The reply to the anonymous referee #2 (RC2)

We are grateful to the referee for the very attentive reading of our manuscript and for many insightful remarks. We accept the criticism as very helpful. While preparing the revised version of our article, we took into account all comments made by the referee.

Below, the actual comments of the referee are given in **bold courier font and blue colour**. The text added to the revised version of the manuscript is marked by red colour.

Notice: Since both anonymous referees made several similar remarks, our answers to these remarks which are given in both replies are identical.

<u>Notice2: Numbering of figures and sections has been changed considerably in the</u> <u>revised version of the manuscript.</u>

Synthesis:

This study presents a method that can be applied to microwave radiometers operated close to a water surface to determine differences in cloud liquid water path over land and water. The results of the newly developed algorithm for the ground-based microwave radiometer is compared to satellite observations.

In the current form, I do not recommend the study to be published. There are several points that should be addressed, in particular a thorough uncertainty analysis. Please find my comments below.

General comments:

• The study lacks a thorough uncertainty analysis, from the brightness temperature uncertainties to the retrieval errors. You discuss the error sources in Chapter 3.2, but you do not provide any values for the different errors which would be crucial for interpreting the results. The LWP differences in your study on the order of much less than 10 g/m² are well within the error ranges (both bias and random errors). Please provide a detailed uncertainty analysis including error bars in Figures 6, 7, 9, 10, and 11 !

As a reply to this comment, we expanded the uncertainty analysis. Following the advice of the referee, we began with the brightness temperature uncertainties and LWP retrieval errors for zenith geometry in Section 3.2:

The input data for the retrievals are the values of brightness temperature of down-welling microwave radiation in 14 spectral channels of the HATPRO radiometer. In the so-called "humidity channels" which are located in the range 22.24-31.4 GHz, the random error of brightness temperature measurements are declared by the manufacturer of the instrument as 0.1 K. In the so-called "temperature channels" which are located in the range 51.26-58.0 GHz, the random error are declared to be 0.2 K. There is also a small systematic error which remains after calibration by liquid nitrogen. It can not be controlled but according to special studies does not exceed 0.5 K. The random errors of brightness temperature measurements have a direct influence on the estimation of the retrieval errors of all profiles of atmospheric parameters on the basis of the Fisher matrix calculations (Eq. 5). As noted above, the LWP retrieval errors are obtained with the help of Eq. 9. According to our earlier studies (Kostsov et al., 2018a), the bias of LWP retrievals for zenith geometry derived from cloud-free observations is very stable and constitutes 0.010 kg m⁻². The random error of the LWP retrieval has been estimated from cloud-free observations as 0.001 kg m⁻². The random errors of LWP retrieval derived from the error matrix calculations at the final iteration step of each retrieval are comparable to the estimations made on the basis of analysis of cloud-free periods and constitute in average 0.003-0.004 kg m⁻². We assume that the influence of the systematic brightness temperature error remaining after calibration is cancelled in the final LWP retrieval results by applying bias correction.

Physical retrievals imply calculations of brightness temperatures and kernels of the linearised radiative transfer equation for all spectral channels and elevation angles. Such calculations require accurate absorption models. Since start of operation of HATPRO at the observational station of St.Petersburg University, the absorption models for oxygen, water vapour and cloud liquid water were updated several times. At present the absorption by Rozenkranz (2017)is used, namely version 2019 model described its from (http://cetemps.aquila.infn.it/mwrnet/lblmrt ns.html, last access 5 May 2022).

In the present study, we slightly modified the retrieval setup in order to provide equal sensitivity of zenith and off-zenith observations to LWP, see Section 3.3 below. As a result, the LWP retrieval errors estimated from Fisher matrix are somewhat higher than reported in earlier studies for routine zenith observations and constitute about 0.006-0.008 kg m⁻².

The assessment of the uncertainty of bias values in the revised version of the manuscript was done and described in Section 4:

The uncertainties of bias assessment were estimated in the following way:

- the three-step procedure described above was repeated with the value of the threshold 0.010 kg m⁻² at step 1 while other steps were kept the same;
- the differences between bias values obtained for thresholds 0.010 kg m⁻² and 0.005 kg m⁻² were attributed to the uncertainties of the bias assessment.

The uncertainties of bias assessment averaged over all months and years for zenith direction and two elevation angles 11.4° and 14.4° were found to be 0.002 kg m⁻², 0.001 kg m⁻² and 0.001 kg m⁻² respectively. These values are shown in Fig. 6 as error bars.



Figure 6: The values of the LWP retrieval bias b_i for zenith and off-zenith geometry derived for summer months in 2013-2021. Index i designates the elevation angle (1=90°, 2=14.4°, 3=11.4°). The uncertainties of bias assessment are shown as error bars in panel (a) only.

The uncertainty of the values of the LWP land-sea contrast was obtained in the same way in Section 5.2:

The assessment of the uncertainty of the results was made similar to the assessment of the uncertainty of bias. Two values of the threshold for bias estimation were taken and the LWP contrast was derived for these two cases. The difference between the results was equal to 0.001 kg m^{-2} if averaged over all months and years. It was attributed to the uncertainty of the obtained values of the LWP land-sea contrast and is shown in Fig. 8 in the form of error bars.



Figure 8: The results of the retrieval of LWP land-sea contrast for summer months within the period 2013-2021. No scaling factors are applied. The uncertainties of the results are shown as error bars in panel (a) only.

The uncertainty of the scaling factors is discussed below as a reply to the special remark which concerns scaling factors.

The uncertainty of the scaled multi-year averaged LWP contrast values has been estimated also. Fig. 14 now contains error bars. The text describing this figure has been slightly changed, see Section 6.3:

In Fig. 14 we demonstrate a comparison of the results of the assessment of the LWP land-sea contrast based on ground-based microwave measurements with the results of the satellite observations by the SEVIRI instrument. The satellite data were taken from the study by Kostsov et al. (2021). In the mentioned study, the time period 2011-2017 was analysed which partly overlaps with the time period considered in the present work (2013-2021). So, we compare the mean monthly values of the LWP contrast averaged over these overlapping 8-year and 9-year periods. The values D_1 and D_2 obtained from ground-based measurements have been averaged jointly. The following values of scaling factor F_2 were applied: 5.3 ± 1.3 for June, 5.8 ± 1.5 for July and 7.4 ± 2.3 for August respectively (see Section 4 for derivation of these values). The uncertainty of the scaled LWP contrast values is shown as error bars in Fig. 14. It was estimated accounting both for the uncertainty of original data on the LWP contrast and the uncertainty of the scaling factor. The information on the uncertainty of the averaged SEVIRI data is not available.

Since the mean LWP contrasts for summer months are analysed, the so-called "August anomaly" should be mentioned which was revealed by the satellite observations and shows up as the practically total absence of the LWP contrast in August if compared to June and July. It should be emphasised that this "August anomaly" concerns the Gulf of Finland only; this effect is absent for neighboring large and small lakes (Kostsov et al., 2021). One can see that the ground-based measurements produce no evidence of this anomaly: the LWP land-sea contrast values for all summer months are almost the same. Moreover, the highest values are detected in August. For June and July, the results obtained from satellite observations are higher than the results obtained from ground-based measurements by 0.008-0.009 kg m⁻². The discrepancies are well within the limits determined by error bars for HATPRO data. To our opinion, the agreement between the space-borne and ground-based results for these two months can be estimated as very good. As it was mentioned above, the estimates of F_2 obtained in section 4 were the lower ones. In reality, F_2 can be larger and in this case the discrepancy between the ground-based and the satellite data for June and July will be smaller. As far as the comparison for August is concerned, the discrepancy goes far beyond the error limits, so the absence of the August anomaly effect has been verified quantitatively.



Figure 14: The estimations of the LWP land-sea contrast in the region of Neva Bay of the Gulf of Finland for summer months. The results are shown which were derived from ground-based microwave measurements by the RPG-HATPRO instrument (scaled) and from space-borne observations by the SEVIRI instrument during multi year periods. The uncertainty of the scaled LWP contrast values from HATPRO is shown as error bars

• For your cloud retrieval you set up a so-called "cloud area of interest" which is between 1 and 4 km above ground. In general, there are many shallow clouds over the sea with both base and top below 1 km which would be completely neglected by this study. This is also confirmed by the cloud base observations used in the study (see line 481). It would be important to consider using lower elevation angles for the microwave radiometer to also catch the lower clouds. Otherwise, too many clouds are just not sampled for this study and a meaningful comparison with satellites becomes nearly impossible.

Following the suggestion made by the referee, we considered using lower elevation angles and presented the results in Subsection 5.5:

5.5 Test retrievals for elevation angles 19.2° and 8.4°

It is interesting to investigate the dependence of the derived values of the LWP land-sea contrast on the elevation angle. It has been explained above that two elevation angles 11.4° and 14.4° have been selected as optimal for solving the task of detecting the LWP land-sea contrast for specific geometry of the experiment which is determined by the location of the instrument and the size of the water body. The lines of sight for these two angles intersect the area of interest over water body spanning vertically from 1 to 4 km. Despite the fact that there can be possible influence of the underlying surface on the results of microwave measurements when elevation angles are smaller than 10° , test retrievals were made for the elevation angle 8.4° . Also, test retrievals were made for the elevation which could be sufficient for derivation of a dependence on elevation angle. Both "extra" elevation angles fit well the atmospheric model compiled for the LWP contrast retrievals since the corresponding measurements still probe a significant amount of the designated area of interest (see Fig. 1).

Validation of the results for two extra elevation angles was made on the basis of comparison of the LWP contrast values derived by physical and regression algorithms. This comparison has shown that the discrepancy between the outputs of physical and regression algorithms for the angle 19.2° has the same magnitude as for the optimal angles 11.4° and 14.4° . For the angle 8.4° , the discrepancy is noticeably larger. This fact is the confirmation of the recommendation to avoid using elevation angles smaller than 10° . Nevertheless, we kept all results for analysis.

The values of the LWP land-sea contrast are plotted as a function of elevation angle in Fig. 11 for each summer month and each year separately. One can notice a clear and well pronounced dependence of the LWP contrast on elevation angle which is characteristic for all cases except two. Maximal contrasts are detected for the optimal elevation angles 11.4° and 14.4°. For "extra" angles, the contrasts are always lower (or sometimes equal to contrasts for optimal angles). Two exceptions refer to July 2014 and July 2016: in these cases the dependence on elevation angle is absent. The detected dependence can be explained by clear physical reasons. For large elevation angles, the portions of air, which are probed, are shifted up and towards the instrument. The liquid water content for high clouds usually is less than for the lower clouds, hence the contrasts should be smaller. Also, the contrast in the vicinity of the coastline is expected to be smaller. For small elevation angles, the air portion, which is probed, is shifted down and towards the opposite shore. The influence of clouds over the opposite shore can cause the decrease of mean values of the LWP contrast. One can see that in some cases the LWP contrast obtained for extra elevation angles is negative. These cases require special study, which should be based probably on the analysis of synoptic situations.



Figure 11: Retrieved LWP land-sea contrast as a function of elevation angle for June, July and August in 2013-2021. Symbols correspond to four discrete values of elevation angle $(19.2^{\circ}, 14.4^{\circ}, 11.4^{\circ}, and 8.4^{\circ})$ and are connected by lines only for illustrative purpose.

• The setup of the study lacks some comparison to land areas for the low elevation angles. It would have been good to also perform scans to the other direction (i.e. south-west) to check if the algorithm performs well over land, too. With a HATPRO microwave radiometer these bi-lateral scans can be performed easily. This would have provided a reference area to see whether

the results between zenith and slant observations are in fact caused by the different surface conditions.

We are grateful to the referee for proposing this idea. At present, we try to think over how to implement it. There is one obstacle. Our HATPRO radiometer is installed on top of a tower together with several other instruments. All instruments are powered from a stand which is located in the centre of a tower. If we simply turn HATPRO by 180°, the line of sight will meet this stand at low elevation angles. So we are now trying to solve the problem if it is possible to move HATPRO slightly aside without affecting the functionality of other instruments.

• The assumptions for the physical algorithm are very rough and the information on the forward model is quite sparse. The a-priori profiles (page 6, lines 191-192) are not described. Where do you get these profiles from, especially also the information on cloud liquid water? Which assumptions are used concerning clouds? And what are the absorption models used in the study?

We do not quite understand what assumptions are meant here. The physical algorithm is well tuned, tested and used for routine observations by the HATPRO radiometer at St.Petersburg University already for years. The reference to previous studies and information on retrieval accuracy are provided in the revised version in the beginning of subsection 3.2:

The input data for the retrievals are the values of brightness temperature of down-welling microwave radiation in 14 spectral channels of the HATPRO radiometer. In the so-called "humidity channels" which are located in the range 22.24-31.4 GHz, the random error of brightness temperature measurements are declared by the manufacturer of the instrument as 0.1 K. In the so-called "temperature channels" which are located in the range 51.26-58.0 GHz, the random error are declared to be 0.2 K. There is also a small systematic error which remains after calibration by liquid nitrogen. It can not be controlled but according to special studies does not exceed 0.5 K. The random errors of brightness temperature measurements have a direct influence on the estimation of the retrieval errors of all profiles of atmospheric parameters on the basis of the Fisher matrix calculations (Eq. 5). As noted above, the LWP retrieval errors are obtained with the help of Eq. 9. According to our earlier studies (Kostsov et al., 2018a), the bias of LWP retrievals for zenith geometry derived from cloud-free observations is very stable and constitutes 0.010 kg m⁻². The random error of the LWP retrieval has been estimated from cloud-free observations as 0.001 kg m⁻². The random errors of LWP retrieval derived from the error matrix calculations at the final iteration step of each retrieval are comparable to the estimations made on the basis of analysis of cloud-free periods and constitute in average 0.003-0.004 kg m⁻². We assume that the influence of the systematic brightness temperature error remaining after calibration is cancelled in the final LWP retrieval results by applying bias correction.

We added the information about a priori profiles in the end of subsection 3.1:

A priori profile of LWC is assumed as nearly zero profile $(10^{-8} \text{ kg m}^{-2})$ in the altitude interval (1-4 km) which simulates cloud-free conditions. In contrast, the variability of LWC is quite large which allows retrieving high range of LWP. For temperature and absolute humidity a priori profiles, we use the data from nearest radiosonde station which were averaged over several years of radiosonde launches.

We added the information about absorption models in subsection 3.2:

Physical retrievals imply calculations of brightness temperatures and kernels of the linearised radiative transfer equation for all spectral channels and elevation angles. Such calculations require accurate absorption models. Since start of operation of HATPRO at the observational station of St. Petersburg University, the absorption models for oxygen, water vapour and cloud liquid water were updated several times. At present the absorption model described by Rozenkranz (2017) is used. namelv its version from 2019 (http://cetemps.aquila.infn.it/mwrnet/lblmrt_ns.html, last access 5 May 2022).

Rosenkranz, P. W.: Line-by-line microwave radiative transfer (non-scattering), Remote Sens. Code Library, https://doi.org/10.21982/M81013, 2017.

• I'm not convinced by the definition of the scaling factors F1 and F2. You are assuming that the vertical distribution of clouds is the same over all the years. Other factors like air or water temperature anomalies, as well as

the precipitation patterns (dry/wet months) will strongly influence the cloud distribution of a special month which makes it very difficult to believe that these scaling factors are stable for a special month. Did you see interannual differences for the period of the cloud base height dataset? If so, this would add uncertainty to the scaling factors. Furthermore, in Figure 6 it can be seen that the scaling factor depends very much on the location where the cloud base height has been taken. Also, it can be seen that there is quite a strong monthly variability. Do you have an explanation for this behaviour?

We agree with the statement that scaling factors are not expected to be stable for a special month. And of course we agree that the precipitation patterns can influence the cloud distribution. We admit that Fig. 8 showing scaled monthly values for each year can be to some extent misleading because we apply average scaling factors to specific month of a specific year. Therefore we removed this figure and relevant discussion. We keep Fig. 10 since we believe that the results of comparison averaged over nine years are robust and valuable. In the revised version we emphasise that our comparison with satellite data which uses scaling factors is based on several strong assumptions and we estimate the uncertainty of LWP contrast values averaged over nine years.

In order to provide a kind of validation of scaling factors derived from statistics collected by human observers at meteorological stations we compared scaling factors from meteorological stations with the factors derived from ceilometer measurements. We also added the discussion of the uncertainty of scaling factors:

In order to provide a kind of validation of scaling factors derived from meteorological data we calculated scaling factors using the CBH measurements made with a ceilometer. The CHM 15k ceilometer was in operation at the observational site of St.Petersburg University in 2013, 2014 and the first half of 2015. It was installed on the metal tower on the roof of the building just nearby the HATPRO microwave radiometer. The full description of the CHM 15k ceilometer can be found on the web page of a manufacturer (<u>https://www.lufft.com/products/cloud-height-snow-depth-sensors-288/ceilometer-chm-15k-nimbus-2300/</u>, last access 6 May 2022). The CBH values were derived by the original data processing algorithm embedded in the instrument. For the purpose of comparison, the selection of CBH data for calculation of scaling factors was done exactly in the same way as the selection of data provided by human observers at meteorological stations.

Resulting monthly values of F_1 and F_2 for daytime are shown in Fig. 13. Since scaling factors obtained from the ceilometer observations appeared to be very similar to factors at the meteorological station St.Petersburg, they are shown in one plot Fig. 13a. The factors F_1 and F_2 from ceilometer observations are practically indistinguishable, therefore only the F_2 factor is shown in this plot. Comparison of F_1 and F_2 obtained from the St.Petersburg station records is given in Fig. 13a and demonstrates also very similar values for all months. Minimum monthly values of scaling factors from all data sources are observed in spring and summer, maximal values – in autumn and winter. In spring, summer and early autumn, the differences between the multi-year average values of F_2 from meteorological station and the values of F_2 for specific years are the smallest if compared to late autumn and winter. This fact is the strong indication that the cloud statistics are stable for these months. It is surprising that for June and July the results obtained from ceilometer measurements in 2013, 2014 and 2015 are nearly identical.

Comparison of scale factor F_2 derived from the records of all three meteorological stations is shown in Fig. 13b. One can see that the main feature of intra-annual variability is the same for all stations: minimal values in spring and maximal in late autumn. Apparently, this behavior is due to the predominance of the lowest clouds in late autumn, and of the medium and high clouds – in spring. But there are also noticeable differences. First, while F_2 for the St.Petersburg station is nearly constant from March to September, F_2 for the Kronstadt and Lomonosov stations increases during this period. From December to April, the values of F_2 for all three stations are very similar. From May to November, there is noticeable difference between the values obtained at St.Peterburg station and two other stations. For Kronstadt and Lomonosov, the scaling factor is approximately 1.5-2.5 times higher than for St.Petersburg.

Comparison of Fig. 13a with Fig. 13b leads to several principal conclusions. First, the scaling factors are essentially different in summer and autumn for so-called "continental" and "marine" locations. Second, the location of the HATPRO radiometer can be attributed to the category of "continental" locations. And third, while for "continental" locations there is some evidence of the stability of scaling factors for specific months, we can not

prove it for "marine" locations. As a result, the problem arises what scaling factor to choose and how to estimate the uncertainty of chosen factor. Since the main part of the line of sight of the radiometer passes over water body, it is reasonable to choose the scaling factor obtained at marine locations. The average scaling factors derived from the data obtained at the two meteorological stations Lomonosov and Kronstadt are 5.3, 5.8, and 7.4 for June, July, and August respectively. These values have been chosen for scaling the LWP land-sea contrast data (see Section 6 below). The half difference between these values and the correspondent values from the "continental" station St.Petersburg seems to be reasonable uncertainty estimate. So finally we have the following data for F_2 : 5.3±1.3 for June, 5.8±1.5 for July and 7.4±2.3 for August.



Figure 13: (a) Scaling factors F_1 and F_2 derived from the data of meteorological observations of the cloud base height at the St.Petersburg station in 2011-2017 (average values) and from ceilometer observations in 2013, 2014 and 2015 at the location of the HATPRO radiometer. (b) Scaling factor F_2 derived from the data of meteorological observations of the cloud base height at three stations in the vicinity of the radiometer (see the legend) in 2011-2017 (average values).

• Did you compare your LWP from the physical retrieval with statistical approaches? I would be interested to see whether there are differences, as you provided a new (physical) algorithm here.

In the original version of the manuscript, we deliberately did not present the comparison of the results obtained by physical approach with the results obtained by regression approach because it was not the main focus of the work. However we agree with the referee that it is very important

comparison. Since the esteemed referee attracted attention to this issue, we clarified it in the revised version as follows:

5.4 Cross-comparison of the LWP contrast values derived by the physical algorithm and by the regression algorithm as a means of validation of the obtained results

We would like to discuss briefly the problem of choice of a retrieval algorithm (physical or regression) for the specific task which we solve in this study and the problem of validation of obtained results. The LWP contrast values for 2013 and 2014 obtained by the regression algorithm in the previous study (Kostsov et al., 2020 and Fig. 18 therein) are of the same range as ones produced by the physical approach in the present work. As one can see in Fig. 6, the years 2013 and 2014 are somewhat special: the LWP retrieval bias is minimal and comparable for zenith and off-zenith observations. It is no wonder that both algorithm work well. The situation is completely different for the years 2015-2021 when the LWP retrieval bias values for off-zenith observations are considerably larger. In order to compare the results produced by the two algorithms we made two tests. In the first test, we applied the regression algorithm to the HATPRO measurements which successfully passed quality control (convergence of the physical retrieval process and spectral residual check). In the second test we applied regression algorithm to all measurements (no quality control at all). It is important to emphasise that in both cases the bias of the LWP retrievals by regression method was estimated from measurements selected by the physical method. The outcome was quite demonstrative. In the first case, the results produced by the physical and regression algorithms were in good qualitative and quantitative agreement. They are demonstrated in Fig. 10, panels (a), (c), and (e). One can see the overall very good agreement with only two noticeable deviations of the results obtained by regression algorithm from the results of the physical algorithm (July 2016, August 2013). In the second test, the results obtained by the two algorithms were completely different and they are not shown. These tests clearly indicated the superiority of the physical algorithm in the problem of assessment of the LWP contrast. As it was noted in the beginning of Section 2, the identification of cloud-free periods of time and quality checks are impossible using the results obtained by the regression method. Therefore, it is necessary to emphasise once again that for the data set of HATPRO measurements, which we process in the present study, the application of the regression algorithm only would have produced wrong results.

Comparison of the results obtained by different algorithms can be a valuable means of cross-validation. A vivid demonstration of such cross-validation has been presented in the study by Kostsov et al. (2018a). In this study a special case of ground-based measurements by HATPRO radiometer after a rain event was considered. After rain, the radome of microwave instrument is wet for some time. During this period of time measurements are erroneous. Kostsov et al. (2018a) have shown that the discrepancy between the outputs of regression and physical algorithms is maximal during a rain and becomes smaller and smaller after a rain event while water evaporates from the radome. This effect clearly demonstrates that controlling the discrepancy between the outputs of regression and physical algorithms can be a means of validation of the final results. This statement refers not only to an "after a rain" period but has a general character and can be applied to different sophisticated situations and problems like the problem of detecting the LWP land-sea contrast. That is why, one can consider the good agreement of LWP contrast values produced by regression and physical algorithms as a successful validation of the obtained results.

In order to get one more confirmation of the validity of the obtained results, we processed the HATPRO data applying the "standard" atmospheric model which is used in routine zenith microwave observations and is characterized by the cloud altitude range 0.3-5.5 km. The data processing procedure was the same as for the model with cloud altitude range 1-4 km, with two exceptions:

- the threshold for bias assessment was taken as 0.015 kg m-2 since the "standard" model has larger a priori uncertainty of cloud liquid water and hence larger bias;
- the retrieval setup was not specially tuned to provide equal sensitivity of zenith and off-zenith measurements to atmospheric parameters, the retrieval setup for the model with cloud altitude range 1-4 km was used without any modifications.

The results of the derivation of the LWP land-sea contrast with the "standard" model are presented in Fig. 10, panels (b), (d), and (f). One can see that the discrepancies between the outputs of physical and regression algorithms are noticeably larger than for the "1-4 km" model. Also, the differences between D_1 and D_2 values for both algorithms are very much larger than ones obtained for the "1-4 km" model. These two facts indicate that in case of "standard" model the results are very much less self consistent than for the "1-4 km" model. Comparison of left and right panels in Fig. 10 leads to the conclusion that the modification of "standard" model for the specific task of detecting the LWP land-sea contrast was the correct decision.



Figure 10: Comparison of the LWP land-sea contrast values (D_1 and D_2) obtained by the physical algorithm and by the regression algorithm for June (a, b), July (c, d) and August (e, f) in the period 2013-2021 and for two cloud altitude range models: 1-4 km (a, c, e) and 0.3-5.5 km (b, d, f).

• For the LWP bias correction (Figure 7), why are there sometimes considerable differences between zenith and off-zenith observations, and sometimes not (e.g. 2020 in June vs. July?). Are you sure that your bias correction algorithm is working properly? What might be the reason for these differences?

We agree with this remark and we added the discussion of the variability of bias values in Section 4:

We tried to find the reasons for the variability of bias values for off-zenith geometry. The primary guess was the influence of different synoptic situations, namely the situations with different integrated water vapour (IWV). However, this guess was not confirmed. As shown in Fig. 7a, there is no noticeable correlation between the monthly mean values of bias b_2 and monthly mean values of IWV during the period 2013-2021. The important notice should be made: we calculated mean IWV values exactly for the time periods which were selected for bias assessment. In Fig. 7a one can notice large inter-annual variability of IWV for all summer months. Lowest mean IWV values are detected in June, and the highest values are detected in July. We made an attempt to find a correlation between monthly mean values of bias b_2 and monthly mean values of temperature at the ground level during the period 2013-2021, but no noticeable correlation has been found. As a result, the conclusion was made that the influence of synoptic situation on LWP bias was not detected.

Another idea about the reason for off-zenith bias variations was related to possible horizontal inhomogeneities of temperature in the vicinity of the radiometer. It has been already noted that the radiometer is

installed on the roof of the building which is heated by solar irradiance. The building is about 200 m long and the line-of-sight passes directly over it. Fig. 7b shows the values of the LWP retrieval bias b_2 for summer months in 2013-2021 as a function of mean value of the temperature horizontal difference ΔT at 100 m altitude near the radiometer for these months. This temperature difference was derived from the temperature profiles which were retrieved using zenith and off-zenith geometry. Of course, one should keep in mind that the spatial resolution is very poor, but nevertheless this temperature difference can be used either an indicator of horizontal temperature gradients or an indicator of some effects which interfere in the retrieval process. The assessment of correlations between b_2 and ΔT using the Fisher criterion for small number of samples has shown that correlations in July and August are statistically significant. The correlation is also statistically significant if the entire summer period is analysed without division by months. So we accepted the hypothesis that the reason for the variability of LWP bias for off-zenith observations can be a temperature horizontal inhomogeneity in the close vicinity of the radiometer. Probable mechanism could be the following: under conditions of considerable temperature inhomogeneity, the temperature error propagates into the LWP error and the LWP bias increases.



Figure 7: (a) The values of the LWP retrieval bias b_2 for summer months in 2013-2021 as a function of mean value of IWV for these months. (b) The values of the LWP retrieval bias b_2 for summer months in 2013-2021 as a function of mean value of the temperature horizontal difference at 100 m altitude near the radiometer for these months. Dashed lines demonstrate linear fits. The values of correlation coefficient are given as r.

```
Minor comments:
- Page 2, lines 40-46: Too much detailed information
```

We completely removed the presentation of scanning radiometers. Instead, we added brief discussion of the importance of studying land-sea contrasts of atmospheric parameters.

- Page 5, line 125: I would use the term "approach" instead of "algorithm"

The term "algorithm" was replaced by the term "approach".

- Page 5, line 145: What do you mean by "model form"?

In order to make it clear, we changed the sentence in the following way:

The applicability of the physical method to the problem of the LWP and IWV retrieval by two-channel radiometers implies that the a priori profiles of pressure, temperature and humidity are available from external data sources and the cloud liquid water content (LWC) profile is taken from some statistical or numerical cloud model.

- Page 12, lines 315-316: Why do you think that the LWP contrast is the same for cloud scenes with different cloud base heights? I don't think that is a valid assumption!

We believe that in the considered specific case this assumption is pretty good due to two reasons. First, the difference in CBH for low and medium clouds is less than 700 m, so the LWP contrasts are not expected to differ considerably. And second, the frequency of occurrence for high clouds is much less than of low and medium clouds, therefore the contribution of error caused by different LWP contrasts for high clouds will be small. In the revised text we wrote this explanation:

However, to achieve this goal, one additional assumption should be made: the mean values of the LWP contrast for cloud scenes with different CBH are assumed to be similar:

$$D_{medium} = D_{low} = D_{high} \tag{24}$$

We believe that in our case with the quite large cloud altitude range of interest (1-4 km) this assumption is pretty good due to two reasons. First, the difference in CBH for low and medium clouds is less than 700 m, so the LWP contrasts are not expected to differ considerably. And second, the frequency of occurrence for high clouds is much less than of low and medium clouds, therefore the contribution of error caused by different LWP contrast for high clouds will be small.

- Page 17, line 452: I don't understand what you want to say here. Do you mean that the sensitivity is instrument specific? If so, then please write it that way.

No, we just mean that the manipulations with the assignment of measurement error values can not increase the sensitivity because we can not use the error value smaller than the quantity which is specific for our instrument and is declared by the manufacturer. In order to avoid confusion we decided to remove the unclear sentence.

Summary of main revisions:

• The structure of the manuscript has been changed considerably: the application of scaling factors to the obtained LWP contrast values is now a separate part of study (Section 6) which refers only to comparisons with the satellite data (the conclusions have been changed accordingly). The table of contents now is the following:

1 Introduction 1.1 Background 1.2 Motivation 1.3 Novelty 2 Formulation of the inverse problem 3 Retrieval strategy 3.1 Elevation angles and atmospheric model 3.2 Error sources 3.3 Retrieval setup and sensitivity functions 4 Assessment of the LWP retrieval bias 5 Main results of the estimation of the LWP land-sea contrast 5.1 Information on data processing 5.2 General overview of the results 5.3 Trend assessment and the problem of analysis of diurnal evolution of the LWP land-sea contrast 5.4 Cross-comparison of the LWP contrast values derived by the physical algorithm and by the regression algorithm as a means of validation of the obtained results 5.5 Test retrievals for elevation angles 19.2° and 8.4° 6 Comparison of ground-based and satellite data 6.1 General assumptions and the concept of scaling factors 6.2 Assessment of the scaling factors

6.3 Results of comparison 7 Summary and conclusion

- The extensive uncertainty analysis has been provided.
- Ceilometer data were added for verification of scaling factors.
- The results have been validated using the approach of cross-validation by comparing the outputs of the physical and regression algorithms.
- The "standard" model of cloud altitude range 0.3-5.5 km was applied to data processing and the results were analysed
- Two extra elevation angles were considered and the results were analysed.

Vladimir Kostsov (corresponding author)

13 May 2022