

# 1 Long-term Evaluation of Commercial Air Quality Sensors: An 2 Overview from the QUANT Study

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17 **Abstract.** In times of growing concern about the impacts of air pollution across the globe, lower-cost sensor  
18 technology is giving the first steps in helping to enhance our understanding and ability to manage air quality issues,  
19 particularly in regions without established monitoring networks. While the benefits of greater spatial coverage and  
20 real-time measurements that these systems offer are evident, challenges still need to be addressed regarding sensor  
21 reliability and data quality. Given the limitations imposed by intellectual property, commercial implementations are  
22 often “black boxes”, which represents an extra challenge as it limits end-users' understanding of the data production  
23 process. In this paper we present an overview of the QUANT (Quantification of Utility of Atmospheric Network  
24 Technologies) study, a comprehensive 3-year assessment across a range of urban environments in the United  
25 Kingdom, evaluating 43 sensor devices, including 119 gas sensors and 118 particulate matter sensors, from multiple  
26 companies. QUANT stands out as one of the most comprehensive studies of commercial air quality sensor systems  
27 carried out to date, encompassing a wide variety of companies in a single evaluation and including two generations  
28 of sensor technologies. Integrated into an extensive data set open to the public, it was designed to provide a long-term  
29 evaluation of the precision, accuracy, and stability of commercially available sensor systems. To attain a nuanced  
30 understanding of sensor performance, we have complemented commonly used single-value metrics (e.g., Coefficient  
31 of Determination ( $R^2$ ), Root Mean Square Error (RMSE), Mean Absolute Error (MAE)) with visual tools. These  
32 include Regression plots, Relative Expanded Uncertainty (REU) plots, and Target plots, enhancing our analysis  
33 beyond traditional metrics. This overview discusses the assessment methodology, and key findings showcasing the  
34 significance of the study. While more comprehensive analyses are reserved for future detailed publications, the results

35 shown here highlight the significant variation between systems, the incidence of corrections made by manufacturers,  
36 the effects of relocation to different environments, and the long-term behaviour of the systems. Additionally, the  
37 importance of accounting for uncertainties associated with reference instruments in sensor evaluations is emphasised.  
38 Practical considerations in the application of these sensors in real-world scenarios are also discussed, and potential  
39 solutions to end-user data challenges are presented. Offering key information about the sensor systems' capabilities,  
40 the QUANT study will serve as a valuable resource for those seeking to implement commercial solutions as  
41 complementary tools to tackle air pollution.

42 **Keywords:** air pollution, commercial sensor systems, QUANT, long-term evaluation.

## 43 1. Introduction

44 Emerging lower-cost sensor systems<sup>1</sup> offer a promising alternative to the more expensive and complex monitoring  
45 equipment traditionally used for measuring air pollutants such as PM<sub>2.5</sub>, NO<sub>2</sub>, and O<sub>3</sub> (Okure et al., 2022). These  
46 innovative devices hold the potential to expand spatial coverage (Malings et al., 2020) and deliver real-time air  
47 pollution measurements (Tanzer-Gruener et al., 2020). However, concerns regarding the variable quality of the data  
48 they provide still hinder their acceptance as reliable measurement technologies (Karagulian et al., 2019; Zamora et  
49 al., 2020).

50 Sensors<sup>2</sup> face key challenges such as cross-sensitivities (Bittner et al., 2022; Cross et al., 2017; Levy Zamora et al.,  
51 2022; Pang et al., 2018), internal consistency (Feenstra et al., 2019; Ripoll et al., 2019), signal drift (A. Miech et al.,  
52 2023; Li et al., 2021; Sayahi et al., 2019), long term performance (Bulot et al., 2019; Liu et al., 2020) and data coverage  
53 (Brown & Martin, 2023; Duvall et al., 2021; Feinberg et al., 2018). Additionally, environmental factors such as  
54 temperature and humidity (Bittner et al., 2022; Farquhar et al., 2021; Crilley et al., 2018; Williams, 2020) can  
55 significantly influence sensor signals.

56 In recent years, manufacturers of both sensing elements (Han et al., 2021; Nazemi et al., 2019) and sensor systems  
57 have made significant technological advances (Chojer et al., 2020). For example, there are now commercial and non-  
58 commercial systems equipped with multiple detectors to measure distinct pollutants (Buehler et al., 2021; Hagan et  
59 al., 2019; Pang et al., 2021) helping to mitigate the effects of cross-interferences. Additionally, enhancements in  
60 electrochemical OEMs have been demonstrated in terms of their specificity (Baron & Saffell, 2017; Ouyang, 2020).

61 However, the complex nature of their responses, coupled with their dependence on local conditions means sensor  
62 performance can be inconsistent (Bi et al., 2020). This complicates the comparison of results or anticipating sensor  
63 future performance across different studies. Moreover, assessments of sensor performance found in the academic

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<sup>1</sup> The term “sensor systems” refers to sensors housed within a protective case, which includes a sampling and power system, electronic hardware and software for data acquisition, analog-to-digital conversion, data processing and their transfer (Karagulian et al., 2019). Unless specified otherwise, the term “sensor” will be used as a synonym of “sensor systems”. Other alternative names for “sensor systems” used here are “sensor devices” (or “devices”), “sensor units” (or “units”).

<sup>2</sup> In a narrower sense, “sensor” typically denotes the specific component within a sensor system that detects and responds to environmental inputs, producing a corresponding output signal. To distinguish this from the broader use of “sensor” as equivalent to “sensor system” in our text, we will utilise alternative terms such as “detector”, “sensing element”, or “OEM” (original equipment manufacturer) when referring specifically to this component, thereby preventing confusion.

64 literature often rely on a range of protocols (e.g., CEN (2021) and Duvall et al. (2021)) and data quality metrics (e.g.,  
65 Spinelle et al. (2017) and Zimmerman et al. (2018)), with many studies limited to a single-site co-location and/or  
66 short-term evaluations that do not fully account for broader environmental variations (Karagulian et al., 2019).

67 The calibration of any instrument used to measure atmospheric composition is fundamental to guarantee their accuracy  
68 (Alam et al., 2020; Long et al., 2021; Wu et al., 2022). Using out-of-the-box sensor data without fit-for-purpose  
69 calibration can produce misleading results (Liang & Daniels, 2022). An effective calibration not only involves  
70 identifying but also compensating for estimated systematic effects in the sensor readings, a process defined as a  
71 correction (for a detailed definition and differentiation of calibration and correction see JCGM, 2012). For standard  
72 air pollution measurement techniques, calibration is often performed in a controlled laboratory environment (Liang,  
73 2021). For example, for gases, a known concentration is sampled from a certified standard. Similarly, for PM, particles  
74 of known density and size are generated. Both gases and PM calibration are conducted under controlled airflow  
75 conditions.

76 Yet, the aforementioned challenges with lower-cost sensor-based devices suggest that such calibrations may not  
77 always accurately reflect real-world conditions (Giordano et al., 2021). A frequent approach involves co-locating  
78 sensors alongside regulatory instruments in their intended deployment areas and/or conditions and using data-driven  
79 methods to match the reference data (Liang & Daniels, 2022). Numerous studies have investigated the effectiveness  
80 of calibration methods for sensors e.g. (Bigi et al., 2018; Bittner et al., 2022; Malings et al., 2020; Spinelle et al., 2017;  
81 Zimmerman et al., 2018), including selecting appropriate reference instruments (Kelly et al., 2017), the need for  
82 regular calibration to maintain accuracy (Gamboa et al., 2023), the necessity of rigorous calibration protocols to ensure  
83 consistency (Kang et al., 2022), and transferability (Nowack et al., 2021) of results. Ultimately, the reliability and  
84 associated uncertainty of any applied calibration will influence the final sensor data quality.

85 For end-users to make informed decisions on the applicability of air pollution sensors, a realistic understanding of the  
86 expected performance in their chosen application is necessary (Rai et al., 2017). Despite this, there has been relatively  
87 little progress in clarifying the performance of sensors for air pollution measurements outside of the academic arena.  
88 This is largely due to the significant variability in both the number of sensors and the variety of applications tested,  
89 compounded by the proliferation of commercially available sensors/sensor systems with different configurations.  
90 Furthermore, the access to highly accurate measurement instrumentation and/or regulatory networks remains limited  
91 for those outside of the atmospheric measurement academic field (e.g. Lewis and Edwards (2016) and Popoola et al.  
92 (2018)). From a UK clean air perspective, this ambiguity represents a major problem. The lack of a consistent message  
93 undermines the exploitation of these devices' unique strengths, notably their capability to form spatially dense  
94 networks with rapid time resolution. Consequently, there is potential for a mismatch in users' expectations of what  
95 sensor systems can deliver and their actual operating characteristics, eroding trust and reliability.

96 In this work, as part of the UK Clean Air program funded QUANT project, we deployed a variety of sensor  
97 technologies (43 commercial devices, 119 gas and 118 PM measurements) at 3 representative UK urban sites —  
98 Manchester, London and York— alongside extensive reference measurements, to generate the data for an  
99 comprehensive in-depth performance assessment. This project aims to not only evaluate the performance of sensor  
100 devices in a UK urban climatological context but also provide critical information for the successful application of  
101 these technologies in various environmental settings. To our knowledge, QUANT is the most extensive and longest-  
102 running evaluation of commercial sensor systems globally to date. Furthermore, we tested multiple manufacturers'  
103 data products, such as out-of-the-box data versus locally calibrated data, for a significant number of these sensors to

104 understand the implications of local calibration. This comprehensive approach offers unprecedented insights into the  
 105 operational capabilities and limitations of these sensors in real-world conditions. Significantly, some of the insights  
 106 gathered during QUANT have contributed to the development of the Publicly Available Specification (PAS 4023,  
 107 2023), which provides guidelines for the selection, deployment, maintenance, and quality assurance of air quality  
 108 sensor systems. While this manuscript serves as an initial overview, detailed analyses of the measured pollutants and  
 109 study phases, offering a more comprehensive perspective on sensor performance, are planned for future publications.

110 In the following sections, we delve into the methodology and provide an overview of the QUANT dataset, as well as  
 111 a discussion of some of the key findings and potential considerations for end-users.

## 112 2. QUANT study design

113 To capture the variability of UK urban environments, identical units were installed at three carefully selected field  
 114 sites. Two of these sites are highly instrumented urban background measurement supersites: the London Air Quality  
 115 Supersite (LAQS; for more details, refer here: [https://uk-air.defra.gov.uk/networks/site-info?site\\_id=HPI](https://uk-air.defra.gov.uk/networks/site-info?site_id=HPI)) and the  
 116 Manchester Air Quality Supersite (MAQS; for more details, see: <http://www.cas.manchester.ac.uk/restools/firs/>),  
 117 located in densely populated urban areas with unique air quality challenges. The third site is a roadside monitoring  
 118 site in York, which is part of the Automatic Urban and Rural Network (AURN; refer here for more details: [https://uk-  
 119 air.defra.gov.uk/networks/site-  
 120 info?uka\\_id=UKA00524&search=View+Site+Information&action=site&provider=archive](https://uk-air.defra.gov.uk/networks/site-info?uka_id=UKA00524&search=View+Site+Information&action=site&provider=archive)), representing a urban  
 121 environment more influenced by traffic. This selection strategy ensures that the QUANT study's findings reflect the  
 122 dynamics of urban air quality across different UK settings, while providing comprehensive reference measurements.  
 123 Further details about each site can be found in Section S1 in the Supp.

### 124 2.1 Main study

125 The Main QUANT assessment study aimed to perform a transparent long-term (19 Dec 2019 - 31 Oct 2022) evaluation  
 126 of commercially available sensor technologies for outdoor air pollution monitoring in UK urban environments. Four  
 127 units of five different commercial sensor devices (Table 1) were purchased in Sept 2019 for inclusion in the study,  
 128 with the selection criteria being: market penetration and/or previous performance reported in the literature, ability to  
 129 measure pollutants of interest (e.g. NO<sub>2</sub>, NO, O<sub>3</sub>, and PM<sub>2.5</sub>), and capacity to run continuously reporting high time  
 130 resolution data (1-15 min data) ideally in near real-time (i.e., available within minutes of measurement) with data  
 131 accessible via an API.

132 **Table 1. Main QUANT devices description. The 20 units, all commercially available and ready for use as-is, offered 56 gas  
 133 and 56 PM measurements in total. For a detailed description of the devices see Section S3 in the Supp.**

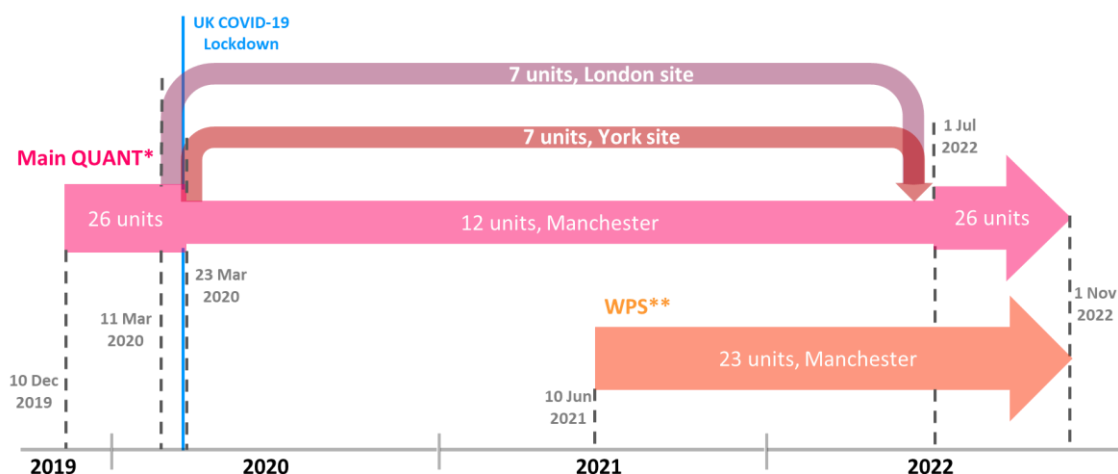
Product* (# units)	Company <sup>3</sup>	Measurements								Cost (£)**
		NO	NO <sub>2</sub>	O <sub>3</sub>	CO	CO <sub>2</sub>	PM <sub>1</sub>	PM <sub>2.5</sub>	PM <sub>10</sub>	
AQY (4)	Aeroqual	-	✓	✓	-	-	-	✓	✓	~4.7K

<sup>3</sup> Throughout this article, the terms “manufacturers” and “company” are used interchangeably to refer to entities that produce, and/or sell sensor systems or devices. This usage reflects the industry practice of referring to businesses involved in the production and distribution of technology products without distinguishing between their roles in manufacturing or sales.

AQM (4)	AQMesh	✓	✓	✓	-	✓	✓	✓	✓	~8.6K
Ari (4)	QuantAQ	✓	✓	✓	✓	✓	✓	✓	✓	~8.6K
PA (4)	PurpleAir	-	-	-	-	-	✓	✓	✓	~0.3K
Zep (4)	EarthSense	✓	✓	✓	-	-	✓	✓	✓	~7K

\*AQY: Aeroqual; AQM: AQMesh; Ari: Arisense; PA: PurpleAir; Zep: Zephyr. \*\*Cost (Sep 2019) per unit including UK taxes and associated contractual costs (i.e., communication, data access, sensor replacement, etc.).

134 Initially, all the sensors were deployed in Manchester for approximately 3 months (mid-Dec 2019 to mid-Mar 2020)  
 135 before being split up amongst the three sites (Fig. 1). At least one unit per brand was re-deployed to the other two  
 136 sites (mid-March 2020 to early-July 2022) leaving two devices per company in Manchester to assess inter-device  
 137 consistency. In the final 4 months of the study, all the sensor systems were relocated back to Manchester (early July  
 138 2022 to the end of October 2022).



\*: Aeroqual (x4), AQMesh (x4), Zephyr (x4), QuantAQ (x4), PurpleAir (x10)

\*\* : AQMesh (x3), Bosch (x2), Clarity (x3), Kunak (x3), Oizom (x2), QuantAQ (x3), South Coast Science (x2), Respirer Living Sciences (x2), Vortex (x3)

139

140 **Figure 1. Main QUANT and Wider Participation Study (WPS) timeline.**

141 **2.2 Wider Participation Study**

142 The Wider Participation Study (WPS) was a no-cost complementary extension of the QUANT assessment, specifically  
 143 designed to foster innovation within the air pollution sensors domain. This segment of the study took place entirely at  
 144 the MAQS from 10th June 2021 to 31st October 2022 (Fig. 1). It included a wider array of commercial platforms (9  
 145 different sensor systems brands), and offered manufacturers the opportunity to engage in a free-of-charge impartial  
 146 evaluation process. Although participation criteria matched those of the Main QUANT study, a key distinction lay in  
 147 the voluntary nature of participation: manufacturers were invited to contribute multiple sensor devices throughout the  
 148 WPS study (see Table 2). Participants were able to demonstrate their systems' performance against collocated high-  
 149 resolution (1-minute) reference data at a state-of-the-art measurement site such as the Manchester supersite.

150 **Table 2. The 23 WPS devices deployed at the Manchester supersite, all commercially available and ready for use as-is,**  
 151 **provided 63 gases and 62 PM measurements in total. For a detailed description of the devices see the Section S4 in the Supp.**

Product* (# units)	Company	Measurements							
		NO	NO <sub>2</sub>	O <sub>3</sub>	CO	CO <sub>2</sub>	PM <sub>1</sub>	PM <sub>2.5</sub>	PM <sub>10</sub>
Mod (3)	QuantAQ	-	-	-	-	-	✓	✓	✓
AQM (3)	AQMesh	✓	✓	✓	✓	✓	✓	✓	✓
Atm (2)	RLS**	-	-	-	-	-	✓	✓	✓
IMB (2)	Bosch	-	✓	✓	-	-	-	✓	✓
Poll (2)	Oizom	✓	✓	✓	✓	✓	-	✓	✓
AP (3)	Kunak	✓	✓	✓	✓	✓	✓	✓	✓
SA (3)	Vortex IoT	-	✓	✓	-	-	-	✓	✓
NS (3)	Clarity	-	✓	-	-	-	✓	✓	✓
Prax (2)	SCS***	✓	✓	✓	✓	✓	✓	✓	✓

152 \*Mod: Modulair; AQM: AQMesh; Atm: Atmos, Poll: Polludrone; AP: Kunak Air Pro; SA: Silax Air, NS: Node-S, Prax: Praxis.

153 \*\*RLS: Respirer Living Sciences. \*\*\*SCS: South Coast Science.

## 154 2.3 Sensor deployment and data collection

155 All sensor devices were installed at the measurement sites as per manufacturer recommendations, adhering strictly to  
156 manufacturers' guidelines for electrical setup, mounting, cleaning, and maintenance. Since all deployed systems were  
157 designed for outdoor use, no additional protective measures were necessary. Each of the systems were mounted on  
158 poles acquired specifically for the project or on rails at the co-location sites, without the need for special protections.  
159 Following the manufacturer's suggestions, sensors were positioned within 3 metres of the reference instruments' inlets.  
160 Custom electrical setups were developed for each sensor type, incorporating local energy sources and weather-  
161 resistant safety features, alongside security measures to deter vandalism and ensure uninterrupted operation. Routine  
162 maintenance was conducted monthly, although the COVID-19 pandemic necessitated longer intervals between visits.  
163 Despite these obstacles, efforts to maintain sensor security and functionality continued unabated, employing both  
164 physical safeguards and remote monitoring to preserve data integrity.

165 In addition to the device supplier's own cloud storage (accessed on-demand via each supplier's web portals), an  
166 automated daily scraping of each company's API was performed to save data onto a secure server at the University  
167 of York to ensure data integrity. Unlike other brands that utilise mobile data connections, PurpleAir sensors rely on  
168 WiFi for data transmission. Due to poor internet signal at the sites, we locally collected and manually uploaded  
169 readings for these units. Minor pre-processing was applied at this stage, including temporal harmonisation to ensure  
170 that all measurements had a minimum sampling period of 1-minute, ensuring consistency in measurement units and  
171 labels, and coercing into the same format to allow for full compatibility across sensor units. No additional  
172 modifications to the original measurements were applied; missing values were kept as missing and no additional flags  
173 were created based on the measurements beyond those provided by the manufacturers. For an overview of the sensor  
174 measurands and their corresponding data time resolutions as provided by the companies participating in the Main  
175 QUANT study and the WPS, please see Seccion S3 and S4 (Table S4 and S5) respectively.

## 176 2.4 Data products and co-located reference data

177 In addition to providing an independent assessment of sensor performance, QUANT also aimed to contribute to device  
178 manufacturers to help advance the field of air pollution sensors. During QUANT, device calibrations were performed  
179 solely at the discretion of the manufacturers without any intervention from our team, thus limiting the involvement of  
180 manufacturers in the provision of standard sensor outputs and unit maintenance as would be required by any standard  
181 customer. This approach enabled manufacturers to independently assess and benchmark their sensors' performance,  
182 using provided reference data to potentially develop calibrated data products. It's noteworthy that not all manufacturers  
183 chose to utilise these data for corrections or enhancements. However, those who did were expected to create and  
184 submit calibrated data products, subsequently named as "out-of-box" (initial data product), "cal1" (first calibrated  
185 product), and "cal2" (second calibrated product). This differentiation highlighted the varying degrees of engagement  
186 and application of the reference data by different manufacturers. Figures S2 and S3 (section S3 and S4 respectively)  
187 show a time-line of the different data products.

188 To this end, three separate 1-month periods of reference data, spaced every 6 months, were shared with each supplier,  
189 provisional data soon after each period, and ratified data when available. All reference data were embargoed until it  
190 was released to all manufacturers simultaneously to ensure consistency across manufacturers. For an overview of  
191 reference and equivalent-to-reference instrumentation, as defined in the European Union Air Quality Directive  
192 2008/50/EC (hereafter referred to as EU AQ Directive), at each site, please refer to Section S2 (Table S1). For details  
193 on the quality assurance procedures applied to the reference instruments, see Table S2. To see the dates and periods  
194 of the shared reference data refer to Table S3.

### 195 **3. Results and discussion**

196 A key challenge in sensor performance evaluation is the high spatial and temporal variability errors that impact the  
197 accuracy of their readings, making the application of laboratory corrections more challenging. Furthermore, the  
198 overreliance on global performance metrics is a significant concern in sensor assessment. The Coefficient of  
199 Determination ( $R^2$ ), Root Mean Squared Error (RMSE), and Mean Absolute Error (MAE) are among the most popular  
200 single-value metrics for evaluating sensor performance, alongside others (e.g., the bias, the slope and intercept of the  
201 regression fit). However, while single-value metrics offer an overview of performance, they can be limiting or  
202 misleading. They condense vast amounts of data into a single value, simplifying complexity at the expense of a  
203 nuanced understanding of error structures and information content (Diez et al., 2022), potentially overlooking critical  
204 aspects of sensor performance (Chai & Draxler, 2014). Visualisation tools (such as Regression plots, Target plots,  
205 and Relative Expanded Uncertainty plots) complement these metrics, allowing end users to identify relevant features,  
206 which could be beyond the scope of global metrics. For additional details on the metrics utilised in this study, including  
207 some of their limitations and advantages refer to section "S5. Performance Metrics". This section also provides a  
208 summary of current guidelines and standardisation initiatives, which may offer a foundation for end-users to select  
209 appropriate metrics for their own analyses (refer to table S6). For further discussion on metrics and visualisation tools  
210 for performance evaluation, readers are directed to Diez et al. (2022).

211 In response to these challenges, the QUANT assessment represents the most extensive independent appraisal of air  
212 pollution sensors in UK urban atmospheres. As the results presented here illustrate, QUANT is dedicated to examining  
213 sensor performance through multiple complementary metrics and visualisation tools, aiming to integrate these to  
214 accurately reflect the complexity of this dataset. This methodology promotes a nuanced understanding of sensor  
215 performance, extending beyond the limitations of conventional global single-value metrics.

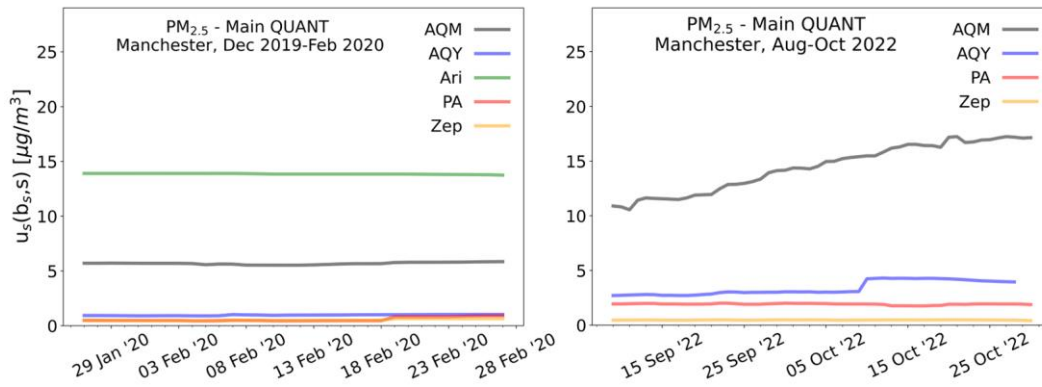
216 Furthermore, by providing open access to the dataset, we encourage stakeholders to explore and utilise the data  
217 according to their unique needs and contexts, as detailed in the “Data Availability” section. In addition, we have  
218 developed a publicly accessible analysis platform (<https://shiny.york.ac.uk/quant/>), designed for straightforward  
219 offline analysis of the QUANT dataset. This platform enables users to interactively visualise the data through various  
220 representations, such as time series, regression plots, and Bland-Altman plots. It also offers statistical parameters  
221 (including regression equation,  $R^2$ , and RMSE) for analysing different pollutants, selecting specific sensors or  
222 manufacturers, and comparing across various co-location timeframes.

223 The following sections aim to provide an overview of the data and provide initial findings, with a focus on those that  
224 are most relevant to end-users of these technologies. The majority of examples presented here focus on  $PM_{2.5}$  and  
225  $NO_2$  measurements, due to both a larger dataset available for these pollutants and their critical role in addressing the  
226 exceedances that predominantly impact UK air quality. All metrics and plots presented here are based on 1-hour  
227 averaged data. Unless otherwise specified, a data inclusion criterion of 75% was uniformly applied across our analyses  
228 to ensure the reliability and representativeness of the results. This threshold aligns with the EU AQ Directive, which  
229 mandates this proportion when aggregating air quality data and calculating statistical parameters. To highlight broad  
230 implications and insights into sensor technology, rather than focusing on the performance of specific manufacturers,  
231 figures illustrating brand-specific features have been anonymized. This is intended to prevent potential bias and  
232 encourage a holistic view of the data, ensuring interpretations remain focused on general trends rather than isolated  
233 examples.

### 234 3.1 Inter-device precision

235 Inter-device precision refers to the consistency of measurements across multiple identical devices (i.e., same brand  
236 and model), an important characteristic to ensure the reliability of sensor outputs over time (Moreno-Rangel et al.,  
237 2018). During QUANT, all the devices were collocated for the first 3 months and the final 3 months of the deployment  
238 to assess inter-device precision and its changes over time. Fig. 2 shows the inter-device precision (as defined by the  
239 CEN/TS 17660-1:2021, i.e., the “between sensor system uncertainty” metric:  $u_s(b_s, s)$ ) of  $PM_{2.5}$  measurements during  
240 these periods. For an overview of  $NO_2$  and  $O_3$  inter-device precision, see the “S6. Complementary plots” section in  
241 the supplementary (figures S4 and S5). While most of the companies display a certain level of inter-device precision  
242 stability in each period (except for one, with a seemingly upward trend in the final period), there are evident long-  
243 term changes. Notably, out of the four manufacturers assessed in the final period (each having 3 devices running  
244 simultaneously), three experienced a decline in their inter-device precision compared to two years earlier. This is  
245 likely due to both hardware degradation but also drift in the calibration, which at this point had been applied between  
246 16 and 34 months prior (depending on the manufacturer). For extended periods, inconsistencies among devices from  
247 the same manufacturer might emerge, leading to varying readings under similar conditions. Consequently, data  
248 collected from different devices may not be directly comparable, which could result in inaccuracies or  
249 misinterpretations when analysing air quality trends or making decisions.



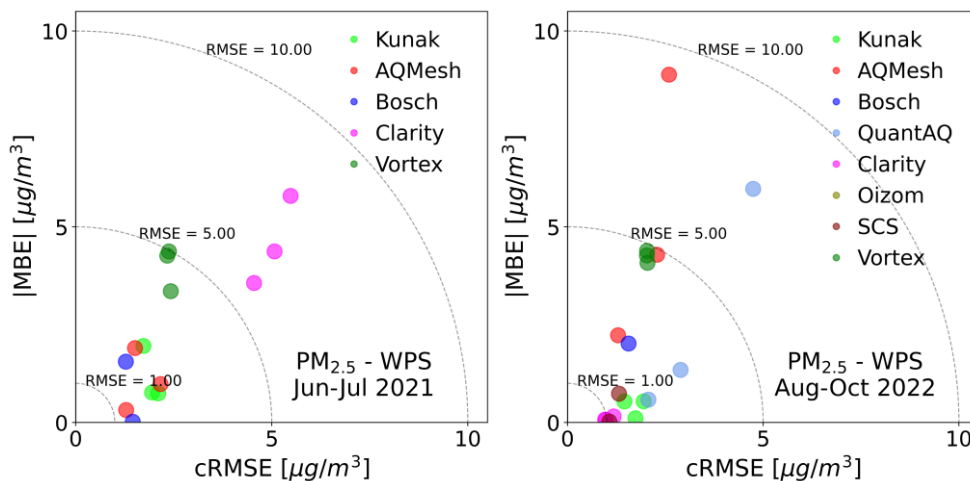


250  
 251 **Figure 2. The inter-device precision of PM<sub>2.5</sub> measurements from “identical” devices across the 5 companies participating**  
 252 **in QUANT is assessed using the “between sensor system uncertainty” metric (defined by the CEN/TS 17660-1:2021 as  $u_s(b_s, s)$ ).**  
 253 **Each line represents this metric as a composite of all sensors per brand (excluding units with less than 75% data) within**  
 254 **a 40-day sliding window.**

255 It is worth noting that the inter-device precision provides no information on the accuracy of the sensor measurements;  
 256 a batch of devices may provide a highly consistent, but also highly inaccurate measurement of the target pollutant.

257 The “target plot” (as shown in Fig. 3) is a tool commonly used to depict the bias/variance decomposition of an  
 258 instrument’s error relative to a reference (for more details see Jolliff et al. (2009)). The mean bias error (MBE) is used  
 259 to characterise accuracy and precision is quantified by the centered Root Mean Squared Error (cRMSE, e.g. Kim et  
 260 al. (2022) also called unbiased Root Mean Squared Error (uRMSE, e.g. Guimarães et al. (2018)). Fig. 3 visualises the  
 261 performance of a set of PM<sub>2.5</sub> sensors of the WPS deployment for the first 2 months (out-of-box data) and the last 3  
 262 months of colocation (manufacturer-supplied calibrations). In addition to showcasing inter-device precision, Fig. 3  
 263 also serves as a transition to accuracy evaluation (the focus of the subsequent section).

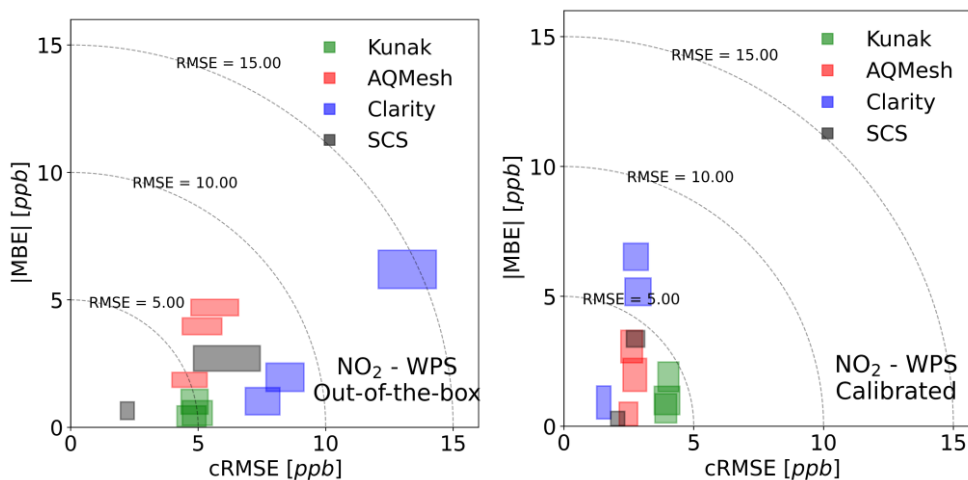
264



265  
 266 **Figure 3. Target diagrams for the WPS PM<sub>2.5</sub> measurements during the initial co-location period (Jun-Jul 2021, left) and**  
 267 **final co-location period (Aug-Oct 2022, right). The error (RMSE) for each instrument is decomposed into the MBE (y-axis)**  
 268 **and cRMSE (x-axis). Each point represents an individual sensor device, with duplicate devices having the same colour.**  
 269 **Since only units with more than 75% of the data were considered, the plot on the right shows fewer units than the plot on**  
 270 **the left.**

### 271 3.2 Device accuracy and co-location calibrations

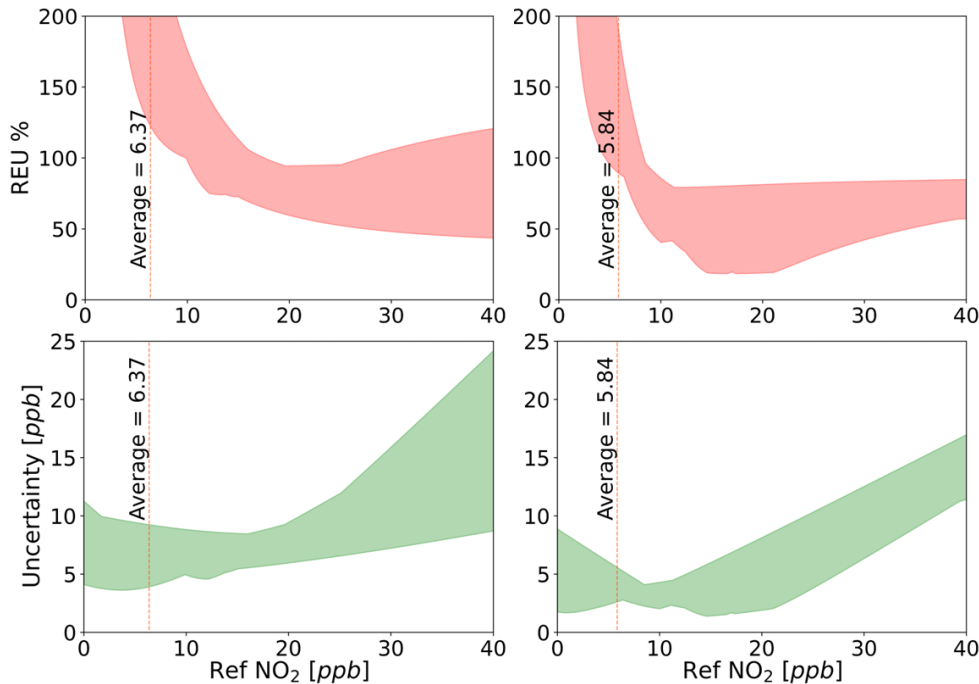
272 Sensor measurement accuracy denotes how close a sensor's readings are to reference values (Wang et al., 2015).  
273 Characterising this feature is imperative for establishing sensor reliability and making informed decisions based on  
274 its data. Fig. 4 shows that co-location calibration can greatly impact observed NO<sub>2</sub> sensor performance in a number  
275 of ways. Firstly, measurement bias is often, but not always, reduced following calibration, as evidenced by a general  
276 trend for devices to migrate towards the origin (RMSE = 0 ppb). Secondly, it can help to improve within-manufacturer  
277 precision, as evidenced by sensor systems from the same company grouping more closely as the right plot in Fig. 4  
278 shows. The figure also highlights a fundamental challenge with evaluating sensor systems: the measured performance  
279 can vary dramatically over time—and space—as the surrounding environmental conditions change. To quantify this,  
280 95% Confidence Intervals (CIs) were estimated for each device using bootstrap simulation and are visualised as a  
281 shaded region. For the out-of-the-box data, these regions are noticeably larger than in the calibrated results for most  
282 manufacturers, suggesting that colocation calibration has helped to tailor the response of each device to the specific  
283 site conditions. This observation suggests that colocation calibration effectively improves each device's response to  
284 particular site conditions. This improvement is underscored by the more substantial reduction in the cRMSE  
285 component compared to the MBE. The cRMSE, representing the portion of error that persists after bias removal,  
286 essentially measures errors attributable to variance within the data space. In the context of out-of-the-box data, this  
287 “data space” spans all potential deployment locations used by manufacturers for initial calibration model training (i.e.,  
288 before shipping the sensors for the QUANT study), thus exhibiting high variability. However, applying site-specific  
289 calibration significantly narrows this variability, leveraging local training data to minimise variance.



290  
291 **Figure 4. Effect of colocation calibration on NO<sub>2</sub> sensor accuracy. The accuracy is quantified using RMSE, which is**  
292 **decomposed into MBE (y-axis) and cRMSE (x-axis). 95% confidence regions were estimated using bootstrap sampling. The**  
293 **left panel displays results from the period Jun - Jul 2021 (‘out-of-the-box’ data), while the right-hand panel summarises**  
294 **Aug 2021 when calibrations were applied for all the WPS manufacturers.**

295 However, it is important to note a limitation of Target Plots: they primarily focus on sensor behaviour around the  
296 mean. Therefore, the collective improvement evidenced by Fig. 4 might be only partial. For applications where it is  
297 important to understand how calibrations impact lower or higher percentiles, considering other metrics or visual tools  
298 would be advisable. An example of this is the absolute and Relative Expanded Uncertainty (REU, defined by the  
299 Technical Specification CEN/TS 17660-1:202). Unlike the more commonly used metrics such as R<sup>2</sup>, RMSE, and  
300 MAE, which measure performance of the entire dataset, the REU offers a unique “point by point” evaluation, enabling

301 its representation in various graphical forms, such as time series or concentration space (for the REU mathematical  
 302 derivation, refer to section “S5. Performance Metrics”). The REU approach also incorporates the uncertainty of the  
 303 reference method into its assessment, highlighting the intrinsic uncertainty present in all measurements, including  
 304 those from reference instruments. This consideration of reference uncertainty is crucial for a holistic understanding of  
 305 sensor performance and calibration effectiveness. For a comprehensive discussion on this, refer to Diez et al. (2022).  
 306 Fig. 5 illustrates how NO<sub>2</sub> calibrations might not only improve collective performance around the mean (as indicated  
 307 by the dotted red line in Fig. 5 and previously displayed in the target plot) but across the entire concentration range.



308  
 309 **Figure 5. The top plots display the REU (%) across the concentration range, while the bottom plots depict the Absolute**  
 310 **Uncertainty (ppb) —both before (left plots) and after (right plots) calibrating NO<sub>2</sub> WPS systems. The shaded areas**  
 311 **represent the collective variability evolution (all sensors from all companies) of both metrics. These plots were constructed**  
 312 **using the minimum and maximum value of the REU and the Absolute Uncertainty for the entire concentration range.**

313 However, a note of caution when interpreting results from observational studies such as these is that it is impossible  
 314 to ascertain a direct causal relationship between calibration and sensor performance as there are numerous other  
 315 confounding factors at play (Diez et al., 2022). Notably these two data products are being assessed over different  
 316 periods when many other factors will have changed, for example, the local meteorological conditions as well as  
 317 human-made factors such as reduced traffic levels following the COVID-19 lockdown that commenced in March  
 318 2020.

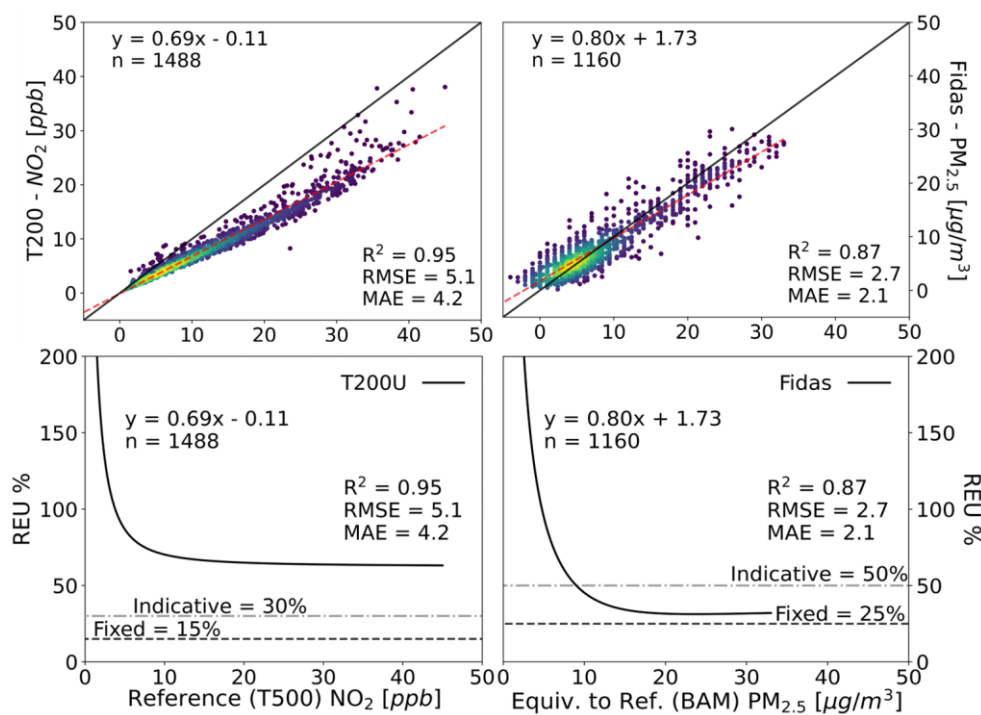
### 319 3.3 Reference instrumentation is key

320 A common assumption when evaluating the performance of sensors is that the metrological characteristics of the  
 321 sensor predominantly influence discrepancies detected in co-locations. While this presumption can often be justified  
 322 due to both devices' (sensor and the reference method) relative scales of measurement errors, it is not always the case.  
 323 Since every measurement is subject to uncertainties, it is crucial to consider those associated with the reference when  
 324 deriving the calibration factors of placement.

325 Fig. 6 (left plots) displays the performance of a NO<sub>2</sub> reference instrument (Teledyne T200U) specifically installed for  
326 QUANT, located next to the usual instrument at the Manchester supersite (Teledyne T500). Although they use  
327 different analytical techniques (chemiluminescence for the T200U and Cavity Attenuated Phase Shift Spectroscopy  
328 for the T500), their measurements are highly correlated ( $R^2 \sim 0.95$ ). However, it's possible to identify  
329 a proportional bias (slope=0.69), attributed to retaining the initial calibration  
330 (conducted in York) without subsequent adjustments, a situation exacerbated by an  
331 unnoticed mechanical failure of one of the instrument's components. The REU  
332 demonstrates that, under these circumstances, an instrument designated as a  
333 reference does not meet the minimum requirements ( $REU \leq 15\%$  for NO<sub>2</sub> reference  
334 measurements) set out by the Data Quality Objectives (DQOs) of the EU AQ Directive. Figure S6 shows a unique  
335 sensor evaluated against both the T500 and the T200U. The comparison against the T200U yields better results,  
336 suggesting that, in a hypothetical scenario where it was the only instrument at the site, this could lead to misleading  
337 conclusions. This situation reinforces the idea that instruments should not only be adequately characterised but also  
338 undergo rigorous quality assurance and data quality control programs, as well as receive appropriate maintenance  
339 (Pinder et al., 2019). All of this must be performed before and during the use of any instrument.

340 For PM monitoring, the current EU reference method is the gravimetric technique (CEN EN 12341, 2023), which is  
341 a non-continuous monitoring method that requires weighing the sampled filters and off-line processing of the results.  
342 Techniques that have proven to be equivalent to the reference method (called "equivalent to reference" in the EU AQ  
343 Directive) are very often used in practice. In the UK context, the Beta Attenuated Monitor (BAM) and FIDAS (optical  
344 aerosol spectrometer) are equivalent-to-reference methods commonly used as part of the Urban AURN Network  
345 (Allan et al., 2022). To illustrate these differences in practice, Fig. 6 compares these two equivalent-to-reference PM<sub>2.5</sub>  
346 measurements obtained with a BAM (AURN York site, located on a busy avenue), and a FIDAS unit specifically  
347 installed for QUANT. During this specific period, they show a strong linear association ( $R^2 = 0.87$ ). Although the bias  
348 is not extremely pronounced (slope=0.80), the FIDAS measurements are, on average, systematically lower compared  
349 to BAM.

350 In the hypothetical case that the BAM were to be considered the reference method  
351 (arbitrarily chosen for this example as it is the current instrument at the AURN York  
352 site) when assessing the FIDAS under these test conditions, it would only meet the  
353 criterion stipulated by the EU DQOs for indicative measurements ( $REU \leq 50\%$  for PM<sub>2.5</sub>),  
354 but not for fixed (i.e., reference) measurements ( $REU \leq 25\%$  for PM<sub>2.5</sub>). This example is  
355 primarily intended to illustrate the magnitude of differences between both methods for this particular application, and  
356 by no means does this observation imply that the FIDAS measurements are inherently problematic.

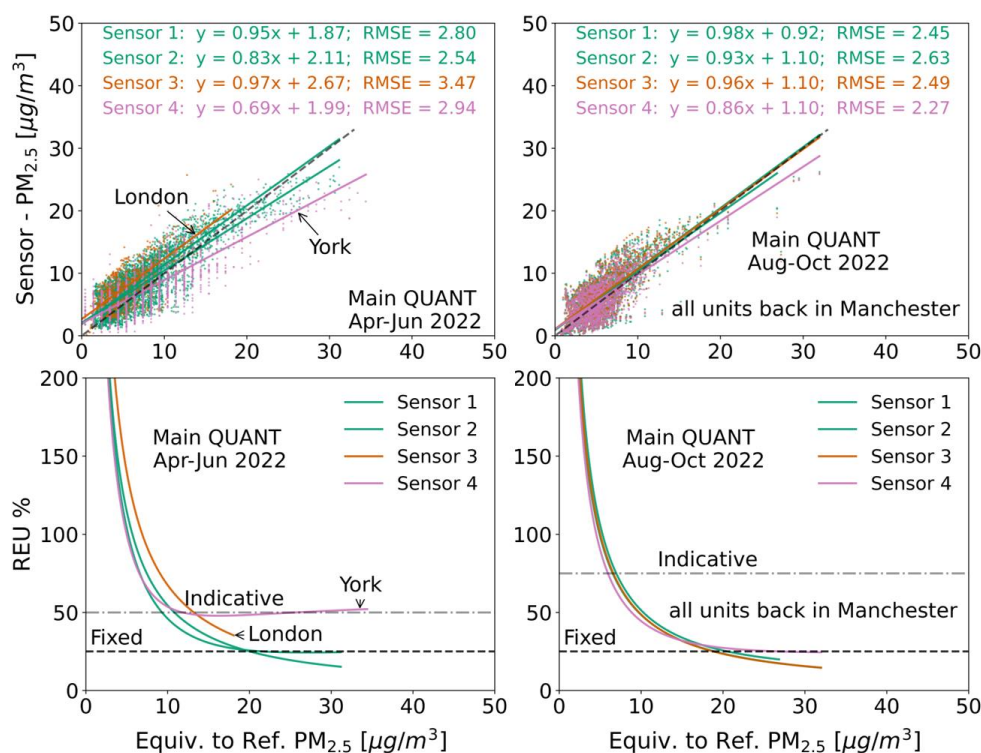


357  
 358 **Figure 6. The left plots depict the comparison between the Teledyne T200U (chemiluminescence analyzer) and the reference**  
 359 **method (Teledyne T500 CAPS analyzer) at the Manchester supersite. The plots to the right illustrate PM<sub>2.5</sub> measurements**  
 360 **in York, taken with a FIDAS instrument (optical aerosol spectrometer) and a BAM 1020 (beta attenuation monitor), both**  
 361 **equivalent-to-reference methods. While the top plots show the regression (including some typical single-value metrics),**  
 362 **those on the bottom present the REU alongside the DQOs defined by the EU AQ Directive.**

363 Although these two instruments (BAM and Fidas) show a greater concordance between themselves than with sensors  
 364 (for the comparison of two sensor systems against the BAM and the Fidas, refer to Fig. S7), the choice of the  
 365 measurement method can have a considerable impact on evaluations of this type. This underscores the importance of  
 366 adequately characterising the uncertainties of the reference monitor when evaluating sensors.

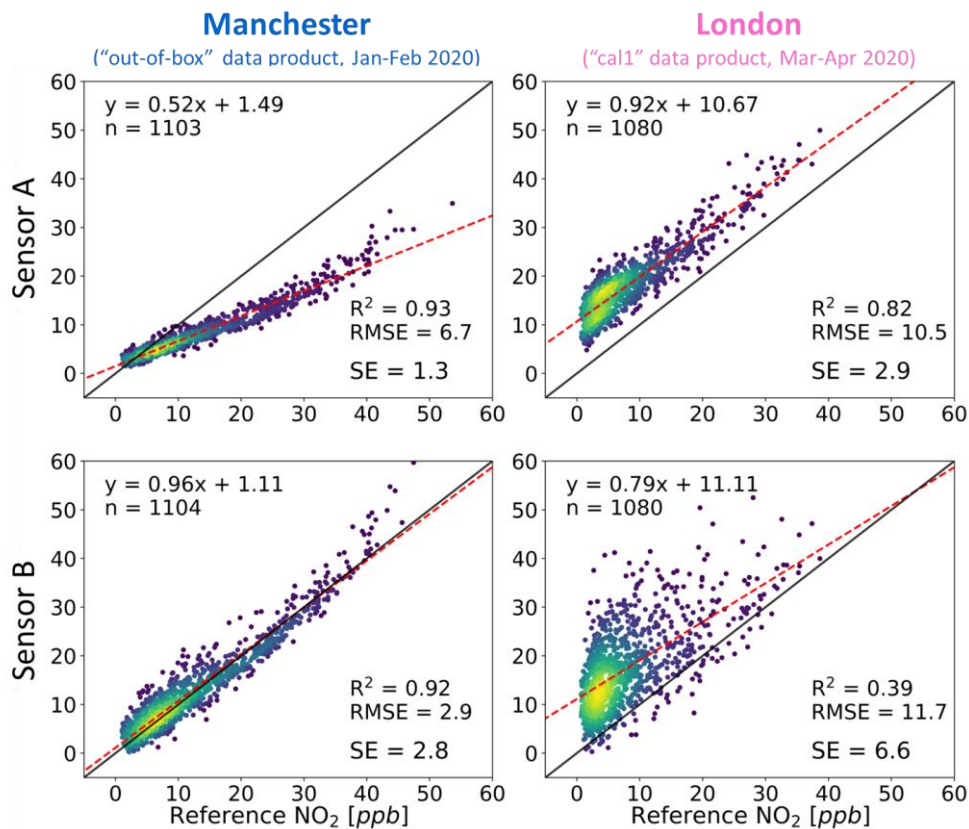
### 367 3.4 Inter-location performance

368 An extreme example of sensor performance varying due to environmental conditions is when sensors are moved  
 369 between locations, as their apparent performance may vary drastically. Fig. 7 displays the REU and regression plots  
 370 for four of the same PM<sub>2.5</sub> sensor system in two periods: April-June 2022 when the devices were working across the  
 371 3 sites (York, Manchester and London), and August-October 2022 when they were all reunited in Manchester. The  
 372 RMSE remains reasonably consistent (range 2.27 to 3.47 ppb) between the devices across the periods and locations.  
 373 However, for the device that moved from York to Manchester, a change in slope from 0.69 to 0.86 was observed.  
 374 Because this device's slope is consistent with the other units while running in Manchester, this is likely due to the  
 375 different sensor responses in the specific environments. The precise cause of this change is not immediately evident  
 376 and will be the focus of a follow-up study, but could be due to changes in local conditions (e.g., weather, emissions,  
 377 etc.) impacting sensor calibration and/or differences in actual PM<sub>2.5</sub> sources and particle characteristics at the sites  
 378 (Raheja et al., 2022).



379  
 380 **Figure 7. Regression (top) and REU (bottom) plots showing data from four PM<sub>2.5</sub> sensors (same manufacturer) over 2 time**  
 381 **periods: Apr-Jun 2022 and Aug-Oct 2022. The four devices were in separate locations in the first period, but all deployed**  
 382 **in Manchester in the second. The horizontal dashed lines represent a reference for the PM<sub>2.5</sub> DQOs as defined by the EU**  
 383 **AQ Directive (for “fixed” PM<sub>2.5</sub> measurements, REU < 25%; for “indicative” PM<sub>2.5</sub> measurements, REU < 50%). Readers**  
 384 **are encouraged to consult the specified standard for further details.**

385 A second example of inter-location performance is presented in Fig. 8, showing NO<sub>2</sub> data from two sensor systems  
 386 (from two different manufacturers, identified as Systems A and B) before (left plots) and after (right plots) they were  
 387 moved from Manchester to London in March 2020. Both sensors saw a reduction in agreement with the reference  
 388 instrument at the London site compared to Manchester, despite both these sites being classified as urban-background  
 389 with reference instrument performance regularly audited by the UK National Physical Laboratory.



390  
 391 **Figure 8. Comparative analysis of NO<sub>2</sub> measurements from two systems (A and B), across two urban settings. The left plots**  
 392 **display Manchester “out-of-box” data product (January to February 2020), while the right plots show London “call” data**  
 393 **product (April to May 2020). This “call” label does not indicate corrections specific to London's conditions but denotes a**  
 394 **data product from a specific period (as detailed in Figures S2 and S3). The colour gradient represents the density of data**  
 395 **points, with darker shades indicating lower densities and brighter shades signifying higher densities.**

396 The primary distinction between both systems' behaviour lies in the fact that the sensor located in the top row (Sensor  
 397 A), even after being relocated to London, maintains a linear response (albeit slightly more degraded than that observed  
 398 in Manchester, as indicated by the R<sup>2</sup> and RMSE). In contrast, Sensor B's response becomes significantly noisier upon  
 399 relocation to London, as highlighted by the Standard Error (SE)—which represents the remaining error after applying  
 400 a perfect bias correction. Despite both systems utilising identical sensing elements, the variance in residuals between  
 401 them may stem from the distinct calibration approaches applied by the respective companies.

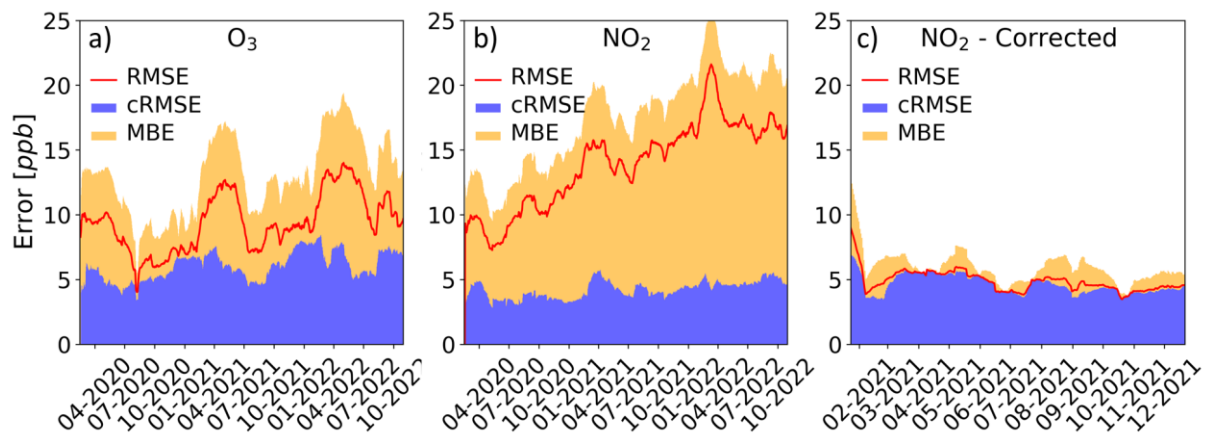
402 For cases resembling Sensor A, users might find it beneficial to implement simple linear correction methods (e.g.,  
 403 using reference instruments if available) or explore other strategies for zero and span correction. A practical and cost-  
 404 effective approach, for example, is using diffusion tubes for NO<sub>2</sub> measurements, as discussed in Section 3.6.  
 405 Conversely, in scenarios characterised by high variance in residuals, such as those observed with Sensor B, a-  
 406 posteriori attempts to apply a simple linear correction are unlikely to result in significant improvement. While more  
 407 sophisticated corrections are theoretically feasible, their effectiveness is limited by the end-user's domain knowledge  
 408 and the availability of additional complex data sources. Furthermore, it is important to consider that excessive post-  
 409 processing may lead to overfitting—a situation where a model excessively conforms to specific patterns in the training  
 410 data, resulting in poor performance on new, unseen data (Aula et al., 2022).

### 411 3.5 Long-term stability

412 The long-term stability of sensor response is also an important facet of its performance, especially for certain use  
 413 cases such as multi-year network deployments. There can be multiple causes of long-term changes to sensor response,  
 414 for example, particles settling inside the sampling chamber in optical-based sensors (e.g. Hofman et al. (2022)), or the  
 415 gradually changing composition of electrochemical cells (e.g. Williams (2020)). How these changes manifest  
 416 themselves in the data must be identified if ways to account for them are to be implemented.

417 Fig. 9 shows the temporal nature of the O<sub>3</sub> and NO<sub>2</sub> errors (MBE, cRMSE and RMSE) from a sensor system between  
 418 February 2020 and October 2022. The O<sub>3</sub> shows (Fig. 9a) a gradual increase in the overall measurement error, largely  
 419 due to an increase in the MBE. It also shows a distinct seasonality MBE, increasing by a factor of 3-4 between March  
 420 and July compared to the August-February period. The cRMSE component shows fluctuations during the study but  
 421 only has a small increasing trend. The NO<sub>2</sub> system (Fig. 9b) demonstrates a consistently increasing overall error, with  
 422 a less pronounced seasonal influence. The bias contributes greatly to the total error (see Section 3.6 for NO<sub>2</sub> sensor  
 423 correction, Fig. 9c).

424



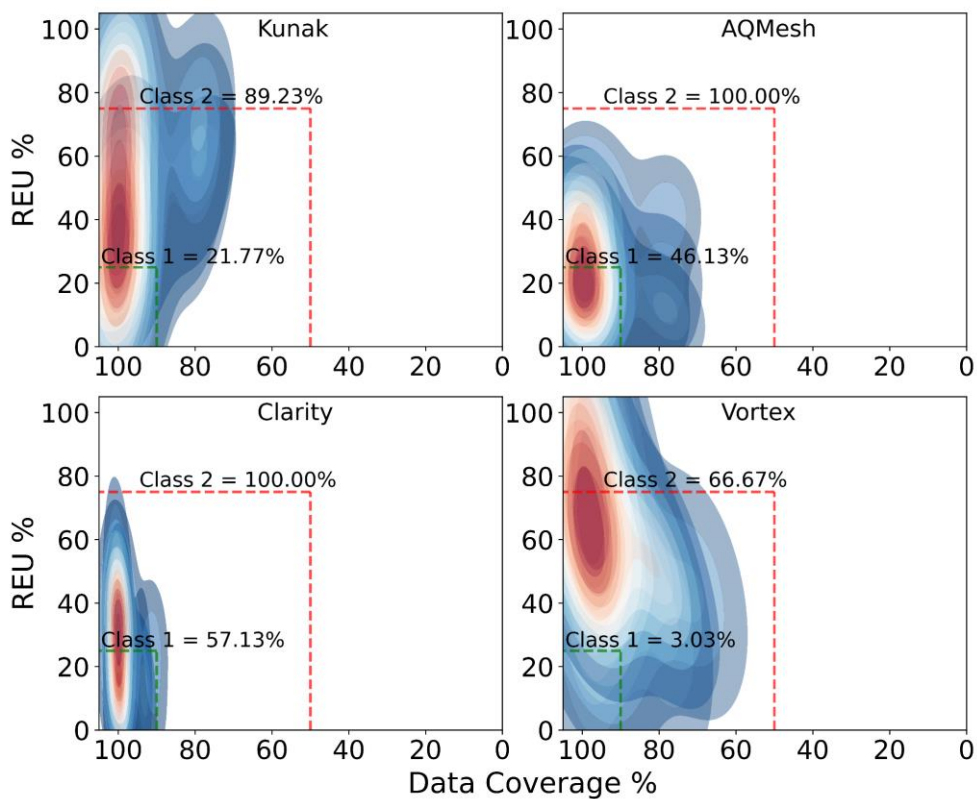
425  
 426 **Figure 9. Seasonal variation of error (as RMSE, red line) of one of the systems belonging to the Main QUANT, decomposed**  
 427 **into cRMSE (in blue) and MBE (in yellow) estimated based on a 40-day (aligning with the sample size recommendation by**  
 428 **the CEN/TS 17660-1:2021 standard for on-field tests) moving window approach with a 1-day slide (i.e., advancing the**  
 429 **calculation 1 day at a time). Panel a) is for O<sub>3</sub> measurements, and panel b) is for NO<sub>2</sub> (April 2020-Oct 2022). Panel c) is also**  
 430 **for NO<sub>2</sub>, this time showing the effect of a linear correction using diffusion tubes (see next section for more details).**

### 431 3.6 Informing end-use applications

432 Ultimately, for any air pollution monitoring application, the requirements of the task should dictate the measurement  
 433 technology options available. For example, if the requirement for a particular measurement is to assess legal  
 434 compliance, then lower measurement uncertainty must be a key consideration as the reported values need to be  
 435 compared to a limit value. In contrast, if an application aimed to look at long-term trends in pollutants, then absolute  
 436 accuracy may not be as important as the long-term stability of sensor response. To realise the potential of air pollution  
 437 sensor technologies, end users need to align their specific measurement needs with the capabilities of available  
 438 devices. Achieving this necessitates access to unbiased performance data, such as long-term stability and accuracy  
 439 across varying conditions, ideally in an easy-to-access and interpret manner.



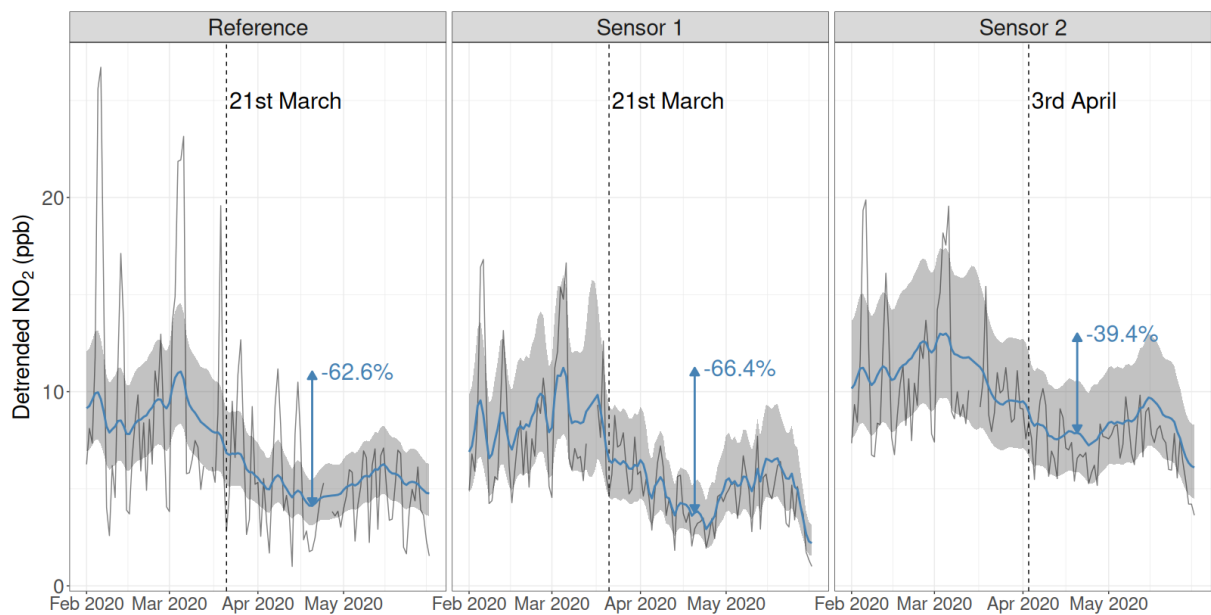
440 Understanding the uncertainty associated with a instrument is essential for recognizing its capabilities and limitations.  
 441 Accurate instruments are crucial, especially in areas like public health decision-making, where inaccurate data can  
 442 have profound implications (Molina Rueda et al., 2023). Furthermore, instruments that operate autonomously ensure  
 443 consistent, uninterrupted data collection, making them more efficient and cost-effective in terms of maintenance and  
 444 calibration. Figure 10 illustrates the collective behaviour of NO<sub>2</sub> sensors from each of the four companies with more  
 445 than two working systems, showcasing their REU (y-axis) versus Data Coverage (DC, x-axis). Both parameters were  
 446 calculated for each sensor system using a 40-day moving window approach and then aggregated by brand, ensuring a  
 447 comprehensive analysis. This methodology leverages overlapping data from multiple sensors to provide a robust  
 448 representation of company-wide sensor performance and aims to prevent biased interpretations. Both REU and DC  
 449 are key criteria within the EU scheme (EU 2008/50/EC) for evaluating the performance of measurement methods, and  
 450 are complemented by the CEN/TS 17660-1:2021 specifically for sensors. The latter document defines three different  
 451 sensor system tiers. Class 1 NO<sub>2</sub> sensors, bounded by the green rectangle (REU < 25% and DC > 90%), offer higher  
 452 accuracy than Class 2 sensors (REU < 75% and DC > 50%), delimited by the red rectangle (Class 3 sensors have no  
 453 set requirements). Presenting the REU and DC like in Fig. 10 helps users anticipate the performance of sensor systems  
 454 —under the assumption that all sensors from the same brand will behave similarly in equivalent environmental  
 455 conditions— providing more insight into selecting the appropriate instrument for a given project or study.



456  
 457 **Figure 10. REU vs. DC for 4 sensor system companies measuring NO<sub>2</sub>, with more than two units working simultaneously**  
 458 **during the WPS (period Nov 2021-Oct 2022, after all companies provided at least one calibrated product). Each heat map**  
 459 **plot (cooler colours for lower densities and warmer colours for higher densities) aggregates the REU and DC from sensors**  
 460 **of the same brand working concurrently. The calculation of these two parameters employ a 40-day (aligning with the sample**  
 461 **size recommendation by the CEN/TS 17660-1:2021 standard for on-field tests) moving window approach with a 1-day slide**  
 462 **(i.e., advancing the calculation 1 day at a time). The green dashed rectangle limits the Data Quality Objectives (DQOs) for**  
 463 **Class 1 sensors, and the red dashed rectangle outlines the DQOs for Class 2 sensors.**

464 Depending on the nature of the sensor data uncertainty, methods can be implemented to improve certain aspects of  
465 the data quality for a particular application. One such example is the use of distributed networks to estimate sensor  
466 measurement errors, such as that described by (Kim et al., 2018). Depending on the application and available options,  
467 users can access alternative methods to reduce bias, thus enhancing the accuracy of sensor systems and networks. For  
468 example, “Indicative methods”, as defined by the EU AQ Directive, such as diffusion tubes (e.g., NO<sub>x</sub>, SO<sub>2</sub>, VOCs,  
469 etc.), can be an option. Specifically, our study leverages diffusion tube data for NO<sub>2</sub>, illustrating one effective approach  
470 to bias correction using supporting observations, as exemplified in Fig. 9b. These measurements are widely used to  
471 monitor NO<sub>2</sub> concentrations in UK urban environments, due to their lower cost (~£5 per tube) and ease of deployment,  
472 but only provide average concentrations over periods of weeks to months (Butterfield et al., 2021). During QUANT,  
473 NO<sub>2</sub> diffusion tubes were deployed at the 3 colocation sites (see Section S7 at the Supp. for more details). Combining  
474 these measurements offers the possibility of quantifying the average sensor bias, thus reducing the error on the sensor  
475 measurement whilst maintaining the benefits of its high time-resolution observations. It is important to note that while  
476 bias correction has been applied to the sensor data, the NO<sub>2</sub> diffusion tube concentrations used for comparison  
477 purposes must also be adjusted (e.g. following Defra (2022)). Fig. 9c shows the accuracy of the same NO<sub>2</sub> sensor data  
478 shown in Fig. 9b but applies a monthly offset calculated as the difference between its monthly average measurement  
479 and that from the diffusion tube (see Figure S8). This shows a dramatic reduction in overall error largely driven by its  
480 bias correction. What remains largely resulting from the cRMSE, i.e. the error variance that might arise from  
481 limitations from the sensing technology itself and/or the conversion algorithms used to transform the raw signals into  
482 the concentration output. To validate the efficacy and reliability of this bias correction method, further long-term  
483 studies are warranted.

484 The development and communication of methods that improve sensor data quality, ideally in accessible case studies,  
485 would likely increase the successful application of sensor devices for local air quality management. There is also a  
486 need for similar case studies showcasing the successful application of sensor devices for particular monitoring tasks.  
487 An example of this from the QUANT dataset is the use of sensor devices to successfully identify change points in a  
488 pollutant’s concentration profile. These are points in time where the parameters governing the data generation process  
489 are identified to change, commonly the mean or variance, and can arise from human-made or natural phenomena  
490 (Aminikhanghahi and Cook, 2017). Determining when a specific pollutant has changed its temporal nature is a  
491 challenging task as there are a large number of confounding factors that influence atmospheric concentrations,  
492 including but not limited to seasonal factors, environmental conditions (both natural and arising from human  
493 behaviour), and meteorological factors. This challenge has led to several “deweathering” techniques being proposed  
494 in the literature (Carslaw et al., 2007; Grange and Carslaw, 2019; Ropkins et al., 2022). While change point detection  
495 is highlighted here as a promising application of sensor data, it represents just one of many potential methodologies  
496 that could be explored with the QUANT dataset.



497

498 **Figure 11. NO<sub>2</sub> measurements (black solid line) and detrended estimates (blue solid line with 95% confidence interval in**  
 499 **the shaded grey region) from the reference instrument (left panel) and 2 sensor systems (middle and right panels) from**  
 500 **Manchester in 2020. Vertical dashed lines and their corresponding dates indicate identified change points, which**  
 501 **correspond to the introduction of the first national lockdown due to COVID-19 on the 23rd of March 2020. The percentage**  
 502 **in blue represents the relative peak-trough decrease from 5th March to 20th April.**

503 A state-space based deweathering model was applied to NO<sub>2</sub> concentrations measured from the sensor systems that  
 504 had remained in Manchester throughout 2020 to remove these confounding factors, with the overarching objective to  
 505 identify whether the well-documented reduction in ambient NO<sub>2</sub> concentrations due to changes in travel patterns  
 506 associated with COVID-19 restrictions could be observed in the low-cost sensor systems. To provide a quantifiable  
 507 measure of whether a meaningful reduction had occurred, the Bayesian online change-point detection (Adams &  
 508 MacKay, 2007) was applied. Of the 8 devices that measured NO<sub>2</sub>, clear change points corresponding to the  
 509 introduction of a lockdown were identified in 2 (Fig.11), demonstrating the potential of these devices to identify long-  
 510 term trends with appropriate processing, even with only 3 months of training data.

#### 511 4. Conclusions

512 Lower-cost air pollution sensor technologies have significant potential to improve our understanding and ability to  
 513 manage air pollution issues. Large-scale uptake in the use of these devices for air quality management has, however,  
 514 been primarily limited by concerns over data quality and a general lack of a realistic characterisation of the  
 515 measurement uncertainties making it difficult to design end uses that make the most of the data information content.  
 516 Advances are occurring rapidly, in both the measurement technology and particularly in the data post-processing and  
 517 calibration. A challenge with the use of sensor-based devices is that many of the end-use communities do not have  
 518 access to extensive reference-grade air pollution measurement capability (Lewis & Edwards, 2016), or in many cases,  
 519 expertise in making atmospheric measurements or the technical ability for data post-processing. For this reason,  
 520 reliable information on expected sensor performance needs to be available to aid effective end-use applications. Large-  
 521 scale independent assessments of air sensor technologies are non-trivial and costly, however, making it difficult for  
 522 end users to find relevant performance information on current sensor technologies. The QUANT assessment is a multi-

523 year study across multiple locations, that aims to provide relevant information on the strengths and weaknesses of  
524 commercial air pollution sensors in UK urban environments.

525 The QUANT sensor systems were installed at two highly instrumented urban background measurement sites, in  
526 Manchester and London, and one roadside monitoring station in York. The study design ensured that multiple devices  
527 were collocated to assess inter-device precision, and devices were also moved between locations and able to test  
528 additional calibration data products to assess and enable developments in sensor performance under realistic end-use  
529 scenarios. A wider participation component of the Main QUANT assessment was also run at the Manchester site to  
530 expand the market representation of devices included in the study, and also to assess recent developments in the field.

531 A high-level analysis of the dataset has highlighted multiple facets of air pollution sensor performance that will help  
532 inform their future usage. Inter-device precision has been shown to vary, both between different devices of the same  
533 brand and model and over different periods of time, with the most accurate devices generally showing the highest  
534 levels of inter-device precision. The accuracy of the reported data for a particular device can be impacted by a variety  
535 of factors, from the calibrations applied to its location or seasonality. This has important implications for the way  
536 sensor-based technologies are deployed and supports the case made by others (Bittner et al., 2022; Farquhar et al.,  
537 2021; Crilley et al., 2018; Williams, 2020; Bi et al., 2020) that practical methods to monitor sensor bias will be crucial  
538 in uses where data accuracy is paramount. Ultimately, this work shows that sensor performance can be highly variable  
539 between different devices and end-users need to be provided with impartial performance data on characteristics such  
540 as accuracy, inter-device precision, long-term drift and calibration transferability in order to decide on the right  
541 measurement tool for their specific application.

542 In addition to these findings, this overview lays the groundwork for more detailed research to be presented in future  
543 publications. Subsequent analyses will focus on providing a more nuanced understanding of the uncertainty in air  
544 pollution sensor measurements, thus equipping end-users with better insights into the capability of sensor data. Future  
545 studies will delve into specific aspects of air pollution sensor performance: 1) a comprehensive performance  
546 evaluation of PM<sub>2.5</sub> data, assessing their accuracy and reliability under different environmental conditions; 2) an in-  
547 depth analysis of NO<sub>2</sub> measurements, examining their sensitivity and response in various urban environments; and 3)  
548 a detailed investigation into the detection limits of these sensor technologies, targeting their optimised application in  
549 low concentration scenarios. These focused studies are basic steps needed to further advance our understanding of  
550 sensors' capabilities and limitations, ensuring informed and effective application in air quality monitoring.

## 551 **Supplementary**

552 The supplement related to this article is available online at:

## 553 **Data availability**

554 The QUANT dataset, accessible at the Centre for Environmental Data Analysis (CEDA) (Lacy et al., 2023;  
555 <https://catalogue.ceda.ac.uk/uuid/ae1df3ef736f4248927984b7aa079d2e>), is the most extensive collection to date  
556 assessing air pollution sensors' performance in UK urban settings. It encompasses gas and PM sensor data recorded  
557 in the native reporting frequency of each device. The reference data from the three monitoring sites can be found at:

- 558 • MAQS: <https://data.ceda.ac.uk/badc/osca/data/manchester>;
- 559 • LAQS: <https://www.londonair.org.uk/london/asp/datadownload.asp>;

560 • YoFi: [https://uk-air.defra.gov.uk/data/data\\_selector](https://uk-air.defra.gov.uk/data/data_selector).

561 A comprehensive data descriptor manuscript, detailing the QUANT dataset's collection methods, processing  
562 protocols, accessibility features, and overall structure—including variables, data reporting frequencies, and QA/QC  
563 practices—has been submitted for publication. At the time of this writing, the manuscript is still under review.

564 A GitHub repository at <https://github.com/wacl-york/quant-air-pollution-measurement-errors> provides access to  
565 Python and R scripts designed for generating diagnostic visuals and metrics related to the QUANT study, along with  
566 sample analyses using the QUANT dataset.

### 567 **Author contributions**

568 The initial draft of the manuscript was created by SD, PME, and SL. The research was conceptualised, designed, and  
569 conducted by PME and SD. Methodological framework and conceptualization were developed by SD, PME, and SL.  
570 Data analysis was primarily conducted by SD and SL. The software tools for data visualisation and analysis were  
571 developed by SD and enhanced by SL. MF, MP and NM supplied the reference data critical for the study. TB, HC,  
572 DH, SG, NAM and JU made substantive revisions to the manuscript, enriching the final submission.

### 573 **Competing interests**

574 The authors declare that they have no conflict of interest.

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