radiances $F^h(\mathbf{x}, \lambda)$ over the 2210-2410 nm spectral range at 0.02 nm
187 resolution, and assemble these in a vector $\mathbf{F}^h(\mathbf{x})$ representing the high-resolution spectrum as simulated by the forward
188 model for a given \mathbf{x} . We convolve this spectrum with the instrument FWHM and then sample at the known wavelength
189 positions. For example, for EnMAP, we convolve $\mathbf{F}^h(\mathbf{x})$ with a 10 nm FWHM and sample the resulting spectra at
190 EnMAP's 10 nm intervals to get the low-resolution $\mathbf{F}(\mathbf{x})$. We also explored performing separate convolutions on the
191 high resolution transmission and polynomial terms in Equation 3, and then multiplying them together to get $\mathbf{F}(\mathbf{x})$. We
192 found little difference in the results between methods.

193 Observed backscattered TOA radiances (\mathbf{y}) can be represented as

194
$$\mathbf{y} = \mathbf{F}(\mathbf{x}) + \boldsymbol{\epsilon} \quad (4)$$

195 where the observational error $\boldsymbol{\epsilon}$ is the sum of instrument and forward model errors. As is commonly done for satellite
196 retrievals, we assume that the forward model error is small compared to the instrument error characterized by the SNR.
197 The forward model is non-linear so that the solution must be obtained iteratively. A Jacobian matrix is calculated for
198 each iteration of the state vector

199
$$\mathbf{K}_i = \left. \frac{\partial \mathbf{F}}{\partial \mathbf{x}} \right|_{\mathbf{x}=\mathbf{x}_i} \quad (5)$$

200 and we employ a Gauss-Newton iteration to solve iteratively for the optimal state vector (Rodgers, 2000):



201
$$\mathbf{x}_{i+1} = \mathbf{x}_A + (\mathbf{K}_i^T \mathbf{S}_0^{-1} \mathbf{K}_i + \mathbf{S}_A^{-1})^{-1} \mathbf{K}_i^T \mathbf{S}_0^{-1} [y - \mathbf{F}(\mathbf{x}_i) + \mathbf{K}_i(\mathbf{x}_i - \mathbf{x}_A)] \quad (6)$$

202 Here $\mathbf{S}_0 = [\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T]$ is the observation error covariance matrix defined by the instrument SNR, \mathbf{x}_A is the prior estimate of the
203 state vector, and \mathbf{S}_A is the prior error covariance matrix. We set a weak prior error variance for methane, $\sigma_{\text{SCH}_4}^2 = 5$, to
204 accommodate large plume enhancements. The prior X_{CH_4} estimate is 1800 ppb. The iterative analytical solution to the
205 inverse problem as described by equation (6) also provides the posterior error covariance matrix ($\hat{\mathbf{S}}$) as part of the
206 solution:

207
$$\hat{\mathbf{S}} = (\mathbf{K}_i^T \mathbf{S}_0^{-1} \mathbf{K}_i + \mathbf{S}_A^{-1})^{-1} \quad (7)$$

208

209 $\hat{\mathbf{S}}$ gives information on the error correlation between retrieved methane and surface reflectivity, which is a major
210 concern for methane retrievals (Butz et al., 2012).

211

212 4. Results and Discussion

213 4.1 EnMAP plume retrievals over different surfaces

214 Figure 3 shows examples of the IMAP-DOAS retrievals of 500 kg h⁻¹ and 900 kg h⁻¹ WRF-LES plumes over
215 the Grass and Urban scenes. Near the emission source, the 500 kg h⁻¹ plume is clearly defined in the Grass scene. It is
216 also detectable in the Urban scene but obscured by surface retrieval artifacts. The 900 kg h⁻¹ plume is better captured
217 over both surfaces, though major retrieval artifacts remain in the Urban scene.

218 Varon et al. (2018a) previously estimated the theoretical ability of a satellite instrument to quantify source
219 rates from point sources as a function of instrument precision, assuming a uniform surface reflectance. They concluded
220 that an instrument with 1-5% precision on X_{CH_4} would be able to quantify point sources with an error of 70-170 kg h⁻¹.
221 Here we characterize the EnMAP instrument precision as the relative root-mean squared-error (RRMSE) between the
222 true and retrieved column methane concentrations for individual 30 × 30 m² pixels in the scenes of Figure 2 including
223 the WRF-LES plumes. Figure 4 summarizes the results for the four scenes of Figure 2. We find precisions of 8.2 ±
224 0.7% for Grass, 13 ± 0.7% for Urban, and 3.7 ± 0.5% for Bright scenes. The standard deviations refer to the RRMSEs
225 computed for the 15 different realizations of the WRF-LES plumes and for the 3 source rates of 100, 500, and 900 kg h⁻¹.
226 The Dark scene was consistently unsuccessful, with error of at least 100% for each realization, and we do not discuss
227 it further. The Bright scene performs the best because of the large backscattered photon flux. The Urban scene performs
228 worse than the Grass scene, even though its average SWIR surface reflectance is larger, due to the larger variability in



229 reflectance over the scene including dark pixels. As illustrated in Figure 3, the 8% precision over the relatively uniform
230 grass surface should enable EnMAP to successfully quantify 500 kg h⁻¹ point sources in a single pass.

231 Beyond the precision for the methane retrieval, an additional limitation for retrieving point sources is the error
232 correlation with variable surface reflectance. This is illustrated in Figure 3 with the retrieved X_{CH_4} enhancements over
233 Grass and Urban scenes relative to the background. In the case of the Grass scene with a 500 kg h⁻¹ source, the 8%
234 precision limits the ability to observe the downwind plume but there is a clear enhancement over background at the
235 source location. With a 900 kg h⁻¹ source the downwind plume becomes well-defined against the background. In the
236 case of the Urban scene, the detection of the 500 kg h⁻¹ plume is far more problematic because of large positive artifacts
237 over dark (water) pixels. The 900 kg h⁻¹ plume is still difficult to distinguish from the artifacts and would require prior
238 knowledge of source location to be identified and quantified. The error correlation between methane and surface
239 reflectance in the retrieval can be reduced by increasing the spectral resolution of the instrument as discussed in Section
240 4.2.

241

242 *4.2 Sensitivity to instrument spectral resolution and SNR*

243 Here we examine the potential of future instruments with improved spectral resolution and SNR relative to
244 EnMAP (Table 1) to achieve improved retrievals of point sources. Figure 5 shows the change in retrieval precision as
245 we vary the spectral resolution from 10 to 1 nm and the SNR from 100 to 500. The precision estimates are calculated
246 using two methods. First, we estimate the precision by evaluating the RRMSEs averaged over the Grass, Urban, and
247 Bright scenes of Figure 2, for 3 source rates and 15 instantaneous plume realizations, following the procedure of
248 Section 4.1. Since SNR varies on a per-pixel basis, the plotted SNRs for this method represent the mean scene SNR.
249 Specifications of the instruments in Table 1 are identified on the plot. Precision improves as spectral resolution and
250 SNR increase, as expected. The dependencies are not linear, and the contours are concave, meaning that precision is
251 more effectively improved by increasing spectral resolution by a certain factor than by increasing SNR by the same
252 factor. Increasing the spectral resolution improves precision through multiple independent factors: by increasing the
253 number of independent measurements across the methane interval; by increasing the effective squared depth of the
254 sharpest methane absorptions, for improved spectral contrast relative to the continuum; and by better resolution of the
255 unique methane absorption shape, which improves discrimination against potential surface confusers.

256 Second, we estimate theoretical precision in Figure 5 by extracting the associated X_{CH_4} posterior error
257 covariance term of $\hat{\mathbf{S}}$ from Equation 7. Here we find that instrument precision improves more as a function of SNR than



258 spectral resolution, which is a different result than the first precision method. Issues with the surface retrieval drive the
259 contrasting results between the two methods. This underscores the difficulty in assigning a single retrieved X_{CH_4}
260 uncertainty value for different instrument configurations. For a spaceborne AVIRIS-NG instrument, multiple along-
261 track samples would increase the SNR as a function of \sqrt{N} , where N = number of along-track frames. For the second
262 precision method, doing multiple along-track samples improves the theoretical precision from 5% to 1%. Varon et al.
263 (2018a) found that an instrument with 5% precision could constrain most anthropogenic point sources above 170 kg h⁻¹.
264 Using both the RRMSE and theoretical precision methods of Figure 5, we find that a spaceborne AVIRIS-NG
265 instrument (spectral resolution 5 nm, SNR 200-400) would have a precision of 5.5 – 1.0%, meaning that such an
266 instrument could constrain a majority of anthropogenic methane point sources.

267 A benefit of increasing spectral resolution is to improve decoupling of surface and methane spectroscopic
268 features. We saw in Figure 3 that this was a major source of error over inhomogeneous surfaces such as the Urban
269 scene. It is manifested in the retrieval by an error correlation between state vector elements s_{CH_4} (scaling factor for
270 methane column mixing ratios) and a_k (coefficients for the surface reflectivity described by Legendre polynomials).
271 This error correlation is described by the posterior error covariance matrix $\hat{\mathbf{S}}$ obtained as part of the retrieval (Equation
272 6). For example, the error correlation decreases significantly between EnMAP ($r = -0.33$) and AMPS ($r = -0.19$). This
273 driven by the increase in spectral resolution from 10 nm to 1 nm. A separate test shows that simply increasing the SNR
274 to 300 (as for SBG) does not improve the error correlation.

275 An important implication of decoupling X_{CH_4} from the surface reflectance in the retrieval is to improve the
276 capability for plume pattern recognition, which is necessary to convert observed plume methane enhancements into
277 source rates (Varon et al., 2018a). Figure 6 illustrates this for the Grass and Urban scenes of Figure 3 including the
278 plume from the 500 kg h⁻¹ point source. Following Varon et al. (2018a), we define the plume for the retrieved scenes
279 with a plume mask that applies median and Gaussian filters to pixels above the 80th percentile of X_{CH_4} within the scene.
280 Retrievals are performed with the specifications of the EnMAP instrument (10 nm spectral resolution, SNR 180), SBG
281 (10 nm, 300), and AMPS (1 nm, 400).

282 For the Grass scene we find that all three instruments can discern the plume pattern near the emission source
283 and separate it from surface features. SBG and AMPS capture larger plume domains because of their higher precisions
284 (Figure 5), but a source rate can still be estimated successfully with EnMAP by taking into account the dependence of
285 the retrieved plume extent on instrument precision (Varon et al., 2018a). For the Urban scene, EnMAP plume detection
286 is swamped by surface artifacts. Simply increasing the SNR as in the SBG instrument does not improve the situation.



287 Increasing the spectral resolution to 1 nm as in the AMPS instrument enables detection of the plume though
288 quantification would still be prone to surface artifacts.

289

290 4.3 Evaluation with AVIRIS-NG observations

291 To test the EnMAP retrieval capability with actual observations, we downsampled AVIRIS-NG spectra taken
292 over California methane emitting facilities (CARB, 2017). We chose three scenes observed by AVIRIS-NG on
293 different days over oil and gas facilities. Figure 7 shows the RGB images, the AVIRIS-NG plume retrievals performed
294 by applying the method of Section 3 with a variable AMF, and the downsampled EnMAP retrievals. Plume masks
295 have been applied in the same way as for Figure 6. At the altitudes used for the California survey, AVIRIS-NG has 3×3
296 m² pixel resolution and hence features much sharper methane enhancements than EnMAP (note the different scales for
297 the middle and right panels).

298 We see from Figure 7 that EnMAP is able to detect the same plumes as AVIRIS-NG (two plumes in the
299 bottom panels). This is facilitated by the brightness of the surfaces. The surface reflectivities retrieved simultaneously
300 with the methane enhancements in our IMAP-DOAS algorithm are 0.39-0.49, brighter than the Bright EeteS scene in
301 Section 4.1.

302 The plume observations can be related to the corresponding source rates by computing the integrated mass
303 enhancements (IME) within the plume mask (Frankenberg et al., 2016; Varon et al., 2018a). The IME is calculated as:

$$304 \quad \text{IME} = \sum_{i=1}^N \Delta\Omega_i \Lambda_i \quad (7)$$

305 where $\Delta\Omega_i$ is the plume mass enhancement in pixel i relative to background (kg m⁻²), Λ_i is the corresponding area of
306 the pixel, and the summation is over the N pixels within the plume mask. The point source rate Q is then inferred from
307 the IME as (Varon et al., 2018a)

$$308 \quad Q = \frac{U_{eff}}{L} \text{IME} \quad (8)$$

309 where $L = \sqrt{\sum_{i=1}^N \Lambda_i}$ is a characteristic plume size and U_{eff} is an effective wind speed describing the rate of turbulent
310 dissipation of the plume (L/U_{eff} is the lifetime of the plume against turbulent dissipation to below the detection limit).
311 Varon et al. (2018a) relate U_{eff} to the 10-m wind speed (U_{10}) by fitting to WRF-LES simulations. Here we use their
312 relationship derived for the a 50 m pixel resolution, 5% precision instrument (Varon et al., 2018), and apply it as a
313 rough approximation to the AVIRIS-NG and downsampled EnMAP plumes:

$$314 \quad U_{eff} = 1.1 \log U_{10} + 0.6 \quad (9)$$



315 where U_{eff} and U_{10} are in units of $[m\ s^{-1}]$. We obtain U_{10} from the HRRR-Reanalysis at 3-km hourly resolution
316 (<https://rapidrefresh.noaa.gov/>).

317 Figure 7 shows the source rates inferred from the AVIRIS-NG and EnMAP retrievals for each point source.
318 The AVIRIS-NG source rates are a factor of 1.2-3.0 greater (average 1.9) than the EnMAP source rates. There could be
319 several factors behind this discrepancy including error correlation with surface reflectivity in the EnMAP retrieval that
320 would cause some loss of the plume, and use of a generic plume mask and IME algorithm for both instruments. As
321 pointed out by Varon et al. (2018a), the U_{10} - U_{eff} relationship needs to be tailored to the pixel resolution and precision of
322 the particular instrument, and to the choice of plume mask. Nevertheless, the results do confirm that EnMAP should be
323 able to detect plumes and quantify source rates down to $\sim 100\ kg\ h^{-1}$ when the scene is sufficiently bright.

324

325 5 Conclusions

326 We examined the potential of next-generation spaceborne imaging spectrometers (EnMAP, PRISMA, EMIT,
327 SBG,) for observing atmospheric methane plumes from point sources and inferring the corresponding source rates.
328 These instruments have launch dates of 2019-2025 and focus on observing the Earth surface with fine pixel resolution
329 ($30 \times 30\ m^2$), but they also have observing channels at 2200-2400 nm with 7-10 nm spectral resolution that could be
330 used to retrieve methane plumes. This would achieve much finer spatial resolution than the standard satellite
331 instruments designed to measure atmospheric methane, and would provide a unique resource for global mapping of
332 individual methane point sources.

333 We focused our baseline analysis on EnMAP (spectral resolution 10 nm, SNR 180, 2020 launch date) as its
334 specifications are well documented (Guanter et al, 2015). We created synthetic spectra using the EnMAP End-to-End
335 Simulation Tool (EeteS) to simulate various surface scenes (Grass, Urban, Bright) with instrument errors and with
336 superimposed methane plumes generated by a WRF Large Eddy Simulation (LES). We then retrieved these scenes for
337 atmospheric methane together with surface reflectivities using the Iterative Maximum A Posteriori - Differential
338 Optical Absorption Spectroscopy (IMAP-DOAS) approach. The resulting precisions for methane are 8% for the Grass
339 scene, 13% for Urban, and 4% for Bright. A $500\ kg\ h^{-1}$ methane plume (typical of very large point sources) is readily
340 detected over the relatively homogeneous Grass surface. The highly heterogeneous Urban surface is much more
341 challenging because of retrieval artifacts.

342 The limitation of EnMAP in detecting methane plumes over heterogeneous surfaces is caused by error
343 correlation between methane and surface reflectivity in the retrieval. We examined how precision and error correlation



344 could be improved by increasing spectral resolution and SNR. We find that spectral resolution reduces error
345 correlation more important than SNR. The proposed Atmospheric Methane Plume Spectrometer (AMPS), which
346 bridges the gap between imaging spectrometers and atmospheric sensors (1 nm spectral resolution, SNR 400), can
347 greatly decrease surface artifacts and detect a 500 kg h⁻¹ plume even over the heterogeneous Urban surface. Alternative
348 surface parameterizations might also improve X_{CH_4} and surface separation. For example, a channelwise representation
349 with reflectances tied through an empirical covariance structure (Thompson et al., 2018) has been used previously to
350 improve consistency in water vapor estimations. Alternative algorithms, such as matched filter approaches (Ong et al.,
351 2019) may show different X_{CH_4} sensitivities, and in particular may be better able to represent structured reflectances of
352 more complex surfaces.

353 We tested the EnMAP capability with actual observations by downsampling AVIRIS-NG images taken from
354 aircraft (3 × 3 m² pixels, 5 nm spectral resolution, SNR 200) over California methane emitting facilities (CARB, 2017).
355 We showed that these EnMAP-like images are able to detect and quantify actual plumes of magnitude ~100 kg h⁻¹ over
356 relatively bright surfaces. Source rates inferred from the plumes with a generic Integrated Mass Enhancement (IME)
357 method are a factor of 1.2 to 3 lower for EnMAP than for AVIRIS-NG, which could be due in part to unaccounted
358 dependence of the IME method on instrument pixel size and precision.

359 In summary, our analysis shows that future spaceborne imaging spectrometers designed to map the Earth
360 surface in the SWIR also have considerable potential for detecting methane plumes from point sources and quantifying
361 source rates. The detection capability of 100-500 kg h⁻¹ over relatively bright or homogeneous land surfaces would
362 allow accounting for a wide range of point sources. The fine spatial resolution of these instruments should make them a
363 unique resource to contribute to tiered observing systems for greenhouse gases (Duren and Miller, 2012).

364

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Table 1. Shortwave infrared (SWIR) remote sensors for observing methane point sources

| Instrument | Pixel size (km ²) | SWIR spectral range (nm) ^a | Spectral resolution (nm) ^b | Signal-to-noise ratio (SNR) ^c | Observing epoch |
|------------------------------|-------------------------------|---------------------------------------|---------------------------------------|--|-----------------|
| <i>Aircraft</i> | | | | | |
| AVIRIS-NG ^d | 0.003 × 0.003 | 1600–1700; 2200–2510 | 5.0 | 200–400 ^e | Campaigns |
| <i>Satellite</i> | | | | | |
| <i>Atmospheric sensors</i> | | | | | |
| SCIAMACHY ^f | 30 × 60 | 1630–1670 | 1.4 | 1500 | 2002–2012 |
| GOSAT ^g | 10 × 10 | 1630–1700 | 0.06 | 300 | 2009– |
| GHGSat ^h | 0.05 × 0.05 | 1600–1700 | 0.1 | TBD | 2016– |
| TROPOMI ⁱ | 7 × 7 | 2305–2385 | 0.25 | 100 | 2017– |
| AMPS ^j | 0.03 × 0.03 | 1990–2420 | 1.0 | 200–400 | Proposed |
| <i>Imaging spectrometers</i> | | | | | |
| PRISMA ^k | 0.03 × 0.03 | 1600–1700; 2200–2500 | 10 | 180 | 2019– |
| EnMAP ^l | 0.03 × 0.03 | 1600–1700; 2200–2450 | 10 | 180 | 2020– |
| EMIT ^m | 0.06 × 0.06 | 1600–1700; 2200–2510 | 7–10 | 200–300 | 2022– |
| SBG ⁿ | 0.03 × 0.03 | 1600–1700; 2200–2510 | 7–10 | 200–300 | 2025– |

^aMethane has absorption bands near 1650 and 2300 nm.

5 ^bSpectral resolution is represented by the full-width at half-maximum (FWHM).

^cFor SCIAMACHY and GOSAT, SNR is for CO₂ band used in the CO₂-proxy method retrieval. For other instruments, SNR is at 2300 nm.

10 ^dAirborne Visible/Infrared Imaging Spectrometer – Next Generation (Thorpe et al., 2017). AVIRIS-NG provides roughly a ground sampling distance (GSD) of 1 m per km altitude. The Frankenberg et al. (2016) and Duren et al. (2019) campaigns operated at 3–4 km altitude.

^eAlong-track oversampling increases SNR by \sqrt{N} where N = number of along-track frames. AVIRIS-NG routinely achieves $N > 4$ so AVIRIS-NG effective SNR at 2300 nm can be as much as 400.

^fScanning Imaging Absorption SpectroMeter for Atmospheric CHartography (Frankenberg et al., 2006)



- ^eTANSO-FTS instrument aboard the Greenhouse gases Observing SATellite (Kuze et al., 2016). Pixels are circles of 10 km diameter.
- ^hGreenHouse Gases Satellite (McKeever et al., 2017). Revisit times are for selected 12×12 km² scenes. The demonstration GHGSat-D instrument presently in space has additional instrument imperfections that limit its precision to 13% (McKeever et al. 2017).
- ⁱTROPOspheric Monitoring Instrument (Hu et al., 2018)
- ^jAirborne Methane Plume Spectrometer (Thorpe et al., 2016)
- ^kPRecursore IperSpettrale della Missione Applicativa (<http://prisma-i.it>)
- ^lEnvironmental Mapping and Analysis Program (Guanter et al., 2015)
- 10 ^mEarth Surface Mineral Dust Source Investigation (Green et al., 2018)
- ⁿSurface Biology and Geology, previously called HypsIRI (Hochberg et al., 2015)

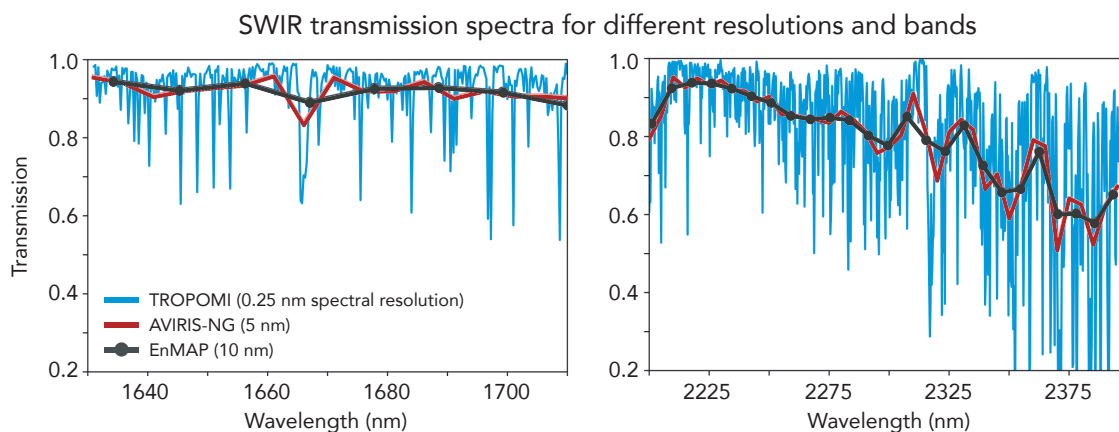
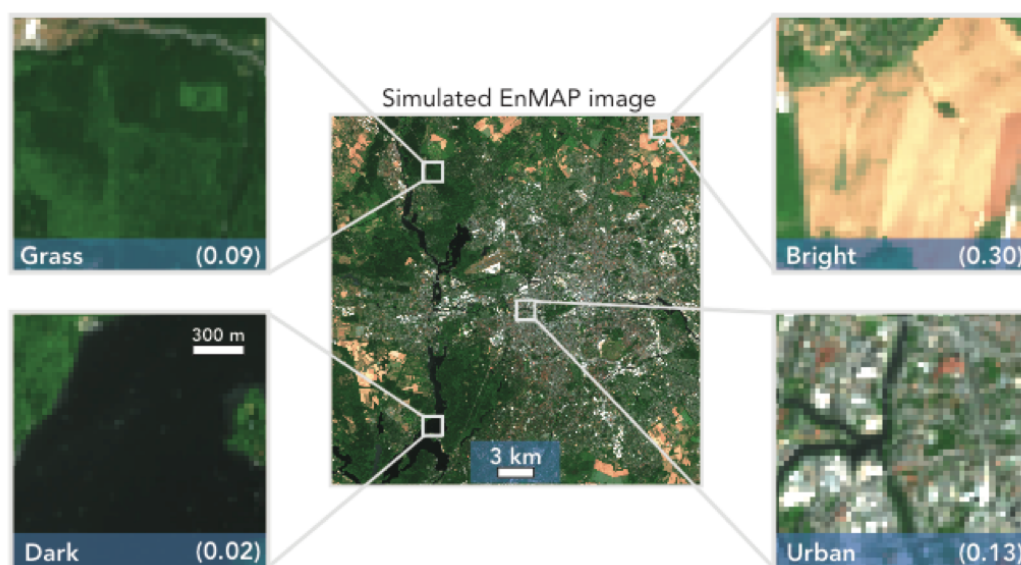


Figure 1. Simulated top of the atmosphere (TOA) transmission spectra for different spectral resolutions (FWHM = full-width at half-maximum) in the 1650 nm (left panel) and 2300 nm (right panel) shortwave infrared (SWIR) bands. High-resolution spectra were simulated for the U.S. Standard Atmosphere with 1800 ppb total column methane using the HITRAN spectroscopic database and the HITRAN Application Programming Interface (HAPI) tool (Kochanov et al., 2016), and were then sampled with spectral resolutions of 0.25 nm (TROPOMI), 5 nm (AVIRIS-NG), and 10 nm (EnMAP) at the appropriate wavelength positions.

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5 **Figure 2.** RGB image of a synthetic EnMAP scene simulated using the EnMAP End-to-End Simulation Tool (EetsS) over Berlin. Four scenes with $30 \times 30 \text{ m}^2$ pixel resolution are shown (Grass, Dark, Bright, Urban) with average surface reflectances in the SWIR (2210-2410 nm) given in parentheses. These different scenes are used in Section 3 to evaluate the sensitivity of EnMAP to atmospheric methane.

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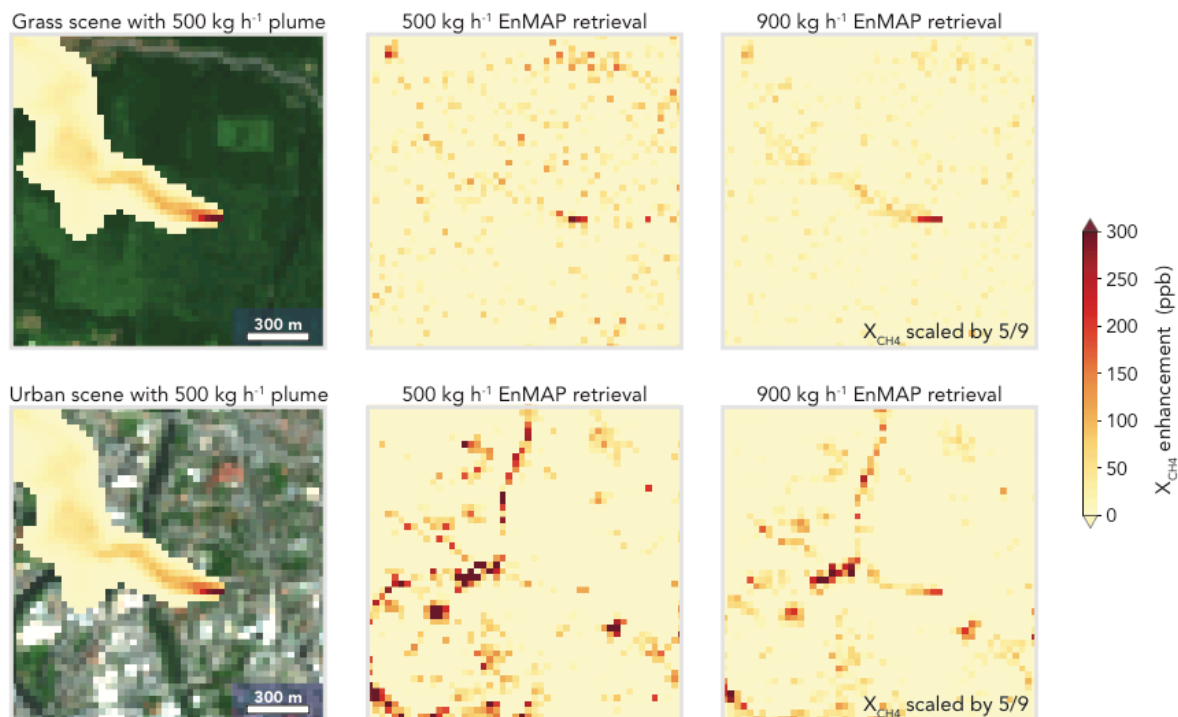


Figure 3. Retrieval of a methane plume over grass and urban EnMAP scenes. The plume was generated by WRF-LES with a source rate of either 500 kg h⁻¹ or 900 kg h⁻¹. The left panels show the dry air column mixing ratio enhancements relative to the 1800 ppb background for a 500 kg h⁻¹ methane plume superimposed on the RGB images of Figure 2. The middle panels show the retrieval of those enhancements using the IMAP-DOAS retrieval algorithm applied to the EnMAP instrument specifications. The right panels show the retrieval of the 900 kg h⁻¹ plume. The X_{CH_4} enhancements in the right panels are scaled by 5/9 to be comparable with the other panels. Negative enhancements are reset to equal the background.

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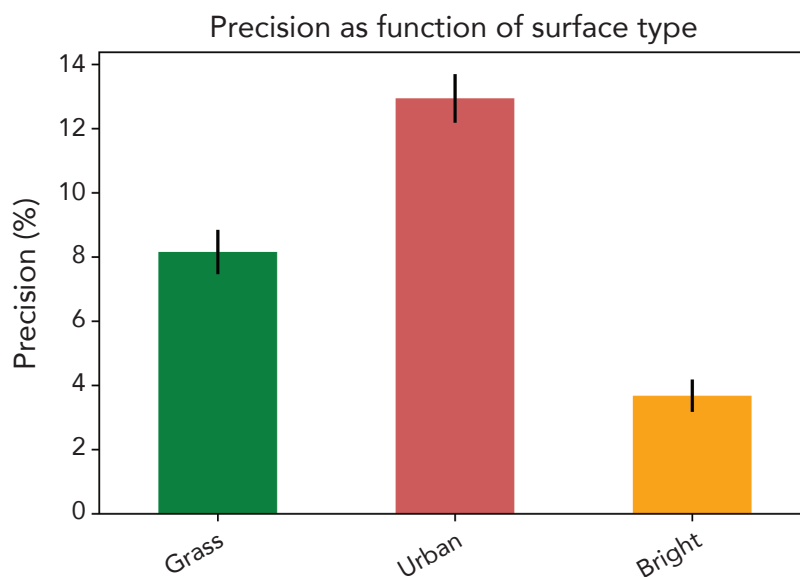


Figure 4. Precision of atmospheric methane retrievals from the EnMAP instrument (Table 1) over different surfaces. The precisions are the relative root-mean squared errors (RRMSE) between the “true” methane columns in synthetic scenes and values obtained from the IMAP-DOAS retrieval applied to the EnMAP top-of-atmosphere (TOA) backscattered radiances. The error bars represent the standard deviation over 15 WRF-LES plume realizations and 3 source magnitudes for the plume (100, 500, 900 kg h⁻¹).



Precision of methane retrievals for imaging spectrometers

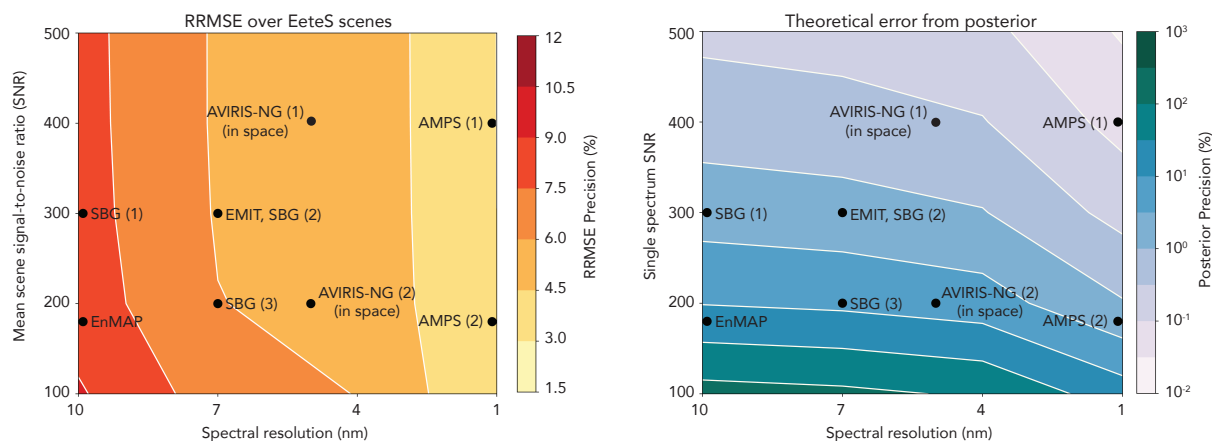


Figure 5. Precision of methane retrievals for spaceborne imaging spectrometers observing in the SWIR (2210-2400 nm), as a function of instrument signal-to-noise (SNR) and full-width half-maximum (FWHM) spectral resolution. The left panel shows precision expressed as the relative root-mean-square error (RRMSE) for synthetic retrievals over three scenes of Figure 2 (Grass, Urban, Bright) including a point source of $100\text{-}900\text{ kg h}^{-1}$ and 15 different WRF-LES plume realizations. The SNR in the left panel represents the mean SNR over all three EteS scenes. The right panel shows theoretical precision expressed from the posterior error covariance matrix in Equation 7. Black dots show different instrument specifications from Table 1. Specifications for the SBG and AMPS instruments are still at the design stage and values shown here are for the ranges under consideration. Results given for AVIRIS-NG are for a satellite instrument with $30\times 30\text{ m}^2$ pixel resolution, with (1) or without (2) along-track oversampling, and with other specifications (spectral resolution, SNR) the same as the airborne instrument.

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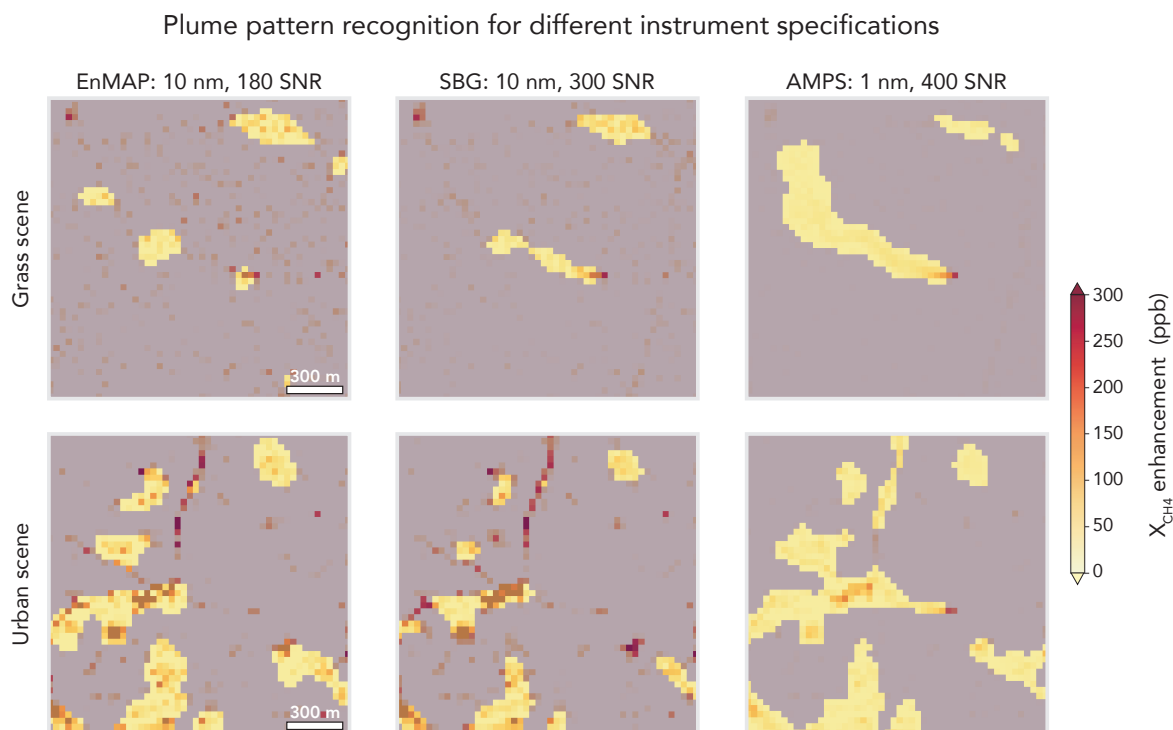


Figure 6. Plume pattern recognition applied to a point source of 500 kg h^{-1} over Grass and Urban scenes as shown in Figure 3. The plume pattern is defined by applying median and Gaussian filters to pixels above the 80th percentile of X_{CH_4} in the scene. Areas excluded by the mask are shown in gray. The panels show retrievals from the EnMAP, SBG, and AMPS instruments.



Methane retrievals over oil/gas facilities in California

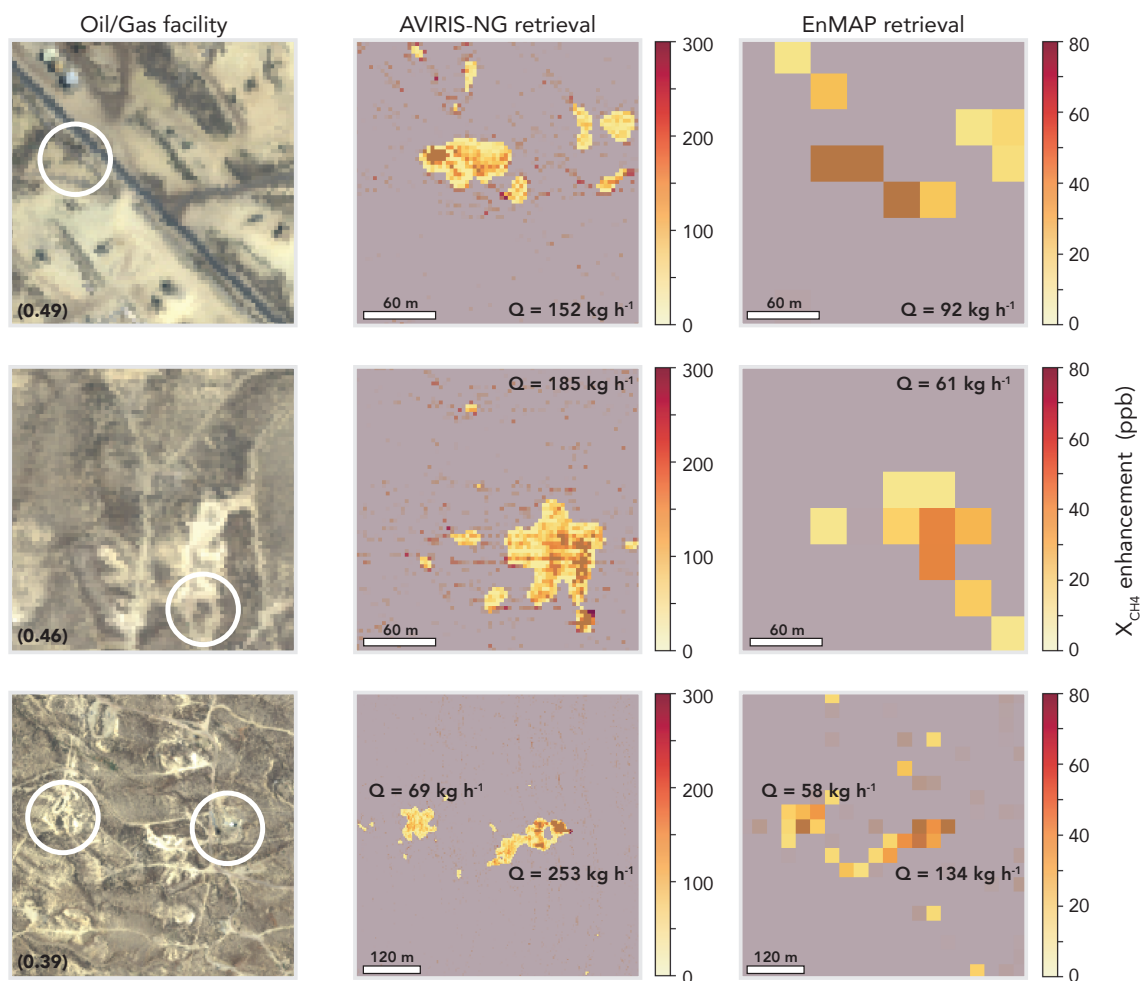


Figure 7. Retrieval of atmospheric methane plumes from oil/gas facilities imaged by the AVIRIS-NG instrument at 3-4 km altitude over California (CARB, 2017). The left panels show the RGB images mapped by AVIRIS-NG with the oil/gas facilities of interest circled. Inset in the bottom left corner is the mean retrieved SWIR surface reflectivity for the scene. The middle panels show the IMAP-DOAS retrieval applied to the AVIRIS-NG images with $3 \times 3 \text{ m}^2$ pixel resolution and 5 nm spectral resolution. The right panels show the IMAP-DOAS retrieval applied to spectra that were spatially and spectrally



downsampled to match EnMAP instrument specifications (30×30 m² pixels, 10 nm spectral resolution). Note the difference in color scale for the methane enhancements in the AVIRIS-NG and EnMAP retrievals, reflecting the coarser pixel resolution of EnMAP. The plume mask is overlaid on each. The source rates for each plume obtained from the IME method are inset.