



1 Long-term Evaluation of Commercial Air Quality Sensors: An

2 Overview from the QUANT Study

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18 Abstract. In times of growing concern about the impacts of air pollution across the globe, lower-cost sensor 19 technology is giving the first steps in helping to enhance our understanding and ability to manage air quality issues. 20 While the benefits of greater spatial coverage and real-time measurements that these systems offer are evident, 21 challenges still need to be addressed regarding sensor reliability and data quality. Given the limitations imposed by 22 intellectual property, commercial implementations are often "black boxes", which represents an extra challenge as it 23 limits end-users' understanding of the data production process. In this paper we present an overview of the QUANT 24 (Quantification of Utility of Atmospheric Network Technologies) study, a comprehensive 3-year assessment across a 25 range of urban environments in the United Kingdom. QUANT stands out as one of the most comprehensive studies 26 of commercial air quality sensor systems carried out to date, encompassing a wide variety of companies in a single 27 evaluation and including two generations of sensor technologies. Integrated into an extensive data set open to the 28 public, it was designed to provide a long-term evaluation of the precision, accuracy, and stability of commercially 29 available sensor systems. This overview discusses the assessment methodology, and key findings showcasing the 30 significance of the study. The results shown here highlight the significant variation between systems, the incidence of 31 corrections made by manufacturers, the effects of relocation to different environments and the long-term behaviour 32 of the systems. Additionally, the importance of accounting for uncertainties associated with reference instruments in 33 sensor evaluations is emphasised. Practical considerations in the application of these sensors in real-world scenarios





- 34 are also discussed, and potential solutions to end-users data challenges are presented. Offering key information about
- 35 the sensor systems' capabilities the QUANT study will serve as a valuable resource for those seeking to implement
- 36 commercial solutions as complementary tools to tackle air pollution.
- 37 Keywords: air pollution, commercial sensor systems, QUANT, long-term evaluation.

38 1. Introduction

Emerging lower-cost sensor systems¹ offer a promising alternative to the more expensive and complex monitoring equipment traditionally used for measuring air pollutants such as $PM_{2.5}$, NO_2 , and O_3 (Okure et al., 2022). These innovative devices hold the potential to expand spatial coverage (Malings et al., 2020) and deliver real-time air pollution measurements (Tanzer-Gruener et al., 2020). However, concerns regarding the variable quality of the data they provide still hinder their acceptance as reliable measurement technologies (Karagulian et al., 2019; Zamora et al., 2020).

Sensors face key challenges such as cross-sensitivities (Cross et al., 2017; Levy Zamora et al., 2022; Pang et al., 2018),
internal consistency (Feenstra et al., 2019; Ripoll et al., 2019), signal drift (A. Miech et al., 2023; Li et al., 2021;
Sayahi et al., 2019), long term performance (Bulot et al., 2019; Liu et al., 2020) and data coverage (Brown & Martin,
2023; Duvall et al., 2021; Feinberg et al., 2018). Additionally, environmental factors such as temperature (Bittner et al., 2022; Farquhar et al., 2021), and humidity (Crilley et al., 2018; Williams, 2020) can significantly influence sensor signals.

In recent years, manufacturers of both sensing elements (Han et al., 2021; Nazemi et al., 2019) and sensor systems have made significant technological advances (Chojer et al., 2020). For example, there are now commercial and noncommercial systems equipped with multiple sensing elements to measure distinct pollutants (Buehler et al., 2021; Hagan et al., 2019; Pang et al., 2021) helping mitigating the effects of cross-interferences. Additionally, enhancements in electrochemical sensors have been demonstrated in terms of their specificity (Baron & Saffell, 2017; Ouyang, 2020).

However, the complex nature of their responses, coupled with their dependence on local conditions means sensor
performance can be inconsistent (Bi et al., 2020). This complicates the comparison of results or anticipating sensor
future performance across different studies. Moreover, assessments of sensor performance found in the academic
literature often rely on a range of protocols (e.g., CEN (2021) and Duvall et al. (2021)) and data quality metrics (e.g.,
Spinelle et al. (2017) and Zimmerman et al. (2018)), with many studies limited to a single-site co-location and/or of
short-term evaluations that do not fully account for broader environmental variations (Karagulian et al., 2019).

63 The calibration of any instrument used to measure atmospheric composition is fundamental to guarantee their accuracy
64 (Alam et al., 2020; Long et al., 2021; Wu et al., 2022). Using out-of-the-box sensor data without fit-for-purpose

- 65 calibration can produce misleading results (Liang & Daniels, 2022). An effective calibration involves identifying and
- 66 correcting systematic errors in the sensor readings. For standard air pollution measurement techniques, calibration is

¹ The term "Sensor Systems" refers to sensors housed within a protective case, which includes a sampling and power system, electronic hardware and software for data acquisition, analog-to-digital conversion, data processing and their transfer (Karagulian et al., 2019). Unless specified otherwise, the term "sensor" will be used to refer to "Sensor Systems".





67 often performed in a controlled laboratory environment (Liang, 2021), or by sampling gas from a certified standard68 cylinder in the field.

69 Yet, the aforementioned challenges with lower-cost sensor-based devices suggest that such calibrations may not 70 always accurately reflect real-world conditions (Giordano et al., 2021). A frequent approach involves co-locating 71 sensors alongside regulatory instruments in their intended deployment areas and/or conditions and using data-driven 72 methods to match the reference data (Liang & Daniels, 2022). Numerous studies have investigated the effectiveness 73 of calibration methods for sensors e.g. (Bigi et al., 2018; Bittner et al., 2022; Malings et al., 2020; Spinelle et al., 2017; 74 Zimmerman et al., 2018), including selecting appropriate reference instruments (Kelly et al., 2017), the need for 75 regular calibration to maintain accuracy (Gamboa et al., 2023), the necessity of rigorous calibration protocols to ensure 76 consistency (Kang et al., 2022), and transferability (Nowack et al., 2021) of results. Ultimately, the reliability and 77 associated uncertainty of any applied calibration will influence the final sensor data quality.

78 For end-users to make informed decisions on the applicability of air pollution sensors, a realistic understanding of the 79 expected performance in their chosen application is necessary (Rai et al., 2017). Despite this, there has been relatively 80 little progress in clarifying the performance of sensors for air pollution measurements outside of the academic arena. 81 This is largely due to the significant variability in both the number of sensors and the variety of applications tested, 82 as well as the availability of highly accurate measurement instrumentation and/or regulatory networks to those outside 83 of the atmospheric measurement academic field (e.g. Lewis and Edwards (2016) and Popoola et al. (2018)). From a 84 UK clean air perspective, this ambiguity represents a major problem. The lack of a consistent message undermines 85 the exploitation of these devices' unique strengths, notably their capability to form spatially dense networks with rapid 86 time resolution. Consequently, there is potential for a mismatch in users' expectations of what sensor systems can 87 deliver and their actual operating characteristics, eroding trust and reliability.

88 In this work, as part of the UK Clean Air program funded QUANT project, we deployed a variety of sensor 89 technologies (43 commercial devices, 119 gas and 118 PM measurements) at 3 representative UK urban sites -90 Manchester, London and York— alongside extensive reference measurements, to generate the data for an extensive 91 in-depth performance assessment. This project aims to not only evaluate the performance of sensor devices in a UK 92 urban climatological context but also provide critical information for the successful application of these technologies 93 in various environmental settings. To our knowledge, QUANT is the most extensive and longest-running evaluation 94 of commercial sensor systems globally to date. Furthermore, we tested multiple manufacturers' data products for a 95 significant number of these sensors to understand the implications of local calibration. This comprehensive approach 96 offers unprecedented insights into the operational capabilities and limitations of these sensors in real-world conditions. 97 Significantly, some of the insights gathered during QUANT have contributed to the development of the Publicly 98 Available Specification (PAS 4023, 2023), which provides guidelines for the selection, deployment, maintenance, and 99 quality assurance of air quality sensor systems.

- In the following sections, we delve into the methodology and provide an overview of the QUANT dataset, as well asa discussion of some of the key findings and potential considerations for end-users.
- 102 2. QUANT study design
- 103 2.1 Main study





The Main QUANT assessment study aimed to perform a transparent long-term (19 Dec 2019 - 31 Oct 2022) evaluation of commercially available sensor technologies for outdoor air pollution monitoring in UK urban environments. Four duplicates of five different commercial sensor devices (Table 1) were purchased in Sept 2019 for inclusion in the study, with the selection criteria being: market penetration and/or previous performance reported in the literature, ability to measure pollutants of interest (e.g. NO₂, NO, O₃, and PM_{2.5}), and capacity to run continuously reporting high time resolution data (1-15 min data) ideally in near real-time with data accessible via an API.

Table 1. Main QUANT devices description. The 20 units offered 56 gas and 56 PM measurements in total. For a detailed description of the devices see Section S1 in the Supp.

Product*	Company	Measurements							Cost (f)**	
(# units)		NO	NO ₂	O ₃	со	CO ₂	\mathbf{PM}_1	PM _{2.5}	PM10	
AQY (4)	Aeroqual	-	√	✓	-	-	-	√	1	~4.7K
AQM (4)	AQMesh	√	√	√	-	√	√	√	√	~8.6K
Ari (4)	QuantAQ	√	√	√	√	√	√	√	√	~8.6K
PA (4)	PurpleAir	-	-	-	-	-	✓	√	√	~0.3K
Zep (4)	Earthsense	√	√	√	-	-	√	√	√	~7K

*AQY: Aeroqual; AQM: AQMesh; Ari: Arisense; PA: PurpleAir; Zep: Zephyr.

**Cost (Sep 2019) per unit including UK taxes and associated contractual costs (i.e., communication, data access, sensor replacement, etc.).

113 To capture the variability of UK urban environments, identical units were installed at three carefully selected field 114 sites. Two of these sites are highly instrumented urban background measurement supersites: the London Air 115 Quality Supersite (LAQS) and the Manchester Air Quality Supersite (MAQS), located in densely populated urban 116 areas with unique air quality challenges. The third site is a roadside monitoring site in York, which is part of the 117 Automatic Urban and Rural Network (AURN, https://uk-air.defra.gov.uk/data/), representing a urban environment 118 more inlfuenced by traffic. This selection strategy ensures that the QUANT study's findings reflect the dynamics 119 of urban air quality across different UK settings, while providing comprehensive reference measurements. Further 120 details about each site can be found in Section S3 in the Supp., and the available reference instrumentation in 121 Section S4.

122 Initially, all the sensors were deployed in Manchester for approximately 3 months (mid-Dec 2019 to mid-Mar 2020) before being split up amongst the three sites (Fig. 1). At least one unit per brand was re-deployed to the other two sites (mid-March 2020 to early-July 2022) leaving two devices per company in Manchester to assess inter-device consistency. In the final 4 months of the study, all the sensor systems were relocated back to Manchester (early July 2022 to the end of October 2022).





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128 Figure 1. Main Quant and Wider Participation Study (WPS) timeline.

129 2.2 Wider Participation Study

130 The Wider Participation Study (WPS) was a no-cost complementary extension of the QUANT assessment, 131 specifically designed to foster innovation within the air pollution sensors domain. This segment of the study took 132 place entirely at the at MAQS from 10th June 2021 to 31st October 2022 (Fig. 1). It included a wider array of 133 commercial platforms (9 different sensor systems brands), and offered manufacturers the opportunity to engage in 134 a free-of-charge impartial evaluation process. Although participation criteria matched those of the Main QUANT 135 study, a key distinction lay in the voluntary nature of participation: vendors were invited to contribute multiple 136 sensor devices throughout the WPS study (see Table 2). Participants were able to demonstrate their systems' 137 performance against collocated high-resolution (1-minute) reference data at a state-of-the-art measurement site 138 such as the Manchester supersite.

Table 2. The 23 WPS devices deployed at the Manchester supersite provided 63 gases and 62 PM measurements in total. For a detailed description of the devices see the Section S2 in the Supp.

Product*	Company	Measurements							
(# units)		NO	NO_2	O_3	со	CO ₂	\mathbf{PM}_1	PM _{2.5}	PM ₁₀
Mod (3)	QuantAQ	-	-	-	-	-	√	√	√
AQM (3)	AQMesh	√	√	√	√	√	√	√	~
Atm (2)	RLS**	-	-	-	-	-	√	~	√
IMB (2)	Bosch	-	√	√	-	-	-	√	√
Poll (2)	Oizom	√	√	√	√	√	-	√	√
AP (3)	Kunak	√	√	√	√	√	√	√	√
SA (3)	Vortex IoT	-	√	√	-	-	-	√	√
NS (3)	Clarity	-	√	-	-	-	√	√	√
Prax (2)	SCS***	√	√	√	√	√	√	√	√

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142 *Mod: Modulair, AQM: AQMesh; Atm: Atmos, Polludrone: Poll; AP: Kunak Air Pro; SA: Silax Air, NS: Node-S, Prax:

Praxis. **RLS: Respirer Living Sciences. ***SCS: South Coast Science.





144 2.3 Data collection, co-located reference data and data products

All sensor devices were installed at the measurement sites as per manufacturer recommendations. In addition to the device supplier's own cloud storage (accessed on-demand via each supplier's web portals), an automated daily scraping of each company's API was performed to save data onto a secure server at the University of York to ensure data integrity. PurpleAir units were exempt from this due to a lack of mobile data connection and poor internet signal at the sites; instead, readings were locally collected and manually uploaded. Minor pre-processing was applied at this stage to standardise the data format across all the devices. No outlier checks or data modifications were applied.

In addition to providing an independent assessment of sensor performance, QUANT also aimed to contribute to device manufacturers to help advance the field of air pollution sensors. To this end, three separate 1-month periods of reference data, spaced every 6 months, were shared with each supplier, provisional data soon after each period, and ratified data when available. For an overview of reference instrumentation at each site refer Table S1, and for details on the quality assurance procedures applied to the reference instruments see Table S2.

157 Access to colocated reference data allowed the companies to assess sensors' performance and, if they chose, to 158 generate and provide additional calibrated data products. These products are distinct data versions provided by 159 manufacturers throughout QUANT, before and/or after sharing reference data ---for instance, "out-of-box", "call", 160 "cal2", etc. Figures S1 and S2 show a time-line of the different data products. To see the dates and periods of the 161 shared reference data refer to Table S3. All reference data was embargoed until it was released to all manufacturers 162 simultaneously to ensure consistency across manufacturers. Not every manufacturer opted to use this data to apply 163 corrections or improve calibrations, but if they chose to do so, the updated measurements were treated as a separate 164 data product. Device calibrations were performed solely at the discretion of the manufacturers without any 165 intervention from our team, thus limiting the involvement of vendors/manufacturers in the provision of standard 166 sensor outputs and unit maintenance as would be required by any standard customer.

167 3. Results and discussion

168 A key challenge in sensor performance evaluation is the high spatial and temporal variability errors that impact 169 the accuracy of their readings, making the application of laboratory corrections more challenging. Furthermore, 170 the overreliance on global performance metrics, such as R² (i.e., the Coefficient of Determination), RMSE (i.e., 171 the Root Mean Squared Error), and MAE (i.e., the Mean Absolute Error) is an important issue when assessing 172 sensors. While these metrics provide a general understanding of sensor performance, they can be limiting or even 173 misleading, restricting a comprehensive understanding of the error structure and the measurement information 174 content (Diez et al., 2022).

In response to these challenges, the QUANT assessment represents the most extensive independent appraisal of air pollution sensors in UK urban atmospheres. As the results presented here illustrate, QUANT is dedicated to examining sensor performance through multiple complementary perspectives and metrics, aiming to integrate these to accurately reflect the complexity of this dataset. By making the dataset open-access, it enables other stakeholders to evaluate it based on criteria that align with their specific needs and contexts. The following sections aim to provide an overview of the data and provide initial findings, with a focus on those that are most relevant to end-users of these technologies.





182 3.1 Inter-device precision

183 Inter-device precision refers to the consistency of measurements across multiple devices of the same type, an 184 important characteristic to ensure the reliability of sensor outputs over time (Moreno-Rangel et al., 2018). During 185 QUANT, all the devices were collocated for the first 3 months and the final 3 months of the deployment to assess 186 inter-device precision and its changes over time. Fig. 2 shows the inter-device precision (as defined by the CEN/TS 187 17660-1:2021, i.e., the "between sensor system uncertainty" metric: $u_s(b_s, s)$ of PM_{2.5} measurements during these 188 periods. While most of the companies display a certain level of inter-device precision stability in each period 189 (except for one, with a seemingly upward trend in the final period), there are evident long-term changes. Notably, 190 out of the four manufacturers assessed in the final period (each having 3 devices running simultaneously), three 191 experienced a decline in their inter-device precision compared to two years earlier. This is likely due to both 192 hardware degradation but also drift in the calibration, which at this point had been applied between 16 and 34 193 months prior (depending on the manufacturer). For extended periods, inconsistencies among devices from the 194 same manufacturer might emerge, leading to varying readings under similar conditions. Consequently, data 195 collected from different devices may not be directly comparable, which could result in inaccuracies or 196 misinterpretations when analyzing air quality trends or making decisions.



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Figure 2. The inter-device precision of PM_{2.5} measurements from "identical" devices across the 5 companies participating in QUANT is assessed using the "between sensor system uncertainty" metric (defined by the CEN/TS 17660-1:2021 as *u(bs, s)*). Each line represents this metric as a composite of all sensors per brand (excluding units with less than 70% data) within a 40-day sliding window.

202 It is worth noting that the inter-device precision provides no information on the accuracy of the sensor 203 measurements; a batch of devices may provide a highly consistent, but also highly inaccurate measurement of the 204 target pollutant.

The "target plot" (as shown in Fig. 3) is a tool commonly used to depict the bias/variance decomposition of an instrument's error relative to a reference (for more details see Jolliff et al. (2009)). The mean error bias (MBE) is
used to characterise accuracy and precision is quantified by the centered Root Mean Squared Error (cRMSE, e.g.
Kim et al. (2022) also called unbiased Root Mean Squared Error (uRMSE, e.g. Guimarães et al. (2018)). Fig. 3
visualises the performance of a set of PM_{2.5} sensors of the WPS deployment for the first 2 months (out-of-box data) and the last 3 months of colocation (manufacturer-supplied calibrations). In addition to highlighting which devices are most accurate, Fig. 3 also provides an additional perspective of inter-device precision.





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Figure 3. Target diagrams for the WPS PM_{2.5} measurements during the initial co-location period (Jun-Jul 2021, left) and final co-location period (Aug-Oct 2022, right). The error (RMSE) for each instrument is decomposed into the MBE (y-axis) and cRMSE (x-axis). Each point represents an individual sensor device, with duplicate devices having the same colour. Since only units with more than 75% of the data were considered, the plot on the right shows fewer units than the plot on the left.

219 3.2 Device accuracy and collocation calibrations

220 Sensor measurement accuracy denotes how close a sensor's readings are to reference values (Wang et al., 2015). 221 Characterizing this feature is imperative for establishing sensor reliability and making informed decisions based on 222 its data. Fig. 4 shows that collocation calibration can greatly impact observed NO₂ sensor performance in a number 223 of ways. Firstly, measurement bias is often, but not always, reduced following calibration, as evidenced by a general 224 trend for devices to migrate towards the origin (RMSE = 0 ppb). Secondly, it can help to improve within-manufacturer 225 precision by grouping sensor systems from the same company closer together. The figure also highlights a 226 fundamental challenge with evaluating sensor systems: the measured performance can vary dramatically over time — 227 and space— as the surrounding environmental conditions change. To quantify this, 95% Confidence Intervals (CIs) 228 were estimated for each device using bootstrap simulation and are visualised as a shaded region. For the out-of-box 229 data, these regions are noticeably larger than in the calibrated results for most manufacturers, suggesting that 230 colocation calibration has helped to tailor the response of each device to the specific site conditions. This is reinforced 231 by the cRMSE component reducing by a greater extent than the MBE, in the terminology of machine learning the 232 calibration has helped reduce the variance portion of the bias-variance trade-off.







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Figure 4. Effect of colocation calibration on NO₂ sensor accuracy. The accuracy is quantified using RMSE, which is
 decomposed into MBE (y-axis) and cRMSE (x-axis). 95% confidence regions were estimated using bootstrap sampling.
 The left panel displays results from the period Jun - Jul 2021 ('out-of-the-box' data), while the right-hand panel
 summarises Aug 2021 when calibrations were applied for all the WPS manufacturers.

However, it is important to note a limitation of Target Plots: they primarily focus on sensor behaviour around the mean. Therefore, the collective improvement evidenced by Fig. 4 might be only partial. For applications where it is important to understand how calibrations impact lower or higher percentiles, considering other metrics or visual tools would be advisable. An example of this is the absolute and Relative Expanded Uncertainty (REU, defined by the Technical Specification CEN/TS 17660-1:202). Fig. 5 illustrates how NO₂ calibrations might not only improve collective performance around the mean (as indicated by the dotted red line in Fig. 5 and previously displayed in the target plot) but across the entire concentration range.



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Figure 5. The top plots display the REU (%) across the concentration range, while the bottom plots depict the Absolute Uncertainty (ppb) —both before (left plots) and after (right plots) calibrating NO₂ WPS systems. The shaded areas





represent the collective variability evolution (all sensors from all companies) of both metrics. These plots were constructed using the minimum and maximum value of the REU and the Absolute Uncertainty for the entire concentration range.

However, a note of caution when interpreting results from observational studies such as these is that it is impossible to ascertain a direct causal relationship between calibration and sensor performance as there are numerous other confounding factors at play (Diez et al., 2022). Notably these two data products are being assessed over different periods when many other factors will have changed, for example, the local meteorological conditions as well as human-made factors such as reduced traffic levels following the COVID-19 lockdown that commenced in March 2020.

256 3.3 Reference instrumentation is key

A common assumption when evaluating the performance of sensors is that the metrological characteristics of the sensor predominantly influence discrepancies detected in colocations. While this presumption can often be justified due to both devices' relative scales of measurement errors, it is not always the case. Since every measurement is subject to uncertainties, it is crucial to consider those associated with the reference when deriving the calibration factors of placement.

262 Fig. 6 (left plots) displays the performance of a NO₂ reference instrument (Teledyne T200U) specifically installed for 263 QUANT, located next to the usual instrument at the Manchester supersite (Teledyne T500). Although they use 264 different analytical techniques (chemiluminescence for the T200U and Cavity Attenuated Phase Shift Spectroscopy 265 for the T500), their measurements are highly correlated ($R^2 \sim 0.95$). However, it's possible to identify a proportional 266 bias (slope=0.69), attributed to retaining the initial calibration (conducted in York) without subsequent adjustments, 267 a situation exacerbated by an unnoticed mechanical failure of one of the instrument's components. The REU 268 demonstrates that, under these circumstances, an instrument designated as a reference does not meet the minimum 269 requirements set out by the Data Quality Objectives (DQOs) of the EU Air Quality Directive 2008/50/EC. Figure S3 270 shows a unique sensor evaluated against both the T500 and the T200U. The comparison against the T200U yields 271 better results, suggesting that, in a hypothetical scenario where it was the only instrument at the site, this could lead 272 to misleading conclusions. This situation reinforces the idea that instruments should not only be adequately 273 characterised but also undergo rigorous quality assurance and data quality control programs, as well as receive 274 appropriate maintenance (Pinder et al., 2019). All of this must be performed before and during the use of any 275 instrument.

276 For PM monitoring the current EU reference method is the gravimetric technique (CEN EN 12341, 2023), which is 277 a non-continuous monitoring method that requires weighing the sampled filters and off-line processing of the results. 278 Techniques that have proven to be equivalent to the reference method (called "equivalent to reference" in the EU Air 279 Quality Directive) are very often used in practice. In the UK context, the Beta Attenuated Monitor (BAM) and FIDAS 280 (optical aerosol spectrometer) are equivalent-to-reference methods commonly used as part of the Urban AURN 281 Network (Allan et al., 2022). To illustrate these differences in practice, Fig. 6 compares these two equivalent-to-282 reference PM2.5 measurements obtained with a BAM (AURN York site, located on a busy avenue), and a FIDAS unit 283 specifically installed for QUANT. During this specific period, they do not fully agree ($R^2 = 0.87$). Despite a not very 284 pronounced bias (slope=0.80), the dispersion of points around the best-fit line is noticeable, limiting the linearity of 285 the FIDAS compared to the BAM.





In the hypothetical case that the BAM were to be considered the reference method (arbitrarily chosen for this example as it is the current instrument at the AURN York site) when assessing the FIDAS under these test conditions, it would only meet the criterion stipulated by the EU DQOs for indicative measurements, but not for fixed (i.e., reference) measurements. Of course, this example is primarily intended to illustrate the magnitude of differences between both methods for this particular application, and by no means does this observation imply that the FIDAS measurements are inherently problematic.



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Figure 6. The left plots depict the comparison between the Teledyne T200U (chemiluminescence analyzer) and the reference method (Teledyne T500 CAPS analyzer) at the Manchester supersite. The plots to the right illustrate PM_{2.5} measurements in York, taken with a FIDAS instrument (optical aerosol spectrometer) and a BAM 1020 (beta attenuation monitor), both equivalent-to-reference methods. While the top plots show the regression (including some typical single-value metrics), those on the bottom present the REU alongside the DQOs defined by the European Directive 2008/50/EC.

Although these two instruments (BAM and Fidas) show a greater concordance between themselves than with sensors (for the comparison of two sensor systems against the BAM and the Fidas, refer to Fig. S4), the choice of the measurement method can have a considerable impact on evaluations of this type. This underscores the importance of adequately characterising the uncertainties of the reference monitor when evaluating sensors.

303 3.4 Systems performance after location transfer

An extreme example of sensor performance varying due to environmental conditions is when sensors are moved between locations, as their apparent performance may vary drastically. Fig. 7 displays the REU and regression plots for four of the same PM_{2.5} sensor system in two periods: April-June 2022 when the devices were working across the 3 sites (York, Manchester and London), and August-October 2022 when they were all reunited in Manchester. The RMSE remains reasonably consistent between the devices across the periods and locations. However, the device that moved from York to Manchester saw its slope change from 0.69 to 0.86. Because this device's slope is consistent with the other units when running in Manchester, this is likely due to the different





- 311 sensor responses in the specific environments. The precise cause of this change is not immediately evident and
- 312 will be the focus of a follow-up study, but could be due to changes in local conditions impacting sensor calibration
- and/or differences in actual PM_{2.5} sources and particle characteristics at the sites (Raheja et al., 2022).



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Figure 7. Regression (top) and REU (bottom) plots showing data from four PM_{2.5} sensors (same manufacturer) over 2 time
 periods: Apr-Jun 2022 and Aug-Oct 2022. The four devices were in separate locations in the first period, but all deployed
 in Manchester in the second.

A second example of performance changing between locations is presented in Fig. 8, showing NO₂ data from two
sensor systems (different brands, one shown on top of the other) before (left plots) and after (right plots) they were
moved from Manchester to London in March 2020. Both sensors saw a reduction in agreement with the reference
instrument at the London site compared to Manchester, despite both these sites being classified as urban-background
with reference instrument performance regularly audited by the UK National Physical Laboratory.







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Figure 8. Comparison of NO₂ measurements for two systems (A and B) that were moved between Manchester (left plots)
 and London (right plots). The Manchester deployment was from January - February 2020, and the London data was
 recorded from April - May 2020.

327 The primary distinction between both systems' behaviour lies in the fact that the sensor located in the top row, even 328 after being relocated to London, maintains a linear response (albeit slightly more degraded than that observed in 329 Manchester, as the R^2 and RMSE show). In contrast, in the second system (bottom row), the response is notably 330 noisier as the Standard Error (SE) ---which is the dispersion of the data around the best-line fit line, i.e., the remaining 331 error after bias correction. In scenarios akin to this latter, where there is a high variance in the residuals, a linear 332 correction will not provide a significant improvement. While more sophisticated corrections could be applied, these 333 will be limited by domain knowledge of the end-user, and potentially by other complex data sources that might be 334 available. However, it is important to remember that additional post-processing could increase the risk of overfitting 335 (Aula et al., 2022). On the other hand, for cases like the top plots, users might benefit from trying to correct them 336 using simple linear correction (e.g. using reference instruments if available) or other approaches that could provide 337 means for zero and span correction. A straightforward and cost-effective example could be the use of diffusion tubes 338 for the case of NO₂, as discussed in Section 3.6.

339 3.5 Long-term stability

340 The long-term stability of sensor response is also an important facet of its performance, especially for certain use 341 cases such as multi-year network deployments. There can be multiple causes of long-term changes to sensor 342 response, for example, particles settling inside the sampling chamber in optical-based sensors(e.g. Hofman et al. 343 (2022)), or the gradually changing composition of electrochemical cells (e.g. Williams (2020)). How these changes 344 manifest themselves in the data must be identified if ways to account for them are to be implemented.





Fig. 9 shows the temporal nature of the O₃ and NO₂ errors (MBE, cRMSE and RMSE) from a sensor system
between February 2020 and October 2022. The O₃ shows (Fig. 9a) a gradual increase in the overall measurement
error, largely due to an increase in the MBE. It also shows a distinct seasonality MBE, increasing by a factor of 34 between March and July compared to the August-February period. The cRMSE component shows fluctuations
during the study but only has a small increasing trend. The NO₂ system (Fig. 9b) demonstrates a consistently
increasing overall error, with a less pronounced seasonal influence. The bias contributes greatly to the total error
(see Section 3.6 for NO₂ sensor correction, Fig. 9c).

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Figure 9. Error (as RMSE, red line) of one of the systems belonging to the Main QUANT, decomposed into cRMSE (in
blue) and MBE (in yellow) estimated based on a 40-day (1-day slide) moving window. Panel a) is for O₃ measurements,
and panel b) is for NO₂ (April 2020-Oct 2022). Panel c) is also for NO₂, this time showing the effect of a linear correction
using diffusion tubes (see next section for more details).

358 3.6 Informing end-use applications

359 Ultimately, for any air pollution monitoring application, the requirements of the task should dictate the 360 measurement technology options available. For example, if the requirement for a particular measurement is to 361 assess legal compliance, then lower measurement uncertainty must be a key consideration as the reported values 362 need to be compared to a limit value. In contrast, if an application aimed to look at long-term trends in pollutants, 363 then absolute accuracy may not be as important as the long-term stability of sensor response. In order to realise 364 the potential of air pollution sensor technologies, end users need to be provided with the information required to 365 critically assess the strengths and weaknesses of potential candidate sensor devices, ideally in an easy-to-access 366 and interpret manner.

367

368 Understanding the uncertainty associated with a measurement instrument is essential for recognizing its 369 capabilities and limitations. Accurate instruments are crucial, especially in areas like public health decision-370 making, where inaccurate data can have profound implications (Molina Rueda et al., 2023). Furthermore, 371 instruments that operate autonomously ensure consistent, uninterrupted data collection, making them more 372 efficient and cost-effective in terms of maintenance and calibration. Figure 10 shows the REU (y-axis) and Data 373 Coverage (DC, x-axis) of companies measuring NO₂ with more than 2 systems running to avoid ambiguity in the





374 results. Using multiple systems, not only avoids ambiguity in results but also enhances the robustness of the data 375 collected. Both REU and DC are key criteria within the EU scheme (EU 2008/50/EC) for evaluating the 376 performance of measurement methods, and are complemented by the CEN/TS 17660-1:2021 specifically for 377 sensors. This document defines three different sensor system tiers. Class 1 sensors, bounded by the green rectangle, 378 offer higher accuracy than Class 2 sensors, highlighted by the red rectangle (Class 3 sensors have no set 379 requirements). Presenting the data like this helps users anticipate the performance of sensor systems ---under the 380 assumption that all sensors from the same brand will behave similarly in equivalent environmental conditions-381 providing more insight into selecting the appropriate instrument for a given project or study.



382

Figure 10. The REU vs. Data Coverage (DC) for 4 systems companies was evaluated during the WPS for the period Nov
2021-Oct 2022 (after all companies had at least one calibrated product). Both the REU and the DC were estimated
based on a 40-day size (which is the number of days used by CEN/TS 17660-1:2021 for on-field tests) moving window
(1-day slide). While the green rectangle represents the DQOs for Class 1 sensors, the red one limits the DQOs for Class
2 sensors (Class 3 sensors have no requirements).

388 Depending on the nature of the sensor data uncertainty, methods can be implemented to improve certain aspects 389 of the data quality for a particular application. One such example is the use of distributed networks to estimate 390 sensor measurement errors, such as that described by (J. Kim et al., 2018). Depending on the application, simpler 391 methods could also be available to reduce the magnitude of the changing bias, and thus significantly improve the 392 accuracy of an individual sensor system, but also that of broader sensor networks. For the case shown in Fig.9b, 393 one possible way to do this would be using supporting observations of NO₂ made via diffusion tubes. These 394 measurements are widely used to monitor NO2 concentrations in UK urban environments, due to their lower cost 395 (~£5 per tube) and ease of deployment, but only provide average concentrations over periods of weeks to months 396 (Butterfield et al., 2021). During QUANT, NO2 diffusion tubes were deployed at the 3 colocation sites (see Section 397 S8 at the Supp. for more details). Combining these measurements offers the possibility of quantifying the average





398 sensor bias, thus reducing the error on the sensor measurement whilst maintaining the benefits of its high-time 399 resolution observations. It is important to note that while bias correction has been applied to the sensor data, the 400 NO2 diffusion tube concentrations used for comparison purposes must also be adjusted (e.g. following DEFRA 401 (2022)). Fig. 9c shows the accuracy of the same NO2 sensor data shown in Fig. 9b but applies a monthly offset 402 calculated as the difference between its monthly average measurement and that from the diffusion tube (see Figure 403 S5). This shows a dramatic reduction in overall error largely driven by its bias correction. What remains largely 404 resulting from the cRMSE, i.e. the error variance that might arise from limitations from the sensing technology 405 itself and/or the conversion algorithms used to transform the raw signals into the concentration output. To validate 406 the efficacy and reliability of this bias correction method, further long-term studies are warranted.

407 The development and communication of methods that improve sensor data quality, ideally in digestible case 408 studies, would likely increase the successful application of sensor devices for local air quality management. There 409 is also a need for similar case studies showcasing the successful application of sensor devices for particular 410 monitoring tasks. An example of this from the QUANT dataset is the use of sensor devices to successfully identify 411 change points in a pollutant's concentration profile. Determining when a specific pollutant has changed its 412 temporal nature is a challenging task as there are a large number of confounding factors that influence a pollutant's 413 concentration at a specific point in time, including but not limited to seasonal factors, environmental conditions 414 (both natural and arising from human behaviour), and meteorological factors. A novel statistical approach to 415 smoothing air quality measurements was applied, accounting for these external factors (Lacy & Moller). This 416 method was applied to NO2 concentrations determined from the sensor systems that had remained in Manchester 417 throughout 2020, aiming to identify whether the well-documented reduction in ambient NO₂ concentrations could 418 be observed due to changes in travel patterns associated with COVID-19 restrictions. To provide an objective 419 quantification of whether a change-point had occurred, the Bayesian online change-point detection (Adams & 420 MacKay, 2007) was applied. Of the 8 devices that measured NO₂, clear changepoints corresponding to the 421 introduction of a lockdown were identified in 2 (Fig.11). While this is an unsupervised analysis, it demonstrates 422 the potential of these devices to identify long-term trends with appropriate processing, even with only having had 423 3 months of training data to fit the model to. This is especially aided by the given algorithm's ability to use 424 reference data as a prior allowing sensor systems to fine-tune the model.







425

Figure 11. NO₂ measurements (black solid line) and detrended estimates (blue solid line with 95% confidence interval in the shaded grey region) from the reference instrument (left panel) and 2 sensor systems (middle and right panels) from Manchester in 2020. Vertical dashed lines and their corresponding dates indicate identified change points, which correspond to the introduction of the first national lockdown due to COVID-19 on the 23rd of March 2020. The percentage in blue represents the relative peak-trough decrease from 5th March to 20th April.

431 4. Conclusions

432 Lower-cost air pollution sensor technologies have significant potential to improve our understanding and ability 433 to manage air pollution issues. Large-scale uptake in the use of these devices has been primarily limited by 434 concerns over data quality and a general lack of a realistic characterisation of the measurement uncertainties 435 making it difficult to design end uses that make the most of the data information content. Developments in the 436 field of air pollution sensor technology are also developing rapidly, with advances in both the measurement 437 technology and particularly in the data post-processing and calibration. A challenge with the use of sensor-based 438 devices is that many of the end-use communities do not have access to extensive reference-grade air pollution 439 measurement capability (Lewis & Edwards, 2016), or in many cases expertise in making atmospheric 440 measurements. For this reason, reliable information on expected sensor performance needs to be available to aid 441 effective end-use applications. Large-scale independent assessments of air sensor technologies are non-trivial and 442 costly, however, making it difficult for end users to find relevant performance information on current sensor 443 technologies. The OUANT assessment is a multi-year study across multiple locations, that aims to provide relevant 444 information on the strengths and weaknesses of commercial air pollution sensors in UK urban environments.

The QUANT sensor systems were installed at two highly instrumented urban background measurement sites, in Manchester and London, and one roadside monitoring station in York. The study design ensured that multiple devices were collocated to assess inter-device precision, and devices were also moved between locations and able to test additional calibration data products to assess and enable developments in sensor performance under realistic end-use scenarios. A wider participation component of the Main QUANT assessment was also run at the Manchester site to expand the market representation of devices included in the study, and also to assess recent developments in the field.





452 A high-level analysis of the dataset has highlighted multiple facets of air pollution sensor performance that will 453 help inform their future usage. Inter-device precision has been shown to vary, both between different device types 454 and over different periods of time, with the most accurate devices generally showing the highest levels of inter-455 device precision. The accuracy of the reported data for a particular device can be impacted by a variety of factors, 456 from the calibrations applied to its location or seasonality. This has important implications for the way sensor-457 based technologies are deployed and supports the case made by others (Bittner et al., 2022; Farquhar et al., 2021; 458 Crilley et al., 2018; Williams, 2020; Bi et al., 2020) that practical methods to monitor sensor bias will be crucial 459 in uses where data accuracy is paramount.

460 In addition to these findings, this overview lays the groundwork for more detailed research to be presented in 461 future publications. Subsequent analyses will focus on on providing a more nuanced understanding of the 462 uncertainty in air pollution sensor measurements, thus equipping end-users with better insights into of the 463 capability of sensor data. Future studies will delve into specific aspects of air pollution sensor performance: 1) a 464 comprehensive performance evaluation of $PM_{2.5}$ data, assessing their accuracy and reliability under different 465 environmental conditions; 2) an in-depth analysis of NO2 measurements, examining their sensitivity and response 466 in various urban environments; and 3) a detailed investigation into the detection limits of these sensor technologies, 467 targeting their optimized application in low concentration scenarios. These focused studies are basic steps needed 468 to further advance our understanding of sensors' capabilities and limitations, ensuring informed and effective 469 application in air quality monitoring.

470 Supplementary

471 The supplement related to this article is available online at:

472 Data availability

473The data for this study can be found at the Centre for Environmental Data Analysis (CEDA): Lacy, S.; Diez, S.;474Edwards, P. (2023): Quantification of Utility of Atmospheric Network Technologies: (QUANT): Low-cost air475quality measurements from 52 commercial devices at three UK urban monitoring sites. NERC EDS Centre for476EnvironmentalDataAnalysis,dateofcitation.477https://catalogue.ceda.ac.uk/uuid/ae1df3ef736f4248927984b7aa079d2e.

478 Author contributions

479 The initial draft of the manuscript was created by SD, PME, and SL. The research was conceptualized, designed, 480 and conducted by PME and SD. Methodological framework and conceptualization were developed by SD, PME, 481 and SL. Data analysis was primarily conducted by SD and SL. The software tools for data visualization and 482 analysis were developed by SD and enhanced by SL. MF, MP and NM supplied the reference data critical for the 483 study. TB, HC, DH, SG, NAM and JU made substantive revisions to the manuscript, enriching the final 484 submission.

485 Competing interests

- 486 The authors declare that they have no conflict of interest.
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