

## Water vapor density and turbulent fluxes from three generations of infrared gas analyzers

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**Abstract.** Fast-response infrared gas analyzers (IRGAs) have been widely used over three decades in many ecosystems for long-term monitoring of water vapor fluxes in the surface layer of the atmosphere. While some of the early IRGA sensors are still used in these national and/or regional eco-flux networks, optically-improved IRGA sensors are newly employed in the same networks. The purpose of this study was to evaluate the performance of water vapor density and flux data from three generations of IRGAs – LI-7500, LI-7500A, and LI-7500RS (LI-COR Bioscience, Inc., Nebraska, USA) – over the course of a growing season in Bushland, Texas, USA in an irrigated maize canopy for 90 days. Water vapor density measurements were in generally good agreement, but temporal drift occurred in different directions and magnitudes. Water vapor density fluctuation means exhibited mostly shift changes that did not impact the flux magnitudes, while their variances of water vapor density fluctuations were occasionally in poor agreement, especially following rainfall events. LI-7500 variances were largest compared to LI-7500RS and LI-7500A manifesting in cospectra, especially under unstable and neutral static stability. Agreement among the sensors was best under the typical irrigation-cooled boundary layer, with a 14% interinstrument coefficient of variability under advective conditions. Generally, the smallest variances occurred with the LI-7500RS, and high-frequency spectral corrections were larger for these measurements resulting in similar fluxes between the LI-7500A and LI-7500RS. Fluxes from the LI-7500 were best representative of growing season evapotranspiration based on a world-class lysimeter reference measurement but using the energy balance ratio as an estimate of systematic bias corrected most of the differences among measured fluxes.

## 1. Introduction

35 The eddy covariance (EC) method is a standard way to monitor water vapor flux between the surface and atmosphere at most spatial scales and environments, including marine (Honkanen et al., 2018; Takahashi et al., 2005), forest (Novick et al., 2013; Zhang et al., 2012), grassland (Haslwanter et al., 2009; Hirschi et al., 2017), and cropland (Ding et al., 2013; Kochendorfer and Paw, 2011). In water-limited regions, the need to conserve a subsurface source, such as the U.S. Ogallala Aquifer, serves as motivation for agricultural producers to estimate the crop water use for daily irrigation scheduling (Xue et al., 2017). Current crop production involves innovative water saving measures, such as variable rate irrigation management, requiring high quality evapotranspiration (ET) data to supplement efforts to calculate the correct amount of water to apply to crops (O'Shaughnessy et al., 2016). In ecosystem networks both large (FLUXNET Baldocchi et al., 2001), and small (e.g., Delta-Flux see Runkle et al., 2017), as well as at individual research fields in Texas (Evelt et al., 2012a) and California (Oncley et al., 2007), the IRGAs built by LI-COR Biosciences, Inc. (Lincoln, Nebraska, USA) have been widely used for over two decades to monitor water vapor fluxes.

The accuracy of ET measurements relative to a reference system can be assessed to investigate potential systematic problems with instrumentation (Mauder et al., 2006). Based on this analysis, an open-path, nondispersive infrared gas analyzer (IRGA) has long been selected as the standard fast-response hygrometer for decades after the era of Lyman-alpha and krypton hygrometer absorption sensors (absorption of ultraviolet radiation by water vapor, e.g., Kaimal and Finnigan, 1994). The optical sensor of the IRGA detects water vapor through differential or ratio measurement of infrared transmittance at two adjacent wavelengths with one located in a region of large water vapor absorption and the other where absorption is negligible (Kaimal and Finnigan,

1994). The transmitting path is typically 0.2-1.0 m long, and beams are usually modulated by a mechanical chopper to permit high-gain amplification of the detected signal. Generally, such an optical device is unreliable when air humidity reaches saturation (rainfall or dew) because of liquid  
60 water present in optical pathways. The ratio detecting technique used to improve the signal-noise ratio of water vapor signals and also removes the common noise in the absorption path length. For water vapor detected in all LI-COR 7500 models, the ratio of these measurements determines an estimate of vapor absorptance, which is converted to a concentration or density (absolute humidity),  $\rho_v$ , using a third-order calibration polynomial. Any biases occurring in this absorption,  
65 therefore, propagate to  $\rho_v$  measurement errors. Fratini et al. (2014) described contributing factors to this error, including the magnitude of absorptance fluctuations, and showed that drift in the calibration zero of  $\rho_v$ , i.e., the bias, tends to occur in steps rather than in a continuous fashion.

The IRGA specifications for water vapor density measurement  $\rho_{v,m}$ , including accuracy, precision, and drift have been unchanged over three models of sensors: LI-7500, LI-7500A, and LI-7500RS.  
70 The LI-7500 was first introduced in 1999, followed by the LI-7500A in 2010 and LI-7500RS in 2016. The differences between the LI-7500 and LI-7500A reported by LI-COR primarily address electrical power requirements in cold climate conditions and ease of use. Progressing from the LI-7500A to the LI-7500RS, while no physical differences are evident, optical changes were made to improve the stability of measurements in the presence of window contamination which can cause  
75 systematic bias (Heusinkveld et al., 2008). LI-COR reported that  $\rho_{v,m}$  drift was more than an order of magnitude smaller in the LI-7500RS than the original LI7500A and was accompanied by reduced interinstrument variability (Burba et al., 2018). They also found that after rainfall, LI-7500A and LI-7500RS measurements were similar but agreement lessened after approximately one week. As the duration of IRGA deployment increases from weeks to months and years,

80 calibration becomes more important to ensure accuracy for fast-response water vapor  
measurements since their measurement stability is relatively low (Iwata et al., 2012). The factory  
calibration procedure, resulting in span and zero coefficients, consists of measured water vapor  
density being compared to the absorption of water vapor from a dewpoint generator over a range  
of temperatures from 17 to 41°C. Based on the manufacturer calibration and re-calibration sheets  
85 (after a certain period the IRGA is returned to the manufacturer for re-calibration), the span drift  
is primarily a function of temperature, whereas the zero drift is chiefly influenced by the  
measurement range of water vapor density.

In addition to the IRGA, a sonic anemometer is necessary to determine water vapor flux. This pair  
of instruments introduces systematic error due to their physical separation, which is a source of  
90 high frequency turbulent signal loss (Massman, 2000). The magnitude of flux attenuation is  
enhanced by lighter wind speed and a greater ratio of horizontal separation to sensing height (Horst  
and Lenschow, 2009). The expected cospectra, or eddy flux in the spectral domain, can be  
estimated analytically with a series of transfer functions (Massman, 2000; Moncrieff et al., 1997)  
that account for signal loss at low and high frequencies. A spectral correction factor can often be  
95 determined based on how this modeled cospectrum departs from the measured cospectrum,  
indicating the degree of flux loss for a given observation period and EC system.

To address offset errors of water vapor density from an IRGA, data are typically compared to  
another type of sensor. In a comparison to the enclosed-path EC155 system (Campbell Scientific,  
Logan, UT, USA), errors in water vapor density were generally between -3 and 3 g m<sup>-3</sup> (Novick et  
100 al., 2013). Such errors were largest in early to mid-morning hours coinciding with the likely  
formation of dew and fog, and after bias correction, the linear regression slope and offset were  
1.01 and 1.68 g m<sup>-3</sup>, respectively. In a study involving an LI-7500 and Krypton hygrometer in a

semi-arid climate where rainfall is irregular (34.6 mm in three events from approximately three weeks of data), flux comparisons were made using simple linear regression (Martínez-Cob and Suvočarev, 2015). With the Krypton hygrometer being unable to measure absolute concentration of water vapor, comparisons of  $\rho_v$  data were not made. In this case,  $\rho_v$  can be calibrated to a sensor explicitly designed to determine absolute humidity. This calibration should be stable (avoid short timescale errors) and not drift (avoid long timescale errors). In an environment prone to contamination, the measurement timeframe could be 1–2 weeks (Iwata et al., 2012). Accurate water vapor determination is also crucial in flux processing procedures, specifically to account for air density fluctuations which complicate the effect of error propagation into water vapor flux (Fratini et al., 2014).

Due to the high expense of infrared gas analyzers (IRGA), there is little research intercomparing multiple instruments except by the manufacturer itself. Historically, instrumentation errors from EC systems average 10–20%, with additional contributions from random errors and a smaller, non-negligible amount from systematic bias (Alfieri et al., 2011). Gas analyzers from the same manufacturer have been shown to differ in short-term drifts (Moncrieff et al., 2004). Here, we assess three generations of LI-7500 instruments in advective field conditions over 90 days by evaluating differences in water vapor density measurements and how those differences impact the estimation of the turbulent exchange of water vapor compared with that measured using a large weighing lysimeter. Flux characteristics and how they deviate over the course of the growing season are also analyzed to determine any advantages one set of water vapor analyzer may have over other models.

## 2. Data and Methods

### 125 2.1 Site description and measurements

The field study was conducted between 16 June [day of the year (DOY) 168] and 13 September 2016 (DOY 257) on the lysimeter field at the USDA-ARS Conservation & Production Research Laboratory, Bushland, Texas (described by Moorhead et al., 2019), located in the Texas panhandle (35.19° N, 102.09° W, 1170 m elevation above sea level). Corn (*Zea mays* L.) was planted on 10  
130 May, with emergence eleven days later, and thereafter crop height grew steadily during the first part of the study period. From 20 June to 19 July, crop height  $h_c$  increased nearly linearly from 0.85 m to its peak of 2.30 m. After this point, plants were in their reproductive stage with a decreasing leaf area index trend ensuing. The high ET demand of corn during its development is well known and necessitated irrigation to complement precipitation. Both in intensity and  
135 frequency, precipitation was erratic (Evelt et al., 2019) as typical for a semi-arid climate, which is mostly in the range of 250–350 mm (Gowda et al., 2009; Tolk et al., 2013) during the corn growing season at Bushland.

The EC experiment included three systems consisting of IRGA models LI-7500, LI-7500A, and LI-7500RS, with a sonic anemometer (CSAT3, Campbell Scientific, Inc., Logan, UT, USA),  
140 sampling at 20 Hz. Each IRGA outputs CO<sub>2</sub>, H<sub>2</sub>O, barometric pressure, and a diagnostic value indicating signal strength and statuses of optical wheel rotation rate, detector temperature, and chopper temperature. The gas analyzers were mounted at a height of 4.6 m above the ground ( $\geq 2$   
 $h_c$ ), facing southward with the anemometers situated west of the gas analyzers perpendicular to the dominant (southerly) wind direction. Two systems (EC1 and EC2) were at a tower instrumented  
145 with an LI-7500RS, LI-7500A, and CSAT3. The horizontal separation between each gas analyzer

and the sonic anemometer was approximately 10 cm and 20 cm, respectively. This spacing on the same tower is comparable to a recent intercomparison of fluxes from two open-path IRGAs (Polonik et al., 2019). The third system (EC3) affixed on a tower 26 m to the south, had an LI-7500 and CSAT3 separated by 10 cm horizontally. All gas analyzers were approximately 10 cm lower than the sonic anemometers and angled slightly downward in accordance with the manufacturer's recommendation to reduce collection of water droplets and contamination on the lens. Both towers had reference  $\rho_v$  data from an air temperature-humidity probe (HMP 155A, Vaisala, Helsinki, Finland) containing a capacitive-type humidity sensor (HUMICAP 180R, Vaisala, Helsinki, Finland). Ancillary data were taken of net radiation  $R_n$  (NR-LITE2, Kipp & Zonen, Delft, The Netherlands) at 2.6 m above ground, soil heat flux  $G$  (HFT-3.1, Radiation and Energy Balance Systems, Seattle, WA, USA) at 8 cm below ground, and thermistors and water-content reflectometers (CS655, Campbell Scientific, Inc., Logan, Utah, USA) at 2 and 6 cm below ground, which were used to estimate soil heat storage (Kutikoff et al., 2019).

## 2.2 Data processing and statistical analysis

Water vapor density data among the three infrared open-path IRGAs were compared in a fashion similar to Mauder et al. (2006). The following characteristics of variance ( $\overline{\rho_v' \rho_v'}$ ) and covariance ( $\overline{w' \rho_v'}$ ) were of interest: regression intercept ( $a$ ), slope ( $b$ ), and coefficient of determination ( $r^2$ ); root mean square deviation ( $rmsd$ ); and bias ( $d$ ). Comparability between LI-7500RS and the other two models was found using  $rmsd$ , defined as:

$$rmsd = \sqrt{\sum (x_{A,i} - x_{REF,i})^2}, \quad (1)$$

where  $x_{A,i}$  is the  $i^{\text{th}}$  observation for the LI-7500/A and  $x_{REF,i}$  is the  $i^{\text{th}}$  observation for the reference LI-7500RS. Interinstrument variability was also determined by *rmsd* except using the average value of three IRGAs or three EC systems as a reference value. For fluxes, interinstrument variability was expressed relative to flux magnitude using the coefficient of variation ( $CV_{I-J}$ ). The data de-spiking process set all data beyond the upper ( $30 \text{ g m}^{-3}$ ) and lower ( $2 \text{ g m}^{-3}$ ) values as missing. Both upper and lower bounds were estimated by all possible water vapor density observations during the growing seasons in Bushland, Texas. Additionally, while the LI-7500A and LI-7500 were calibrated in 2014 and 2015, a correction to these data was made based on a factory calibration after data was collected. Otherwise, no additional conditioning was performed on the raw data. Given the interest in sensor sensitivity, comparisons were also made between collocated HMP155A and IRGA(s) at each tower, which were assumed to be sensing identical air parcels containing equal water vapor density.

To further ascertain the performance of IRGAs, (co)spectral density of  $\rho_v$  ( $w\rho_v$ ) measurements were calculated for each of three EC systems using Welch's periodogram method (Blanken et al., 2003). The distribution of power across frequencies, particularly signal loss at high frequencies, can indicate differences in flux characteristics with an expectation that latent heat would be underestimated. Of particular interest are results from an advective environment in which high frequency variation is enhanced (Prueger et al., 2012). This condition was defined by finding half-hour observations between 10:00 and 18:00 LST in which latent heat exceeded available energy (a difference between net radiation and soil heat flux), or sensible heat flux was significantly negative ( $\leq -10 \text{ W m}^{-2}$ ) (Kutikoff et al., 2019). Data were conditioned by linear detrending on half-hour (36,000 points) segments (Zhang et al., 2010). Spectral density ( $S_{\rho_v}$ ) was calculated across these segments with a Hamming window length of 360 and overlap of 180 observations. Then the



spectra were averaged into 100 evenly spaced bins on the logarithmic scale. The same procedure  
190 was repeated for the cospectra of vertical velocity and water vapor density, indicating the behavior  
of water vapor flux in the spectral domain. Finally, ogives were calculated to summarize  
differences in cospectra across wavelengths by integrating the cospectra from low-frequency  
energy to high-frequency energy on a scale from 0 to 1. The (co)spectra and ogives were multiplied  
by the frequency and normalized by mean (co)variance to make the data dimensionless.

195 After examining raw variances and covariances, water vapor fluxes ( $E$ ) were processed using  
Eddypro (v6.2.0) software (LI-COR Bioscience, Lincoln, Nebraska, USA) for half-hour averaging  
periods when availability of data exceeded 90% ( $w$  and  $\rho_v$  were recorded for at least 32,400 of  
36,000 possible observations). Prior to computing fluxes, a statistical screening of time series data  
was implemented. Spikes were detected using the median absolute deviation for each half-hour  
200 (Mauder et al., 2013) and replaced with the half-hour mean of non-outlier observations. Then data  
was detrended by block average and corrections were made to account for sensor separation, tilt  
of the sonic anemometer via double rotation (Fratini and Mauder, 2014), and spectral energy loss  
in both low (Moncrieff et al., 2004) and high (Moncrieff et al., 1997) frequency ranges. The  
original water vapor flux was multiplied by the spectral correction factor of  $\overline{w'\rho_v'}$  before adding  
205 WPL density fluctuation terms (Kaimal and Finnigan, 1994). Sensible heat ( $H$ ) was then corrected  
for humidity effects that arise from using sonic temperature in place of air temperature (Van Dijk  
et al., 2004). Finally, this corrected  $H$  was multiplied by its spectral correction factor, and the WPL  
term was added to the corrected water vapor flux to create a final  $E$  or  $\lambda E$ . Approximately 13.5%  
of available data were removed through the results of steady-state and fully developed turbulence  
210 tests (Mauder and Foken, 2004). The acquisition ratio of each half-hour was obtained by dividing  
the count of non-filtered fluxes by the maximum number of observations (Kim et al., 2015).

Intercomparison of  $\lambda E$  and its systematic error ( $\delta$ ) and random uncertainty ( $\varepsilon$ ) components was conducted on half-hourly and daily timescales. The measured  $\lambda E$  is assumed to be the difference between the actual flux and these errors. Systematic error can be evaluated in the context of surface energy balance, such that  $\delta$  is zero when turbulent flux equals the available energy measured through solar radiation, ground heat flux, and heat storage during a given period (Mauder et al., 2013). The estimate of systematic error is then

$$\delta = \lambda E \left( \frac{1}{EBR} - 1 \right), \quad (2)$$

and

$$EBR = \frac{H + \lambda E}{R_n - G - J}, \quad (3)$$

where the terms in the numerator are independent ( $H$  is sensible heat flux, and  $\lambda E$  is latent heat flux) for each EC system and those in the denominator are shared among the EC systems.  $J$  was calculated as the sum of soil and photosynthesis heat storage since the other components of heat storage contribute negligibly to instantaneous energy balance in this ecosystem (Kutikoff et al., 2019). Random error associated with sampling was quantified with the method of Finkelstein and Sims (2001), which calculates the variance of the covariance using the raw timeseries data for each averaging period. Together, error quantification can indicate if half-hour fluxes from the three EC systems statistically differ for half-hours in which turbulent flux measurements are reliable.

Water vapor flux was compared using the equivalent total water depth  $ET$  for daily totals. Gap filling, following Reichstein et al. (2005), was done for half-hours that were flagged for any of the three EC systems based on steady-state and developed turbulence tests (Mauder and Foken, 2004), occurrence of precipitation, and high relative humidity ( $RH > 95\%$ ). Total gap-filled  $ET$  was close

to the sum of the half-hour observations, with approximately a 3% greater flux for each EC system. Flux accuracy of the three EC systems was assessed in relation to a large weighing lysimeter, which has an accuracy of  $0.05 \text{ mm hr}^{-1}$  (Evetts et al., 2012b). Located within 30 m of the EC system, lysimeter ET was computed using a soil water balance approach from a subsection of the same field. Briefly, the mass change of water measured by the weighing lysimeter was calculated and converted into a flux based on the surface area of the lysimeter and density of water. Description of the lysimeter data can be found in Moorhead et al. (2017).

### 240 3. Results

The findings of the study are presented in three subsections, including water vapor density mean and fluctuations, spectra and cospectra, and fluxes. All were influenced by irrigation and precipitation events. Water added to the field included 498 mm from 33 separate subsurface drip irrigations (SDI) (Evetts et al., 2019) and 238 mm of precipitation (Evetts et al., 2018), consistent with an average growing season (Gowda et al., 2009; Tolk et al., 2013). However, much of that rainfall (88%) occurred after 1 August, and combined with crop maturity, eliminated the need for irrigation after 18 August.

Data filtering also impacted all comparisons. After all threshold and precipitation screenings, 3,577 out of a possible 4,320 half-hour observations are available for analysis. The acquisition ratio was comparable to similar studies (Wu et al., 2015). Between 9:00 AM and 9:00 PM (LST), the ratio exceeded 92%, whereas EC system issues reduced availability in the predawn hours to as low as 61% for the half-hour ending at 7:00 AM (Fig. 1).

### 3.1 Water vapor density validation

The long-term zero drift of water vapor density for the three IRGAs was evaluated as the three-month change in bias  $\Delta\rho_v$ . As the study period began, the reference value of water vapor density  $\rho_{v,r}$  ranged from 3 to 18 g m<sup>-3</sup>. Accordingly, the measured values  $\rho_{v,m}$  for the LI-7500 and LI-7500RS were biased low and the LI-7500A was biased high. After applying the post-correction to the LI-7500 and LI-7500A data, all  $\rho_{v,m}$  were between 0.11 and 1.31 less than  $\rho_{v,t}$  (Fig. 2). At the end of the study period, all IRGAs clearly showed an increased bias relative to the HMP155. Interestingly, the LI-7500 and LI-7500A had moved towards larger values, whereas the LI-7500RS moved towards smaller values (Fig. 2). That resulted in the LI-7500  $\Delta\rho_v$  decreasing, whereas the other two newer analyzers ended with greater  $\Delta\rho_v$ . The magnitude of bias was larger for the LI-7500 and LI-7500A than the LI-7500RS and a similar degree of day/night variability (sensitivity to solar radiation) was apparent among the IRGAs regardless of  $\overline{\rho_v}$ . These temporal patterns may indicate a low frequency modulated signal hidden in the instruments.

The divergence of  $\rho_{v,m}$  between early and late times in the study period is the result of many short-term changes in bias. To assess short-term drift  $\Delta\rho_v$ , half-hour differences between LI-7500s and HMP155s were calculated, with each timeseries bias corrected to set the initial value to zero (Fig. 3). The magnitude of daily drift averaged 0.09 g m<sup>-3</sup> for the LI-7500RS, 0.1 g m<sup>-3</sup> for the LI-7500A, and 0.13 g m<sup>-3</sup> for the LI-7500. Over 10-day periods, this drift increased to 0.36, 0.27, and 0.29, respectively. Rainfall contributed to the bulk of changes in drift. Rain-free periods as noted over the initial 10 days, gave the best insight into the stability of the sensors, and suggested that the LI-7500RS performed best. However, the extended dry period between DOY 186 and DOY 196 suggested the opposite, when the LI-7500RS suffered from large short-term drift. After this time,

275 the LI-7500RS appeared to be more stable, with steady *rmsd* over the final 50 days compared to the other two instruments.

According to Figs. 2 and 3, analyzer performance differed between day and night. This diel cycle is indicative of a solar radiation-induced error (Mauder et al., 2006; Miloshevich et al., 2009) and although amplitude varies, it appeared most prominently for the LI-7500 and least substantially  
280 for the LI-7500A. Periods with more instrument drift were coincident mainly with larger cycles, but the sudden performance change of the LI-7500RS on DOY 191 did not reflect this tendency. Accidental window contamination may explain this observation, with typical behavior of absolute humidity from the LI-7500RS resuming from DOY 192 onward.

To investigate the unexpected large drift exclusive to the LI-7500RS on DOY 191,  
285 biometeorological data were assessed. Light southerly winds and moderately humid conditions were observed when  $\Delta\rho_{v,RS}$  increased from -0.96 to -2.45 between 8:30 and 9:30 PM LST. While nothing unusual occurred meteorologically, a 3°C drop in temperature and 10% increase in RH accompanying the loss of daytime heating was noted. It was instructive to look at the variation in RH as estimated using vapor and ambient pressure from the IRGAs and sonic temperature from  
290 the CSAT3. While the magnitude of RH did vary slightly among the sensors, the increase in RH was similar for the LI-7500 and LI-7500A while being less than half for the LI-7500RS. In the hours immediately prior and after, the slopes of  $\Delta\rho_{v,RS}$  among the IRGAs and HMPs were nearly in lockstep. Unlike other deviations that exist on a sub-daily timescale, this new offset continued until DOY 197. Step changes are a dominant feature in the linear regression between  $\rho_{v,75/A}$  and  
295  $\rho_{v,75RS}$ .

Differences between the means and fluctuations of  $\rho_v$  are summarized in Fig. 4 as a function of day of year. Since variance of the  $\rho_v$  time series reflects the mean of squared fluctuations  $\overline{\rho_v'^2}$ , greater variance in the half-hourly data reflects larger fluctuations  $\rho_v'$ . While the LI-7500 tended to have consistently greater  $\overline{\rho_v'^2}$  values, the comparison between the LI-7500A and LI-7500RS was more complicated. For example, the LI-7500A initially had slightly larger or the same fluctuations as the LI-7500RS for most daytime observations. After noon on DOY 196, the LI-7500RS consistently began to have larger fluctuations. Then from midday on DOY 226 to DOY 232 noon, the pattern flipped again. Following DOY 232, agreement was consistently close until DOY 254, and greater fluctuations from the LI-7500A were again found through the remainder of the study period. Even when the LI-7500RS fluctuations tended to be relatively large, it did not have the large overestimation of fluctuations observed periodically with the LI-7500A, such as noted on DOY 184, 190, 193, 211, 216, and 253. While the stochastic nature of turbulence is partially responsible for the large scatter in  $\overline{\rho_v'^2}$  shown in Fig. 4, the degree of variance in the older sensors exceeded that of the LI-7500RS.

Agreement between  $\overline{\rho_v}$  of the LI-7500RS and the older IRGAs was generally strong and stable despite occasional large errors. In the first week of the study, regardless of the absolute error, linear regression parameters indicated well-calibrated measurements for the purpose of eddy covariance, in which offset has no effect on the statistic. During the middle 30 days of the study, agreement was also high, reflected by  $r^2$  values of 0.94 and 0.97 and slopes of 0.98 and 0.93, respectively for LI-7500 and LI-7500A. Little change from those parameters occurred across a wide range of  $\rho_v$  during the final 30 days of the study, when lower temperature and higher relative humidity reduced evaporative demand. As expected, greater comparability in  $\overline{\rho_v}$  was accompanied by a small  $\rho_v'$  error. However, while step changes in  $\overline{\rho_v}$  occurred,  $\rho_v'$  did not change over time.

Variance of water vapor density  $\overline{\rho_v'^2}$  was compared using the LI-7500RS as reference, for the entire  
320 dataset including daytime and advective periods only (Table 1). Nighttime estimates were  
particularly prone to overestimation by the LI-7500. Advective periods were prone to greater errors  
while having reduced interinstrument variability.

### 3.2 Spectra and cospectra

Since the three analyzers had the same specifications and were configured to measure turbulence  
325 in the same fashion, any deviations in spectral characteristics would be an indication of possible  
drift. Returning to the distinct LI-7500RS error on DOY 191, spectra were examined during the  
interval from 8:00-9:30 PM (LST), which consisted of three spectra corresponding to consecutive  
flux averaging periods. Overall, as evident from Fig. 5a–c, the shapes of spectra were in close  
agreement during the daytime, whereas the nighttime peak frequency was shifted to lower  
330 frequencies indicating the predominance of large eddies after sunset. At 8 PM, the three spectra  
were nearly identical and matched the predicted -2/3 slope (Fig. 5d). In the following hour, the  
spectra of the LI-7500A and LI-7500 remained nearly identical, whereas the LI-7500RS spectra  
were greatly modified. Based on the 20 Hz timeseries, air humidity began to decrease suddenly at  
roughly 8:40 PM in concert with a doubling of fluctuation amplitude. As the other two IRGAs and  
335 HMPs continued to indicate increasing air humidity,  $\Delta\rho_{v,LI-7500RS}$  steadily rose for nearly one  
hour until  $\rho_{v,LI-7500RS}$  again agreed with the other instruments. Because only the averaging period  
between 9 and 9:30 PM is affected by increased variance water vapor, the spectrum corresponding  
to that half-hour is the period with a shift towards higher frequencies.

Cospectra were viewed through the lens of atmospheric stability because it predicts their shape  
340 according to Monin-Obukhov similarity theory (Kaimal and Finnigan, 1994). For all cospectra,

the LI-7500 tends to have greater energy in the production and dissipation spectral regions while being nearly identical in the inertial subrange, and these differences translate into higher latent heat fluxes (Fig. 6). Lower frequency components of flux were clearly greater, especially in unstable and neutral conditions, as observed by the LI-7500 (the oldest version), compared to the  
345 LI-7500A and LI-7500RS. While the two newer sensors exhibited similar behavior and relatively smaller fluxes than the LI-7500, under unstable conditions the LI-7500RS showed a difference in performance from the LI-7500A at high frequencies. For all three IRGA, co-spectra dipped at 2.5 Hz, which should not occur in any desired instruments (Kaimal and Finnigan, 1994). Strong turbulent motions were likely captured more by the LI-7500A within the surface layer. These  
350 cospectra were shifted towards lower frequency compared to those in neutral and stable conditions, favoring larger eddy sizes with a smaller percentage of energy accumulated in the inertial subrange (Fig. 6b). This middle frequency range is where the IRGAs were most similar. Regardless of sensor, unstable conditions featured a flattened peak and more energy towards lower frequencies, as expected for various scalar fluxes measured with the same instrumentation (Wolf and Laca,  
355 2007). However, in an irrigated cropland environment, the surface layer is prone to become stable more often than the surrounding area due to a temperature inversion forced by the relatively wetter, cooler canopy. A previous study demonstrated this effect by using simultaneous sensing over adjacent irrigated cotton and non-irrigated winter wheat fields, where energy production as depicted by  $S_{\rho v}$  was two orders of magnitude smaller for the irrigated field than the non-irrigated  
360 field (Prueger et al., 2012). Accordingly, in the present study, variability among cospectra was small under these conditions with relatively few large eddies (Fig. 6e). In contrast, under neutral and unstable conditions, the LI-7500 departed largely from the other two sensors with energy contribution from low frequency eddies.



### 3.3 Water vapor fluxes

365 For much of the study period,  $\lambda E$  from the LI-7500RS and LI-7500A were similar with slightly larger magnitude than the LI-7500. Overall interinstrument variability  $CV_{I-I}$  of  $\lambda E$  was 20%, about that of the underlying water vapor variance, and errors on average were less during daytime hours than nighttime (Table 2). For an average diel cycle, the largest  $CV_{I-I}$  occurred during the middle of the night, rapidly declined after sunrise, reached its smallest value of 10% at 4 PM, and then  
370 increased at a relatively slow rate after sunset. On a seasonal basis, there was a slight, nonlinear increase in  $CV_{I-I}$  over time, with mean values increasing from approximately 16% to 24%. Overall, the LI-7500 measured a 15% greater flux than the LI-7500RS both on average and during only daytime hours. Meanwhile, LI-7500A and LI-7500RS fluxes were nearly identical, with 0.5% less flux measured by the LI-7500A and an additional 0.2% difference during the daytime. While the  
375 daily bias was as equally positive as negative, the LI-7500A tended to underestimate flux through the first and last third of the study period although possible rainfall effects exist. Greater flux was observed on 27 of the 41 days from DOY 196 – 226, which coincided with greater accumulated ET (Fig. 7). Relative error varied little by time of day. An increase in variability during advective conditions was due to greater mean (co)variance. Under advective conditions, the coefficient of  
380 determination was particularly small (see Table 2), but this advection coincided with large turbulent fluxes including downward sensible heat that was also slightly biased towards increased magnitude.

The 90-day ET (Fig. 7) was in good agreement among the three IRGAs, with slightly greater seasonal flux from the LI-7500, consistent with the larger variance in the timeseries of  $\rho_v$ .

385 Systematic underestimation of ET for all IRGAs is consistent with advective conditions, especially

in the earlier part of the growing season where the gap in daily ET is particularly large for a similar magnitude of ET (Fig. 7). Even if all spectral loss is corrected for, based on the conservation of water vapor and eddy covariance theory, the measured EC flux should be less than the true flux under advective conditions. Approximately 16% of accumulated ET was underestimated from LI-  
390 7500A or LI-7500RS relative to the accumulated lysimeter ET at the end of the growing season (Fig. 7). However, only less than 5% of accumulated ET was underestimated from the oldest LI-7000 analyzer (Fig. 7). Furthermore, the EC and lysimeter should differ more with increasing mean ET because the advective component of ET, not captured by EC systems, is more likely to be elevated (Alfieri et al., 2012).

395 The greater flux from the LI-7500 occurs nearly symmetrically on a diel basis, with relative differences smallest during the day. The mean daytime error of measured flux  $\lambda E$  between the LI-7500A and LI-7500RS systems was 4.5%, with the LI-7500A estimating greater ET than the LI-7500RS on approximately three out of every four days. Systematic error  $\delta$  averaged 0.08 mm for the LI-7500RS system, which is rather large considering the mean measuring flux of 0.2 mm.  
400 Larger systematic error is typically associated with greater flux underestimation due to failure to capture all low frequency signals, consistent with the observed cospectra (Vickers and Mahrt, 1997). In contrast, daily  $\lambda E$  differed by 18.6% between LI-7500 and LI-7500RS systems and the magnitude from the LI-7500RS only exceeded that of the LI-7500 on a single day. Comparing daily ET as a function of error, systematic error  $\delta$  calculated as shown in Eq. (2), decreases during  
405 the study period consistent with declining ET (Fig. 8). Random error  $\epsilon$  was overwhelmingly similar among the sensors, indicating that uncertainty due to sampling has little effect on differences in estimated ET.

## 4. Discussion

### 4.1 Water vapor variance errors

410 Water vapor variance and flux were compared from three generations of IRGAs yielding similar results in rain-free periods. However, large  $\overline{\rho_v}$  errors occurred under relatively small flux conditions, primarily with the LI-7500A systems. A pattern of increasing flux error corresponding with greater water vapor density error as observed by Fratini et al. (2014) was not found. These flux results are encouraging despite demonstrated substantial errors in the water vapor density  
415 measurements because the (co)variance of the water vapor density is more important for the flux quantity. Overestimation of water vapor variance could contribute to overestimated flux but is not necessarily the case (Mauder et al., 2006). During the half-hour beginning at 3:00 PM LST on DOY 181, LI-7500 underestimated flux by approximately  $20 \text{ W m}^{-2}$  despite an overestimation of  $\overline{\rho_v'^2}$  ( $3.5 \text{ g}^2 \text{ m}^{-6}$  and  $0.84 \text{ g}^2 \text{ m}^{-6}$  greater relative to LI-7500A and LI-7500RS).

420 In a vast majority of cases, large  $\overline{\rho_v'^2}$  was observed with both the LI-7500 and LI-7500A relative to the LI-7500RS and were associated with a recent rainfall event. A large discrepancy in  $\overline{\rho_v'^2}$  among the three IRGAs occurred an hour after light rain on DOY 211, which suggests that thick water droplets may have been still evaporating from the mirror surface. Antecedent conditions were dry and with the cessation of precipitation, a sudden increase in mean wind speed  
425 from under  $3$  to  $5 \text{ m s}^{-1}$  and a wind shift from east to south enabled sensible heat advection as clouds began to dissipate. Although air humidity decreased by the end of the half-hour for all IRGAs, the magnitude measured by the LI-7500 was much smaller at the start of the averaging period than at the end, in contrast to observations by the LI-7500A and LI-7500RS. Further, we observed that the LI-7500A air humidity began decreasing within the first 15 minutes, suddenly

430 increased by approximately  $5 \text{ g m}^{-3}$ , and then began a rapid decrease. This pattern is different from what was observed by the LI-7500RS, which initially increased and then quickly decreased at an earlier time than for the LI-7500A (not shown).

A similar event occurred on DOY 196. However, for the half-hour of interest, a relatively small difference in  $\overline{\rho'_v{}^2}$  of the LI-7500 and LI-7500A resulted in a larger flux difference, in which a large, 435 likely overestimated flux was measured by the LI-7500. Interestingly, 20 Hz fluctuations for all systems were dampened during roughly the first half of this averaging period, showing signs of low frequency atmospheric motion. Once turbulence became more typical of a well-mixed boundary layer, the amplitude of  $\rho'_v$  then grew with a larger variance noted in the LI-7500A and LI-7500 compared to the LI-7500RS. This behavior is exactly what was observed on DOY 211 440 during its relevant averaging period.

#### 4.2 Water vapor flux errors

In the context of ET measurement, total daily magnitude is of prime importance for practical applications. Therefore, flux errors during the daytime, roughly between 09:00 and 17:00 LST, contribute to the vast majority of ET variation. The similarity between the LI-7500A and LI- 445 7500RS fluxes is reflected by the lack of scatter in covariance data. As expected, errors were larger during advective periods than for other times, but overall correlation between  $\overline{\rho'_v{}^2}$  and  $\lambda E$  errors was weak. Highly advective conditions have been associated with large interinstrument variability (Alfieri et al., 2011).

Uncorrected fluxes were assessed to assure that the data processing steps did not appreciably affect 450 our findings. Post-processing of turbulent fluxes could increment fluxes while causing greater error

(Irmak et al., 2014). The magnitudes of  $a$ ,  $d$ , and  $rmsd$  were slightly smaller for all comparisons, and  $b$  and  $r^2$  were nearly identical, indicating that the corrections contributed little to measurement uncertainty. For instance, the  $rmsd$  decreased by 6.8% and 7.3% for daytime fluxes against the LI-7500 and LI-7500A, respectively. Among the corrections, sensor separation and frequency response were of most interest for the LI-7500RS and LI-7500A pair since they are newer optical  
455 analyzers. These findings may be why among the three generations of IRGAs, the LI-7500RS consistently had a larger spectral correction factor by approximately 2 to 4%, but again, this served to only slightly decrease flux error. Its midday mean value of 1.11, though slightly larger than for the LI-7500 and LI7500A, was still less than reported in a feedlot for an LI-7500 and CSAT-3 EC  
460 system (Prajapati and Santos, 2017). This suggests that high frequency attenuation was relatively minor when turbulent intensity was large, and any missing flux was more attributable to low frequency. While the LI-7500 high frequency energy compared more favorably to the LI-7500A than the LI-7500RS, a large departure from the LI-7500A and LI-7500RS pattern was clearly observed at low frequencies (Fig. 6).

465 It has previously been shown that turbulent flux error partitions primarily into random error, with daytime systematic error only as large as 0.018 mm (30 min<sup>-1</sup>) (Alfieri et al., 2011). In contrast, Sect. 3.3 demonstrated that the magnitudes of systematic error were generally large in response to daytime energy balance residuals. The different findings are based on different assumptions of what is true latent heat. In the prior study, the mean of multiple EC measurements was considered  
470 the true flux, and the systematic error was the variance of residuals between predicted and true flux. Following that approach, daytime error was comparable and ranged from 0.014 (LI-7500RS) to 0.024 (LI-7500) mm (30 min<sup>-1</sup>). Also, the prior study was conducted during the period of rapid

LAI increase of a cotton crop, while the present study was performed during both the period of rapid LAI increase and crop maturation.

## 475 **5. Conclusion**

The guidelines written by Fratini et al. (2014) can be used to avoid water vapor concentration errors. Even in the event that absorptances are not output via datalogger code, and detection of contamination in real time is not done, the water vapor density errors will not adversely affect accuracy of eddy covariance on a growing season timescale. The averaged water vapor density  
480 from LI-7500RS was drifted in an opposite direction of both LI-7500A and LI-7500 analyzers' drifts. For the latent heat flux, larger fluxes were found from the older LI-7500 system evidenced not only from low frequency energy components but also from high frequency components under unstable conditions. Our study suggests that the LI-7500 outperformed newer LI7500A and 7500RS sensors in terms of accumulated ET comparison with lysimeter observations.

485 Differences in the response from the same model sensor measuring presumably the same air parcel were identified. In this study, the growth and maturation of the corn crop drove a change in turbulent flux partitioning. Increases in interinstrument variation for both water vapor variance and flux were observed when conditions were advective during the period of peak canopy development. Following precipitation, while performance characteristics were consistent in well-  
490 mixed turbulent air, larger interinstrument variation was observed under light winds that could cause variation in effects on the IRGA. Adjusting measured fluxes by the systematic error, which tended to be larger at one EC tower compared to the other, brought the water vapor fluxes into strong agreement.

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## Figures and Tables Captions ( 8 Figs and 2 Tables)

660

**Table 1.** Performance characteristics of LI-7500A and LI-7500 with reference to the LI-7500RS for water vapor variance  $\overline{\rho_v'^2}$ . These include regression offset value (*a*), regression slope (*b*), coefficient of determination ( $r^2$ ), mean absolute bias (*d*), and comparability (*rmsd*).

665

**Table 2.** Performance characteristics of LI-7500A and LI-7500 with reference to the LI-7500RS for corrected latent heat fluxes ( $\lambda E$ ). These include regression offset value (*a*), regression slope (*b*), coefficient of determination ( $r^2$ ), mean absolute bias (*d*), and comparability (*rmsd*).

670

**Figure 1.** Screening effects on the data acquisition ratio (AR) as a function of (a) diel cycle and (b) day of year. Precip + RH + Flux shows AR after all filtering has been completed, RH + Flux indicates AR after RH threshold and steady-state turbulence tests, and Flux denotes AR after only turbulent tests.

675

**Figure 2.** Absolute humidity  $\rho_v$  (top) magnitude and (bottom) difference  $\Delta\rho_v$  between paired IRGA and HMP instruments (HMP155-N is paired with the LI-7500RS and LI-7500A; HMP155-S is paired with the LI-7500) during the first and last three days of the study. Shaded areas indicate daytime.

**Figure 3.** Evolution of absolute humidity bias over nine 10-day periods, shown as half-hour bias  $\Delta\rho_v$  (points), 1- (thin solid lines) and 10-day (dotted lines) moving averages. Half-hours with observed rainfall are indicated with vertical lines.

680

**Figure 4.** Intercomparison of absolute humidity  $\rho_v$  means and standard deviations for (a, b) the LI-7500 and LI-7500RS and (c, d) the LI-7500A and LI-7500RS.

**Figure 5.** Binned spectra of absolute humidity on DOY 191 are shown for 45 half-hour observations from (a) LI-7500RS, (b) LI-7500A, and (c) LI-7500 as a function of normalized frequency. A close-up comparison of the performance of the three gas analyzers is illustrated in (d) for three half-hours.

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**Figure 6.** Ensemble median daytime (a, c, and e) cospectra and corresponding (b, d, and f) ogives under unstable, neutral, and stable conditions. For cospectra, the area between dotted lines shows the interquartile range.

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**Figure 7.** Daily ET determined with (a) LI-7500RS (red), (b) LI-7500A (blue), and (c) LI-7500 (cyan). The daily lysimeter ET is displayed by open diamond markers. Accumulated lysimeter ET is shown with solid diamonds and accumulated eddy covariance ET measurements with solid lines.

**Figure 8.** Daytime (9 AM–7 PM LST) ET fluxes for EC systems with an (a) LI-7500RS, (b) LI-7500A, and (c) LI-7500 and the accompanying systematic errors (d–f) and random errors (g–i). Mean values are displayed as larger points.

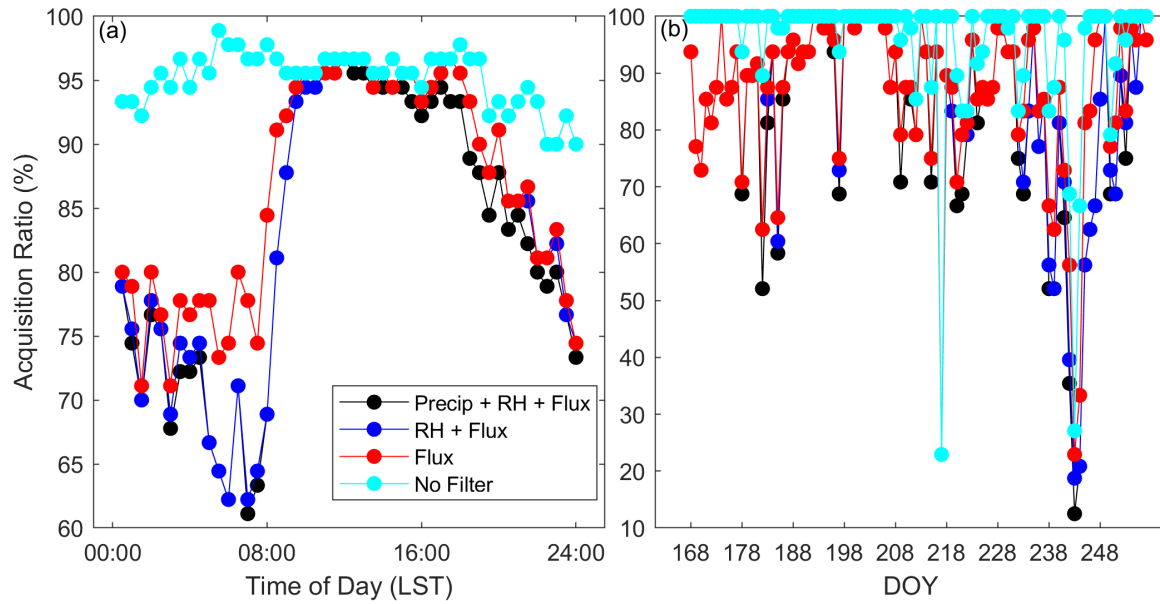
695 **Table 1.** Performance characteristics of LI-7500A and LI-7500 with reference to the LI-7500RS for water vapor variance  $\overline{\rho'_v{}^2}$ . These include regression offset value (*a*), regression slope (*b*), coefficient of determination ( $r^2$ ), mean absolute bias (*d*), and comparability (*rmsd*).

	$\overline{\rho'_v{}^2}$	<i>a</i> (g <sup>2</sup> m <sup>-6</sup> )	<i>b</i> (-)	$r^2$	<i>d</i> (g <sup>2</sup> m <sup>-6</sup> )	<i>rmsd</i> (g <sup>2</sup> m <sup>-6</sup> )
<b>75</b>	All	0.04	1.17	0.42	0.09	0.88
	Daytime	0.06	1.08	0.49	0.10	0.75
	Advective	0.22	1.02	0.57	0.24	1.33
<b>75A</b>	All	0.02	1.07	0.56	0.04	0.60
	Daytime	0.02	1.03	0.79	0.03	0.36
	Advective	0.08	1.02	0.83	0.09	0.63

700 **Table 2.** Performance characteristics of LI-7500A and LI-7500 with reference to the LI-7500RS for corrected latent heat fluxes ( $\lambda E$ ). These include regression offset value ( $a$ ), regression slope ( $b$ ), coefficient of determination ( $r^2$ ), mean absolute bias ( $d$ ), and comparability ( $rmsd$ ).

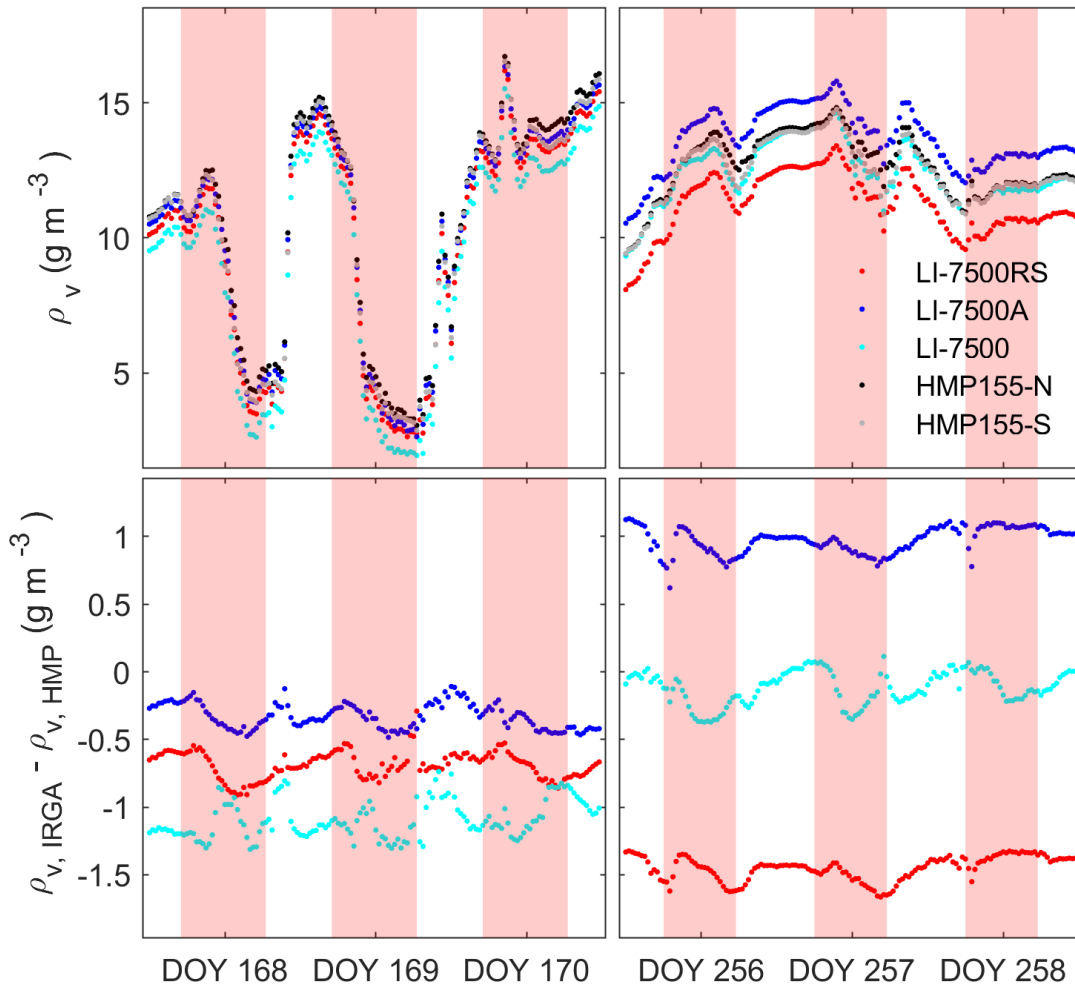
$\lambda E$		$a$ ( $W\ m^{-2}$ )	$b$ (-)	$r^2$	$d$ ( $W\ m^{-2}$ )	$rmsd$ ( $W\ m^{-2}$ )
<b>75</b>	All	6.20	1.12	0.96	27.13	54.31
	Daytime	23.91	1.08	0.92	49.42	73.66
	Advective	47.07	1.05	0.87	69.80	97.94
<b>75A</b>	All	-1.48	1.00	0.99	-0.87	16.69
	Daytime	2.34	0.99	0.99	0.34	14.53
	Advective	2.04	1.00	0.98	-0.10	21.67

705



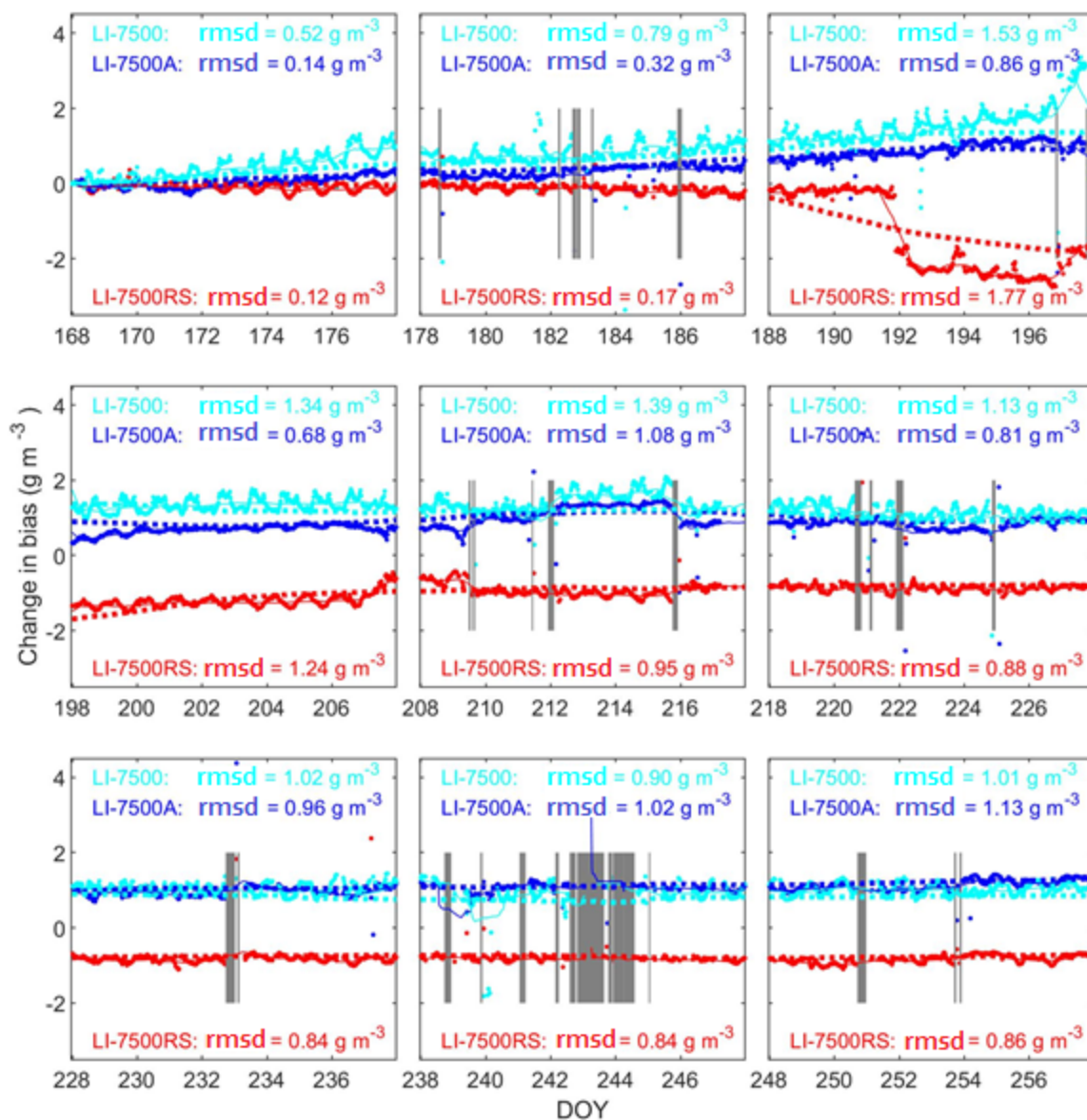
**Figure 1.** Screening effects on the data acquisition ratio (AR) as a function of (a) diel cycle and (b) day of year. Precip + RH + Flux shows AR after all filtering has been completed, RH + Flux indicates AR after RH threshold and steady-state turbulence tests, and Flux denotes AR after only turbulent tests.

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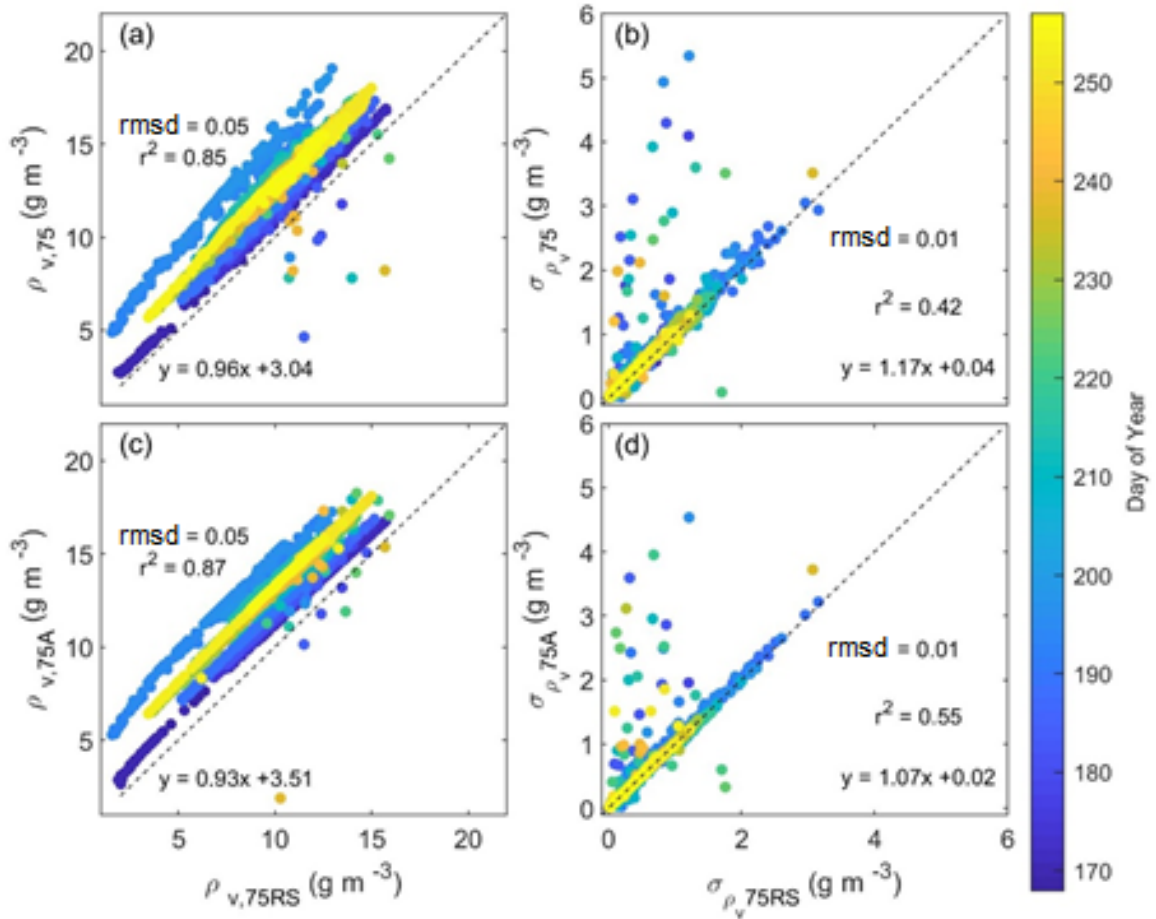


715 **Figure 2.** Absolute humidity  $\rho_v$  (top) magnitude and (bottom) difference  $\Delta\rho_v$  between paired IRGA and HMP instruments (HMP155-N is paired with the LI-7500RS and LI-7500A; HMP155-S is paired with the LI-7500) during the first and last three days of the study. Shaded areas indicate daytime.

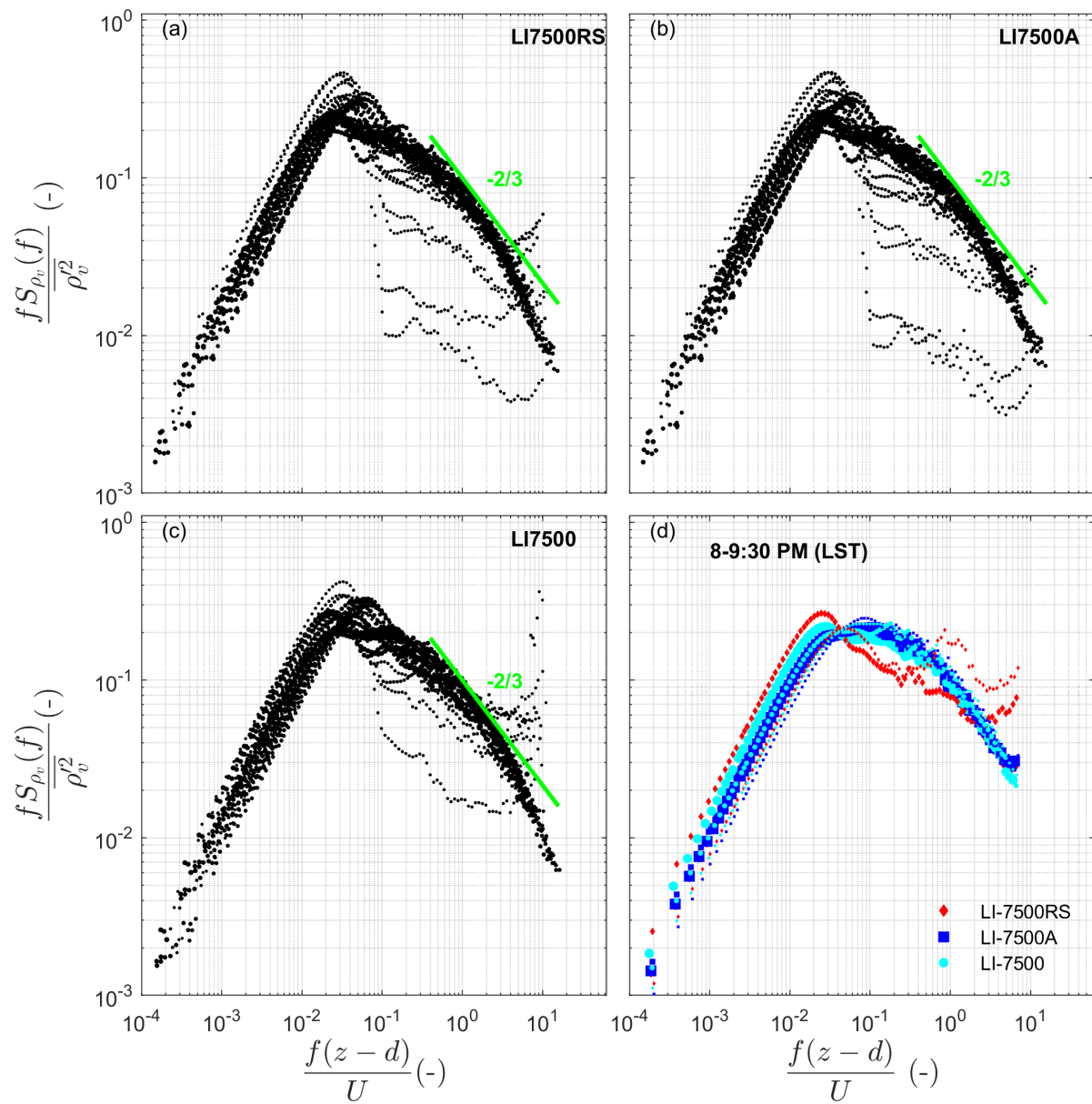




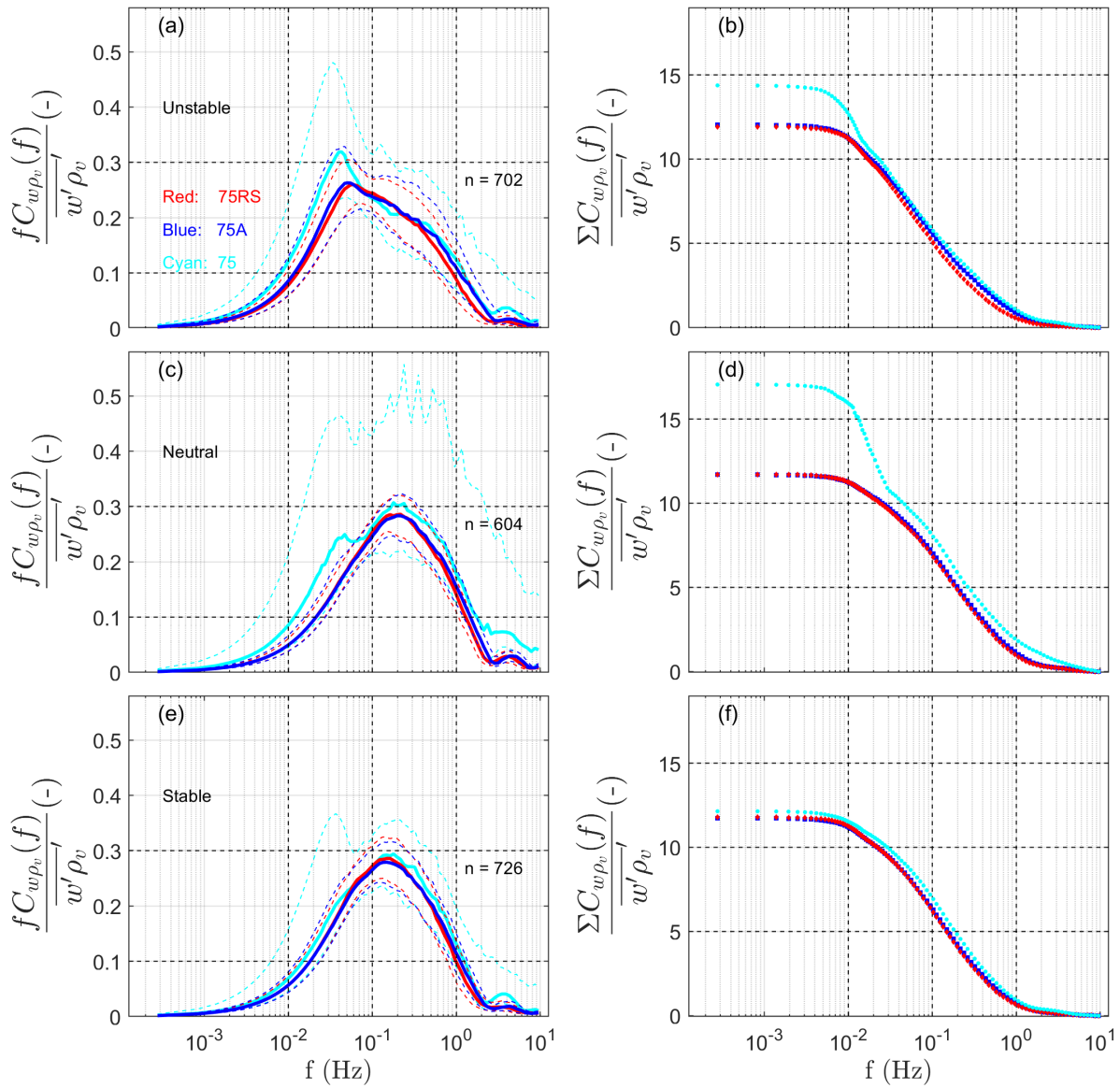
720 **Figure 3.** Evolution of absolute humidity bias over nine 10-day periods, shown as half-hour bias  $\Delta\rho_v$  (points), 1- (thin solid lines) and 10-day (dotted lines) moving averages. Half-hours with observed rainfall are indicated with vertical lines.



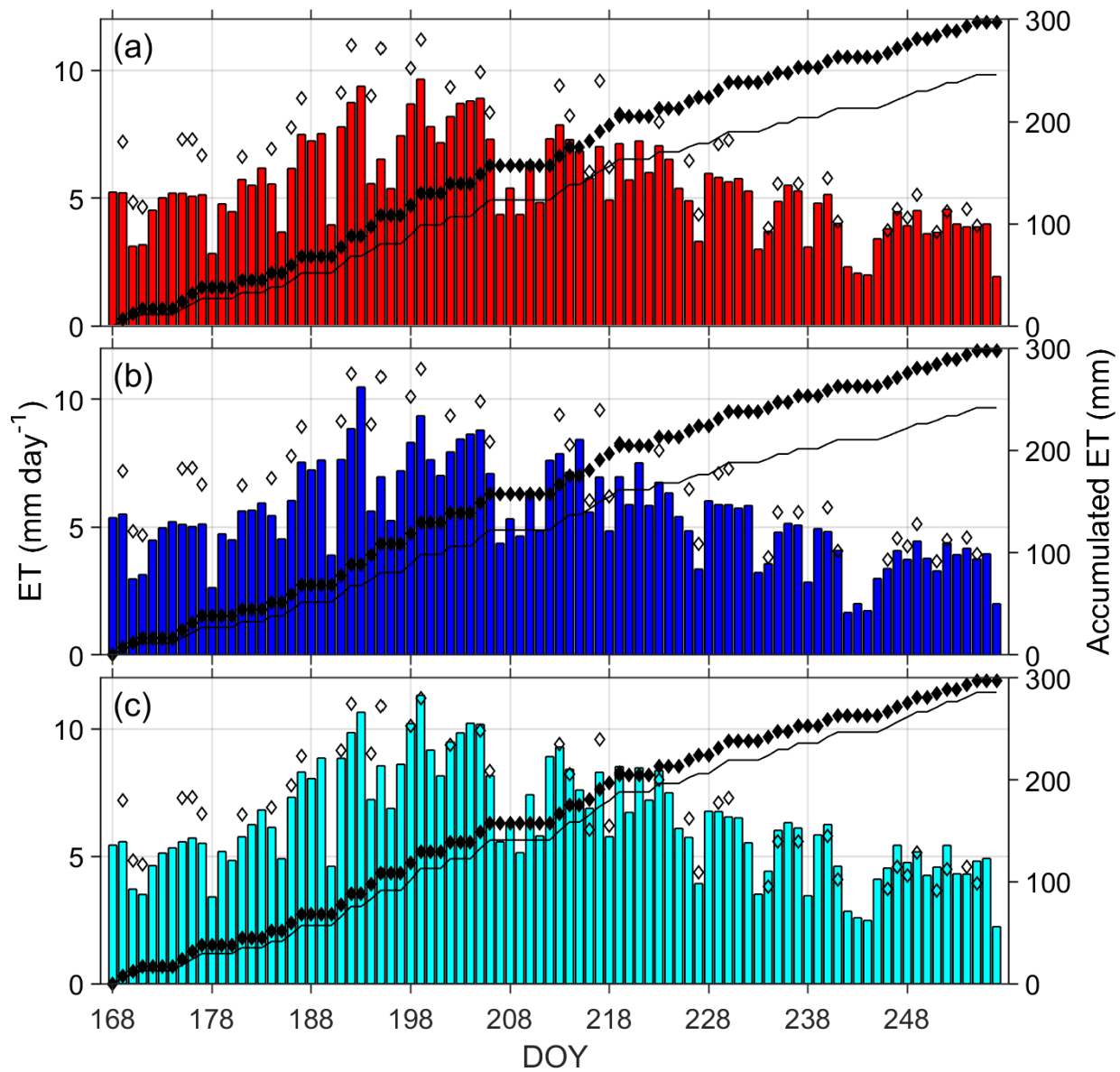
725 **Figure 4.** Intercomparison of absolute humidity  $\rho_v$  means and standard deviations for (a, b) the LI-7500 and LI-7500RS and (c, d) the LI-7500A and LI-7500RS.



730 **Figure 5.** Binned spectra of absolute humidity on DOY 191 are shown for 45 half-hour observations from (a) LI-7500RS, (b) LI-7500A, and (c) LI-7500 as a function of normalized frequency. A close-up comparison of the performance of the three gas analyzers is illustrated in (d) for three half-hours.

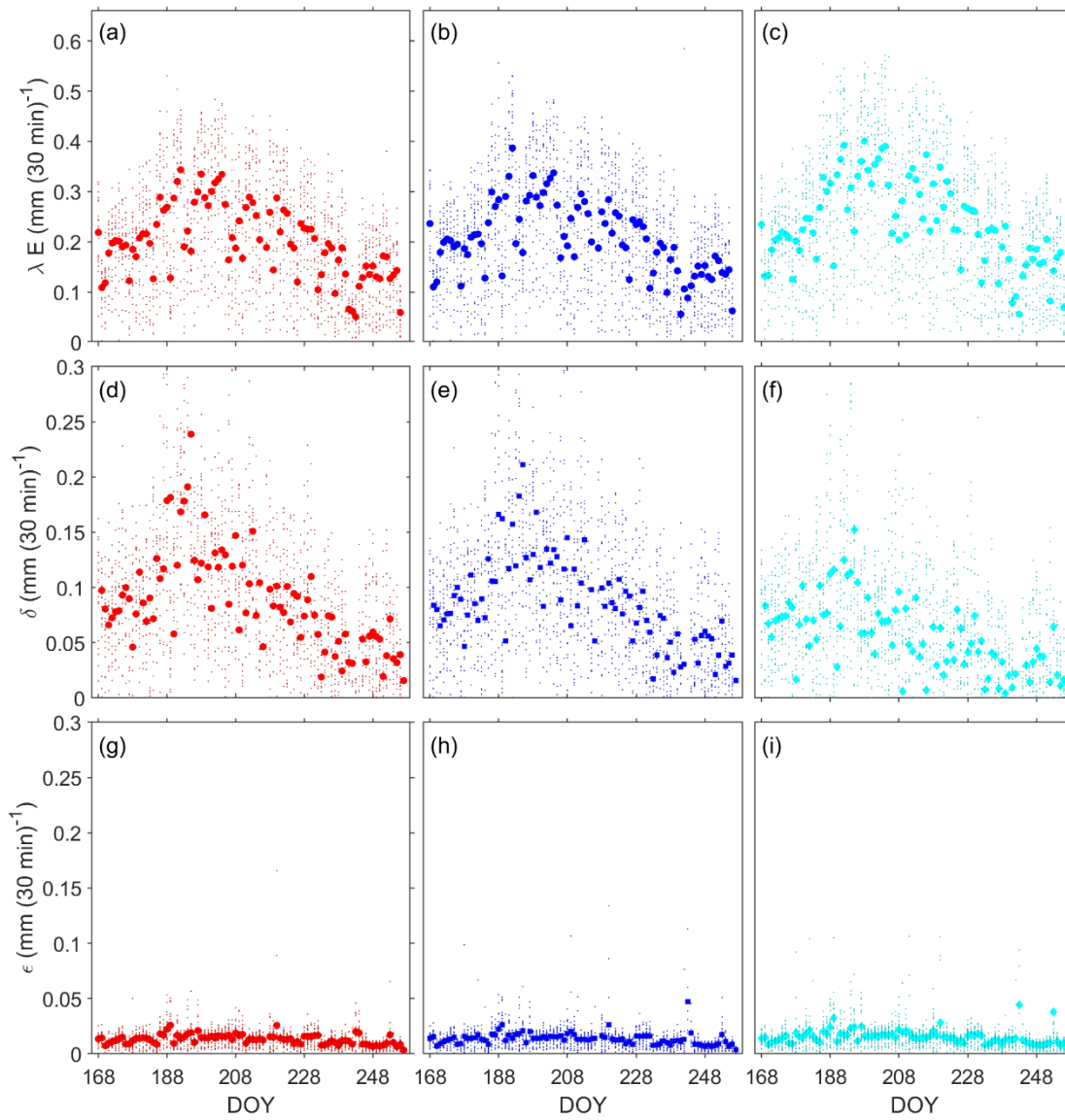


735 **Figure 6.** Ensemble median daytime (a, c, and e) cospectra and corresponding (b, d, and f) ogives under unstable, neutral, and stable conditions. For cospectra, the area between dotted lines shows the interquartile range.



740

**Figure 7.** Daily ET determined with (a) LI-7500RS (red), (b) LI-7500A (blue), and (c) LI-7500 (cyan). The daily lysimeter ET is displayed by open diamond markers. Accumulated lysimeter ET is shown with solid diamonds and accumulated eddy covariance ET measurements with solid lines.



**Figure 8.** Daytime (9 AM–7 PM LST) ET fluxes for EC systems with an (a) LI-7500RS, (b) LI-7500A, and (c) LI-7500 and the accompanying systematic errors (d–f) and random errors (g–i). Mean values are displayed as larger points.