

## Anonymous Referee #1

This paper describes a new method to obtain high resolution NH<sub>3</sub> columns from satellite by combining oversampling with wind-rotation. A global inventory of point sources is then developed by considering changes in columns for upwind and downwind locations. The science seems sound, the method is novel and the product will be very useful to researchers. Furthermore, the paper was very well written and a pleasure to read. I am happy to recommend it for publication.

Thank you very much for your review, your appreciation and positive assessment of the paper. Thank you also for the two references and corrections to the English – we have followed all suggested changes.

In terms of references, I would suggest adding the following 2 citations:

Page 3: The following is one of the early applications of oversampling: Russell, Ashley R., Lukas C. Valin, Eric J. Bucsela, Mark O. Wenig, and Ronald C. Cohen. "Space-based Constraints on Spatial and Temporal Patterns of NO<sub>x</sub> Emissions in California, 2005–2008." *Environmental science & technology* 44, no. 9 (2010): 3608-3615.

Page 8, Line 1: As far as I am aware, the following introduced rotation first: Valin, L. C., A. R. Russell, and R. C. Cohen. "Variations of OH radical in an urban plume inferred from NO<sub>2</sub> column measurements." *Geophysical Research Letters* 40, no. 9 (2013): 1856-1860.

We have added these references now.

My only other comments are minor proof-reading comments.

Page 1, Line 1: is one \*of\* the primary, or is \*a\* primary

Corrected

Page 1, Line 6: do not use “allows to . . .” in English (see also line 15 and page 10, line 5). Allows needs a subject (allows you to) – which you probably don’t want here. Maybe “enables the”?

After having researched a bit the alternatives, in the end we went for the active form “*Oversampling allows one to increase the spatial resolution of averaged satellite data, beyond what the satellites natively offer.*” (so we added a subject) instead of the passive voice “Oversampling enables the spatial resolution of averaged satellite data to be increased” . We have also went through the rest of the text and fixed similar occurrences.

I’m not much of a fan of “so-called” – but that may be just personal preference.

We removed this from the abstract, and also once in the text.

Page 1, Line 20: what about: “diffuse background with higher concentrations” or something like that?

Corrected

Fig 1 Caption: “measurements” not “measured”

Corrected

Page 10, Line 19: town \*of\* Lanigan

Corrected

Page 10, Line 25: maxima not maximums, \*the\* location

Corrected (here and in two other places)

Page 10, Line 34: fix “with with”

Corrected

Page 11, Line 14: \*by\* varying

Corrected

Page 14, Line 1: This sentence seemed a bit hyperbolic

Yes, we agree and changed “*far beyond*” into “*beyond*”.

Page 14, Line 27: “and that allows” needs fixing. “go-to” sounds a bit clumsy.

We have reformulated these last two sentences now as follows: *For this reason, and to keep track of emerging emission sources, we have setup a website, with an interactive global map, visualizing the distribution, type and time evolution of the different point sources (<http://www.ulb.ac.be/cpm/NH3-IASI.html>). With the help of the community, we hope it can become a useful resource for information on global NH<sub>3</sub> point sources.*

## Anonymous Referee #2

This is a very-well written, and innovative study on how to use statistical techniques on long-time series to identify point sources of NH<sub>3</sub> emissions across the globe. The paper is an extension of an earlier study published in Nature (Van Damme et al., 2018), and shows that adding information on winds derived from ECMWF's ERA re-analysis, allows to further increase the statistical power to discriminate point sources from the background signal. The publication is build up in a logical well-chosen manner, examples (even if not pertaining per se to NH<sub>3</sub>) are well chosen. Somewhat surprising is that in this paper the authors do not estimate source strengths and uncertainties related to the point sources, for reasons not entirely clear to me. In contrast, the earlier Van Damme (2018) did provide such estimates (+uncertainties) so I do not see a strong reason why this paper wouldn't- of course provided that everything works well.

Thank you very much for your positive assessment of the paper and the detailed review. We have addressed all comments below, and where possible updated the text (this includes addressing the comment on mass conservation). The main exception is the comment on providing emission estimates. As we argue below, we think that such an analysis is largely beyond the scope of this paper, whose focus is on the new detection methodology.

In this context my main concerns are following:

- Mass conservation. Figure 3 nicely shows how oversampling and supersampling show enhanced plumes strength (as expressed by the maximum values). Given the short lifetime of NH<sub>3</sub> (likely short due to the abundant presence of sulfate aerosol), one can assume that the average column values in the 60x120 km domain are mostly (entirely?) determined by the local source. Can the authors demonstrate that the domain average (or integrated) NH<sub>3</sub> columns are conservative across cases a) through e). Have such screening been performed for all identified large sources, and what was the result? With other words can we be sure that the algorithm does not artificially add mass, and be used to receive source strengths?

Thank you very much for bringing up this question, which indeed should be addressed in this paper. The answer is not so simple however, as it depends whether it is discussed with respect to the spatial grid (ground truth) or with respect to the measurements. In fact, none of the procedures is mass conserving with respect to the ground truth, due to the finite number of measurements and their coarse resolution. In practice however, mass can be assumed to be conserved. In addition, in measurement space, supersampling is strictly mass conserving in the limit of a large number of iterations (we verified this on the examples of Fig 1, 2, and 3, as a way of verifying that the computer code did not contained any bugs). We have now added the values of the average columns in each subpanel in Figure 3, by means of illustration, and discussed the conservation issue in some length at the end of section 3:

*One useful property of the different procedures is that they all approximately conserve the quantity that is being averaged, i.e. the averaged quantity in each grid is approximately the same as the average quantity in the grid representing the ground truth, given sufficient number of measurements across the entire grid. When the number of measurements is low, this can break down dramatically, as can be seen with the extreme example of single high-value measurement over an isolated point source. When a gridded average is made from this single measurement onto a coarse grid (e.g. 5° × 5°), the entire grid cell containing the measurement will be associated with this high value, thus yielding an overestimation of the reality. A strict conservation is therefore not possible in general, as not enough information is contained in the original measurements to reconstruct the ground truth perfectly, even on average. That being said, supersampling conserves quantity with respect to the original*

*measurements, when the number of iterations is large enough. This is a consequence of the fact that the backprojected measurements converge to the actual measurements, and therefore also their averages. Finally note that wind-rotation does not alter quantity in anyway, as rotation simply redistributes the measurements to different locations on the grid. The average total NH<sub>3</sub> columns are indicated on each subpanel of Fig 3. The average of the ungridded measurements within the considered box equals  $5.23 \times 10^{15} \text{ molec}\cdot\text{cm}^{-2}$ . As can be seen the largest change in average column is caused by the rotation procedure, but this is simply an artifact caused by limiting the average to a square box around a point source (instead of a circle). This example illustrates that in practice, with differences smaller than one percent, the different gridding procedures can be assumed to conserve quantity.*

- This publication is an extension of the previous paper by Van Damme, which makes an important statement on the possible underestimation in inventories like EDGAR of nearly all agricultural and industrial point sources. As this paper is adding even more source, it would imply that the problem could be even aggravated. However, in none of these 2 papers an analysis is made of the potential impacts on regional and global emission budgets. I can easily imagine that the spatial allocation data used in inventories are not realistically representing a 0.1x0.1 degree resolution, but that 'point source' emissions are smeared out over larger areas. While the lack of spatial information in itself a serious problem, it may be less an issue for larger scale model analysis. It would be extremely helpful if the current paper could 1) provide quantitative information on derived emission strengths, similar to the previous paper 2) provide regional/global statistics of the aggregated amounts of annual point source emissions versus those in EDGAR and compared to all emissions, to get a better impression on how these new data would change our view on the global NH<sub>3</sub> budget. I recommend publication of this paper, after taken into account my concerns.

The focus of this paper is on introducing new methodologies for averaging satellite data and for the identification of point sources. In the second part of the paper the strengths of the new approach are demonstrated on NH<sub>3</sub>, and we show that with the new method, we can identify twice the amount of NH<sub>3</sub> point sources compared to regular oversampling. The paper was written specifically with AMT in mind, as its focus is on introducing this new methodology. As such, it already represents a significant body of research, code writing, data analysis and computational effort. In our opinion, the topic and results constitute a well-separated entity that deserves to be published separate from a quantitative derivation, analysis and discussion of emissions. While we agree that what the reviewer asks is important, and can in principle be done, it is not something that we wanted to do in this paper. In addition, doing so would entirely draw away the attention from the focus of the paper, which is on introducing a new detection method for point sources.

Minor comments:

P2 I. 14 what were these adverse effects?

The adverse effects of decreasing NO<sub>x</sub> and SO<sub>2</sub> emissions, is that these have been shown to increase NH<sub>3</sub> emissions and/or concentrations. We have clarified the sentence.

P2 I. 15 It is also related to other pollutant becoming relatively less important.

We do not understand how this comment relates to I15 as here we state that the regulative framework of NH<sub>3</sub> is limited due to the historical relative difficulty in measuring NH<sub>3</sub>.

P2 I. 24 Clarify what is meant with conservative residence time. Van Damme varied between 1, 12 and 48 hours. I presume you meant 48 hours- as this would imply the lowest emission rate? Not for this

paper, but you could get a better handle on the lifetime issue by collaborating with one or more modellers and relate lifetime to column and emission rates.

We meant 12 hours, which is already above the mean value reported (and thus indeed implies that our corresponding emission estimate is a lower bound). We have clarified the sentence by adding this 12 hour value.

P3 l. 16 'reduces spread and contribution of nearby source': I didn't get it. Explain better.

The entire sentence reads: *"As we will also demonstrate, this reduces the overall spread of the transported pollutants and reduces contributions of nearby sources."* At this point of the introduction, this is just anticipating what is about to come. The point is developed in detail in section 3, and so now we explicitly refer to it.

P 3 l. 30 What is meant with a constant underlying distribution? Of what? I didn't get it.

This sentence means that superresolution is only viable when each low resolution image is derived from the same reality, i.e. that the underlying distribution does not change in time. We have replaced "constant" with "an underlying distribution that does not change in time".

p. 5 l. 30 I haven't seen what is the case for NH<sub>3</sub>, only few iteration or many? And why?

Too many iterations result in overfitting on the data, especially for NH<sub>3</sub>, which has a large measurement uncertainty. In practice, we found that three iterations is a good compromise between smoothness and increasing the resolution. This was already partially covered in section 3, point d, but we have now added this sentence: *"Note that in general for NH<sub>3</sub>, 3 iterations of the IBP algorithm seems to offer a good compromise between increasing the resolution of the average, without introducing artefacts related to overfitting."*

p.6 l. 9 As described above the example seems to add 'mass' to with the oversampling/super sampling. The authors should show whether this is the case or not.

At first sight, it might seem that oversampling or supersampling adds mass in this example. This is a visual effect: while the mass clearly increases inside the NH<sub>3</sub> plume, it also seen to decrease outside the plume, in a much larger area. In response to the very first comment of the review, we have added the average column on each subpanel, and added a discussion on mass conservation (see above).

p. 6 l. 31 If understand it well this is discussing the McLinden approach (but not yours). 100 km<sup>2</sup> is quite a large area to calculate background and signal of point sources.

This is correct. 10 x 10 km<sup>2</sup> is large, but definitely not too large, given the lifetime of SO<sub>2</sub>/NH<sub>3</sub>.

p. 8 l. 25 what is meant with an NH<sub>3</sub> map. Concentration/column or emission?

The map, being built from averages of downwind maps of columns, is also a column map; as further explained in that section (see also the example provided in Fig 4).

P 10 l. 3. Noisy map and fictitious sources. How do you know that? Are you still speaking about 10x10 km areas for which oversampling/supersampling would create a noisy map?

It is not the oversampling/supersampling as such that creates a noisy map, but the application of the McLinden et al. approach of calculating differences up and downwind. As explained in the text, the problem comes from larger area sources, which produce a slowly varying NH<sub>3</sub> distribution. Small local differences are amplified in the McLinden et al. approach, which relies on differences between neighbouring column averages.

p. 10 l. 4 It sounds counterintuitive that only looking at downwind concentrations an improved point source map can be improved. What would this mean for the retrieved emission values? Some more theoretical foundation for this approach would be valuable.

From the discussion around figure 3, it can already be intuitively understood that looking at the downwind plume only, the map as described will show large local enhancements around point sources. The map has nothing to do with emission values. The only values that represent a reality are the values just above the point sources, representing the mean value of the downwind plume. As also written in the conclusion: *“However, other than for the identification of point sources, such a map is not easily exploitable, as it is a distorted representation of the reality that favours point sources.”*

p. 10 l. 23 ‘The new NH<sub>3</sub> map’. It would help the reader if you could give a better name to this map, describing what it really is. Something like ‘satellite derived source attribution map’ - it should be made clear that this is a calculated map- not something that is directly observable by the satellite instrument.

In fact, throughout the text we have consistently referred to the map as an “NH<sub>3</sub> point source map”, which we believe is a term that covers quite well the meaning of the map. We have now also used this terminology in this sentence.

p. 11 l. 3 improved performance in geo-allocation of the sources.

We have added “in geo-allocation of the sources” in this sentence.

p. 11 l. 4 point source map? See earlier comment. Use unique name for this product. I think it is more than a point source map (in the sense that there is quantitative information on source strength).

As explained above, we believe that this term is appropriate. It does give some quantitative information just above the point sources, but that quantitative aspect is also not reflected in the term ‘satellite derived source attribution map’ (and in fact the latter term does not express the fact that the map specifically is designed to highlight the point sources).

p. 11 l. 14 0.01x0.01 degree corresponds roughly to 1-1 to 2-2 km? Maybe helpful to give the reader a feeling for this.

Yes that is correct – we have added this info now: “corresponding to a horizontal resolution of the order of 1-2 km”.

p. 11 l. 16 I am wondering if there is not something smarter possible, based on a prescreening of all available IASI observations. If no elevated concentrations are found in any data point it is not likely to be a relevant points source. Possibly for discussion or future work. Or maybe I understood it wrong, and you are describing what you don’t want to do?

You did understand this correctly. Yes, it is definitely possible to be more selective by prescreening, and removing entire regions, but the danger always exist to miss weak point sources (recall that we can detect even very weak point sources, as long as they increase NH<sub>3</sub> locally).

p. 11 | 23 what is meant with a single point source map? A single year? A single source? Clarify.

A single point source map is a map like in Figure 4. For this study, as explained in the beginning of that section, we constructed several ones: *“A few such maps were constructed varying the size of the averaging box, and the applied wind speeds (either in the middle of the boundary layer or at 100 meter).”*

p. 11 | 29/30 This is confusing as statements are made on disagreement with emission inventories.

In this paper we strictly deal with a qualitative detection of point sources, and make no statements on disagreement with emission inventories (unlike in Van Damme et al. , 2018). This sentence reinforces this, stating that the presence of a point source in the catalog should not be seen as a quantitative indicator of its emission strength.

P 13 | 26. What would be the equivalent retrieved concentration (with some reasonable assumption on BL height).

We assume the reviewer means equivalent column. Assuming an approximate conversion (from a standard model of)  $3 \times 10^{15}$  molec/cm<sup>2</sup> per ppb this would be of the order of 1 to  $2 \times 10^{17}$  molec/cm<sup>2</sup>.

### **List of changes to the manuscript**

- A few English corrections (as detailed in the reply to reviewer 1)
- Clarifications to the text (mostly related to comments of the reviewer 2).
- Additions of a large paragraph on mass conservation (see reply to reviewer 2).

Apart from these changes, that are all the results of reviewer comments, a handful of very small improvements to text were introduced (like the removal of two times “much” in the abstract, which was a bit hyperbolic). All changes are shown in the “difference” document below.



# Tracking down global NH<sub>3</sub> point sources with wind-adjusted superresolution

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**Abstract.** As a precursor of atmospheric aerosols, ammonia (NH<sub>3</sub>) is one of the primary gaseous air pollutants. Given its short atmospheric lifetime, ambient NH<sub>3</sub> concentrations are dominated by local sources. In a recent study, Van Damme et al. (2018) have highlighted the importance of NH<sub>3</sub> point sources, especially those associated with feedlots and industrial ammonia production. Their emissions were shown to be largely underestimated in bottom-up emission inventories. The discovery was made possible thanks to the use of oversampling techniques applied on 9 years of global daily IASI NH<sub>3</sub> satellite measurements. Oversampling allows one to increase the spatial resolution of averaged satellite data, beyond what the satellites natively offer. Here, we apply for the first time ~~the so-called~~ superresolution techniques, which are commonplace in many fields that rely on imaging, to measurements of an atmospheric sounder, whose images consist of just single pixels. We demonstrate the principle on synthetic data and on IASI measurements of a surface parameter. Superresolution is a priori less suitable to be applied on measurements of variable atmospheric constituents, in particular those affected by transport. However, by first applying the ~~so-called~~ wind-rotation technique, which was introduced in the study of other primary pollutants, superresolution becomes highly effective to map NH<sub>3</sub> at very high spatial resolution. We show in particular that ~~it allows revealing plume transport in much~~ plume transport can be revealed in greater detail than what was previously thought to be possible. Next, using this wind-adjusted superresolution technique, we introduce a new type of NH<sub>3</sub> map that allows ~~to track~~ tracking down point sources ~~much~~ more easily than the regular oversampled average. On a subset of known emitters, ~~it allows to locate the source~~ the source could be located within a median distance of 1.5 km. We subsequently present a new global point source catalog consisting of more than 500 localized and categorized point sources. Compared to our previous catalog, the number of identified sources more than doubled. In addition, we refined the classification of industries into five categories: fertilizer, coking, soda ash, geothermal and explosive industry; and introduced a new urban category for isolated NH<sub>3</sub> hotspots over cities. The latter mainly consists of African megacities, as clear isolation of such urban hotspots is almost never possible elsewhere due to the presence of a ~~larger diffuse background~~ diffuse background with higher concentrations. The techniques presented in this paper can most likely be exploited in the study of point sources of other short-lived atmospheric pollutants such as SO<sub>2</sub> and NO<sub>2</sub>.

## 1 Introduction

As one of the primary forms of reactive nitrogen,  $\text{NH}_3$  is essential in many of the Earth's biogeochemical processes. It is naturally present along with the nitrogen oxides in the global nitrogen cycle (Canfield et al., 2010; Fowler et al., 2013). However, the discovery of ammonia synthesis through the Haber-Bosch process in the early 1900s has made this vital compound available in almost unlimited quantities, supporting the explosive population growth in the last century (Erisman et al., 2008). As a result, the nitrogen cycle is currently perturbed beyond the safe operating space for humanity, which has led to a host of environmental and societal problems (Steffen et al., 2015). The most obvious direct impact of excess  $\text{NH}_3$  is that on air quality, as atmospheric  $\text{NH}_3$  is one of the main precursors of secondary particulate matter, which has important adverse health impacts (Lelieveld et al., 2015; Bauer et al., 2016). Emissions of the two other important precursors ( $\text{SO}_2$  and  $\text{NO}_x$ ) have thanks to effective legislation drastically decreased in the past twenty years in Europe and North America, and have started to level off in East Asia (Aas et al., 2019; Georgoulias et al., 2018). In contrast, no such decreases are observed or expected in the near future for  $\text{NH}_3$  (e.g. Warner et al. (2017); Sutton et al. (2013)). Unlike the other precursors,  $\text{NH}_3$  emissions are not well regulated, and in fact, the focus on decreasing  $\text{NO}_x$  and  $\text{SO}_2$  has already ~~shown adverse effects on~~ led to increased  $\text{NH}_3$  emissions (Chang et al., 2016) and concentrations (Lachatre et al., 2018; Liu et al., 2018).

The lack of a global regulative framework stems in part from the historical relative difficulty in measuring  $\text{NH}_3$  concentrations. Satellite-based measurements of  $\text{NH}_3$ , which were discovered about a decade ago, offer an attractive complementary means of monitoring  $\text{NH}_3$ . Satellite datasets have now reached sufficient maturity to be directly exploitable, even when the individual measurements come with large and variable uncertainties. Using satellite observations we have recently shown the importance of ammonia point sources on regional scales (Van Damme et al., 2018). In total, over 240 of the world's strongest point sources were identified, categorized and quantified. Somewhat expectedly, many of these point sources (or clusters thereof) were found to be associated with ~~so-called~~ 'concentrated animal feeding operations' (CAFOs) (Zhu et al., 2015; Yuan et al., 2017). However, much more surprisingly was the number of ~~industrial emitters that was found~~ identified industrial emitters, and in particular those associated with ammonia and urea-based fertilizer production. An evaluation of the EDGAR inventory in addition showed that emission inventories vastly underestimate the majority of all point source emissions, even when a conservative average  $\text{NH}_3$  lifetime of 12 hours is assumed in the calculation of the satellite derived fluxes. Industrial processes could therefore be extremely important, especially on a regional scale. Altogether, these findings were made possible due to the availability of the large multiyear  $\text{NH}_3$  dataset (Whitburn et al., 2016; Van Damme et al., 2017) derived from measurements of the IASI spaceborne instrument (Clerbaux et al., 2009), and the oversampling technique that was applied to sufficiently resolve localised emitters.

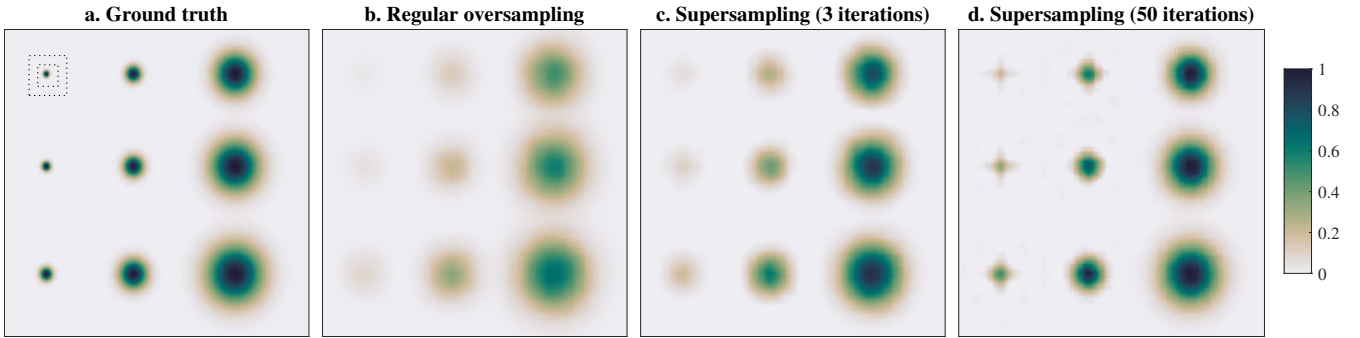
Oversampling techniques applied on measurements of satellite sounders allow ~~to obtain~~ obtaining average distributions of atmospheric constituents at a higher spatial resolution than the original measurements (Sun et al., 2018). They exploit the fact that the footprint on ground of satellite measurements varies in location, size and shape each time the satellite samples an area. When pixels partially overlap, some information becomes available on their (sub-pixel) intersection. A high resolution mapping can however only be obtained by combining typically many hundreds of measurements. A crucial condition on which

oversampling relies, is that the pixel centre and ground instantaneous field of view (GIFOV) of satellite measurements is known with a high accuracy (typically <1 km, as opposed to the coarse spatial resolution of the extent of the satellite pixel which is typically >10 km). Practical implementation of oversampling is relatively straightforward once the footprint is known: a fine subgrid is constructed where the value of each cell of the grid is obtained as the average value of all overlapping GIFOVs.

5 Optionally, the averaging can be weighted, to take into account measurement error, total pixel surface area and spatial response function. We refer to Sun et al. (2018) and Van Damme et al. (2018) for comprehensive reference material on averaging and oversampling, detailed algorithmic descriptions and practical considerations for their implementation.

Oversampling has gradually become commonplace in the field of atmospheric remote sensing, especially in the study of short-lived pollutants such as NO<sub>2</sub> (~~Wenig et al., 2008~~)([Wenig et al., 2008](#); [Russell et al., 2010](#)), SO<sub>2</sub> (Fioletov et al., 2011, 10 2013), HCHO (Zhu et al., 2014) and NH<sub>3</sub> (Van Damme et al., 2014, 2018). The increased spatial resolution ~~allows~~-enables in first instance a much better identification of emission (point) sources, quantification of their emissions (Streets et al., 2013) and study of transport and plume chemistry (de Foy et al., 2009). Oversampling applied to the study of point sources becomes even more useful when wind fields are taken into account. Beirle et al. (2011) showed that binned averaging per wind direction allows simultaneous estimates of both emission strengths and atmospheric residence times. Valin et al. (2013) and Pommier 15 et al. (2013) introduced the wind-rotation technique, whereby each observation is rotated around the presumed point source according to the horizontal wind direction, effectively yielding a distribution where the winds blow in the same direction. As we will also demonstrate ([see Sec. 3](#)), this reduces the overall spread of the transported pollutants and reduces contributions of nearby sources. Combining plume rotation with oversampling has proven to be a very successful technique for the study of NO<sub>2</sub> and SO<sub>2</sub> point sources, leading to massively improved inventories and emission estimates, and better constraints on the 20 atmospheric lifetime of these pollutants (Fioletov et al., 2015; Wang et al., 2015; de Foy et al., 2015; Lu et al., 2015; Liu et al., 2016; McLinden et al., 2016; Fioletov et al., 2016, 2017).

However, as pointed out in Sun et al. (2018), while oversampling offers an increased resolution, it still yields a smoothed representation of the true distributions. There exists a large field of research, collectively referred to as superresolution (Milanfar, 2010) that attempts to construct high resolution images from several, possibly moving or distorted, low resolution representa- 25 tions of the same reality. Oversampling is in essence the simplest way of performing superresolution, but in a way that does not fully exploit the spatial information of the measurements. Superresolution has been applied before in the field of remote sensing of land(cover) (e.g. Boucher et al. (2008); Xu et al. (2017)), but even though theoretically possible, it has not been applied to atmospheric sounding measurements. In this case, the ‘images’ as taken by sounders, are of the lowest resolution, i.e. they correspond to single, uniformly colored pixels. Perhaps the main reason why superresolution has not been attempted 30 before on atmospheric sounders, is that these rely on the fact that the low resolution samples should be derived from ~~a constant underlying distribution~~-[an underlying distribution that does not change in time](#) (de Foy et al., 2009). When this is not the case, the smoothing introduced by oversampling is actually desirable. With the arrival of the wind-rotation technique, most of the variability observed for point source emitters can be corrected for, and therefore superresolution becomes viable for short-lived species as NH<sub>3</sub>.



**Figure 1.** Illustration of the supersampling technique on synthetic data. The left panel depicts an imaginary ground truth, made up of two-dimensional Gaussian distributions, each with a different spread (0.5 to 40 pixels). The rectangles [in panel a](#) indicate the assumed footprint size of the measurements, varying between 7 and 13 pixels. Panel b shows the results of the common oversampling approach applied to 100000 [measured-measurements](#) scattered randomly over the area. Panels c and d provide the results of the supersampling technique after respectively 3 and 50 iterations.

In Sec. 2 we introduce superresolution and demonstrate its effectiveness on measurements of the IASI sounder for a parameter related to (a constant) surface emissivity. Next we illustrate the application of what we coin ‘wind-adjusted supersampling’ on an industrial point source of  $\text{NH}_3$ . In Sec. 3 we use ideas from McLinden et al. (2016) to provide a new type of  $\text{NH}_3$  map, one that is supersampled and wind-corrected at the same time. This map [allows-enables](#) the identification of many new point sources in addition to the ones reported in Van Damme et al. (2018). We performed a detailed global analysis of this new map, which led to the identification and categorization of more than 500 point sources and which we present in Sec. 4.

## 2 Superresolved oversampling

The general superresolution problem does not have a unique solution, as the available low resolution measurements typically do not hold all the required information content (i.e. the problem is underdetermined). It is usually also overdetermined, because of measurement noise and, for our use case especially, because of temporal variability. As a consequence, there is no unique best algorithm, and a myriad of alternatives exist. For this study, we chose the Iterative Back-Projection algorithm (IBP, Irani and Peleg (1993)) as it takes a particular intuitive and simple form for single-pixel satellite observations, and allows addressing the ill-determined nature of the problem. It proceeds as follows. Suppose we have a set of single pixel measurements  $M_0$  of a spatially variable quantity. For the first iteration, the solution of the algorithm corresponds to the regular oversampling, which we will write as  $SS_1 = OS_1 = \mathbf{OS}(M_0)$  ( $SS_i$  stands for the solution of the supersampling obtained in iteration  $i$  and  $\mathbf{OS}$  stands for the oversampling operator). From this oversampled average, we then calculate simulated observations for each of the original individual observations, corresponding to what the instrument would see if the ground truth was  $SS_1$ . The entire set of these simulated measurements will be denoted by  $M_1 = \mathbf{M}(SS_1)$  (with  $\mathbf{M}$  the operator that simulates the measurements). If the oversampled average  $OS_1 = SS_1$  would correspond to the ground truth, then  $M_1$  would clearly coincide with  $M_0$ .

However, as oversampling typically smooths out the observations, this is generally not the case. An improved estimate of the average ( $SS_2$ ), can be obtained by adding  $\mathbf{OS}(M_0 - M_1)$  to the oversampled average, therefore correcting (partially) the observed differences. This process then is repeated to obtain increasingly better estimates. The entire algorithm thus reads:

$$SS_1 = \mathbf{OS}(M_0) = OS_1 \quad \rightarrow M_1 = \mathbf{M}(SS_1) \quad (1)$$

$$5 \quad SS_2 = SS_1 + \mathbf{OS}(M_0 - M_1) = SS_1 + OS_1 - OS_2 \quad \rightarrow M_2 = \mathbf{M}(SS_2) \quad (2)$$

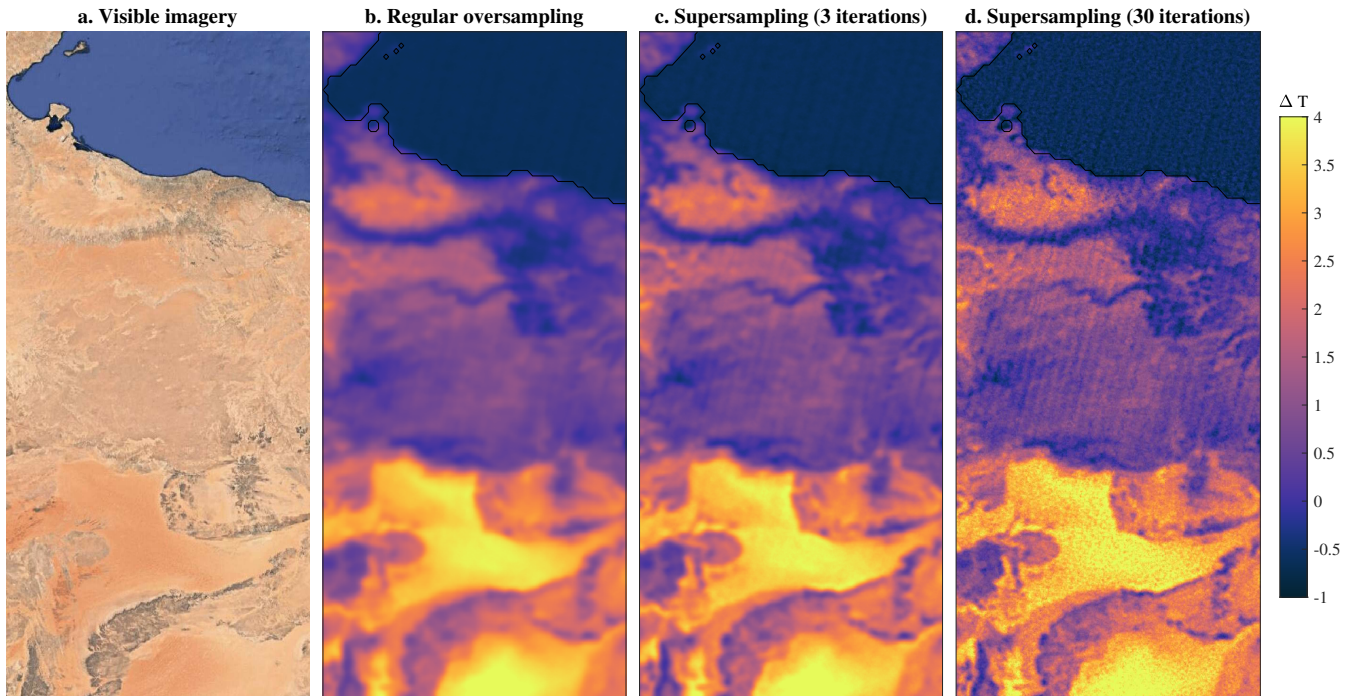
$\vdots$

$$SS_k = SS_{k-1} + \mathbf{OS}(M_0 - M_{k-1}) = SS_{k-1} + OS_1 - OS_k \quad \rightarrow M_k = \mathbf{M}(SS_k) \quad (3)$$

The solution converges to an average that is maximally consistent with the observations, i.e.  $M_0 \approx M_k$  for sufficiently large  $k$  (as shown in Elad and Feuer (1997), IBP converges to the maximum likelihood estimate whereby  $M_0 - M_k$  is minimized).

10 Figure 1 illustrates the algorithm on synthetic data with an idealized ground truth made up of 9 point sources (panel a), with a Gaussian spread between 0.5 and 40 pixels. The measurement footprint was assumed to be variable between 7 and 13 pixels. The  $SS_1$  (panel b),  $SS_3$  (panel c) and  $SS_{50}$  (panel d) averages illustrate well the convergence and strengths of the algorithm, which reproduces most of the point sources near-perfectly, and even partly resolves the smallest feature (compare also with Sun et al. (2018), Figure 8). Some small ringing effects are noticeable though after 50 iterations (best visible on a screen),  
 15 which are the result of the undetermined nature of the problem (Dai et al., 2007).

An example on real data is shown in Figure 2, which shows part of the Sahara Desert and Mediterranean Sea. The quantity on which the oversampling is applied, is the Brightness Temperature Difference (BTD) between the IASI channels at 1157 and 1168  $\text{cm}^{-1}$ . This BTD, located in the atmospheric window, is sensitive to the sharp change in surface emissivity due to the presence of quartz (see Takashima and Masuda (1987), who also illustrate that the relevant feature is not seen in airborne  
 20 dust). Being related to the surface, it can be assumed to be reasonably constant for each overpass of IASI (note that it is not entirely the case: sand dunes do undergo changes over time and surface emissivities can depend on the viewing angle and can be affected by changes in moist content). Comparison with visible imagery (panel a) shows, as expected, that the largest BTD values ( $> 4$  K) are associated with the most sandy areas. The other desert areas exhibit widely varying values, oceans are slightly negative. The oversampled average (panel b) captures most large features, down to about 5 km in size. Recalling that  
 25 the footprint of IASI is a 12 km diameter circle at nadir, and elongates to an ellipse of up to 20 by 39 km at off-nadir angles, this example illustrates well why oversampling is such a powerful technique. However, the additional resolution brought by the supersampling is clear, even after 3 iterations. The smallest features that can be distinguished are about 3–4 km (after 3 iterations, panel c) and 2–3 km (after 30 iterations, panel d) in diameter. That said, with increasing iterations, artifacts starts to appear due to enhancements of noise and the specific sampling of IASI (in particular, stripes parallel to the orbit track  
 30 become apparent). Such overfitting to the data and a sensitivity to outliers, is often seen in maximum likelihood optimizations (Milanfar, 2010). It can therefore be advantageous to stop the algorithm after a few iterations (which can also be required for computational reasons).

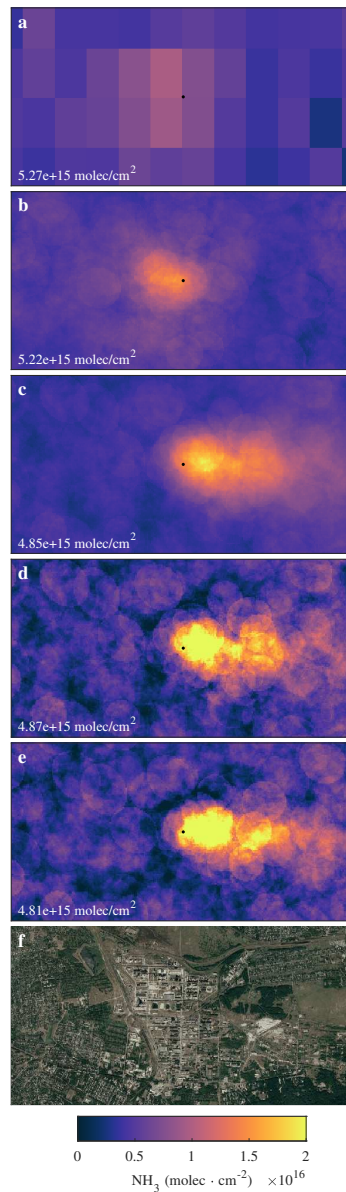


**Figure 2.** Illustration of the IBP superresolution technique on IASI observations of a BTM sensitive to surface quartz. All cloud-free observations of IASI for the period 2007-2018 were used for the averages. Panel a shows the corresponding visible imagery from Google Maps.

### 3 Wind-adjusted supersampling

In this section we illustrate the previously introduced supersampling on a wind-rotated  $\text{NH}_3$  average centered around a point source. The ammonia plant at Horlivka (Gorlovka), Ukraine was chosen as a test case. This plant made the news in 2013 because of the major  $\text{NH}_3$  leak that occurred on 6 August, killing five people and injuring many more. We refer to the Wikipedia article for a detailed description of the event, and a list of related newspaper articles (Wikipedia, 2019). The accident itself was not detected by IASI, but an abrupt drop in the average concentrations after the incident is seen in the satellite observations. In fact, after 2013  $\text{NH}_3$  enhancements are no longer detected at or near the plant. Fig. 3 illustrates the processes of oversampling, supersampling and wind-rotation on IASI data from 2007 to 2013. Each subpanel depicts the  $120 \text{ km} \times 60 \text{ km}$  area centered around the plant, from top to bottom:

- 10 **a. Gridded average** In the regular gridded average, each grid cell is assigned the arithmetic average of all observations whose center falls into the grid cell. This method only gives a faithful representation for larger grid cell sizes, whereas smaller grid sizes provide a higher resolution at the cost of larger noise. Here a grid size of  $0.15^\circ \times 0.15^\circ$  was chosen.  $\text{NH}_3$  enhancements are seen in wide area around the plant, with a maximum (north)east of the plant of  $1 \cdot 10^{16} \text{ molec}\cdot\text{cm}^{-2}$ .



**Figure 3.** Averaging techniques illustrated on the ammonia plant at Horlivka on IASI  $\text{NH}_3$  data between 2007 and 2013. From top to bottom: a. gridded average, b. oversampled average, c. wind-rotated oversampling, with the rotation center located at the maximum of (b), d. wind-rotated supersampling, with the rotation center located at the maximum of (b), e. wind-adjusted supersampling around the assumed source (center of the plant), f. Zoom in (factor 20) over the ammonia plant (data: Google Maps). For each subpanel, the number in the left bottom corner is the total average  $\text{NH}_3$  columnar amount averaged over the entire area.

**b. Oversampled average** Oversampling the daily maps before averaging increases the resolution and reveals the point source nature of the emission, with a maximum close to the plant (around  $1.6 \cdot 10^{16} \text{ molec} \cdot \text{cm}^{-2}$ ).

**c. Wind-rotated oversampling** The wind-rotation technique (Fioletov et al., 2015) (Valin et al., 2013; Fioletov et al., 2015)

consists of rotating the map of daily observations around a presumed point source, and along the direction of the wind direction at that point. The rotation was applied here to align the winds in the  $x$ -direction. Daily horizontal wind fields were taken from the ERA5 reanalysis (ERA5, 2019), and interpolated at an altitude equal to half of the boundary layer height. The  $\text{NH}_3$  average shown in this panel was obtained via oversampling applied to all the daily wind-rotated maps. It is important to note that such a distribution can no longer be interpreted as a geographical map, since each pixel is an average of measurements taken at different places. The only map element that is preserved is the distance to the point source. However, looking at the resulting distribution, the advantages brought by wind-rotation are obvious. Whereas in the normal oversampled average the  $\text{NH}_3$  enhancements are scattered across, aligning the winds significantly enhances both the source and transport (with a maximum of  $2 \cdot 10^{16} \text{ molec}\cdot\text{cm}^{-2}$ ).

**d. Wind-adjusted supersampling (i)** The figure in this panel was obtained from wind-rotated daily maps, as in the previous panel, but this time the average was calculated with 3 iterations of the IBP supersampling algorithm. As explained above, supersampling offers most benefits when the underlying distribution can be assumed reasonably constant, which is in part achieved by aligning the winds. The resolution is further increased, and as the plume is much less smoothed out, maximum observed columns are also much higher ( $3.3 \cdot 10^{16} \text{ molec}\cdot\text{cm}^{-2}$ ). Note that in general for  $\text{NH}_3$ , 3 iterations of the IBP algorithm seems to offer a good compromise between increasing the resolution of the average, without introducing artifacts related to overfitting.

**e. Wind-adjusted supersampling (ii)** In panels c and d, the point source location was taken from Van Damme et al. (2018), where the locations were determined based on the location of the ~~maximums~~ maxima in the oversampled averages. In this last panel, the rotation was applied around the center of the presumed source (the chemical plant). The performance of the wind-rotation is further enhanced, yielding a distribution fully consistent with that of a single emitting point source whose emissions undergo transport in a fixed direction. The part of the plume located furthest from the source is a bit off-axis, which is probably caused by inhomogeneities in the wind fields across the entire scene. This panel also illustrates the sensitivity of the rotation method to small shifts in the location of the center, a fact that we will exploit in the next section.

One useful property of the different procedures is that they all approximately conserve the quantity that is being averaged, i.e. the averaged quantity in each grid is approximately the same as the average quantity in the grid representing the ground truth, given sufficient number of measurements across the entire grid. When the number of measurements is low, this can break down dramatically, as can be seen with the extreme example of a single high-value measurement over an isolated point source. When a gridded average is made from this single measurement onto a coarse grid (e.g.  $5^\circ \times 5^\circ$ ), the entire grid cell containing the measurement will be associated with this high value, thus overestimating reality. A strict conservation is therefore not possible in general, as not enough information is contained in the original measurements to reconstruct the ground-truth perfectly, even on average. That being said, supersampling conserves quantity with respect to the original measurements, when the number of iterations is large enough. This is a consequence of the fact that the backprojected measurements converge to the actual



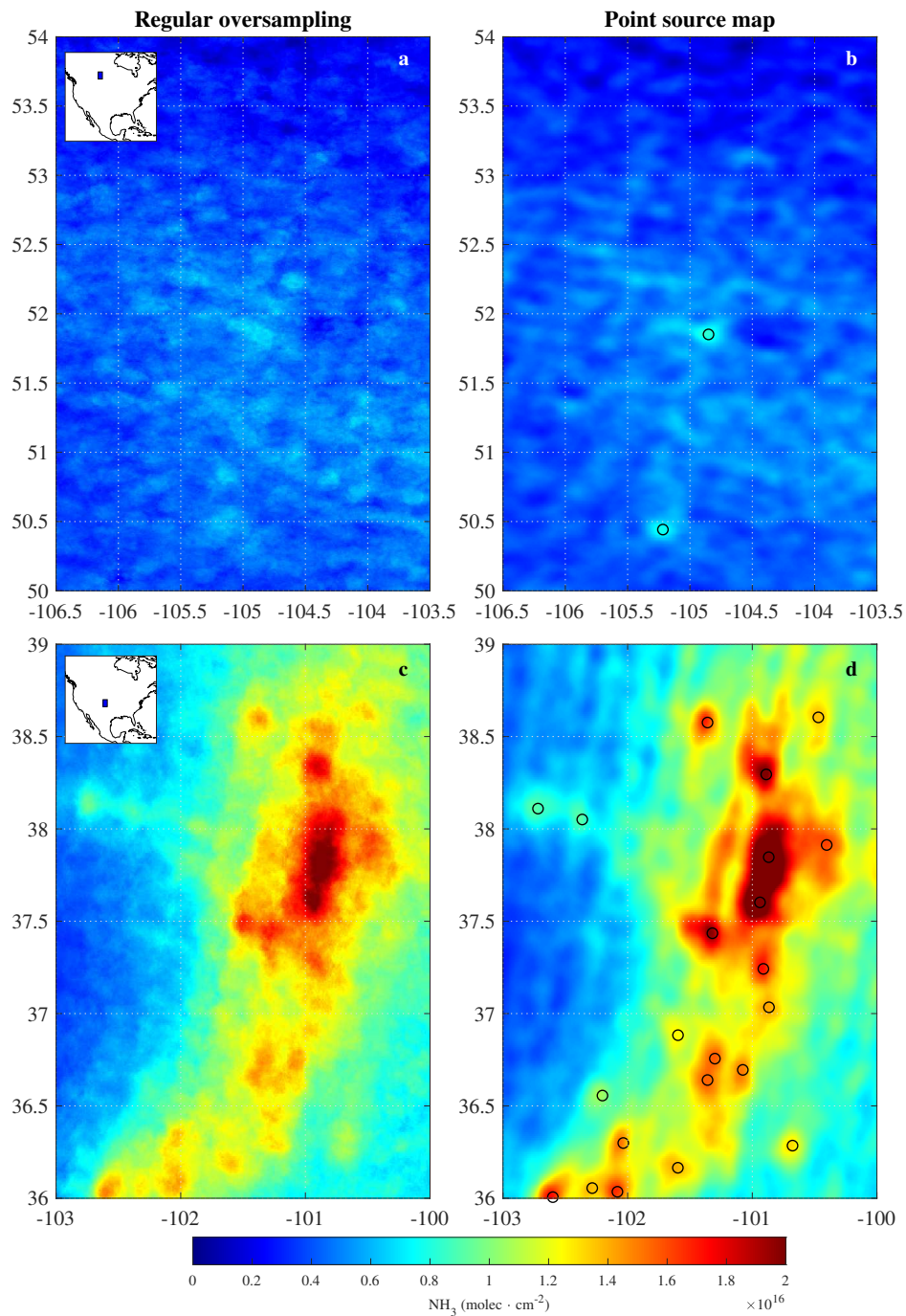
measurements, and therefore also their averages. Finally note that wind-rotation does not alter the grid average, as rotation simply redistributes the measurements to different locations on the grid. The average total  $\text{NH}_3$  columns are indicated on each subpanel of Fig. 3. The average of the ungridded measurements within the considered box equals  $5.23 \cdot 10^{15} \text{ molec}\cdot\text{cm}^{-2}$ . As can be seen the largest change in average column is caused by the rotation procedure, but this is simply an artifact caused by limiting the average to a square box around a point source (instead of a circle). This example illustrates that in practice, with differences smaller than one percent, the different gridding procedures can be assumed to conserve quantity.

#### 4 An $\text{NH}_3$ point source map

Having demonstrated the effectiveness of both the wind-rotation and supersampling approaches in revealing point sources, we are now in a position to introduce a new type of  $\text{NH}_3$  map, specifically designed to track down point sources. It is based on a similar map presented in McLinden et al. (2016) for  $\text{SO}_2$ , but some important differences were introduced here to make it work for  $\text{NH}_3$ . The main idea of McLinden et al. (2016) is to treat each location on Earth as a potential point source and to assign it a value proportional to the downwind (the source) minus upwind (the background) column. In particular, for a given location, a wind-rotated average is constructed first, similar to Fig. 3c. Representative average columns are then obtained downwind and upwind from the potential source (e.g. in boxes of  $10 \times 10 \text{ km}^2$ ). Finally, the difference of the up and downwind average is calculated, and this value is then used to represent the point source column at that specific location. While the method works nicely for  $\text{SO}_2$ , this method proved to be only moderately successful when we applied it to the IASI  $\text{NH}_3$  data. In particular, for those places where area sources dominate or where point sources are clustered over a too large area, local variation in the columns produce a noisy map, with many fictitious point sources.

We found that instead of the differences, the downwind average alone produced a more representative point source map. In addition, applying the method not on the oversampled average, but on the supersampled one, allows ~~to increase~~ increasing the resolution. There are two key advantages offered by a point source map constructed in this way as opposed to a regular oversampled average: brighter point sources and smoother (lower) values over the background. The fact that point sources appear brighter is a direct consequence of the plume concentration achieved with wind-rotated supersampling, as shown in the previous section. Smoothing of the background is accomplished by the process of averaging the area downwind. However, by applying the method not on an oversampled average, but on a supersampled one, this smoothing is partially offset for point sources. The resulting point source map has a similar horizontal resolution as the oversampled map, but with increased averaged columns at the point sources and a smoother background distribution.

Examples over two selected regions in North America are shown in the right panels of Fig. 4. In these examples, the downwind averages were calculated in boxes extending from -5 to 5 km in the  $y$ -direction and 0 to 20 km in the  $x$ -direction. The left panels of the figure correspond to the regular oversampled averages. In panel a, which shows the oversampled average of the southern part of the Saskatchewan province of Canada, no point sources are apparent in the patchy  $\text{NH}_3$  distribution. The corresponding point source map, shown in panel b, is smoother over areas dominated by the diffuse sources, where column variations are close to the measurement uncertainty. In addition, two bright spots are evident, which upon investigation coincide



**Figure 4.**  $\text{NH}_3$  point sources over Canada (top) and the US (bottom). The left panels show maps produced with a regular oversampled average, the right panels depict the corresponding  $\text{NH}_3$  point source maps. The black circles indicate the identified point sources.

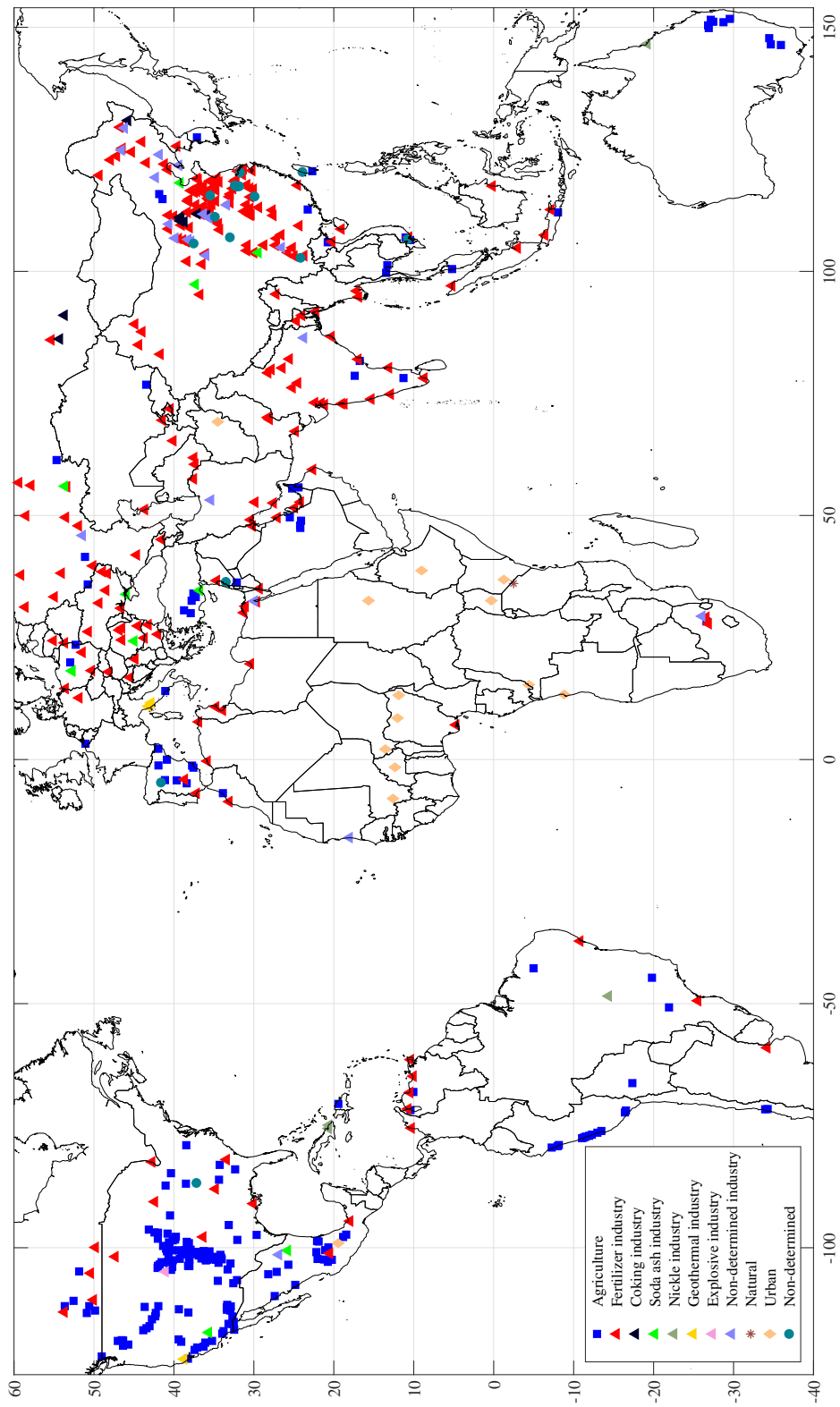
with the location of an ammonia plant (Belle Plaine) and a very large feedlot (> 2 km in length) near the town [of Lanigan](#). Looking back at the oversampled average, even with the advantage of hindsight, these sources can hardly be singled out. Panels c and d show the (south)western part of Kansas, US. It is an area well known for its cattle (Harrington and Lu, 2002). In Van Damme et al. (2018) several point sources associated with feedlots were isolated in Kansas and the rest of the High Plains region, but most of the area was found to be too diffuse to allow identification of individual point sources. The [new-NH<sub>3</sub> point source](#) map facilitates greatly the attribution of these. This is due to the reduction in noise and the fact that the main point sources contrast much more with the background. An added benefit of this is that [the](#) location of the [maximums-maxima](#) in the map is in general closer to the actual emission source than is the case in the oversampled map, making it easier to track down the suspected source with visible imagery, and therefore also to assign and identify the point source.

Displaced [maximums-maxima](#) that are seen in regular averages (wind-adjusted or not) can also be the result of transport, as noted by Van Damme et al. (2018), who found that especially for coastal sites, the shift can be as much as 20 km. The suspected reason is vertical uplift during transport, which makes NH<sub>3</sub> easier to detect and to measure (as can be seen in Fig. 3c) downwind of the source. The way the point source map is setup, corrects for the effects of transport as the columns are partially re-allocated back to their source by assigning the average downwind column to the point source. We have quantified the ability to locate sources on a careful selection of 36 industrial emitters. These were all chosen to be relatively isolated, with no nearby other industries or other sources, so that the actual emitting source is known with [with](#)-confidence. In addition, only small to medium sized plants were chosen (< 1 km across), so that the precise location of the emission is known within a distance of about 500 m. For the regular oversampled map, the sources were found within a median distance of 3.9 km and a mean of  $5.4 \pm 3.7$  km. The furthest distance was 15.2 km. For the point source map, all but five sites were located within 3 km (with a median of 1.5 km, a mean of  $2.1 \pm 1.7$  km and a maximum of 7.3 km), which confirms its improved performance [in geo-allocation of the sources](#).

A final advantage of the point source map is its performance in areas mildly affected by fires (e.g. in South East Asia, Mexico, parts of South America). Certain hotspots due to fires, with a plume center of around 25 km, can look just like actual point sources. In the point source map, these often appear less bright and are blurred out over a wider area, with lower columns as compared to the oversampled average. On the other hand, as before, actual point sources appear brighter, and can emerge from the patchy NH<sub>3</sub> distribution that is characteristic for areas affected by fires. For that reason, comparing the oversampled and the point source map was found to be very useful for singling out point sources, especially in those areas with larger background values. Example point sources are the ammonia plant in Campana (Argentina) and Bastos (Brazil), an important center of egg production. These were previously difficult to detect but are now easily identified.

## 30 **5 Updated point source catalog**

Using the methodology presented in the previous section, NH<sub>3</sub> point source maps of the world ([land only](#)) were constructed at a resolution of  $0.01^\circ \times 0.01^\circ$  ([land-only corresponding to a horizontal resolution of the order of 1–2 km](#)). A few such maps were constructed [by](#) varying the size of the averaging box, and the applied wind speeds (either in the middle of the boundary layer or



**Figure 5.** Global distribution of  $\text{NH}_3$  point sources and their categorization. The total number per category is: Agriculture (215), Coking Industry (9), Explosive Industry (1), Fertilizer Industry (217), Geothermal Industry (3), Non-Determined Industry (21), Nickel Industry (4), Soda ash Industry (11), Natural (1), Non-Determined (15), Urban (13)

at 100 meter). While oversampling and backprojection are computationally not that demanding, we recall that the construction is based on the treating each gridcell of the  $0.01^\circ \times 0.01^\circ$  map as potential point source, and therefore relies on the construction of wind-adjusted supersampled maps like Fig. 3e for each grid cell. Therefore, producing a worldmap at that resolution entails the generation of over 100,000,000 maps similar to Fig. 3e, each at a resolution of 1 km and each using more than 250,000 IASI measurements. A single point source map therefore takes more than a month of computation. We decided to use all the available 2007–2017  $\text{NH}_3$  data both from IASI/Metop A (2007–2017) and IASI/Metop B (2013–2017), which helps to reduce the noise, even though it creates averages which are biased towards the last five years. The maps were then analyzed to provide an update of the point source catalog presented in Van Damme et al. (2018). We refer to it for a detailed description of the methodology for the identification and categorization of the point sources, as we used the same here. In brief, first, the global map is analyzed region per region, in search for  $\text{NH}_3$  hotspots that are no larger than 50 km across and that exhibit localized and concentrated enhancements compatible with a point source or dense cluster of point sources. Areas dominated by fires are excluded from the analysis. Analysis of areas with many sources or large ambient background concentrations, such as the Indo-Gangetic plain, is severely hampered, and reveals only the very large point sources. Isolated point sources in remote areas on the other hand can easily be picked up. The presence of a point source in the catalog should therefore not be seen as a quantitative indicator of its emission strength. Note that in this study we did not attempt to quantify the emission strengths of each. The categorization of the suspected point sources is performed using Google Earth imagery and third party information (mainly inventories of fertilizer plants and online resources). The original categories were: ‘Agriculture’, ‘Fertilizer industry’, ‘Other industry’, ‘Natural’ and ‘Non-Determined’. Here we expanded the number of categories considerably and in particular introduced an urban category and subdivided ‘other industry’ in five new categories as detailed below.

The new point source catalog is listed in Table A1 and illustrated on a world map in Fig. 5. Agricultural point sources were found to be invariably associated with CAFOs. Their number more than doubled, from 83 to 216, largely due to the increased attribution in areas of densely located point sources. For many of the previously tagged ‘source regions’, it was possible to resolve large individual emitters. This was the case in the US (particularly in the geographical region that corresponds to the High Plains Aquifer), Mexico and along the coast of Peru. Also notable are several newly exposed large feedlots in Canada and in eastern Australia. For the first time, agricultural point sources were also identified in China and Russia.

Industrial point sources, as before, are mainly associated with ammonia or urea-based fertilizer production (216, coming from 132) in Europe, North Africa and Asia. Industrial hotspots were categorized as fertilizer industry as soon as evidence was found of fertilizer production, even when there are clearly other industries present that may contribute. Separate categories were introduced for the previously identified soda ash, geothermal, nickel mining and coking industries, as additional examples were found for each. One ammonia plant in the US, associated with the manufacturing of explosives, was also assigned a separate category. Emission over unidentified industries were labeled ‘Non-determined industry’.

An important new category is the ‘Urban’ one. Previously, localized emissions near Mexico City, Bamako (Mali) and Niamey (Niger) were noted. While these hotspots represent diffuse sources, they have been included in the catalog as the extent of the emissions in the relevant cities is sufficiently local, and sufficiently in excess of background values. Thanks to the improved source representation, clear enhancements were found in Kabul (Afghanistan) and 12 African urban agglomerations: Ou-

gadougou (Burkina Faso), Bamako (Mali), Kano (Nigeria), Niamey (Niger), Maiduguri (Nigeria), Khartoum-Omdurman (Sudan), Luanda (Angola), Kinshasa (Congo), Nairobi (Kenya), Addis Ababa (Ethiopia), Bamako (Mali) and Kampala (Uganda). Especially in Asia, atmospheric  $\text{NH}_3$  is found in excess over most megacities, and with much larger columns than found in these African megacities. However, because of the much larger background columns, and much denser clusters of cities, these could not be singled out as was the case in Africa. Apart from industry, known urban sources of  $\text{NH}_3$  include emissions from vehicles, human waste (waste treatment, sewers), biological waste (garbage containers) and domestic fires (including waste incineration) (Adon et al., 2016; Sun et al., 2017; Reche et al., 2015). At least the hotspot at Bamako is consistent with in situ measurements (Adon et al., 2016), that report year-round very high concentrations, between 28–73 ppb on a monthly averaged basis. Local conditions surely are key to explain why some cities in Africa exhibit much larger concentrations than others. Johannesburg (South Africa) for instance blends in completely in the background, with ambient values almost not larger than in the rest of South Africa. While outside of the scope of this paper, there is no doubt that the IASI  $\text{NH}_3$  data could be further exploited to understand better the driving factors of urban emission on a global scale.

Other than at Lake Natron (Clarisse et al., 2019), no other natural  $\text{NH}_3$  hotspots have been identified. For a number of presumed point sources no likely source could be attributed; however given their location (central US, Middle East, East Asia), these are most likely anthropogenic.

## 6 Conclusions

Oversampling is a technique now commonplace in the field of atmospheric sounding for achieving hyperresolved spatial averages, far beyond what the satellites natively offer. There is a class of algorithms referred to as superresolution that goes beyond oversampling, but these have until now only been applied to measurements of satellite imagers for surface parameters. Here, we have shown that it is a viable method that can also be applied to the single pixel images taken by atmospheric sounders for short lived gases. We demonstrated this with measurements of a quartz emissivity feature over the Sahara Desert, for which a spatial resolution down to 2–3 km could be achieved.

Superresolution is a priori less suitable for measurements of atmospheric gases because of variations in their distribution, related to variations in transport. However, by aligning the winds around point source emitters, much of this variability can be removed. In Sec. 3, we have shown the advantage of applying IBP superresolution on such wind-corrected data. The resulting averaged plumes originating from point sources not only reveal much more detail, maximum concentrations and gradients are also much larger, and presumably more realistic. Studies of atmospheric lifetime (e.g. Fioletov et al. (2015)), which rely on the precise shape of the dispersion, could potential benefit from this increase in accuracy.

Wind-adjusted superresolution images around point sources form the basis of the  $\text{NH}_3$  point source map, which is an  $\text{NH}_3$  average that simultaneously corrects for wind transport, accentuates point sources and smooths area sources. It was inspired by the  $\text{SO}_2$  ‘difference’ map presented in McLinden et al. (2016), but as we do not look at differences, the  $\text{NH}_3$  map still looks like an  $\text{NH}_3$  total column distribution. However, other than for the identification of point sources, such a map is not easily exploitable, as it is a distorted representation of the reality that favors point sources. In depth analysis allowed us to perform a

major update of the global catalog of point sources presented in Van Damme et al. (2018), with more than 500 point sources identified and categorized. As a whole, this study further highlights the importance of point sources on local scales. The world map shows distinct patterns, with agricultural point sources completely dominant in America, in contrast to Europe and Asia where industrial point sources are prevalent. In Africa, NH<sub>3</sub> hotspots are mainly found near urban agglomerations.

- 5 While the point source catalog was established with a great deal of care, given its size, mistakes will inevitably be present, both in the localization of the point sources (due to e.g. noise in the data or NH<sub>3</sub> in transport) and in the categorization. Improvements can probably best be achieved with feedback from the international community, with complementary knowledge on regional sources. For this reason, and to keep track of emerging emission sources, we have setup ~~an interactive a~~ website, with ~~the catalog and that allows to visualize the distribution and type of the~~ [an interactive global map, visualizing the](http://www.ulb.ac.be/cpm/NH3-IASI.html)  
 10 [distribution, type and time evolution of the different](http://www.ulb.ac.be/cpm/NH3-IASI.html) point sources (<http://www.ulb.ac.be/cpm/NH3-IASI.html>). With the help of the community, we hope it can ~~evolve as a go-to~~ [become a useful](http://www.ulb.ac.be/cpm/NH3-IASI.html) resource for information on global NH<sub>3</sub> point sources.

*Data availability.* The IASI NH<sub>3</sub> product is available from the Aeris data infrastructure (<http://iasi.aeris-data.fr>). It is also planned to be operationally distributed by EUMETCast, under the auspices of the Eumetsat Atmospheric Monitoring Satellite Application Facility (AC-SAF ; <http://ac-saf.eumetsat.int>).

## 15 Appendix A: Point Source Catalog

**Table A1.** Updated point source catalog. The categories are abbreviated as: A = Agriculture, CI = Coking Industry, EI = Explosive Industry, FI = Fertilizer Industry, GI = Geothermal Industry, NDI= Non-Determined Industry, NI = Nickle Industry, SI = Soda ash Industry, N = Natural, ND = Non-Determined, U = Urban.

Country	Lat	Lon	Name	Type	Country	Lat	Lon	Name	Type
Australia	-35.92	146.37	Redlands	A	Australia	-34.66	146.49	Merungle Hill	A
Australia	-34.46	147.77	Springdale	A	Australia	-29.52	151.72	Emmaville	A
Australia	-28.74	151.04	Beebo	A	Australia	-27.46	151.13	Grassdale	A
Australia	-27.15	151.54	Moola	A	Australia	-26.90	149.84	Morabi	A
Australia	-26.82	150.40	Greenswamp	A	Belarus	52.28	23.52	Malyja Zvody	A
Belgium	51.06	3.25	Wingene	A	Bolivia	-17.34	-66.28	Cochabamba	A
Brazil	-21.93	-50.77	Bastos	A	Brazil	-19.79	-44.69	Carioca	A
Brazil	-4.98	-42.76	Teresina	A	Canada	49.03	-122.28	Abbotsford	A
Canada	49.86	-112.87	Picture Butte	A	Canada	50.59	-111.96	Brooks	A
Canada	50.90	-113.37	Stangmuir	A	Canada	51.85	-104.85	Lanigan	A
Canada	52.56	-110.88	Hughenden-Czar	A	Canada	53.65	-111.97	Norma	A
Chile	-34.26	-71.60	Las Chacras	A	Chile	-33.95	-71.64	La Manga	A
China	41.42	114.81	Erdao Canal, Zhangbei (HE)	A	China	41.84	115.83	Xingtai Yong, Guyuan (HE)	A
China	23.26	112.67	Lianhuaazhen (HI)	A	Dominican Republic	19.43	-70.54	Moca - Tamboril	A
Emirates	24.41	55.74	Masaken	A	Emirates	25.21	55.53	Dubai	A
India	11.29	78.14	Namakkal	A	India	16.75	81.65	Tanaku	A
India	17.39	78.61	Hyderabad	A	Indonesia	-8.04	112.07	Blitar City	A
Italy	41.08	14.04	Cancelo ed Arnone	A	Jordania	32.13	36.27	Dhlail Sub-District	A
Kazakhstan	43.47	76.78	North of Almaty	A	Malaysia	5.21	100.48	Sungai Jawi	A
Marocco	33.87	-6.88	Temara	A	Mexico	18.45	-97.31	Tehuacan	A
Mexico	18.84	-97.80	Tochtepec	A	Mexico	20.25	-102.47	Vista Hermosa de Negrete	A
Mexico	20.68	-99.93	Ezequiel Montes	A	Mexico	20.75	-102.88	Acatic	A
Mexico	21.08	-100.49	San Antonio - La Canlea	A	Mexico	21.21	-102.41	San Juan de Los Lagos	A
Mexico	21.89	-98.73	Tampaon	A	Mexico	22.03	-102.30	Aguascalientes	A
Mexico	22.10	-98.62	Loma Alta	A	Mexico	22.18	-100.90	San Luis Potosi	A

Country	Lat	Lon	Name	Type	Country	Lat	Lon	Name	Type
Mexico	24.82	-107.61	Culiacancito	A	Mexico	25.69	-103.48	Torreón	A
Mexico	27.15	-104.94	Jiménez	A	Mexico	27.39	-109.89	Obregon	A
Mexico	28.20	-105.43	Delicias	A	Mexico	32.46	-116.80	La Presa	A
Mexico	32.51	-115.22	Puebla	A	Mexico	32.61	-115.63	Santa Isabel	A
Peru	-16.54	-71.89	Vitor District	A	Peru	-16.42	-72.28	Majes	A
Peru	-13.46	-76.09	Alto Laran District	A	Peru	-12.97	-76.43	Quilmana District	A
Peru	-12.28	-76.83	Punta Hermosa	A	Peru	-11.94	-77.07	Carabayllo District	A
Peru	-11.53	-77.23	Huaral District	A	Peru	-11.30	-77.42	Irrigacion Santa Rosa	A
Peru	-11.05	-77.56	Tiroles	A	Peru	-8.15	-78.97	Trujillo	A
Peru	-7.99	-79.20	Chiquitoy	A	Peru	-7.25	-79.48	Guadalupe	A
Poland	52.97	19.89	Biezun	A	Russia	50.78	35.87	Rakitnoye	A
Russia	51.12	41.51	Novokhoporskiy	A	Russia	54.67	61.35	Klyuchi	A
Saudi Arabia	24.10	48.92	Haradh	A	Saudi Arabia	24.19	47.45	Al Qitar	A
Saudi Arabia	24.22	47.93	At Tawdihyah	A	Saudi Arabia	25.50	49.61	Al Hofuf	A
South Africa	-26.62	28.28	Ratanda	A	South Korea	37.12	127.44	Anseong - Icheon	A
Spain	37.56	-1.66	Lorca - Puerto Lumbrecas	A	Spain	37.73	-1.24	Canovas	A
Spain	38.40	-4.87	El Viso - Pozoblanco	A	Spain	39.65	-4.27	Menasalbas	A
Spain	41.12	-4.21	Mozoncillo	A	Spain	41.95	2.21	Vic - Manlleu	A
Spain	40.87	-0.03	La Portellada	A	Spain	41.93	-1.21	Tauste	A
Taiwan	22.69	120.52	Pingtung	A	Thailand	13.30	101.26	Nong Irun	A
Thailand	13.46	99.70	Thung Luang - Chom Bueng	A	Turkey	37.26	33.29	Alacati	A
Turkey	37.57	34.02	Eregli	A	Turkey	37.78	32.53	Konya	A
Turkey	37.90	29.99	Basmakci	A	Turkey	38.73	30.57	Afyonkarahisar	A
USA	34.36	-86.07	Hopewell (AL)	A	USA	32.68	-114.08	Wellton (AZ)	A
USA	32.88	-112.02	Stanfield (AZ)	A	USA	32.94	-112.87	Gila Bend (AZ)	A
USA	33.33	-111.70	Higley (AZ)	A	USA	33.37	-112.70	Palo Verde (AZ)	A
USA	33.39	-112.23	Avondale (AZ)	A	USA	33.17	-115.59	Calipatria (CA)	A
USA	33.79	-117.09	San Jacinto (CA)	A	USA	33.96	-117.60	Chino (CA)	A
USA	35.23	-119.09	Bakersfield (CA)	A	USA	36.08	-119.43	Tulare (CA)	A
USA	36.29	-120.28	Coalinga - Huron (CA)	A	USA	37.09	-120.44	Chowchilla (CA)	A
USA	37.41	-120.93	Hilmar (CA)	A	USA	38.24	-122.73	Petaluma (CA)	A
USA	38.05	-102.36	Granada (CO)	A	USA	38.07	-103.76	Rocky Ford (CO)	A
USA	38.11	-102.72	Lamar (CO)	A	USA	38.23	-103.72	Ordway (CO)	A
USA	39.27	-102.27	Burlington (CO)	A	USA	40.13	-102.57	Eckley - Yuma (CO)	A
USA	40.21	-103.78	Fort Morgan (CO)	A	USA	40.22	-103.96	Wiggins (CO)	A
USA	40.36	-104.53	Greeley (CO)	A	USA	40.55	-103.30	Atwood (CO)	A
USA	40.78	-102.94	Iliff-Crook (CO)	A	USA	32.34	-83.94	Montezuma (GA)	A
USA	34.27	-83.03	Royston (GA)	A	USA	43.13	-96.29	Sioux county (IA)	A
USA	42.26	-113.36	Malta (ID)	A	USA	42.33	-114.05	Oakley (ID)	A
USA	42.75	-114.65	Jerome - Wendell (ID)	A	USA	43.05	-116.07	Grand View (ID)	A
USA	43.43	-116.48	Melba (ID)	A	USA	43.66	-112.11	Roberts (ID)	A
USA	43.83	-116.90	Parma (ID)	A	USA	38.49	-86.88	Jasper (IN)	A
USA	41.04	-87.26	Fair Oaks (IN)	A	USA	37.03	-100.87	Liberal (KS)	A
USA	37.24	-100.91	Seward county (KS)	A	USA	37.44	-101.32	Ulysses (KS)	A
USA	37.60	-100.94	Haskell county (KS)	A	USA	37.85	-100.87	Garden City (KS)	A
USA	37.91	-100.40	Cimarron (KS)	A	USA	38.12	-99.07	Larned (KS)	A
USA	38.30	-100.89	Scott county (KS)	A	USA	38.39	-98.80	Great Bend (KS)	A
USA	38.58	-101.36	Wichita county (KS)	A	USA	38.60	-100.47	Shields (KS)	A
USA	39.07	-100.84	Oakley (KS)	A	USA	39.41	-100.52	Hoxie (KS)	A
USA	39.76	-97.76	Scandia (KS)	A	USA	39.85	-98.32	Burr Oak (KS)	A
USA	40.48	-93.39	Lucerne (MO)	A	USA	40.15	-98.50	Cowles (NE)	A
USA	40.22	-100.54	McCook (NE)	A	USA	40.57	-99.52	Westmark (NE)	A
USA	40.62	-98.90	Newark (NE)	A	USA	40.67	-101.63	Chase county (NE)	A
USA	40.76	-99.72	Lexington (NE)	A	USA	40.79	-97.11	Seward county (NE)	A
USA	40.87	-100.74	Wellfleet (NE)	A	USA	40.98	-100.19	Gothenburg (NE)	A
USA	41.35	-99.63	Broken Bow (NE)	A	USA	41.54	-102.96	Bridgeport (NE)	A
USA	41.78	-103.43	Minatare (NE)	A	USA	41.99	-96.93	Wisner (NE)	A
USA	42.00	-103.71	Mitchell (NE)	A	USA	42.01	-98.15	Elgin (NE)	A
USA	42.43	-96.86	Allen (NE)	A	USA	32.10	-106.63	Vado (NM)	A
USA	32.57	-107.27	Hatch (NM)	A	USA	32.92	-103.23	Lovington (NM)	A
USA	33.28	-104.44	Dexter - Rosswell (NM)	A	USA	34.51	-106.78	Veguita (NM)	A
USA	39.08	-119.26	Lyon county (NV)	A	USA	39.41	-118.77	Fallon (NV)	A
USA	40.36	-84.73	Coldwater (OH)	A	USA	36.56	-102.20	Griggs (OK)	A
USA	36.64	-101.36	Guymon (OK)	A	USA	36.70	-101.08	Adams (OK)	A
USA	36.76	-101.30	Optima (OK)	A	USA	36.88	-101.60	Hough (OK)	A
USA	45.72	-119.83	Boardman (OR)	A	USA	29.65	-97.37	Gonzales (TX)	A
USA	32.07	-98.39	Dublin (TX)	A	USA	33.14	-95.35	Hopkins county (TX)	A
USA	34.01	-102.37	Amherst (TX)	A	USA	34.09	-102.00	Hale Center (TX)	A
USA	34.19	-101.45	Lockney (TX)	A	USA	34.42	-103.08	Farwell (TX)	A
USA	34.50	-102.41	Castro (TX)	A	USA	34.63	-101.86	Happy - Tulia (TX)	A
USA	34.75	-102.46	Hereford (TX)	A	USA	35.02	-102.36	Deaf Smith (TX)	A
USA	35.07	-102.04	Bushland (TX)	A	USA	35.55	-100.75	Pampa (TX)	A



Country	Lat	Lon	Name	Type	Country	Lat	Lon	Name	Type
USA	35.85	-102.45	Hartely (TX)	A	USA	36.01	-102.60	Dalhart (TX)	A
USA	36.03	-102.08	Cactus (TX)	A	USA	36.05	-102.28	Dalhart (east) (TX)	A
USA	36.16	-101.60	Morse (TX)	A	USA	36.28	-100.68	Ochiltree (TX)	A
USA	36.30	-102.03	Stratford (TX)	A	USA	38.19	-113.26	Milford (UT)	A
USA	39.38	-112.60	Delta (UT)	A	USA	41.95	-111.97	Trenton (UT)	A
USA	38.45	-79.00	Bridgewater (VA)	A	USA	46.35	-119.00	Eltopia (WA)	A
USA	46.37	-120.07	Yakima Valley - Sunnyside (WA)	A	USA	46.52	-118.94	Mesa (WA)	A
USA	47.01	-119.09	Warden (WA)	A	USA	42.04	-104.14	Torrington (WY)	A
Venezuela	10.05	-68.09	Tocuyito - Barrerita	A	Venezuela	10.41	-71.79	La Concepcion	A
Vietnam	10.46	106.42	Tan An	A	Vietnam	11.02	106.94	Bien Hoa	A
Vietnam	20.76	105.95	Khoai Chau	A	China	45.77	130.91	Qitaihe (HL)	CI
China	38.72	110.17	Jinjiezhen (SN)	CI	China	39.11	110.74	Xinminzhen, Fugu (SN)	CI
China	39.18	110.31	Sunjiachazhen, Shenmu (SN)	CI	China	39.27	111.07	Shishanzecun, Fugu (SN)	CI
China	35.90	111.44	Xiangfen (SX)	CI	China	37.08	111.79	Xiaoyi (SX)	CI
Russia	53.72	91.01	Chernogorsky	CI	Russia	54.30	86.15	Bachatsky	CI
USA	41.08	-104.90	Cheyenne (WY)	EI	Algeria	35.83	-0.32	Arzew	FI
Algeria	36.90	7.72	Annaba	FI	Argentina	-34.19	-59.03	Campana	FI
Bangladesh	22.27	91.83	Chittagong	FI	Bangladesh	24.01	90.97	Ashuganj	FI
Bangladesh	24.68	89.85	Tarakandi	FI	Belarus	53.67	23.91	Grodno	FI
Brazil	-25.53	-49.40	Curitiba	FI	Brazil	-10.79	-37.18	Laranjeiras	FI
Bulgaria	42.02	25.66	Dimtrovdgrad	FI	Bulgaria	43.21	27.63	Devnya	FI
Canada	42.76	-82.41	Courtright	FI	Canada	49.82	-99.92	Brandon	FI
Canada	50.07	-110.68	Medicine Hat	FI	Canada	50.44	-105.22	Belle Plaine	FI
Canada	53.73	-113.17	Fort Saskatchewan	FI	China	30.05	116.83	Xiangyuzhen (AH)	FI
China	30.50	117.02	Anqing (AH)	FI	China	30.88	117.74	Tongling (AH)	FI
China	32.43	118.44	Lai'an (AH)	FI	China	32.63	116.97	Huainan (AH)	FI
China	32.93	115.84	Fuyang (AH)	FI	China	33.06	115.30	Linquan (AH)	FI
China	24.54	117.64	Longwen (FJ)	FI	China	36.06	103.59	Xigu - Lanzhou (GS)	FI
China	38.38	102.07	Jinchang (GS)	FI	China	24.34	109.35	Luzhou (GX)	FI
China	25.18	104.84	Xingyi - Qianxinan (GZ)	FI	China	26.61	107.48	Fuquan (GZ)	FI
China	27.17	106.74	Xiaozhaibazhen (GZ)	FI	China	27.29	105.34	Yachizhen (GZ)	FI
China	32.97	114.05	Zhumadian (HA)	FI	China	34.79	114.42	Kaifeng (HA)	FI
China	35.25	113.74	Xinxiang (HA)	FI	China	35.55	114.59	Huaxian (HA)	FI
China	30.34	111.64	Zhijiang (HB)	FI	China	30.43	115.25	Xishui (HB)	FI
China	30.45	111.49	Xiaoting (HB)	FI	China	30.50	112.88	Qianjiang (HB)	FI
China	30.78	111.82	Dangyang (HB)	FI	China	30.94	113.66	Yingcheng - Yunmeng (HB)	FI
China	31.22	112.29	Shiqiaoyizhen (HB)	FI	China	37.87	116.55	Dongguang (HE)	FI
China	38.13	114.74	Shijiazhuang - Gaocheng (HE)	FI	China	46.46	125.20	Xinghuacun (Longfen) (HL)	FI
China	46.75	129.54	Haolianghe (HL)	FI	China	47.17	123.63	Hulan Ergi (HL)	FI
China	27.59	111.45	Heqing (HN)	FI	China	27.71	112.54	Xianxiang (HN)	FI
China	29.40	113.11	Yueyang (HN)	FI	China	35.76	114.96	Puyang (HN)	FI
China	44.01	126.56	Jilin (JL)	FI	China	45.31	124.47	Changshan (JL)	FI
China	31.32	121.01	Kunshan (JS)	FI	China	31.43	119.83	Yixing (JS)	FI
China	31.98	120.51	Zhangjiagang, Suzhou Shi, (JS)	FI	China	32.22	118.77	Dachang - Nanjing (JS)	FI
China	34.36	118.31	Xinyi (JS)	FI	China	34.60	119.13	Lianyungang (JS)	FI
China	34.75	116.63	Fengxian (JS)	FI	China	40.76	120.83	Huludao (Liaoning)	FI
China	41.20	121.98	Shuangtaizi, Panjin (LS)	FI	China	38.07	108.98	Nalin river (NM)	FI
China	39.08	109.47	Tuke Sumu (NM)	FI	China	39.43	106.70	Wuda - Hainan - Huinong (NM)	FI
China	40.04	111.28	Lamawanzhen (NM)	FI	China	40.69	108.70	Wulashan (NM)	FI
China	40.70	111.50	Hohhot (NM)	FI	China	43.45	122.25	Multizhen (NM)	FI
China	47.94	122.83	Zalatun (NM)	FI	China	49.36	119.67	Hulun Buir (NM)	FI
China	38.46	106.07	Yinchuan (NX)	FI	China	38.89	106.42	Shizuishan (NX)	FI
China	36.48	101.49	Huangzhong (QH)	FI	China	36.75	95.25	Chaerhan Salt Lake (QH)	FI
China	28.75	105.38	Naxi (SC)	FI	China	30.00	103.83	Dongpo (SC)	FI
China	30.84	105.35	Shehong (SC)	FI	China	30.90	104.25	Deyang - Guanghan - Xindu (SC)	FI
China	34.91	118.48	Linyi (SD)	FI	China	35.00	117.24	Mushizhen, Tengzhou (SD)	FI
China	35.51	118.51	Yinan (SD)	FI	China	35.87	116.43	Dongping (SD)	FI
China	36.30	117.52	Yanglizhen (SD)	FI	China	36.35	116.15	Liaocheng (SD)	FI
China	36.90	117.43	Shuizhaizhen (SD)	FI	China	36.95	118.77	Shouguang (SD)	FI
China	37.09	119.03	Houzhen (Shouguang) (SD)	FI	China	37.16	116.38	Pingyuan (SD)	FI
China	37.46	116.22	Decheng (SD)	FI	China	34.28	108.53	Xingping (SN)	FI
China	34.41	109.77	Guapozhen (SN)	FI	China	35.10	110.72	Xian de Linyi (SX)	FI
China	35.45	112.60	Beiliuzhen (SX)	FI	China	35.66	112.84	Zezhou - Gaoping (SX)	FI
China	36.35	113.31	Lucheng (SX)	FI	China	36.37	112.87	Tunliu (SX)	FI
China	36.60	111.70	Huozhou (SX)	FI	China	37.27	113.62	Pingsongxiang (SX)	FI
China	37.55	112.18	Jiaocheng (SX)	FI	China	38.33	112.11	Jingle (SX)	FI
China	41.72	83.03	Kuqa (XJ)	FI	China	43.99	87.64	Midong - Fukang (XJ)	FI
China	44.40	84.95	Kuytun (XJ)	FI	China	44.88	89.21	Wucaiwai (XJ)	FI
China	23.73	103.21	Kaiyuan (YN)	FI	China	24.97	103.13	Yiliang (YN)	FI
China	25.76	103.86	Huashan (YN)	FI	China	30.23	120.64	Xiaoshan, Hangzhou (ZJ)	FI
China	38.26	114.40	Lingshou (HE)	FI	China	19.08	108.67	Dongfang (HI)	FI
Colombia	10.30	-75.49	Cartagena - Mamonal	FI	Croatia	45.48	16.82	Kutina	FI

Country	Lat	Lon	Name	Type	Country	Lat	Lon	Name	Type
Egypt	29.66	32.32	Ain Sukhna	FI	Egypt	31.07	31.40	Talkha	FI
Egypt	31.26	30.09	Abu Qir	FI	Emirates	24.18	52.73	Ruwais	FI
Georgia	41.54	45.08	Rustavi	FI	Germany	51.86	12.64	Piesteritz	FI
India	8.72	78.14	Tuticorin	FI	India	12.92	74.84	Mangalore	FI
India	13.13	80.25	Manali - Chennai	FI	India	15.34	73.85	Zuarinigar	FI
India	16.96	82.00	Bikkavolu - Balabhadrapuram	FI	India	18.71	72.86	Thal	FI
India	19.03	72.88	Trombai - Mumbai	FI	India	20.32	86.64	Paradip - Batighara	FI
India	21.17	72.71	Hazira - Surat	FI	India	21.59	73.00	Ankleshwar	FI
India	22.39	73.10	Vadodara	FI	India	24.51	77.14	Vijapur	FI
India	25.19	76.17	Gadepan	FI	India	25.56	82.05	Phulphur	FI
India	26.46	80.21	Kanpur	FI	India	27.23	95.33	Namrup	FI
India	27.84	79.91	Shahjahanpur	FI	India	28.24	79.21	Aonla	FI
Indonesia	-7.16	112.64	Gresik	FI	Indonesia	-6.39	107.43	Derwolong - Cikampek	FI
Indonesia	-2.97	104.79	Palembang	FI	Indonesia	0.18	117.48	Bontang City	FI
Indonesia	5.23	97.05	Lhokseumawe	FI	Iran	27.56	52.55	Asaluyeh	FI
Iran	29.86	52.72	Marvdasht	FI	Iran	30.40	49.11	Bandar Imam Khomeini	FI
Iran	37.54	57.49	Bojnourd	FI	Iraq	30.18	47.84	Khor Al Zubair	FI
Kazakhstan	43.66	51.21	Aktau	FI	Lituania	55.08	24.34	Jonava	FI
Lybia	30.42	19.61	Marsa el Brega	FI	Mexico	17.99	-94.54	Cosolaecaque	FI
Mexico	20.52	-101.14	Salamanca - Villagran	FI	Morocco	33.10	-8.61	Jorf Lasfar	FI
Myanmar	16.90	94.76	Kangyidaunt	FI	Myanmar	17.15	95.98	Hmawbi	FI
Nigeria	4.73	7.11	Port Harcourt	FI	North Korea	39.63	125.64	Anju	FI
Oman	22.64	59.41	Sur Industrial Estate	FI	Pakistan	24.81	67.24	Bin Qasim	FI
Pakistan	28.07	69.69	Daharki	FI	Pakistan	28.27	70.07	Sadiqabad	FI
Poland	50.30	18.23	Kedzierzyn - Kozle	FI	Poland	51.47	21.96	Pulawy	FI
Poland	53.58	14.55	Police	FI	Qatar	24.91	51.58	Mesaieed	FI
Romania	43.70	24.89	Turnu Magurele	FI	Romania	44.53	27.37	Slobozia - Dragalina	FI
Romania	46.52	24.49	Targu Mures	FI	Romania	46.52	26.94	Bacau	FI
Romania	46.84	26.51	Savinessi - Roznov - Slobozia	FI	Russia	44.67	41.91	Nevinnomysk	FI
Russia	50.14	39.68	Rossosh	FI	Russia	51.93	47.89	Balakovo	FI
Russia	53.40	55.87	Salavat	FI	Russia	53.54	49.61	Togliatti	FI
Russia	54.08	38.18	Novomoskovsk	FI	Russia	54.96	33.33	Dorogobuzh	FI
Russia	55.36	85.96	Kemerovo	FI	Russia	57.88	56.17	Perm	FI
Russia	58.53	49.95	Kirovo-Chepetsk	FI	Russia	58.61	31.24	Novgorod	FI
Russia	59.15	37.80	Cherepovets	FI	Russia	59.40	56.73	Berezniki	FI
Saudi Arabia	27.08	49.57	Al Jubayl	FI	Saudi Arabia	29.32	35.00	Haql	FI
Serbia	44.87	20.60	Pancevo	FI	Slovakia	48.16	17.96	Sala	FI
South Africa	-26.85	27.82	Sasolburg	FI	South Africa	-26.57	29.16	Secunda	FI
Spain	37.19	-6.91	Huelva	FI	Spain	38.67	-4.06	Puertollano	FI
Syria	34.67	36.68	Homs	FI	Trinidad and Tobago	10.40	-61.48	Point Lisas	FI
Tunisia	33.91	10.10	Gabes	FI	Tunisia	34.76	10.79	Sfax	FI
Turkmenistan	37.37	60.47	Tejen	FI	Turkmenistan	37.50	61.84	Mary	FI
Ukraine	46.62	31.00	Odessa-Yuzhne	FI	Ukraine	48.31	38.11	Gorlovka	FI
Ukraine	48.50	34.66	Kamianske	FI	Ukraine	48.94	38.47	Severodonetsk	FI
Ukraine	49.37	32.05	Cherkasy	FI	Ukraine	50.70	26.20	Rivne	FI
USA	34.82	-87.95	Cherokee (AL)	FI	USA	42.41	-90.57	Massey (IO)	FI
USA	36.37	-97.79	Etna (KS)	FI	USA	30.09	-90.96	Donaldsonville (LA)	FI
USA	47.35	-101.83	Beulah (ND)	FI	USA	33.44	-81.94	Beech Island (SC)	FI
Uzbekistan	40.10	65.30	Navoi	FI	Uzbekistan	40.46	71.83	Ferghana	FI
Uzbekistan	41.44	69.51	Chirchik	FI	Venezuela	10.07	-64.86	El Jose	FI
Venezuela	10.50	-68.20	Moron	FI	Venezuela	10.74	-71.57	Maracaibo	FI
Vietnam	10.62	107.02	Phu My	FI	Vietnam	20.24	106.07	Ninh Binh	FI
Italy	42.87	11.62	Mt. Amiata	GI	Italy	43.22	10.91	Larderello	GI
USA	38.77	-122.80	The Geysers (CA)	GI	Tanzania	-2.49	36.06	Lake Natron	N
China	31.83	117.43	Feidong (AH)	ND	China	32.11	117.38	Jianbei (AH)	ND
China	32.39	117.61	Gaotangxiang (AH)	ND	China	29.91	115.34	Fuchizhen (HB)	ND
China	31.73	120.22	Yuqizhen (JS)	ND	China	37.53	105.71	Zhongning (NX)	ND
China	35.47	115.53	Juancheng (SD)	ND	China	33.00	106.97	Hanzhong (SN)	ND
China	34.88	111.17	Pinglu (SX)	ND	China	24.16	102.77	Tonghai (YN)	ND
Spain	41.63	-4.71	Valladolid	ND	Syria	33.51	36.40	East of Damascus	ND
Taiwan	23.93	120.35	Fangyuan	ND	USA	37.19	-86.73	Morgantown (WV)	ND
Vietnam	10.74	106.59	Ho Chi Minh	ND	China	36.00	103.28	Yongjing (GS)	NDI
China	26.55	104.88	Zhongshan (GZ)	NDI	China	33.42	113.62	Wuyang (HA)	NDI
China	46.19	129.36	Dalianhezhen (HL)	NDI	China	46.57	124.83	Cheng'ercun, Ranghulu (HL)	NDI
China	39.40	121.73	Xiaochentun, Wafangdia (LN)	NDI	China	41.83	123.93	Fushun (LN)	NDI
China	39.87	106.81	Huanghecun (NM)	NDI	China	40.64	109.69	Baotou (NM)	NDI
China	42.31	119.24	Yuanbaoshanzhen (NM)	NDI	China	37.88	106.15	Wuzhong (NX)	NDI
China	38.23	106.54	Ningdongzhen (NX)	NDI	China	35.64	110.95	Hejin - Jishan - Xinjiang (SX)	NDI
China	36.31	111.74	Hongtong (SX)	NDI	Egypt	29.94	32.47	Al-Adabiya	NDI
India	23.77	86.40	Jharia	NDI	Iran	35.40	53.16	Nezami	NDI
Mauritania	18.05	-15.98	Nouakchott	NDI	Mexico	26.89	-101.42	Monclova	NDI

Country	Lat	Lon	Name	Type	Country	Lat	Lon	Name	Type
Russia	51.44	45.90	Saratov	NDI	South Africa	-26.05	29.36	Springbok	NDI
Australia	-19.20	146.61	Yabulu	NI	Brazil	-14.35	-48.45	Niquelandia	NI
Cuba	20.64	-74.89	Moa	NI	Cuba	20.67	-75.57	Nicaró	NI
China	39.22	118.13	Douyangu (HE)	SI	China	37.32	97.33	Delingha (QH)	SI
China	29.46	103.84	Wutongqiao (SC)	SI	Mexico	25.78	-100.56	García	SI
Poland	52.75	18.17	Janikowo	SI	Poland	52.75	18.15	Inowrocław	SI
Romania	44.99	24.28	Stupareí	SI	Russia	53.66	55.99	Sterlitamak	SI
Turkey	36.79	34.67	Mersin	SI	Ukraine	45.97	33.85	Krasnoperekopsk	SI
USA	35.67	-117.35	Searles Valley (CA)	SI	Afghanistan	34.51	69.17	Kabul	U
Angola	-8.82	13.32	Luanda	U	Burkina Faso	12.35	-1.58	Ouagadougou	U
Congo	-4.39	15.32	Kinshasa	U	Ethiopia	9.02	38.71	Addis Ababa	U
Kenya	-1.27	36.87	Nairobi	U	Mali	12.59	-7.99	Bamako	U
Mexico	19.45	-99.07	Mexico City	U	Niger	13.55	2.12	Niamey	U
Nigeria	11.88	13.17	Maiduguri	U	Nigeria	12.03	8.50	Kano	U
Sudan	15.65	32.55	Omdurman - Khartoum	U	Uganda	0.30	32.55	Kampala	U

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