



Separation of Convective and Stratiform Precipitation Using Polarimetric Radar Data with A Support Vector Machine Method

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Abstract. A precipitation separation approach using a support vector machine method was developed and tested on a C-band polarimetric weather radar located in Taiwan (RCMK). Different from some existing methods requiring a whole volume scan data, the proposed approach utilizes the polarimetric radar data from the lowest tilt to classify precipitation echoes into either stratiform or convective type. Through a support vector machine method, the inputs of radar reflectivity, differential reflectivity, and the separation index are integrated in the classification. The feature vector and weight vector in the support vector machine were optimized using well-classified training data. The proposed approach was tested with multiple precipitation events including two widespread mixed stratiform and convective events, a tropical typhoon precipitation event, and a stratiform precipitation event. In the evaluation, the results from the multi-radar-multi-sensor (MRMS) precipitation classification approach were used as the ground truth, and the performances from proposed approach were further compared with the approach using separation index only with different thresholds. It was found that the proposed method can accurately identify the convective cells from stratiform rain, and produce better results than using the separation index only.

1 Introduction

Convective and stratiform precipitations exhibit significant differences in precipitation growth mechanisms and thermodynamic structures (e.g., Houghton, 1968; Houze, 1993, 1997). Generally, convective precipitation is associated with strong but small areal vertical air motion ($> 5 \text{ m s}^{-1}$) (Penide et al., 2013), and delivers high rainfall rate (R) (Anagnostou, 2004). On the other hand, stratiform precipitation is associated with weak updrafts/downdrafts ($< 3 \text{ m s}^{-1}$) and relative low R . Therefore, classifying a precipitation into either convective or stratiform type not only promotes the understanding of cloud physics, but also enhances the accuracy of quantitative precipitation estimation (QPE). For these purposes, numerous methods using ground in situ measurements or satellite observations were developed during the past four decades (e.g., Leary and Jr., 1979; Adler and Negri, 1988; Tokay and Short, 1996; Hong et al., 1999).

Ground-based weather radars, such as Weather Surveillance Radar, 1988, Doppler (WSR-88D), are currently used in all aspects of weather diagnosis and analysis. Precipitation classification using single- or dual-polarization radars were developed during the past three decades. For a single-polarization radar, developed algorithms mainly rely on radar reflectivity (Z) and



its derived variables (e.g., Biggerstaff and Listemaa, 2000; Anagnostou, 2004; Yang et al., 2013; Powell et al., 2016). For
25 example, Steiner et al. (1995) (hereafter SHY95) proposed a separation approach that utilizes the texture features derived
from radar reflectivity field. In this approach, a grid point in Z field is identified as the convective center if its value is larger
than 40 dBZ, or exceeds the average intensity taken over the surrounding background by specified thresholds. Those grid
points surrounding the convective centers are classified as convective area, and far regions are classified as stratiform. Penide
et al. (2013) found that SHY95 may misclassify those isolated points embedded within stratiform precipitation or associated
30 with low cloud-top height. Powell et al. (2016) modified SHY95's approach, and the new approach can identify shallow
convection embedded within large stratiform regions, and those isolated shallow and weak convections. A neural network
based convective-stratiform classification algorithm was developed by Anagnostou (2004). It utilizes six variables as inputs
including storm height, reflectivity at 2 km elevation, vertical gradient of reflectivity, the difference in height, the standard
deviation of reflectivity, and the product of reflectivity and height. Similar variables are also used in a fuzzy logic based
35 classification approach proposed by Yang et al. (2013).

Although these listed classification algorithms have been developed and validated for years, a robust algorithm utilizing
the lowest tilt radar data only is still needed for the following two reasons. First, according to U.S. Radar Operations Center
(ROC), the WSR-88D radars are currently operated without updating a complete volume during each volume scan, especially
during precipitation events. New radar scanning schemes are designed to reorganize the updating order for a high frequency
40 in low elevations and a less frequency for high elevations. Therefore, WSR-88D radars are able to promptly capture the storm
development for weather forecast and to obtain a more accurate precipitation estimation. These new schemes include the
automated volume scan evaluation and termination (AVSET), supplemental adaptive intra-volume low-level scan (SAILS),
the multiple elevation scan option for SAILS, and the mid-volume rescan of low-level elevations (MRLE). Under these new
scanning schemes, the separation of stratiform/convective becomes challenge for those algorithms requiring a full volume scan
45 of data. Second, with the developments in radar polarimetry, polarimetric weather radars have been well applied in radar QPE,
severe weather detection, hydrometeor classification, and microphysical retrievals (Ryzhkov and Zrnica, 2019; Zhang, 2016).
Through transmitting and receiving electromagnetic waves along the horizontal and vertical directions, a polarimetric radar can
obtain extra information about hydrometeors' size, shape, species, and orientation. Therefore, the polarimetric measurements
may reveal more precipitation's microphysical and dynamic properties. Inspired by these features, a C-band polarimetric radar
50 precipitation separation approach was developed by Bringi et al. (2009) (hereafter BAL), which classifies the precipitation into
stratiform, convective and transition regions based on retrieved drop size distribution (DSD) characteristics. However, it was
found that strong stratiform echoes might have similar DSDs to weak convective echoes and lead to wrong classification results
(Powell et al., 2016).

In this work, a novel precipitation separation algorithm using separation index with other radar variables was developed and
55 tested on a C-band polarimetric radar located in Taiwan. This approach classifies precipitations into stratiform or convective
type with a support vector machine (SVM) method. Different from some existing classification techniques that require the
whole volume scan of radar data, this new approach uses the unblocked data from the lowest scanning tilt. The major advantage
of this method is that it can provide real-time classification results even if the radar is operated under AVSET, SAILS, and



MRLE scanning schemes, where the lowest tilt is the most frequently scanned and updated. This paper is organized as follows:
60 section 2 introduces the proposed method including radar variables and processings, the SVM method, and the training process.
The performance evaluation is shown in Section 3, and the discussion and summary are given in Section 4.

2 Precipitation Separation With a Support Vector Machine Method

In the current work, the SVM precipitation separation approach was developed and validated on a C-band polarimetric radar (RCMK) located at Makung, Taiwan (Figure 1). The Weather Wing of the Chinese Air Force deployed this radar and made
65 the data available to the Central Weather Bureau (CWB) of Taiwan since 2009. Together with three single-polarization S-band WSR-88D (RCCG, RCKT, and RCHL) and one dual-polarization S-band radar (RCWF), these five radars provide real-time QPEs for CWB to support missions of flood monitoring and prediction, landslide forecasts and water resource management.

2.1 Input polarimetric radar variables and preprocesses

Three direct measured or derived radar variables are proposed as inputs to the SVM approach: Z , differential reflectivity
70 fields (Z_{DR}), and separation index (i). In most of precipitation classification approaches, Z is used as one of inputs because reflectivities from convective generally show higher values than from stratiform type. For example, a radar echo with the reflectivity of 40 dBZ and above is automatically classified as convective type in the approach developed by SHY95.

Differential reflectivity, which is highly related to raindrop's mass weighted mean diameter (D_m), is another good indicator of precipitation type. It was found the values of D_m in stratiform and convective precipitation generally are within 1-1.9
75 mm and above 1.9 mm, respectively (Chang et al., 2009). Higher Z_{DR} values are expected from convective than stratiform precipitation. Therefore, Z_{DR} field is used as another input of the proposed approach.

For short wavelength radars such as C-band or X-band radars, the Z and Z_{DR} fields may be significantly attenuated when the radar beam propagates through heavy precipitation regions. Both Z and Z_{DR} fields need to be corrected from attenuation before applied in the precipitation classification and QPE. Different attenuation correction methods were proposed using the
80 differential phase (ϕ_{DP}) measurement such as the linear ϕ_{DP} approach, the standard ZPHI method, and the iterative ZPHI method (e.g., Jameson, 1992; Carey et al., 2000; Testud et al., 2000; Park et al., 2005). Because of its simplicity and easy implementation in a real-time system, the linear ϕ_{DP} method was applied in the current work.

$$Z(r) = Z'(r) + \alpha(\phi_{DP}(r) - \phi_{DP}(0)) \quad (1a)$$

$$Z_{DR}(r) = Z'_{DR}(r) + \beta(\phi_{DP}(r) - \phi_{DP}(0)) \quad (1b)$$

85 where $Z'(r)$ ($Z'_{DR}(r)$) is the observed reflectivity (differential reflectivity) at range r ; $Z(r)$ ($Z_{DR}(r)$) is the corrected value; $\phi_{DP}(0)$ is the system value; $\phi_{DP}(r)$ is the smoothed (by FIR filter) differential phase at range r . The attenuation correction coefficients α and β depend on DSD, drop size shape relations (DSR), and temperature. The typical range of α (β) is found 0.06~0.15 (0.01~0.03) dB deg⁻¹ for C-band radars (e.g., Carey et al., 2000; Vulpiani et al., 2012). Following the work from



Wang et al. (2014), optimal coefficients α and β in Taiwan are $0.088 \text{ dB deg}^{-1}$ and 0.02 dB deg^{-1} , respectively. The Z and
 90 Z_{DR} fields are further smoothed with a 3 (azimuthal) by 3 (range) moving window function after corrected from attenuation.

Using the separation index i to identify convective from stratiform precipitation was originally proposed by BAL, where i
 was calculated under a normalized gamma DSD assumption:

$$i = \log_{10}(N_W^{est}) - \log_{10}(N_W^{sep}) \quad (2)$$

$$95 \quad \log_{10}(N_W^{sep}) = -1.6D_0 + 6.3 \quad (3)$$

where N_W^{est} is the estimated N_W (normalized number concentration) from observed Z and Z_{DR} , and is calculated as:

$$N_W^{est} = Z/0.056D_0^{7.319} \quad (4)$$

In Equation 4, D_0 is the median volume diameter, and can be calculated as.

$$D_0 = 0.0203Z_{DR}^4 - 0.1488Z_{DR}^3 + 0.2209Z_{DR}^2 + 0.5571Z_{DR} + 0.801; \quad -0.5 \leq Z_{DR} < 1.25 \quad (5a)$$

$$100 \quad \quad \quad = -0.0355Z_{DR}^3 - 0.3021Z_{DR}^2 + 1.0556Z_{DR} + 0.6844; \quad 1.25 \leq Z_{DR} < 5 \quad (5b)$$

The units of Z_{DR} , Z , N_w , and D_0 are dB , mm^6m^{-3} , $\text{mm}^{-1}\text{m}^{-3}$, and mm , respectively. The positive and negative values
 of index i indicate convective and stratiform rain, respectively, and $|i| < 0.1$ indicates transition regions (Penide et al., 2013).
 BAL pointed out that index i worked well in most of the cases in their study; however, incorrect classification results are likely
 obtained for low Z and high Z_{DR} cases in some convective precipitations.

105 2.2 Drop size distribution and drop shape relation

It should be noted that the relations between Z , N_w , and D_0 were derived using the DSD data collected in Darwin, Australia.
 Coefficients in Equations 2~5 need be adjusted according to different frequency radars or/and other DSD and DSR features
 from the specific location (Thompson et al., 2015). In the current work, the separation index i derived using Equations 2~5 is
 directly used as one of the input variables. It was shown by Wang et al. (2013) that DSD and DSR features in Taiwan is very
 110 similar to those measured from Darwin, Australia. Similar $R(K_{DP})$ relationships were obtained using data collected from
 these two locations. Coefficients derived by BAL could be directly used in Taiwan without further modification. To verify this
 assumption, N_w and D_0 were calculated using DSD data collected by four impact-type Joss-Waldvogel disdrometers (JWD)
 located in Taiwan (Figure 1). The measurement range and temporal resolution of these JWDs are $0.359 \text{ mm} \sim 5.373 \text{ mm}$ and
 1 minute, respectively. Total 4306-minute data from 2011~2014 are used in N_w and D_0 calculation following the approach
 115 described in Bringi et al. (2003). Similar to the work presented in BAL, the distribution of i along median volume diameter D_0
 is shown in Figure 2, where the $(\log_{10}N_w, D_0)$ pairs from stratiform and convective types are represented with gray circles and
 black stars, respectively. Although the relation described in Equation 3 can separate most stratiform from convective types, a
 large number of points are still classified incorrectly. Therefore, the single separation index is not sufficient in the precipitation
 separation, and other variables such as Z and Z_{DR} may be used as the supplement.



120 2.3 Support vector machines (SVM) method

2.3.1 Introduction of SVM

Support vector machine (SVM) can be viewed as a kernel-based machine learning approach, which nonlinearly maps the data from the low-dimension input space to a high-dimension feature space, and then linearly maps to a binary output space (Burges, 1998). Given a set of training samples, the SVM constructs an optimal hyperplane, which maximizes the margin of separation
 125 between positive and negative examples (Haykin, 2011). Specifically, given a set of training data $\{(X_i, y_i)\}_{i=1}^N$, the goal is to find the optimal weights vector W and a bias b such that

$$y_i(W^T X_i + b) \geq 1 \quad i = 1, 2, \dots, N \quad (6)$$

where $X_i \in \mathbb{R}^m$ is the input vector, m is the input variable dimension ($m = 3$ in this work), N is the number of training samples, and y_i is an output with the value of $+1$ or -1 that represents convective or stratiform, respectively. The particular
 130 data points (X_i, y_i) are called support vector when Equation 6 is satisfied with the equality sign. The optimum weights vector W and bias b can be obtained through solving the Lagrangian function with the minimum cost function (Haykin, 2011).

Since the SVM can be viewed as a kernel machine, finding the optimal weight vector and bias in Equation 6 can be alternatively solved through the recursive least square estimations of:

$$\sum_{i=1}^{N_s} \alpha_i y_i k(X, X_i) = 0 \quad (7)$$

135 where N_s is the number of support vectors, α_i is the Lagrange multipliers, and $k(X, X_i)$ is the Mercer kernel defined as:

$$k(X, X_i) = \Phi^T(X_i)\Phi(X) = \exp\left(-\frac{1}{2\sigma^2}\|X - X_i\|^2\right) \quad (8)$$

With the solved $\{\alpha_i\}_{i=1}^{N_s}$, the SVM calculate the classification results with new input data $Z \in \mathbb{R}^m$ as:

$$f(Z) = \text{sign}\left[\sum_{i=1}^{N_s} \alpha_i y_i \Phi^T(X_i)\Phi(Z)\right] \quad (9)$$

When $f(Z) = 1$, the output is classified as convective, otherwise is classified as stratiform.

140 2.3.2 Training of the SVM

In the SVM approach, the weight vector and bias in Equation 6 need to be optimized through a recursive least square estimation using the training data set. Since the training data play a critical role in the SVM approach, Z , Z_{DR} and i from convective and stratiform precipitation events were carefully examined through three steps. Firstly, the training data was checked following general classification principles. For example, training data from convective precipitation is generally associated with relative
 145 strong reflectivity, no apparent bright band signature, and high vertically integrated liquid (VIL). Secondly, the precipitation type is verified by ground observation such as ground severe storm report. Thirdly, the precipitation type is confirmed by the



Multi-Radar-Multi-Sensor (MRMS) precipitation classification algorithm implemented in Taiwan (Zhang et al., 2011, 2016). In this MRMS classification approach, a 3-dimensional radar reflectivity field was mosaicked from 4 S-band single polarization radars (Figure 1), and the composite reflectivity (CREF) together with other fields such as temperature and moisture fields were then used in the surface precipitation classification (Zhang et al., 2016). Based on the classification results, MRMS chooses different $R(Z)$ relations in the rainfall rate estimation. The performance of MRMS has been thoroughly evaluated for years for the quantitative precipitation estimation, flash flood monitoring, severe weather and aviation weather surveillance (e.g., Gourley et al., 2016; Smith et al., 2016), and also used as the benchmark and/or ground truth in many studies (e.g., Grecu et al., 2016; Skofronick-Jackson and Coauthors, 2017). It should be noted that, although the performance of MRMS is well accepted in weather research community, there may be some imperfections in this system, especially it only uses single-polarization variables to determine the precipitation type. Other observations, such as the accumulated rainfall amount measured by gauges may be another reference. However, biases in the gauge measurements and improper $R(Z)$ relations may causes other uncertainties. Therefore, at the current stage, MRMS precipitation classification result is the best benchmark in the training and validation of the proposed algorithm. Moreover, since the MRMS classification results are derived from 4 S-band radars, it can be viewed as an independent reference.

Training data for convective type are mainly from a strong convective precipitation event on 23 July 2014. This thunderstorm, classified as convective precipitation by MRMS, was associated with strong updrafts/downdrafts and caused an aircraft crash on the airport of Makung at 1106 UTC. Radar data collected from 1030 to 1130 UTC were used as the convective type training data. Moreover, the training data are selected when they are associated with $Z > 20$ dBZ, and correlation coefficient (ρ_{HV}) > 0.98 . The stratiform type data are from a mixed stratiform and convective precipitation even on 30 August 2011, and only those data identified as a stratiform type by MRMS are used in training. Total 17281 sets of data (15144 sets of stratiform, and 2137 sets of convective) are used in the training process. The number of support vectors is selected as 1000 in the current work, and the training process is considered as completed when the root-mean-square error reaches a stable value. In the SVM approach, the original 3-dimension input space is nonlinearly maps to a 1000-dimension feature space, and then linearly maps to a binary output space (Burges, 1998). The higher dimension feature space potentially capture more input variables feature, but higher computation cost is needed. Generally, after the number of support vector reach some number, the enhancement in the performance the SVM approach becomes slight. There is a balance between accuracy and computation. In the current work, the numbers of support vectors were tested at 500, 750, 1000, 2000, and 5000, and 1000 can produce less than 5% error with reasonable computation time. As the prototype algorithm, the number of support vectors is selected as 1000 in the current work.

3 Performance Evaluation

3.1 Description of the experiments

The performance of the proposed approach was validated with four precipitation events from 2009 to 2012. These four precipitation events include one stratiform event, one strong tropical precipitation event, and two events of the mixed convective and



180 stratiform. Two experiments based on the BAL approach with different thresholds (i.e., BAL^0 and $BAL^{-0.5}$) were also carried
out in the evaluation. In these two experiments, the separation index i from each radar gate is first calculated using Equations
2~5, and thresholds of $T_0 = 0$ and -0.5 are then used to separate convective type from stratiform type. A pixel is classified
as convective if i is larger than T_0 , and as stratiform otherwise. This work aims at developing a complementary method using
185 separation index i together with other variables to separate convective from stratiform type. The proposed SVM and BAL
methods both can classify the precipitation using the lowest tilt radar data only, which is suitable for fast scanning and quick
updated purpose. Other classification approaches as introduced in section 1 were not examined in the current work, because
they require the data from multiple elevation angles.

The MRMS classification products are used as the reference “ground truth” in the evaluation. Because the MRMS results
are derived using the mosaicked field from four S-band single-polarization radars, the coverage and time stamp are different
190 from the result of the single radar RCMK. The classification results from RCMK (i.e., BAL^0 , $BAL^{-0.5}$ and SVM) and MRMS
could be significantly different with timestamp difference as large as 5 minutes. Given the fact that the convective storms size,
intensity, and cells locations could change significantly during a 5-minute period, it is not appropriate to quantitatively evaluate
the performance using the pixel-to-pixel evaluation criteria of the probability of detection (POD) and false alarm rate (FAR).
Qualitative evaluation maybe the best option for this work, which include two major steps: 1.) Since the MRMS output has
195 much bigger coverage, the MRMS is first truncated according to the coverage of RCMK. This step can assure the RCMK and
MRMS have the same precipitation grids. 2.) A whole coverage convective ratio (R^{CS}) is introduced as:

$$R^{CS} = \frac{N^{con}}{N^{con} + N^{str}} \times 100\% \quad (10)$$

Where N^{con} and N^{str} are the total pixel numbers of convective and stratiform types within the coverage, respectively. The
evaluation results are shown in the following sections, and the overall performances of R^{CS} from the evaluation cases are
200 presented in Table 1.

3.2 Experiment results

3.2.1 Widespread mixed stratiform and convective precipitations

The performance of the proposed approach was first validated with two widespread stratiform and convective mixed precipi-
tation events from 30 August 2011 and 14 June 2012. For these two cases, 24-hour data (0000 UTC~2400 UTC) were used
205 in the evaluation. The results from the BAL approach (BAL^0 and $BAL^{-0.5}$) were also calculated. It should be noted that the
threshold of -0.5 is lower than the value suggested by BAL, and more pixels will be classified as convective by $BAL^{-0.5}$. The
classification results from the proposed SVM were calculated using the trained weight vector and biases, and the convective
ratios from MRMS, SVM, BAL^0 , and $BAL^{-0.5}$ were calculated using Equation 10.

The time series plots of R^{CS} are shown in Figure 3, where results from 30 August 2011 and 14 June 2012 are shown on
210 panel “a” and “b”, and the R^{CS} from MRMS, SVM, BAL^0 , and $BAL^{-0.5}$ are presented by thick solid, thick dashed, thin
solid and thin dashed lines, respectively. In general, $BAL^{-0.5}$ classifies more pixels as convective than BAL^0 as expected for



both cases, and SVM shows the most similar results to MRMS comparing to BAL approaches. For the 30 August 2011 case (Figure 3a), if the MRMS results are considered as the ground truth, BAL⁰ shows obvious under classification of convective type during this 24-hour period, but BAL^{-0.5} shows better performance. On the other hand, BAL^{-0.5} classifies more pixels
215 as a convective type than MRMS in the 14 June 2012 case (Figure 3b), but the results from BAL⁰ are more consistent with MRMS outputs. The overall R^{CS} from MRMS, SVM, BAL⁰, and BAL^{-0.5} are shown in Table 1.

To better understand the performance of each approach, the classification results and radar variables (Z , Z_{DR} , and i) from two distinct moments were examined and shown in Figures 4~7. Classification results from 0303 UTC 30 August 2011 were first shown in Figure 4, where BAL⁰, BAL^{-0.5}, SVM and MRMS are shown in panel ‘a’, ‘b’, ‘c’, and ‘d’, respectively. The
220 time stamp for MRMS result is 0300 UTC and the time difference from the other three approaches is about 3 minutes. These three input variables of SVM at 0303 UTC are shown in Figure 5, where Z , Z_{DR} , and i are presented in panel ‘a’, ‘b’, and ‘c’. From Figures 3 and 4, it could be found that the R^{CS} from MRMS, SVM, and BAL^{-0.5} show similar value, but R^{CS} from BAL⁰ is obviously low. Within the black circle of Figure 5, the averages of Z and Z_{DR} both show relatively large values ($Z > 36$ dBZ and $Z_{DR} > 0.75$ dB), this is a clear indication of convective type precipitation. Both SVM and BAL^{-0.5} classify
225 most of the area within the black circle as convective, and this result is consistent with the MRMS result. Since the separation indexes within the black circle are below or slightly higher than 0, most of the area is classified as stratiform type. For this moment, threshold -0.5 shows better performance than 0.

Figure 6 shows the classification results from SVM, BAL⁰, BAL^{-0.5} (0801 UTC) and MRMS (0800 UTC) on 14 June 2012. In this case, MRMS, SVM, BAL⁰ show similar performance in general, but BAL^{-0.5} shows visible over classification of
230 convective cells. The R^{CS} from MRMS, SVM, and BAL⁰ show similar values around 22%, but BAL^{-0.5} classifies much more pixels as connective with R^{CS} reaches 41% (Figure 6). Radar variables are shown in Figure 7, and a circle is also inserted in both Figures 6 and 7 to emphasize the performance from each approach in this circle. Inside the circle, the echoes with the Z values around 30~35 dBZ have the chances to be either stratiform or convective type. On the other hand, the Z_{DR} shows low value around 0 dB, which is generally considered as the indicator of stratiform. It should be noted, it is impossible to show all
235 the comparison results (every 5 minutes) as Figures 4~7 from these two cases. Therefore, the results are shown in Figure 3 and Table 1 to quantitatively demonstrate their performance.

3.2.2 Tropical convective

Typhoon Morakot (6~10 August 2009) brought significant rainfall to Taiwan. Over 700 people were reported dead in the storm, and the property loss was more than 3.3 billion USD. For most of the time during its landfall in Taiwan, the precipitation was
240 classified as a mixture of tropical convective and tropical stratiform types. The performances of SVM, BAL⁰, and BAL^{-0.5} were validated with 96-hour data from 6 to 9 August 2009, where the results from 10 August 2009 were not included in the evaluation because no significant precipitation was observed. The time series plots of R^{CS} , shown in Figure 8, demonstrate that the R^{CS} from the BAL based approaches is evidently lower than the results from SVM and MRMS, and the latter two show similar performance during this 4-day period.



245 Classification results from BAL^0 , $BAL^{-0.5}$, SVM (0402 UTC), and MRMS (0400 UTC) from 9 August 2009 are shown in
Figure 9a, 9b, 9c, and 9d, respectively. The classification results in those regions, highlighted with two circles, are convective
(SVM and MRMS) and stratiform (BAL^0 and $BAL^{-0.5}$). Figure 10 includes the reflectivity (10a), differential reflectivity (10b),
and separation index (10c) from 0402 UTC, where the reflectivity field within the red rectangular box is shown in Figure 10d
for more details. It was found that the heavy precipitation band is on the top of RCMK (Figure 10d), and this may cause
250 significant attenuation and differential attenuation on Z and Z_{DR} fields. Although both Z and Z_{DR} fields were corrected,
deficient or over compensations on Z and Z_{DR} fields lead to increased uncertainty on the separation index. It may be the
primary reason causing the small values of the separation index. In Figure 10c, the separation index i are equal or less than
-0.5 in the circled areas, and the BAL based approaches classify these regions as stratiform. On the other hand, these regions
clearly show the convective precipitation features in the fields of Z (10a) and Z_{DR} (10b).

255 3.2.3 Stratiform precipitation event

The performances of BAL^0 , $BAL^{-0.5}$, and SVM approaches were also evaluated with a widespread stratiform precipitation
event on 26 March 2011. There were no convective type precipitations identified by MRMS, and all these three approaches
showed consistent classification results with the MRMS result during 8-hour period evaluation.

4 Conclusions

260 A novel precipitation classification approach using support vector machine approach was developed and tested on a C-band po-
larimetric radar located in Taiwan. Different from other classification algorithms that use whole volume scan data, the proposed
method only utilizes the data from the lowest unblocked tilt to separate precipitation into convective or stratiform type. It can be
applied on new scanning schemes with more frequent scans at the lowest tilts and lack of information from a higher tilt, such as
AVSET, SAILS, MRLE, and etc. Three radar variables of reflectivity, differential reflectivity, and the separation index derived
265 by Bringi et al. (2009) are utilized in the new proposed approach, where both reflectivity and differential reflectivity need be
corrected from attenuation and differential attenuation. Although the separation index alone can be used in the precipitation
classification, there may be two potential limitations: thresholds and attenuation. Although the threshold “0” is proposed to
separate convective from stratiform types, it was found that a single threshold may not sufficient for all cases. Other thresholds
(such as “-0.5” used in the current work), sometimes can produce better results than “0”. The attenuation is the other potential
270 issue. Although both reflectivity and differential reflectivity should be corrected from attenuation before used in the separation
index calculation, the correction biases on either field may cause large uncertainty in the derived separation index and further
lead to a wrong classification. This work attempts to propose a complementary method to enhance the performance of using
separation index only. The proposed approach integrates input variables with a support vector machine method. The weights
and bias vectors used in the support vector machine were trained with typical stratiform and convective precipitation events. It
275 should be noted that the proposed approach has a flexible framework, and some other variables can be easily included. With
newly added variables, the weighting and bias vectors need to be retrained. The proposed approach was tested with multiple



cases, and its performance was found similar to a well-developed approach, MRMS, which utilizes multiple tilts radar data in the classification. It should be noted that the time difference between RCMK (i.e., BAL^0 , $BAL^{-0.5}$ and SVM) and MRMS could be as large as 5 minutes. Therefore, the pixel-to-pixel evaluation criteria of the probability of detection (POD) and false alarm rate (FAR) is not feasible for the evaluation. Although a new variable of R^{CS} is used in the performance evaluation, this should be treated as qualitative evaluation.

There are some issues need be noticed before applying this approach into operation. First, this approach is developed for fast scanning and fast update purpose, therefore, only the lowest tilt data is used as the input. With the higher tilt data as the inputs, potential enhancements should be expected. Second, the performance of the proposed approach depends highly on the training data, which should be selected very carefully. Third, coefficients in the separation index calculation depends on the local drop size distribution and drop shape relation features. Therefore, new relations need to be derived for the optimal results. Four, this work only presents a prototype algorithm. Given the flexible framework, other variables (such as differential phase) could be easily integrated into this algorithm, and the performance could be further enhanced.

Code and data availability.

The datasets and source code used in this study are available from the corresponding author upon request (yadwang@siue.edu).

Author contributions.

The algorithm was originally developed by Dr. Y. Wang. Dr. L. Tang processed the radar data including generate results from MRMS. Dr. P.-L. Chang and Miss Y.-S. Tang provided and processed radar data from CWB, they were further involved in algorithm discussion and article writing.

Competing interests.

The authors declare that there is no conflict of interest.

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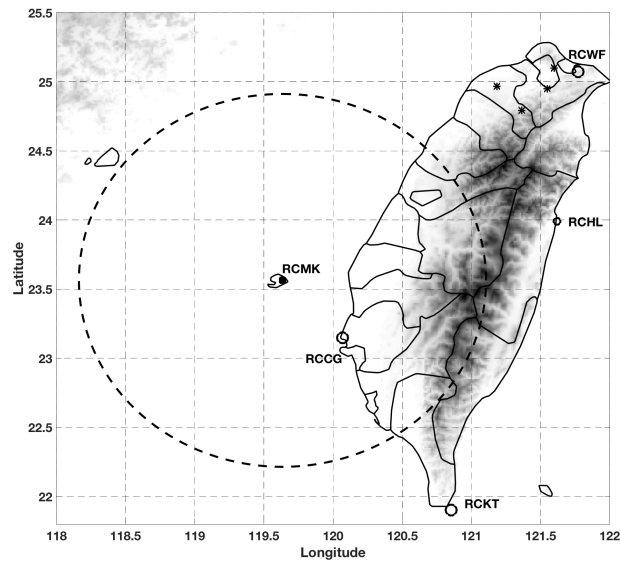


Figure 1. The terrain of Taiwan, the location of a C-band polarimetric radar RCMK (marked with a black square), JWDs (marked with black stars), and four S-band single polarization radar RCGG, RCKT, RCHL, and RCWF (marked with black circles).

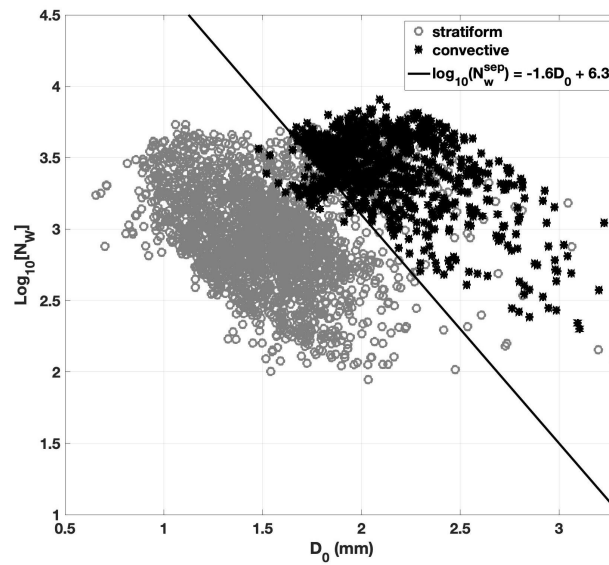


Figure 2. The distribution of $\log_{10}(N_w)$ vs D_0 . The DSD data from stratiform and convective precipitations are presented with gray circles and black stars, and the separator line is shown with a solid line.

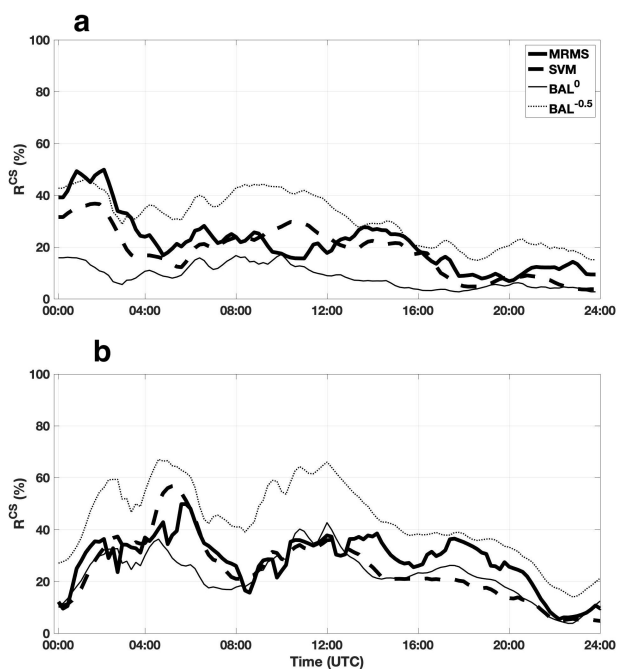


Figure 3. The time series plot of convective cells to stratiform cells ratio (R^{CS}) from 30 August 2011 (A) and 14 June 2012 (B). 24-hours data 0000 UTC–2400 UTC are used in each case. The results from BAL with threshold $T_0 = -0.5$, BAL with threshold $T_0 = 0$, SVM, and MRMS are indicated with thin dashed, thin solid, thick dashed and thick solid lines, respectively.

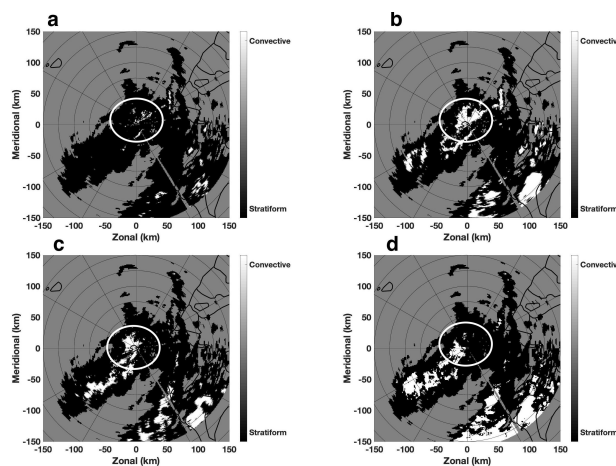


Figure 4. The classification results from BAL^0 (a), $BAL^{-0.5}$ (b), SVM (c) and MRMS (d). The time stamp for BAL^0 , $BAL^{-0.5}$, and SVM is 0303 UTC 30 August 2011, and time stamp for MRMS is 0300 UTC 30 August 2011.

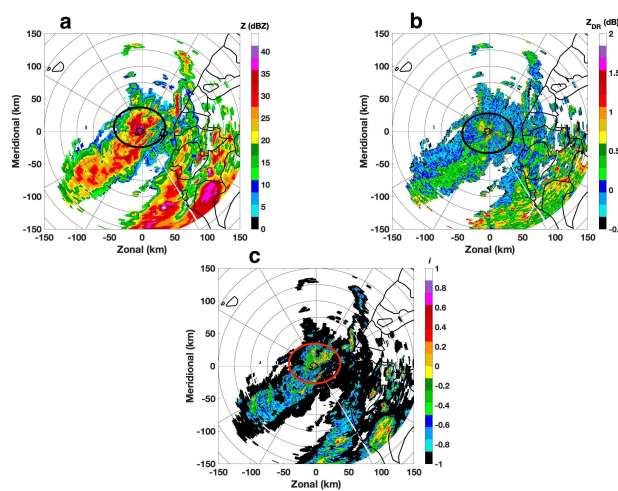


Figure 5. Radar variables of reflectivity (a), differential reflectivity (b), and separation index (c). The radar data was collected by RCMK at 0303 UTC 30 August 2011.

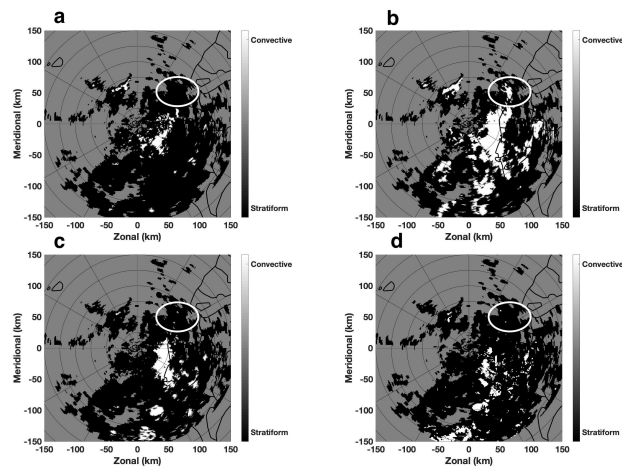


Figure 6. Similar to Figure 4 The results are from 14 June 2012. The time stamp for BAL^0 , $BAL^{-0.5}$, and SVM is 0801 UTC, and time stamp for MRMS is 0800 UTC.

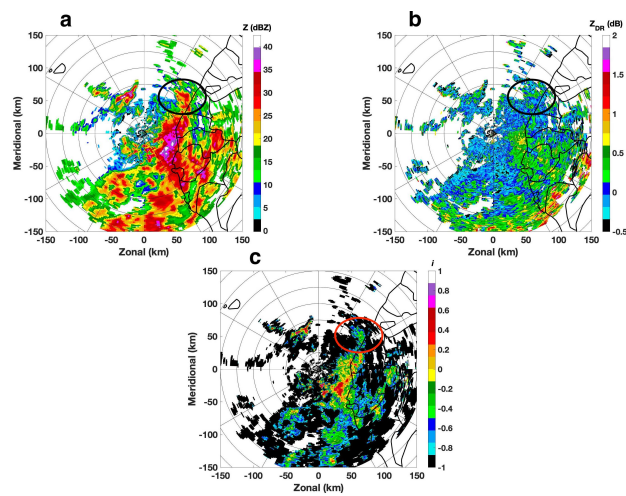


Figure 7. Similar to Figure 5, but radar data from 0801 UTC 14 June 2012.

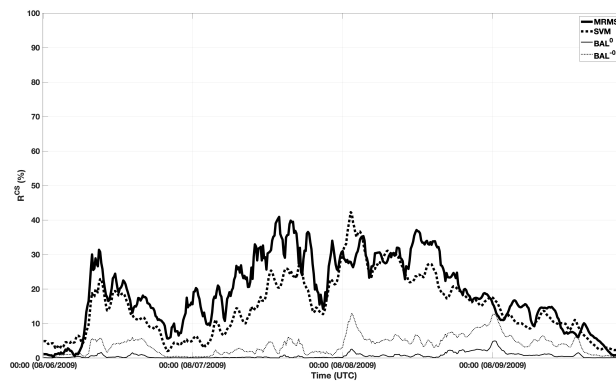


Figure 8. The time series plot of convective cells to stratiform cells ratio (R^{CS}) from 06 09 August 2009. 96-hours data are used in each case. The results from BAL with threshold $T_0 = -0.5$, BAL with threshold $T_0 = 0$, SVM, and MRMS are indicated with thin dashed, thin solid, thick dashed and thick solid lines, respectively.

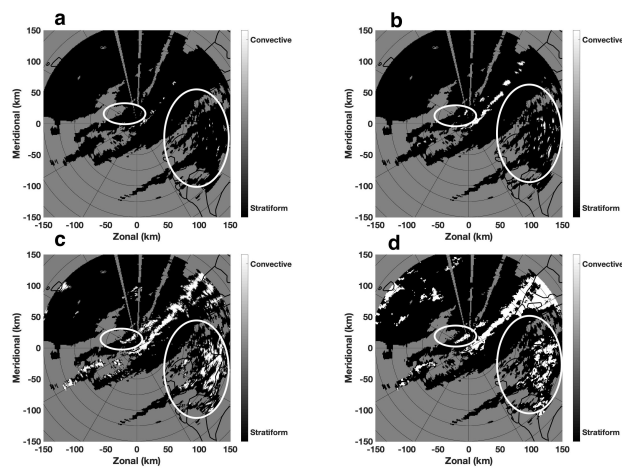


Figure 9. The classification results from BAL^0 (a), $BAL^{-0.5}$ (b), SVM (c) and MRMS (d). The time stamp for BAL^0 , $BAL^{-0.5}$, and SVM is 0402 UTC 9 August 2009, and time stamp for MRMS is 0400 UTC 9 August 2009.

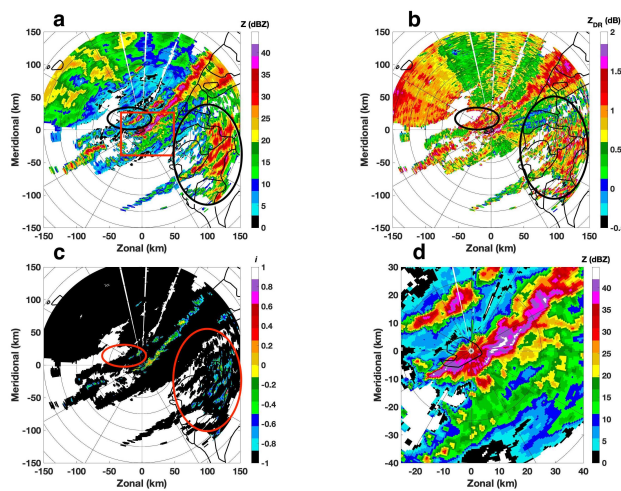


Figure 10. Radar variables of reflectivity (a), differential reflectivity (b), separation index (c), and reflectivity within the red rectangular box in A (d). The radar data was collected by RCMK at 0402 UTC 9 August 2009.



Table 1. The overall performance of these four precipitation events.

R^{CS} scores				
Case	BAL ⁰	BAL ^{-0.5}	SVM	MRMS
30 August 2011	8%	30%	19%	21%
14 June 2012	15%	34%	18%	20%
06~09 August 2009	1%	4%	17%	22%
26 March 2011	0%	0%	0%	0%
Total	4.3%	12.6%	16.6%	20.4%