

1 **Derivation of depolarization ratios of aerosol fluorescence and water vapor Raman**
2 **backscatters from lidar measurements**

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12
13 **Abstract**

14 Polarization properties of the fluorescence induced by polarized laser radiation are widely
15 considered in laboratory studies. In lidar observations, however, only the total backscattered power
16 of fluorescence is analyzed. In this paper we present results obtained with a modified Mie-Raman-
17 Fluorescence lidar operated at the ATOLL observatory, Laboratoire d'Optique Atmosphérique,
18 University of Lille, France, allowing to measure depolarization ratios of fluorescence at 466 nm
19 (δ_F) and of water vapor Raman backscatter. Measurements were performed in May-June 2023
20 during the Alberta forest fires season when smoke plumes were almost continuously transported
21 over the Atlantic Ocean towards Europe. During the same period, smoke plumes from the same
22 sources were also detected and analyzed in Moscow, at the General Physics Institute (GPI), with
23 a 5-channel fluorescence lidar able to measure fluorescence backscattering at 438, 472, 513, 560
24 and 614 nm. Results demonstrate that, inside the planetary boundary layer (PBL), the urban aerosol
25 fluorescence is maximal at 438 nm, then it gradually decreases with increase of wavelength. The
26 smoke layers observed within 4-6 km height present a maximum of fluorescence at 513 nm, while
27 in the upper troposphere, fluorescence maximum shifts to 560 nm. Regarding the fluorescence
28 depolarization ratio, for smoke its value typically varies within the 45-55 % range.

29 The depolarization ratio of the water vapor Raman backscattering at 408 nm is shown to be
30 quite low ($2\pm 0.5\%$) in the absence of fluorescence, because the narrowband interference filter (0.3
31 nm) in the water vapor channel selects only the strongest vibrational lines of the Raman spectrum.

32 As a result, the depolarization ratio at the water vapor Raman channel is sensitive to the presence
33 of strongly depolarized fluorescence backscattering and can be used for evaluation of the aerosol
34 fluorescence contribution to measured water vapor mixing ratio.

35

36 **1. Introduction**

37 Possibility to measure the laser induced fluorescence becomes an important added-value to
38 existing Mie-Raman lidars, because fluorescence measurements provide new independent
39 information about aerosol properties. Nowadays, the spectroscopic lidars based on 32-channel
40 PMT combined with spectrograph proved the ability to measure the fluorescence spectrum
41 (Sugimoto et al., 2012; Reichardt, 2014; Reichardt et al., 2018, 2023, Richardson et al., 2019; Liu
42 et al., 2022). On the other hand, lidars, with a single fluorescence channel can be widespread due
43 to their simplicity (Rao et al., 2018; Veselovskii et al., 2020). Such single-channel fluorescence
44 lidar combined with depolarization measurements at the elastic wavelength, provide new
45 independent information about aerosol type (Veselovskii et al., 2022). However, in all lidar
46 studies, only the total scattered power was analyzed, while the polarization properties of the
47 fluorescence were ignored. At the same time, fluorescence depolarization measurements are
48 widely used in laboratory research (Lakowicz, 2006). When polarized laser radiation is used for
49 excitation, the fluorescence emission is also partly polarized and degree of its depolarization
50 (anisotropy) depends on the fluorescence lifetime, on the angle between excitation and emission
51 dipoles, and on the rotational mobility of molecules (Lakowicz, 2006). In the fluorescence
52 spectroscopy, the polarization state of emission is described by the anisotropy (Lakowicz, 2006),
53 introduced as:

$$54 \quad r = \frac{P_F^\square - P_F^\perp}{P_F^\square + 2P_F^\perp} \quad (1)$$

55 where P_F^\square and P_F^\perp are the powers of co- and cross-polarized fluorescence components. In lidar
56 measurements, however, the fluorescence depolarization ratio, δ_F is given as.

$$57 \quad \delta_F = \frac{P_F^\perp}{P_F^\square} \quad (2)$$

58 Therefore, the anisotropy is expressed as a function of the δ_F as follows:

$$59 \quad r = \frac{1 - \delta_F}{1 + 2\delta_F} \quad (3)$$

60 For randomly oriented fluorophores with collinear absorption and emission dipoles, in the
61 absence of rotational motion, the anisotropy $r=0.4$ (Lakowicz, 2006), which corresponds to
62 $\delta_F=33\%$. This is the minimal value one can expect in lidar measurements. Existence of any angle
63 between absorption and emission dipoles, as well as molecule rotation in the process of emission
64 will increase δ_F (Lakowicz, 2006). Thus, measurement of fluorescence depolarization ratio may
65 bring additional information about atmospheric aerosol, as we will show below.

66 Water vapor is a key atmospheric component playing essential role in the planet's radiative
67 balance, and Raman lidars today are widely used for such observations (Whiteman, 2003, Chouza
68 et al., 2022 and references therein). However, when the UV laser beam passes through a smoke
69 layer, the broadband fluorescence signal is induced and its spectrum includes the region of water
70 vapor Raman lines. Thus, the signal in the water vapor channel (around 407.5 nm, when 354.7 nm
71 laser radiation is emitted) becomes contaminated by the fluorescence backscatter signal (Immler et
72 al., 2005; Immler and Schrems, 2005). This contamination can be reduced by decreasing the width
73 of the transmission band in the water vapor channel down to tenths of nm. However, as it was
74 shown recently, fluorescence still remains the source of uncertainties, especially when the water
75 vapor mixing ratio (WVMR) is measured inside the smoke layers in the upper troposphere (Chouza
76 et al., 2022; Reichardt et al., 2023).

77 Depolarization measurements provide an opportunity to monitor the presence of
78 fluorescence signal in the Raman channel. The Q-branch of water vapor Raman lines (near 407.5
79 nm) provides a weakly depolarized backscatter, while fluorescence is strongly depolarized. Thus,
80 the presence of fluorescence should increase the depolarization ratio of signal in the water vapor
81 channel. Moreover, if the depolarization ratios of water vapor and fluorescence are known, the
82 contribution of fluorescence to the measured WVMR can be evaluated.

83 In this article, we report and analyze, for the first time, the depolarization ratio of aerosol
84 fluorescence and of water vapor Raman backscatter from lidar observations performed at the
85 ATOLL observatory (ATmospheric Observation at liLLe), Laboratoire d'Optique
86 Atmosphérique, University of Lille, during dense smoke events occurred on May - June 2023. We
87 start with a description of the experimental setup in Sect.2.1 and derive, in Sect. 2.2, the main
88 equations for estimating the fluorescence contribution to the water vapor Raman channel. In the
89 first part of the results section (Sect.3.1), the fluorescence depolarization ratios over ATOLL are
90 analyzed for different aerosol types. The measurements of fluorescence spectra performed with a

91 new five-channel fluorescence lidar, operated in Moscow, are presented in Sect.3.2. In Sect. 3.3,
92 we analyze the depolarization ratio in the water vapor Raman channel and estimate the
93 contamination of fluorescence to the derived WVMR profiles. Finally, in Sect.4 we present our
94 conclusions.

95

96 **2. Experimental setup and data analysis**

97 **2.1 Lidar system**

98 In our study, two lidar systems are considered. The first one, LILAS ((Lille Lidar
99 AtmosphereS) is a multiwavelength Mie-Raman-Fluorescence lidar, whereas the second one is a
100 multiwavelength fluorescence lidar operated by the General Physics Institute (GPI), Moscow
101 (Veselovskii et al., 2023). Both systems are based on a tripled Nd:YAG laser (Q-Smart 450) with a
102 20 Hz repetition rate and pulse energy about 100 mJ at 355 nm. The backscattered laser light in
103 both systems is collected by a 40 cm aperture telescope and the lidar signals are digitized with
104 transient recorders (Licel) with 7.5 m range resolution, allowing simultaneous detection in the
105 analog and photon counting mode.

106 LILAS allows the so called $3\beta+2\alpha+3\delta$ configuration, including three particle
107 backscattering (β_{355} , β_{532} , β_{1064}), two extinction (α_{355} , α_{532}) coefficients along with three particle
108 depolarization ratios (δ_{355} , δ_{532} , δ_{1064}). The Raman channel with a 407.54/0.3 nm spectral width
109 interference filter allows also water vapor profiling. At the end of 2019, the lidar was modified to
110 enable fluorescence measurements. A part of the fluorescence spectrum is selected by a wideband
111 interference filter of 44 nm width centered at 466 nm (Veselovskii et al. 2020).

112 In the fluorescence lidar of GPI only 355 nm wavelength is emitted, while fluorescence is
113 measured in five spectral intervals. The central wavelengths and widths of spectral transmission
114 bands (in parentheses) are: 438(29), 472(32), 513(29), 560(40) and 614(54) nm (Veselovskii et al.,
115 2023). Thus, the fluorescence spectrum could be sampled at five different wavelengths. The
116 transmission bands of the fluorescence channels (Fig.1 in Veselovskii et al., 2023) are separated
117 and there are no cross-talks between the channels. At GPI, the measurements were performed at
118 an angle of 48 deg to the horizon. The strong sunlight background restricts the fluorescence
119 observations of both systems to only the nighttime hours.

120 Several aerosol properties can be derived from fluorescence. The fluorescence
121 backscattering coefficient, $\beta_{F\lambda}$, at wavelength λ_F , is calculated from the ratio of fluorescence and

122 nitrogen Raman backscattering signals, as described in Veselovskii et al. (2020). We remind that
 123 $\beta_{F\lambda}$ is related to fluorescence signals integrated over the filter transmission band D_λ . In Moscow
 124 measurements are performed at five wavelengths, and to compare $\beta_{F\lambda}$ between different channels
 125 one makes use of the “fluorescence spectral backscattering coefficient” $B_\lambda = \frac{\beta_{F\lambda}}{D_\lambda}$ (fluorescence
 126 backscattering per spectral interval). LILAS has only one single fluorescence channel, therefore,
 127 when presenting data from LILAS, for the sake of simplicity, one uses notation $\beta_{F466} = \beta_F$. The
 128 intensive property characterizing aerosol fluorescence is the fluorescence capacity $G_{F\lambda}$, which is
 129 the ratio of the fluorescence backscattering at wavelength λ_F to backscattering coefficient at laser
 130 wavelength $G_{F\lambda} = \frac{\beta_F}{\beta_\lambda}$. This ratio, in principle, can be calculated for any laser wavelength. For
 131 LILAS observations $G_{F\lambda}$ is calculated with respect to β_{532} , as β_{532} is derived with rotational Raman
 132 scattering and it does not depend on assumption about the Angstrom exponent (Veselovskii et al.
 133 2015). And again, when presenting LILAS data, for simplicity one will use the notation $G_{F\lambda} = G_F$.
 134 In this work, all profiles of aerosol properties are smoothed with the Savitzky – Golay method,
 135 using second order polynomials with 8 points in the spatial window.

136 Additional information about the atmospheric thermodynamic state was available from
 137 radiosonde measurements performed at Herstmonceux (UK) and Beauvechain (Belgium) stations,
 138 located 160 km and 80 km away from the ATOLL observatory, respectively. When calculating the
 139 relative humidity, one then used the water vapor profiles measured by Raman lidar and temperature
 140 profiles provided by the radiosonde.

141 As discussed in Sect.1, measurements of fluorescence depolarization ratio and
 142 depolarization of water vapor Raman backscatter are expected to bring new information about
 143 aerosol properties and fluorescence contamination in the water vapor Raman channel. In 2023,
 144 LILAS was upgraded to allow depolarization measurements at both 466 nm and 408 nm. The
 145 corresponding optical layout is shown in Fig.1. Dichroic mirrors DM separate the 387, 408 and
 146 466 nm components, while polarizing cubes split the components with polarizations oriented
 147 parallel (s) and perpendicular (p) to the emitted polarized laser beam. For both channels, the
 148 polarizing cube PBS251 from ThorLabs was used. The fluorescence depolarization ratio, δ_F , and
 149 the water vapor Raman scattering depolarisation ratio, δ_w , are both defined and calculated as a
 150 ratio of the perpendicular to the parallel respective components. The calibration of both ratios was

151 performed as described in Freudenthaler et al. (2009). The uncertainty of calibration is estimated
 152 to be below 15% for both 466 and 408 nm channels.

153

154 ***2.2 Expressions for estimating fluorescence impact on water vapor measurements.***

155 As discussed in the recent work of Chouza et al. (2022) and Reichardt et al. (2023), the
 156 broadband aerosol fluorescence is expected to contribute to the signal measured at the water vapor
 157 Raman channel. Below, we provide the basic equations for estimating this contribution, based on
 158 the measurements of the depolarization ratio in the water vapor Raman channel. The elastic
 159 backscattered radiative power, at the laser wavelength λ_L , from distance z , can be modeled, after
 160 background subtraction, by writing the lidar equation:

$$161 \quad P_L = O(z) \frac{1}{z^2} C_L \beta T_L^2 \quad (4)$$

162 where $O(z)$ is the geometrical overlap factor, which is assumed to be the same for all channels. C_L
 163 is a range independent constant, including efficiency of the detection channel, the emitted laser
 164 power and the receiving telescope diameter. T_L is the one-way atmospheric transmission,
 165 describing light losses on the way from the lidar to distance z at wavelength λ_L .

$$166 \quad T_L = \exp \left\{ - \int_0^z [\alpha^a(\lambda_L, z') + \alpha^m(\lambda_L, z')] dz' \right\} \quad (5)$$

167 The backscattering and extinction coefficients contain the aerosol (a) and molecular (m)
 168 contributions: $\beta_{\lambda_L} = \beta_{\lambda_L}^a + \beta_{\lambda_L}^m$ and $\alpha_{\lambda_L} = \alpha_{\lambda_L}^a + \alpha_{\lambda_L}^m$.

169 Radiative power in nitrogen Raman, water vapor Raman, and fluorescence channels can be
 170 written in a similar way.

$$171 \quad P_R = O(z) \frac{1}{z^2} C_R \sigma_R N_R T_L T_R \quad (6)$$

$$172 \quad P_W = O(z) \frac{1}{z^2} C_W N_W \sigma_W T_W T_L \quad (7)$$

$$173 \quad P_F = O(z) \frac{1}{z^2} C_F \beta_F T_F T_L \quad (8)$$

174 where C_R , C_W , C_F are the corresponding range independent constants. T_R , T_V , and T_F are the one-
 175 way transmissions at wavelengths λ_R , λ_W , λ_F , corresponding to the centers of transmission bands of
 176 the channels. N_R and N_W are the concentrations in nitrogen and water vapor molecules while σ_R ,

177 σ_w are their Raman differential scattering cross sections respectively. The fluorescence
 178 backscattering coefficient, β_F , is introduced the same way, as described in Veselovskii et al. (2020).

179 The received power of the fluorescence signal that leaks to the water vapor channel is:

$$180 \quad P_{FW} = O(z) \frac{1}{z^2} C_w \beta_{FW} T_w T_L \quad (9)$$

181 where β_{FW} is fluorescence backscattering coefficient at wavelength λ_w . The WVMR, n_w , can be
 182 obtained from Eqs. 6 and 7, if the calibration constant $K_w = \frac{C_R}{C_w} \frac{\sigma_R}{\sigma_w}$ is known:

$$183 \quad n_w = K_w \frac{P_w}{P_R} \frac{T_R}{T_w} \quad (10)$$

184 The fluorescence backscattering coefficient, β_F , derived from Eq.6 and Eq.8, also contains
 185 the calibration constant K_F . The procedure of calibration is described in Veselovskii et al. (2020).
 186 Finally, β_F reads as:

$$187 \quad \beta_F = K_F n_R \frac{P_F}{P_R} \frac{T_R}{T_F} \quad (11)$$

188 where $n_R = \frac{N_R(z)}{N_R(z=0)}$ is the relative change of number density of nitrogen molecules with height.

189 The fluorescence signal P_{FW} in the water vapor channel can be expressed from P_F using parameter
 190 η , which depends on the ratio of fluorescence cross sections at wavelengths λ_w and λ_F , on the
 191 filters width and on the efficiency of both channels, as follows:

$$192 \quad P_{FW} = P_F \eta \frac{T_w}{T_F} \quad (12)$$

193 The total signal measured in the water vapor channel, \tilde{P}_w , is the addition of both water vapor
 194 backscatter, P_w , and the fluorescence backscatter, P_{FW} ,

$$195 \quad \tilde{P}_w = P_w + P_{FW} = P_w + P_F \eta \frac{T_w}{T_F} \quad (13)$$

196 One should remember, that the fluorescence spectrum, even for the same type of aerosols, can vary
 197 with altitude and from observation to observation, which finally influences η . To minimize this
 198 influence it is desirable to keep λ_w and λ_F as close as possible.

199 If the received lidar signals at the water vapor Raman and fluorescence channels are
 200 separated into co-polarized ($||$) and cross-polarized (\perp) components, in respect to the polarization
 201 of the emitted laser beam, their powers at the water vapor Raman channel are **given** respectively:

$$202 \quad \tilde{P}_W^{\square} = P_W^{\square} + P_F^{\square} \eta \frac{T_W}{T_F} \quad (14)$$

$$203 \quad \tilde{P}_W^{\perp} = P_W^{\perp} + P_F^{\perp} \eta \frac{T_W}{T_F} = \delta_W P_W^{\square} + \delta_F P_F^{\square} \eta \frac{T_W}{T_F} \quad (15)$$

204 where δ_F and δ_W are the fluorescence and water vapor Raman depolarization ratios, defined as:

$$205 \quad \delta_F = \frac{P_F^{\perp}}{P_F^{\square}} \quad \text{and} \quad \delta_W = \frac{P_W^{\perp}}{P_W^{\square}} \quad (16)$$

206 Here we assume that the depolarization ratio of fluorescence is the same at the wavelengths λ_W
 207 and λ_F . This assumption is usually valid, because fluorescence emission is normally from the
 208 lowest singlet state, so the depolarization ratio is spectrally independent (Lakowicz, 2006).

209 Due to the presence of fluorescence, the depolarization ratio measured at the water vapor
 210 Raman channel is:

$$211 \quad \tilde{\delta}_W = \frac{\tilde{P}_W^{\perp}}{\tilde{P}_W^{\square}} = \frac{\delta_W P_W^{\square} + \delta_F P_F^{\square} \eta \frac{T_W}{T_F}}{P_W^{\square} + P_F^{\square} \eta \frac{T_W}{T_F}} \quad (17)$$

212 Here δ_W is the depolarization ratio that would be measured at the water vapor Raman channel in
 213 the absence of atmospheric fluorescence. From Eqs.9, 10, 14, 15, 17 the parameter η can be derived
 214 using the lidar measured values, such as the water vapor mixing ratio \tilde{n}_W , depolarization ratio $\tilde{\delta}_W$,
 215 and fluorescence backscattering, β_F :

$$216 \quad \eta = \frac{\tilde{n}_W}{\beta_F} \frac{K_F}{K_W} n_R \frac{(1 + \delta_F)(\tilde{\delta}_W - \delta_W)}{(1 + \tilde{\delta}_W)(\delta_F - \delta_W)} \quad (18)$$

217 where \tilde{n}_W is the WVMR containing the fluorescence contribution.

218 It should be noted, that the choice of calibration constants K_F , K_W does not influence η , because
 219 \tilde{n}_W and β_F are calculated using the same calibration constants. Finally, the increase of WVMR
 220 Δn_W induced by the fluorescence can be calculated as:

$$\Delta n_w = K_w \frac{P_F \eta \frac{T_w}{T_F} \frac{T_R}{T_w}}{P_R} = \frac{K_w}{K_F} \eta \beta_F \frac{1}{n_R} \quad (19)$$

As soon as the parameter η is calculated from Eq.18, we can estimate the relevant error Δn_w from β_F , which in the case of LILAS is measured at 466 nm (Veselovskii et al., 2020). In such estimation we have to assume that the relationship between fluorescence at 466 nm and 408 nm remains constant with height. A possibility to perform correction from single – channel fluorescence measurements was discussed by Reichardt et al. (2023), where it was shown, that for 466/408 nm channels, correction actually may depend on height. The corresponding analysis based on our measurements will be presented in Sect.3.2.

We should mention that when the depolarization at the water vapor Raman channel is available, the contribution of fluorescence to WVMR can be obtained without using η . From Eqs.18 and 19 we obtain:

$$\Delta n_w = \tilde{n}_w \frac{(1 + \delta_F)(\tilde{\delta}_w - \delta_w)}{(1 + \tilde{\delta}_w)(\delta_F - \delta_w)} \quad (20)$$

However, such correction can be performed only at low altitudes, where the signal-to-noise ratio at the cross-polarized water vapor channel is sufficient for calculation of $\tilde{\delta}_w$.

235

3. Experimental results

In May – June 2023, the Canadian forest fires were at the origin of numerous smoke layers observations in a wide range of altitude, ranging from the PBL to the tropopause. The Boreal wildfire season in 2023 started anomalously early. A wildfire in Alberta, Canada at 53.2° N, 115.7° W has produced an intense Pyrocumulonimbus (PyroCb) cloud on 5 May with the minimum satellite-derived infrared brightness temperature of -66° C, which should correspond to 10-11 km altitude according to local radiosoundings. In order to describe the long-range transport of the smoke plume produced by this event, we use UV absorbing Aerosol Index (AI) measurements by the Ozone Monitoring and Profiling Suite (OMPS) Nadir Mapper (NM) instrument onboard Suomi NPP satellite mission (Flynn et al., 2014). AI is widely used as a proxy of the amount of absorbing aerosols (e.g smoke, dust, ash) and its dimensionless value is proportional to the altitude of the aerosol layers. AI values above 15 are usually associated with smoke plumes at or above the

248 tropopause (Peterson et al., 2018 and references therein), whereas maximum AI value reported by
249 the OMPS-NM instrument for the Alberta event reached a value of 19.9.

250 Fig. 2 displays the spatio-temporal evolution of the smoke plume from the Alberta event
251 represented by the areas of enhanced AI observed between 5–21 May. The smoke in the upper
252 troposphere and lower stratosphere (UTLS) is advected by the westerly winds, crossing the
253 Atlantic about 1 week before reaching Moscow by 15 May. On that date, the Moscow lidar has
254 detected the smoke layer at 10-11 km (see Sect.3.2). The plume was then further advected across
255 Eurasia towards northeastern Siberia. By 22 May the smoke plume completes its first
256 circumnavigation (not shown) and passes over Lille on 23 May and then over Moscow for the
257 second time around 27 May. Thus, we can expect, that the smoke layers observed over Lille and
258 Moscow have the same source.

259

260 ***3.1 Variability of fluorescence depolarization ratio***

261 At the first stage of our research we focused on the variability of the fluorescence
262 depolarization ratio for aerosol types. The main attention was paid to smoke particles, because
263 they provide the strongest impact on the Raman water vapor measurements due to their high
264 fluorescence capacity (Veselovskii et al., 2022).

265 Spatio-temporal distributions of the aerosol elastic and fluorescence backscattering
266 coefficients (β_{532} and β_F), on the night 26-27 June 2023, are shown in Fig.3. Dense smoke layer
267 with β_F as high as $7.0 \times 10^{-4} \text{ Mm}^{-1} \text{sr}^{-1}$ occurred within the 4.0-10.0 km height range. The HYSPLIT
268 back trajectories show that the air masses were transported from North America. The relative
269 humidity increased from 40% at 4 km to >90% at 7 km where formation of ice crystals started.
270 Vertical profiles of aerosol elastic and fluorescence backscattering coefficients (β_{532} and β_F),
271 together with fluorescence capacity, are shown in Fig.3c. Inside the smoke layer, G_F is about 3×10^{-4} ,
272 which is a typical value for smoke (Veselovskii et al., 2022) whereas, above 6 km, it decreases
273 due to ice formation. The presence of ice crystals increased the particle depolarization ratio δ_{532}
274 from 3% at 6 km to 20% at 8 km. Fluorescence signals are strongly depolarized. Inside the PBL,
275 δ_F was about 60% whereas above 2 km it dropped to approximately 45%. The processes of
276 hygroscopic growth and ice formation do not provide a noticeable impact on δ_F value. During May
277 – June observations, the depolarization ratio of smoke varied mainly inside the 45-55% range.

278 As discussed in our previous publications (Veselovskii, et al., 2022; Hu et al., 2022), the
279 fluorescence capacity of aged smoke varies inside the $(2.5-5.5)\times 10^{-4}$ range, probably due to the
280 changes in smoke composition and conditions of atmospheric transport. However, during the
281 Alberta fires, several smoke plumes with high G_F have been observed. The highest fluorescence
282 capacity was observed on the night 16-17 June 2023. Vertical profiles of the aerosol properties for
283 this episode are shown in Fig.4. Dense smoke layers with fluorescence backscattering exceeding
284 $10.0\times 10^{-4} \text{ Mm}^{-1}\text{sr}^{-1}$ occurred within the 7.0 -9.0 km height range. In this case, the maximal value
285 of the fluorescence capacity reached 10.0×10^{-4} . Fluorescence depolarization ratio was measured
286 about 50% through the entire smoke layer and the process of ice formation (just like in Fig.3d)
287 does not influence δ_F . Thus, in May - June 2023 strong variations of G_F in the $(2.5-10.0)\times 10^{-4}$
288 range were accompanied by relatively small variations of δ_F remaining in the 45-55% interval.

289 It is known that in the UTLS smoke particles can reach depolarization ratio, δ_{532} as high as
290 15-20% (Burton et al., 2015; Haarig et al., 2018; Hu et al., 2019; Baars et al., 2019; Ohneiser et
291 al., 2020). High values of the particle depolarization ratio are usually attributed to the complex
292 internal structure of smoke particles (Mishchenko et al., 2016). Two smoke events in the UTLS,
293 characterized by enhanced δ_{532} , on 28-29 May and 3-4 June 2023, are illustrated on Fig.5. On 28-
294 29 May, three smoke layers, at $\sim 3.5, 6.5$ and 11.5 km can be distinguished. High depolarization
295 ratios, reaching 40% at altitudes of 9.8-10.5 km, are due to ice clouds. In the lower smoke plumes
296 ranging between 3.5 and 6.5 km, the particle depolarization did not exceed 8%, whereas above 11
297 km δ_{532} increased to 15%. High values of δ_{532} observed in the UTLS correlate with increase of G_F
298 and with fluorescence depolarization, δ_F , up to 7.0×10^{-4} and 70%, respectively. Similar behavior
299 was observed on 3-4 June, where depolarization ratio, δ_{532} , above 11.5 km increased up to 15%,
300 simultaneously with an increase of G_F and δ_F up to 9.5×10^{-4} and 70% respectively. Thus, change
301 in particle morphology may affect the depolarization ratio at the fluorescence channel. Another
302 possibility is that, in the UTLS, not only the particle structure can change, but the composition as
303 well. At the current stage of analysis, we are not yet able to conclude about the mechanisms
304 explaining the increase of fluorescence depolarization in the UTLS.

305 Furthermore, we did not observe the effect of atmospheric humidity on smoke fluorescence
306 depolarization. However, inside the PBL the observed hygroscopic growth was accompanied by
307 an increase of δ_F . During the 9-16 June 2023 period numerous particle hygroscopic growth cases
308 were observed in the PBL. One of such cases, on the night of 12-13 June, is shown in Fig.6. The

309 relative humidity increased inside the PBL from 50% to 70% causing an increase of β_{532} near the
310 PBL top. Depolarization ratio δ_{532} decreased with height, since the particles in the process of
311 hygroscopic growth became more spherical. The fluorescence depolarization ratio, however,
312 increased inside the PBL from 50% to 70%.

313 All results obtained during 9-16 June, showing dependence of δ_F and δ_{532} on the relative
314 humidity, are summarized in Fig.7. Particle depolarization δ_{532} systematically decreased with RH
315 but, on 16 June, this dependence is not monotonic which could be due to the change of aerosol
316 composition with height. At low RH (below 30%), the fluorescence depolarization ratio was about
317 50%. However, at RH about 90%, δ_F increased up to 70%. One of possible explanations for that
318 behavior could be an increase of rotational mobility of the molecules in the process of particle
319 water uptake.

320

321 ***3.2 Fluorescence spectrum sampled with a with 5-channel lidar***

322 The results presented in the previous section were obtained with a single channel
323 fluorescence lidar. However, for analyzing the variability of smoke properties (for example,
324 increase of the fluorescence capacity with height) it is important to have information about a wider
325 fluorescence spectrum. Moreover, to estimate the fluorescence contamination in the Raman water
326 vapor channel, a relationship between fluorescence backscattering at 466 nm and 408 nm is used.
327 Thus, we need to know the variability of the fluorescence spectrum in the short wavelength region.
328 In our recent work (Veselovskii et al., 2023) we presented the first results obtained with a 5-
329 channel fluorescence lidar in operation at the GPI. This lidar is able to measure the fluorescence
330 backscattering profiles at 5 spectral intervals centered at 438, 472, 513, 560, and 614 nm. During
331 May–June 2023, several smoke plumes originating from Alberta fires were transported over
332 Moscow. Although Lille and Moscow are very distant from each other (above 2200 km), smoke
333 plumes observed have the same origin, hence the fluorescence spectra measured over Moscow are
334 quite helpful for the analysis of the Lille data.

335 Fig.8 (a,b,c) present the fluorescence spectral backscattering coefficients, B_λ , for 3 smoke
336 events detected in the UTLS above 10, 8 and 10 km for 15, 31 May and 20 June 2023, respectively.
337 On 15 and 31 May smoke layers were also present inside the 4-6 km range. Inside the PBL the
338 strongest fluorescence was systematically detected at the 438 nm channel while, at higher altitudes,
339 the maxima shifted to 560 nm. As follows from Figs.8d-f, the ratio B_{560}/B_{438} remained in the range

340 0.4 -0.7 inside the PBL, whereas this ratio increased above 2.0 in the UTLS. Thus, for smoke
341 events the maxima of the fluorescence spectrum shifted with height towards longer wavelengths.
342 The ratio B_{513}/β_{355} also increased with height and, above 10 km, it reached the values of 1×10^{-5}
343 nm^{-1} . In the UTLS, the maximal fluorescence capacity, G_F , measured by LILAS at 466 nm (with
344 44 nm bandwidth filter) was about 10×10^{-4} . In the smoke layer, the ratio of backscattering
345 coefficients β_{355}/β_{532} is about 2, so the maximal ratio B_{466}/β_{355} derived from LILAS measurements
346 was about $1.1 \times 10^{-5} \text{ nm}^{-1}$. Thus, values obtained over Lille and over Moscow are in good
347 agreement.

348 The fluorescence spectra obtained for the above mentioned smoke plumes are shown in
349 Fig.9. The values of B_λ are normalized to B_{438} . Inside the PBL, the maximum of fluorescence was
350 measured at 438 nm and it decreased with wavelength. In the smoke layers within 4-6 km, the
351 maximum of fluorescence is observed at 513 nm while, in the UTLS, the maximum shifted to 560
352 nm.

353 When applying Eq.19 to estimate the contribution of smoke fluorescence into the Raman
354 water vapor channel of LILAS, we assumed that the ratio of the fluorescence backscattering at
355 466 nm to 408 nm (B_{466}/B_{408}), was constant. For the lidar in operation at GPI, the shortest available
356 wavelength was 438 nm, therefore, at least, one can estimate the variability of the ratio B_{472}/B_{438} .
357 Fig. 10 presents the vertical profiles of B_{472}/B_{438} for 11 smoke events occurring during the 15 May-
358 20 June 2023 period. Inside the PBL, this ratio varied in the 0.6–1.0 range. The lowest values
359 correspond to urban aerosols while, values of B_{472}/B_{438} close to 1.0, probably indicate the presence
360 of smoke particles inside the PBL. Smoke layers were observed mainly above 4.0 km and B_{472}/B_{438}
361 showed a tendency to increase in the UT. It is interesting that, for the period 15 May–1 June, the
362 ratio was close to 1.5 whereas after 1 June, it became close to 1.0, which can be related to changing
363 of smoke source. Mean value of B_{472}/B_{438} in the 4.0–11.0 km range over all observations is 1.38
364 with standard deviation of 0.23 (relative variation is about 17%). For the channels 466 nm and 408
365 nm the wavelength separation is larger, so one can expect a variation of B_{466}/B_{408} in the smoke
366 layer to be above that value. It points out the difficulties to face when the estimation of the
367 fluorescence contamination to the Raman water vapor channel is performed from a single
368 fluorescence channel at 466 nm. This issue was also discussed by Reichardt et al. (2023).

369

370 ***3.3 Estimation of fluorescence impact on water vapor Raman measurements***

371 Measuring the depolarization ratio at the water vapor Raman channel provides an
 372 opportunity to control/evaluate the presence of fluorescence leak in this channel. These
 373 depolarization measurements were performed over Lille during May – June 2023. Vertical profiles
 374 of water vapor depolarization ratio $\tilde{\delta}_w$ together with \tilde{n}_w , β_{532} , β_F , and G_F are shown in Fig.11 for
 375 the night 8-9 June and 10-11 June 2023. On 8-9 June the aerosols were confined mainly below 5
 376 km. The fluorescence capacity was about 1.0×10^{-4} below 3.0 km, but above, G_F increased up to
 377 2.5×10^{-4} , indicating to the presence of smoke particles. The depolarization ratio in the water vapor
 378 channel was about 2% in the height range 1.5–3.5 km, where the values of $\tilde{\delta}_w$ ranging within 1.8-
 379 2.0% were observed at this height range, where the contribution of fluorescence was insignificant.
 380 The depolarization ratio δ_w was low, because the interference filter at the water vapor channel
 381 selects only strongest Q-branch lines and most of rotational lines are blocked. The contribution of
 382 fluorescence becomes noticeable above 3.5 km where n_w dropped, resulting in an increase of $\tilde{\delta}_w$
 383 up to ~3%. Below 1 km height we also observed an increase of $\tilde{\delta}_w$ up to 2.2%, where fluorescence
 384 backscattering is enhanced. Similar values of $\tilde{\delta}_w$ were observed on 10-11 June, where the
 385 depolarization ratio increased up to 2.5% inside the smoke layer observed at ~3.75 km and below
 386 2.0 km.

387 As discussed in Sect. 2.2, the contribution of fluorescence to the WVMR channel can be
 388 derived from Eq.20 if $\tilde{\delta}_w$ and δ_F are measured simultaneously. Fig.12 presents the modeling of
 389 the relative error $\frac{\Delta n_w}{\tilde{n}_w}$, introduced by the fluorescence to the WVMR channel as a function of $\tilde{\delta}_w$.
 390 The computations are performed for different fluorescence depolarization ratios $\delta_F=50\%$, 60%,
 391 70% to include both smoke and urban particles. A depolarization ratio in the Raman water vapor
 392 channel in the absence of fluorescence was assumed to be $\delta_w=2\%$. For a depolarization ratio $\tilde{\delta}_w$
 393 below 3% the relative error $\frac{\Delta n_w}{\tilde{n}_w}$ did not exceed 3%. As follows from the fluorescence spectra in
 394 Fig.9, the fluorescence of urban particles increases towards shorter wavelengths, thus one can
 395 expect an impact of the urban aerosol fluorescence on the water vapor measurements. In practice,
 396 however, we did not observe values of $\tilde{\delta}_w$ exceeding 3% in the PBL, thus, contribution of aerosol

397 in the PBL is not critical. The reason is due to the low fluorescence capacity (about one order lower
398 than that of smoke) and higher water vapor content, comparing to the free troposphere.

399 Vertical profiles of $\tilde{\delta}_w$ shown in Fig.11 become noisy at heights where n_w is low, and thus
400 $\tilde{\delta}_w$ cannot be used for correction of the fluorescence effect in the upper troposphere. To overcome
401 this, we derived the parameter η from Eq.18 at low altitudes where $\tilde{\delta}_w$ values are available, and,
402 thus, these η values can be used to calculate Δn_w from Eq.19 in the entire height range. In such an
403 approach, however, one has to assume that the relationship between fluorescence cross sections at
404 466 nm and 408 nm remains constant with height. As discussed in Sect. 3.2, such assumption can
405 yield significant bias in the calculation of Δn_w , and, at this stage, we do not provide corrected
406 profiles of the WVMR.

407 For the accurate calculation of η one needs smoke events with strongly enhanced $\tilde{\delta}_w$ values,
408 which are usually observed in the smoke layers with low WVMR. Such suitable events are shown
409 on the nights of 26-27 May and 5-6 June 2023 in Fig.13. On 26-27 May a smoke layer
410 characterized by high fluorescence (β_F up to $5 \times 10^{-4} \text{ Mm}^{-1} \text{sr}^{-1}$) and low \tilde{n}_w (below 0.2 g/kg) values
411 is observed at 3.5 km. The relevant fluorescence depolarization ratio was about 47% and $\tilde{\delta}_w$
412 increased from 2% up to 12% in the middle of this layer. The parameter η calculated from Eq.18
413 inside this smoke layer was about $2 \times 10^{-3} \text{ (g/kg)/(Mm}^{-1} \text{sr}^{-1})$. On 5-6 June the depolarization ratio
414 $\tilde{\delta}_w$ in the smoke layer increased up to 10% and value of η was very similar. The values of η derived
415 for several smoke episodes varied in the range $(2-2.5) \times 10^{-3} \text{ (g/kg)/(Mm}^{-1} \text{sr}^{-1})$. To estimate Δn_w we
416 used the mean value of $\eta = 2.25 \times 10^{-3} \text{ (g/kg)/(Mm}^{-1} \text{sr}^{-1})$, which is suitable only for smoke, while for
417 particles in the PBL, η can have a different value. However, in the PBL, the low depolarization
418 ratios of $\tilde{\delta}_w$ prevented us from calculating η .

419 Fig.14 presents the vertical profiles of WVMR, the fluorescence backscattering and the error
420 Δn_w introduced by the fluorescence in WVMR on 26-27 May, 28-29 May and 16-17 June. Smoke
421 layers with strong fluorescence occurred systematically in our upper tropospheric observations.
422 The current LILAS system is not powerful enough for deriving accurate water vapor measurements
423 above 10 km, however an increase of \tilde{n}_w in the fluorescent smoke layers is visible. We remind that

424 Eq.19 for Δn_W contains the factor $\frac{1}{n_R}$ (inverse relative change of nitrogen number density), thus,
425 the fluorescence impact on WVMR will increase with height. The uncertainties $\frac{\Delta n_W}{\tilde{n}_W}$ for all events
426 considered are shown in Fig.14d. On 26-27 May and 28-29 May the uncertainty of $\frac{\Delta n_W}{\tilde{n}_W}$ at 11 km
427 is of the order of 100%. On 16 June the smoke layer is lower (at 9 km) and the uncertainty is about
428 50%. Our demonstration shows that smoke fluorescence can significantly impact the water vapor
429 measurements. The proposed approach, based on the analysis of the depolarization ratio of the
430 water vapor signal, has the potential for estimation and correction of this impact.

431 **4. Conclusion**

432 This study is one of the first efforts to measure the depolarization ratio of fluorescence of
433 the atmospheric aerosols. Analysis of more than 30 spring and summer smoke events allows
434 evaluation of the main aerosol intensive properties, including fluorescence capacity, particle and
435 fluorescence depolarization ratio. The fluorescence capacity of smoke in the troposphere varied
436 within $(2.5-10.0)\times 10^{-4}$, however, in spite of strong G_F variation, δ_F was remaining within a
437 relatively narrow interval 45-55%. Additional observations revealed that for smoke plumes in the
438 upper troposphere the fluorescence depolarization ratio increased up to 70%. At the moment, we
439 cannot fully explain the mechanism responsible for this δ_F increase. It can be related to complex
440 particle internal structure at high altitudes, as well as to the change of the chemical composition,
441 revealed by the shift of the maximum of the fluorescence spectra to longer wavelengths in the
442 upper troposphere (Fig. 9).

443 Inside the PBL, the fluorescence depolarization ratio was higher than that of smoke and
444 varied within the 50-70% range. Moreover, the fluorescence depolarization ratio of urban particles
445 strongly depends on the relative humidity and, in contrast to the elastic scattering, the
446 depolarization of fluorescence increases with RH. One possible origin of this phenomena could be
447 attributed to an increase of the rotational mobility of the molecules involved in the process of water
448 uptake.

449 The depolarization ratio of the Raman water vapor backscatter, in the absence of
450 fluorescence, appeared to be quite low ($\delta_W=2\pm 0.5\%$). As a result, the depolarization ratio of the
451 Raman water vapor backscatter is sensitive to the presence of strongly depolarized fluorescence

452 signals, and the contribution of fluorescence to the WVMR can be calculated from the measured
453 value $\tilde{\delta}_w$. However, with the lidar used in this work, measurements of $\tilde{\delta}_w$ are only possible up to
454 the middle troposphere, while the problem of the fluorescence interference is the most crucial in
455 UTLS. To estimate the impact of fluorescence on the WVMR in UTLS, the height independent
456 parameter η , linking fluorescence at 466 nm and at 408 nm, was used. Such an approach relies on
457 the assumption that η remains constant and allows only a rough estimation of the correction term
458 for the WVMR, Δn_w . One possible solution to increase the accuracy of Δn_w is to implement an
459 additional shorter wavelength channel (438 nm or even shorter). Another technical solution could
460 be considered as the depolarization ratio of Raman water vapor backscatter is low, therefore the
461 408 nm channel can be efficiently equipped with a polarizing cube. Thus, the depolarized channel
462 at 408 nm can be used for fluorescence measurements. As the polarizing cubes work in a wide
463 spectral range, so one can select a spectral region outside of the water vapor spectrum (400–418
464 nm) for fluorescence monitoring. We plan this experiment as well as other innovative approaches
465 with our future high-power fluorescence lidar, LIFE (Laser Induced Fluorescence Explorer),
466 whose start of operation is scheduled for the beginning of 2024.

467

468 **Data availability.** Lidar measurements are available upon request
469 (philippe.goloub@univ-lille.fr).

470

471 **Author contributions.** IV processed the data and wrote the paper. QH and TP performed the
472 measurements in Lille. PG supervised the project and helped with paper preparation. WB modified
473 LILAS for polarization measurements. MK and NK performed the measurements in Moscow. SK
474 analyzed transport of smoke layers and RM derived RH profiles from lidar measurements.

475 .

476 **Competing interests.** The authors declare that they have no conflict of interests.

477

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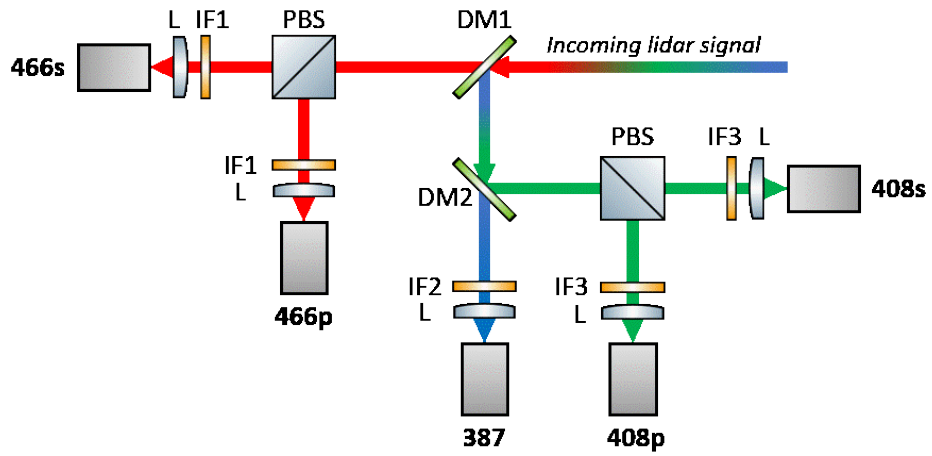
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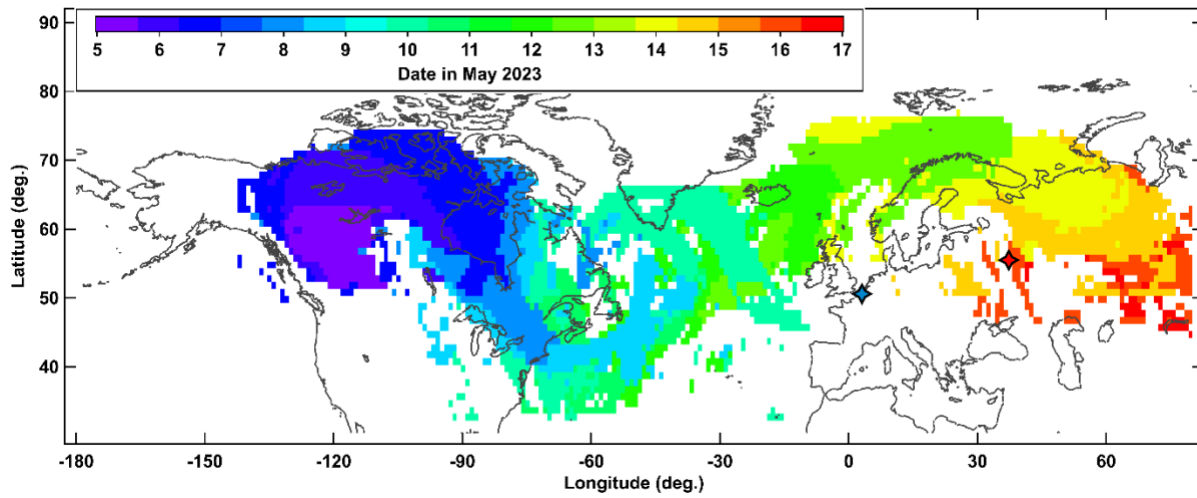
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592 Fig.1. Optical layout of depolarization measurements at 408 nm and 466 nm wavelengths. L –
593 lens; IF1- IF3 – interference filters, DM1, DM2 – dichroic mirrors, PBS – polarizing cube.

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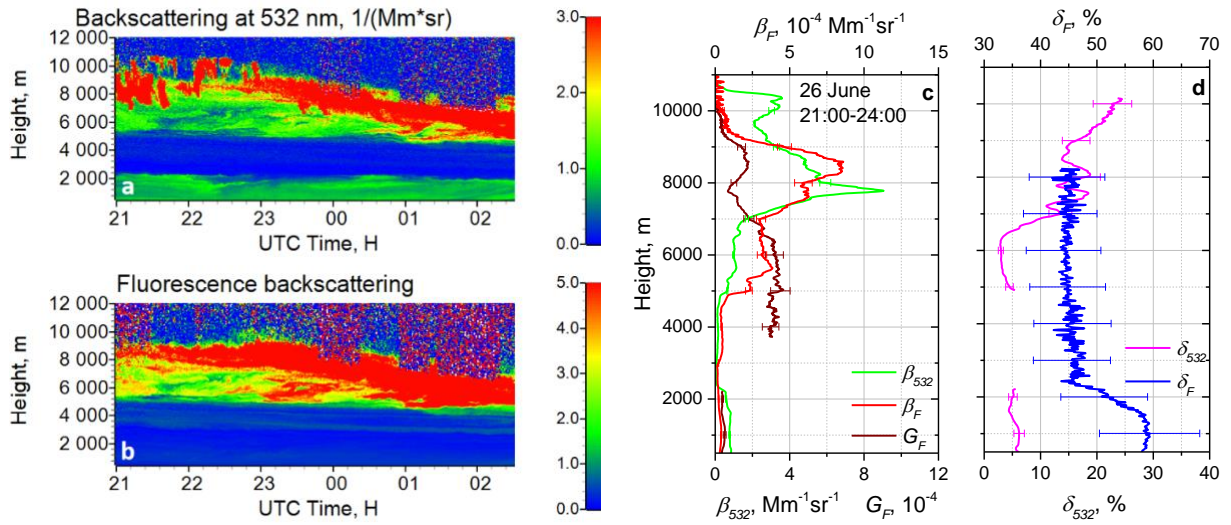


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598 Fig.2. Spatio-temporal evolution of the smoke plume from the wildfire event in Alberta, Canada
599 on 5 May 2023. Color-filled time-coded areas indicate the Aerosol Index (AI) values from the
600 OMPS-NPP instrument exceeding 0.5. The blue and red-filled stars indicate the location of Lille
601 and Moscow lidar stations, respectively.

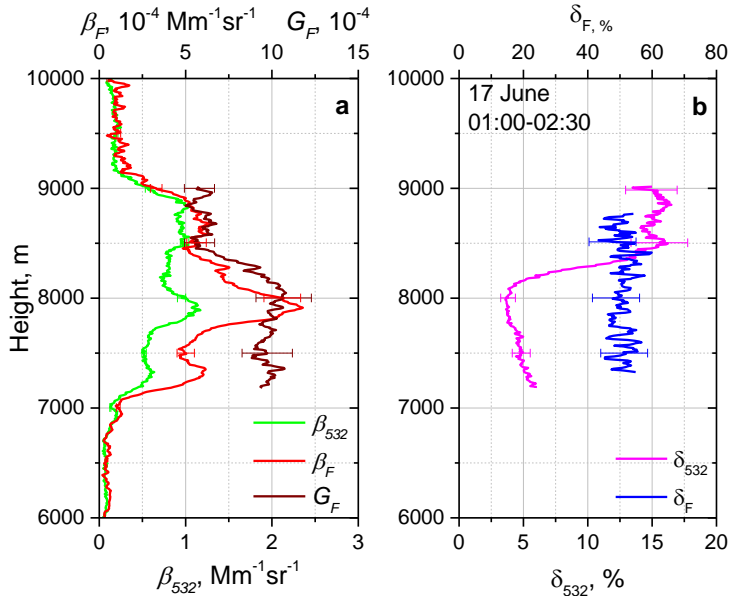
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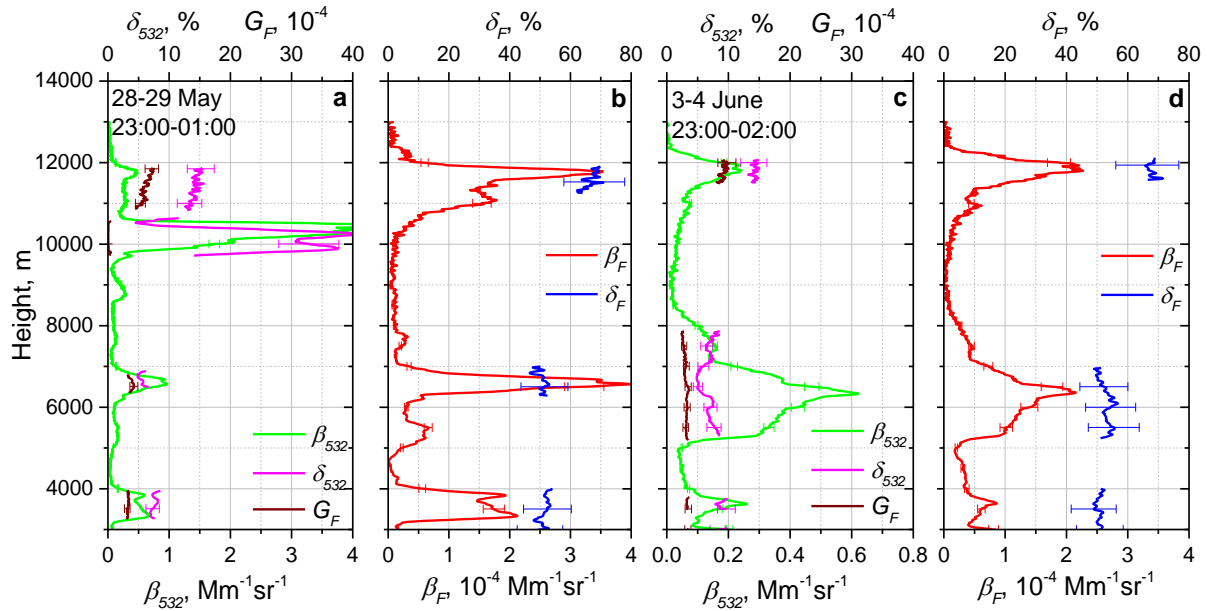
Fig.3. Smoke event on the night 26-27 June 2023 over Lille. Spatio-temporal distributions of (a) aerosol backscattering coefficient β_{532} and (b) fluorescence backscattering β_F (in $10^{-4} \text{ Mm}^{-1}\text{sr}^{-1}$). Vertical profiles of (c) the aerosol β_{532} and fluorescence β_F backscattering coefficients, the fluorescence capacity G_F ; (d) the particle δ_{532} and the fluorescence δ_F depolarization ratios.



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Fig.4. Vertical profiles of (a) aerosol β_{532} and fluorescence β_F backscattering coefficients, fluorescence capacity G_F and (b) particle δ_{532} and fluorescence δ_F depolarization ratios on the night 16-17 June 2023 for period 01:00-02:30 UTC over Lille.

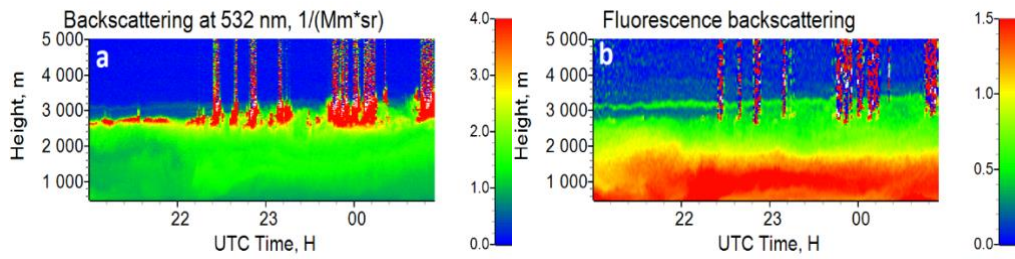
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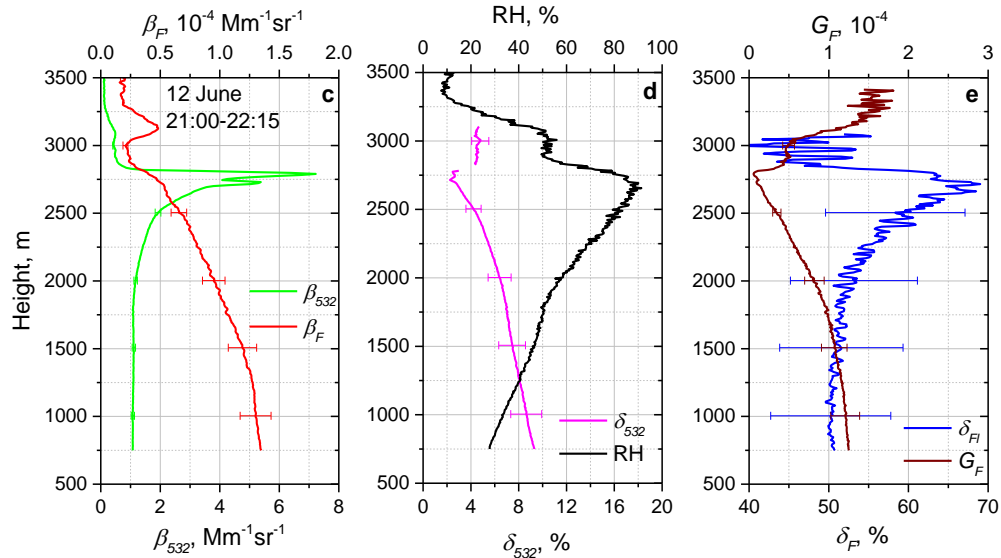
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Fig.5. Vertical profiles of (a, c) backscattering coefficient β_{532} , particle depolarization ratio δ_{532} , fluorescence capacity G_F and (b, d) fluorescence backscattering β_F and fluorescence depolarization ratio δ_F for two smoke episodes on the nights 28-29 May 2023 and 3-4 June 2023 over Lille.

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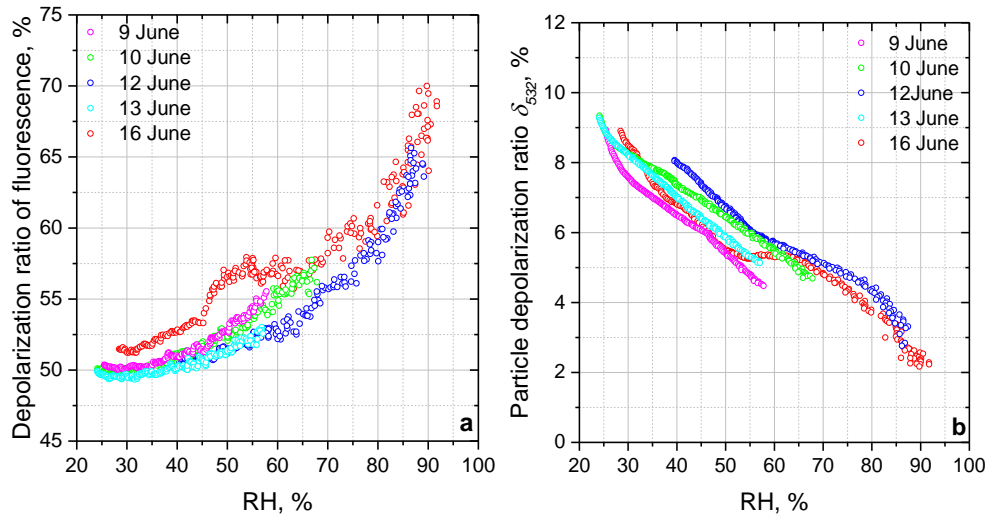
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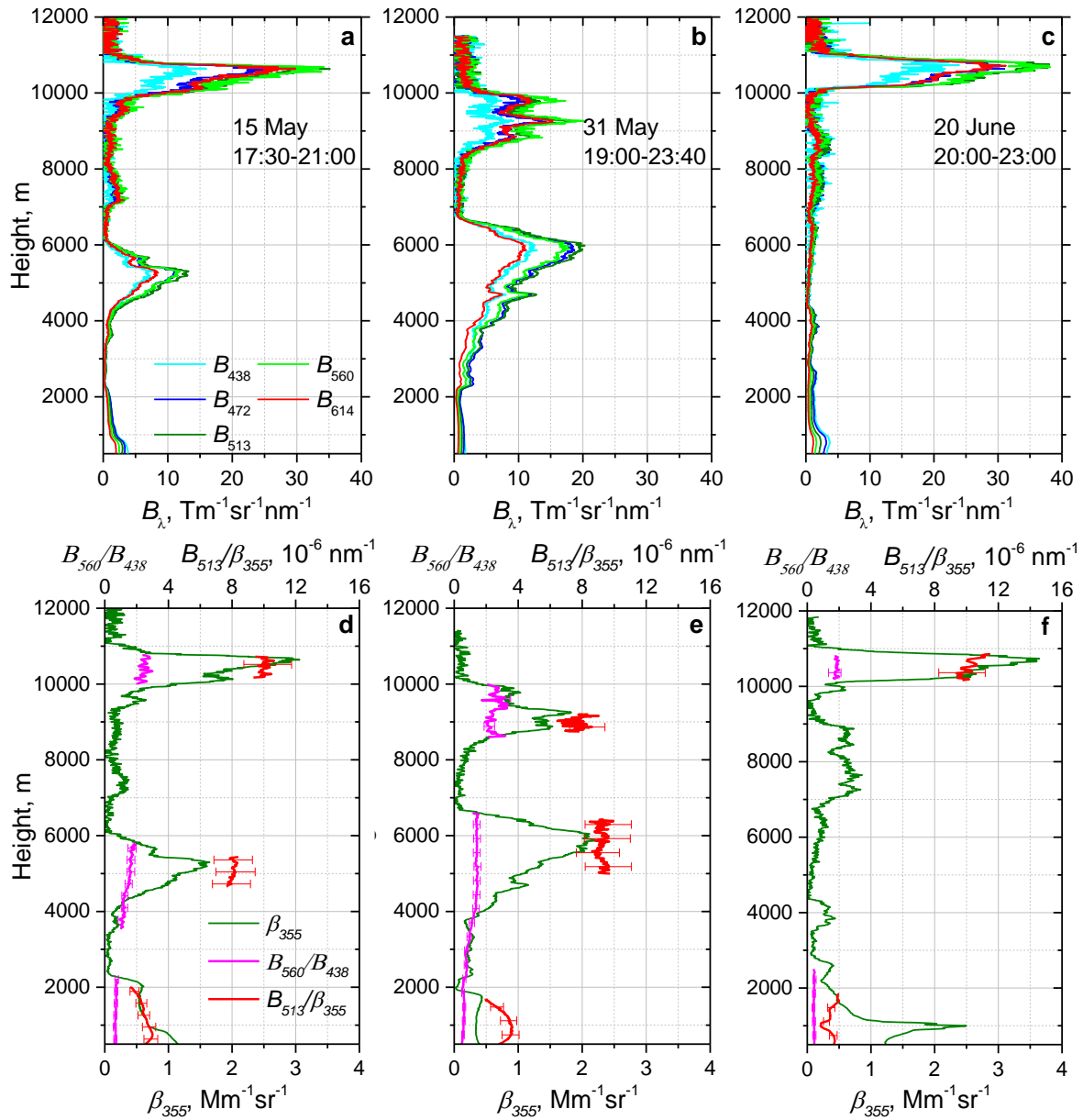
Fig.6. Particle hygroscopic growth in the PBL on the night 12-13 June 2023 over Lille. Spatio-temporal distributions of (a) aerosol backscattering coefficient β_{532} and (b) fluorescence backscattering β_F (in $10^{-4} \text{ Mm}^{-1} \text{ sr}^{-1}$). Vertical profiles of (c) aerosol β_{532} and fluorescence β_F backscattering coefficients; (d) particle depolarization ratio δ_{532} and the relative humidity RH; (e) fluorescence depolarization ratio δ_F and fluorescence capacity G_F for the time period 21:00-22:15 UTC.

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Fig.7. (a) Fluorescence depolarization ratio and (b) particle depolarization ratio δ_{532} as a function of the relative humidity in the PBL for the measurements on 9, 10, 12, 13, 16 June 2023 over Lille.



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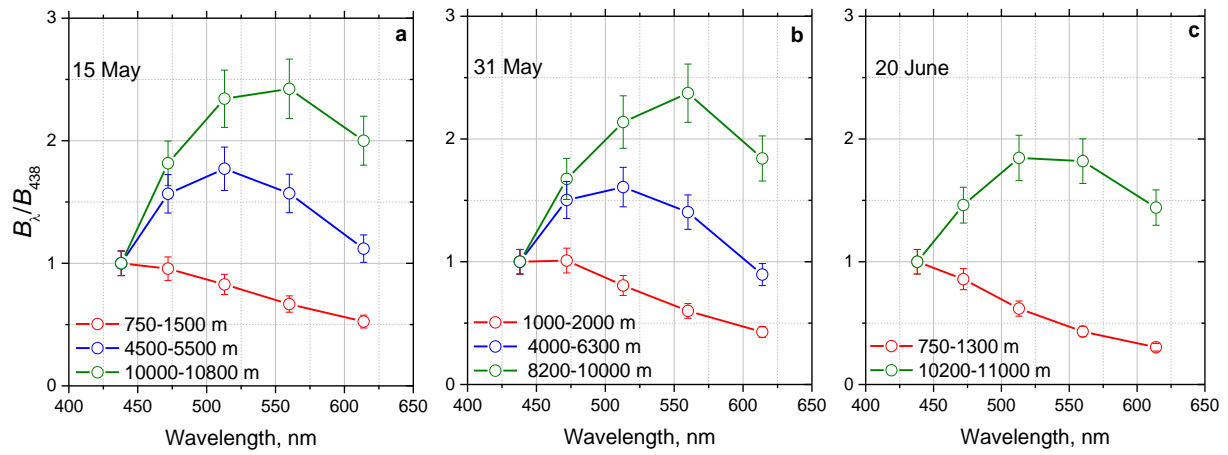
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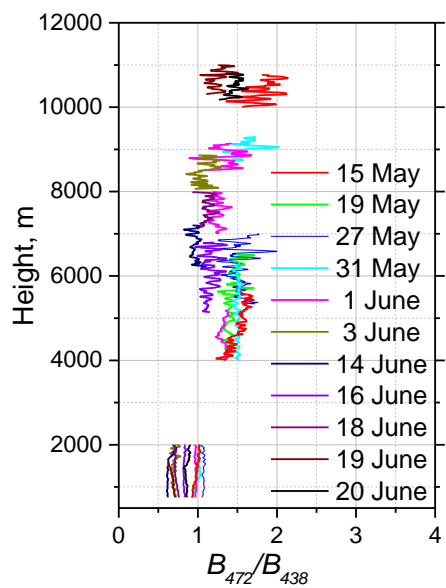
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Fig. 8. Fluorescence measurements over Moscow on 15 May, 31 May, 20 June 2023. Vertical profiles of (a-c) fluorescence spectral backscattering coefficients B_λ at 438, 472, 513, 560, 614 nm and (d-f) aerosol backscattering coefficient β_{355} , the ratio B_{560}/B_{438} and B_{513}/β_{355} . Measurements were performed at an angle of 48° to horizon.



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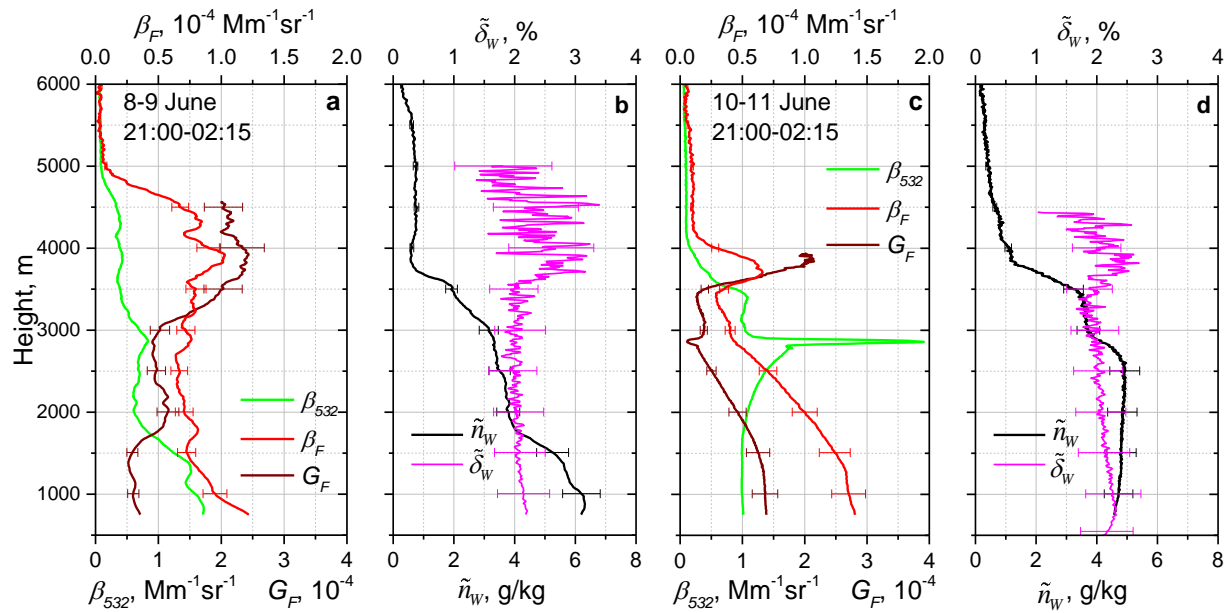
652 Fig.9. Fluorescence spectra B_λ/B_{438} at different height intervals measured during smoke episodes
 653 on 15 May, 31 May, 20 June 2023 over Moscow, for the same temporal intervals as in Fig.8.
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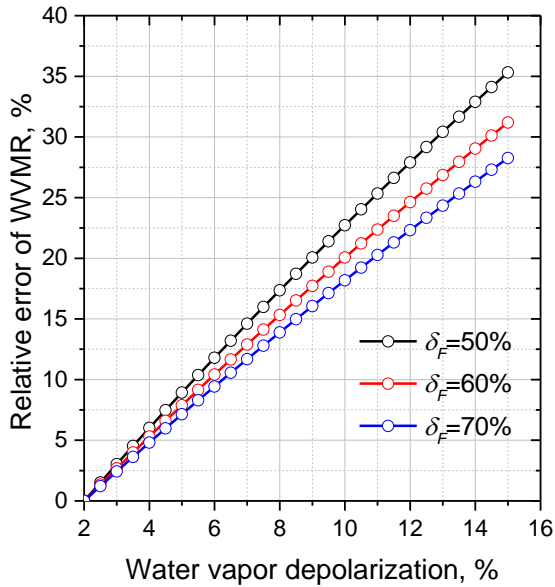
656 Fig.10. Height profiles of the ratio B_{472}/B_{438} for smoke episodes during 15 May – 20 June 2023
 657 over Moscow. Smoke layers start above 4 km up to 11 km.

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Fig.11. Impact of the aerosol fluorescence on the depolarization ratio in the water vapor Raman channel on the nights 8-9 and 10-11 June 2023 over Lille. Vertical profiles of (a, c) particle backscattering β_{532} , fluorescence backscattering β_F , fluorescence capacity G_F and (b, d) depolarization ratio $\tilde{\delta}_w$ of the water vapor Raman signal and the water vapor mixing ratio \tilde{n}_w .



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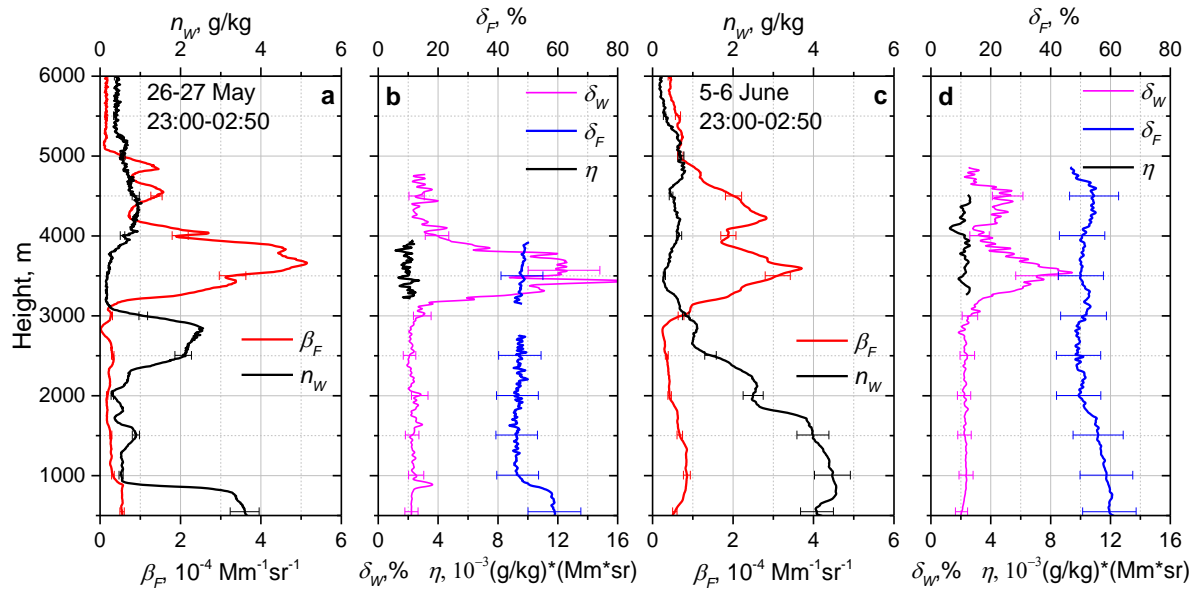
667 Fig.12. Relative error of water vapor mixing ratio (WVMR) $\frac{\Delta n_w}{\tilde{n}_w}$ induced by the fluorescence as

668 a function of depolarization ratio $\tilde{\delta}_w$ in the water vapor Raman channel for three values of
 669 fluorescence depolarization ratio $\delta_F=50\%$, 60% , 70% . The depolarization ratio of water vapor
 670 Raman backscatter in the absence of fluorescence is assumed to be $\delta_w=2\%$.

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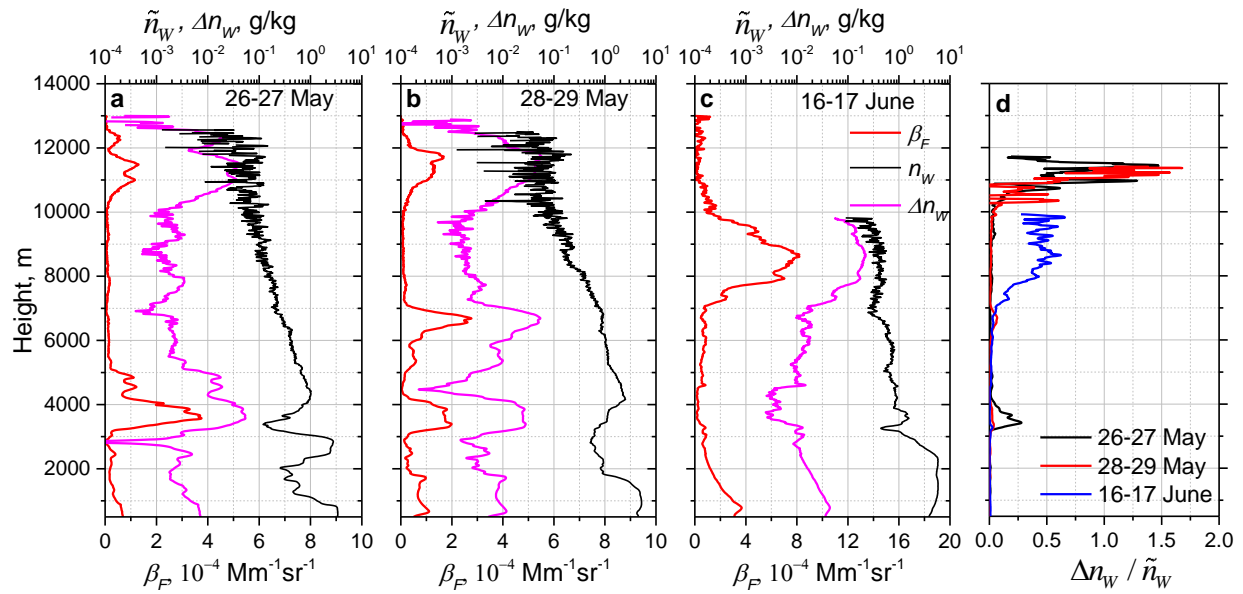


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676 Fig. 13. Fluorescence measurements over Lille on the night 26-27 May and 5-6 June 2023. (a, c)
677 Vertical profiles of the fluorescence backscattering β_F , the water vapor mixing ratio \tilde{n}_W , (b, d) the
678 depolarization ratio of the water vapor Raman signal $\tilde{\delta}_W$, the fluorescence depolarization ratio δ_F
679 and parameter η , describing contribution of the fluorescence to the water vapor channel.
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Fig.14. Impact of smoke fluorescence on the water vapor measurements. Vertical profiles of the fluorescence backscattering β_F , water vapor mixing ratio \tilde{n}_W and bias in water vapor channel Δn_W provided by the fluorescence of smoke for episodes on the nights (a) 26-27 May, (b) 28-29 May and (c) 16-17 June 2023 for time interval 21:00-02:30 UTC over Lille. (d) Error $\frac{\Delta n_W}{\tilde{n}_W}$ introduced

by smoke fluorescence for the three episodes.