

# Top of the Atmosphere Reflected Shortwave Radiative Fluxes from GOES-R

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**Abstract.** Under the GOES-R activity, new algorithms are being developed at the National Oceanic and Atmospheric Administration (NOAA)/Center for Satellite Applications and Research (STAR) to derive surface and Top of the Atmosphere (TOA) shortwave (SW) radiative fluxes from the Advanced Baseline Imager (ABI), the primary instrument on GOES-R. This paper describes a support effort in the development and evaluation of the ABI instrument capabilities to derive such fluxes. Specifically, scene dependent narrow-to-broadband (NTB) transformations are developed to facilitate the use of observations from ABI at the TOA. Simulations of NTB transformations have been performed with MODTRAN4.3 using an updated selection of atmospheric profiles and implemented with the final ABI specifications. These are combined with Angular Distribution Models (ADMs), which are a synergy of ADMs from the Clouds and the Earth's Radiant Energy System (CERES) and from simulations. Surface condition at the scale of the ABI products as needed to compute the TOA radiative fluxes come from the International Geosphere-Biosphere Programme (IGBP). Land classification at 1/6 ° resolution for 18 surface types are converted to the ABI 2-km grid over the (CONTiguous States of the United States) (CONUS) and subsequently re-grouped to 12 IGBP types to match the classification of the CERES ADMs. In the simulations, default information on aerosols and clouds is based on the ones used in MODTRAN.

27 Comparison of derived fluxes at the TOA is made with those from CERES. A satisfactory agreement  
28 between the fluxes was observed for both clear and cloudy conditions and possible reasons for differences  
29 have been identified.

30

## 31 **1. Introduction**

32

33 One of the objectives at NOAA/STAR in respect to the utilization of observations from the Advanced  
34 Baseline Imager (ABI) is to be able to derive shortwave ( $SW\downarrow$ ) radiative fluxes at the surface. To get to  
35 the surface  $SW\downarrow$  from TOA satellite observations, there are two generic approaches: 1) the direct approach  
36 and 2) the indirect approach. In the direct approach one uses all the necessary information needed for  
37 deriving the surface fluxes (some of which can be derived from satellites). Implementation of such an  
38 approach is feasible, for instance, with observations from MODIS which has a long history of product  
39 availability and evaluation. Examples are illustrated in Wang and Pinker (2009), Niu and Pinker, (2015),  
40 Ma et al. (2016), Pinker et al. (2018), Pinker et al., (2017a), Pinker et al. (2017b). GOES-R is a new  
41 instrument and as yet, similar information to the one from MODIS is not yet available. Therefore, the  
42 indirect approach is used where one starts from satellite observations at the TOA and models the  
43 atmosphere and surface with best available information (which does not have to be based on ABI).  
44 Examples of such an approach are discussed in Pinker, Zhang and Dutton (2005), Ma and Pinker (2012)  
45 and Zhang et al. (2019). The “indirect path method” is used at the Center for Satellite Applications and  
46 Research (STAR) (Laszlo et al., 2020) for deriving  $SW\downarrow$  radiative fluxes from satellite observations; it  
47 requires knowledge of the SW broadband (0.2 – 4.0  $\mu\text{m}$ ) top of the atmosphere (TOA) albedo. The  
48 Advanced Baseline Imager (ABI) observations onboard of the NOAA GOES-R series of satellites provide  
49 reflectance in six narrow bands in the shortwave spectrum (**Table 1**); these must be first transformed into  
50 broadband reflectance (the NTB conversion), and the broadband reflectance must be transformed into a  
51 broadband albedo (the ADM conversion). During the pre-launch activity NTB transformations were  
52 developed based on theoretical radiative transfer simulations with MODTRAN-3.7 and 14 land use

53 classifications from the International Geosphere-Biosphere Programme (*IGBP*) (Hansen et al., 2010).  
54 They were augmented with ADMs from (CERES) observed ADMs (Loeb et al., 2003) and theoretical  
55 simulations (Niu and Pinker, 2011) to compute TOA fluxes. The resulting NTB transformations and  
56 ADMs have been tested using proxy data and simulated ABI data. The proxy instruments used in these  
57 early simulations include the GOES-8 satellite, the Advanced Very-High Resolution Radiometer  
58 (AVHRR) sensor on the Polar Orbiting satellites, the Spinning Enhanced Visible Infra-Red Imager  
59 (SEVIRI) sensor on the European METEOSAT Second Generation (MSG) satellites, and the Moderate  
60 Resolution Imaging Spectroradiometer (MODIS) instrument on the NASA Terra and Aqua Polar Orbiting  
61 satellites (Pinker et al., 2021, unpublished). For each of these satellites, the evaluation of the  
62 methodologies was done differently; some results were evaluated against ground observations while  
63 others, against TOA information from CERES as well as from the (ESA) Geostationary Earth Radiation  
64 Budget (GERB) satellite (Harries et al., 2005). The results obtained provided an insight on the expected  
65 performance of the new ABI sensor. Those procedures have been subsequently updated and applied to  
66 the new ABI instrument once it was built and fully characterized.

67 In this paper we describe activity in support of the effort to derive surface shortwave ( $SW\downarrow$ ) radiative  
68 fluxes from the operational Advanced Baseline Imager (ABI) instrument on the GOES-R series of the  
69 NOAA geostationary meteorological satellites using the latest version of the ABI data. We describe the  
70 physical basis and the development of the (NTB) transformations of satellite observed radiances and the  
71 bi-directional corrections to be applied to the broadband reflectance to obtain broadband TOA albedo.  
72 The methodology will be presented in section 2, data used are described in section 3, results in section 4  
73 and a summary and discussion in section 5.

74

## 75 **2. Methodology**

76

77 The following two flowcharts (**Figs. 1 and 2**) describe the necessary steps to derive the NTB  
78 transformations and the ADMs. Details on these two steps will follow.

79 The TOA narrowband and broadband reflectance can be calculated from the spectral radiances  
 80 simulated from MODTRAN 4.3 and the response functions of the satellite sensor as shown in equations  
 81 (1) and (2):

$$82 \quad \rho_{nb}(\theta_0, \theta, \phi) = \frac{\pi \int_{\lambda_1}^{\lambda_2} I(\lambda, \theta_0, \theta, \phi) G(\lambda) d\lambda}{\int_{\lambda_1}^{\lambda_2} \cos(\theta_0) S_0(\lambda) G(\lambda) d\lambda} \quad (1)$$

$$83 \quad \rho_{bb}(\theta_0, \theta, \phi) = \frac{\pi \int_{0.2 \mu m}^{4 \mu m} I(\lambda, \theta_0, \theta, \phi) d\lambda}{\int_{0.2 \mu m}^{4 \mu m} \cos(\theta_0) S_0(\lambda) d\lambda} \quad (2)$$

84

85 where  $\rho_{nb}$  is narrowband reflectance;  $\rho_{bb}$  is broadband reflectance;  $\theta_0$ : solar zenith angle;  $\theta$ : view  
 86 (satellite) zenith angle;  $\phi$ : relative azimuth angle;

87  $I_\lambda$ : reflected spectral radiance;  $S_0(\lambda)$ : solar spectral irradiance;

88  $G_\lambda$ : spectral response functions of satellite sensors;  $\lambda_1$  and  $\lambda_2$  are the spectral limits of the sensor spectral  
 89 band. This approach is widely used in the scientific community as also implemented in the work of Loeb  
 90 et al (2005), Wielicki et al. (2008), Su et al. (2015) and Akkermans et al. (2020).

91 As stated previously, the ADMs from CERES-based observations (Loeb et al., 2005; Kato et al. 2015)  
 92 were augmented with theoretical simulations (Niu and Pinker, 2011) to compute TOA fluxes. This was  
 93 done since CERES observations at that time were under-sampled. at higher latitudes.

94 The combined ADMs are developed for each angular bin by weighting the modeled and CERES ADMs  
 95 based on the number of samples used to derive the ADMs of each type (Niu et al., 2011). Specifically:

$$\bar{R}(\theta_0, \theta, \phi) = \frac{1}{m+n} (m \times R_{CERES}(\theta_0, \theta, \phi) + n \times R_S(\theta_0, \theta, \phi)) \quad (3)$$

97  $\bar{R}(\theta_0, \theta, \phi)$ : averaged ADMs at each angular bin;

98  $R_{CERES}$ : anisotropic factor from CERES ADMs;

99  $R_S$ : anisotropic factor from simulated ADMs;

100  $m$  and  $n$ : observation numbers at angular bins for CERES and simulated ADMs.

101

## 102 **2.1 Selection of Atmospheric profiles for simulations**

103

104 We have selected 100 atmospheric profiles covering the globe and the seasons as input for simulations  
 105 with MODTRAN4.3. The atmospheric profiles at each pressure level include temperature, water vapor  
 106 and ozone. Each season includes 25 profiles. A tool was developed to select profiles from a Training Data  
 107 set known as SeeBor Version 5.0 ([https://cimss.ssec.wisc.edu/training\\_data/](https://cimss.ssec.wisc.edu/training_data/)) (Borbas et.al. 2005).  
 108 Originally it consisted of 15704 global profiles of temperature, moisture, and ozone at 101 pressure levels  
 109 for clear sky conditions. The profiles are taken from NOAA-88, and the European Centre for Medium-  
 110 Range Weather Forecasts (ECMWF) 60L training set, TIGR-3, ozone-sondes from 8 NOAA Climate  
 111 Monitoring and Diagnostics Laboratory (CMDL) sites, and radiosondes from the Sahara Desert during  
 112 2004. A technique to extend the temperature, moisture, and ozone profiles above the level of existing data  
 113 was also implemented by the providers (University of Wisconsin-Madison, Space Science and  
 114 Engineering Center, Cooperative Institute for Meteorological Satellite Studies (CIMSS)). **Fig. 3** shows the  
 115 location of the selected profiles.

116 The SeeBor profiles are clear sky profiles. The top of the profiles is at 0.005 mb which is about 82.6 km.  
 117 We did an experiment to check the impact of reducing the number of levels for a profile (initially, we  
 118 have used only 40 levels). In the experiment computed were radiances from profiles with 50 levels as

119 well as radiances from profiles with 98 Levels. The difference between the two radiances (50 lev-98 lev)  
120 were below 5 % reaching 15 % around 2.5  $\mu\text{m}$ . In the experiment we used the odd number levels starting  
121 from surface (plus the highest level) to reduce the number of profile levels. Based on these experiments  
122 we have opted to keep all 98 profile levels.

123 The surface variables we have used are from MODIS and include surface skin temperature, 2 m  
124 temperature, land/sea mask, and albedo. We have conducted a thorough investigation how the selected  
125 profiles represent the entire sample of 15704 profiles. An example showing the comparison of  
126 temperature, humidity and ozone profiles is shown in **Fig. 4**. As seen, there is a positive bias in the selected  
127 profile of temperature due to their higher concentration at the lower latitudes. A positive bias can be found  
128 at the lower levels while a negative bias is seen above 1 mb. Since our domain of study is in such latitudes  
129 this selection should not have adverse effects on the simulations performed.

130

## 131 **2.2 Surface conditions**

132

133 Surface condition is one of the primary inputs into the MODTRAN simulations. The International  
134 Geosphere-Biosphere Programme (IGBP) land classification is used as a source (Hansen et al., 2010;  
135 Loveland et al., 2010). The dataset is at 1/6-degree resolution and includes 18 surface types. We have  
136 converted the 1/6 $^\circ$  (~18.5 km) resolution to the ABI 2-km grid using the nearest grid method (**Fig. 5**). The  
137 surface type is fixed in time. The method for cloudy sky uses 4 surface types; these are also derived from  
138 12 IGBP types (**Table 2**).

139

## 140 **2.3 Clear and cloudy sky simulations**

141

142 Under clear sky, scattering from aerosols is important. We have included 6 aerosol types (**Table 3**) to  
143 cover a range of possible conditions under clear sky. Aerosol models are selected based on the type of  
144 extinction and a default meteorological range for the boundary-layer aerosol models as listed below:

145 Aerosol Type 1: Rural extinction, visibility = 23 km

146 Aerosol Type 4: Maritime extinction, visibility = 23 km

147 Aerosol Type 5: Urban extinction, visibility = 5 km

148 Aerosol Type 6: Tropospheric extinction, visibility = 50 km

149 Aerosol Type 8: Advective Fog extinction, visibility = 0.2 km

150 Aerosol Type 10: Desert extinction for default wind conditions

151 For the 6 aerosol types, the total number of MODTRAN simulations for each surface type is 462,000. It  
152 is obtained as follows: 6 aerosol types x 100 profiles x 770 angles.

153 When performing NTB simulations, we use all 6 types of aerosols. The Rural, Ocean, Urban and Fog  
154 aerosols are distributed in the lower 0-2 km region. Tropospheric aerosol is distributed from 0 to 10 km  
155 tropopause. The Rural, Ocean, Urban and Tropospheric aerosol optical properties have Relative Humidity  
156 (RH) dependency. The Single Scattering Albedo (SSA) is given on 4 RH grids (0, 70, 80, 99) on a spectral  
157 grid of 788 points ranging from 0.2 to 300 microns.

158 Simulations were performed for ABI for all the cloud cases described in **Table 3**. To merge cloud layers  
159 with atmospheric profiles we have followed the procedure as described in *Berk et al.* (1985, 1998),  
160 namely: “Cloud profiles are merged with the other atmospheric profiles (pressure, temperature, molecular  
161 constituent, and aerosol) by combining and/or adding new layer boundaries. Any cloud layer boundary  
162 within half a meter of an atmospheric boundary layer is translated to make the layer altitudes coincide;  
163 new atmospheric layer boundaries are defined to accommodate the additional cloud layer boundaries.”  
164 100% relative humidity is assumed within the cloud layers (default).

165

## 166 **2.4 Selection of angles**

167

168 The total number of angles used in the simulations is given in **Table 4**. The selected spectral grids for  
169 solar zenith angles, satellite view angles and relative azimuth angles are at Gaussian quadrature points,  
170 plus 0° to solar zenith angles (sza) and satellite viewing angles (vza) and 0° and 180° (forward and  
171 backward view) to the satellite relative azimuth angles. Solar angle and satellite view angle are referenced

172 to target or surface for satellite simulation with  $0^\circ$  meaning looking up (zenith). Relative azimuth angle is  
173 defined as when the relative azimuth angle equals  $180^\circ$ , the sun is in front of observer.  
174 The definitions of solar zenith angle and azimuth angle in this table corresponds to the definitions of  
175 MODTRAN but that is not the case for the satellite zenith angle. MODTRAN uses nadir angle as  $180^\circ$ -  
176 satellite zenith angle, ignoring spherical geometry.

177

## 178 **2.5 Selection of optimal computational scheme**

179

180 MODTRAN4.3 provides three multiple scattering models (Isaacs, DISORT, and Scaled Isaacs) and three  
181 band models at resolutions ( $1 \text{ cm}^{-1}$ ,  $5 \text{ cm}^{-1}$ , and  $15 \text{ cm}^{-1}$ ). The DISORT model (Stamnes et al., 1988)  
182 provides the most accurate radiance simulations but the runs are very time consuming. The Isaacs (Isaacs  
183 et al. 1987) 2-stream algorithm is fast but oversimplified. The Scaled Isaacs method performs radiance  
184 calculations using Isaacs 2-stream model over full spectral range and using DISORT model at a small  
185 number of atmospheric window wavelengths. The multiple scattering contributions for each method are  
186 identified and ratios of the DISORT and Isaacs methods are computed. This ratio is interpolated over the  
187 full wavelength range, and finally, applied as a multiple scattering scale factor in a spectral radiance  
188 calculation performed with the Isaacs method.

189 To optimize simulation speed and accuracy, we performed various sensitivity tests, including  
190 combinations of multiple scattering models, band resolution, and number of streams. **Table 5** lists  
191 simulation options and their corresponding calculation speed.

192 Based on results presented in **Table 5**, the efficient options ( $< 40$  seconds) are Isaacs, DISORT 2-stream  
193 with  $15 \text{ cm}^{-1}$ , DISORT 4-stream  $15 \text{ cm}^{-1}$ , and Scaled Isaacs all streams at all resolutions. Although the  
194 ideal option is DISORT 8-stream with  $1 \text{ cm}^{-1}$  resolution, there is a trade-off between speed and accuracy.

195 **Fig. 6** compares DISORT simulated radiances at three band resolutions. We use two spectral ranges of  
196  $0.4 - 0.5 \text{ }\mu\text{m}$  and  $1.5 - 2.0 \text{ }\mu\text{m}$  to illustrate differences. **Fig. 6** shows that the coarser band resolution has  
197 smoothed out the radiance variations. The  $15 \text{ cm}^{-1}$  has the smoothest curve among the three, and  $1 \text{ cm}^{-1}$   
198 shows more variations than the other two. Another (scientific) criteria for selecting the spectral resolution



199 is the ability to resolve/match the relative spectral response function (SRF) of a sensor. For example, the  
200 SRFs of channels 1-6 of ABI are given at every  $1 \text{ cm}^{-1}$ .  
201 Accordingly, we have chosen the  $1 \text{ cm}^{-1}$  band model for the MODTRAN radiance simulations. Performed  
202 were also radiance simulations from different multiple scattering models at  $1 \text{ cm}^{-1}$  resolution. The whole  
203 spectrum of  $0.2 - 4 \text{ }\mu\text{m}$  was separated to 14 sections so that the differences can be assessed clearly. For  
204 wavelength below  $0.3 \text{ }\mu\text{m}$  and beyond  $2.5$  no discernible differences were found among Isaacs, DISORT  
205 2-, 4-, and 8-stream, and Scaled Isaac. The largest differences occurred in the spectral range of  $0.4 - 1.0$   
206  $\mu\text{m}$ . Scaled Isaac 8-stream follows DISORT 8-stream closely across the whole spectral range; the Scaled  
207 Isaac method provided near-DISORT accuracy with the speed of Isaacs. Thus, the MODTRAN4.3  
208 simulations for GOES-R ABI were set-up with Scaled Isaac 8-stream with  $1 \text{ cm}^{-1}$  band resolution.  
209 For illustration, in **Fig. 7** compared are radiances simulated by Isaac 2 stream, Scaled Isaac, and DISORT-  
210 4 stream for the case of Relative Azimuthal Angle= $1.9^\circ$ , View Angle= $76.3^\circ$ , Solar Zenith Angle= $87.2^\circ$ .  
211 The lines are differences between various settings and DISORT-8 stream (e.g. Isaacs minus DISORT-8).  
212 Isaac has the least accuracy since it is oversimplified, 4-stream showed some improvements when  
213 compared with Isaac while still has large differences for  $0.4 \text{ }\mu\text{m}$  and is still computationally demanding.  
214 Scaled Isaac provides the smallest differences between DISORT-8. **Fig. 7** (lower) zoomed in to the large  
215 difference area of  $0.3-0.35 \text{ }\mu\text{m}$  which indicates that Scaled Isaacs still provides satisfactory results.

216

## 217 **2.6 Regression methodologies**

218

219 We have derived coefficients of regression using a constrained least-square curve fitting methods of  
220 Matlab, “lsqnonneg”, which can solve a linear or nonlinear least-squares (data-fitting) problem and  
221 produce non-negative coefficients. Non-negative coefficients avoid generating negative TOA flux, which  
222 is not a physically valid.

223 To ensure that information from all channels is used and avoid the complex cross-correlation problem, it  
224 was opted to generate Narrow to Broad (NTB) coefficients for each ABI channel separately. These  
225 channel specific NTB coefficients are applied to each channel to convert ABI narrow-band reflectance to

226 extended band. The final broad-band TOA reflectance is taken as the weighted sum of all 6-channel  
 227 specific broad-band reflectance. The logic behind this approach is the assumption that the narrow-band  
 228 reflectance from each channel is a good representative for a limited spectral region centered around the  
 229 channel and the total spectral reflectance is dominated by the spectral region that contains the most solar  
 230 energy.

231 To generate “separate-channel” NTB coefficients, each narrow-band ABI channel reflectance is  
 232 converted to a reflectance  $\rho_{bb,i}$  separately,

$$233 \quad \rho_{bb,i}(\theta_0, \theta, \phi) = c_{0,i}(\theta_0, \theta, \phi) + c_{1,i}(\theta_0, \theta, \phi) * \rho_{nb,i}(\theta_0, \theta, \phi) \quad (4)$$

234 where  $\rho_{bb,i}$  is the band reflectance for an interval around each channel  $i$ ;  $c_{0,i}$  and  $c_{1,i}$  are regression  
 235 coefficients for channel  $i$ . These regression coefficients are derived separately for various combination of  
 236 surface, cloud and aerosol types. The total shortwave broad band (0.25 – 4.0 $\mu$ m) reflectance  $\rho_{bb}^{est}$  is  
 237 obtained by taking the weighted sum of all 6  $\rho_{bb,i}$  reflectance

$$238 \quad \rho_{bb}^{est}(\theta_0, \theta, \phi) = \sum_i \rho_{bb,i}(\theta_0, \theta, \phi) \frac{S_{0,i}}{S_0} \quad (5)$$

239 Here,  $S_0$  and  $S_{0,i}$  are total solar irradiance and band solar irradiance for each channel, respectively. Band  
 240 edges around the six ABI channels are: 49980-18723, 18723-13185, 13185-9221, 9221-6812, 6812-5292,  
 241 2500 cm<sup>-1</sup> 0.2001-0.5341, 0.5341-0.7584, 0.7584-1.0845, 1.0845-1.4680, 1.4680-1.8896, 1.8896-4.0000  
 242  $\mu$ m). The corresponding solar irradiance band values are 364, 360, 287, 168, 91, 87

243 W m<sup>-2</sup>. **Fig. 8** shows the sensor response function (SRF) and locations of the six ABI channels.

244 Coefficients are generated for clear condition and 3 types of cloudy conditions. Comparison between ABI  
 245 TOA flux and CERES products are shown in **Fig. 9**. The “separate-channel” coefficients work well for  
 246 predominantly clear sky (**Fig.10**). Differences are somewhat more scattered for cloudy cases. The reason  
 247 may be due to the fact that the ABI observation time and CERES product time do not match perfectly  
 248 since cloud condition change quickly. As discussed in Gristey et al. (2019) there are SW spectral  
 249 reflectance variations for different cloud types. Possibly, for ABI bands some spectral variations  
 250 associated with cloud variability are missed. It is important to have the correct cloud properties to be able  
 251 to select correct ADM. Misclassification of cloud properties will therefore result in flux differences. They

252 also argue that ADMs have an uncertainty due to within-scene variability and within-angular bin  
253 variability leading to additional flux differences.

254

### 255 **3. Data used**

256

#### 257 **3.1 Satellite data for GOES-16 and GOES17**

258

259 The GOES Imager data used (**Table 6**) were downloaded from <https://www.bou.class.noaa.gov/> and the  
260 SRF from <https://ncc.nesdis.noaa.gov/GOESR/ABI.php>

261 The CODC data were not always available from CLASS and had to be obtained from NOAA/STAR  
262 temporary archives. Also, not all the required angular information needed for implementation of  
263 regressions was available online and had to be recomputed.

264

#### 265 **3.2 Reference data from CERES**

266

267 The CERES Single Scanner Footprint (SSF) is a unique product for studying the role of clouds, aerosols,  
268 and radiation in climate. Each CERES footprint (nadir resolution 20-km equivalent diameter) on the SSF  
269 includes reflected shortwave (SW), emitted longwave (LW) and window (WN) radiances and top-of-  
270 atmosphere (TOA) fluxes from CERES with temporally and spatially coincident imager-based radiances,  
271 cloud properties, and aerosols, and meteorological information from a fixed 4-dimensional analysis  
272 provided by the Global Modeling and Assimilation Office (GMAO). Each file in this data product  
273 contains one hour of full and partial-Earth view measurements or footprints at a surface reference level.  
274 Detailed information can be found via <https://ceres.larc.nasa.gov/data/#ssf-level-2>.

275 Near real-time CERES fluxes and clouds in the SSF format are available within about a week of  
276 observation (Kratz et al., 2014). They do not use the most recent CERES instrument calibration and thus

277 contains some uncertainty. Before GOES data were transferred to the Comprehensive Large Array-data  
278 Stewardship System (CLASS) system, the NOAA/STAR archive was holding new data for about a week.  
279 Therefore, the initial evaluations had to be done only with data that overlapped in time. The CERES data  
280 known as the FLASHFlux Level2 (FLASH\_SSF) are available almost in real time from:

281 <https://ceres.larc.nasa.gov/products.php?product=FLASHFlux-Level2>

282 Due to such constraints the early comparison was done between ABI data as archived at NOAA/STAR  
283 and the FLASHFlux products (in this paper, the FLASHFlux data were used only in Fig. 9). The archiving  
284 of GOES-R at the NOAA Comprehensive Large Array-data Stewardship System (CLASS) started only  
285 in 2019, however, it contains data starting from 2017. Once the CLASS archive became available, we  
286 have augmented GOES-16 cases with observations from GOES-17; only those cases will be shown in this  
287 paper.

288

### 289 **3.3 Data preparation**

290

291 For the re-mapping, we adopted the ESMF re-gridding package. The detailed information can be found  
292 at: <http://earthsystemmodeling.org/regrid/>

293 For an ideal situation, the ABI high-resolution TOA SW fluxes should be mapped into the CERES  
294 footprint for validation. However, there are reasons that make it difficult to do so. There can be more than  
295 18000 pixels in a single swath of the SSF, when constrained to U.S. Different pixels have different times.  
296 Neglecting the seconds, there are still more than 30 mins differences (this changes case by case) between

297 the first pixel and the one at the end and this brings up a time matching issue. By remapping the SSF to  
298 ABI, we can set up a unique time for ABI (ABI is at 5 min intervals) and then constrain the region and  
299 the time range of SSF.

300 Both re-mapping the ABI to SSF and remapping SSF to the ABI bring up spatial matching errors as  
301 recognized by the scientific community (Rilee and Kuo, 2018; Ragulapati et al., 2021). In **Fig. 11**, we  
302 show the SSF before re-gridding (**Figs 11 (a) & (b)**) and after re-gridding (**Figs. 11 (c) and (d)**). The  
303 fluxes after re-mapping CERES SSF to the ABI resolution resemble well the original structure. Another  
304 consideration is the computational efficiency of re-mapping the curvilinear tripolar grid to unconstructed  
305 grid. For large arrays, it is more efficient to remap the unconstructed grid to the curvilinear tripolar grid.

306

## 307 **4. Results**

308

### 309 **4.1 Comparison between ABI TOA fluxes to those from CERES SSF**

310 A case for 2019/12/26 (doy 360) UTC 19:36 is illustrated in **Figs. 11-14**. Statistical summaries from an  
311 extended number of cases that cover all four seasons are presented in **Table 7**.

312 We have conducted several experiments to select an appropriate regression approach to the NTB  
313 transformation ensuring that non-physical results are not encountered. Based on the samples used in this  
314 study (**Table 7**) the differences found for Terra and GOES-16 were in the range of -0.5-(-17.37) for bias  
315 and 43.28-81.72 for standard deviation; for Terra and GOES-17 they were 11.26-47.09 and 70.25-108.73,  
316 respectively. For Aqua and GOES-16 they were 7.63-33.87 and 58.68-117.43 respectively while for Aqua  
317 and GOES-17 they were 0.19-31.53 and 47.55-129.42, respectively (all units are  $W m^{-2}$ ). The evaluation  
318 process revealed the challenges in undertaking such comparisons. Both estimates of TOA fluxes (CERES  
319 and GOES) do no account for seasonality in the land use classification; the time matching for the different

320 satellites is important and limits the number of samples that can be used in the comparison. Based on the  
321 results of this study recommendation for future work include the need to incorporate seasonality in land  
322 use and spectral characteristic of the various surface types. Possible stratification by season in the  
323 regressions could also be explored.

324

## 325 **4.2 Causes for differences between ABI and CERES TOA fluxes**

326

### 327 **4.2.1 Differences in surface spectral reflectance**

328

329 In the MODTRAN simulations we use the spectral reflectance information on various surface types as  
330 provided by MODTRAN. MODTRAN version 4.3.1 contains a collection of spectral surface reflectance  
331 dataset from the Moderate Spectral Atmospheric Radiance and Transmittance (MOSART) model  
332 (Cornette et al., 1994) and others from Johns Hopkins University Spectral Library (Baldrige et al., 2009).  
333 When doing simulation, we call the built-in surface types and use the provided surface reflectance. As  
334 such, the spectral dependence of the surface reflectance used in the simulations and matched to the  
335 CERES surface types may not be compatible with the classification of CERES. Also, seasonal changes  
336 in surface type classification can introduce errors due to changes in the spectral surface reflectance for  
337 different surface types (**Fig. 15**).

338

### 339 **4.2.2 Issues related to surface classification**

340

341 Another possible cause for differences between the TOA fluxes is the classification of surface types as  
342 originally identified by the IGBP and used in the simulations. No seasonality is incorporated in the surface  
343 type classification while such variability is part of the CERES observations.

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### 347 **4.2.3 Issues related to match-up between GOES-R and CERES**

348  
349 Both Terra and Aqua have sun-synchronous, near-polar circular orbits. Terra is timed to cross the equator  
350 from north to south (descending node) at approximately 10:30 am local time. Aqua is timed to cross the  
351 equator from south to north (ascending node) at approximately 1:30 pm local time. The periods for Terra  
352 and Aqua are 99 and 98 minutes, respectively. Both have 16 orbits per day. CERES on Terra and Aqua  
353 optical FOV at nadir is 16 x 32 or 20 km resolution. Terra passes CONUS during 03-06 UTC (US night  
354 time), 16-20 UTC (US day time), and Aqua passes CONUS during 07-11 UTC (US night time), 18-22  
355 UTC (US day time).

356 Both Terra and Aqua have an instantaneous FOV values at SWATH level. There is no perfect overlap,  
357 temporally or spatially with ABI data. The ABI radiance and cloud data are on a regular grid of 2\*2 km  
358 over CONUS at each hour. To use CERES data for evaluation of ABI, there is a need to perform  
359 collocation in both time and space.

## 361 **5. Summary**

362  
363 The derivation and evaluation of TOA radiative fluxes as simulated for any given instrument are quite  
364 challenging. In principle, there is a need to account for all possible changes in the atmospheric and surface  
365 conditions one may encounter in the future. Yet, to know what these conditions are at the time of actual  
366 observation when there is a need to select the appropriate combination of variables from the simulations,  
367 is a formidable task. Differences in assumed cloud properties can also lead to differences in the fluxes  
368 derived from the two instruments. Therefore, error can be expected due to discrepancies between the  
369 actual conditions and the selected simulations and these are difficult to estimate. The approach we have  
370 selected is based on high-quality simulations using a proven and accepted radiative transfer code  
371 (MODTRAN) of known configurations and a wide range of atmospheric conditions. We have also  
372 selected the best available estimates of TOA radiative fluxes from independent sources for evaluation.  
373 However, the matching between different satellites in space and time is challenging. In selecting the cases

374 for evaluation, we have adhered to strict criteria of time and space coincidence as described in section  
375 3.3.

376 Critical elements of an inference scheme for TOA radiative flux estimates from satellite observations are:

377 1) transformation of narrowband quantities into broadband ones;

378 2) transformation of bi-directional reflectance into albedo by applying Angular Distribution Models

379 (ADMs). In principle, the order in which these transformations are executed is arbitrary. However, since

380 well established, observation-based broadband ADMs derived from the Clouds and the Earth's Radiant

381 Energy System (CERES) project already exist, the logical procedure is to do the NTB transformation on

382 the radiances first, and then apply the ADM. This is the sequence that has been followed here. While the

383 road map to accomplish above objectives seems well defined, reaching the final goal of having a stable

384 up-to-date procedure for deriving TOA radiative fluxes from a new instrument like the ABI on the new

385 generation of GOES satellites is quite complicated. Since the final configuration of the instrument

386 becomes known at a much later stages the evaluation of new algorithms is in a fluid stage for a long time

387 so early evaluation against "ground truth" needs to be repeated frequently. Additional complication is

388 related to the lack of maturity of basic information needed in the implementation process, such as a

389 reliable cloud screened product which in itself is in a process of development and modifications. The

390 "ground truth", namely, the CERES observations are also undergoing adjustments and recalibration. As

391 such, the process of deriving best possible estimates of TOA radiative fluxes from ABI underwent

392 numerous iterations to reach its current status. An effort was made to deal the best way possible with the

393 fluid situation. All the evaluations against CERES were repeated once the ABI data reached stability and

394 were archived in CLASS and we used the most recent auxiliary information. This study sets the stage for

395 future possible improvements. One example is land classification which currently is static. Another issue

396 is related to the representation of real time aerosol optical properties which are important under clear sky

397 conditions. It is believed that only now when NOAA/STAR has a stable aerosol retrieval algorithm, it

398 would be timely to address the aerosol issue in the estimation of TOA fluxes under clear sky.

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401 Data availability. The data are available upon request from the corresponding author.

402 Author contributions. The investigation and conceptualization were carried out by RTP, IL and JD. YM  
403 and WC developed the software. RTP prepared the original draft. All authors contributed to the writing,  
404 editing and review of the publication.

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## Tables

Table 1. Channel information and spectral bands for ABI.

<i>ABI Band #</i>	<i>Central wavelength ( <math>\mu m</math> )</i>	<i>Spectral band ( <math>\mu m</math> )</i>
1	VIS 0.47	0.45-0.49
2	VIS 0.64	0.60-0.68
3	NIR 0.86	0.847-0.882
4	NIR 1.38	1.366-1.380
5	NIR 1.61	1.59-1.63
6	NIR 2.26	2.22-2.27

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542 Table 2. Surface classification description for IGBP 18 types, IGBP 12 types, CERES clear sky 6 types,  
 543 and NTB cloudy sky 4 types

IGBP (18 types)	IGBP (12 types)	CERES clear-sky (6 types)	NTB cloudy-sky (4 types)
Evergreen Needleleaf	Needleleaf Forest	Mod-High Tree/Shrub	Land
Deciduous Needleleaf			
Evergreen Broadleaf	Broadleaf Forest		
Deciduous Broadleaf			
Mixed Forest	Mixed Forest		
Closed Shrublands	Closed Shrub		
Woody Savannas	Woody Savannas		
Savannas	Savannas		
Grasslands	Grasslands		
Permanent Wetlands			
Tundra			
Croplands		Croplands	
Open Shrublands	Open Shrub		
Urban and Built-up	Open Shrub	Dark Desert	Desert
Bare Soil and Rocks	Barren and Desert	Bright Desert	
Snow and Ice	Snow and Ice	Snow and Ice	Snow and Ice
Water Bodies	Ocean	Ocean	Water

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548 Table 3. The various classes for which NTB coefficients are generated.

<b>Parameter</b>	<b>Clear condition</b>	<b>Cloudy condition</b>
Aerosol or cloud type	6 aerosol types (rural, maritime, urban, tropospheric, fog, desert)	3 cloud types (cirrus, stratocumulus, altostratus)
Optical depth (OD)	Typical VIS (km) values for each aerosol types (no OD grid for each aerosol type). Rural: 23, maritime: 23, urban: 5, tropospheric: 50, fog: 0.2, desert: (default VIS for wind speed 10m/s)	Cirrus: [0, 0.8, 1.2, 1.8, 3.2] Stratocumulus: [0, 0.8, 1.2, 1.8, 3.2, 5.8, 8.2, 15.8, 32.2, 51.8, 124.2] Altostratus: [0, 15.0, 30.0, 50.0, 80.0]
Surface type	12 IGBP surface types	4 types (Water, Land, Desert, Snow/Ice)

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553 Table 4. Angles used in simulations. To be consistent with what is presented in the

554 ABI Shortwave Radiation Budget (SRB) Algorithm Theoretical Basis Documents (ATBD) (Laszlo

555 et al, 2018) the additional angles used in the simulations are not given in this Table.

Angle Type	Angles
Solar Zenith Angle [°]	0.0, 12.9, 30.8, 41.2, 48.3, 56.5, 63.2, 69.5, 75.5, 81.4, 87.2
Satellite Zenith Angle [°]	0.0, 11.4, 26.1, 40.3, 53.8, 65.9, 76.3
Azimuth Angle [°]	0.0, 1.9, 10.0, 24.2, 44.0, 68.8, 97.6, 129.3, 162.9, 180

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Table 5. MODTRAN simulation speed test (CPU MHz 2099.929).

Algorithm	Stream	Band Resolution (cm <sup>-1</sup> )	Speed (~seconds)
Isaacs	2	1	40
DISORT	2	1, 5, 15	280, 70, 30
	4	1, 5, 15	560, 120, 40
	8	1, 5, 15	930, 300, 110
Scaled Isaac	2	1, 5, 15	30, 10, 6.67
	4	1, 5, 15	30, 10, 6.67
	8	1, 5, 15	30, 10, 6.67

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565 Table 6. Details on data used as input for calculations.

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Short Name	Long Name	MODE	ABI-Channel	Scan Sector	Spatial Resolution
RadC	L1b Radiance	M6	C01-C06	CONUS	5000x3000
AODC	L2 Aerosol	M6	--	CONUS	2500x1500
ACMC	L2 Clear Sky Masks	M6	--	CONUS	2500x1500
ACTPC	L2 Cloud Top Phase	M6	--	CONUS	2500x1500
CODC*	L2 Cloud Optical Depth	M6	--	CONUS	2500x1500

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570 Table 7. Statistical summary for all selected cases intercompared at instantaneous time scale.

Case	CERES	GOES-R	Corr	Bias	Std	RMSE	N
07/31 2019	Terra	G16	0.82	0.81	69.81	69.81	0.22 x10 <sup>6</sup>
		G17	0.87	29.13	90.10	94.70	1.78 x10 <sup>6</sup>
UTC 19	Aqua	G16	0.76	33.87	117.43	122.22	1.58 x10 <sup>6</sup>
		G17	0.78	31.53	129.42	133.21	0.29 x10 <sup>6</sup>
09/13 2019	Terra	G16	0.87	-17.37	81.72	83.54	0.13x10 <sup>6</sup>
		G17	0.71	47.09	108.73	118.48	1.73x10 <sup>6</sup>
UTC 20	Aqua	G16	0.76	18.22	108.50	110.02	1.46x10 <sup>6</sup>
		G17	0.73	25.14	81.95	85.72	0.53x10 <sup>6</sup>
09/21 2019	Terra	G16	0.85	6.78	66.66	67.00	0.35x10 <sup>6</sup>
		G17	0.83	26.41	87.64	91.57	1.75x10 <sup>6</sup>
UTC 19	Aqua	G16	0.82	29.66	105.09	109.20	1.67x10 <sup>6</sup>
		G17	0.76	6.03	94.70	94.89	0.15x10 <sup>6</sup>
09/30 2019	Terra	G16	0.88	4.49	64.79	64.94	0.40x10 <sup>6</sup>
		G17	0.80	19.35	86.41	88.55	1.74x10 <sup>6</sup>
UTC 19	Aqua	G16	0.80	19.87	100.45	102.40	1.69x10 <sup>6</sup>
		G17	0.72	2.71	91.79	91.83	0.12x10 <sup>6</sup>
	Terra	G16	0.86	5.84	51.44	51.77	0.35x10 <sup>6</sup>

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10/23		G17	0.87	22.47	70.25	73.76	1.75x10 <sup>6</sup>
2019		G16	0.89	17.10	75.95	77.85	1.67x10 <sup>6</sup>
UTC	Aqua	G17	0.78	8.98	72.52	73.07	0.15x10 <sup>6</sup>
19		G16	0.87	-0.50	43.28	43.28	0.35x10 <sup>6</sup>
11/08	Terra	G17	0.82	17.18	71.27	73.31	1.75x10 <sup>6</sup>
2019		G16	0.90	10.08	71.27	71.98	1.67x10 <sup>6</sup>
UTC	Aqua	G17	0.68	1.53	47.55	47.58	0.15x10 <sup>6</sup>
19		G16	0.79	7.98	49.10	49.75	0.35x10 <sup>6</sup>
11/24	Terra	G17	0.87	14.10	78.35	79.61	1.76x10 <sup>6</sup>
2019		G16	0.82	7.63	58.68	59.17	1.67x10 <sup>6</sup>
UTC	Aqua	G17	0.65	0.19	63.14	63.14	0.15x10 <sup>6</sup>
19		G16	0.88	5.24	53.28	53.54	0.35x10 <sup>6</sup>
12/26	Terra	G17	0.76	11.26	73.95	74.80	1.76x10 <sup>6</sup>
2019		G16	0.83	9.79	58.90	59.56	1.67x10 <sup>6</sup>
UTC 19	Aqua	G17	0.73	0.85	52.53	52.54	0.15x10 <sup>6</sup>

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579

## 580 List of Figures

- 581 Figure 1. Flowchart of the NTB transformations illustrating the main processing sections.
- 582 Figure 2. Schematic illustration of the logic employed to synthesize modeled and observed ADMs.
- 583 Figure 3. The location of the 100 selected clear sky profiles from SeeBor used in the simulations.
- 584 Figure 4. Profile statistics of: (a) temperature; (b): water vapor; (c) ozone for the entire available sample  
585 and for the reduced sample used in this study. Error bar is 1 standard deviation.
- 586 Figure 5. Re-mapped IGBP surface classifications over the CONUS at 2-km ABI grid.
- 587 Figure 6. Simulated Radiances from DISORT 8-stream (with 1, 5, and 15  $\text{cm}^{-1}$  resolution band model  
588 for spectral range of 0.4 – 0.5  $\mu\text{m}$  (left) and 1.5 – 2.0  $\mu\text{m}$  (right).
- 589 Figure 7. Radiance differences between various multi-scattering algorithms and DISORT-8 stream.  
590 *Upper*: the whole simulated spectrum of 0.2-4  $\mu\text{m}$ ; *Lower*: zoom on 0.3-0.35  $\mu\text{m}$  (Relative  
591 Azimuthal Angle=1.9°, View Angle=76.3°, Solar Zenith Angle=87.2°).
- 592 Figure 8. Locations of the six ABI channel SRFs. X-axis is wavenumber. Y-axis is solar irradiance.
- 593 Figure 9. Comparison of TOA flux from ABI and CERES FLASHFlux for 2017/11/25, 17:57Z. (a)  
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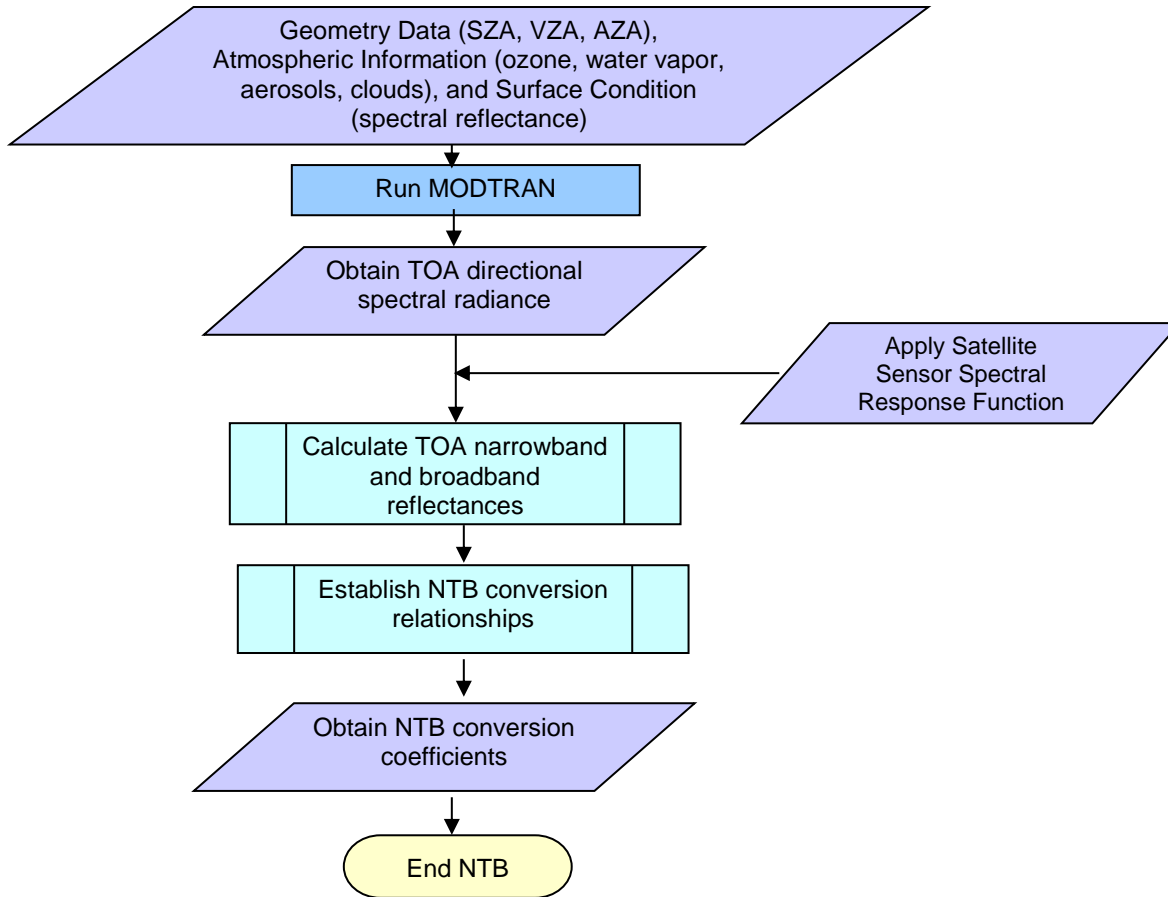
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643 **Figures**

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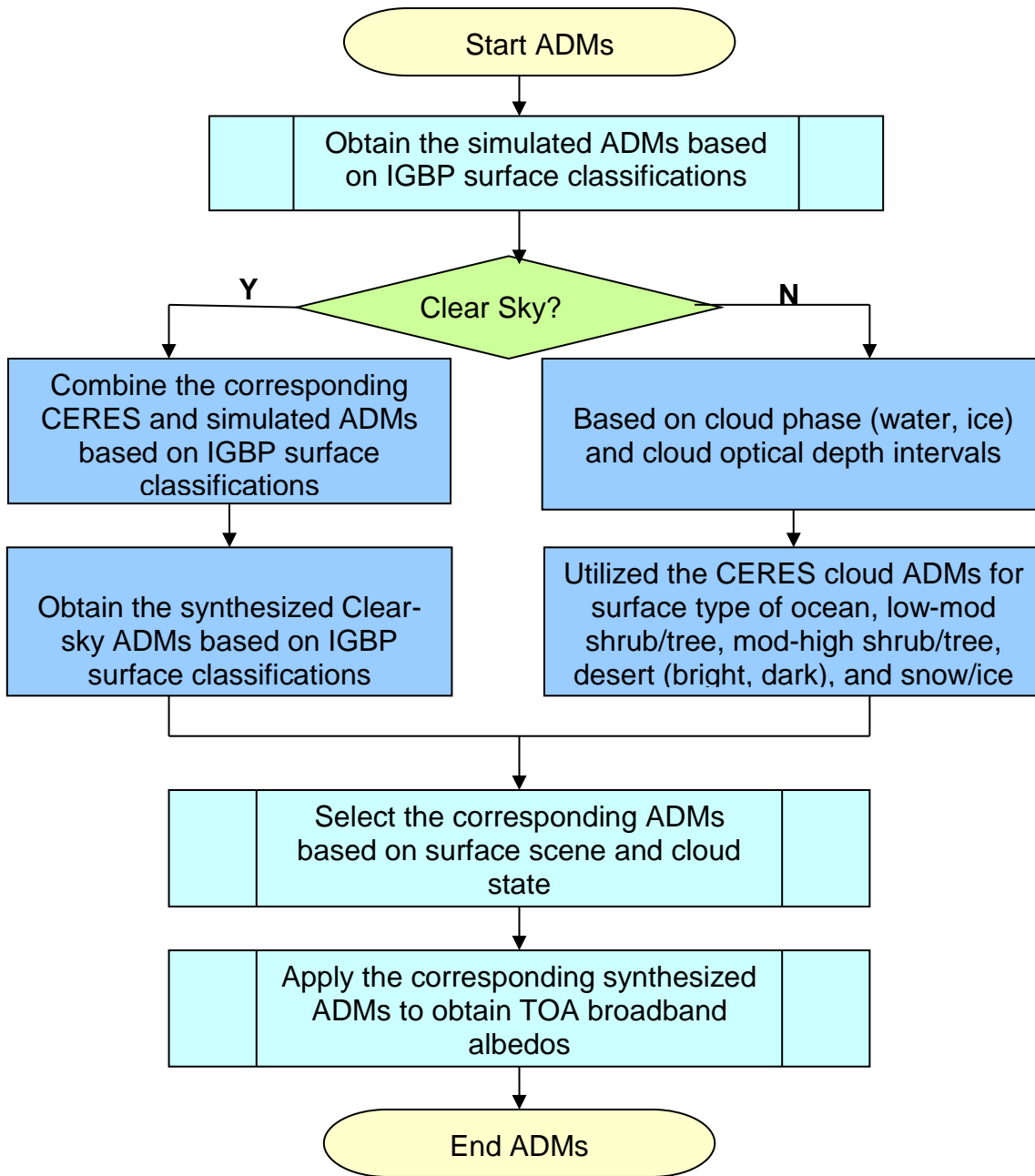
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647 Figure 1. Flowchart of the NTB transformations illustrating the main processing sections.

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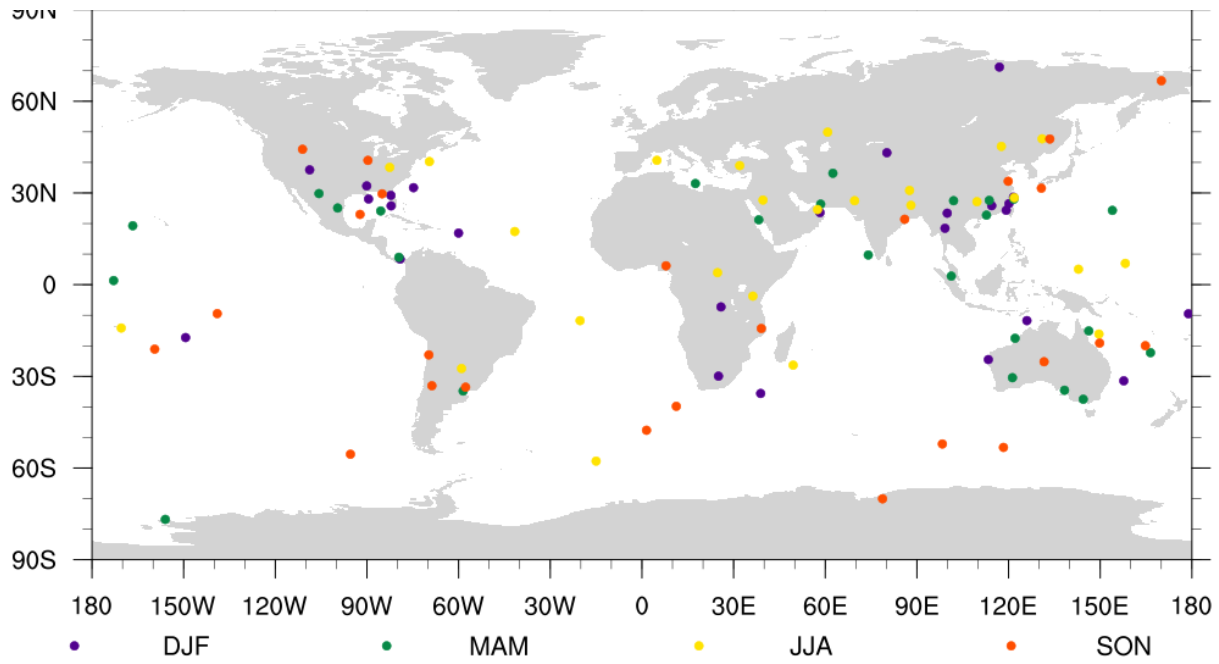
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652 Figure 2. Schematic illustration of the logic employed to synthesize modeled and observed ADMs.

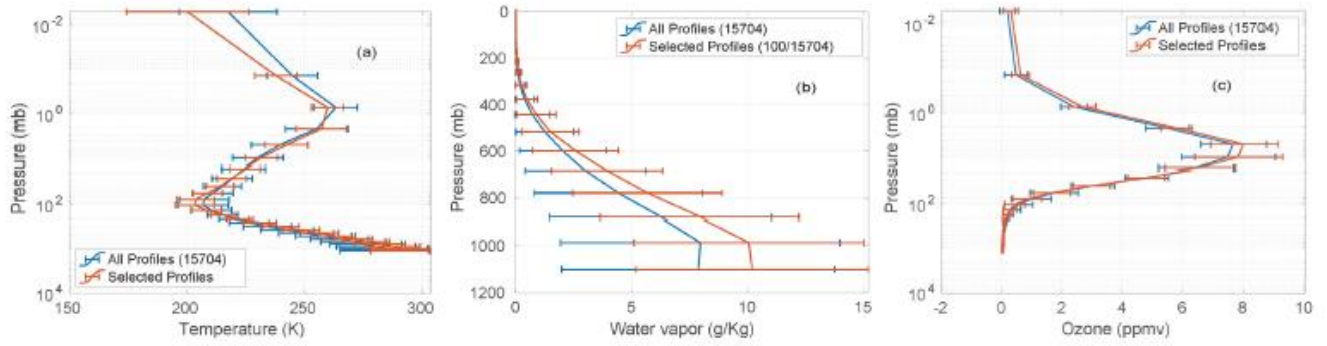
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Figure 3. The location of the 100 selected clear sky profiles from SeeBor used in the simulations.

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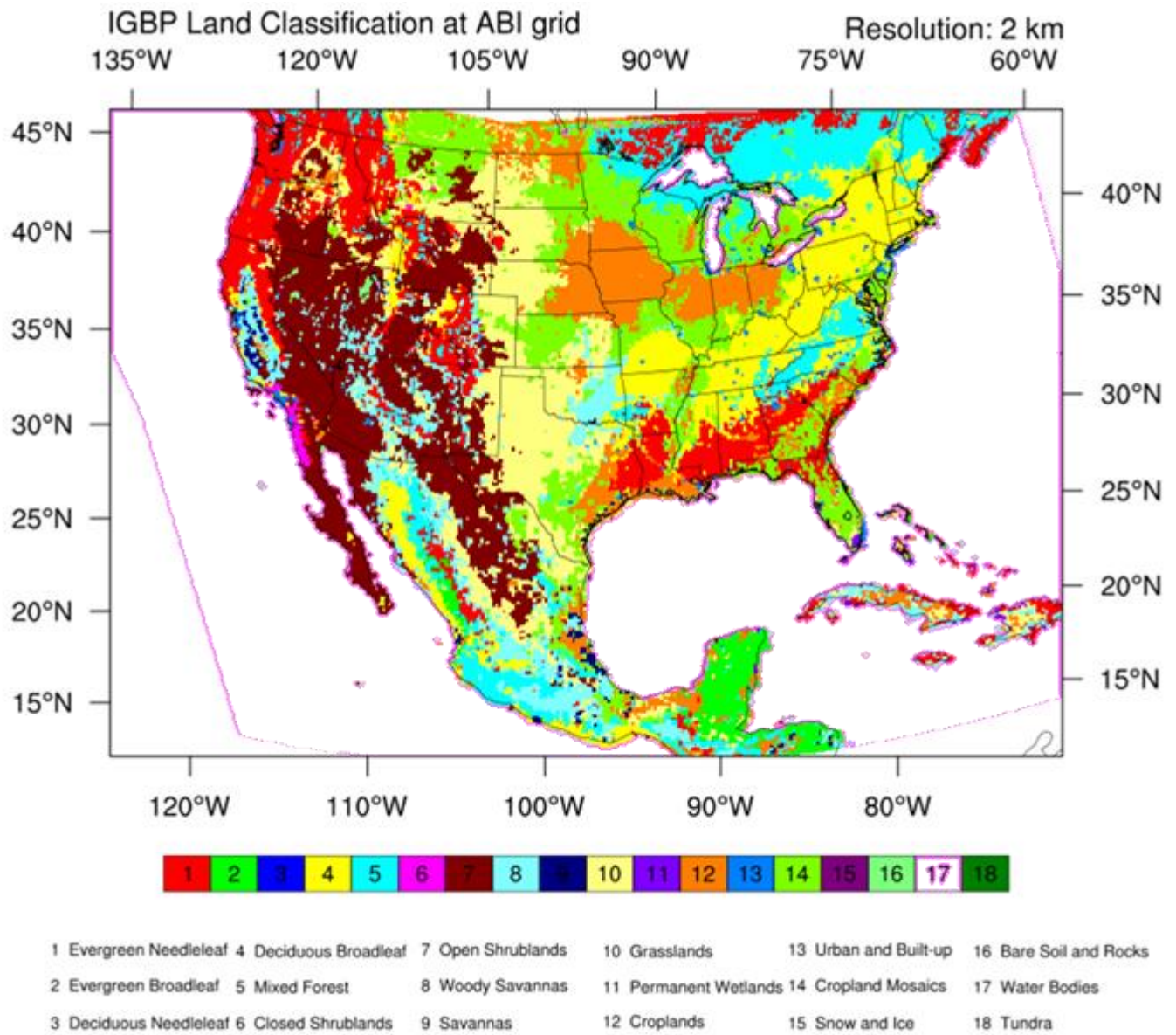


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662 Figure 4. Profile statistics of: (a) temperature; (b): water vapor; (c) ozone for the entire available sample  
663 and for the reduced sample used in this study. Error bar is 1 standard deviation.

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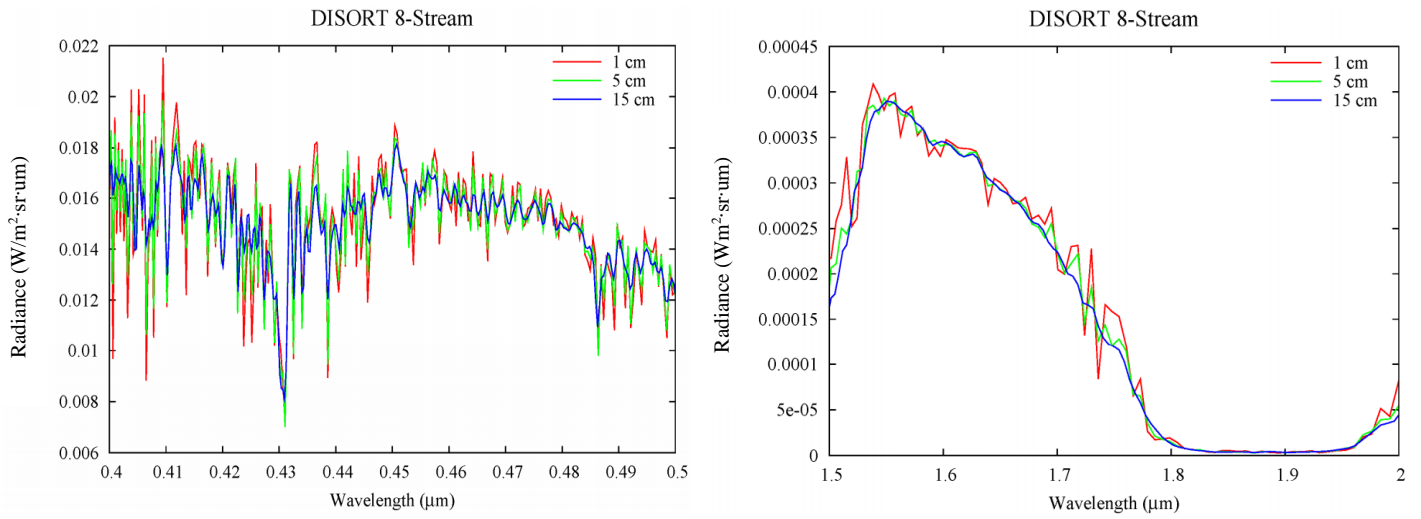
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668 Figure 5. Re-mapped IGBP surface classifications over the CONUS at 2-km ABI grid.

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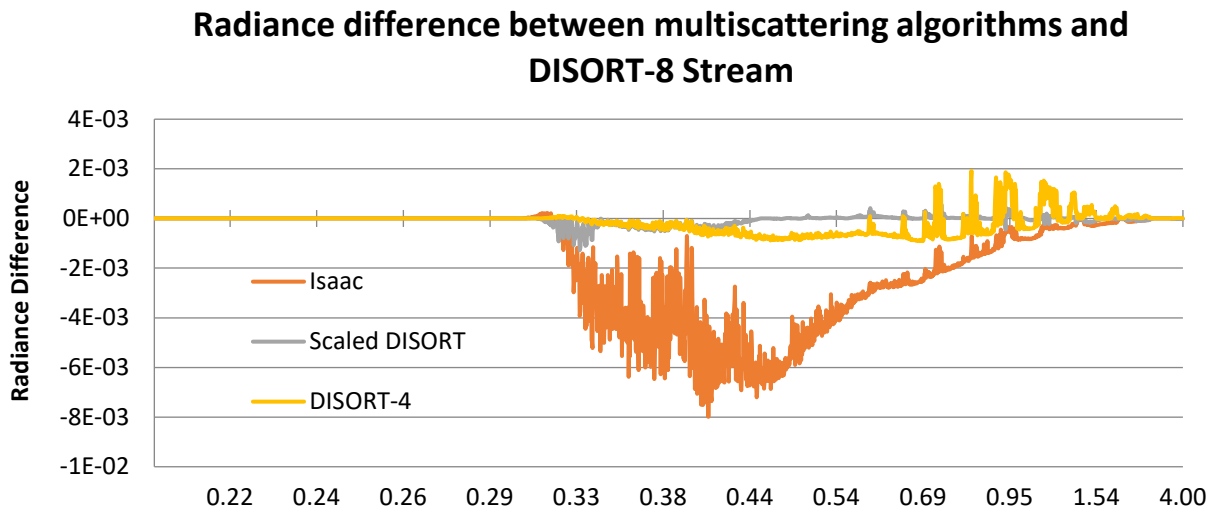
673 Figure 6. Simulated Radiances from DISORT 8-stream (with 1, 5, and 15 cm<sup>-1</sup> resolution band  
674 model for spectral range of 0.4 – 0.5 μm (left) and 1.5 – 2.0 μm (right).

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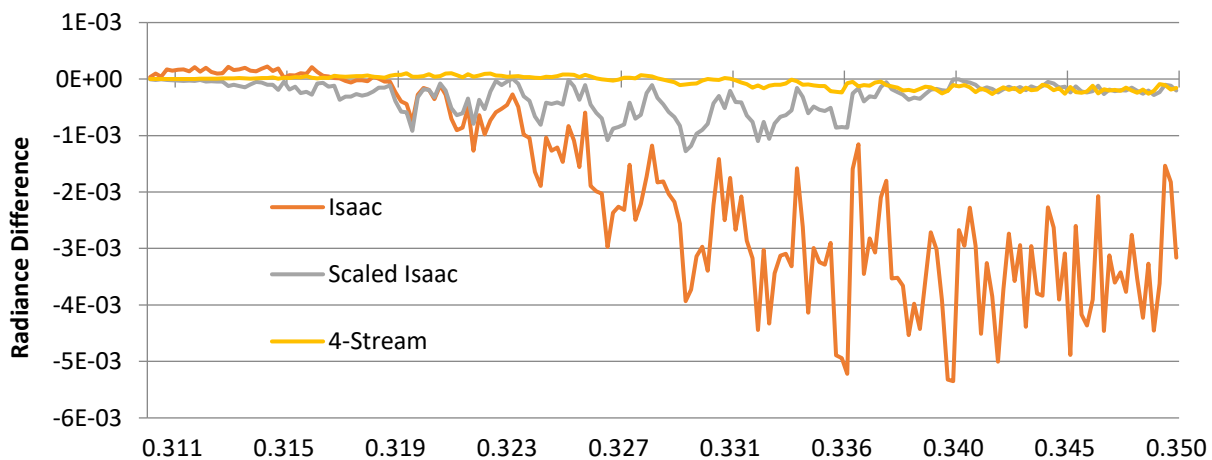
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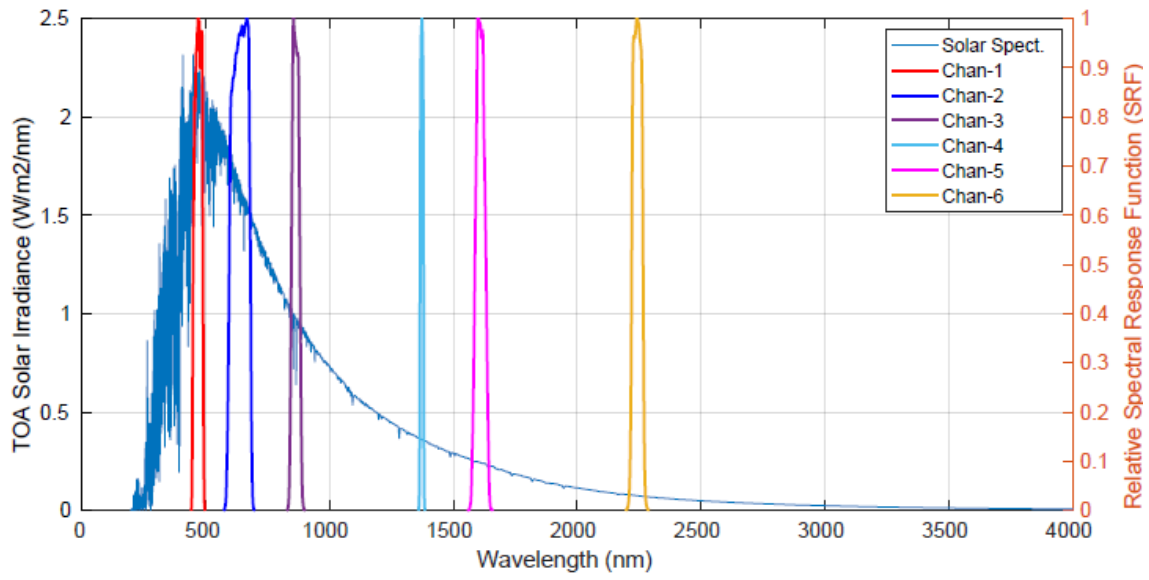
681 Figure 7. Radiance differences between various multi-scattering algorithms and DISORT-8 stream.

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*Upper: the whole simulated spectrum of 0.2-4  $\mu\text{m}$ ; Lower: zoom on 0.3-0.35  $\mu\text{m}$  (Relative Azimuthal Angle=1.9°, View Angle=76.3°, Solar Zenith Angle=87.2°).*



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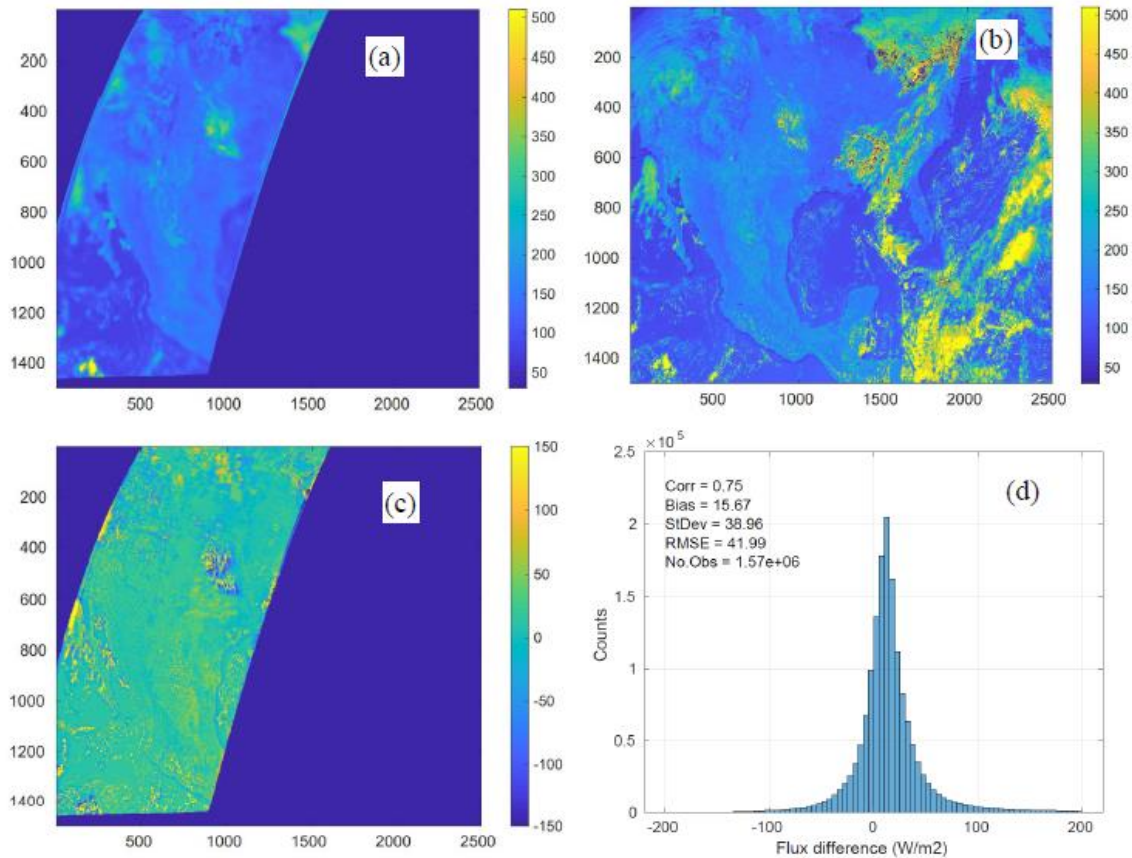
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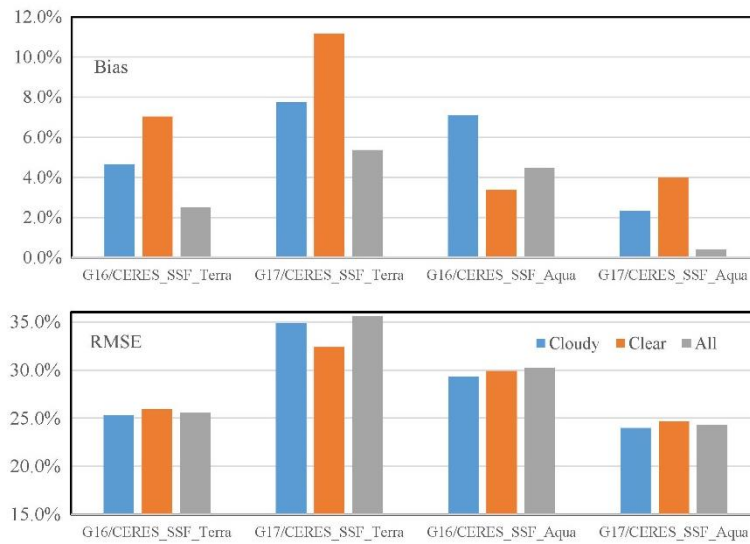
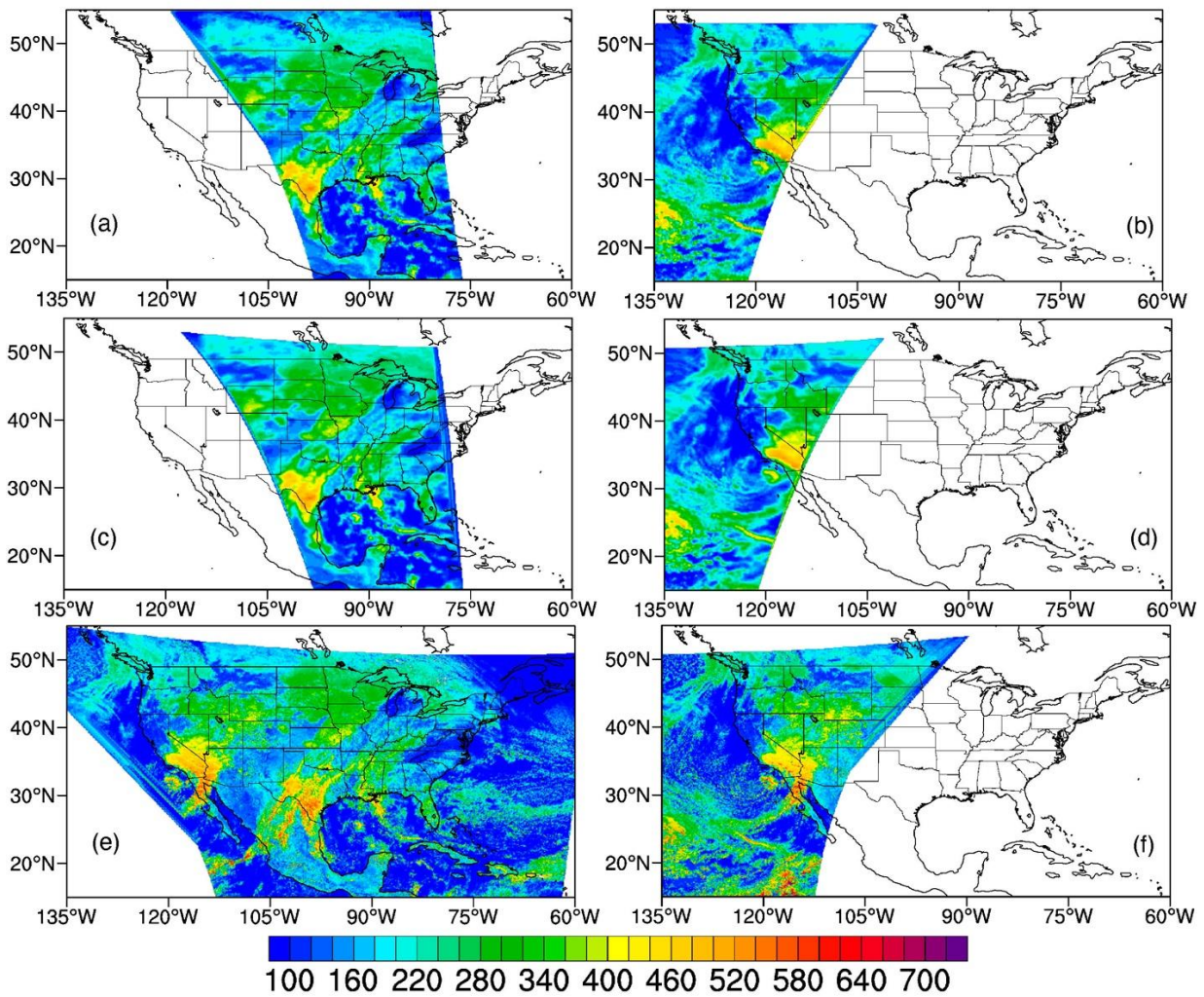


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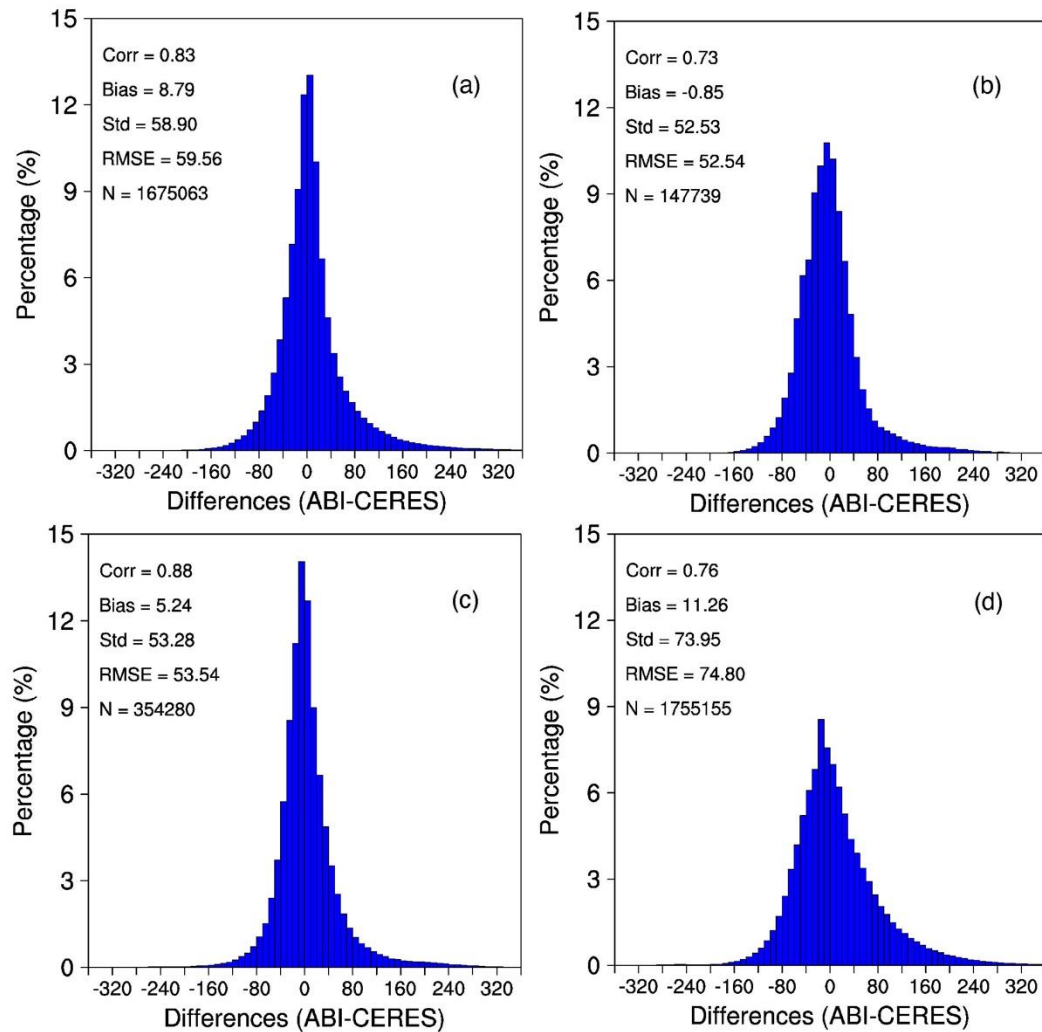


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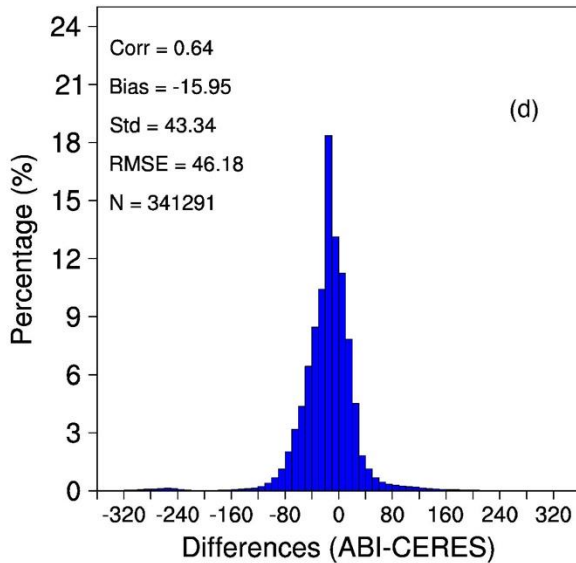
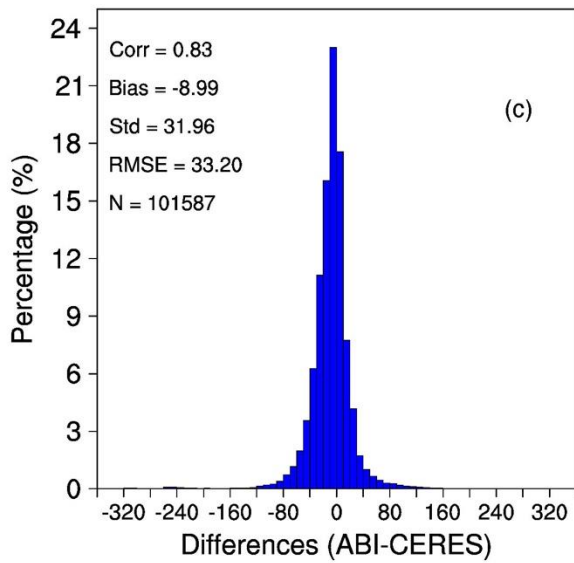
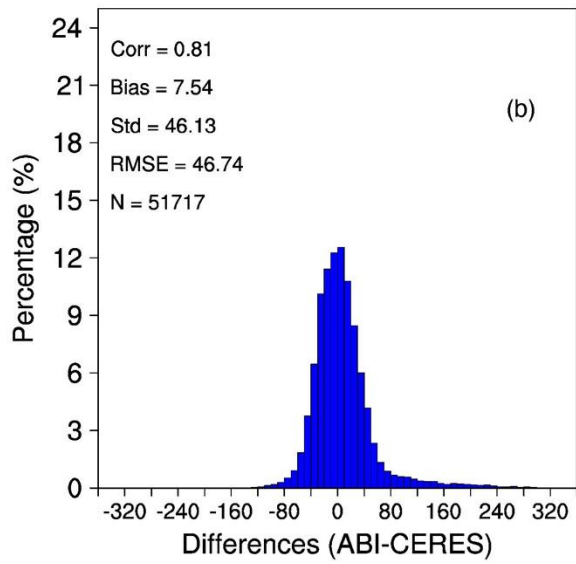
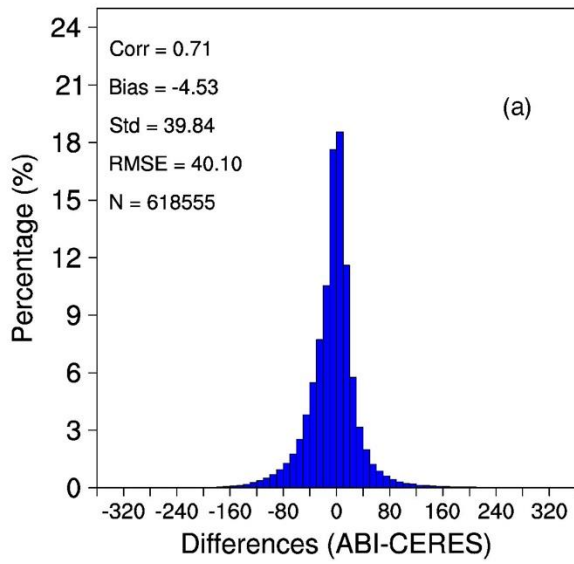
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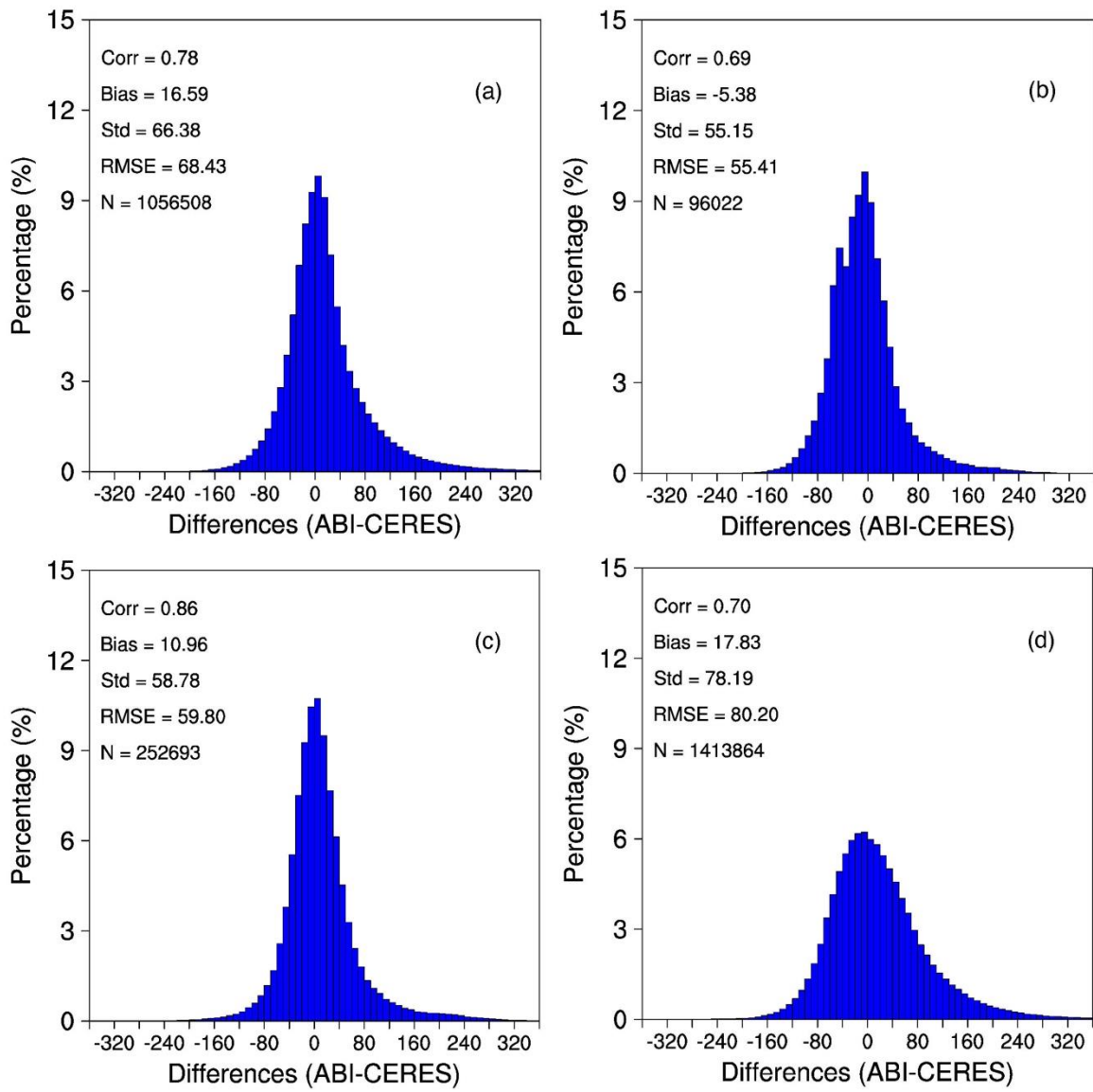
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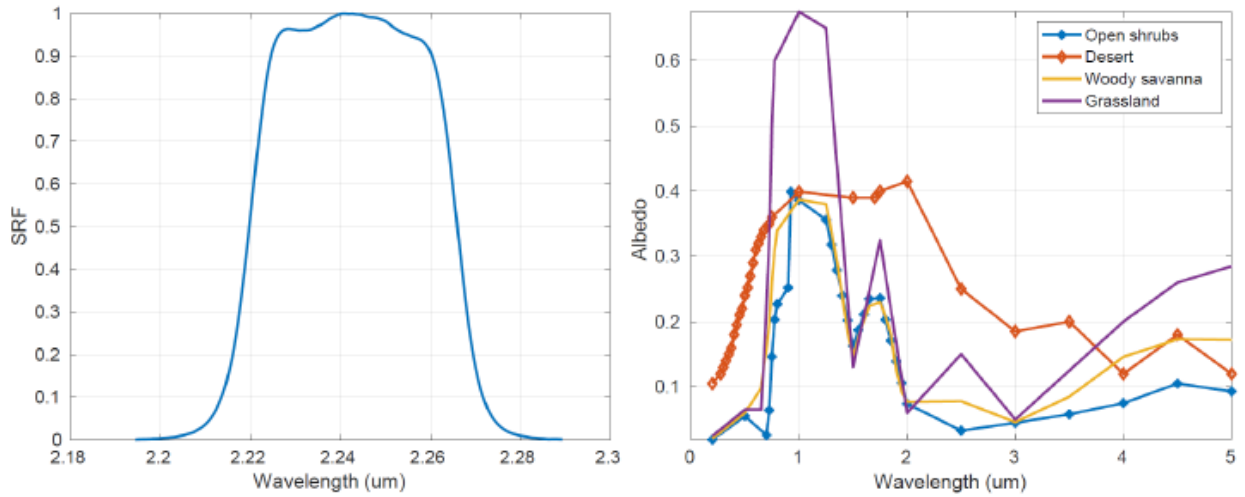
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