# **On the r**<u>R</u>elationship between wind observation accuracy and the ascending node of <u>the</u> sun-synchronous orbit for the Aeolus-type spaceborne Doppler wind lidar

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Abstract. The launch and operation of first spaceborne Doppler wind lidar (DWL), Aeolus, is of great significance in-to observing global wind field. Aeolus operates on the a sun-synchronous dawn-dusk orbit to minimize the negative impact of 10 solar background radiation (SBR) on wind observation accuracy. For that tFhe future spaceborne DWLs may not operate on sun-synchronous dawn-dusk orbits due to their observation purposes. Tethe impact of the local time of ascending node (LTAN) crossing of sun-synchronous orbits on the wind observation accuracy was studied in this paper by proposing two added-given Aeolus-type spaceborne DWLs operated on the sun-synchronous orbits with LTANs of 15:00 and 12:00. On these two new orbits, the increments of the averaged SBR received by the new spaceborne DWLs range from 39 to 56 mW·m<sup>-2</sup>·sr<sup>-1</sup>·nm<sup>-1</sup> 15 under cloud-free skies near the summer and winter solstices, which will lead to the increment of averaged Rayleigh channel wind observation uncertainties of 0.19 m/s and 0.27 m/s in the increment of the averaged Rayleigh channel wind observations for 15:00 orbit and 0.27 m/s for 12:00 orbits when using the instrument parameters of new spaceborne DWLs are the same with those of Aeolus with 30 measurements per observation withand 20 laser pulses per measurement. This demonstrates that Aeolus operating on the sun-synchronous dawn-dusk orbit is the optimal observation scenario, and the random error caused 20 by the SBR will is larger on other sun-synchronous orbits. Increasing the laser pulse energy of the new spaceborne DWLs is used to lower the wind observation uncertainties. Furthermore, And a method to quantitatively design the laser pulse energy according to the specific accuracy requirements is given proposed in this paper study based on the relationship between the signal--to-noise ratio and the uncertainty of the response function of the Rayleigh channel. The laser pulse energies of the two new spaceborne DWLs are should be set to 70 mJ based on the statistical results according toobtained using the method. 25 meanwhilThee other instrument parameters are should be the same as those of Aeolus. Based on the proposed parameters proposal, the accuraciesy of about 77.19% and 74.71% of the bins of the two new spaceborne DWLs would meet the accuracy requirements of the European Space Agency (ESA) for Aeolus, of which. These values are very closely equivalent to the percentage of 76.46% accuracy of Aeolus when Aeolus areit is free of the impact of the SBR. And Moreover, the averaged uncertainties of the two new spaceborne DWLs in the free troposphere and stratosphere are 2.62 and 2.69 m/s-respectively, 30 which perform better than that of Aeolus (2.77 m/s).

#### **1** Introduction

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The first spaceborne Doppler wind lidar (DWL) mission, the ADM Aeolus (ADM, Atmospheric Dynamics Mission) (ADM)-Aeolus, designed by the European Space Agency (ESA) was launched successfully on 22 August 2018, which. This mission has improveds people's our knowledge on of the global wind field. Aeolus carries a spaceborne DWL, Atmospheric Laser 35 Doppler Instrument (ALADIN), which has been used to make preliminary observations of the global wind field since the its launch. And the first-Numerical Weather Prediction (NWP) experiments have shown that the assimilated wind observations have a significant positive impact on the forecast of short-range wind, humidity and temperature at short-range forecasts, especially in the tropical troposphere and the south South hemisphere Hemisphere (Straume et al., 2019). Furthermore, scientists have also designed several possible observation scenarios of for future spaceborne DWLs. For example, 40 cConsidering that Aeolus can-can only realize theattain observations of single horizontal line-of-sight (LOS) wind components, Ma et al., (2015) and Masutani et al., (2010) proposed a spaceborne DWL concept with two pairs of telescopes (azimuth angles from of one pair is are 45° and 315°, and those of the other pair is are 135° and 225°) using both coherent-detection and direct-detection technology; and ISHII et al.; (2017) proposed the a spaceborne coherent DWL-concept with one pair of telescopes (azimuth angles of  $45^{\circ}$  and  $315^{\circ}$ ). both-Both of these two- observation scenarios can provide detect the horizontal 45 vector wind. In addition, Marseille et al. (2008) demonstrated that a larger observation coverage is more beneficial in the improvement of NWP results onin global scale compared to the measurements of the horizontal vector wind by proposing several multi-satellites joint observation scenarios with Aeolus-type instruments. However, the measurements of horizontal vector wind perform better for NWP results in the region close to the satellite tracks.Regarding multi-satellite joint observation scenarios, according to the World Meteorological Organization's (WMO) Observing Systems Capability Analysis and Review 50 Tool (OSCAR) (Eyre, 2009), an observation cycle of 12 h with Aeolus operating on a sun-synchronous dawn-dusk orbit would meet "the minimum" requirements that have to be met to ensure the observations are useful for global NWP. When another Aeolus-type satellite operates on a sun-synchronous noon-midnight orbit combined with Aeolus, the observation cycle may become 6 h, which would meet breakthrough requirement that, if achieved, would result in a significant improvement in global NWP compared with those based on a single Aeolus. In short, Aeolus is a demonstration mission which primarily aims to 55 improve NWP and medium range weather forecast, and there will be more observation scenarios of spaceborne DWLs with different observation purposes launched in the future.

Aeolus operates on the <u>a</u> sun-synchronous, dawn-dusk orbit to minimize the impact of <u>the</u> solar background radiation (SBR) on the accuracy of <u>the</u> wind observations (Heliere *et al.*, 2002, Baars *et al.*, 2019). In this study, The SBR is defined as the top-of-atmosphere (TOA) radiance which that is directsed toward the telescopes of the spaceborne DWL; and the the solar background noise (SBN) is the photon counts excited by the SBR and imaged byon the photon detectors (Zhang *et al.*, 2018), which would lowers the observation accuracy bydue to the Poisson noise (Liu *et al.*, 2006; Hasinoff *et al.*, 2010). The

dawn-dusk orbit is <u>an-considered to be</u> optimal <u>proposal tofor</u> lower<u>ing the impact of the</u> SBR for<u>on</u> spaceborne DWLs operating on sun-synchronous orbits. <u>The fuFu</u>ture spaceborne DWLs may operate on different orbits <u>which should be</u> <u>relatedaccording</u> to their observation purposes. <u>For example, according to Marseille et al. (2008), larger coverage of wind</u>

65 observations would perform better in improving results of NWP. According to experience gained from scatterometers used in global NWP (Stoffelen *et al.*, 2013), it has been demonstrated that the forecasting errors of tropical cyclone positions are much lower when the Indian Space Research Organisation's (ISRO) scatterometer, which has an ~12:00 UTC local overpass time, is assimilated in the NWP with the original METOP-A and METOP-B (~9:30 UTC local overpass time). FurthermoreTherefore, if-it is assumed that if the global wind field at about 00:00/12:00 or 03:00/15:00 can also be observed, we can reconstruct the wind speed diurnal cycle combing with the wind observations of Aeolusthe global forecast may also be significantly improved. However, ilf the future spaceborne DWLs-would operate on the sun-synchronous orbits with different the local time of ascending node (LTAN) crossing LTAN) crossing differ, the received SBR would become larger, which would lead to higher uncertainties of the wind observations.

Aeolus is a direct-detection Doppler wind lidar that senses the winds through a Mie channel and a Rayleigh channel. 75 AAccording to the technology mechanism of Aeolus, the factors that affect the observations accuracy of the wind observations of spaceborne DWLs include atmospheric heterogeneity, and SBR, et al. The Aeolus is a direct detection Doppler wind lidar which senses winds through Mie channel and Rayleigh channel. Mie channel senses winds using the laser signal backscattered from aerosol/cloud particles, and Rayleigh channel sensing winds using molecular backscatter signal. aAtmospheric heterogeneity mainly affects the wind observations on of the Mie channel, which senses the wind using the laser 80 signal backscattered from the aerosol/cloud particles. Sun et al<sub> $\tau_{2}$ </sub> (2014) indicate reported that typical values for wind uncertainties on for the Mie channel in the free troposphere caused by atmospheric heterogeneity are in the range of 1-1.5m/s-caused by atmospheric heterogeneity, which cannot be easily corrected. And fFor the Rayleigh channel, the uncertainties caused by atmospheric heterogeneity range betweenare 0.2—and 0.6 m/s in the troposphere, which can be largely reduced by using a scene classification algorithm. The SBR mainly affects the observations on-obtained by the Rayleigh channel, which 85 senses the wind using molecular backscatter signals., Theand SBR has less impact on the observations in obtained by the Mie channel (Rennie, 2017). The study of Zhang et al., (2019) illustrates demonstrated that the received SBR of Aeolus ranges from 0 to 169 mW·m<sup>-2</sup>·sr<sup>-1</sup>·nm<sup>-1</sup>. And wWhen the SBR is greater than 80 mW·m<sup>-2</sup>·sr<sup>-1</sup>·nm<sup>-1</sup>, the whole profiles of entire wind observation profiles would beis less accurate.

The oObservations of the global winds would improve the results of NWPs., <u>Hhowever</u>, <u>tif</u> the <u>assimilation of</u> observations of low accuracy <u>observations</u> are assimilated, the <u>has a</u> negative impact on <u>the</u> NWP results would be introduced (Stoffelen *et al.*, 2005, 2006). According to the accuracy requirements of <u>the</u> ESA, the uncertainties of the horizontally projected line-of-sight (HLOS) wind observations in the Planetary Boundary Layer (PBL), free troposphere, and stratosphere should be less than 1, 2, and 3 m/s, respectively (Stoffelen et al., 2005). And tThe latest research <u>has</u> also demonstrated that the uncertainties of 1 m/s in the PBL, 2.5 m/s in the free troposphere, and 3\_5 m/s in the stratosphere would also allow have significant positive impacts oin the NWP results (Straume *et al.*, 2019). The heights of the boundaryies between the PBL, free troposphere, and stratosphere are 2 km and 16 km, respectively. In this paper, we assumed that the an accuracy of 5 m/s in the stratosphere was is required. The free troposphere mentioned below specially is hereinafter referred to as the free troposphere.

Assuming that the future Aeolus-type spaceborne DWLs will would operate on the sun-synchronous orbits with different LTANs, the distributions of the received SBR near the winter and summer solstices and the corresponding uncertainties of the 100 wind observations caused by the SBR were figured outdetermined in this paper. The A method to of lowering the uncertainty to a specific accuracy level, *i.ethat is*, to meet the accuracy requirements of the ESA, or to reach the similar an accuracy level similar to that of Aeolus, was also discussed developed. In general, the only way to reduce the effect of the Poisson noise was is to capture more signal (Vahlbruch et al., 2008). According to the Lidar equation, the following methods can be used to increase the return signal energy of spaceborne DWLs: 1) increasing the laser pulse energy; 2) lowering the height of the orbits; 105 3) enlarging the telescope aperture; and 4) reducing the vertical resolution (Marseille and Stoffelen, 2003). In addition, the The orbit height of Aeolus was adjusted from the originally designed 400 km to 320 km to increase the energy of the received signal. In this paper, the <u>increasing</u> laser pulse energy was <u>used-increased</u> to lower the uncertainty. The remainder of this paper is organized as follows-. The The details of the orbits of the three spaceborne DWLs and the Aeolus-type spaceborne DWL simulation system are presented in Section-2. Section 3 gives describes the a method toof quantitatively designing the 110 laser pulse energy of spaceborne DWLs based on specific accuracy requirements. Before thisat, the relationship between the signal-to--noise ratio (SNR) and the uncertainty of the response function of the Rayleigh channel is also are discussed. In Section- 4, the a preliminary proposal of for laser pulse energiesy of the two new spaceborne DWLs is presented based ongiven using \_\_\_\_\_the method mentioneddescribed in Section- 3 based on, the global distributions of SBR and wind observation uncertainties, as well as and the accuracy requirements for spaceborne DWLs. Section, 5 presents the summary and conclusions.

# 115 2 The sSun-synchronous orbits and simulation system of spaceborne DWLs

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In general, for sun-synchronous orbits, the <u>a</u> spaceborne DWL <u>running operating</u> on the <u>a</u> dawn-dusk orbit (LTAN of 18:00) would receive the minimum amount of SBR, and the <u>a</u> spaceborne DWL <u>running operating</u> on the <u>a</u> noon-midnight orbit (LTAN of 12:00) would receive the maximum amount of SBR. In order to study the impact of the orbit selection on the <u>accuracy of the wind observations</u> accuracy, the spaceborne DWLs operating on three sun-synchronous orbits with LTANs of 18:00, 15:00, and 12:00 respectively were are proposed. And thThee simulation system used to calculate the uncertainty of the wind observations was is also described.

#### 2.1 The sSun-synchronous orbits

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The three sun-synchronous orbits with LTANs of 18:00, 15:00, and 12:00 are illustrated in Fig. 1-(a). Aeolus, which operating on the sun-synchronous, dawn-dusk orbit with height of 320 km, is marked in blue. The spaceborne DWL is equipped with a single-perspective telescope, which scanning scans at 90° with respect to the satellite track, under has a slant angle of 35° versus the nadir, and measuring measures the profiles of the HLOS wind components. The other two spaceborne DWLs running operating on the sun-synchronous orbits with LTANs of 15:00 and 12:00 which are marked in yellow and red lines, respectively. The intersection points between the laser beam and the Eearth's surface are called the off-nadir points of which lines and are illustrate in Fig. 1(b). (b)



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**Figure 1.** The orbits of the spaceborne DWLs operating on the sun-synchronous orbits with LTANs of 18:00, 15:00, and 12:00, which are marked in blue, yellow, and red, respectively. (a) 3D graphics; (b) 2D graphics.

The two new spaceborne DWLs are assumed to be Aeolus-type instruments whose with the same instrument parameters the same as thoseas of Aeolus, except different their laser pulse energies, which aims are altered to improve the wind 135 observation accuracies of theiry wind observations. The When demonstrating the instrument parameters of spaceborne DWLs, people also pay attention to the observation accuracy under worst cases. sSolar zenith angle is the dominant factor for the SBR received by spaceborne DWLs. The variations of the solar zenith angles of the off-nadir points on the three orbits within one -year-range are illustrated in Fig. 2., which indicates This shows that the received SBR would reaches the maximum values near the summer solstice and reach maximal values near winter solstices. For the off-nadir points, in the north-North 140 Hhemisphere, the SBR will reach the maximum near summer solstice-, And SBR whereas it will reach the maximum near the winter solstice for the off nadir points in the Ssouth Hhemisphere. In this paper, When demonstrating the instrument parameters of spaceborne DWLs, people alsowe pay attention to focused on the observation accuracy under the worst cases SBR <u>conditions</u>, the <u>The</u> global distributions of the maximum SBR in <u>a</u>  $1^{\circ} \times 1^{\circ}$  grid near the summer solstice which range from (June 14 to 28) and near the winter solstice which ranges from (December 15 to 30) arewere used for the investigations of the 145 worst cases with maximum Rayleigh channel wind observation uncertainties due to SBR. Furthermore, the annual variation characteristics of the solar zenith angles are less obvious on for the two new orbits compared to that those of Aeolus as shown in-(Fig. 2), which indicates that the observations of the two new spaceborne DWLs would --more likely-frequently to encountersuffer the worste cases <u>SBR conditions</u> on the Rayleigh channel compared to that of with Aeolus.



150 Figure 2. The variations of in solar zenith angles of the off-nadir points on the three orbits within one\_-year-range. The 4 time ranges divided by 8 red lines denote 15 days near the autumn equinox, winter solstice, spring equinox and summer solstice, respectively. Sun-synchronous orbits with LTANs of 18:00 (a), 15:00(b), and 12:00(c).

#### 2.2 Spaceborne DWL simulation system

- An Aeolus type spaceborne DWL simulation system eConsidering the impact of the SBR on the wind observation uncertainties, 155 an Aeolus-type spaceborne DWL simulation system was developed \_-was developed to retrieve HLOS wind components and calculate the observation uncertainties. The simulation system was built according to the optical structure of Aeolus. 7 which It consists of <u>a</u> laser transmitter, the <u>a</u> telescope and front optics, <u>a</u> Mie spectrometer, <u>a</u> Rayleigh spectrometer, and <u>front</u> detection front units (Marseille and Stoffelen, 2003-and; Paffrath, 2006). Considering that the SBR mainly affects the observation accuracy of the Rayleigh channel, we focused on the simulation of the wind retrievaled method on the Rayleigh channel, and 160 assumed that the cross-talk effect between the Mie channel and the Rayleigh channel is negligible. The details of the working principle and the instrument parameters forof Aeolus used in the simulation system, expect for the laser pulse energy, were set according to the ADM-Aeolus Algorithm Theoretical Basis Document (ATBD) Level\_1B products (Reitebuch et al., 2018), expect laser pulse energy which is set to 60 mJ, which was consist with the laser pulse energy of onboard Aeolus. - In addition, In the simulation system, one observation consistsed of 30 accumulations (also called <u>30 as measurements), and one</u> 165 measurement consists of 20 shots, resulting in an average horizontal averaging length of about 90 km per observation. The dDetection chain noise of 4.7 e<sup>-</sup>/pixel on the Rayleigh channel for each measurement was also taken into account considered. The vertical resolutions of the retrieved wind were 500 m in the PBL, 1 km in the troposphere, and 2 km in the stratosphere (Marseille et al., 2008).
- The input parameters of <u>the</u> simulation system included <u>the</u> u- and v- components<u>of the</u> wind, temperature, pressure, aerosol optical properties, and TOA radiance. In this paper, the impacts of <u>the</u> SBR on the wind observation accuracy of <u>the</u> spaceborne DWLs under cloudy <u>atmosphere-conditions</u> were not considered. The first five components were derived from the pseudo-truth global atmospheric condition dataset, which consiste<u>s</u><del>d</del> of the Ozone Monitoring Instrument (OMI) database (McPeters *et al.*, 2008), including the latitude-averaged profiles of <u>the</u> temperature, pressure, and density of ozone, and the lidar climatology of vertical aerosol structure for spaceborne lidar simulation studies (LIVAS) database (Amiridis *et al.*, 2015), which was used to describe <u>the</u> aerosol optical properties. Only <u>the</u> aerosols in the PBL were considered here. The details <u>used</u> to derive the global distributions of <u>the</u> SBR received by Aeolus-type spaceborne DWLs <u>could refer to have been described by</u>

Zhang *et al.* (2019), which wereand thus only briefly introduced here. First, the positions of the off-nadir points of the spaceborne DWLs were obtained using satellite orbit simulation software. The aAtmospheric conditions were retrieved from the pseudo-truth databases and were spatially interpolated to the off-nadir points. The surface albedo was-is\_also needed to generate the TOA radiance, which was derived from the database of lambert-equivalent reflectivity (LER) database (Koelemeijer *et al.*, 2003). Then, the SBR of the off-nadir point was generated by using the radiative transfer model (RTM) libRadtran with the input of atmospheric optical properties, and surface albedo (Emde *et al.*, 2016). Finally, the earth-Earth was divided into 1°×1° grids, and the maximum SBR in each grid is pieked-outwas selected as the worst cases conditions offor the Rayleigh channel wind observation uncertainties due to the SBR. Once the atmospheric conditions and SBR were input to the simulation system, the HLOS winds and their corresponding uncertainties in the grids could be figured outwere determined.

#### 3 Methodology

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In this study, a mMethod of increasing the laser pulse energies of Aeolus-type spaceborne DWLs was used-developed to lower wind observation uncertainties in this paper. To assess the performance of the spaceborne DWLs under worst case conditionss of the Rayleigh channel, and quantitatively design the laser pulse energies of two new spaceborne DWLs as mentioned in Sect-ion 2.1, we take the steps are as follows:-\_\_1) the The global distributions of the maximum SBR received by the spaceborne DWLs on the three orbits were figured outdetermined to compare the SBR received by the two new spaceborne DWLs with that of Aeolus;\_ 2) the The uncertainties of the wind observations on of the Rayleigh channel of the three spaceborne DWLs were derived, and the uncertainty-increments of the uncertainties of the two new spaceborne DWLs were compared to that those of Aeolus were figured out;\_ 3) tThe relationship between the wind observation uncertainty and the laser pulse energy was established.; 4) Tthe values of the laser pulse energies which that would lower the uncertainties to the required accuracy level were derived based on the relationship established in <u>sthe step 3</u>).

# 3.1 Uncertainty of the wind observations on of the Rayleigh channel

The double-edge technique is was used to retrieve the HLOS wind components on of the Rayleigh channel for Aeolus (Flesia and Korb, 1999; Zhang et al., 2014). The study of Tan *et al.*, (2008) showeds that the uncertainty on of the Rayleigh channel is determined by the response function, temperature, and pressure. <u>A Ll</u>ookup table between for the wind speed, and \_\_response function, temperature, and pressure is was established prior to the launch of Aeolus. In operation mode, the profiles of temperature and pressure profiles arewere obtained from the European Centre for Medium-Range Weather Forecasts' (ECMWF) data assimilation system. Once the response function of the Rayleigh channel is detected by spaceborne DWL, the wind speed will-can be figured outretrieved. The uncertainty of the wind observation is estimated as

$$\sigma_{\nu_{HLOS}} = \frac{\partial v_{HLOS}}{\partial R_{ATM}} \sigma_{R_{ATM^{2}}} \tag{1}$$

where  $\sigma \cdot \frac{\text{denotes} - is \text{ the }}{\text{uncertainty}, \cdot} \partial \cdot \frac{\text{denotes} - is \text{ the }}{\text{partial derivative. }} \frac{v_{HLOS}}{v_{HLOS}}$  means is the HLOS wind component.  $R_{ATM}$  means is the response function of the Rayleigh channel which is defined as

$$R_{ATM} = \frac{N_A - N_B}{N_A + N_B^2} \tag{2}$$

where  $N_A$  and  $N_B$  are the useful signals detected by the Rayleigh channel.

The  $\partial v_{HLOS} / \partial R_{ATM}$  is a function of temperature and pressure, which and it ranges from 420 to 520 m/s upon on most occasions, as shown in (Fig. 1 of Zhang et al., (2019). The uncertainty of the response function is derived from

$$\sigma_{R_{ATM}} = \frac{2}{(N_A + N_B)^2} \sqrt{N_B^2 \sigma_A^2 + N_A^2 \sigma_B^2}$$
(3)

where  $\sigma_A$  and  $\sigma_B$  denote-are the uncertainties of  $N_A$  and  $N_B$ , respectively. Here,  $N_A$  and  $N_B$  can be obtained using the simulation system of the spaceborne DWLs. Taking the SBR and the noise of the spaceborne DWL detectors into account, according to the features of the Poisson noise, the uncertainties in  $N_A$  and  $N_B$  can be estimated as follow:

$$\sigma_A^2 = N_A + N_{S,A} + N_{noise}^2, \text{ and } \sigma_B^2 = N_B + N_{S,B} + N_{noise}^2$$

$$\tag{4}$$

where the  $N_{S,A}$  and  $N_{S,B}$  are the photon counts which are excited by the SBR onfor the Rayleigh channel.  $N_{noise}$  denote is the noise of the detection unit onfor Rayleigh channel.

 $N_{S,A}$  and  $N_{S,B}$  can be derived using the following method  $\pm T$  the SBR is viewed as atthe spectrum following with thea uniform distribution, and of which its energy can be obtained using Eq. (5) (Nakajima *et al.*, 1999), and the bandwidth is equals to that of the interference filter of the Rayleigh channel.  $N_{S,A}$  and  $N_{S,B}$  can be obtained from the simulation system with the input of when the spectrum is input.

$$S_{SBR} = nE_Q E_O L_S \varphi_R \frac{A_F^2 \cdot \pi}{4} \Delta \lambda \Delta t_{\perp}$$
<sup>(5)</sup>

where  $S_{SBR}$  denotes is the energy of the SBR<sub>1</sub>, *n* denotes is the number of the accumulated laser shots;  $E_Q$  and  $E_O$  denote are the quantum efficiency of the detector on of the Rayleigh channel (Reitebuch *et al.*, 2018); and  $L_S$  denotes is the TOA radiance of the off-nadir point. As to for the instrument parameters,  $\varphi_R$  denotes is the field of view;  $A_r$  denotes is the diameter of the telescope; and  $\Delta\lambda$  denotes is the bandwidth of the interference filter.  $-\Delta t$  denotes the laser detection time, which was is dependent on the vertical resolution.

# 230 **3.2 Relationship between uncertainty and laser pulse energy**

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The laser pulse energy of <u>the</u> laser transmitter has an important influence on the uncertainty of <u>the</u> wind observation. Provided that the atmospheric conditions remain unchanged, the higher the laser energy, the <u>stronger the</u> backscattered signal received by the telescope of <u>the</u> Aeolus-type instrument <u>will become stronger</u>, and the <u>smaller the</u> influence of <u>the</u> corresponding Poisson noise-<u>will be smaller</u>, which will <u>finally</u> lower the uncertainty of <u>the</u> wind observation<u>s</u>-finally. However, the quantitative relationship between <u>the</u> laser pulse energy and <u>the</u> wind observation uncertainty <u>is has</u> not yet derived due to the fact that the

wind observation uncertainties are affected by various factors such as the atmospheric conditions and instrument parameters. In this <u>paperstudy</u>, <u>the a</u> method <u>for of quantitatively</u> derivation <u>ing</u> of the laser pulse energy according to <u>the</u> specific <u>wind</u> <u>observation</u> accuracy requirements <u>of wind observation</u> is <u>proposeddeveloped</u> throughby establishing the relationship between the SNR of the Rayleigh channel and <u>the</u> uncertainty of <u>the</u> response function of <u>the</u> Rayleigh channel.

According to the characteristics of <u>the</u> Poisson noise, Marseille and Stoffelen, (2003) defined the SNR of <u>the</u> Rayleigh channel:-

$$SNR_{Ray} = \frac{N_A + N_B}{\sqrt{N_A + N_B + N_{S,A} + N_{S,B} + 2N_{noise}^2}}$$
(6)

For the Rayleigh channel of <u>a</u> spaceborne DWL, <u>the</u> difference between  $N_A$  and  $N_B$  is not large, especially when the wind speed is close to zero, <u>that is</u>,  $N_A \approx N_B$ . Based on the assumption that  $N_A \approx N_B$  and  $N_{S,A} \approx N_{S,B}$ , we derived the relationship between the SNR and <u>the</u> uncertainty of <u>the</u> response function of the Rayleigh channel:

$$\sigma_{R_{ATM}} \approx \frac{1}{_{SNR_{Ray}}}.$$
(7)

The details of the derivations and <u>the</u> proofs are <u>shown-presented</u> in <u>the</u> Appendix. Then, the uncertainty of <u>the</u> wind observations <u>on-from the</u> Rayleigh channel can be estimated as

$$\sigma_{v_{HLOS}} \approx \frac{\partial v_{HLOS}}{\partial R_{ATM}} \cdot \frac{1}{SNR_{Ray}}$$
(8)

While increasing When the laser pulse energy is increased, the value of  $N_A + N_B$  will increase proportionally increase <u>s</u>; <u>S</u>similarly,  $N_{S,A} + N_{S,B}$  will increase proportionally increase with the increase of SBR increases, which can be written as

$$E_{laser} \propto N_A + N_B, S_{SBR} \propto N_{S,A} + N_{S,B}$$
(9)

According to Eqs. (6) and (8), setting  $x = N_A + N_B$ , which is in proportional to the energy of the laser pulse  $E_{lasr}$ ;  $y = N_{S,A} + N_{S,B}$ , which is in proportional to the energy of the SBR  $S_{SBR}$  and  $z = \sigma_{HLOS}$ ,  $f(T, P) = \frac{\partial v_{HLOS}}{\partial R_{ATM}}$  and  $\tau C = 2N_{noise}^2$ , where T denotes is temperature and P denotes is pressure. Thus,  $\tau$  the relationship between x, y, and z can be expressed as

$$z \approx f(T, P) \frac{\sqrt{x + y + c}}{x}$$
(10)

Equation (10) can be solved as <u>follows</u>:

$$\chi \approx \frac{f^2(T,P) + f(T,P) \cdot \sqrt{f^2(T,P) + 4z^2(y+C)}}{2z^2}.$$
 (11)

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Equation (10) illustrates that the uncertainty is determined by temperature, pressure, variable x, the SBR, and dark noise of the detector. The value of x can be estimated using Eq. (11). Knowing the value of x, the value of <u>the</u> laser energy cannot be figured outdetermined for that because the variable x is dependent on the laser energy and <u>the</u> wind speed. However, when the wind speed keeps-remains unchanged, the variable x would be inis proportional to the energy of <u>the</u> laser pulse  $E_{laser}$ . That is to say, if the laser energy increases by several times, the corresponding value of the variable x will increase by the

same multiples when the HLOS wind speed keeps-remains unchanged. Then, the required value of the laser energy can be obtained based on the proportional relationship between x and  $E_{laser}$ .

## 3.3 Derivation of laser pulse energy

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In Sect<u>ion</u>- 3.2 and <u>the</u> Appendix, the relationship between <u>the</u> laser pulse energy  $E_{laser}$  and <u>the</u> wind observation uncertainty was established based on <u>someseveral</u> assumption and simplifications. The following method was used to solve the problem <u>thatof</u> how <u>muchhigh to set</u> the laser energy <u>could be set</u> to increase the accuracy of the observations of <u>the</u> new spaceborne DWLs to the meet specific accuracy requirements.

Firstly, the laser pulse energies of the two new spaceborne DWLs were assumed to be 60 mJ, and the \_-of which parameters are the same as those of Aeolus<sub>7</sub>. The profiles of the uncertainties were derived using simulation system based on the global distributions of the maximum SBR foron the three orbits; secondly, Second, the profiles of variable x at each bin (layer, the concept-can refers to Fig. 5 in Tan et al., (2008)) were figured outdetermined using Eq. (11), which and they were set as x1. Provided Assuming that the accuracy requirements of the two new spaceborne DWLs are to-that their accuracies reach the accuracy level of Aeolus, then<sub>7</sub> the uncertainties of the new spaceborne DWLs were replaced with the uncertainties of Aeolus at the same bins, and the variables of f(T, P), y, and C were kept unchanged the same x Tthe variables x were figured outdetermined using Eq. (11), which and they were set as  $x2_x$ ; Efinally, according to the proportional relationship between x and the laser energy,  $E_{new}/E_{Aeolus} \approx x2/x1$ , the required laser pulse energy at each bin could bewas derived. Therefore, we could determine the laser energies of the two new spaceborne DWLs according to the statistical results.

In the same way, if the accuracy requirements is of the two new spaceborne DWLs were required to meet the accuracy requirements of the ESA, we needed to replace the wind observation uncertainties when the laser energy was 60 mJ with the accuracy requirements of the ESA when calculating the values of  $x^2$ , and the other steps were are the same as above.

#### 285 4 Results and discussions

The preliminary results to of determine the laser pulse energies of the two new spaceborne DWLs were are presented in this section. To obtain the laser pulse energies, first the global distributions of the maximum SBR on of the three orbits and the corresponding wind observation uncertainties caused by the SBR wereare calculated, firstly. Then, the distributions of the required laser energies weare obtained according to the accuracy requirements based on the method mentioneddescribed in Subsect-ion 3.3. Finally, based on these results, the proposal ofed laser pulse energies of the two new spaceborne DWLs arewas presented. TAnd the global distributions of wind observation uncertainties of the three spaceborne DWLs were figured outare determined according to the new instrument parameter proposal laser pulse energies. The details were shownare provided in the following subsections.

<u>The g</u>Global distributions of <u>the</u> maximum SBR received by the spaceborne DWLs <u>runningoperating</u> on the three orbits in summer and winter are shown in Fig. 3 based on the instrument parameters of Aeolus and the three orbits <u>mentioned\_described</u> in Sect<u>-ion</u> 2.

The contours in Fig. 3 denote the differences between the SBRs of the two new orbits and sun-synchronous dawn-dusk orbit, which demonstrates that the dawn-dusk orbit is an effective solution the optimal observation scenario to for minimizinge 300 received SBR for Aeolus-type spaceborne DWLs operating on sun-synchronous orbits. While-When operating on the a sunsynchronous dawn-dusk orbit, the maximum SBR of the off-nadir points located in the southern bemisphere Hemisphere is nearly equal to zero in summer, and the maximum SBR of the off-nadir points located in the northern-Northern Hhemisphere is nearly equal to zero in winter. For the two new orbits, almost all of the wind observations of a few areas are not affected by the SBR, which are mainly located in the regions near the Antarctic and Arctic circles. According to the 305 contours, the order of ascending order of the values of maximum SBR, on the three orbits is are dawn-dusk orbit, the orbits with an LTAN of 15:00, and that of the orbit with an LTAN of 12:00 respectively. The closer the LTANs of the orbits are to noon, the larger the values and the affected area affected of by the SBR will become larger. The sStatistics illustrate that the averaged SBR values of the dawn-dusk, 15:00, and 12:00 orbits illustrated in Fig. 3 are 20.99, 60.68, and 76.36  $mW \cdot m^{-2} \cdot sr^{-1} \cdot nm^{-1}$ , respectively, near the summer and winter solstice periods. The averaged increments of the SBR received by new spaceborne DWLs are  $60.68 \cdot 20.99 = 39.69 \text{ mW} \cdot \text{m}^{-2} \cdot \text{sr}^{-1} \cdot \text{nm}^{-1}$  and  $76.36 \cdot 20.99 = 55.37 \text{ mW} \cdot \text{m}^{-2} \cdot \text{sr}^{-1} \cdot \text{nm}^{-1}$  compared 310 (c) (e) tohigher than that of Aeolus, respectively.



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### 4.2 Uncertainties of wind observations based on the instrument parameters of Aeolus

Figure 3 illustrates the global distributions of the maximum SBR near the summer and winter solstice periods, which paid more attention tofocus on the worst SBR cases of for the Rayleigh channel wind observation uncertainties. In fact, for sun-

320 synchronous orbits, nearly half of the off-nadir points would beare in darkness, which would so they are be free of the impact of the SBR, and while the other half would beare in daylight and are affected by the SBR. As toFor the off-nadir points in darkness, the latitude-averaged global distributions of the wind observation uncertainties for Aeolus-type instruments in the second se latitude averaged were are shown in Fig. 4.

Figure 4 illustrates that: 1) wwwithout the impact of SBR, most of the wind observations in the free troposphere and 325 stratosphere would-meet the accuracy requirements of the ESA. The bins forof which the uncertainties are beyond exceed the requirements of the ESA are mostly located in the upper layer of troposphere and stratosphere. In addition, the accuracy of the wind observations in the PBL is relatively low, which and basically eannot does not meet the requirements of the ESA. In fact, the Mie channel is mostly used for wind observations due to the widespread presence of aerosols in the PBL. Therefore, the accuracy of the Rayleigh channel in the PBL is not considered in the following section of this paper. The sstatistics show that the averaged uncertainties without the impact of the SBR are all about 2.61 m/s in summer and winter, and overall, about 76.46% of the bins would meet the accuracy requirements of the ESA-overall.

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2) Without the impact of the SBR, the wind observation uncertainties have little differences amongare very similar at different latitudes.

3) The wind observation uncertainties increase with atmospheric altitudes when the heights of the range gates are remain 335 unchanged. This is mainly due to the fact that the molecular number density is proportional to the pressure. Near the height of 16 km, the uncertainties decrease first-initially and then increase with the increases ing altitude, which is attributed to the change in the thickness of the bins from 1 km to 2 km.

4) Compared with other regions, the uncertainties in the equatorial region are higher at the bottom of the troposphere, and are lower in the stratosphere. The trend of the temperature profile in the equatorial region is the main reason for this phenomenon, which is consist with the trend of the uncertainties. The nNumber density of molecules is inversely proportional to the temperature. A l-ow molecular number density leads to a weak return signal of spaceborne DWLs, which leads to higher wind observation uncertainties.



Figure 4. The latitude-averaged global distributions of the wind observation uncertainties in latitude average without the impact of the SBR. 345 (a) summer; (b) winter.

Based on the global distributions of <u>the</u> maximum SBR of the three orbits illustrated in Fig. 3, the worst<u>SBR</u> cases of <u>for</u> <u>the</u> Rayleigh channel with maximum wind observation uncertainties due to SBR were also derived <u>as shown in (Fig. 5)</u>. Considering that the distributions of <u>the</u> maximum SBR <u>were-are</u> nearly horizontal to <u>the</u> latitudes, <u>and in</u> to simplify the calculations. Fig. 5 was obtained using the 10 ° latitude-averaged SBR and atmospheric conditions.

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As can be seen by comparing Comparisons between Fig. 4 and Fig. 5, illustrate that the wind observation uncertainties become larger with as the impact of the SBR increases. And tThe uncertainties show exhibt obvious characteristics of latitudinal variations., which This is mainly attributed to the latitudinal variations of in the maximum SBR shown in Fig. 3. As the LTANs of the orbits get closer to noon, the wind observation uncertainties gradually increases, so do and the number of bins of which that do not accuracy cannot meet the accuracy requirements of the ESA also increases. For the bins in the troposphere and stratosphere, about 71.35% can-meet the accuracy requirements of the ESA for Aeolus,-; while the percentages are 63.45% for the orbit of 15:00 orbit and 60.67% for the orbit of 12:00 orbit. The averaged uncertainties of the three spaceborne DWLs in the troposphere and stratosphere are 2.77, 2.96, and 3.04 m/s respectively, which illustrates that the increments in averaged of the average uncertainties of the Rayleigh channel on of the new orbits are about 3.25-3.06=0.19 m/s and 3.32-3.06=0.27 m/s larger than that of Aeolus. Considering that the impact of the SBR on the wind observations is minimal on dawn-dusk orbit, and reaches the maximum on noon-midnight orbit, the phenomenon indicates the selection of the LTANs of sun-synchronous orbits will make the global average wind observation uncertainties leads to a maximum a maximum difference of 0.27 m/s in average global wind observation uncertainties for the Rayleigh channel of Aeolus-type DWLs near the summer and winter solstices. This small degradation of the uncertainties could also be used as an argument for operating Aeolus-type spaceborne DWLs on other sun-synchronous orbits rather than a dawn-dusk orbit. In addition, the average global averaged uncertaintiesty without impact of SBR is 2.61 m/s without impact of the SBR as Fig. 4 indicates; and the average global averaged uncertaintiesy is 3.04 m/s under the worst SBR cases offor the Rayleigh channel on the orbit with LTAN of 12:00. Thise comparison illustrates that SBR causesd athe- maximum increase in the averaged wind observation uncertainty of about 3.04-2.61=0.43 m/s for Aeolus-type DWLs operating on the-sunsynchronous orbits.



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Figure 5. The zonal distributions of the Rayleigh channel wind uncertainties in clear air conditions observed by the three spaceborne DWLs operatinged on the three orbits of which the instrument parameters are the same as those of Aeolus. The contours show the accuracy requirements of ESA. The arrangement of the subgraphs corresponds to that of Fig. 2.

## 4.3 Distributions of the required laser pulse energy

375 In order to make the accuracies of the two new spaceborne DWLs-to reach the specific accuracy level under the worst SBR cases for theof Rayleigh channel, the required laser pulse energies were obtained using the method mentioned-described in Sect-ion 3.3. According to Eq. (11), the required energy is determined by depends on the temperature, pressure, wind uncertainties, SBR, and noise of the instrument, and thus, the required laser pulse energy is different in different bins. Therefore, the laser pulse energies of the new spaceborne DWLs should be determined by the statistics of the profiles of their required 380 energiesy.

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Supposed Assuming that the wind observation accuracy of the two new spaceborne DWLs is requiredneeds to reach the accuracy level of the Aeolus as is as-shown in Figs. 5(a, b), which can be used for joint observations of the three satellites, the global distributions of the required laser pulse energies are-were derived and are illustrated in Fig. 6, which. Fig. 6 illustrates shows that for of the most bins of the two new spaceborne DWLs, it is necessary to increase the laser pulse energy if the accuracy of the wind observations is expected to reach the accuracy level of Aeolus. Especially in the equatorial region, a higher laser pulse energy is needed.

Statistics reveal that the averaged values of required laser pulse energies in Fig. <u>6 is 64.80 mJ for the 15:00 orbit. and</u> 66.59 mJ for the 12:00 orbit respectively. The quantiles of the required energy of the two spaceborne DWLs are shown in Table 1, which means that the corresponding percentages of the bins whose accuracy will reach the accuracy level of Aeolus once the laser pulse energies equal to the specific values. For example, 90% of the bins will reach or exceed the accuracy level Aeolus when the laser energy is 70.37 mJ for the spaceborne DWL operating on the 15:00 orbit. As we can see from Table when the instrument parameters of two new spaceborne DWLs are the same as Aeolus, of which the laser pulse energies are equal to 60 mJ, only the accuracy of about 20% of the bins can reach the accuracy level of Aeolus near summer and winter

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laser pulse energies reach 70 mJ, the accuracy of about 90% of bins could reach or exceed the accuracy level of Aeolus on the orbit 15:00, and the percentage is about 80% on the orbit 12:00.



**Figure 6.** <u>The G</u>global distributions of the required laser pulse energies in troposphere and stratosphere to make <u>the the wind observation</u> accuracies of the two new spaceborne DWLs reach the accuracy level of <u>the</u> Aeolus. Figs. 4(a, b) and (c, d) denote the sun-synchronous orbits with LTANs of 15:00 and 12:00 respectively. The upper panels denote the distributions in summer, and the lower panels denote the distributions in winter.

Table 1. The qQuantiles of the required laser pulse energies of the two new spaceborne DWLs to reach the accuracy level of Aeolus.

Quantile (%)		20	40	50	60	70	80	90	100
Required energy	Orbit 15:00	60.62	62.53	64.00	65.26	66.54	67.85	70.37	81.68
(mJ)	Orbit 12:00	60.71	65.04	66.47	67.34	68.59	70.59	73.74	89.78

The statistics reveal that the average values of the required laser pulse energies in Fig. 6 are 64.80 mJ and 66.59 mJ for the 15:00 and 12:00 orbits, respectively. The quantiles of the required energies of the two spaceborne DWLs are shown in
Table 1, which shows the corresponding percentages of the bins in which the accuracy reaches the accuracy level of Aeolus once the laser pulse energies are equal to the specific value. For example, 90% of the bins will reach or exceed the accuracy level of Aeolus when the laser energy is 70.37 mJ for the spaceborne DWL operating on the 15:00 orbit. As can be seen from Table 1, when the instrument parameters of the two new spaceborne DWLs are the same as those of Aeolus, i. e., laser pulse energies of 60 mJ, the accuracies of only about 20% of the bins reach the accuracy level of Aeolus near the summer and winter
solstices. However, when the laser energy is slightly increased, the percentages of the bins greatly increases. When the laser pulse energy reaches 70 mJ, the accuracies of about 90% and about 80% of the bins reach or exceed the accuracy level of Aeolus on the orbit 15:00 and 12:00 orbits, respectively.

Another potential application of the new spaceborne DWLs is to enlarge the global wind observation coverage to improve the forecast results of NWPs. It is supposed to This should have a positive impact on the NWP results once-when the wind observation accuracy meets the requirements of the ESA. The distributions of the required laser pulse energies of the three orbits required to meet the accuracy requirements of the ESA are illustrated in Fig. 7.

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Figure 7 illustrates that the wind observation uncertainties of most bins in the low level of troposphere and stratosphere can meet the accuracy requirements of ESA for the three spaceborne DWLs with the laser pulse energy of 60 mJ. Higher energies are needed in the upper level of troposphere and stratosphere, especially for the regions close to Antarctic and Arctic 420 eircles. On the boundary line with height of 16 km, there is an obvious sudden decrease in required laser energies. This is mainly because the vertical thickness of observation bins changes from 1 km in the troposphere to 2 km in the stratosphere, which makes the integration time of detection units of Rayleigh channel double. And larger atmospheric backscattered signal will be integrated. On the other hand, the required wind observation uncertainties increase from 2 m/s to 3 m/s. Therefore, the required laser energies reduce suddenly when going from troposphere to stratosphere near the height of 16 km. Comparisons 425 among the required laser energies of the three orbits illustrate that the closer the orbital LTANs are to noon, the averaged values of the required laser energies will become larger. Statistics show that the averaged values of required energies are 53.27 mJ for Aeolus, 57.60 mJ for the 15:00 orbit, and 59.19 mJ for the 12:00 orbit respectively. The quantiles of the required energies of the three spaceborne DWLs are shown in Table 2. The statistics of Table 2 illustrate that the percentages of bins which can meet the accuracy requirements of ESA increase by 10% even if the laser pulse energy is not increased much when 430 quantile is between 40% to 90%. The averaged increment of laser pulse energy is 6.75 mJ which can increase the quantiles by 10% considering the three orbits as a whole. When the laser pulse energies are set to 67.89, 73.71, and 75.98 mJ, the quantiles will be up to be 80%, which exceeds the percentage of bins (76.46%) for Aeolus without the impact of SBR.



**Figure 7.** <u>The g</u>Global distributions of the required laser pulse energies in the troposphere and <u>the</u> stratosphere to reach the accuracy requirements of <u>the</u> ESA. The arrangement of the subgraphs corresponds to that of Fig. 2.

Table 2. The qQuantiles of the required laser pulse energy of the three spaceborne DWLs to meet the accuracy requirements of the ESA.

Quantile (%)		20	40	50	60	70	80	90	100
D	Orbit 18:00	40.93	46.33	49.35	53.87	59.22	67.89	78.63	116.96
(mJ)	Orbit 15:00	42.83	50.88	53.17	58.21	63.96	73.71	84.88	118.20
	Orbit 12:00	45.06	51.81	54.76	59.86	66.46	75.98	86.82	121.19

Figure 7 illustrates that the wind observation uncertainties of most of the bins in the lower level of the troposphere and the stratosphere meet the accuracy requirements of the ESA for the three spaceborne DWLs with a laser pulse energy of 60 mJ. Higher energies are needed in the upper level of the troposphere and the stratosphere, especially in for the regions close to 440 the Antarctic and Arctic circles. On the boundary line with height of 16 km, there is an obvious sudden decrease in the required laser energies. This is mainly because the vertical thickness of the observation bins changes from 1 km in the troposphere to 2 km in the stratosphere, which doubles the integration time of the detection units of Rayleigh channel. Larger atmospheric backscattered signal will be integrated. Moreover, the required wind observation uncertainties increase from 2 m/s to 3 m/s. Therefore, the required laser energies suddenly decrease when transitioning from the troposphere to the stratosphere near a 445 height of 16 km. The comparison of the required laser energies of the three orbits illustrates that the closer the orbital LTANs are to noon, larger the average values of the required laser energies will become. The statistics show that the average values of the required energies are 53.27 mJ for Aeolus, 57.60 mJ for the 15:00 orbit, and 59.19 mJ for the 12:00 orbit. The quantiles of the required energies of the three spaceborne DWLs are shown in Table 2. The statistics presented in Table 2 illustrate that the percentages of the bins that meet the accuracy requirements of the ESA increase by 10% even if the laser pulse energy is not 450 increased significantly when the quantile is between 40% to 90%. The average increment of the laser pulse energy is 6.75 mJ which can increase the quantiles by 10% for the three orbits as a whole. When the laser pulse energies are set to 67.89, 73.71, and 75.98 mJ, the quantiles are up to 80%, which exceeds the percentage of bins (76.46%) for Aeolus without the impact of the SBR.

# 4.4 Uncertainties of wind observations resulting from an increased laser pulse energy

In Sect-<u>ion</u> 4.3, the zonal distributions of <u>the</u> required laser pulse energies were derived for different purposes. In order to offer a feasible proposal for the laser pulse energies of the new spaceborne DWLs, <u>and</u> the percentages of <u>the</u> bins that <del>can</del> meet the specific accuracy requirements when the laser energies reached certain values were <u>figured out,determined</u> as is shown in Table 3.

Considering the accuracy requirements of <u>the</u> ESA and <u>the</u> accuracy level of Aeolus <u>and</u>, <u>while</u> taking the existing technical level into account, the laser energies of the two new spaceborne DWLs <u>are-were</u> set to 70 mJ in this <u>paperstudy</u>. In fact, the laser energy of 80 mJ has<u>been</u> already <u>been</u> required by <u>the</u> ESA in <u>the</u> ATBD (Reitebuch et al., 2018), <u>and it has</u> <u>been achieved in the initial orbiting phase of the satellite</u>. As is shown in Table 3, the percentages of the bins <u>which willthat</u> meet the accuracy requirements of <u>the</u> ESA are 77.19% and 74.71% for <u>orbit-the</u> 15:00 and 12:00 <u>orbits</u>, respectively, <u>which</u> Table 3. Percentages of bins which will meet the specific accuracy requirements with certain laser pulse energies for spaceborne DWLs.

Accuracy requirements		Laser pulse energy (mJ)								
		50	60	70	80	90	100			
ESA (%) <sup>a</sup>	Orbit 18:00	51.61	71.35	82.89	90.50	96.64	98.54			
	Orbit 15:00	37.13	63.45	77.19	85.53	93.42	97.66			
	Orbit 12:00	33.33	60.67	74.71	84.21	91.96	97.22			
Aeolus (%) <sup>b</sup>	Orbit 15:00	0	19.44	89.04	99.42	100	100			
	Orbit 12:00	0	16.67	77.34	96.78	100	100			

<sup>a</sup> The percentage of bins which will meet the accuracy requirements of ESA when the laser energies reach the specific value.

<sup>b</sup> The percentage of bins which will reach the accuracy level of Aeolus in the corresponding bins when the laser energies reach the specific value.

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Provided that<u>For</u> the three spaceborne DWLs opera<u>teting</u> on the sun-synchronous orbits shown in Fig. 1, and the instrument parameters of Aeolus <u>keep-remain</u> unchanged. As to the two new Aeolus-type spaceborne DWLs, the other instrument parameters are set <u>as the</u> same as those of Aeolus<sub>2</sub> except for the laser pulse energies of 70 mJ. The wind observation uncertainty distributions of the three spaceborne DWLs <u>are-were</u> derived <u>as isand are</u> shown in Fig. 8. Note that Figs. 8-(a, b) are is identical to those of Figs. 5-(a, b), for that<u>because</u> both of them arewere obtained with laser energies of 60 mJ.

As <u>is</u> illustrated <u>byin</u> Table 3, when the laser pulse energies of <u>three-the sawn-dusk</u>, <u>15:00</u>, <u>and 12:00</u> spaceborne DWLs are 60, 70, and 70 mJ<sub>4</sub> respectively, the percentages of <u>the</u> bins <del>which that</del> meet the accuracy requirements of <u>the</u> ESA are close (71.35%, 77.19%, and 74.71%, <u>respectively</u>). And Fig. 8 illustrates that the bins that reach <u>the</u> ESA's accuracy requirements are of high consistency in <u>have very consistent</u> latitude and height distributions. <u>By</u> Comparisonsng among Fig. 8-(c\_f) and Fig. 4, <u>it can be seen-illustrate</u> that the wind observation accuracy <u>is significantly improved promotes much</u> in the hemisphere that <u>is</u> less affect by <u>the</u> SBR. However, limited improvement <u>happens-occurs</u> in the other hemisphere. <u>The factThis</u> indicates that increasing the laser energy to 70 mJ cannot compensate <u>the for the</u> negative influence of <u>the</u> large <u>amount of the</u> SBR. <u>By</u> Comparisonsng <u>among</u>-Fig. 8-(c\_f) and Fig. 5-(c\_f), <u>it can be seen-show</u>\_that the wind observation accuracy <u>is</u> greatly improved when <u>the</u> laser pulse energy <u>is</u> increaseds from 60 mJ to 70 mJ. The fact that such improvements are obtained <del>with</del> for only <u>a</u> 10 mJ incre<u>asement</u> in <u>the</u> laser pulse energy illustrates that <u>the</u> wind observation uncertainties are sensitive to the laser pulse energy<del>ies</del> of <u>the</u> spaceborne DWLs. The averaged uncertainties of the two new spaceborne DWLs with <u>a</u> laser pulse energy<del>ies</del> of 70 mJ in troposphere and stratosphere are 2.62 and 2.69 m/s respectively. Compared to the averaged uncertainties with for a laser pulse energy of 60 mJ, the difference in <u>the</u> uncertainties <u>is are</u> 2.96\_-2.62=0.34 m/s and 3.04\_-2.69=0.35 m/s

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(a)

(e)

#### conditions.

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## 5 Summary and conclusions

The successful launch of Aeolus is significant for people to observeing the global wind field. Aeolus operates on the sunsynchronous dawn-dusk orbit to minimize the impact of the SBR on the accuracy of the wind observations. If the future spaceborne DWLs operate on other sun-synchronous orbits for to fulfil their specific observation purposes, the received SBR 500 may become larger, which would lead to higher observation uncertainties. In general, for sun-synchronous orbits, the a spaceborne DWL running operating on the a dawn-dusk orbit (LTAN of 18:00) will receive the minimum SBR, and the a spaceborne DWL running-operating on the a noon-midnight orbit (LTAN of 12:00) will receive the maximum SBR. In this paper, the influence of the LTAN-crossing of the sun-synchronous orbit on the wind observation accuracy for of Aeolus-type spaceborne DWLs was studiedinvestigated. And based on two the spaceborne DWLs running operating on three sun-505 synchronous orbits with LTANs of 18:00, 15:00, and 12:00 respectively were proposed combined with Aeolus. The method of increasing the laser pulse energyies of spaceborne DWLs was used to lower the observation uncertainties. Furthermore, the a method to of quantitatively designing laser pulse energy to meet the specific accuracy requirements was also studied developed. Assuming-For two new Aeolus-type spaceborne DWLs operatinge on the sun-synchronous orbits with LTANs of 15:00 and 12:00<sub>37</sub> the global distributions of the SBR illustrate that the increments of the averaged SBR range from 39 to 56 510 mW·m<sup>-2</sup>·sr<sup>-1</sup>·nm<sup>-1</sup> on the two new orbits near the summer and winter solstices compared to that of the Aeolus under cloud-

free skies, which will. This lead to the averaged uncertainty increments of 0.19 m/s for 15:00 orbit and 0.27 m/s for the 15:00

12:00 orbits, respectively. Considering that the impact of the SBR on the wind observations is minimal on a dawn-dusk orbit, and reaches the maximum on a noon-midnight orbit, the phenomenon indicates the selection of the LTAN of a sun-synchronous orbits will make-result in a maximum difference of 0.27 m/s in the global average wind observation uncertainties a maximum

515 difference of 0.27 m/s for the Rayleigh channel of Aeolus-type DWLs near the summer and winter solstices. Furthermore, the average global averaged uncertainty is 2.61 m/s ies without the impact of the SBR is 2.61 m/s, and the average global averaged uncertaintiesy is 3.04 m/s under the worst SBR cases offor Rayleigh channel on the orbit with an LTAN of 12:00. Theis fact illustrates that the maximum increase in the averaged value of average global wind observation uncertainty by about due to SBR is 3.04–-2.61=0.43 m/s for Aeolus-type DWLs operating on the sun-synchronous orbits-due to SBR. In addition, the statistics 520 show that 71.35% of the bins of Aeolus can-meet the accuracy requirements of the ESA in the free troposphere and in the stratosphere near the summer and winter solstices. For the two new spaceborne DWLs, the percentages are 63.45% for the orbit of 15:00 and 60.67% for the orbit of 15:00 and 12:00 orbits. Therefore, it is necessary to increase the laser pulse energies of the two new spaceborne DWLs to promote wind observation accuracy and to increase the percentages of bins which that could meet accuracy requirements of the ESA. On the other hand Moreover, the wind observation uncertainties are sensitive to 525 the laser pulse energiesy, and results inof this paperstudy show that the percentages of bins which could that meet the accuracy requirements of the ESA would increase by 10% with when the laser pulse energy is increased by anonly averaged of only increment of 6.75 mJ in laser pulse energies considering for the three orbits.

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-To quantitatively design the required laser pulse energies of the new spaceborne DWLs to so that they meet the specific accuracy requirements, i.e., to meet the accuracy requirements of the ESA, or to reach the similar accuracy level of Aeolus, the relationship between the SNR and the uncertainty of the response function of the Rayleigh channel is was established based on some-several assumption and simplifications, which is proven of This is demonstrated to have a wide feasibility by simulation experiments, asymptic is shown in the Appendix. Finally, the a method to of derivinge the required laser energies according to the accuracy requirements is proposed.

According to the method, tThe required energy is determined by temperature, pressure, wind uncertainty, SBR, and noise of instrument, and thus, the required laser pulse energies are different in different bins. Therefore, the laser pulse energies of the spaceborne DWLs should be determined through based on the statistics. Considerations are givenIn order to reach both of reaching the accuracy level of Aeolus and improving improve the forecast results of the NWPs, and taking the existing technical level of spaceborne DWLs into account, the laser pulse energies of two new spaceborne DWLs wereare set to 70 mJ, while other parameters are were the same as those of Aeolus. Based on the proposed parameter proposals, 89.04% and 77.34% of the bins-can reach the accuracy level of Aeolus on for the two new15:00 and 12:00 orbits. And Moreover, the percentages of the bins that meet the ESA's accuracy requirements are 77.19% and 74.71% for the two new spaceborne DWLs, of which values are higher than that of Aeolus (71.35%), and are closely equivalent to the percentage offor 76.46% when Aeolus when it is are free of the impact of the SBR. The averaged uncertainties of the two new spaceborne DWLs with laser pulse energies

of 70 mJ in <u>the</u> free troposphere and stratosphere are 2.62 and 2.69 m/s<sub>a</sub> respectively, which perform better than that of Aeolus (2.77 m/s). Furthermore, when the laser pulse energies of <u>the</u> two new spaceborne DWLs increase from 60 mJ to 70 mJ, the <u>average</u> global <u>averaged</u> wind observation uncertainties <u>will</u> decrease <u>by</u> about 0.34 m/s under the impact of <u>the</u> maximum SBR. In summary, it is necessary to increase the laser pulse energies of <u>the</u> two new Aeolus-type spaceborne DWLs operating on the sun-synchronous orbits with LTANs of 15:00 and 12:00. The wind measurement accuracy <u>has beenis</u> greatly improved when <u>the</u> laser pulse energies <u>are</u> increased from 60 mJ to 70 mJ.

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The essence of lowering the wind observation uncertainties of spaceborne DWLs by increasing the laser pulse energies is to increase the SNR of <u>the</u> received signal. Other methods can be used to improve the SNR of <u>the</u> received signal, such as enlarging the telescope aperture or reducing <u>the</u> vertical resolution. Once the quantitative relationship between these instrument parameters and the SNR is established, we can also quantitatively adjust these parameters according to <u>our\_the</u> accuracy requirements as-using the method shown-described in this paper.

#### 555 Appendix

To build the relationship between <u>the</u> laser pulse energies and uncertainties of wind observations for Aeolus-type spaceborne DWLs, we derived the relationship between the response function and <u>the</u> SNR of <u>the</u> Rayleigh channel. According to Eqs. (3) and (4), the uncertainty of response function of Rayleigh channel can be written as follows based on the assumption that  $N_A \approx$  $N_B$  and  $N_{S,A} \approx N_{S,B}$ ,

$$\begin{aligned} \sigma_{R_{ATM}} &= \frac{2}{(N_A + N_B)^2} \sqrt{N_B^2 (N_A + N_{S,A} + N_{noise}^2) + N_A^2 (N_B + N_{S,B} + N_{noise}^2)} \\ &\approx \frac{2}{4N_A^2} \sqrt{2N_A^2 (N_A + N_{S,A} + N_{noise}^2)} \\ &= \frac{\sigma_A}{\sqrt{2N_A}} \end{aligned}$$
(A1)

According to Eq. (6), the SNR of the Rayleigh channel for spaceborne DWLs can be expressed as

$$SNR_{Ray} = \frac{N_A + N_B}{\sqrt{N_A + N_B + N_{S,A} + N_{S,B} + 2N_{noise}^2}}$$

$$\approx \frac{2N_A}{\sqrt{2(N_A + N_{S,A} + N_{noise}^2)}}$$

$$= \frac{\sqrt{2}N_A}{\sigma_A}$$
(A2)

Therefore,

$$SNR_{Ray} \approx \frac{1}{\sigma_{R_{ATM}}}$$
 (A3)

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As is the equations derivation process shown in Sect-<u>ion</u> 3.2, the relationship between <u>the</u> SNR and <u>the</u> uncertainty of response function shown in Eq. (A3) is the basis to derive the relationship between <u>the</u> laser pulse energy and <u>the</u> wind observation uncertainty shown in Eqs. (10) and (11). However, Eq. (A3) is derived through assumption and simplifications, especially the assumption  $N_A \approx N_B$ , of which the values may be of large differences when the absolute values of HLOS wind

speed are large. To test the correctness of Eq. (A3) in the actual atmosphere with variable wind speed, we verified the equation

570 using reanalysis data, aerosol optical parameters database LIVAS and surface albedo database. The verification process is shown in Fig. A1.

The reanalysis data <u>is-were\_obtained</u> from the 20th Century Reanalysis Project (Compo *et al.*, 2011). In the validation experiments, the monthly averaged 24 level profiles of <u>the</u> temperature, pressure, u- and v-components of the wind with  $1^{\circ} \times 1^{\circ}$  spatial resolutions <u>are-were\_obtained</u> from the reanalysis data. In this study, the reanalysis data for June 2015 and December 2015 <u>are-were\_used</u> as the atmospheric conditions in summer and winter, respectively. As is shown in Fig. A1, the verification process <u>of-described by Eq.</u> (A3) can be described as follows.

(1) The off-nadir points of <u>the</u> spaceborne DWLs are obtained using orbit simulation software based on the orbit information of <u>the</u> spaceborne DWLs.

(2) The profiles of <u>the</u> temperature, pressure, wind speed, aerosol optical parameters, and surface albedo are interpolated
 into the off-nadir points.

(3) The SBR values of the off-nadir points are derived using the RTM libRadtran with the inputs provided in step (2).

(4) The profile values of  $N_A$ ,  $N_B$  and  $N_{S,A}$ ,  $N_{S,B}$  are figured outdetermined using spaceborne DWL simulation system mentioned described in Section- 2.2 with the inputs of SBR and atmospheric conditions of the off-nadir points.

(5) The values of  $\sigma_{R_{ATM}}$  and  $SNR_{Ray}$  are obtained using Eqs. (3), (4), and (6). In addition, according to the ADM-Aeolus ATBD Level\_1B products (Reitebuch *et al.*, 2018), the noise of the detection chain for each measurement is 4.7 e<sup>-</sup>/pixel. And There are 30 measurements are include in one observation, therefore,  $C = 2N_{noise}^2 = 2 \times (4.7 \times 30)^2 = 39762$  in Eq. (10), which cannot be not negligible.



Figure A1. The verification process of Eq. (A3).

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The scatters of  $\sigma_{R_{ATM}}$  and  $1/SNR_{Ray}$  are plotted to verify the accuracy of Eq. (A3), as is shown in Fig. A2. The spatial resolution of the reanalysis data is 1°×1°, so the earth Earth is divided into 1°×1° grids during the verification process, and one

off-nadir point in each grid is selected as the verification point. Considering the SBR in summer and winter, and excluding some grid points with invalid data, a total of 28460 profiles are used in <u>this the</u> verification. Each profile contains 24 bins, <u>and</u> the verification uses 683040 scattered points.

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In the verification, the HLOS wind components derived from u- and v-wind components ranges from -73.02 to 33.14 m/s. Fig. A2 illustrates that the scatter-points plot between of the reciprocal SNR and versus the uncertainty of the response function of the Rayleigh channel is plot very close to the line y = x line, which demonstrates that the assumption and simplifications used in deriving the relationship between the laser pulse energy and the uncertainty of the wind observation are reasonable, and Eq. (A3) is of has a wide applicability and feasibility in the real atmosphere.



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**Figure A2.** The scatter plot between of the reciprocal SNR versus theand uncertainty of the response function of the Rayleigh channel and their first order fitting relationship.

The variables used in the verification of Eq. (A3) can <u>be</u>-also <u>be</u> used in the verification of Eq. (11). The variable of  $\partial v_{HLOS}/\partial R_{ATM}$  is also needed, which. It is the <u>a</u> function of temperature and pressure, and can be obtained through a precalculated lookup table. The verification results of for Eq. (11) are shown in Fig. A3.



Figure A3. The scatter plot of the <u>values of x values</u> which are derived from Eq. (11) and simulation system <u>which</u>. And x is the sum of  $N_A$  and  $N_B$ -respectively.

As is shown in Fig. A3, the fitting line of the scatterpoints on the plot of value-the x values derived from Eq. (11) and versus the values derived from the simulation system is plot very close to the line y = x line. Furthermore, the residuals

between the <u>scattered</u> points and the fittinged line are very small, which indicates the wide feasibility and applicability of Eq. (11). In addition, it is noteworthyshould be noted that the scattered points of in Fig. A3 are mostly located plot below the line y = x line, which indicates that the <u>value of x values</u> calculated by using Eq. (11) is are smaller than the actual values. According to Section: 3.3, the laser pulse energy is derived based on the equation  $E_{new}/E_{Aeolus} \approx x2/x1$ ; aAnd x1 is obtained from the simulation system, which is regarded to be close to the real value. The A smaller x2 may lead to a smaller  $E_{new}$ , which is about 0.97 times to the real value.

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*Code and Data availability*. The codes in this article are mainly compiled using matlab and are available upon request from the first author by email, zhang01020@hotmail.com. The databases used in this paper include: OMI database, which provided the latitude-averaged temperature, pressure, and ozone, can be accessed via anonymous ftp from toms.gsfc.nasa.gov/pub/LLM\_climatology; LIVAS database, providing the golabl aerosol optical properties with 1°×1° grid, offered by Dr. V. Amiridis from Institude for space applications and remote sensing, National observatory of Athens, and can be assessed from http://lidar.space.no a.gr:8080/livas/; the global LER database is available upon request from the authors, Dr. R. B. A. Koelemeijer from Air Research Laboratory, National Institute of Public Health and the Environment, robert.koelemeijer@rivm.nl; and the reanalysis data of 20th Century Reanalysis provided by the NOAA/OAR/ESRL PSD, Boulder, Colorado, USA, from their Web site at https://www.esrl.noaa.gov/psd/.

*Author contributions.* CZ, XS, and WL designed the studies; CZ built the simulation systems, performed the computation and analysis, and wrote the paper text; YS, ND, and SL provided important information on data delivery and processing. All authors engaged in discussions on studies, interpretation of results, as well as contribution to the finalization of the paper text. *Competing interests.* The authors declare that they have no conflict of interest.

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