



Cloud properties over the Southern Ocean during the MARCUS field

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Abstract. To investigate the cloud properties over the Southern Ocean (SO), the MARCUS field campaign (41 to 69 °S; 60 to 160 °E) was conducted from October 2017 to March 2018, using ship-based measurements. To examine cloud properties over the mid-latitude and Polar regions, the study domain is separated into northern (NSO) and southern (SSO) parts of the SO with a demarcation line of 60 °S. The total cloud fractions (CFs) were 77.9 %, 67.6 %, and 90.3 % for the entire domain, NSO and SSO, respectively, indicating that higher CFs were observed in the Polar region. Low-level clouds, deep cumulus, and shallow cumulus clouds are the three most common cloud types over the SO. For single-layered low-level clouds, mixed-phase clouds dominate with an occurrence frequency (Freq) of 54.5 %, while the Freq of the liquid and ice clouds were 10.1 % (most drizzling) and 17.4 % (least drizzling). The meridional distributions of low-level cloud boundaries are nearly independent of latitude, whereas the cloud temperatures increased ~ 8 K and atmospheric precipitable water vapor increased from ~5 mm at 69 °S to ~18 mm at 43 °S. The mean cloud liquid water paths over NSO were much larger than those over SSO.





Most liquid clouds occurred over NSO with very few over SSO, whereas more mixed-phase clouds occurred over SSO than over NSO. There were no significant differences for ice cloud *Freq* between NSO and SSO. These results will be valuable for advancing our understanding of the meridional and vertical distributions of clouds and can be used to improve model simulations over the SO.

1. Introduction

The Southern Ocean (SO) is one of the cloudiest and stormiest regions on the Earth (Chubb et al., 2013). The majority of the aerosols are naturally produced via oceanic sources given the remote environment. However, we have limited knowledge about cloud formation processes within such clean environments and their associated aerosol and cloud properties. The unique nature of the SO region features low-level supercooled liquid and mixed-phase clouds, which is significantly different from the subtropical marine boundary layer (MBL) clouds where warm liquid clouds are dominant (Dong et al., 2014; Wu et al., 2020; Zhao et al., 2020). Large biases in cloud amount and microphysics over the SO in the Coupled Model Intercomparison Project phase 5 (CMIP5) climate models result in a near 30 W m⁻² shortwave radiation deficit at the top of the atmosphere (TOA) (Marchand et al., 2014; Stanfield et al., 2014, 2015), which further leads to unrealistic cloud feedbacks and equilibrium climate sensitivity (Bony et al., 2015; Stocker et al., 2013). Meanwhile, the efficiency of aerosol-cloud interaction (ACI) over the SO was found to be crucial for the models' sensitivities to the radiation budget. A new aerosol scheme in the Hadley Centre Global Environmental model can dampen the ACI and suppress negative clear-sky shortwave feedback, both of which contribute to a larger climate sensitivity (Bodas-Salcedo et a., 2019).



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higher temperature variations across 27 GCMs in response to doubled CO₂ than those in CMIP5, which may have resulted from the decreased extratropical low-level cloud cover and cloud albedo over the SO in CMIP6 (Zelinka et al., 2020). Low-level clouds are a key climate uncertainty and can explain 50 % of the inter-model variations (Klein et al., 2017) because conversion from liquid cloud droplets to ice cloud particles decreases the cloud albedo and reduces the reflected shortwave radiation at TOA. Models, however, have difficulties accurately partitioning the cloud phase (Kalesse et al., 2016). The phase changes in mixed-phase clouds over the Arctic have proved to affect the cloud lifetime and radiative properties significantly, that is, converting from ice cloud particles to liquid cloud droplets may increase the cloud optical depth and the reflected shortwave radiation at TOA (Morrison et al., 2012). In contrast, models that allow mixed-phase clouds to glaciate rapidly can produce 30% more warming from doubling CO₂ (McCoy et al., 2014). Phase transition processes have been investigated by several groups using both satellite and ground-based measurements. A study (Mace and Protat, 2018) found that there are more mixedphase clouds over the SO measured from the ship than retrieved from CloudSat and CALIPSO measurements because the satellites cannot accurately measure clouds below ~1 km. A previous study (Lang et al., 2018) used a model to investigate the clouds under post cold frontal systems and found large biases in model simulations and concluded that the cloud cover and radiative biases over the SO are highly regime dependent. Of all cloud types, low-level clouds are primarily responsible for the biases in the model simulations due to the lack of reliable measurements, which leads to a poor understanding of the conditions where these clouds form and the phase(s) that result. In other words, a physical representation of clouds, especially for low-level clouds, is unclear but truly necessary for improving model simulations. Therefore, reliable observations of the cloud

A climate sensitivity study using CMIP6 general circulation models (GCMs) shows much



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macro- and micro-physical properties from ground-based active and passive remote sensors are crucial for the improvement of model simulations.

Previous studies show that cloud phase is primarily dependent on cloud temperature, and the transition from one cloud phase to another will modify the cloud optical properties, which further affects the radiation budgets (Hu et al., 2010; Intrieri et al., 2002; Morrison et al., 2012). Based on satellite observations and retrievals, they found that supercooled liquid water (SLW) clouds are most common in the low-level clouds over the SO, where 80% of low-level clouds contain SLW in a wide range of cloud temperatures from 0°C to -40°C (Hu et al., 2010). The formation of SLW clouds is usually related to strong boundary layer convection. However, when ice nuclei exist in the mixed-phase clouds, the ice particles can grow quickly and become bigger through consuming supercooled liquid water drops. The SLW is inherently unstable due to the higher vapor pressure over liquid than over ice and the quicker vapor deposition on ice particles than on liquid droplets (Intrieri et al., 2002). As the supercooled liquid cloud droplets glaciate to ice particles, the cloud layer becomes darker because the ice particles scatter less shortwave radiation and absorb more radiation in the near IR wavelength regime. It is unclear, however, what role these ice particles play in the low-level clouds over the SO, which includes the impact on drizzle development. During HIAPER Pole-to-Pole Observation (HIPPO) campaigns, the study in Chubb et al. (2013) found that there are rarely ice particles in non-drizzling and light drizzling clouds over the SO, which may imply that the ice particles in the mixed-phase clouds may modulate the drizzle formation. To investigate the aerosol and cloud properties over the SO, a field campaign called the Measurements of Aerosols, Radiation, and Clouds over the Southern Ocean (MARCUS) was conducted using the ship-based measurements between Hobart, Australia, and the Antarctic during



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the period October 2017-March 2018. The Department of Energy (DOE) Atmospheric Radiation Measurement (ARM) Mobile Facility (AMF2) was installed on the Australian icebreaker Aurora Australis, which voyaged from Hobart, Tasmania to the Australian Antarctic stations of Casey, Mawson, and Davis, as well as Macquarie Island as illustrated in Fig. 1. Another field campaign, called South Ocean Clouds, Radiation, Aerosol Transport Experimental Study (SOCRATES) field campaign was conducted during austral summer from January 15 to February 26, 2018, which insitu measurements may use as a reference for this analysis. The SOCRATES domain has shown as black dotted rectangle box in Fig. 1. The objectives of the MARCUS campaign are to investigate the vertical distribution of boundary layer clouds and reveal the reasons why the mixed-phase clouds are common in the warm season (McFarquhar et al., 2016), which will be our focuses for this study. MARCUS ship-based instruments include AMF2 cloud radar, lidar, microwave radiometer, micropulse lidar, radiosonde sounding, precision solar pyranometer and precision infrared radiometer, as well as aerosol sensors. Through these comprehensive observations over the SO, we are tentatively answering the following three scientific questions: (1) What is the total cloud fraction over the SO during MARCUS, as well as vertical and meridional variations in cloud fraction? What are the dominant cloud types over the SO, their associated cloud properties, (2) as well as their vertical and meridional distributions? What are the vertical and meridional distributions of the low-level clouds over the (3) SO?





This manuscript is organized as follows: the data and method are introduced in section 2. The statistical results for all clouds during MARCUS are summarized in section 3. The low-level cloud properties are described in section 4, followed by a summary and conclusions in section 5.

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2. Data and Method

The cloud properties analyzed in this study are derived from the data collected by AMF2, including the 95-GHz W-band cloud radar, ceilometer, micropulse lidar, microwave radiometer, aerosol observation system (AOS), meteorological measurements (MET, includes the following data: temperature, pressure, specific humidity, wind direction, and speed) on the ship, rain gauge and the radiosonde soundings. The combined cloud radar and ceilometer measurements can provide the cloud boundaries as long as there are no optically thin clouds and the cloud-base heights (H_{base}) are not greater than the upper limit (7.7 km) of the ceilometer. The micropulse lidar will be used to identify optically thin clouds and the clouds with $H_{\text{base}} > 7.7$ km. A previous study has shown that these additional clouds detected by the micropulse lidar can be a non-negligible supplement to the total cloud fraction (Mace et al., 2021). There are about 4 to 5 radiosonde soundings per day. We adopted a linear interpolation method based on these daily soundings to achieve a better temporal resolution of temperature, pressure, and specific humidity. The method considers MET measurements to ensure vertical continuity and adjacent soundings for temporal continuity. Using these interpolated atmospheric profiles, cloud temperatures can be accurately estimated. The cloud occurrence frequency can be determined through two steps: the column cloud fraction is simply the ratio of cloudy samples to the total observations in every 5-min; the

occurrence frequency for each type of cloud during the entire time period equals the ratio of the

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number where column cloud fraction is greater than zero to the total 5-min samples. The cloud liquid water path (LWP) and atmospheric precipitable water vapor (PWV) are retrieved based on a physical-iterative algorithm using observations of the microwave radiometer brightness temperature at 23.8 and 31.4 GHz with uncertainties ranging from 15 to 30 g m⁻² (Marchand et al., 2003). It is important to note that the brightness temperature biases switch signs among different climatological regions because a threshold of 5 °C in cloud-base temperature was used in their physical retrievals. Therefore, we propose an extra step to determine the uncertainties during MARCUS. Both the AOS and rain gauge measurements were used to determine whether rain is reaching the surface qualitatively, but not quantitatively in this study. All the measurements were averaged over 5 minutes except radar reflectivity, Doppler velocity, and spectrum width used in Section 4.3. The detailed classification method will be introduced in Section 4.1. In brief, we used the measurements of interpolated sounding, microwave radiometer retrieved LWP, radar reflectivity. Doppler velocity and spectrum width to classify the cloud phase in each radar range volume of low-level clouds during MARCUS. We also used ERA5 reanalysis data to study the environmental conditions during MARCUS and calculated the lower tropospheric stability (LTS) and estimated inversion strength (EIS) when the low-level clouds appeared along the shiptracks. A classification method developed in Xi et al. (2010) was used to calculate the occurrence frequencies of different types of clouds and their corresponding cloud macrophysical properties, e.g., cloud base (H_{base}) and top (H_{top}) heights, cloud thickness (ΔH) , and LWP. The relative contributions of mixed-phase, liquid and ice clouds to the single-layered low-level clouds as well as their drizzling status are analyzed in this study. To further investigate the drizzling status under different cloud phases, we also calculated their LTS and EIS. The latitudinal and longitudinal





variations of the single-layered low-level clouds as well as their vertical distributions are also explored in this study.

The occurrence frequencies of total cloud cover and different types of clouds and their

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3. Statistical results for all clouds during MARCUS

associated properties over the entire study domain during MARCUS are presented in Figs. 2-4. In order to examine the cloud properties over the mid-latitude and Polar regions, we separate the SO domain into northern (NSO, north of 60°S) and southern (SSO, south of 60°S) parts using a demarcation line of 60°S. A total of 2,447 hours cloud samples were collected during MARCUS in this study, in which 1,181 hours of samples were located in the NSO and 1,266 hours of samples were collected from the SSO. It is important to note that adding micropulse lidar measurements increased the total samples of non-liquid-containing clouds by ~20% because micropulse lidar is more sensitive to optically thin clouds than cloud radar. However, micropulse lidar signals are usually attenuated and cannot provide a meaningful signal when the liquid cloud layer is thicker than a couple of hundred meters (Sassen, 1991). Figure 2 shows the vertical distributions of total cloud cover over the entire domain, as well as over NSO and SSO. For the vertical distributions, the occurrence frequencies of total cloud increase from the first radar gate (~ 226 m) to ~700 m, then monotonically decrease with altitude with a few small increments at different levels, especially over SSO. We can draw the following conclusions by comparing the occurrence frequencies of the total cloud between NSO and SSO. 1) The SSO has more cloudiness than the NSO under 7 km, while the NSO has more cloudiness than the SSO above 7 km. 2) Below 3 km, the occurrence frequencies of clouds over the NSO decrease dramatically from 37 % at an altitude of ~700 m to 16 % at 3 km and from 45 % to 28 % over the



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SSO, which is similar to the vertical distributions of the low-level clouds over some Northern Hemisphere mid-latitude regions, such as Eastern North Atlantic (ENA, Dong et al., 2014). The occurrence frequencies measured during MARCUS are much lower than these shown in Fig. 8 of Mace et al. (2009) throughout the entire vertical column between the same range of latitudes, especially, the occurrence frequencies during MARCUS are almost half of these measured by CloudSat and CALIPSO from 1 to 3 km. The reason has been explained in Xi et al. (2010), that is, a comparison of occurrence frequencies between measurements of two different platforms can only be performed under an equivalent spatial-to-temporal resolution. In other words, our results were calculated under 5-min temporal resolution, and the results in Mace et al. (2009) were statistically in the 2 ° grid box. Therefore, the comparison between these two results is not reasonable. To make a fair comparison, one has to know the cloud amount at each area or time step, then the product of amount and frequency is independent of either temporal and spatial measurement. To compare with other studies, we calculated the cloud fractions (CFs) of total and different types of clouds. The total CFs were 77.9 %, 67.6 %, and 90.3 % for the entire domain, NSO and SSO, respectively, indicating that 22.7 % more clouds occurred in the Polar region than in the midlatitude region. The total CF over the entire domain is very close to the 76 % calculated by Mace and Protat (2018) using ship-based measurements during the Cloud, Aerosols, Precipitation, Radiation and Atmospheric Composition (CAPRICORN) field experiment. The total CF over the SSO is very close to that estimated by using the complementarity of CALIOP lidar aboard CALIPSO and CPR aboard CloudSat (DARDAR version 2 data) from Listowski et al. (2019). Figure 3 shows the occurrence frequencies of categorized clouds and their cloud boundaries using the maximum H_{top} and the minimum H_{base} . The definition of each type of cloud follows the



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method of Xi et al. (2010). A brief description of the classification of cloud types is as follows. The single-layered low-level clouds (LOW) is the fraction of time when low clouds with $H_{top} \le 3$ km occur without clouds above them. Middle clouds (MID) range from 3 to 6 km without any clouds below and above, while high clouds (HGH) have $H_{\text{base}} > 6$ km with no cloud underneath. Other types of clouds are defined by different combinations of the above three types, middle over low (MOL), high over low (HOL), high over mid (HOM), and the cloud column through the entire troposphere is defined as HML. Three types, MOL, HOM, and HML, include both contiguous and non-contiguous cloud layers, and their thicknesses may be overestimated when clear layer(s) are present between any two cloud layers. As illustrated in Fig. 3a, the single-layered low-level (LOW), deep cumulus or multi-layered (HML), and shallow cumulus (MOL) clouds are the three dominant types of clouds over the SO. Comparing the clouds between NSO and SSO, all types of clouds in SSO are higher than those in NSO except HOL. The differences range from less than 1 % (LOW) to more than 10 % (MOL). Comparing the clouds over mid-latitude oceans between the two hemispheres, i.e., between NSO and ARM ENA site (Dong et al., 2014), we find: (1) The total cloud fractions (CFs) are close to each other (67.6 % over NSO vs. 70.1 % at ARM ENA); (2) LOW CFs are 22.9 % vs. 27.1 %, which is the dominant type of cloud in both regions; and (3) Both MOL and HML clouds, including underneath low clouds, are 14.2 % and 16.5 % over NSO, much higher than those (4.2 % and 12.1 %) at ARM ENA site, indicating that there are more shallow and deep convective clouds over NSO than over ENA. Figure 3b shows the vertical locations of different types of cloud layers, which represent the maximum H_{top} and minimum H_{base} , as well as their deepest ΔH for any type of cloud. Nearly all H_{top} and ΔH values over NSO are higher or deeper than those over SSO, presumably due to stronger



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solar radiation and stronger convection over NSO. H_{base} values basically followed their cloud-top counterparts with a couple of exceptions. These cloud properties are closely associated with largescale dynamic patterns and environmental conditions. By analyzing the ERA-I reanalysis (not shown), the 850 hPa geopotential heights show persistent westerlies with slightly higher geopotential heights over the northwest corner of the domain, which may closely relate to the higher H_{top} over NSO than over SSO. Furthermore, the boundary layer over NSO is relatively more stable than over SSO based on lower troposphere stability analysis. When we plot the probability density functions (PDFs) of cloud LWPs for different types of clouds, we find that the PDFs of LWPs for HGH and HOM peak at less than 10 g m⁻². These results make physical sense because HGH clouds should not contain any liquid droplets, and most HOM clouds, especially those over SSO, should be ice phase dominant. In addition, the 10 g m⁻² of LWP is close to the uncertainty of the LWP retrieval in Marchand et al. (2003). Therefore, this value is used as a threshold for all types of clouds, which leads to less than one percent reduction of the total samples. As shown in Fig. 4a, the LWPs (> 10 g m⁻²) for all types of clouds are much higher over NSO than over SSO because the low-level and shallow convective clouds in the mid-latitudes contain more liquid water than those in Polar regions. The mean LWPs for liquid containing lowlevel and middle-level clouds over NSO, such as LOW, MID and HOL, range from ~130 to 150 g m⁻², while the mean LWPs for shallow and deep convective clouds, such as MOL and HML, are two times higher (~270 g m⁻²) than the mean LWP of LOW, MID and HOL. Note that the mean LWPs for most types of clouds over the SSO are much lower than those over the NSO, except for the LOW clouds. Table 1 provides a summary of the average, standard derivation, minimum and maximum for cloud boundaries, liquid water path and the percentage of multi-layered cloud for each cloud type



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HML. The LWP for single-layered clouds is greater than that for multi-layered clouds. The LWP for single-layered HML almost doubles that for multi-layered HML. The occurrence frequencies of LWPs (> 10 g m⁻²) over NSO and SSO contradict their cloud LWP counterparts, as demonstrated in Fig. 4b. To further investigate the amount of available precipitable water vapor (PWV), we found that mean PWV values in SSO are at least 2 to 3 times less than those in NSO for the same types of clouds (figure not shown). Note that the samples of MID, HGH, and HOM clouds are excluded from this study when they have LWPs less than 10 g m⁻², since these low LWPs are within the retrieval uncertainty of cloud LWP and hence may not contain any liquid cloud droplets. The higher LWPs, larger cloud droplets, drizzle drops and ice particles, and greater drizzling occurrence frequencies over NSO (which is discussed later) will lead to the quick dissipation of clouds over NSO. In contrast to NSO, the SSO cloud LWPs and particle sizes are much smaller with fewer drizzling events, which increases cloud lifetime relative to NSO. The 67.6 % and 90.3 % CFs over NSO and SSO provide strong evidence for this argument. We can draw the following conclusions by comparing the cloud properties between NSO and SSO in Figs. 3 and 4. The LOW fraction, thickness, and LWP over NSO and SSO are comparable to each other. For other types of clouds, cloud thicknesses are similar to each other or slightly deeper over NSO, but the cloud LWPs over NSO are much larger than those over SSO, resulting in more precipitation events over NSO. As pointed out in (Albrecht 1989), more precipitation events may reduce the cloud lifetime. This argument is consistent with the results shown in Figs. 2 and 3a for all clouds except for HOL. Cloud lifetimes over NSO are shorter than those over SSO, which leads to lower CFs over NSO than over SSO.

over the SO. Non-contiguous clouds over the SO occur very frequently, especially for HOM and





4. Single-layered low-level clouds

As discussed in Section 3, single-layered low-level clouds (LOW) are the dominant cloud type in both northern (NSO) and southern (SSO) parts of the SO. Figs. 3 and 4 further reveal that LOW cloud type is the only one having comparable *CF*, cloud, thickness, *LWP* over both NSO and SSO. This warrants further study: Are the cloud phases, properties, and vertical and meridional variations of LOW clouds over these two regions similar to each other or significantly different?

4.1. Cloud phase

In this study, cloud boundaries are determined by combining cloud radar, ceilometer and micropulse lidar measurements at a temporal resolution of 5-min. The cloud phase, liquid water droplets or ice particles, are determined in each radar range volume. A flow chart for classifying the phases of single-layered low-level clouds is drawn in Fig. 5. The determination of warm liquid clouds is straightforward using both cloud-base (T_{base}) and -top (T_{top}) temperatures greater than 0 °C, and cloud LWPs greater than the threshold (10 g m⁻²). The determination of supercooled liquid clouds is slightly complicated. When either T_{base} or T_{top} is below 0° C, and cloud LWPs are greater than the threshold, the radar Doppler spectrum width (WID) and velocity (V_{d}) are used for the determination of supercooled liquid water clouds. If the majority (10 seconds of original radar measurements) of WID are less than 0.4 m s⁻¹ and V_{d} are equal to or less than 0.0 m s⁻¹ (updrafts) in the volume, then this range volume is defined as supercooled liquid clouds.

Mixed-phase clouds are determined when the medians (calculated from 10 seconds of original radar measurements) of WID is greater than 0.4 m s^{-1} and V_d is greater than 0.0 m s^{-1} (downdrafts) due to the existence of large ice particles in the clouds. If cloud LWP is below the threshold, then it is defined as an ice cloud, otherwise, it is defined as a mixed-phase cloud. It is worth mentioning that large ice particles, which grow through vapor deposition or rime processes, dominate the radar





reflectivity and are heavier than cloud droplets. Therefore, these large ice particles not only broaden the spectrum width but also have relatively large fall speeds.

To further evaluate our classification method, we compared the classified mixed-phase and ice clouds with the micropulse lidar linear depolarization ratios (LDR) as an extra measure. The LDR ranges follow the method in Shupe et al. (2005), which are 0.11 < LDR < 0.15 for mixed-phase clouds, and LDR > 0.15 for ice clouds. Table 2a shows the quantitative comparison of the cloud phase identifications between these two classification methods. The numbers represent the counts of each matched 5-min sample, where the diagonal numbers indicate that both methods are identifying the same type of cloud phase. In general, the two methods have 89 % agreement on the phase identification. Secondly, we performed the phase classification directly from microphysical probes onboard G-1 aircraft during SOCRATES and treated them as 'ground-truth' (Mohrmann et al., 2021). By changing the time step of sampling to mimic what the radar may observe the cloud for each range volume, Table 2b shows the statistics of the possibility of the cloud phase that may be detected by cloud radar. As sampling time increases from 1 second to 30 seconds, more mixed-phase clouds and fewer single-phase clouds can be observed.

Figure 6 shows the occurrence frequencies of the matched results for mixed-phase clouds (left panel) and ice clouds (right column). For the classified ice clouds, most of the Doppler spectrum widths range from 0.08 to 0.16 m s⁻¹ and the *LDR* ratios can be up to ~0.5, representing a narrow range of ice particle size distribution with higher *LDR* ratios. Cloud liquid is identified by low *LDR* of ~0.11 (Fig. 6d) and high lidar backscatter from 10⁻⁵ to 10⁻⁴ m⁻¹ sr⁻¹ (Fig. 6e). For the classified mixed-phase clouds, most of the Doppler spectrum width range from 0.15 to 0.35 m s⁻¹ and most of the *LDR* signals are less than 0.4, representing a broad particle size distribution resulting from the mixture of liquid droplets and ice particles but lower *LDR* ratios. Based on the Doppler velocity,



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are dominant in both types of clouds. The broader particle size distribution with lower LDR ratios for mixed-phase clouds and narrower particle size distribution with higher LDR ratios for ice clouds further corroborate that the classified results from this study are consistent with the traditional micropulse lidar LDR method. It is important to note that the micropulse lidar signals are usually attenuated and cannot provide a meaningful signal when the liquid cloud layer is thicker than a couple of hundred meters (Sassen, 1991). Arctic mixed-phase clouds are typical, with the liquid-dominant layer on the top of the mixed-phase clouds and the ice-dominant layer underneath. The ceilometer-derived cloudbase height represents the base of the liquid-dominant layer near the cloud top, while MPL-derived cloud-base height represents the base of the lower ice-dominant layer (Qiu et al., 2015; Shupe, 2007; Shupe et al., 2005). Over the Arctic, the micropulse lidar signals can penetrate through the ice-dominant layer to the liquid-dominant layer. However, the mixed-phase clouds over the Southern Ocean are totally different from those over the Arctic region: they are well mixed (liquid droplets and ice particles) from cloud base to cloud top, which is found in this study. Thus, the micropulse lidar signals can be attenuated in the mixed-phase clouds over the Southern Ocean. Statistical results show that 43 % of micropulse data were attenuated during MARCUS compared to our classified results. This classification method is further supported by the onboard cloud radar measurements during the Southern Ocean Clouds Radiation Aerosol Transport Experimental Study (SOCRATES, not shown). In that campaign, the reflectivity measurements were usually greater, and the spectrum widths were much wider when the aircraft observed large ice particles compared to the time periods when liquid cloud droplets were observed. It is also worth mentioning that about 5.5 % of

the mode values for both mixed-phase and ice clouds occur at ~ 0.5 m s⁻¹, where the ice particles



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not available during MARCUS. Therefore, using our classification method, a total of 6,934 5-min single-layered low-level cloud samples were determined in this study, including 697 liquid cloud samples, 3,777 mixed, 1,205 ice, and 1,255 'OTHER' clouds. The category of 'OTHER' clouds represents more than one phase in each column. Figure 7 (upper panel) shows the drizzling status for each categorized cloud type, e.g., no rain (yellow-green), virga (brown) and rain (navy blue). The definition of drizzling status follows the method in Wu et al., (2015, 2017), which used both ceilometer and cloud radar measurements to determine the status of MBL clouds under non-drizzling, virga and rain conditions. The percentages shown below the x-axis represent the portion of drizzling status in each type of clouds, such as liquid, mixed-phase, ice and 'OTHER' clouds. Figure 7 (bottom panel) also shows the percentages and vertical distributions of classified liquid, mixed-phase, ice, and 'OTHER' clouds for each column in the single-layered low-level clouds, represented by different colors. After classification, the samples in each category are sorted by their H_{top} . In detail, Fig. 7 demonstrates that the mixed-phase clouds dominate the single-layered low-level cloud category with an occurrence frequency of 54.5 %. The 'OTHER' and ice clouds have similar occurrence frequencies of 18.1 % and 17.4 %, respectively, while the liquid clouds have the least occurrence frequency of 10.1 %. The liquid topped mixed-phase clouds (included in 'OTHER'), which frequently occur in the Arctic region (Qiu et al., 2015), are rarely found over the SO. The existence of ice particles in mixed-phase clouds should strongly depend on the distribution of ice nuclei (IN), whereas spatially unevenly distributed IN may result in the OTHER type of clouds. Based on the results in Fig. 7, we draw the following conclusions. Most of the ice clouds are non-drizzling clouds, and the percentages with virga and drizzle below the cloud base are 12 %

single-layered low-level cloud phases cannot be determined when the radar measurements were





and 15 %, respectively. The percentages of non-drizzling, virga and drizzling mixed-phase clouds are 50 %, 21 %, and 29 %. The liquid and 'OTHER' clouds have similar percentages, they are 36 %, 25 % and 39 % for liquid clouds, and 35 %, 22 % and 44 % for 'OTHER' clouds. For liquid and 'OTHER' clouds, the drizzling frequencies are independent of H_{top} . In contrast, for mixed-phase and ice clouds, the drizzling frequencies strongly depend on H_{top} , i.e., higher drizzling frequencies occur mostly at higher H_{top} .

The properties of single-layered low-level clouds are summarized in Table 3. The liquid clouds have the lowest H_{base} and H_{top} but more available water vapor than other types of clouds. Since the 'OTHER' clouds are a transitional stage among mixed-phase, liquid and ice clouds, they have the highest H_{top} , deepest cloud layer and largest LWP. The ice clouds occur in relatively dry environments and have the highest H_{base} at 1.218 km. The mixed-phase clouds have similar H_{base} , but lower H_{top} , LWP and PWV compared to those of 'OTHER' clouds. Since LWPs in mixed-phase clouds have larger standard deviations, which implies that SLW is more common at higher LWPs and ice is more common at lower LWPs.

4.2. Meridional variations of cloud properties

Figure 8 shows the meridional variation in single-layered low-level cloud properties during MARCUS. As illustrated in Fig. 8a, the meridional distributions of H_{base} , H_{top} and ΔH are nearly independent of latitude, however, their corresponding temperatures (T_{base} and T_{top}) increased about 8 K from 69 °S to 43 °S, though there were slight fluctuations. These results suggest that the cloud and sea surface temperatures have minimal impact on the cloud boundaries over the SO, which is consistent with the findings in McFarquhar et al. (2016). The meridional variation of LWPs mimics those of T_{base} and T_{top} , with an increasing trend from south to north. It is important to point out that a big drop in LWP at ~50 °S results from fewer occurrences of low-level clouds there, indicating





that the cloud samples at some latitudes are not statistically significant. The atmospheric *PWV* increased dramatically from ~ 5 mm at 69 °S to ~18 mm at 43 °S, presumably due to increased sea surface and atmospheric temperatures.

Figure 9 shows the latitudinal and meridional distributions of categorized liquid, mixed-phase, ice and 'OTHER' in single-layered low-level clouds over the SO during MARCUS. Each circle represents the exact location and time along the ship track. Mixed-phase clouds occurred everywhere over the SO during the MARCUS field campaign and became dominant in November, December and February. Liquid clouds dominated in March, while ice clouds dominated in January. The 'OTHER' clouds are a kind of transitional phase falling in between the mixed-phase and ice/liquid clouds because there are no stand-alone occurrences in any month during MARCUS.

4.3 Vertical distribution of cloud properties

The vertical distributions of classified liquid, mixed-phase, and ice clouds are presented in Figs. 10-12. The focus of this section will be comparisons of cloud properties between the north (NSO) and south (SSO) regions of the domain. Figure 10a shows the vertical distributions of liquid clouds, which were capped at ~ 1.6 km, mostly in the marine boundary layer. The vertical occurrence frequencies are up to 27 % over NSO, while they were less than 4 % over SSO, i.e., liquid clouds occurred fairly often over the mid-latitude region, but very few occurred over the Polar region. On the contrary, the occurrence frequencies of mixed-phase clouds between NSO and SSO are opposite to liquid clouds, as illustrated in Fig. 10b, though the differences are not so obvious. Mixed-phase clouds increased with altitude until ~1.6 km, then decreased monotonically towards 3 km. The highest frequencies were ~37 % at 0.6 km over SSO and ~27 % at 1.5 km over NSO. The vertical distributions of ice clouds are similar to those of mixed-phase clouds (Fig. 10c). However, there were no significant differences between NSO and SSO. It is worth mentioning that





411 the vertical distributions of mixed-phased clouds over SO are quite different to those from DOE 412 ARM Northern Slope Alaska (NSA) site where the liquid topped mixed-phase low-level clouds 413 are common (e.g., Qiu et al., 2015). 414 To further investigate the vertical distributions of classified liquid, mixed-phase, and ice clouds 415 over NSO and SSO, we plot the normalized vertical distributions (cloud base as 0, cloud top as 1) 416 of radar reflectivity, Doppler velocity and spectrum width in Figs. 11 and 12, respectively. In this 417 study, the threshold of -50 dBZ was used to determine the cloud boundary over the SO instead of 418 the threshold of -40 dBZ radar reflectivity used at the ARM ENA site (Dong et al., 2014). If we 419 used the threshold of -40 dBZ over the SO, then there would be only 73 % cloud samples available 420 for this study. About 9.6 % of radar reflectivities during MARCUS are less than -50 dBz for all 421 single-layered low-level cloud samples. Thus all radar parameters used in this study are based on 422 90.4 % of the radar measurements with reflectivity greater than -50 dBz. 423 Figures 11a-11c represent the normalized vertical distributions of radar reflectivity. Doppler 424 velocity and spectrum width of liquid clouds. Liquid clouds had the lowest reflectivity near the 425 cloud top because of cloud-top entrainment., The reflectivity had a nearly constant median value 426 of ~ -22 dBZ from near cloud top height (~ 0.8 for normalized height) of the cloud layer to the 427 cloud base. Most of the reflectivities were less than -15 dBz, which is the threshold to distinguish 428 cloud and drizzle-sized particles in each radar range volume (Wu et al., 2020). Most of the Doppler 429 velocities were greater than 0.0 m s⁻¹, indicating that downwelling motion is dominant in liquid 430 clouds. The profiles of Doppler velocity and spectrum width increased smoothly from the cloud 431 top to base, suggesting that larger cloud droplets and broader size distributions exist near the cloud 432 base, which is attributable to more drizzle drops near the cloud base, as illustrated in Fig. 7.



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The vertical distributions of mixed-phase clouds in Figs. 11d-11f are similar to those of liquid clouds. The more occurrences of larger reflectivity measurements and larger median values of spectrum width near the cloud base are most likely due to the presence of moderate ice particles and/or drizzle drops. The nearly same median values of reflectivity, Doppler velocity and spectrum width (but slightly larger standard deviations in each level in mixed-phase clouds) in both liquid and mixed-phase clouds suggest that the ice particle sizes in mixed-phase clouds are comparable to cloud droplets and drizzle drops. The nearly uniform vertical distributions of Doppler velocity and spectrum width indicate well-mixed liquid cloud droplets and ice particles throughout the cloud layer in the mixed-phase clouds over NSO. Ice clouds had much lower reflectivity and narrower spectrum width than liquid and mixedphase clouds, as shown in Figs. 11g-11i. Almost all reflectivity measurements were less than -25 dBz with a median value of -35 dBz at the cloud base, resulting from small or moderate ice particles but much lower concentration. A nearly constant Doppler velocity within the cloud layer further supports the discussion of mixed-phase clouds above, i.e., the ice particle sizes are independent of cloud height and comparable to liquid cloud droplets in the low-level clouds over the SO. Because there are no mechanisms for growing large ice particles in such shallow ice clouds, the accretion process cannot take place. From the statistical results in Fig. 7, these ice particles have relatively little chance to become virga or raindrops and usually dissipate or transition to other types of clouds. Since there are not enough liquid cloud samples over the Polar region, only the mixed-phase and ice clouds results are plotted in Fig. 12. Compared to the vertical distributions of ice clouds over NSO, the median values of reflectivity and Doppler spectrum width over SSO were lower

and narrower, indicating a lack of large ice particles in the Polar region. The small ice particles in





the Polar region were also reflected in their mixed-phase clouds. Compared to the vertical distributions of the mixed-phased clouds over NSO, the median values of reflectivity and Doppler spectrum width over SSO were dramatically lower (-35 dBz at SSO vs. -22 dBz at NSO; 0.25 m s⁻¹ at SSO vs. 0.32 m s⁻¹ at NSO). Figure 12 illustrates that the ice particle sizes over SSO are smaller, their size distributions are narrower than those over NSO, indicating of lack of large ice particles over SSO.

5. Summary and Conclusions

In this study, we presented the statistical results of clouds over the Southern Ocean (SO) and the northern (NSO) and southern (SSO) parts during MARCUS IOP. We used the method developed in Xi et al. (2010) to calculate the occurrence frequencies of different types of clouds and their corresponding cloud macrophysical properties. We developed a new method to classify liquid, mixed-phased, and ice clouds in the single-layered low-level clouds as well as their corresponding drizzling status. Lastly, we explored the meridional and vertical distributions of these classified cloud properties. Analysis of the MARCUS cloud properties has yielded the following conclusions.

1. The total cloud fractions (*CF*s) were 77.9 %, 67.6 %, and 90.3 % for the entire domain, NSO and SSO, respectively, indicating that 22.7 % more clouds occurred in the Polar region than in the mid-latitude region. The SSO had more clouds under 7 km, while the NSO had more clouds above 7 km. Below 3 km, the occurrence frequencies of clouds over NSO decrease dramatically from 37 % at an altitude of ~700 m to 16 % at 3 km, which is similar to the vertical distributions of the low-level clouds over some Northern Hemisphere mid-latitude regions, such as Eastern North Atlantic.





- 2. The single-layered low-level (LOW), deep cumulus or multi-layered (HML), and shallow cumulus (MOL) clouds are the three dominant types of clouds over the SO. Comparing the clouds between NSO and SSO, all types of clouds in SSO are higher than those in NSO except HOL. The LOW fraction, thickness, LWP over both NSO and SSO are comparable to each other. The mean *LWP*s for low clouds over NSO, such as LOW, MOL and HOL, range from ~130 to 150 g m⁻², while the mean *LWP*s for shallow and deep convective clouds, such as MOL and HML, are two times (~270 g m⁻²) higher than the same types of clouds. The mean *LWP*s of clouds over SSO are much lower than the *LWP*s over NSO. Over the Southern Ocean, the single-layered or contiguous clouds usually have higher liquid water paths than their counterpart of multi-layered or non-contiguous clouds. There are more non-contiguous HML and HOM than contiguous ones.
- 3. A new method was developed to classify liquid, mixed-phase and ice clouds in the single-layered low-level clouds (LOW) based on comprehensive ground-based observations. The mixed-phase clouds are dominant in the single-layered low-level cloud category with an occurrence frequency of 54.5 %. The 'OTHER' and ice clouds had similar occurrence frequencies of 18.1 % and 17.4 %, respectively, while the liquid clouds had the least occurrence frequency of 10.1 %. The percentages of non-drizzling, virga and drizzling for mixed-phase clouds were 50 %, 21 %, and 29 %, and the drizzling frequencies of mixed-phase clouds strongly depend on H_{top} , that is, higher drizzling frequencies occurred mostly at higher H_{top} .
- 4. The meridional distributions of H_{base} , H_{top} and ΔH are nearly independent on latitude. However, their corresponding temperatures increased about 8 K from 69 °S to 43 °S. The meridional variation of LWPs mimics that of cloud temperatures, having an increasing trend from south to north. The mean PWV increased dramatically from ~5 mm at 69 °S to ~18





mm at 43 °S due to increased sea surface and atmospheric temperatures. More liquid clouds occurred over NSO but very few occurred over SSO, whereas more mixed-phase clouds occurred over SSO than over NSO. There were no significant differences in ice clouds occurrences between NSO and SSO.

5. The nearly same median values of reflectivity, Doppler velocity and spectrum width in both liquid and mixed-phase clouds over NSO suggest that the ice particle sizes in mixed-phase clouds are comparable to cloud droplets and drizzle drops. The uniform vertical distributions of Doppler velocity and spectrum width suggest well-mixed liquid cloud droplets and ice particles throughout the cloud layer in the mixed-phase clouds over NSO, which are quite different from those over the DOE ARM NSA site where the liquid topped mixed-phase low-level clouds are common. The median values of reflectivity and Doppler spectrum width over SSO were lower and narrower than those over NSO, indicating lack of large ice particles in the polar region.

These results provide comprehensive statistical properties of all clouds over the SO during MARCUS, including the occurrence frequencies of different types of clouds and their corresponding cloud macrophysical properties. We also examined the meridional and vertical distributions of the classified cloud properties. These statistics can be used as ground truth to evaluate satellite retrieved cloud properties and model simulations over the SO. The results of this study will help to advance our understanding of these clouds, which may lead to improved model simulations over the SO as well as a better representation of global climate.

Data availability. Data used in this study can be accessed from the DOE ARM's Data Discovery at

524 https://adc.arm.gov/discovery/





526 Author contributions. The idea of this study is discussed by BX, XD, and XZ. BX and XZ performed 527 the analyses and BX wrote the manuscript. BX, XD, XZ and PW participated in scientific discussions 528 and provided substantial comments and edits on the paper. 529 530 Competing interests. The authors declare that they have no conflict of interest. 531 532 Acknowledgements. The ground-based measurements were obtained from the Atmospheric 533 Radiation Measurement (ARM) Program sponsored by the U.S. Department of Energy (DOE) 534 Office of Energy Research, Office of Health and Environmental Research, and Environmental 535 Sciences Division. The data can be downloaded from http://www.archive.arm.gov/. Researchers 536 were supported by the NSF project under grant AGS-2031750 at the University of Arizona. 537 Specially thanks to Mr. Xingyu Zhang for providing analysis from CDP and 2DS microphysical 538 sensors during SOCRATES and Dr. Dale Ward at the University of Arizona for proofreading this 539 manuscript. 540 541 542 543 References. 544 Albrecht, B. A.: Aerosols, cloud microphysics, and fractional cloudiness, Science, 545 doi:10.1126/science.245.4923.1227, 1989. 546 Bodas-Salcedo, A., Mulcahy, J. P., Andrews, T., Williams, K. D., Ringer, M. A., Field, P. R. and 547 Elsaesser, G. S.: Strong Dependence of Atmospheric Feedbacks on Mixed-Phase 548 Microphysics and Aerosol-Cloud Interactions in HadGEM3, J. Adv. Model. Earth Syst., 549 doi:10.1029/2019MS001688, 2019.





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Table 1. Minimum cloud base heights (H_{base}), maximum cloud top heights (H_{top}), and liquid water paths (LWPs) (all samples, single-layered, multilayered) of all seven types of clouds over the Southern Ocean. Cloud heights have unit of kilometer, and LWP has unit of g m⁻².

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	LOW	MID	MOL	HGH	HOM	\mathbf{HML}	HOL
$H_{\mathrm{base}} \pm \mathrm{std}$	0.92 ± 0.57	4.14 ± 0.61	1.37 ± 0.96	8.51 ± 2.23	4.70 ± 0.80	1.22 ± 0.98	1.14 ± 1.12
min, max	0.06, 2.86	3.00, 5.84	0.06, 5.27	6.00, 18.67	3.01, 7.72	0.06, 7.81	0.07, 10.37
$H_{\text{top}} \pm \text{std}$	1.62 ± 0.63	4.88 ± 0.68	4.29 ± 0.89	9.75 ± 2.13	7.93 ± 1.27	7.81 ± 1.35	8.93 ± 1.66
min, max	0.29, 3.0	3.17, 6.0	1.39, 5.99	6.20,18.79	5.47, 17.98	3.62,17.38	1.79, 17.56
$LWP \pm std$	122.4±134.2	86.7±124.5	168.7±236.7	/	40.9±40.8	169.2±238.4	129.8±202.
Max LWP	1470.8	501.1	1937.1	/	345.7	1819.3	1785.2
LWP ± std (single layer)	126.6±138.1	88.7±128.9	193.1±271.9	/	48.7±51.7	270.8±349.5	/
max	1470.8	501.1	1937.1	/	345.7	1819.3	/
LWP ± std (multi-layer)	96.2±103.4	77.2±109.2	139.0±180.7	/	32.3±21.3	148.4±202.4	129.8±202.
max	842.3	305.6	1830.2	/	86.8	1690.7	1785.2
Multi-layer percentage %	18.1	39.6	50.0	44.9	73.1	77.7	100

^{*} The definition of the cloud types as follow: LOW (H_{base} and $H_{\text{top}} \le 3 \text{ km}$); MID ($H_{\text{base}} > 3 \text{ km}$ and $H_{\text{top}} \le 6 \text{ km}$); HGH ($H_{\text{base}} > 6 \text{ km}$); MOL ($H_{\text{base}} < 3 \text{ km}$ and $H_{\text{top}} \le 6 \text{ km}$); HOM ($3 \text{ km} < H_{\text{base}} < 6 \text{ km}$ and $H_{\text{top}} > 6 \text{ km}$); HML ($H_{\text{base}} < 3 \text{ km}$, $H_{\text{top}} \ge 6 \text{ km}$ with a MID layer); HOL (LOW and HGH appear at the same time).





Table 2a. Comparison of cloud phase identifications between our classification method and Shupe et al. (2005) method in each 5-min measurements, the unit is number of 5-min samples.

Shupe / this study	Liquid (this study)	Mixed-phase (this	Ice (this study)
		study	
Liquid	468	490	0
Mixed-phase	98	3840	0
Ice	81	0	1195

^{*}Numbers denote the cloud sample classifications between two methods. For example, the number 98 denote a total of 98 samples are classified as Mixed-phase using Shupe's method, while are classified as Liquid using this study's method.

Table 2b. The cloud phase partitioning from CDP and 2DS during SOCRATES. Cloud Droplet Probe (CDP) measures particle size from 2 to 50 um in diameter; Two-Dimensional Stereo Probe (2DS) measures particle size from 50 to 5000 um in diameter.

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Phase partitioning	1 second	10 seconds	30 seconds		
Samples #	27280	2255	836		
Liquid, %	58.8	26.2	18.8		
Mixed-phase, %	38.9	69.1	77.0		
Ice, %	2.3	4.7	4.2		





Table 3. Liquid, mixed, ice and OTHER phases of cloud properties within the single-layered low-level clouds

Phase	Samples	H _{base} , km	H _{top} , km	ΔH , km	LWP, g m ⁻²	PWV, mm
Liquid	697	0.424±0.204	1.327±0.242	0.903	113.6±90.1	15.7±3.5
Mixed	3777	0.834±0.465	1.434±0.617	0.587	119.7±136.6	8.9±5.0
Ice	1205	1.218±0.635	1.737±0.651	0.519	0	8.4±4.5
OTHER	1255	0.700±0.454	1.774±0.571	1.074	141.9±137.5	11.4±5.9



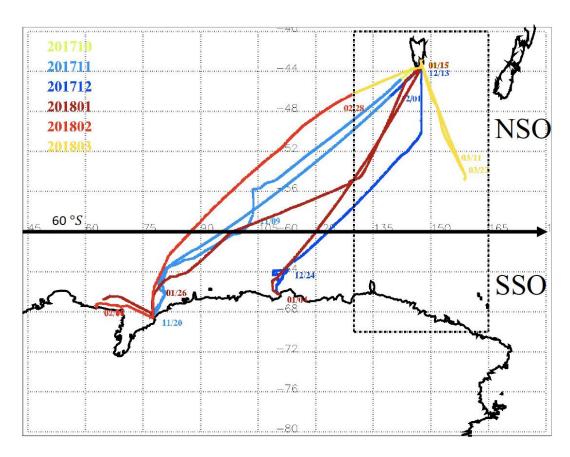


Figure 1. Shiptrack measurements between Hobart, Australia and Antarctica. Different colors represent different month's shiptracks from Oct. 29, 2017 to Mar. 23, 2018 during MARCUS. Along the shiptracks, the study domain is separated into northern (NSO) and southern (SSO) parts of the Southern Ocean with a demarcation line of 60 °S in order to study the clouds over the midlatitudes (North of 60 °S) and Polar region (South of 60 °S). The black dotted rectangle represents the SOCRATES study domain. Some of the dates have labeled along the shiptracks, which can indicate the direction of the ship traveled.



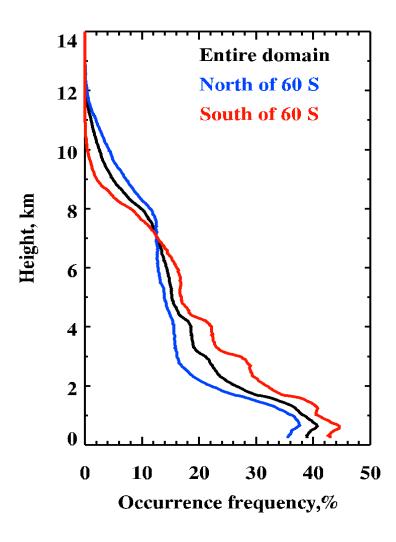


Figure 2. Mean vertical distributions of total clouds derived from ARM radar-lidar observations with a 5-min temporal resolution and a 30-m vertical resolution during MARCUS.



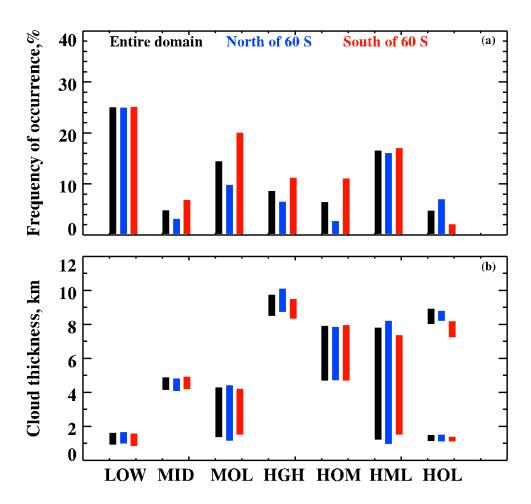


Figure 3. (a) Occurrence frequencies of categorized clouds by their vertical structures. LOW, single - layered low clouds (H_{base} and $H_{\text{top}} \le 3$ km); MID, single-layered middle clouds ($H_{\text{base}} > 3$ km and $H_{\text{top}} \le 6$ km); MOL, MID over LOW ($H_{\text{base}} < 3$ km and $H_{\text{top}} \le 6$ km); HGH, single-layered high clouds ($H_{\text{base}} > 6$ km); HOM, HGH over MID (3 km $< H_{\text{base}} < 6$ km and $H_{\text{top}} > 6$ km); HML, HGH over MID and LOW ($H_{\text{base}} < 3$ km, $H_{\text{top}} \ge 6$ km with a MID layer); and HOL, HGH over LOW (LOW and HGH appear at the same time). (b) Cloud thickness for each type of clouds (bar), the top and bottom of the bar represent the maximum cloud-top and minimum cloud-base heights, respectively. Black, blue, and red bars represent the entire domain (Lat:41-69 °S; Long: 60-160° E), north of 60 °S (NSO), and south of 60°S (SSO), respectively, during the MARCUS field campaign (10/2017-3/2018).



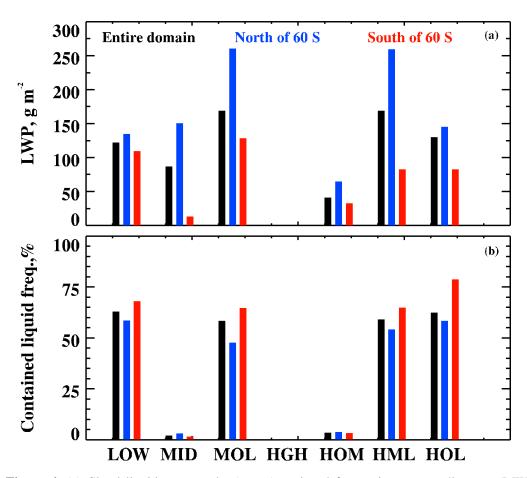


Figure 4. (a) Cloud liquid water paths (LWPs) retrieved from microwave radiometer (MWR) measured brightness temperature using a physical retrieval method for each type of cloud. (b) The occurrence frequencies of $LWPs > 10 \text{ gm}^{-2}$ for each type of clouds





Phase classification algorithm for single layered low level clouds

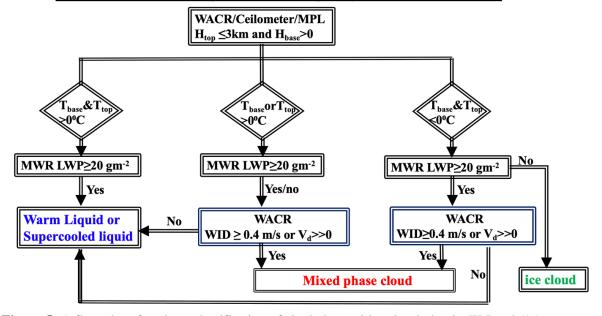


Figure 5. A flow chart for phase classification of single-layered low-level clouds. W-Band (95 GHz) ARM Cloud Radar (WACR) provides radar spectrum width (*WID*) and Doppler velocity (V_d) .



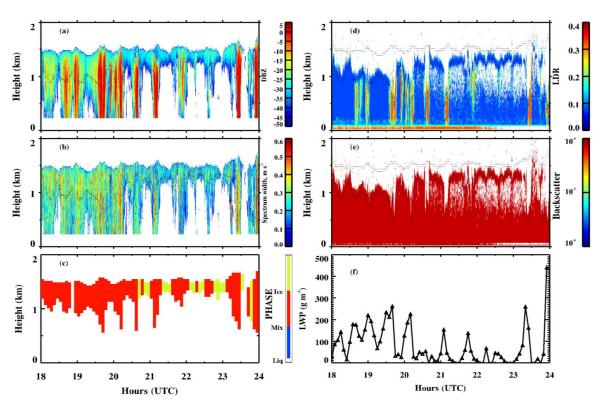


Figure 6. A case study that shows our phase classification (left column) and Micropulse Lidar linear depolarization ratios (*LDR*) and backscatter. W-Band (95 GHz) ARM Cloud Radar (WACR) reflectivity shows in (a) and spectrum width shows in (b); The phase classification shows in (c); MPL *LDR* shows in (d) and backscatter shows in (e); and *LWP* shows in (f).



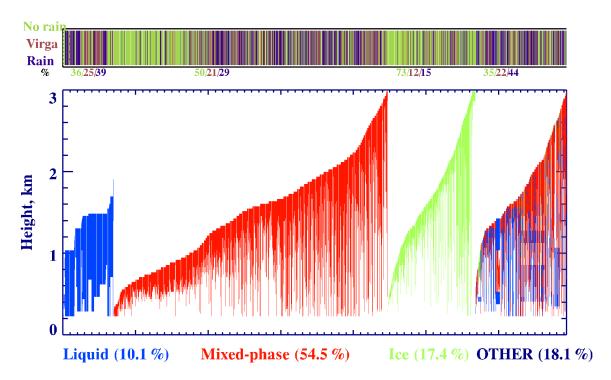


Figure 7. (Upper Panel) The drizzling status for each categorized cloud type, e.g., no rain (yellow-green), virga (brown) and rain (navy blue), the percentages shown below the x-axis represent the portion of drizzling in each type of clouds; And (Bottom Panel) the percentages and vertical distributions of classified liquid, mixed-phase, ice, and 'OTHER' clouds for each column in the single-layered low-level clouds, represented by different colors, over the entire domain during MARCUS. Each line represents one 5-min sample.



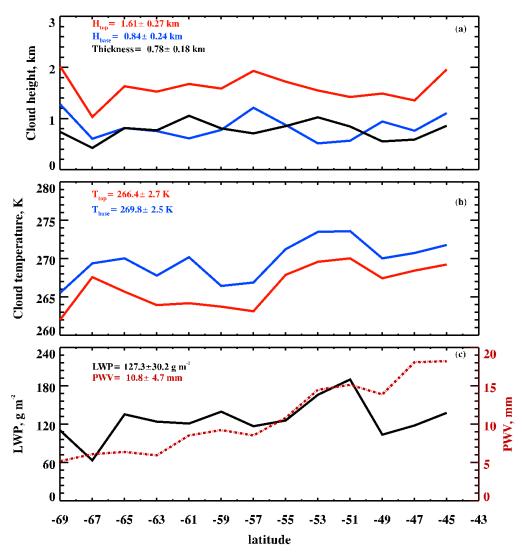


Figure 8. Meridional variations of single-layered low-level cloud properties: (a) cloud-base (H_{base}) and -top (H_{top}) heights, and cloud thickness (ΔH), (b) cloud-base (T_{base}) and -top (T_{top}) temperatures, and (c) cloud liquid water path (LWP) and precipitable water vapor (PWV) over the entire domain during MARCUS.



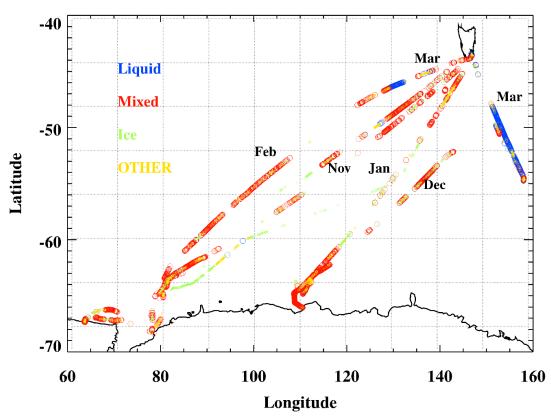


Figure 9. The latitudinal and longitudinal distributions of classified mixed-phase, liquid, and ice clouds in the single-layered low-level clouds. The liquid (blue), mixed (red), ice (light green), and OTHER (yellow) are shown along each shiptrack from October 2017 to March 2018 during MARCUS.



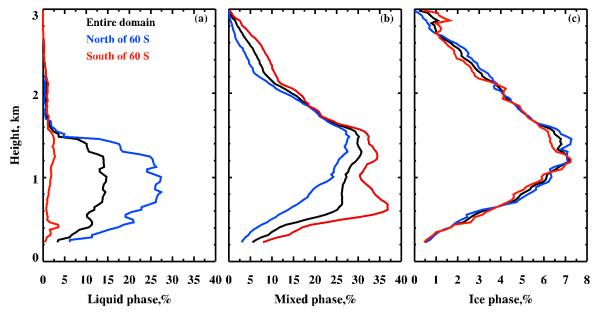


Figure 10. Occurrence frequencies of classified mixed-phase, liquid, and ice clouds over the entire domain (black), North of 60 °S (blue) and South of 60 °S during MARCUS.



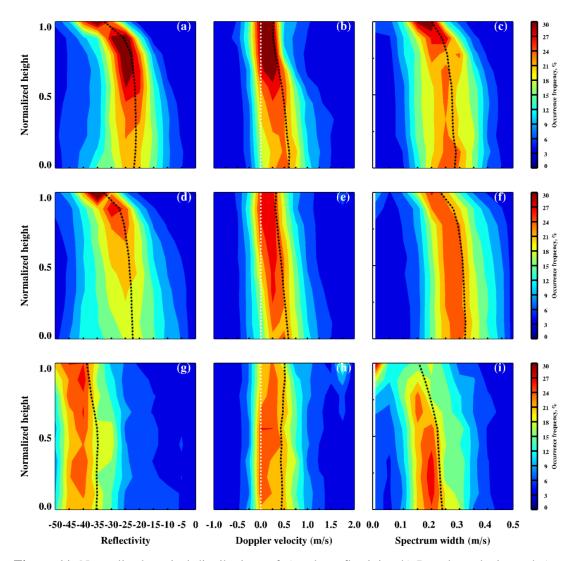


Figure 11. Normalized vertical distributions of a) radar reflectivity, b) Doppler velocity and c) spectrum width for the classified liquid (upper panel), mixed-phase (d to f, middle panel) and ice (g to i, bottom panel) clouds over the North of 60 °S during MARCUS IOP. Normalized height is defined as $=\frac{H-H_{base}}{H_{top}-H_{base}}$ where cloud base is denoted as 0 and cloud top is 1. The black lines represent the median values and the white lines in Doppler velocity represent the reference of 0.0 m s⁻¹.



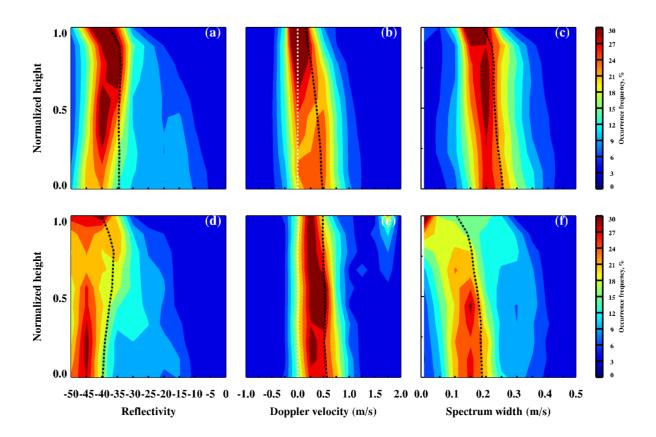


Figure 12. Same as Fig. 11 but only for mixed-phase (a to c, upper panel) and ice (d to f, bottom panel) over the south of 60 °S during MARCUS.