

Interactive comment on “Estimation of PM_{2.5} Concentration in China Using Linear Hybrid Machine Learning Model” by Song et al.

Response to RC2:

referee’s comments are given in blue,

our responses are given in red.

RC2: The study by Song et al. presents a linear hybrid machine learning model to estimate regional PM_{2.5} distributions from Himawari-8 AOD observations. In the manuscript, the authors stated that the proposed RGD-LHMLM method outperforms than three conventional machine learning methods and can perform accurate estimations.

Response: We would like to thank the editor and referee for carefully reading the manuscript and providing detailed and constructive comments, which have helped a lot in improving the manuscript. We quote each comment below, followed by our response.

RC2: The paper does not provide enough evidence to support the major conclusions. The proposed method does not have generality in terms of target period as the training relies fully on the Himawari-8 AOD data over 2019. What about for the PM_{2.5} estimation in some other years? To have a completely new training? Since the authors did not perform any PM_{2.5} estimation for other years, I'd like to ask whether the training data already includes all possible cases between satellite AOD and ground

PM_{2.5}. Even if by including more satellite AOD datasets over a longer period, it can still be questionable whether the selected training data are considered to be representative.

Response: Our research is mainly based on two decision tree models and a neural network model to build a semi-explanatory estimation model. This semi-explanatory nature is mainly reflected in the analysis of the feature importance. In other words, deep learning models are often seen as black boxes with low interpretability. Therefore, we want to use the feature importance obtained by the decision tree model and the computational power of deep learning to build the semi-explanatory estimation model. Since DNN has the highest weight coefficient in the final hybrid model, we believe that this assumption has been realized to a certain extent.

Given factors such as climate change and human controls, the data from just one year cannot represent all possible scenarios between AOD and PM_{2.5}. However, the monthly and hourly variations contained in the data are very significant, and the number of samples retrieved from this data also meets the requirements of machine learning. So, we believe that one year's datasets can provide better training for the model; on the other hand, the Himawari-8 data was updated when we started this study. Based on the core thesis of this research and the above two reasons, we have selected the Himawari-8 AOD of 2019 for training.

In future research, we will extend the time period to study the change trend of PM_{2.5} on a long time scale.

RC2: Section 2: Please include information about data quality of all datasets used for training (e.g., satellite AOD, ground-based data, meteorological data). The current training assumes that Himawari-8 AOD and ground PM_{2.5} data are true values, which in reality, is not true. Thus, please discuss how much impact of their data quality on the model performance in a quantitative way, i.e., what is the error propagation of these training data?

Response: Ground PM_{2.5} can be observed by two methods. The first is an automatic analysis method including trace element oscillation balance method or β -ray attenuation method. The other is manual gravimetric method (HJ618). The observed data are calibrated and quality-controlled according to national standards GB 3095-2012 (China's National Ambient air quality standards)(China, 2012).

Himawari-8 AOD is obtained by an aerosol retrieval algorithm based on Lambertian-surface-assumed developed by Yoshida et al. (2018). Himawari-8 AOD was compared with the AOD data of AERONET (Aerosol Robotic Network)(Zhang et al., 2019), the results show that they are consistent ($R^2=0.75$), RMSE and MAE were 0.39 and 0.21, respectively(Wei et al., 2019). In the study, we selected AOD with strict cloud screening, that is, AOD data with low uncertainty.

Uncertainty estimation of ERA5 data has described in detail in the following website: <https://confluence.ecmwf.int/display/CKB/ERA5%3A+uncertainty+estimation>.

To sum up, the data we used have been quality-controlled and can represent the real situation to some extent. As commented by Referee #2, we have added bias analysis.

There is an irretrievable error between the AOD or $PM_{2.5}$ and its true value. As shown in figure 4, the average bias of the mixed model in different $PM_{2.5}$ concentration ranges was analyzed, and the result is shown in the figure 4. when the $PM_{2.5}$ concentration is less than $60 \mu g/m^3$, the average bias of the model is less than 0. As the $PM_{2.5}$ concentration increases, the model deviation gradually increases. In other words, when the $PM_{2.5}$ concentration is small, the predicted value of the model will generally overestimate $PM_{2.5}$, and when the $PM_{2.5}$ further increases, it will underestimate the $PM_{2.5}$ concentration.

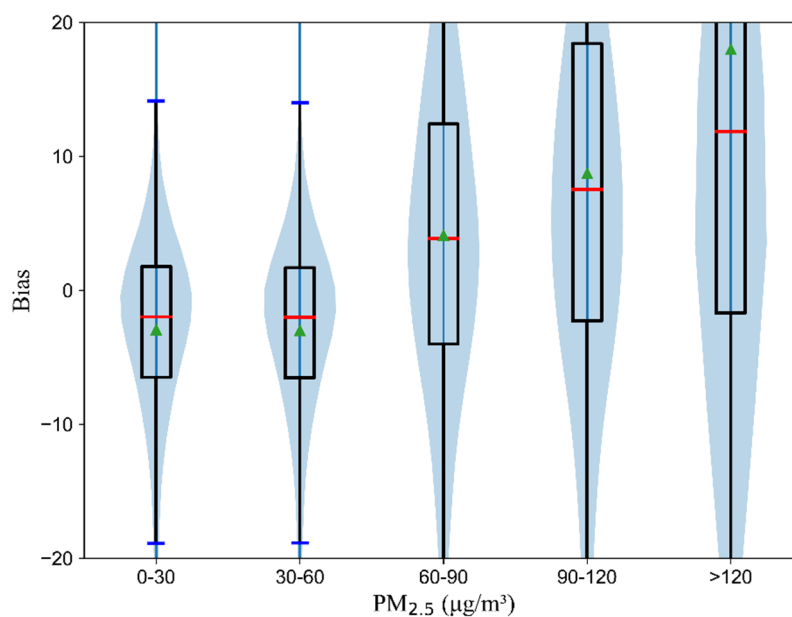


Figure 4 Bias between model predicted values and label values

In the machine learning algorithm, the error of the model will be corrected continuously according to the label value during the training. As is known to all, the data calculated by the model are mainly related to the factors with high feature importance. In this model, the factor with the highest importance of feature is AOD. That is to say, when there is data error in AOD, it will be transmitted to the forecast result, and when there is data error in PM_{2.5}, it will interfere with the error correction of the model. Based on the above discussion, we believe that the errors in the model are mainly caused by the errors of AOD and PM_{2.5} when the pollution is relatively serious. In the case of low PM_{2.5} concentration, this error transfer phenomenon is relatively less.

RC2: These machine learning based models are sort of “black boxes”, which means that it would seem unclear what a physical relationship between input and output are learned, particularly to readers who are not familiar with PM_{2.5} estimation. I would suggest to reformulate the beginning of Section 3 by adding mathematical explanation for such context.

Response: It is a good suggestion. We will add the mathematical expression of the sub-model in the revised manuscript.

$$\begin{aligned}
 PM_{2.5i,j} = & AOD_{i,j} + BLH_{i,j} + RH_{i,j} + TM_{i,j} + LL_{i,j} + LH_{i,j} + SP_{i,j} \quad (1) \\
 & + RAIN_{i,j} + U_{10i,j} + V_{10i,j} + PD_{i,j} + HEIGHT_{i,j} + LON_{i,j} \\
 & + LAT_{i,j} + MONTH_{i,j} + HOUR_{i,j}
 \end{aligned}$$

Formula (1) is applicable to RF, GBRT and DNN. Where $PM_{2.5ij}$ is the $PM_{2.5}$ at time i on station j .

RC2: Section 3: Please specify explicitly the input/output of the training(s).

Response: The input is 16 features including AOD (aerosol optical depth), surface relative humidity (RH, expressed as a percentage), air temperature at a height of 2 m (TM, expressed as K), Wind speed (U10, V10, in m/s), surface pressure (SP, in Pa), boundary layer height (BLH, in m) and cumulative precipitation (RAIN, in m) at 10 m above the ground, high and low vegetation index (LH, LL), ground elevation data (DEM), population density data (PD), longitude, latitude, month and hour.

The output is $PM_{2.5}$ concentrations.

RC2: Section 3: Please describe in detail the linear combination of the three optimal sub-models.

Response: The coefficient is determined by multiple linear regression model. Firstly, we use three sub-models to calculate the predicted value under the corresponding model. Then, multiple linear regressions are performed between the calculated predicted values and the label values in the original data. Finally, the output coefficients and intercepts of the multiple linear regression model are taken as the parameters of the **RGD-LHMLM**.

RC2: Page 8, Line 13: According to Table 1, I do not notice any

“significant” improvement from an individual sub-model to a linear-mixed model. I would prefer to say slightly improved, as can be seen also from Figure 3.

Response: We have revised the description in the revised manuscript.

RC2: Section 4: The current manuscript only discusses the monthly performance of the linear-mixed model. But as far as I know, the usage of geostationary data such as Himawari-8, is especially beneficial to improving the understanding of daily variation of PM_{2.5}. If this study focuses solely on the monthly/seasonal variation, why not use MODIS AOD data over a longer period?

The advantage that AHI can provide high temporal resolution data is also discussed, but for some reasons it was not included in the previous version of the manuscript. In the revised manuscript we have added this content. The results are shown in the figure below.

Figure 6 shows the scatterplot fitted with the inversion results of the mixed model from 9:00-17:00 Local Time. The model R^2 ranged from 0.556 to 0.88 at different times. Except for 17:00 when the model had the worst performance, the model R^2 exceeded 0.7 at other times, indicating that the model had a good performance. The optimal performance time is 13:00, R^2 is 0.88. According to the results, the hourly differences in model performance were significant.

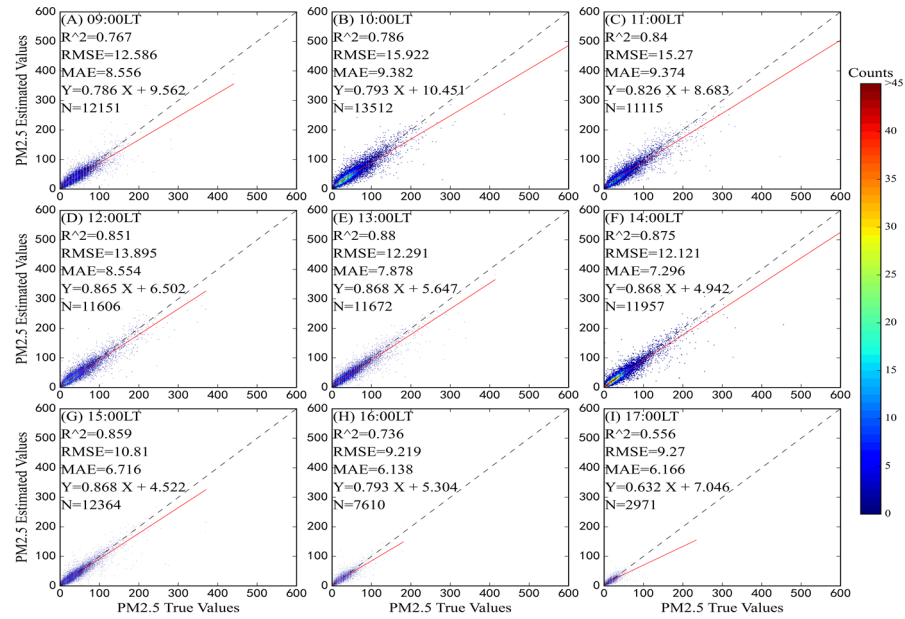


Figure 6 Hourly validation of model performance

The temporal distribution of PM_{2.5} is shown in Figure 10, The PM_{2.5} concentration began to rise from 9:00, and peaked at 55.65 $\mu\text{g}/\text{m}^3$ between 10:00 and 11:00 every day. After that, it maintained a high concentration until 15:00, and began to decrease. In the most polluted areas of China, the peak concentration of PM_{2.5} can reach 85.05 $\mu\text{g}/\text{m}^3$, while the peak in the less polluted areas is only about 40 $\mu\text{g}/\text{m}^3$. On a national scale, daily PM_{2.5} concentrations fluctuate little.

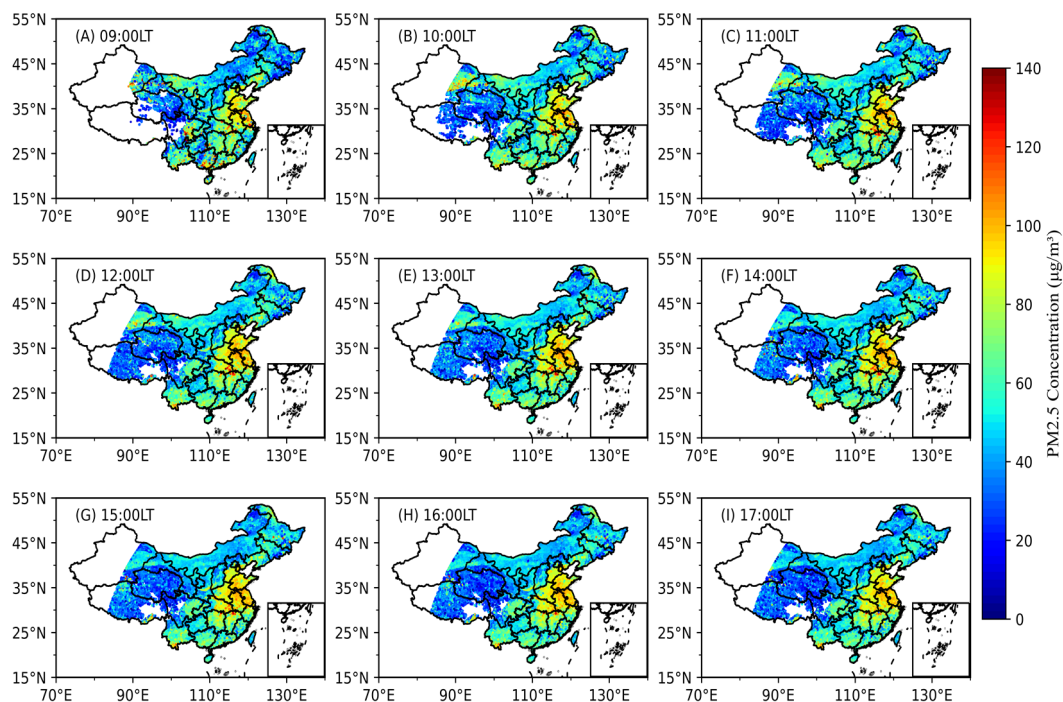


Figure 10 Hourly distribution of PM_{2.5} in China in 2019

RC3: Figure 5: It seems that the estimated PM_{2.5} are in general lower than the “true” values. Is this underestimation pattern related to Himawari-8 data? Please expand the relevant discussion.

Response: That's a very good question. As we all know, AOD is the integral of the aerosol extinction coefficient from the surface to the top of the atmosphere, and PM_{2.5} is small aerosol particles close to the surface which could float in the atmosphere for long period. Thus, PM_{2.5} contributes a significant portion of AOD, and the correlation between AOD and PM_{2.5} has a strong spatial and temporal variation (Ma et al., 2016; Xu et al., 2021). Combined with the feature importance of AOD and the above content, We believe that AOD has a very important influence on the model prediction values. In some studies,

however, Himawari-8 AOD has been found to be underestimated(Zang et al., 2018). Therefore, we believe that the underestimation of PM2.5 is closely related to the value of AOD. But, we need to note that the impact of meteorological parameters on the relationship between PM2.5 and AOD cannot be ignored (Gupta et al., 2006). So, the underestimated PM2.5 predicted value is greatly related to the influence of AOD, but the influence of meteorological factors should also be considered.

RC3: Figure 6: Please include importance of input parameters to DNN as well.

Response: As is answered in the first question, the feature importance of deep learning is difficult to obtain, and we only use the strong computational power of DNN to build the model. The DNN input is the same as the tree model, and the importance of the features in the tree model can explain which features are more important. In future research, we will study how to obtain the feature importance of DNN, and isolate them for analysis.

RC3: Section 4: An error characterization of model estimation is missing. Please discuss (quantitatively if possible) error contributions of the input parameters (at least including dominant error sources) to the final output.

Response: That's a tremendously good suggestion. We believe that the greater the importance of a feature in a model, the greater its contribution to the error of the model when there is an error. Perhaps this is not a

sufficient explanation. In future studies, we will try to discuss the error contribution of input parameters to the model.

RC2: Page 15, Line 19: Any examples of “other satellite data”? If other satellite observations are considered, how do you optimize the model training, as the current training is only based on Himawari-8 data.

Response: Some studies used “other satellite data”, such as FY-4A(Mao et al., 2021), MODIS(Wei et al., 2021b), GOIC(Tang et al., 2019) and VIIRS(Yao et al., 2019).

“If other satellite are considered”, I have two understandings. If it means not using Himawari-8 AOD data but using other satellite data for training, then the optimization process of the model is no different with Himawari-8. If this means using both Himawari-8 AOD data and other satellite data for training, then I think it's best to merge the two AOD datasets. In other words, the two kinds of AOD data are unified into one kind of integrated AOD data through linear regression or other algorithms. There are two benefits to doing this: firstly, The integrated AOD data can improve the data coverage to the surface; secondly, reducing the number of features can reduce the training time of the model and improve the efficiency.

We fully agree with the Referee #2's opinion, and our follow-up work will be done through multi-satellite data fusion.

We have compared other studies with our own and listed the results in Table 1:

Table 1

Model	R ²	RMSE	MAE	Reference
Stacking model	0.85	17.3	10.5	(Chen et al., 2019)
Two-stage random forests (YRD)	0.86	12.4	/	(Tang et al., 2019)
LME (BTH)	0.86	24.5	14.2	(Wang et al., 2017)
GTWR	0.78	20.10	/	(Xue et al., 2020)
STLG	0.85	13.62	8.49	(Wei et al., 2021a)
RGD-LHMLM	0.84	12.92	8.01	This paper

reference

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