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3 Top of the Atmosphere Reflected Shortwave Radiative Fluxes from GOES-R
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12 **Abstract.** Under the GOES-R activity, new algorithms are being developed at the National Oceanic and
13 Atmospheric Administration (NOAA)/Center for Satellite Applications and Research (STAR) to derive
14 surface and Top of the Atmosphere (TOA) shortwave (SW) radiative fluxes from the Advanced Baseline
15 Imager (ABI), the primary instrument on GOES-R. This paper describes a support effort in the
16 development and evaluation of the ABI instrument capabilities to derive such fluxes. Specifically, scene
17 dependent narrow-to-broadband (NTB) transformations are developed to facilitate the use of observations
18 from ABI at the TOA. Simulations of NTB transformations have been performed with MODTRAN4.3
19 using an updated selection of atmospheric profiles and implemented with the final ABI specifications.
20 These are combined with Angular Distribution Models (ADMs), which are a synergy of ADMs from the
21 Clouds and the Earth's Radiant Energy System (CERES) and from simulations. Surface condition at the
22 scale of the ABI products as needed to compute the TOA radiative fluxes come from the International
23 Geosphere-Biosphere Programme (IGBP). Land classification at 1/6 ° resolution for 18 surface types are
24 converted to the ABI 2-km grid over the (CONtiguous States of the United States) (CONUS) and
25 subsequently re-grouped to 12 IGBP types to match the classification of the CERES ADMs. In the
26 simulations, default information on aerosols and clouds is based on the ones used in MODTRAN.

27 Comparison of derived fluxes at the TOA is made with those from CERES. A satisfactory agreement
28 between the fluxes was observed for both clear and cloudy conditions and possible reasons for differences
29 have been identified.

30

31 **1. Introduction**

32

33 One of the objectives at NOAA/STAR in respect to the utilization of observations from the Advanced
34 Baseline Imager (ABI) is to be able to derive shortwave ($SW \downarrow$) radiative fluxes at the surface. To get to
35 the surface $SW \downarrow$ from TOA satellite observations, there are two generic approaches: 1) the direct approach
36 and 2) the indirect approach. In the direct approach one uses all the necessary information needed for
37 deriving the surface fluxes (some of which can be derived from satellites). Implementation of such an
38 approach is feasible, for instance, with observations from MODIS which has a long history of product
39 availability and evaluation. Examples are illustrated in Wang and Pinker (2009), Niu and Pinker, (2015),
40 Ma et al. (2016), Pinker et al. (2018), Pinker et al., (2017a), Pinker et al. (2017b). GOES-R is a new
41 instrument and as yet, similar information to the one from MODIS is not yet available. Therefore, the
42 indirect approach is used where one starts from satellite observations at the TOA and models the
43 atmosphere and surface with best available information (which does not have to be based on ABI).
44 Examples of such an approach are discussed in Pinker, Zhang and Dutton (2005), Ma and Pinker (2012)
45 and Zhang et al. (2019). The “indirect path method” is used at the Center for Satellite Applications and
46 Research (STAR) (Laszlo et al., 2020) for deriving $SW \downarrow$ radiative fluxes from satellite observations; it
47 requires knowledge of the SW broadband (0.2 – 4.0 μm) top of the atmosphere (TOA) albedo. The
48 Advanced Baseline Imager (ABI) observations onboard of the NOAA GOES-R series of satellites provide
49 reflectance in six narrow bands in the shortwave spectrum (**Table 1**); these must be first transformed into
50 broadband reflectance (the NTB conversion), and the broadband reflectance must be transformed into a
51 broadband albedo (the ADM conversion). During the pre-launch activity NTB transformations were
52 developed based on theoretical radiative transfer simulations with MODTRAN-3.7 and 14 land use

53 classifications from the International Geosphere-Biosphere Programme (*IGBP*) (Hansen et al., 2010).
54 They were augmented with ADMs from (CERES) observed ADMs (Loeb et al., 2003) and theoretical
55 simulations (Niu and Pinker, 2011) to compute TOA fluxes. The resulting NTB transformations and
56 ADMs have been tested using proxy data and simulated ABI data. The proxy instruments used in these
57 early simulations include the GOES-8 satellite, the Advanced Very-High Resolution Radiometer
58 (AVHRR) sensor on the Polar Orbiting satellites, the Spinning Enhanced Visible Infra-Red Imager
59 (SEVIRI) sensor on the European METEOSAT Second Generation (MSG) satellites, and the Moderate
60 Resolution Imaging Spectroradiometer (MODIS) instrument on the NASA Terra and Aqua Polar Orbiting
61 satellites (Pinker et al., 2021, unpublished). For each of these satellites, the evaluation of the
62 methodologies was done differently; some results were evaluated against ground observations while
63 others, against TOA information from CERES as well as from the (ESA) Geostationary Earth Radiation
64 Budget (GERB) satellite (Harries et al., 2005). The results obtained provided an insight on the expected
65 performance of the new ABI sensor. Those procedures have been subsequently updated and applied to
66 the new ABI instrument once it was built and fully characterized.

67 In this paper we describe activity in support of the effort to derive surface shortwave ($SW\downarrow$) radiative
68 fluxes from the operational Advanced Baseline Imager (ABI) instrument on the GOES-R series of the
69 NOAA geostationary meteorological satellites using the latest version of the ABI data. We describe the
70 physical basis and the development of the (NTB) transformations of satellite observed radiances and the
71 bi-directional corrections to be applied to the broadband reflectance to obtain broadband TOA albedo.
72 The methodology will be presented in section 2, data used are described in section 3, results in section 4
73 and a summary and discussion in section 5.

74

75 **2. Methodology**

76

77 The following two flowcharts (**Figs. 1 and 2**) describe the necessary steps to derive the NTB
78 transformations and the ADMs. Details on these two steps will follow.

79 The TOA narrowband and broadband reflectance can be calculated from the spectral radiances
80 simulated from MODTRAN 4.3 and the response functions of the satellite sensor as shown in equations
81 (1) and (2):

$$82 \rho_{nb}(\theta_0, \theta, \phi) = \frac{\pi \int_{\lambda_1}^{\lambda_2} I(\lambda, \theta_0, \theta, \phi) G(\lambda) d\lambda}{\int_{\lambda_1}^{\lambda_2} \cos(\theta_0) S_0(\lambda) G(\lambda) d\lambda} \quad (1)$$

$$83 \rho_{bb}(\theta_0, \theta, \phi) = \frac{\pi \int_{4\mu m}^{0.2\mu m} I(\lambda, \theta_0, \theta, \phi) d\lambda}{\int_{4\mu m}^{0.2\mu m} \cos(\theta_0) S_0(\lambda) d\lambda} \quad (2)$$

84

85 where ρ_{nb} is narrowband reflectance; ρ_{bb} is broadband reflectance; θ_0 : solar zenith angle; θ : view
86 (satellite) zenith angle; ϕ : relative azimuth angle;

87 I_λ : reflected spectral radiance; $S_0(\lambda)$: solar spectral irradiance;
88 G_λ : spectral response functions of satellite sensors; λ_1 and λ_2 are the spectral limits of the sensor spectral
89 band. This approach is widely used in the scientific community as also implemented in the work of Loeb
90 et al (2005), Wielicki et al. (2008), Su et al. (2015) and Akkermans et al. (2020).

91 As stated previously, the ADMs from CERES-based observations (Loeb et al., 2005; Kato et al. 2015)
92 were augmented with theoretical simulations (Niu and Pinker, 2011) to compute TOA fluxes. This was
93 done since CERES observations at that time were under-sampled. at higher latitudes.

94 The combined ADMs are developed for each angular bin by weighting the modeled and CERES ADMs
95 based on the number of samples used to derive the ADMs of each type (Niu et al., 2011). Specifically:

96
$$\bar{R}(\theta_0, \theta, \phi) = \frac{1}{m+n} (m \times R_{CERES}(\theta_0, \theta, \phi) + n \times R_s(\theta_0, \theta, \phi)) \quad (3)$$

97 $\bar{R}(\theta_0, \theta, \phi)$: averaged ADMs at each angular bin;

98 R_{CERES} : anisotropic factor from CERES ADMs;

99 R_s : anisotropic factor from simulated ADMs;

100 m and n : observation numbers at angular bins for CERES and simulated ADMs.

101

102 **2.1 Selection of Atmospheric profiles for simulations**

103

104 We have selected 100 atmospheric profiles covering the globe and the seasons as input for simulations
 105 with MODTRAN4.3. The atmospheric profiles at each pressure level include temperature, water vapor
 106 and ozone. Each season includes 25 profiles. A tool was developed to select profiles from a Training Data
 107 set known as SeeBor Version 5.0 (https://cimss.ssec.wisc.edu/training_data/) (Borbas et.al. 2005).
 108 Originally it consisted of 15704 global profiles of temperature, moisture, and ozone at 101 pressure levels
 109 for clear sky conditions. The profiles are taken from NOAA-88, and the European Centre for Medium-
 110 Range Weather Forecasts (ECMWF) 60L training set, TIGR-3, ozone-sondes from 8 NOAA Climate
 111 Monitoring and Diagnostics Laboratory (CMDL) sites, and radiosondes from the Sahara Desert during
 112 2004. A technique to extend the temperature, moisture, and ozone profiles above the level of existing data
 113 was also implemented by the providers (University of Wisconsin-Madison, Space Science and
 114 Engineering Center, Cooperative Institute for Meteorological Satellite Studies (CIMSS). **Fig. 3** shows the
 115 location of the selected profiles.

116 The SeeBor profiles are clear sky profiles. The top of the profiles is at 0.005 mb which is about 82.6 km.
 117 We did an experiment to check the impact of reducing the number of levels for a profile (initially, we
 118 have used only 40 levels). In the experiment computed were radiances from profiles with 50 levels as

119 well as radiances from profiles with 98 Levels. The difference between the two radiances (50 lev-98 lev)
120 were below 5 % reaching 15 % around $2.5 \mu\text{m}$. In the experiment we used the odd number levels starting
121 from surface (plus the highest level) to reduce the number of profile levels. Based on these experiments
122 we have opted to keep all 98 profile levels.

123 The surface variables we have used are from MODIS and include surface skin temperature, 2 m
124 temperature, land/sea mask, and albedo. We have conducted a thorough investigation how the selected
125 profiles represent the entire sample of 15704 profiles. An example showing the comparison of
126 temperature, humidity and ozone profiles is shown in **Fig. 4**. As seen, there is a positive bias in the selected
127 profile of temperature due to their higher concentration at the lower latitudes. A positive bias can be found
128 at the lower levels while a negative bias is seen above 1 mb. Since our domain of study is in such latitudes
129 this selection should not have adverse effects on the simulations performed.

130

131 **2.2 Surface conditions**

132

133 Surface condition is one of the primary inputs into the MODTRAN simulations. The International
134 Geosphere-Biosphere Programme (IGBP) land classification is used as a source (Hansen et al., 2010;
135 Loveland et al., 2010). The dataset is at 1/6-degree resolution and includes 18 surface types. We have
136 converted the $1/6^\circ$ ($\sim 18.5 \text{ km}$) resolution to the ABI 2-km grid using the nearest grid method (**Fig. 5**). The
137 surface type is fixed in time. The method for cloudy sky uses 4 surface types; these are also derived from
138 12 IGBP types (**Table 2**).

139

140 **2.3 Clear and cloudy sky simulations**

141

142 Under clear sky, scattering from aerosols is important. We have included 6 aerosol types (**Table 3**) to
143 cover a range of possible conditions under clear sky. Aerosol models are selected based on the type of
144 extinction and a default meteorological range for the boundary-layer aerosol models as listed below:
145 Aerosol Type 1: Rural extinction, visibility = 23 km

146 Aerosol Type 4: Maritime extinction, visibility = 23 km
147 Aerosol Type 5: Urban extinction, visibility = 5 km
148 Aerosol Type 6: Tropospheric extinction, visibility = 50 km
149 Aerosol Type 8: Advective Fog extinction, visibility = 0.2 km
150 Aerosol Type 10: Desert extinction for default wind conditions
151 For the 6 aerosol types, the total number of MODTRAN simulations for each surface type is 462,000. It
152 is obtained as follows: 6 aerosol types x 100 profiles x 770 angles.
153 When performing NTB simulations, we use all 6 types of aerosols. The Rural, Ocean, Urban and Fog
154 aerosols are distributed in the lower 0-2 km region. Tropospheric aerosol is distributed from 0 to 10 km
155 tropopause. The Rural, Ocean, Urban and Tropospheric aerosol optical properties have Relative Humidity
156 (RH) dependency. The Single Scattering Albedo (SSA) is given on 4 RH grids (0, 70, 80, 99) on a spectral
157 grid of 788 points ranging from 0.2 to 300 microns.
158 Simulations were performed for ABI for all the cloud cases described in **Table 3**. To merge cloud layers
159 with atmospheric profiles we have followed the procedure as described in *Berk et al.* (1985, 1998),
160 namely: “Cloud profiles are merged with the other atmospheric profiles (pressure, temperature, molecular
161 constituent, and aerosol) by combining and/or adding new layer boundaries. Any cloud layer boundary
162 within half a meter of an atmospheric boundary layer is translated to make the layer altitudes coincide;
163 new atmospheric layer boundaries are defined to accommodate the additional cloud layer boundaries.”
164 100% relative humidity is assumed within the cloud layers (default).
165

166 **2.4 Selection of angles**

167
168 The total number of angles used in the simulations is given in **Table 4**. The selected spectral grids for
169 solar zenith angles, satellite view angles and relative azimuth angles are at Gaussian quadrature points,
170 plus 0° to solar zenith angles (sza) and satellite viewing angles (vza) and 0° and 180° (forward and
171 backward view) to the satellite relative azimuth angles. Solar angle and satellite view angle are referenced

172 to target or surface for satellite simulation with 0° meaning looking up (zenith). Relative azimuth angle is
173 defined as when the relative azimuth angle equals 180° , the sun is in front of observer.
174 The definitions of solar zenith angle and azimuth angle in this table corresponds to the definitions of
175 MODTRAN but that is not the case for the satellite zenith angle. MODTRAN uses nadir angle as 180° -
176 satellite zenith angle, ignoring spherical geometry.

177

178 **2.5 Selection of optimal computational scheme**

179

180 MODTRAN4.3 provides three multiple scattering models (Isaacs, DISORT, and Scaled Isaacs) and three
181 band models at resolutions (1 cm^{-1} , 5 cm^{-1} , and 15 cm^{-1}). The DISORT model (Stamnes et al., 1988)
182 provides the most accurate radiance simulations but the runs are very time consuming. The Isaacs (Isaacs
183 et al. 1987) 2-stream algorithm is fast but oversimplified. The Scaled Isaacs method performs radiance
184 calculations using Isaacs 2-stream model over full spectral range and using DISORT model at a small
185 number of atmospheric window wavelengths. The multiple scattering contributions for each method are
186 identified and ratios of the DISORT and Isaacs methods are computed. This ratio is interpolated over the
187 full wavelength range, and finally, applied as a multiple scattering scale factor in a spectral radiance
188 calculation performed with the Isaacs method.

189 To optimize simulation speed and accuracy, we performed various sensitivity tests, including
190 combinations of multiple scattering models, band resolution, and number of streams. **Table 5** lists
191 simulation options and their corresponding calculation speed.

192 Based on results presented in **Table 5**, the efficient options (< 40 seconds) are Isaacs, DISORT 2-stream
193 with 15 cm^{-1} , DISORT 4-stream 15 cm^{-1} , and Scaled Isaacs all streams at all resolutions. Although the
194 ideal option is DISORT 8-stream with 1 cm^{-1} resolution, there is a trade-off between speed and accuracy.

195 **Fig. 6** compares DISORT simulated radiances at three band resolutions. We use two spectral ranges of
196 $0.4 - 0.5\text{ }\mu\text{m}$ and $1.5 - 2.0\text{ }\mu\text{m}$ to illustrate differences. **Fig. 6** shows that the coarser band resolution has
197 smoothed out the radiance variations. The 15 cm^{-1} has the smoothest curve among the three, and 1 cm^{-1}
198 shows more variations than the other two. Another (scientific) criteria for selecting the spectral resolution

199 is the ability to resolve/match the relative spectral response function (SRF) of a sensor. For example, the
200 SRFs of channels 1-6 of ABI are given at every 1 cm^{-1} .
201 Accordingly, we have chosen the 1 cm^{-1} band model for the MODTRAN radiance simulations. Performed
202 were also radiance simulations from different multiple scattering models at 1 cm^{-1} resolution. The whole
203 spectrum of $0.2 - 4\text{ }\mu\text{m}$ was separated to 14 sections so that the differences can be assessed clearly. For
204 wavelength below $0.3\text{ }\mu\text{m}$ and beyond 2.5 no discernible differences were found among Isaacs, DISORT
205 2-, 4-, and 8-stream, and Scaled Isaac. The largest differences occurred in the spectral range of $0.4 - 1.0$
206 μm . Scaled Isaac 8-stream follows DISORT 8-stream closely across the whole spectral range; the Scaled
207 Isaac method provided near-DISORT accuracy with the speed of Isaacs. Thus, the MODTRAN4.3
208 simulations for GOES-R ABI were set-up with Scaled Isaac 8-stream with 1 cm^{-1} band resolution.
209 For illustration, in **Fig. 7** compared are radiances simulated by Isaac 2 stream, Scaled Isaac, and DISORT-
210 4 stream for the case of Relative Azimuthal Angle= 1.9° , View Angle= 76.3° , Solar Zenith Angle= 87.2° .
211 The lines are differences between various settings and DISORT-8 stream (e.g. Isaacs minus DISORT-8).
212 Isaac has the least accuracy since it is oversimplified, 4-stream showed some improvements when
213 compared with Isaac while still has large differences for $0.4\text{ }\mu\text{m}$ and is still computationally demanding.
214 Scaled Isaac provides the smallest differences between DISORT-8. **Fig. 7** (lower) zoomed in to the large
215 difference area of $0.3-0.35\text{ }\mu\text{m}$ which indicates that Scaled Isaacs still provides satisfactory results.
216

217 **2.6 Regression methodologies**

218
219 We have derived coefficients of regression using a constrained least-square curve fitting methods of
220 Matlab, “lsqnonneg”, which can solve a linear or nonlinear least-squares (data-fitting) problem and
221 produce non-negative coefficients. Non-negative coefficients avoid generating negative TOA flux, which
222 is not a physically valid.

223 To ensure that information from all channels is used and avoid the complex cross-correlation problem, it
224 was opted to generate Narrow to Broad (NTB) coefficients for each ABI channel separately. These
225 channel specific NTB coefficients are applied to each channel to convert ABI narrow-band reflectance to

226 extended band. The final broad-band TOA reflectance is taken as the weighted sum of all 6-channel
227 specific broad-band reflectance. The logic behind this approach is the assumption that the narrow-band
228 reflectance from each channel is a good representative for a limited spectral region centered around the
229 channel and the total spectral reflectance is dominated by the spectral region that contains the most solar
230 energy.

231 To generate “separate-channel” NTB coefficients, each narrow-band ABI channel reflectance is
232 converted to a reflectance $\rho_{bb,i}$ separately,

233
$$\rho_{bb,i}(\theta_0, \theta, \phi) = c_{0,i}(\theta_0, \theta, \phi) + c_{1,i}(\theta_0, \theta, \phi) * \rho_{nb,i}(\theta_0, \theta, \phi) \quad (4)$$

234 where $\rho_{bb,i}$ is the band reflectance for an interval around each channel i ; $c_{0,i}$ and $c_{1,i}$ are regression
235 coefficients for channel i . These regression coefficients are derived separately for various combination of
236 surface, cloud and aerosol types. The total shortwave broad band (0.25 – 4.0 μm) reflectance ρ_{bb}^{est} is
237 obtained by taking the weighted sum of all 6 $\rho_{bb,i}$ reflectance

238
$$\rho_{bb}^{est}(\theta_0, \theta, \phi) = \sum_i \rho_{bb,i}(\theta_0, \theta, \phi) \frac{S_{0,i}}{S_0} \quad (5)$$

239 Here, S_0 and $S_{0,i}$ are total solar irradiance and band solar irradiance for each channel, respectively. Band
240 edges around the six ABI channels are: 49980-18723, 18723-13185, 13185-9221, 9221-6812, 6812-5292,
241 2500 cm^{-1} 0.2001-0.5341, 0.5341-0.7584, 0.7584-1.0845, 1.0845-1.4680, 1.4680-1.8896, 1.8896-4.0000
242 μm). The corresponding solar irradiance band values are 364, 360, 287, 168, 91, 87
243 W m^{-2} . **Fig. 8** shows the sensor response function (SRF) and locations of the six ABI channels.

244 Coefficients are generated for clear condition and 3 types of cloudy conditions. Comparison between ABI
245 TOA flux and CERES products are shown in **Fig. 9**. The “separate-channel” coefficients work well for
246 predominantly clear sky (**Fig.10**). Differences are somewhat more scattered for cloudy cases. The reason
247 may be due to the fact that the ABI observation time and CERES product time do not match perfectly
248 since cloud condition change quickly. As discussed in Gristey et al. (2019) there are SW spectral
249 reflectance variations for different cloud types. Possibly, for ABI bands some spectral variations
250 associated with cloud variability are missed. It is important to have the correct cloud properties to be able
251 to select correct ADM. Misclassification of cloud properties will therefore result in flux differences. They

252 also argue that ADMs have an uncertainty due to within-scene variability and within-angular bin
253 variability leading to additional flux differences.

255 **3. Data used**

257 **3.1 Satellite data for GOES-16 and GOES17**

259 The GOES Imager data used (**Table 6**) were downloaded from <https://www.bou.class.noaa.gov/> and the
260 SRF from <https://ncc.nesdis.noaa.gov/GOESR/ABI.php>

261 The CODC data were not always available from CLASS and had to be obtained from NOAA/STAR
262 temporary archives. Also, not all the required angular information needed for implementation of
263 regressions was available online and had to be recomputed.

265 **3.2 Reference data from CERES**

266
267 The CERES Single Scanner Footprint (SSF) is a unique product for studying the role of clouds, aerosols,
268 and radiation in climate. Each CERES footprint (nadir resolution 20-km equivalent diameter) on the SSF
269 includes reflected shortwave (SW), emitted longwave (LW) and window (WN) radiances and top-of-
270 atmosphere (TOA) fluxes from CERES with temporally and spatially coincident imager-based radiances,
271 cloud properties, and aerosols, and meteorological information from a fixed 4-dimensional analysis
272 provided by the Global Modeling and Assimilation Office (GMAO). Each file in this data product
273 contains one hour of full and partial-Earth view measurements or footprints at a surface reference level.
274 Detailed information can be found via <https://ceres.larc.nasa.gov/data/#ssf-level-2>.

275 Near real-time CERES fluxes and clouds in the SSF format are available within about a week of
276 observation (Kratz et al., 2014). They do not use the most recent CERES instrument calibration and thus

277 contains some uncertainty. Before GOES data were transferred to the Comprehensive Large Array-data
278 Stewardship System (CLASS) system, the NOAA/STAR archive was holding new data for about a week.
279 Therefore, the initial evaluations had to be done only with data that overlapped in time. The CERES data
280 known as the FLASHFlux Level2 (FLASH_SSF) are available almost in real time from:
281 <https://ceres.larc.nasa.gov/products.php?product=FLASHFlux-Level2>
282 Due to such constraints the early comparison was done between ABI data as archived at NOAA/STAR
283 and the FLASHFlux products (in this paper, the FLASHFlux data were used only in Fig. 9). The archiving
284 of GOES-R at the NOAA Comprehensive Large Array-data Stewardship System (CLASS) started only
285 in 2019, however, it contains data starting from 2017. Once the CLASS archive became available, we
286 have augmented GOES-16 cases with observations from GOES-17; only those cases will be shown in this
287 paper.
288

289 **3.3 Data preparation**

290
291 For the re-mapping, we adopted the ESMF re-gridding package. The detailed information can be found
292 at: <http://earthsystemmodeling.org/regrid/>
293 For an ideal situation, the ABI high-resolution TOA SW fluxes should be mapped into the CERES
294 footprint for validation. However, there are reasons that make it difficult to do so. There can be more than
295 18000 pixels in a single swath of the SSF, when constrained to U.S. Different pixels have different times.
296 Neglecting the seconds, there are still more than 30 mins differences (this changes case by case) between

297 the first pixel and the one at the end and this brings up a time matching issue. By remapping the SSF to
298 ABI, we can set up a unique time for ABI (ABI is at 5 min intervals) and then constrain the region and
299 the time range of SSF.

300 Both re-mapping the ABI to SSF and remapping SSF to the ABI bring up spatial matching errors as
301 recognized by the scientific community (Rilee and Kuo, 2018; Ragulapati et al., 2021). In **Fig. 11**, we
302 show the SSF before re-gridding (**Figs 11 (a) & (b)**) and after re-gridding (**Figs. 11 (c) and (d)**). The
303 fluxes after re-mapping CERES SSF to the ABI resolution resemble well the original structure. Another
304 consideration is the computational efficiency of re-mapping the curvilinear tripolar grid to unconstructed
305 grid. For large arrays, it is more efficient to remap the unconstructed grid to the curvilinear tripolar grid.

306

307 **4. Results**

308

309 **4.1 Comparison between ABI TOA fluxes to those from CERES SSF**

310 A case for 2019/12/26 (doy 360) UTC 19:36 is illustrated in **Figs. 11-14**. Statistical summaries from an
311 extended number of cases that cover all four seasons are presented in **Table 7**.

312 We have conducted several experiments to select an appropriate regression approach to the NTB
313 transformation ensuring that non-physical results are not encountered. Based on the samples used in this
314 study (**Table 7**) the differences found for Terra and GOES-16 were in the range of -0.5-(-17.37) for bias
315 and 43.28-81.72 for standard deviation; for Terra and GOES-17 they were 11.26-47.09 and 70.25-108.73,
316 respectively. For Aqua and GOES-16 they were 7.63-33.87 and 58.68-117.43 respectively while for Aqua
317 and GOES-17 they were 0.19-31.53 and 47.55-129.42, respectively (all units are W m^{-2}). The evaluation
318 process revealed the challenges in undertaking such comparisons. Both estimates of TOA fluxes (CERES
319 and GOES) do no account for seasonality in the land use classification; the time matching for the different

320 satellites is important and limits the number of samples that can be used in the comparison. Based on the
321 results of this study recommendation for future work include the need to incorporate seasonality in land
322 use and spectral characteristic of the various surface types. Possible stratification by season in the
323 regressions could also be explored.

324

325 **4.2 Causes for differences between ABI and CERES TOA fluxes**

326

327 **4.2.1 Differences in surface spectral reflectance**

328

329 In the MODTRAN simulations we use the spectral reflectance information on various surface types as
330 provided by MODTRAN. MODTRAN version 4.3.1 contains a collection of spectral surface reflectance
331 dataset from the Moderate Spectral Atmospheric Radiance and Transmittance (MOSART) model
332 (Cornette et al., 1994) and others from Johns Hopkins University Spectral Library (Baldridge et al., 2009).
333 When doing simulation, we call the built-in surface types and use the provided surface reflectance. As
334 such, the spectral dependence of the surface reflectance used in the simulations and matched to the
335 CERES surface types may not be compatible with the classification of CERES. Also, seasonal changes
336 in surface type classification can introduce errors due to changes in the spectral surface reflectance for
337 different surface types (**Fig. 15**).

338

339 **4.2.2 Issues related to surface classification**

340

341 Another possible cause for differences between the TOA fluxes is the classification of surface types as
342 originally identified by the IGBP and used in the simulations. No seasonality is incorporated in the surface
343 type classification while such variability is part of the CERES observations.

344

345

346

347 **4.2.3 Issues related to match-up between GOES-R and CERES**

348

349 Both Terra and Aqua have sun-synchronous, near-polar circular orbits. Terra is timed to cross the equator
350 from north to south (descending node) at approximately 10:30 am local time. Aqua is timed to cross the
351 equator from south to north (ascending node) at approximately 1:30 pm local time. The periods for Terra
352 and Aqua are 99 and 98 minutes, respectively. Both have 16 orbits per day. CERES on Terra and Aqua
353 optical FOV at nadir is 16 x 32 or 20 km resolution. Terra passes CONUS during 03-06 UTC (US night
354 time), 16-20 UTC (US day time), and Aqua passes CONUS during 07-11 UTC (US night time), 18-22
355 UTC (US day time).

356 Both Terra and Aqua have an instantaneous FOV values at SWATH level. There is no perfect overlap,
357 temporally or spatially with ABI data. The ABI radiance and cloud data are on a regular grid of 2*2 km
358 over CONUS at each hour. To use CERES data for evaluation of ABI, there is a need to perform
359 collocation in both time and space.

360

361 **5. Summary**

362

363 The derivation and evaluation of TOA radiative fluxes as simulated for any given instrument are quite
364 challenging. In principle, there is a need to account for all possible changes in the atmospheric and surface
365 conditions one may encounter in the future. Yet, to know what these conditions are at the time of actual
366 observation when there is a need to select the appropriate combination of variables from the simulations,
367 is a formidable task. Differences in assumed cloud properties can also lead to differences in the fluxes
368 derived from the two instruments. Therefore, error can be expected due to discrepancies between the
369 actual conditions and the selected simulations and these are difficult to estimate. The approach we have
370 selected is based on high-quality simulations using a proven and accepted radiative transfer code
371 (MODTRAN) of known configurations and a wide range of atmospheric conditions. We have also
372 selected the best available estimates of TOA radiative fluxes from independent sources for evaluation.
373 However, the matching between different satellites in space and time is challenging. In selecting the cases

374 for evaluation, we have adhered to strict criteria of time and space coincidence as described in section
375 3.3.

376 Critical elements of an inference scheme for TOA radiative flux estimates from satellite observations are:
377 1) transformation of narrowband quantities into broadband ones;
378 2) transformation of bi-directional reflectance into albedo by applying Angular Distribution Models
379 (ADMs). In principle, the order in which these transformations are executed is arbitrary. However, since
380 well established, observation-based broadband ADMs derived from the Clouds and the Earth's Radiant
381 Energy System (CERES) project already exist, the logical procedure is to do the NTB transformation on
382 the radiances first, and then apply the ADM. This is the sequence that has been followed here. While the
383 road map to accomplish above objectives seems well defined, reaching the final goal of having a stable
384 up-to-date procedure for deriving TOA radiative fluxes from a new instrument like the ABI on the new
385 generation of GOES satellites is quite complicated. Since the final configuration of the instrument
386 becomes known at a much later stages the evaluation of new algorithms is in a fluid stage for a long time
387 so early evaluation against "ground truth" needs to be repeated frequently. Additional complication is
388 related to the lack of maturity of basic information needed in the implementation process, such as a
389 reliable cloud screened product which in itself is in a process of development and modifications. The
390 "ground truth", namely, the CERES observations are also undergoing adjustments and recalibration. As
391 such, the process of deriving best possible estimates of TOA radiative fluxes from ABI underwent
392 numerous iterations to reach its current status. An effort was made to deal the best way possible with the
393 fluid situation. All the evaluations against CERES were repeated once the ABI data reached stability and
394 were archived in CLASS and we used the most recent auxiliary information. This study sets the stage for
395 future possible improvements. One example is land classification which currently is static. Another issue
396 is related to the representation of real time aerosol optical properties which are important under clear sky
397 conditions. It is believed that only now when NOAA/STAR has a stable aerosol retrieval algorithm, it
398 would be timely to address the aerosol issue in the estimation of TOA fluxes under clear sky.

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401 Data availability. The data are available upon request from the corresponding author.

402 Author contributions. The investigation and conceptualization were carried out by RTP, IL and JD. YM
403 and WC developed the software. RTP prepared the original draft. All authors contributed to the writing,
404 editing and review of the publication.

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Tables

Table 1. Channel information and spectral bands for ABI.

<i>ABI Band #</i>	<i>Central wavelength (μm)</i>	<i>Spectral band (μm)</i>
1	VIS 0.47	0.45-0.49
2	VIS 0.64	0.60-0.68
3	NIR 0.86	0.847-0.882
4	NIR 1.38	1.366-1.380
5	NIR 1.61	1.59-1.63
6	NIR 2.26	2.22-2.27

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542 Table 2. Surface classification description for IGBP 18 types, IGBP 12 types, CERES clear sky 6 types,
 543 and NTB cloudy sky 4 types

IGBP (18 types)	IGBP (12 types)	CERES clear-sky (6 types)	NTB cloudy-sky (4 types)
Evergreen Needleleaf	Needleleaf Forest		
Deciduous Needleleaf			
Evergreen Broadleaf	Broadleaf Forest	Mod-High Tree/Shrub	
Deciduous Broadleaf			
Mixed Forest	Mixed Forest		
Closed Shrublands	Closed Shrub		Land
Woody Savannas	Woody Savannas		
Savannas	Savannas		
Grasslands			
Permanent Wetlands	Grasslands	Low-Mod Tree/Shrub	
Tundra			
Croplands	Croplands		
Open Shrublands	Open Shrub		
Urban and Built-up	Open Shrub	Dark Desert	Desert
Bare Soil and Rocks	Barren and Desert	Bright Desert	
Snow and Ice	Snow and Ice	Snow and Ice	Snow and Ice
Water Bodies	Ocean	Ocean	Water

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548 Table 3. The various classes for which NTB coefficients are generated.

Parameter	Clear condition	Cloudy condition
Aerosol or cloud type	6 aerosol types (rural, maritime, urban, tropospheric, fog, desert)	3 cloud types (cirrus, stratocumulus, altostratus)
Optical depth (OD)	Typical VIS (km) values for each aerosol types (no OD grid for each aerosol type). Rural: 23, maritime: 23, urban: 5, tropospheric: 50, fog: 0.2, desert: (default VIS for wind speed 10m/s)	Cirrus: [0, 0.8, 1.2, 1.8, 3.2] Stratocumulus: [0, 0.8, 1.2, 1.8, 3.2, 5.8, 8.2, 15.8, 32.2, 51.8, 124.2] Altostratus: [0, 15.0, 30.0, 50.0, 80.0]
Surface type	12 IGBP surface types	4 types (Water, Land, Desert, Snow/Ice)

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553 Table 4. Angles used in simulations. To be consistent with what is presented in the
 554 ABI Shortwave Radiation Budget (SRB) Algorithm Theoretical Basis Documents (ATBD) (Laszlo
 555 et al, 2018) the additional angles used in the simulations are not given in this Table.

Angle Type	Angles
Solar Zenith Angle [°]	0.0, 12.9, 30.8, 41.2, 48.3, 56.5, 63.2, 69.5, 75.5, 81.4, 87.2
Satellite Zenith Angle [°]	0.0, 11.4, 26.1, 40.3, 53.8, 65.9, 76.3
Azimuth Angle [°]	0.0, 1.9, 10.0, 24.2, 44.0, 68.8, 97.6, 129.3, 162.9, 180

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Table 5. MODTRAN simulation speed test (CPU MHz 2099.929).

Algorithm	Stream	Band Resolution (cm ⁻¹)	Speed (~seconds)
Isaacs	2	1	40
DISORT	2	1, 5, 15	280, 70, 30
	4	1, 5, 15	560, 120, 40
	8	1, 5, 15	930, 300, 110
Scaled Isaac	2	1, 5, 15	30, 10, 6.67
	4	1, 5, 15	30, 10, 6.67
	8	1, 5, 15	30, 10, 6.67

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565 Table 6. Details on data used as input for calculations.

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Short Name	Long Name	MODE	ABI-Channel	Scan Sector	Spatial Resolution
RadC	L1b Radiance	M6	C01-C06	CONUS	5000x3000
AODC	L2 Aerosol	M6	--	CONUS	2500x1500
ACMC	L2 Clear Sky Masks	M6	--	CONUS	2500x1500
ACTPC	L2 Cloud Top Phase	M6	--	CONUS	2500x1500
CODC*	L2 Cloud Optical Depth	M6	--	CONUS	2500x1500

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570 Table 7. Statistical summary for all selected cases intercompared at instantaneous time

scale.

Case	CERES	GOES-R	Corr	Bias	Std	RMSE	N
07/31 2019	Terra	G16	0.82	0.81	69.81	69.81	0.22 x10 ⁶
		G17	0.87	29.13	90.10	94.70	1.78 x10 ⁶
UTC 19	Aqua	G16	0.76	33.87	117.43	122.22	1.58 x10 ⁶
		G17	0.78	31.53	129.42	133.21	0.29 x10 ⁶
09/13 2019	Terra	G16	0.87	-17.37	81.72	83.54	0.13x10 ⁶
		G17	0.71	47.09	108.73	118.48	1.73x10 ⁶
UTC 20	Aqua	G16	0.76	18.22	108.50	110.02	1.46x10 ⁶
		G17	0.73	25.14	81.95	85.72	0.53x10 ⁶
09/21 2019	Terra	G16	0.85	6.78	66.66	67.00	0.35x10 ⁶
		G17	0.83	26.41	87.64	91.57	1.75x10 ⁶
UTC 19	Aqua	G16	0.82	29.66	105.09	109.20	1.67x10 ⁶
		G17	0.76	6.03	94.70	94.89	0.15x10 ⁶
09/30 2019	Terra	G16	0.88	4.49	64.79	64.94	0.40x10 ⁶
		G17	0.80	19.35	86.41	88.55	1.74x10 ⁶
UTC 19	Aqua	G16	0.80	19.87	100.45	102.40	1.69x10 ⁶
		G17	0.72	2.71	91.79	91.83	0.12x10 ⁶
	Terra	G16	0.86	5.84	51.44	51.77	0.35x10 ⁶

10/23		G17	0.87	22.47	70.25	73.76	1.75x10 ⁶	
2019	UTC 19	Aqua	G16	0.89	17.10	75.95	77.85	1.67x10 ⁶
			G17	0.78	8.98	72.52	73.07	0.15x10 ⁶
			G16	0.87	-0.50	43.28	43.28	0.35x10 ⁶
11/08	UTC 19	Terra	G17	0.82	17.18	71.27	73.31	1.75x10 ⁶
2019			G16	0.90	10.08	71.27	71.98	1.67x10 ⁶
			G17	0.68	1.53	47.55	47.58	0.15x10 ⁶
11/24	UTC 19	Terra	G16	0.79	7.98	49.10	49.75	0.35x10 ⁶
2019			G17	0.87	14.10	78.35	79.61	1.76x10 ⁶
			G16	0.82	7.63	58.68	59.17	1.67x10 ⁶
	UTC 19	Aqua	G17	0.65	0.19	63.14	63.14	0.15x10 ⁶
			G16	0.88	5.24	53.28	53.54	0.35x10 ⁶
			G17	0.76	11.26	73.95	74.80	1.76x10 ⁶
12/26	UTC 19	Aqua	G16	0.83	9.79	58.90	59.56	1.67x10 ⁶
2019			G17	0.73	0.85	52.53	52.54	0.15x10 ⁶

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580 List of Figures

581 Figure 1. Flowchart of the NTB transformations illustrating the main processing sections.

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602 Figure 12. (a) Frequency distribution of all-sky TOA SW differences between ABI on GOES-16 and
603 CERES, (b) ABI on GOES-17 and CERES_SSF using Aqua (Upper) and Terra (Lower). All
604 observations were used (clear and cloudy) on 12/26/2019 at UTC 19:36.

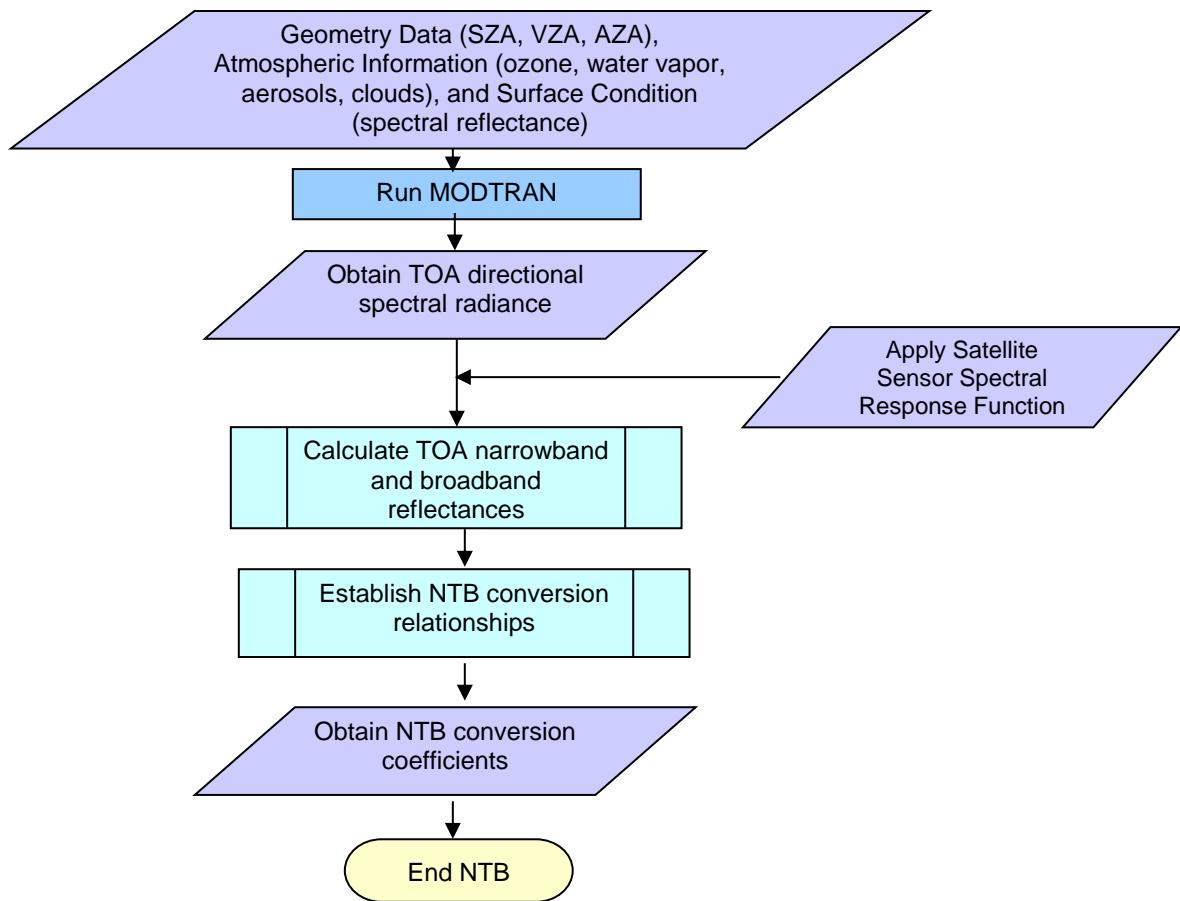
605 Figure 13. Same as Figure 11 but for clear TOA SW differences.

606 Figure 14. Same as Figure 11 but for cloudy TOA SW differences.
607 Figure 15. *Left*: Sensor response function for ABI channel 6; *Right*: Spectral albedo for desert and open
608 shrubs. Desert albedo value is much higher than open shrubs at 2.2 μm .
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643 **Figures**

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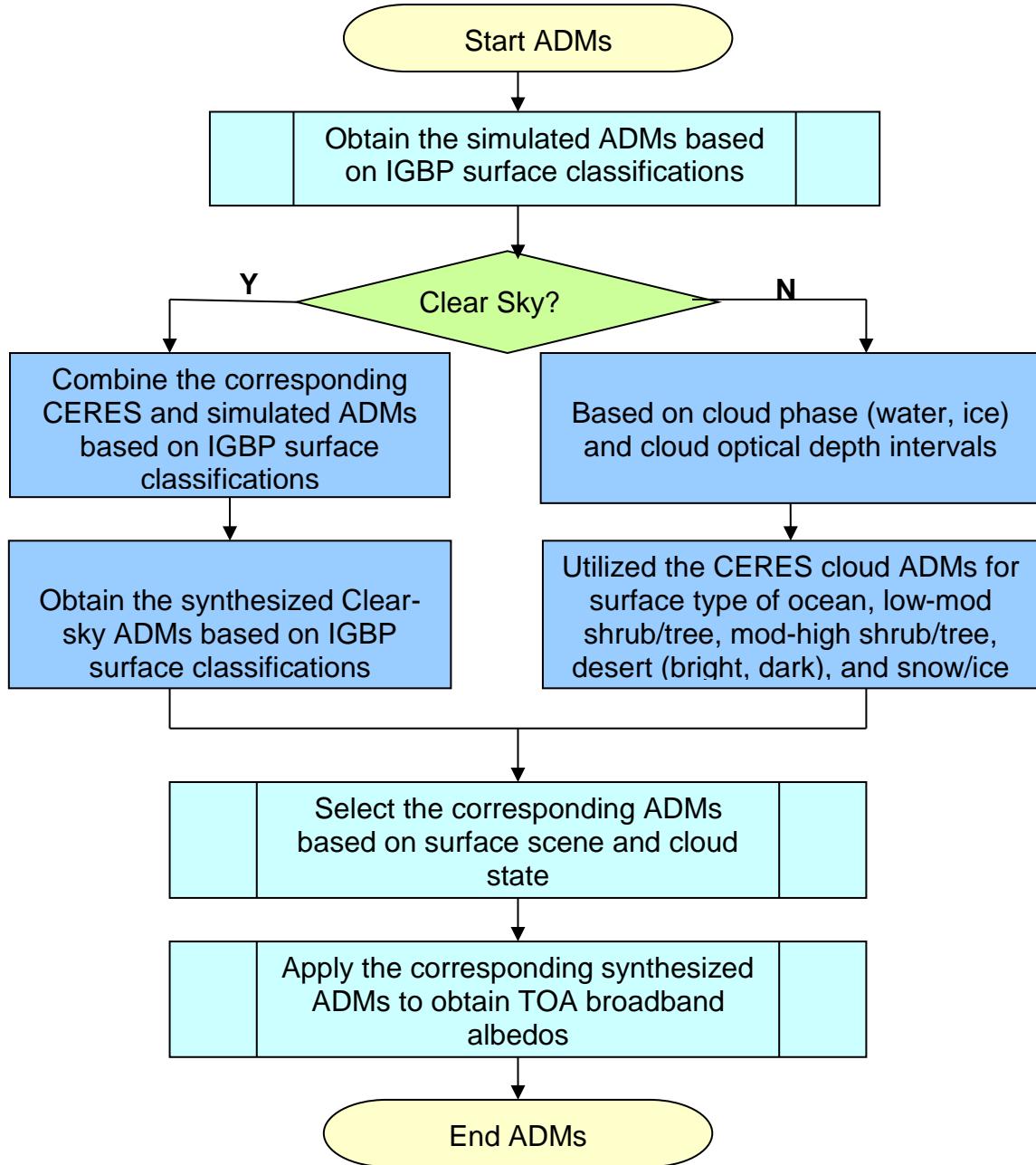
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647 Figure 1. Flowchart of the NTB transformations illustrating the main processing sections.

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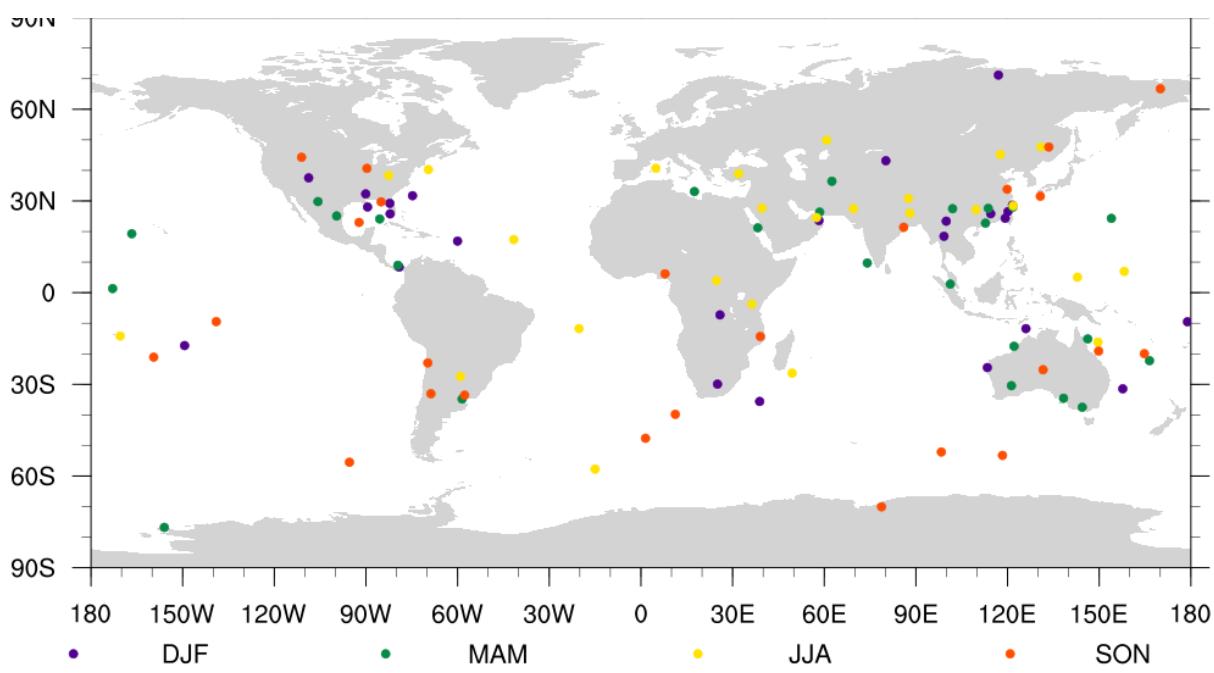
652 Figure 2. Schematic illustration of the logic employed to synthesize modeled and observed ADMs.

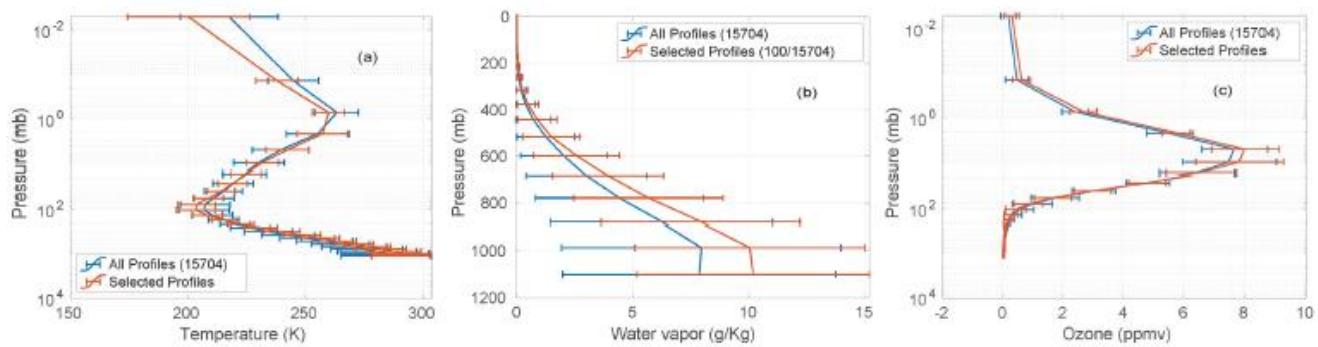
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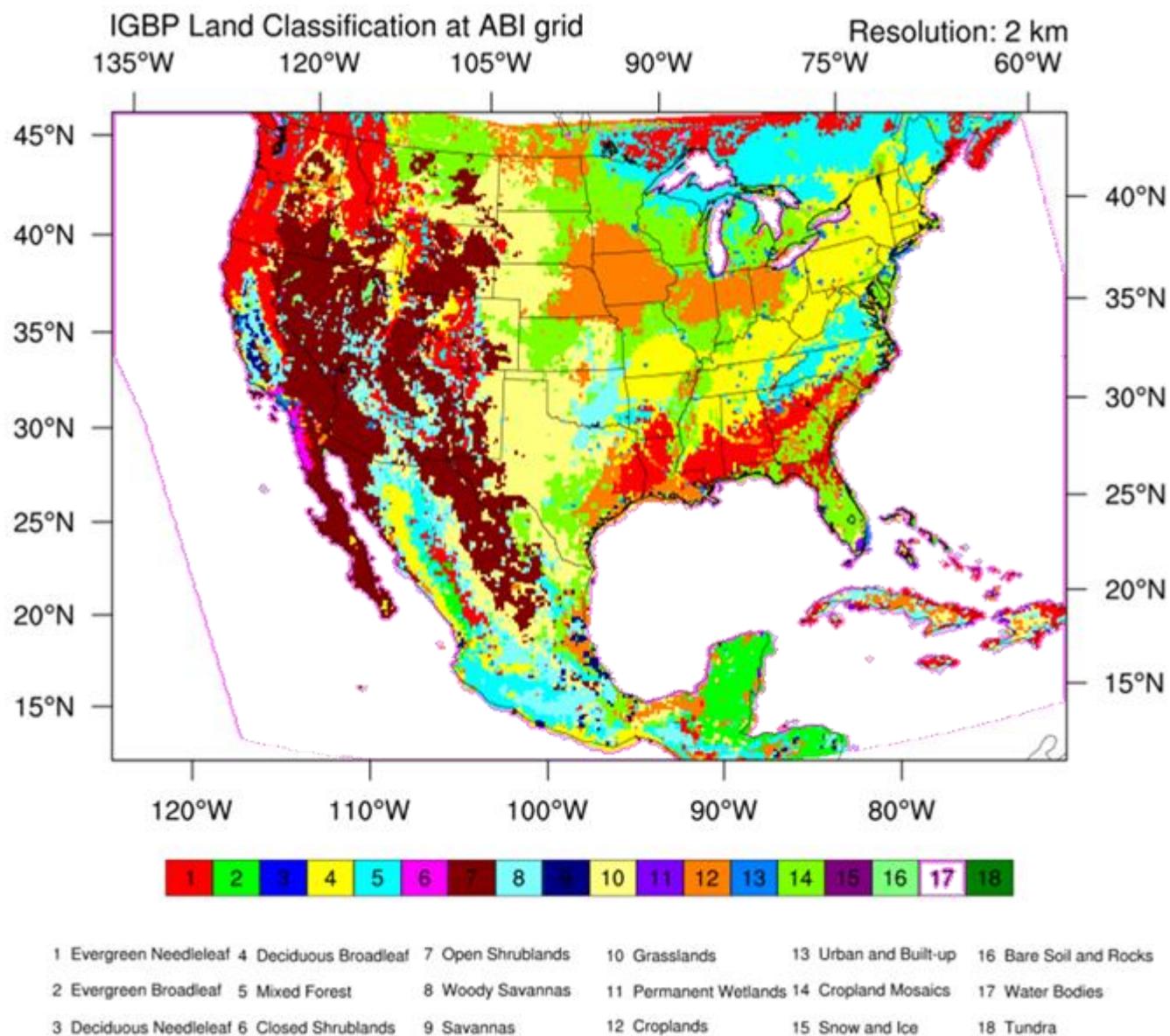
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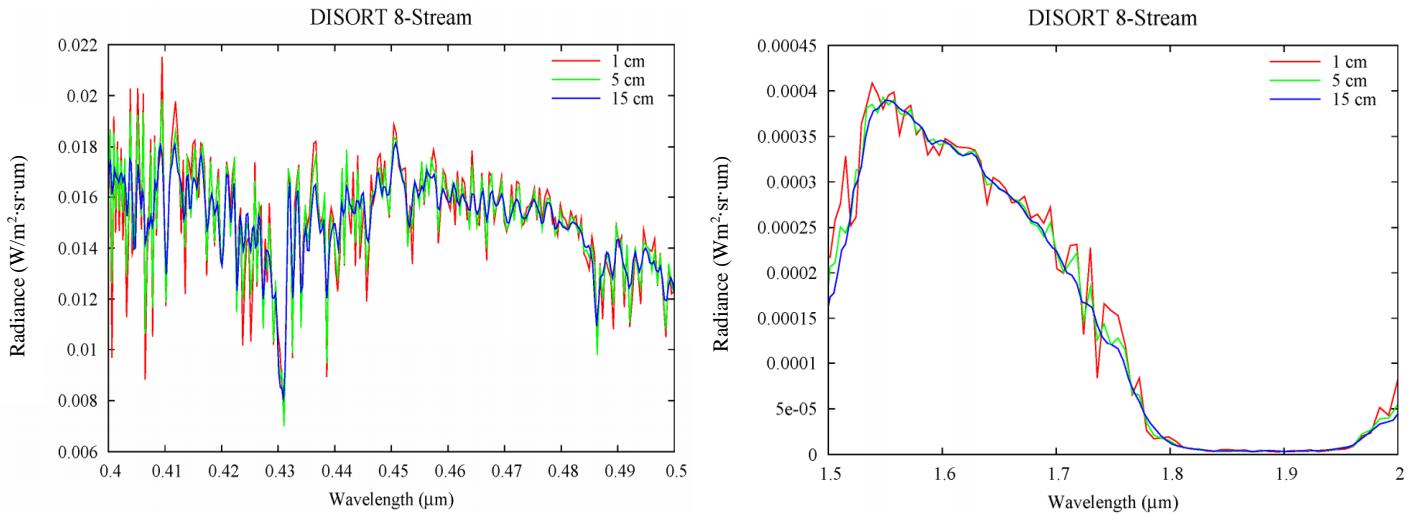
662 Figure 4. Profile statistics of: (a) temperature; (b): water vapor; (c) ozone for the entire available sample
663 and for the reduced sample used in this study. Error bar is 1 standard deviation.



668 Figure 5. Re-mapped IGBP surface classifications over the CONUS at 2-km ABI grid.

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Figure 6. Simulated Radiances from DISORT 8-stream (with 1, 5, and 15 cm^{-1} resolution band model for spectral range of 0.4 – 0.5 μm (left) and 1.5 – 2.0 μm (right).

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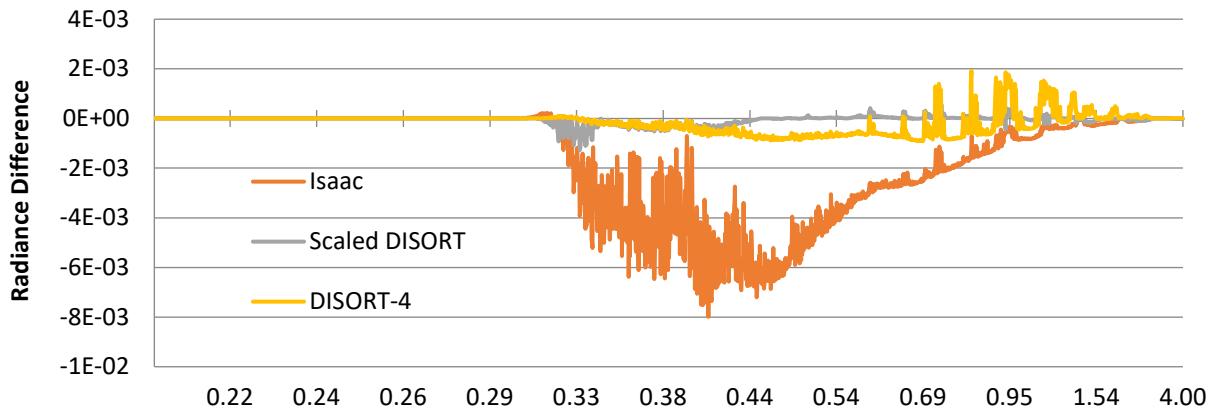
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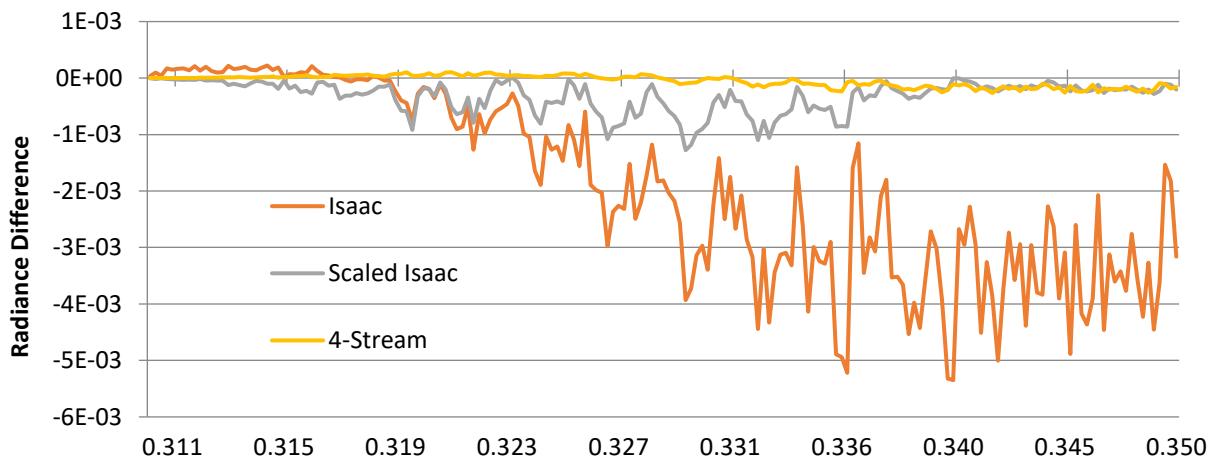
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Radiance difference between multiscattering algorithms and DISORT-8 Stream



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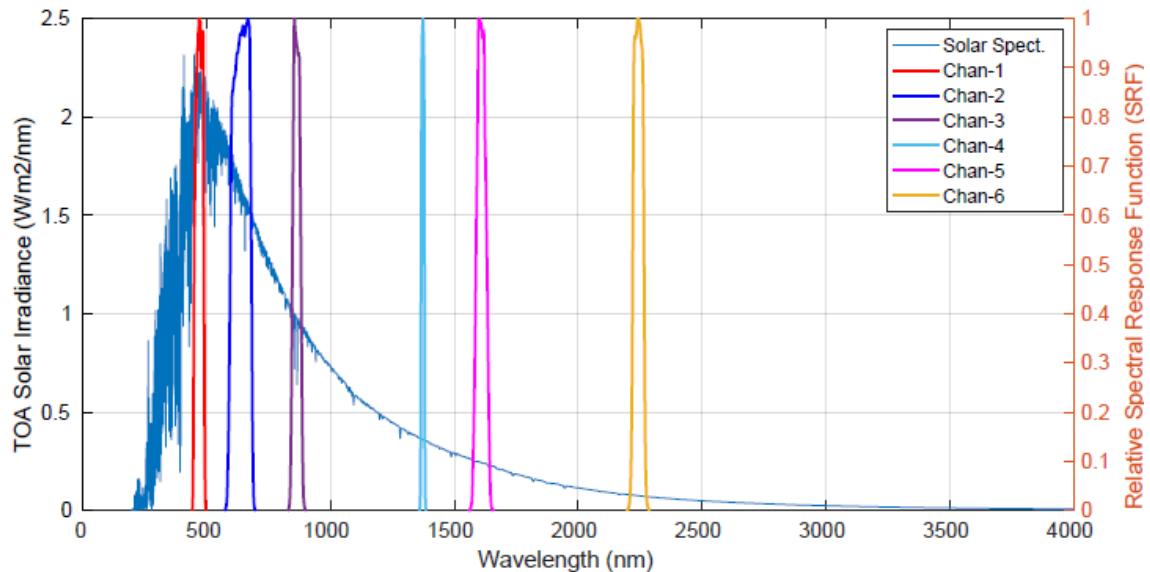


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681 Figure 7. Radiance differences between various multi-scattering algorithms and DISORT-8 stream.

682 *Upper:* the whole simulated spectrum of 0.2-4 μm ; *Lower:* zoom on 0.3-0.35 μm (Relative
683 Azimuthal Angle=1.9°, View Angle=76.3°, Solar Zenith Angle=87.2°).

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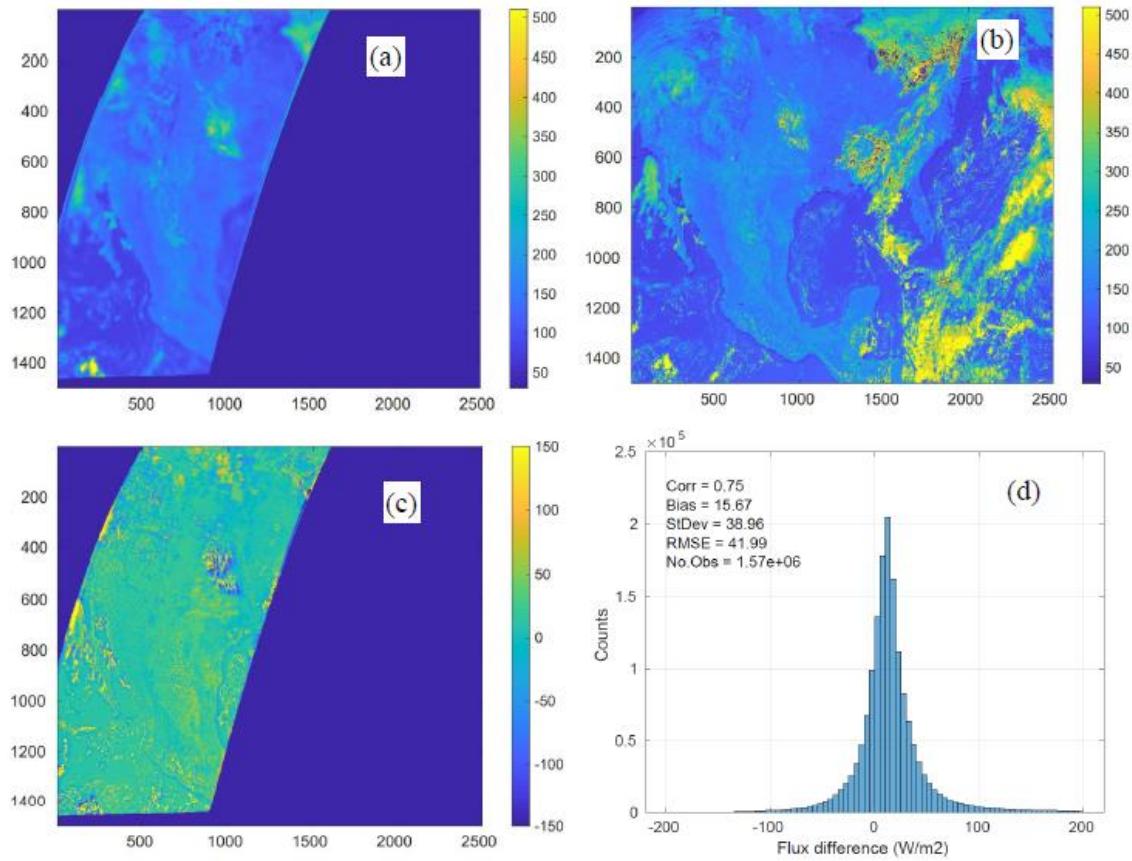
687 Figure 8. Locations of the six ABI channel SRFs. X-axis is wavenumber. Y-axis is solar irradiance.

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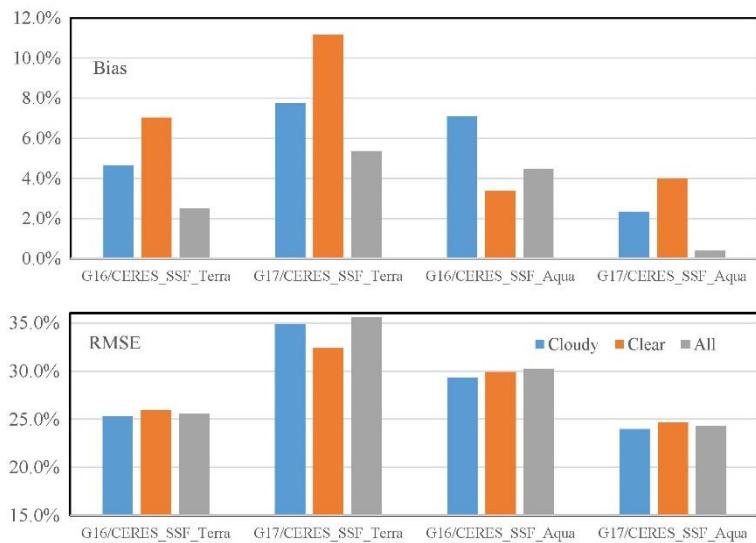


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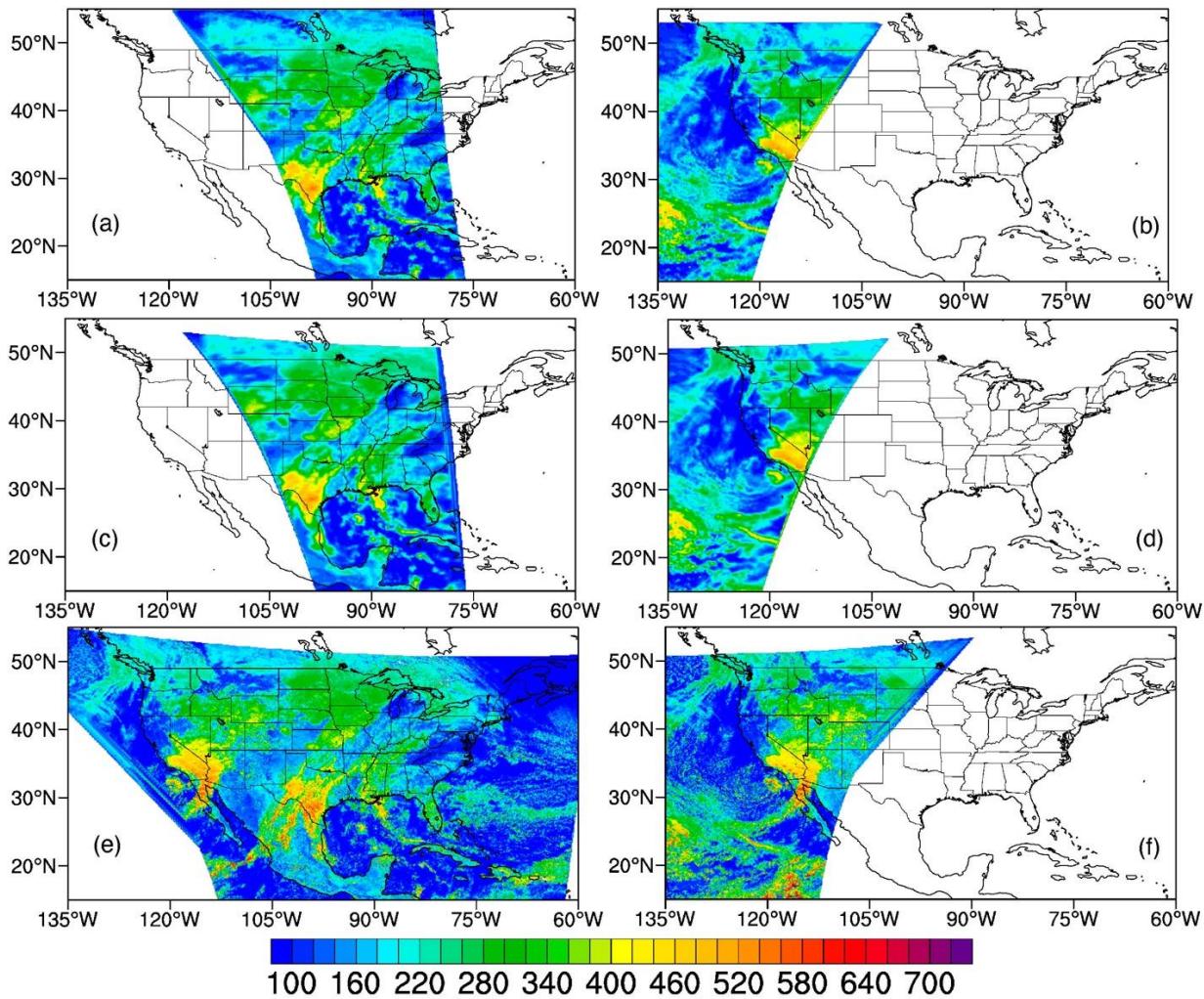
693 Figure 9. Comparison of TOA flux from ABI and CERES FLASHFlux for 2017/11/25, 17:57Z. (a)
 694 CERES Terra product; (b): results with “separate-channel” coefficients. (c): difference (ABI-
 695 CERES); (d): histogram of ABI-CERES differences (this is the only case illustrated in this paper
 696 with data from FLASHFlux).

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702 Figure 10. Statistics for relative Bias and RMSE. The y-axis is percentage. The x-axis is the case used in
 703 the inter-comparison. Blue - cloudy orange - clear sky and t gray - all sky.



713
 714
 715 Figure 11. (a) All sky TOA SW from CERES_SS/Aqua, (b) CERES_SS/Terra, (c) re-gridded
 716 CERES_SS/Aqua, (d) re-gridded CERES_SS/Terra, (e) GOES-16 and (f) GOES-17
 717 on 12/26/2019 at UTC 19:36.

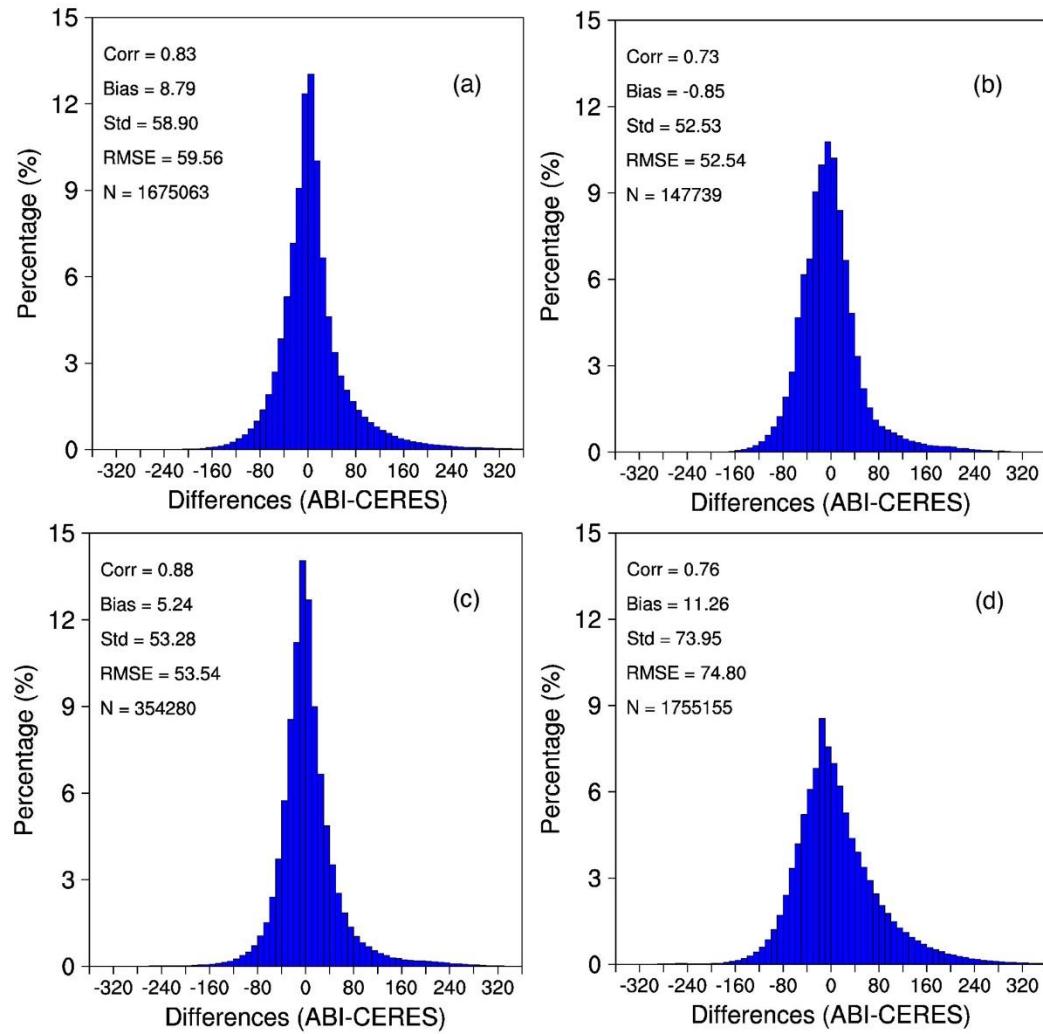
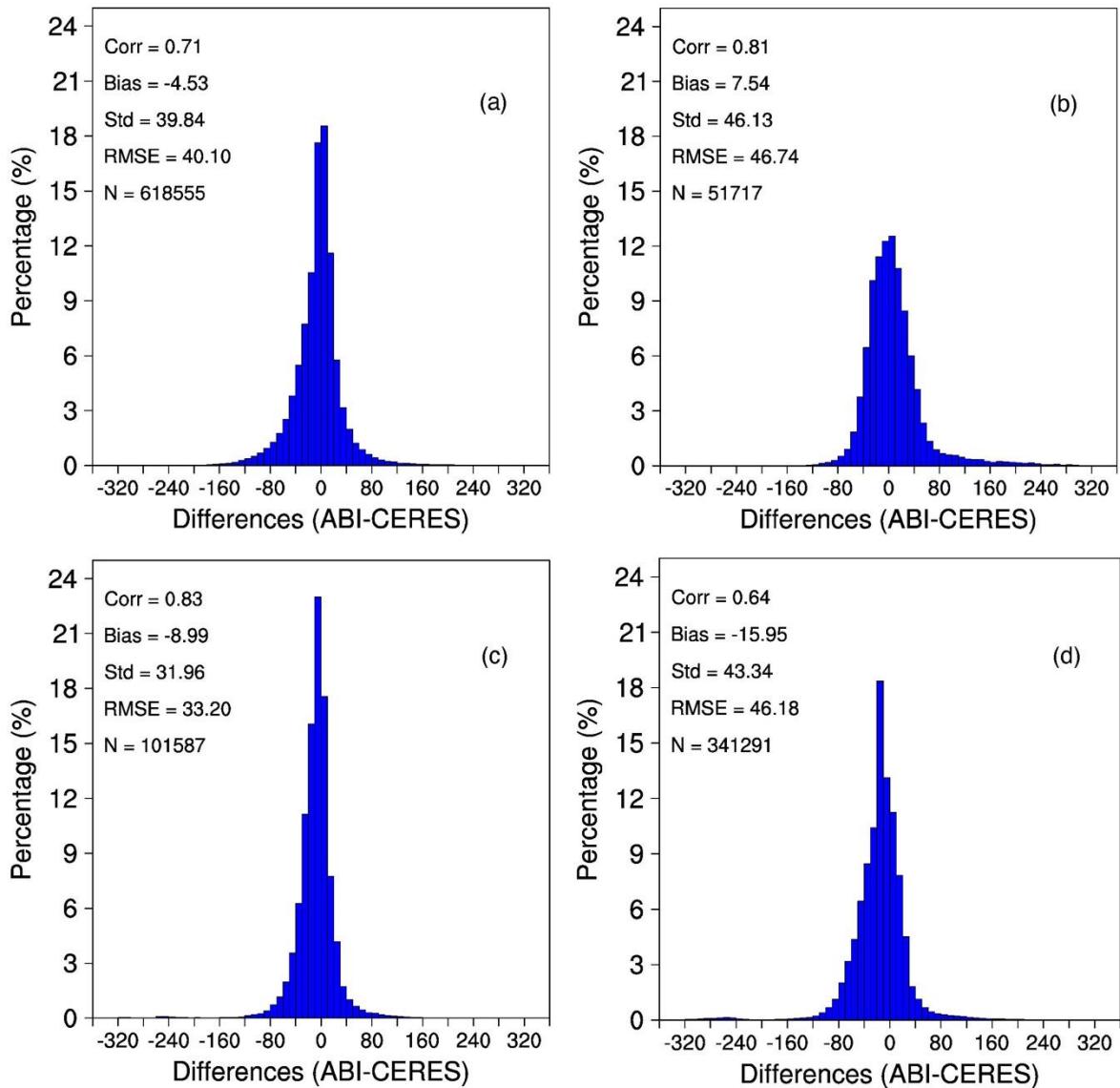
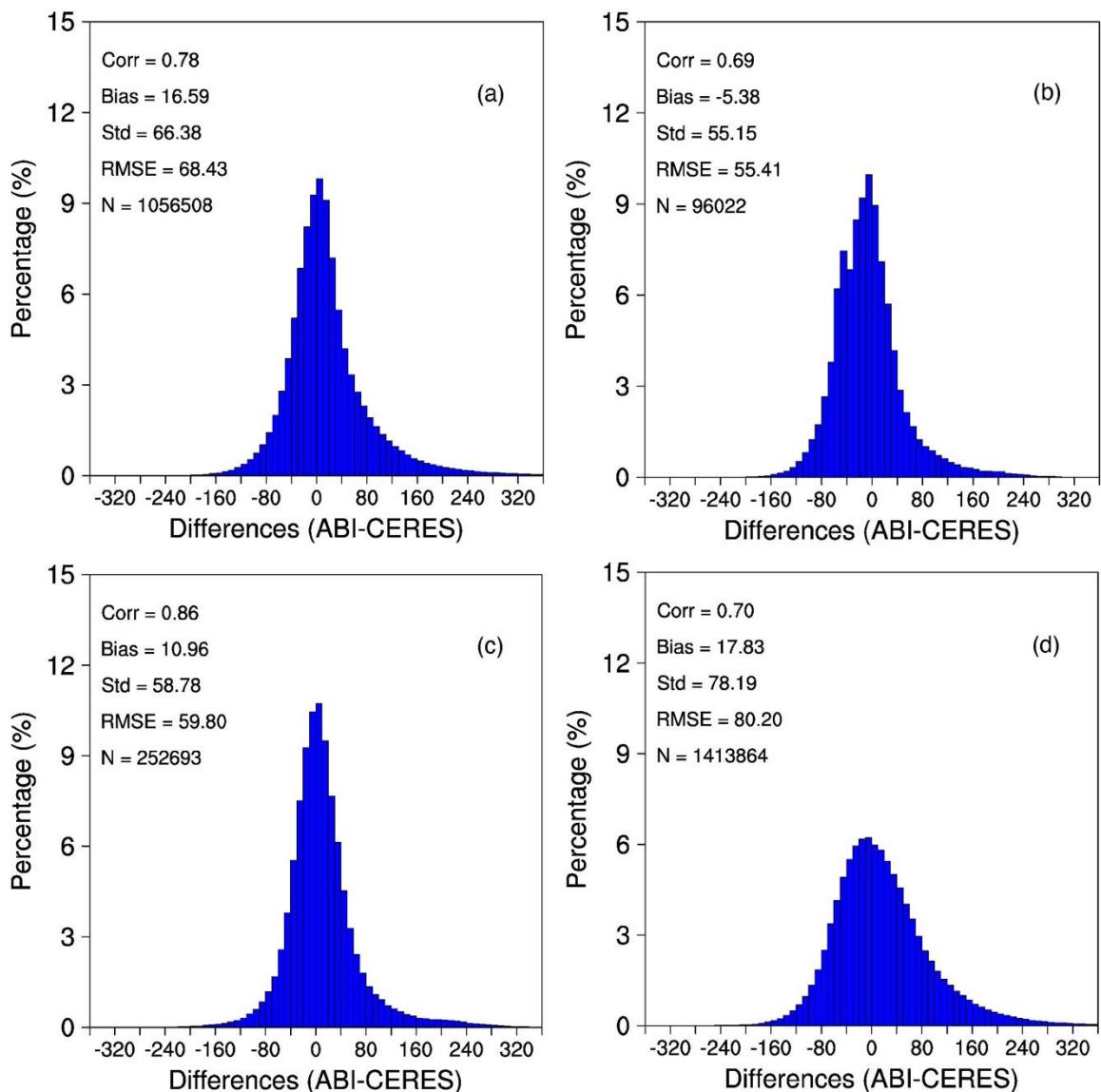


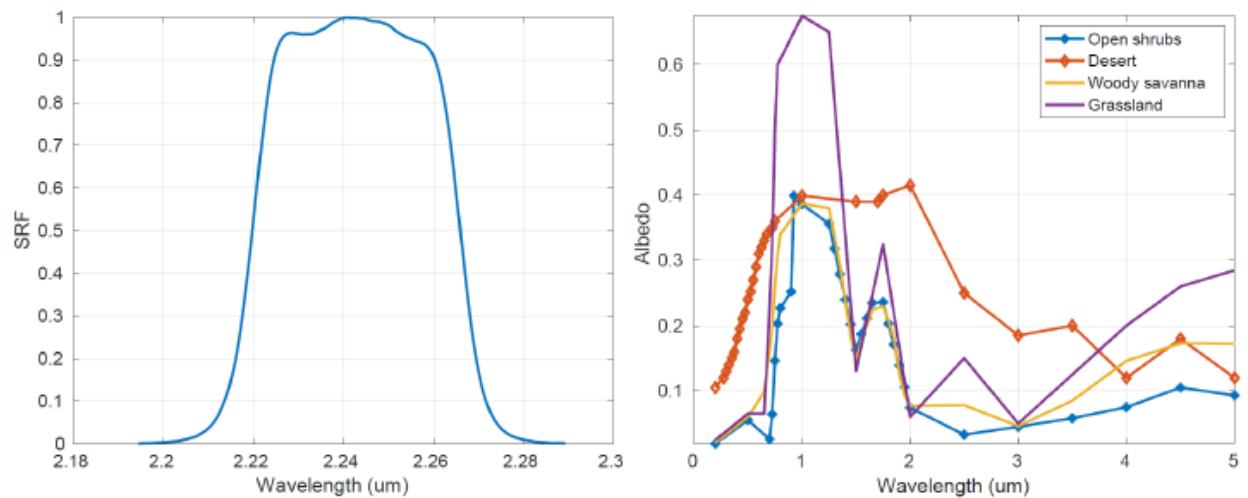
Figure 12. (a) Frequency distribution of all-sky TOA SW differences between ABI on GOES-16 and CERES, (b) ABI on GOES-17 and CERES_SSF using Aqua (Upper) and Terra (Lower). All observations were used (clear and cloudy) on 12/26/2019 at UTC 19:36.



727
728 Figure 13. Same as Figure 11 but for clear TOA SW differences.
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730
731 Figure 14. Same as Figure 11 but for cloudy TOA SW differences.
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736 Figure 15. *Left*: Sensor response function for ABI channel 6; *Right*: Spectral albedo for desert and open
 737 shrubs. Desert albedo value is much higher than open shrubs at 2.2 μm .