

$P = \text{new parameter}$



Gedzelman 1988

25 Altocumulus (Ac) clouds (Korolev et al., 2017) are often mixed-phase clouds that consist predominantly of supercooled liquid water droplets and, hence, are highly susceptible to the effect of ice nucleating particles (INPs). They therefore mark a natural laboratory for studies of heterogeneous glaciation in environments where efficient INPs are present. Polarization lidar measurements can be used to investigate the effect of mineral dust (Ansmann et al., 2005, 2008, 2009, 2019; Seifert et al., 2010), volcanic ash (Seifert et al., 2011), or other aerosol particle types (Kanitz et al., 2011; Seifert et al., 2015; Cheng and Yi, 2020; Radenz et al., 2021; Yi et al., 2021) acting as INP in the heterogeneous glaciation of altocumulus clouds.

30 However, active remote sensing of mid-level and high clouds with lidar at visible wavelengths requires a clear line of sight between the instrument and the target cloud. Particularly low-level liquid water clouds, that ~~already~~ attenuate the emitted laser light ~~rather~~ close to the ground, are a major obstacle for long-term observations of mid- and upper-level clouds. If a lidar was to be deployed for a field experiment or long-term observations that are focused on mid-level or high clouds, it is advisable to carefully assess potential locations. Here, spaceborne lidar observations of clouds, for which the light-attenuation of low-level clouds has no effect on the detection of mid-level and high clouds, are used to assess where ground-based lidar measurements of altocumulus and cirrus are least affected by low-level cloudiness. The same methodology has already been used for finding locations at which tropospheric clouds are likely to have a minimum disturbing effect on the observation of Polar Tropospheric Clouds with ground-based lidar (Tesche et al., 2021). The used data and methodology is presented in Section 2. The results are shown and discussed in Section 3. The paper concludes with a summary in Section 4.

*Hypothesis
Experimentality?
Range?*

2 Data and methodology

2.1 CALIPSO cloud profile data

The Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) lidar aboard the CALIPSO satellite (Winker et al., 2009) is an elastic-backscatter lidar that operates at 532 and 1064 nm. Since June 2006, CALIOP has become an invaluable tool for monitoring the three-dimensional distribution of aerosols and clouds in the troposphere and stratosphere. CALIPSO lidar measurements have been used to study the occurrence and properties of clouds. Such studies are often complemented with measurements of other instruments in the A-Train satellite constellation such as radiometers or cloud radar.

For this study, information on the extent and type of tropospheric clouds with a resolution of 5 km along the CALIPSO ground track and 30-m height bins below 8.2 km height (60-m height bins between 8.2 and 20.2 km height) is taken from the CALIPSO level 2 version 4.20 Cloud Profile product (05kmCPro.v4.20). The extracted parameters are time, latitude, longitude, the day-night flag, and the cloud type as provided in the Vertical Feature Mask. The data considered here cover the years 2010, 2011, 2012, 2015, 2018, and 2019. Table 1 gives an overview of the number of CALIPSO lidar profiles included in this study.

2.2 CATS cloud profile data

Based on the International Space Station (ISS), the Cloud-Aerosol Transport System (CATS, McGill et al. 2015) performed elastic-backscatter measurements at 1064 nm from February 2015 to October 2017 (Pauly et al., 2019). In contrast to CALIPSO,



the orbit of the ISS has an inclination of 51.6° and is not sun-synchronous. Therefore, CATS observations are restricted to latitudes ^{equatorward} lower than 51° but allow for covering different times of the day. This latter capability is used here to assess the representativeness of cloud observations at the fixed CALIPSO times of 0130 and 1330 PM, ^{equatorward consecutive granules.}

Two Level 2 CATS-ISS products were used to document the diurnal variability of clouds. The first is the L2O Profile product (05kmPro.v3.01), (Yorks et al., 2016a) which documents vertical profiles (at 60 m resolution) of various atmospheric properties every 5 km along the ISS ground track, ^{These are} mainly derived from the attenuated backscatter profiles measured by the CATS lidar at 1064 nm. Profiles of feature type (Feature_Type_FOV, 1 indicating a cloud), and of cloud phase (Cloud_Phase_Fore_FOV, 3 indicating ice) for a given time, latitude, and longitude, were used to derive a mask for ice clouds (Yorks et al., 2016b). From the L2O Layer product (05kmLay.v3.01), which documents layer-integrated properties for atmospheric features found in profiles of 1064-nm attenuated backscatter, the feature type (Feature_Type_Fore_FOV, 1 indicating a cloud), base and top altitude and pressure for each detected layer, and the profile opacity indicator (Percent_Opacity_Fore_FOV) were used to document the presence of altocumulus clouds. ^{See} These clouds were identified following the same criteria as in the CALIPSO scene classification (Liu et al., 2005): a non-opaque cloud layer with a top pressure between 440 and 680 hPa. For both products, it was required that the quality scores, that range between 0 and 10, have to be larger than 5 for cloud identification.

A comparison between the fractions of cirrus and altocumulus clouds as inferred from the data sets of CALIPSO and CATS following the approaches described above is presented in the Appendix.

2.3 Determination of cloudiness

The CALIPSO retrieval separates between eight cloud types (Liu et al., 2009): (i) low overcast, transparent; (ii) low overcast, opaque; (iii) transition stratocumulus; (iv) low, broken cumulus; (v) altocumulus (transparent); (vi) altostratus (opaque); (vii) cirrus (transparent); and (viii) deep convective (opaque). For each profile, the number of height bins in which a certain cloud type was identified is summed up. The thus simplified data set is then used to assess if a certain cloud type is present (total count per profile larger zero) or not.

In the analysis, two scenarios are considered. In the first ~~step~~ ^{depict}, the dataset is screened for cloudy profiles that show cirrus in the absence of opaque low- and mid-level clouds. These cases represent conditions under which cirrus could be detected by ground-based lidar without interference of lower clouds and will be referred to as isolated cirrus. The second setup refers to the possibility of detecting mid-level clouds with a ground-based lidar by screening the data set for profiles in which transparent altocumulus is identified without the presence of any of the four low-level cloud types below. Underlying low-level clouds need to be detected to achieve the aim of this study. Hence, opaque altocumulus is not included in the analysis of mid-level clouds.

The number of thus selected profiles is mapped on a grid of 2.50° longitude by 1.25° latitude to assess the occurrence rate of conditions for which a ground-based instrument could observe mid-level and high clouds without attenuation of the laser beam by clouds at lower levels.

The day-night flag is used to assess changes in cloud occurrence for CALIPSO overpasses during day and night. The annual variation is studied by compiling maps for the months December, January, February (DJF); March, April, May (MAM); June,



90 July, August (JJA); and September, October, November (SON). The number of profiles in the different categories is given in
Table 1 to provide an overview of the considered volume of data.

3 Results

3.1 Cirrus clouds

An overview of the occurrence of isolated cirrus as identified from six years of CALIPSO lidar measurements is provided
in Figure 1. The land regions with the highest fraction of ^{cloud-free} such CALIPSO profiles of 0.5 or larger are the Tibetan plateau,
north-eastern Africa (Chad, Egypt, Libya, Sudan), Saharan Africa, California, northern Chile, and western Antarctica. Over
water, the largest fractions are found over the Caribbean, the western Indian ocean, as well as in two bands north and south
of the intertropical convergence zone (ITCZ). The distribution in Figure 1a changes considerable if the number of CALIPSO
profiles that show isolated cirrus is normalized by the number of cirrus-containing cloudy profiles (Figure 1b) rather than all
cloudy CALIPSO profiles (Figure 1a). The absolute number of cirrus-containing CALIPSO profiles in Figure 1c shows that
regions with a high coverage of isolated cirrus in Figure 1a and b, such as north-eastern Africa and California, actually feature
a rather low occurrence rate of cirrus-containing CALIPSO profiles. Combining the information in Figure 1 reveals that the
land sites with the best temporal coverage for observing isolated cirrus clouds from ground have to feature (i) a large ratio of
cirrus observations in the absence of low- and mid-level clouds with (ii) a high occurrence rate of cirrus-containing profiles.

105 A separation with respect to CALIPSO observations during-day (overpasses at 1330 local time) and night (overpasses at 0130
local time) is provided in Figure 2. The differences in this figure are likely related to the combined effect of diurnal variability
and variations in detection sensitivity. The increased detection sensitivity during night (related to the absence of background
noise from scattered sunlight) generally leads to an increase in the number of cirrus-containing cloudy profiles south of about
55°N while the opposite is the case at higher latitudes (not shown). Nevertheless, the patterns of cirrus occurrence for CALIPSO
observations during day and night do not differ much from the overall pattern in figure Figure 1a. *Then why bring up?*

110 The seasonal variation of the occurrence of isolated cirrus clouds is presented in Figure 3. The region with the by far highest
occurrence rate of isolated cirrus clouds is northern Africa during boreal winter. Other regions of pronounced seasonal variation
are the west coast of North America, Chile, the southern tip of Africa, the Arabian peninsula, the Indian Ocean and the Indian
subcontinent, Tibet and western China, the maritime continent, and the equatorial Pacific Ocean. In contrast to these regions,
seasonal variations at the poles are the result of the effect of polar night and day. This can also be seen from comparing Figures 1
and 2. *here*

3.2 Mid-level clouds

The map of the occurrence of transparent mid-level clouds that would be detectable with a ground-based lidar from six years
of CALIPSO data is presented in Figure 4. The land regions with the highest fraction of CALIPSO profiles that contain
transparent altocumulus clouds without low-level clouds below are the Greenland ice sheet, eastern Antarctica, the western



125 flanks of the Rocky Mountains and Andes, western Australia, southern Africa and the Horn of Africa, large parts of the Middle
East, and the area around the Himalayas. Figures 4b and c reveal that cloudy profiles that contain transparent altocumulus are
dominant over the continents and the equatorial oceans. A similar finding is presented in Bourgeois et al. (2016). In contrast,
transparent altocumulus generally occurs less frequently over mid-latitude oceans and the stratocumulus decks to the west of
the continents, though aircraft measurements have shown that the occurrence rate of thin mid-level clouds is non-negligible in
these regions (Adebisi et al., 2020).

The day-night contrast for altocumulus clouds in Figure 5 is more pronounced than the one for isolated cirrus in Figure 2
with a larger occurrence rate of continental transparent altocumulus clouds without low-level clouds underneath during day-
time. This is particularly visible over western North America, southern and eastern Africa, eastern Antarctica, and western
130 Australia. A slight increase in the occurrence rate is found over the equatorial oceans during night, again likely as a result of
increased detection sensitivity in the absence of the solar background. The occurrence rate is lowest over the regions of dense
stratocumulus decks to the west of the continents.

Figure 6 reveals that some regions show a considerable change in the occurrence rate of transparent altocumulus over the
year. This seasonal variation would need to be considered in the choice of location for ground-based lidar observations of
135 mid-level clouds and in the interpretation of the collected data. For instance, ground-based lidar measurements of transparent
altocumulus clouds located in northern Africa, the Middle East, or at the west coast of North America are likely to give the
best yield in observations during summer, while the occurrence of those clouds is considerably lower during other seasons. In
contrast, the opposite is found for Eastern Africa. Occurrence rates are relatively constant over the southern part of Africa, the
Atacama region, Greenland, western Australia, and central Asia.

140 3.3 Diurnal variability

An extensive comparison of the findings from observations with the CATS and CALIPSO lidars is provided in the Appendix.
Here, the capability of CATS to cover the diurnal variability in cloudiness in the latitude band from 51°S to 51°N (Noel et al.,
2018) is used to evaluate the representativeness of the CALIPSO lidar observations at 0130 and 1330 local time for drawing
conclusions regarding the most suitable regions for observing mid-level and high clouds with ground-based lidar instruments.

145 Figure 7 presents the analysis of CATS observations over its full period of operation from March 2015 to October 2017.
Though compiled with a coarser resolution, the map of the occurrence rate of isolated cirrus clouds in Figure 7a can be
compared directly to the CALIPSO observations in Figure 1a. Data from both instruments give a very similar global distribution
of isolated cirrus clouds with clear maxima of occurrence over northern Africa and the Tibetan plateau. It is therefore reasonable
to make use of both time series for a more comprehensive analysis of the best locations for observing mid-level and high clouds
with ground-based lidar. The anomaly in the diurnal variation of the zonal mean occurrence rate of isolated ice clouds over all
surfaces in Figure 7b reveals that nighttime measurements in the northern hemisphere show lower values than the daily average
of CATS observations while the opposite is the case for evening measurements. Much smaller variation from the daily average
is found in the first six to nine hours of a day. A similar picture is found when looking at zonal mean values for different
seasons (not shown). The diurnal variation in zonal bands of 20° is shown in Figure 7d. Over all surfaces, measurements in



165 the tropics show the largest anomaly at noon and in the evening. Smaller variations are found at lower and mid-latitudes. All zonal bands show mean values varying around zero until 0600. Figure 7c shows that the diurnal variation is intensified when considering only data over land – which are the areas where a ground-based lidar would be placed. In that case, a stronger negative anomaly is found around noon compared to the data over all surfaces in Figure 7b, while a positive anomaly extends from 1800 to 0600, though weakening after midnight. This is also corroborated by the zonal means over land in Figure 7d, which reveal the smallest anomaly during the morning hours. From this investigation of diurnal variation and the magnitude of the anomaly during day and night, it can be concluded that CALIPSO night time observations at 0130 local time might be more representative for an objective assessment of the ideal regions for observing mid-level and high clouds with ground-based lidar instruments compared to daytime observations at 1330 local time.

165 The results of an analogous investigation for transparent altocumulus clouds are presented in Figure 8. Again, the distribution of isolated altocumulus clouds from CATS observations resembles that derived from the CALIPSO time series in Figure 4a. However, the smaller volume of the CATS data set in combination with the coarser resolution of the spatial gridding lead to a weaker contrast in altocumulus occurrence in Figure 8a compared to the CALIPSO data in Figure 4a. The anomaly in the diurnal variation of the zonal mean occurrence rate of isolated altocumulus is much weaker than for cirrus for observations over all surfaces as well as land only. In fact, the anomaly is negligible when considering all surfaces (Figure 8b and d). Considering only data over land shows a weak positive anomaly around noon and an even weaker negative anomaly between 1800 and 0600 (Figure 8c). Hence, CALIPSO observations at 0130 local time should be representative for the better part of a day.

3.4 Placing a ground-based lidar for observations of high and mid-level clouds

The findings of this study are summarized in Figure 9. The combination of (i) the ratio of CALIPSO profiles that contain cirrus clouds in the absence of opaque low- and mid-level clouds versus all cloudy profiles with (ii) the normalized number of CALIPSO profiles per grid box is used to identify those land regions where measurements with a ground-based lidar are most likely to yield the highest possible observation rate for studying mid-level and high clouds.

175 Unsurprisingly, cirrus clouds are best observed in the tropics with particularly suitable conditions for ground-based lidar measurements at the northern coast of South America, equatorial Africa, the southern tip of the Indian subcontinent, and the maritime continent. Cirrus observations with lidar in these regions have been performed for instance in Niger (Protat et al., 2010), in southern India (Pandit et al., 2015), at the Maldives (Seifert et al., 2007), and at Nauru (Comstock et al., 2002). Further favourable regions are the Tibetan plateau (Dai et al., 2019; He et al., 2013) and western China, western North America (Sassen and Campbell, 2001; Sassen and Benson, 2001), Florida and the Caribbean (Haarig et al., 2016), the Atacama region, the southern tip of South America (Barja Gonzalez et al., 2020), the Amazon rain forest (Gouveia et al., 2017), Antarctica (Alexander and Klekociuk, 2021), and Greenland (Lacour et al., 2018), where semi-transparent clouds were found to potentially enhance ice sheet melting (Bennartz et al., 2013; Solomon et al., 2017). Less ideal conditions are met over Europe (Giannakaki et al., 2007; Kienast-Sjögren et al., 2016) and most of Asia. The worst regions are the Canadian Arctic, the northern coast of Europe and Asia, the Middle East, southern Africa, and most of Australia. Nevertheless, studies have been published based on measurements at those regions as well, e.g. Platt (1973), Protat et al. (2010).



190 The preferential regions for observing mid-level clouds with ground-based lidar are shown in Figure 9b. These turn out to be
more confined compared to the ones for cirrus in Figure 9a. The regions that stick out are the Greenland plateau and Antarctica
(Del Guasta et al., 1993), where the topography is too high to have low-level clouds as an obstacle for lidar measurements.
200 At low and mid-latitudes, good observational conditions prevail at the western flanks of the Rocky Mountain (Sassen, 2002)
and Andes mountain ranges (Kanitz et al., 2011; Jimenez et al., 2020), over the Amazon, western Australia (Protat et al.,
2011), southern and eastern Africa, the Gulf region, the fringe of the Tibetan plateau, and central Asia. The regions indicated
in Figure 9b mark those for which a ground-based lidar is likely to give the best return rate in terms of observing altocumulus
195 clouds. This is particularly important for short-term deployments such as field experiments which typically extend over a period
of a few weeks to months. Alternatively, long-term measurements are the best option for collecting a volume of data that is
sufficient to allow for identifying specific case studies as well as for enabling a statistical analysis of the observed altocumulus
clouds – even in regions that are not emphasised in Figure 9b, such as central Europe (Ansmann et al., 2005; Seifert et al.,
200 2010; Schmidt et al., 2015).

4 Summary and conclusions

Six years of measurements with the polar orbiting CALIPSO lidar have been used in combination with ^{the two} 92 months of mea-
surements with the CATS lidar aboard the International Space Station between March 2015 and October 2017 to investigate
the global distribution of cloud scenarios that support the observation of mid-level and high clouds with ground-based lidar
205 instruments. The CALIPSO cloud mask was used to select profiles in which:

1. cirrus clouds are observed in the absence of low-level clouds and opaque altocumulus underneath,
 2. transparent altocumulus is observed in the absence of low-level clouds underneath,
- as an analogue for conditions under which a ground-based lidar could be used for unperturbed observations of high and mid-
level clouds, respectively.
- 210 The fixed CALIPSO overpass times at 0130 and 1330 local time inhibit an assessment of the diurnal variation in cloudiness.
Hence, observations with the CATS lidar have been used to investigate the representativeness of the CALIPSO cloud sampling.
In contrast to the CALIPSO data set, the CATS data set does not feature a cloud flag. Scenarios that are comparable to the ones
selected from the CALIPSO observations have been compiled by screening the data set for the occurrence of cloud ice and for
the location of cloud base and top heights.

215 The analysis of the data sets from the two spaceborne lidars shows a remarkable resemblance ⁱⁿ of the regional and vertical
distribution of isolated cirrus and altocumulus clouds despite the different approaches to extract the corresponding information
from the corresponding data sets. The diurnal variation of cloud occurrence from the CATS data set leads to the conclusion that
CALIPSO observations at 0130 local time are representative for the better part of the day while the period of largest anomaly
is covered by the overpass at 1330 local time. Generally, diurnal anomalies in cloud occurrence are (i) stronger over land
220 compared to over all surfaces and (ii) stronger for isolated cirrus clouds compared to isolated altocumulus clouds. The ratio of



225 occurrence of the two cloud types versus all cloudy profiles per grid box in combination with the absolute number of profiles in
a corresponding grid box is used to identify those regions for which a ground-based lidar is likely to encounter the best balance
between the occurrence of the desired cloud types and the prevalence of favourable conditions to actually observe these clouds,
i.e. the absence of strongly light-attenuating clouds below the target cloud. This information is particularly vital in the planning
of deploying lidar instruments in the framework of field experiments or measurement campaigns. Such deployments generally
last between only a few weeks to several months and their success relies strongly on finding atmospheric conditions that meet
the desired research objectives to allow for addressing related science questions. From the approach used in this study, it is
found that the best regions for lidar measurements of cirrus clouds are the tropics, the Tibetan plateau, the western part of North
America, the Atacama region, the southern tip of South America, Greenland, Antarctica, and parts of western Europe. For the
230 observation of altocumulus clouds, a ground-based lidar is best placed on Greenland, Antarctica, the western flank of the Andes
and Rocky Mountains, the Amazon, central Asia, Siberia, western Australia, or the southern half of Africa. Finally, it should
be emphasized that the regions above provide the best gain of a lidar deployment. However, this advantage for short-term
deployments can be compensated by increasing the length of a lidar operating at a certain site as this increases the likelihood
of meeting the desired atmospheric conditions for observing a targeted cloud type.

235 *Data availability.* All spaceborne lidar data used in this study are openly available, e.g. through the ICARE Data and Services Center at <https://www.icare.univ-lille.fr/>. More specifically, the CALIPSO Cloud profile data (CALIPSO Cloud Profile product, 2022) used in this study
are located at <https://www.icare.univ-lille.fr/data-access/data-archive-access/?dir=CALIP/05kmCPro.v4.20/> while the CATS data (CATS
Layer product, 2022; CATS Profile product, 2022) can be found at [https://www.icare.univ-lille.fr/data-access/data-archive-access/?dir=CATS/CATS-ISS_](https://www.icare.univ-lille.fr/data-access/data-archive-access/?dir=CATS/CATS-ISS_L2O_N-M7.2_05kmLay.v3.01/)
240 [L2O_N-M7.2_05kmPro.v3.01/](https://www.icare.univ-lille.fr/data-access/data-archive-access/?dir=CATS/CATS-ISS_L2O_N-M7.2_05kmPro.v3.01/).

Appendix A: Comparability of CALIPSO and CATS observations of the fraction of high and mid-level clouds

The consistency of observations with the CALIPSO and CATS lidars was investigated for the time period from March 2015 to
October 2017, i.e. the period of CATS operation. For this Appendix, CATS observations of ice and mid-level clouds collected
in a time period of ± 1 h around the CALIPSO observations at 0130 and 1330 local time were used to derive cloud fraction (i)
245 in grid boxes of 5° by 5° , (ii) as latitudinal and longitudinal averages, and (iii) in the form of height profiles for comparison
with CALIPSO observations. Note that the temporal constraint leads to a much lower number of CATS profiles compared to
the CALIPSO observations and, thus, more noise in the CATS data.

A1 Cirrus clouds

Figure A1 compares the spatial distribution of the occurrence rate of cirrus clouds as seen by CALIPSO and CATS. Both data
250 sets agree in their main features, i.e. maxima of ice cloud fraction over the tropics, regions of low ice cloud fraction in bands



255 around 30°N and 30°N, and an increase in ice cloud fraction towards higher latitudes from there. This is confirmed when
considering latitudinal and longitudinal averages (not shown). The CATS and CALIPSO data sets agree in the magnitude of
latitudinally averaged ice cloud fraction with the largest deviation of about 0.05 in the band at 25°S – an effect that might be
resulting from the noise in the CATS data. The longitudinally averaged ice cloud fraction shows bands with a larger deviation
between the two data sets (from 150°W to 120 °W and from 50°W to 50°E) as well as bands for which the averages overlay
almost perfectly. Again, noise induced from the decreased amount of grid boxes for deriving the values is likely to affect
the comparison. Both instruments reveal in almost identical vertical distribution of ice clouds (not shown) within the latitude
band between ±5° (where they feature a roughly similar sampling rate). This agreement corroborates the findings of Sellitto
et al. (2020).

260 Figure A1 refers to all ice clouds. For a fair comparison with the CALIPSO data in Figure 1a, i.e. clouds that are (i) flagged
as cirrus and (ii) are the only cloud type in the profile, the CATS data set has been screened for what is referred to here as
isolated cirrus clouds. The cloud subtype classification is not available in the CATS data set. However, when only ice clouds
are present in a profile (i.e., they are not the top of a larger system or part of a mixed-phase system) and these clouds are not
flagged as opaque, they are most likely to be cirrus. The CALIPSO Atmospheric_Volume_Description variable and the CATS
265 Percent_Opacity_Fore_FOV variable were used to select clouds that are neither opaque nor fully attenuated.

Figures A2 shows that the vertical profile as well as the zonal average of the fraction of isolated ice clouds as seen by CATS
match those seen by CALIPSO very closely. About 75% to 95% of isolated ice clouds between 7.5 and 17.5 km height were
categorised as cirrus. Moreover, 88% of profiles containing isolated ice clouds in CALIPSO data between 51°S and 51°N are
categorised as cirrus (92% for 30°S to 30°N). This fraction decreases towards higher latitudes beyond the area of CATS data
270 coverage between 51°S and 51°N. The findings in Figures A2 suggest that the majority of isolated ice clouds in non-opaque
CATS profiles are equivalent to isolated cirrus in CALIPSO data. In addition, cloud-fraction retrievals for isolated ice clouds
in non-opaque profiles give comparable results when using data from the CALIPSO and CATS instruments. As a consequence,
the investigation of the diurnal variability of ice clouds considers CATS profiles that contain isolated ice clouds and are not
opaque, and assumes that these profiles are equivalent to CALIPSO profiles that contain isolated cirrus clouds.

275 A2 Mid-level clouds

Figure A3 compares the spatial distribution of the occurrence rate of transparent mid-level clouds as seen by CALIPSO and
CATS during the CATS period of operation. Overall, the occurrence rate is much lower than for ice clouds in Figure A1. In
addition, transparent altocumulus is observed primarily over land. Both time series resolve comparable regions of high Ac
occurrence rate over southern and eastern Africa, the Middle East, central Asia, western Australia, the Amazon, coastal Peru,
and to the west of the Rocky Mountains. Discernible differences are restricted to northern Africa, central Asia, and eastern
280 Australia – all regions where CATS finds slightly a higher Ac occurrence rate than CALIPSO.

Figure A4a shows that the small differences in Figures A3 don't lead to a large deviation in the zonal mean altocumulus
fraction. The only exception is visible around 40°N where the higher Ac occurrence rates over western North America and
central Asia in CATS observations compared to CALIPSO leads to a higher zonal mean in the CATS data set. The vertical



285 distribution of Ac fraction in Figure A4b shows that both instruments place the target clouds within the same height range with
a maximum at around 5 km height but a larger Ac fraction in the CALIPSO data set compared to the one derived from CATS
measurements.

Author contributions. MT conceived this study, and processed and analysed the CALIPSO data. VN processed and analysed the CATS data.
Both authors contributed equally to the discussion of the findings, the writing of the paper, and the creation of the figures.

290 *Competing interests.* The authors declare no competing interests.

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